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Mutualistic Networks: Moving closer to a predictive theory

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27

28 **Abstract**

29 Plant-animal mutualistic networks sustain terrestrial biodiversity and human food-security.
30 Global environmental changes threaten these networks, underscoring the urgency for developing
31 a predictive theory on how networks respond to perturbations. Here I synthesize theoretical
32 advances towards predicting network structure, dynamics, interaction strengths, and responses to
33 perturbations. I find that mathematical models incorporating biological mechanisms of
34 mutualistic interactions provide better predictions of network dynamics. Those mechanisms
35 include trait matching, adaptive foraging, and the dynamic consumption and production of both
36 resources and services provided by mutualisms. Models incorporating species traits better predict
37 the potential structure of networks (fundamental niche), while theory based on the dynamics of
38 species abundances, rewards, foraging preferences, and reproductive services can predict the
39 extremely dynamic realized structures of networks, and may successfully predict network
40 responses to perturbations. From a theoretician's standpoint, model development must more
41 realistically represent empirical data on interaction strengths, population dynamics, and how
42 these vary with perturbations from global change. From an empiricist's standpoint, theory needs
43 to make specific predictions that can be tested by observation or experiments. Developing
44 models using short-term empirical data allows models to make longer-term predictions of
45 community dynamics. As more longer-term data become available, rigorous tests of model
46 predictions will improve.

47

48 **Introduction**

49 Mutualistic interactions between animal and plant species sustain terrestrial biodiversity
50 (Thompson 1994) and human food-security (Potts et al. 2016, Ollerton 2017). Unfortunately,
51 global environmental changes threaten these diverse systems with species extinctions, climate

52 change, habitat loss, and species invasions (Goulson et al. 2015, Ollerton 2017). This global
53 environmental crisis underscores the urgency for developing theory capable of understanding
54 and predicting the structure and dynamics of mutualistic systems. Predicting the structure of
55 mutualistic systems is critical for understanding and predicting their dynamics, and the dynamics
56 of these systems underlie their important ecosystem functions and will determine their response
57 to anthropogenic perturbations (Memmott et al. 2004, Bascompte & Jordano 2014, Valdovinos et
58 al. 2016, 2018). Understanding how these mutualistic systems operate today, and predicting their
59 dynamics as environments change, is critical for developing plans and policies to manage these
60 systems with the objective of preserving their key ecosystem functions and services. In this
61 review, I synthesize 20 years of scientific advances towards predicting the structure, dynamics,
62 and response of mutualistic networks to global change.

63 Qualitative predictions produced by mathematical models and tested by empirical
64 research have been key to the progress of Ecology as a science. Starting with Gause (1932), who
65 experimentally tested the prediction of competitive exclusion produced by the Lotka-Volterra
66 model of competition, research producing (e.g., Rosenzweig & MacArthur 1963, May 1973, Holt
67 1977) and testing (e.g., Vandermeer 1963, Murdoch & Oaten 1975, Stearns 1977, Wootton 1997,
68 Schmitz 1997, Morin 1999) model predictions on ecological systems have shaped our discipline.
69 Recent research on complex food webs has successfully predicted interaction strengths (Berlow
70 et al. 2009) and relative biomasses of species (Boit et al. 2012) in aquatic systems. Notoriously,
71 however, most of such research has been conducted on antagonistic interactions, leaving our
72 understanding of mutualistic interactions far behind. Fortunately, the last decade has seen a
73 blooming of ecological research on mutualistic interactions promoted by the study of mutualistic
74 networks (Bascompte & Jordano 2014). Here, I organize the abundant literature focusing on the
75 qualitative predictions made by theoretical research and discuss how those predictions have been
76 or need to be tested with empirical data (see Table 1).

77 Networks have helped ecologists to identify patterns in the structure of species
78 interactions in highly complex multi-species systems (i.e., several tens to hundreds of species,
79 Martinez 1991, Bascompte et al. 2003, Thébault & Fontaine 2010). There are almost infinite
80 ways in which hundreds of species can possibly interact based only on all possible combinations
81 of species interactions. This high complexity precluded for long time the detailed study of

82 complex multi-species systems. That is, the seeming intractability of those complex systems
83 caused ecologists to only study the dynamics of a few interacting species even when
84 communities are composed by hundreds of interacting species. Contributions of network studies
85 (and computers) to ecology made the complexity of communities more tractable by identifying
86 clear patterns in the structure of interactions among tens to hundreds of species (Martinez 1991,
87 Bascompte et al. 2003, Thébault & Fontaine 2010) and showing that such structure strongly
88 influences the dynamics of ecological systems (Brose et al. 2004, Bascompte & Jordano 2014,
89 Valdovinos et al. 2016)

90 Initially, research on ecological networks was all about descriptive metrics of the
91 structure of food webs (Martinez 1991, Dunne 2006) and mutualistic networks (Jordano 1987,
92 Bascompte et al. 2003). More recent research, however, takes a dynamic path (e.g., Brose et al.
93 2004, Bascompte et al. 2006, Valdovinos et al. 2013) by using the type of mathematical
94 modelling that ecologists have used for decades to study the dynamics of interacting species
95 (e.g., Rosenzweig & MacArthur 1963, Holt 1977, Yodzis & Innes 1992). The main point of this
96 review is to show that research on ecological networks has recently taken another step forward
97 by producing more testable predictions. This step forward has moved ecological studies closer to
98 predicting the structure (first section), dynamics (second section), and responses (third section)
99 of ecological systems to global change, via better integrating theoretical and empirical research
100 of ecological networks. Further developing and solidifying such predictive theory (e.g., theory
101 that can be empirically tested with data) will be critical in future years to manage and preserve
102 ecological systems in the era of global change.

103

104 **I. Towards predicting the structure of mutualistic networks**

105 This review considers network structure consisting of both the **binary structure** (i.e.,
106 who interacts with whom, Box 1) and the **strength** of those interactions. The first subsection
107 synthesizes the state of the art on proposed mechanisms predicting the binary structure including
108 species traits and abundances, and incomplete sampling. The second subsection conceptualizes
109 interaction strengths and synthesizes the few works predicting them in mutualistic networks.

110 **A. Predicting the binary structure**

111 Most of the research on mutualistic networks has been devoted to characterizing,
112 explaining, and more recently, predicting their binary structure (Box 1; Jordano 1987, 2016,
113 Bascompte & Jordano 2007, 2014, Ramos-Jiliberto et al. 2010, Chacoff et al. 2012, Bartomeous
114 et al. 2016). This subsection organizes the scope and results of such research within three main
115 questions, which constitute sequential steps towards predicting the binary structure. Those
116 questions are: 1) What is the common structure to all mutualistic networks? 2) What are the
117 mechanisms producing such structure? 3) Can we predict interactions among species based on
118 species traits and abundances?

119 *1) What is the common structure to all mutualistic networks?*

120 If a new mutualistic network was sampled in the field, it would likely exhibit: 1) more
121 animal than plant species, 2) moderate connectance, 3) highly heterogeneous degree distribution,
122 4) high nestedness, and 5) moderate modularity (see Box 1 for definitions; Jordano 1987, 2016,
123 Bascompte & Jordano 2007, 2014, Ramos-Jiliberto et al. 2010, Chacoff et al. 2012, Bartomeous
124 et al. 2016). These properties characterize the binary structure of most of the empirical networks
125 reported worldwide.

126 *2) What are the mechanisms producing such structure?*

127 Much research has been devoted to explain the prevalence of the above-mentioned
128 properties (reviewed in Vázquez et al. 2009 and Bascompte & Jordano 2014). One of the key
129 mechanisms proposed to explain those properties are the **barriers or constraints on interaction**
130 **formation** (Table 1; also called forbidden links, Jordano 1987, 2016, Vázquez et al. 2009a).
131 Mechanisms constraining species interactions include temporal or spatial uncoupling (i.e.,
132 species do not co-occur in either time or space), constraints to the accessibility of the resources
133 due to trait mismatches (e.g., proboscis size very different from corolla size), and physiological-
134 biochemical constraints that prevent the interactions (e.g., chemical barriers). Empirical
135 (reviewed in Vázquez et al. 2009a and Jordano 2016) and theoretical (Santamaría & Rodríguez-
136 Gironés 2007) research has shown that those constraining mechanisms predict the absence of
137 interactions among specialist species (characteristic of nestedness), the existence of numerous
138 specialist species and a few highly generalist species (characteristic of heterogeneous degree
139 distributions), and the observed low connectance of networks.

140 Other work, however, has shown that properties of the binary structure observed in
141 mutualistic networks can emerge as a **sampling artefact** (Table 1; Blüthgen et al. 2008,
142 Blüthgen 2010). Blüthgen et al. developed a neutral model assuming incomplete sampling of
143 species interactions, skewed species abundances, and fully generalized systems (i.e., all plant
144 species interact with all animal species). Such a model predicts that the often-missing
145 interactions between rare species (characteristic of nestedness and heterogeneous degree
146 distributions) result from low sampling efforts failing to record the interactions of rare species.
147 This prediction raised the question of whether the observed structure of mutualistic networks
148 represents the ‘true’ architecture of interactions (produced by evolutionary and ecological
149 mechanisms), or merely an artefact of **incomplete sampling**. This question promoted many
150 studies investigating sampling effects on network structure by varying sampling effort both in
151 the field (Nielsen & Bascompte 2007, Petanidou et al. 2008, Hegland et al. 2010, Chacoff et al.
152 2012, Rivera-Hutinel et al. 2012) and in models generating network structures (Blüthgen et al.
153 2008, Vázquez et al. 2007, Bartomeous 2013, Fründ et al. 2016). Those studies showed that
154 incomplete sampling strongly underestimates the number of interactions and overestimates the
155 degree of specialization.

156 Fortunately, recent niche-based models (e.g., Fründ et al. 2016) help disentangle the
157 effect of **incomplete sampling** from the effect of species’ abundances and traits in structuring
158 mutualistic networks. Moreover, complementary data sources can reduce the incidence of
159 missing links caused by incomplete sampling and, therefore, reduce the impacts of sampling
160 effort on network data (Olesen et al. 2010, Jordano 2016). For example, pollen-transport data
161 effectively complement pollinators’ visitation data to show the structure of plant-pollinator
162 network (Bosch et al. 2009, Olesen et al. 2010, Coux et al. 2016). Overall, studies evaluating the
163 impacts of **missing links** and sampling effort on network structure show that low sampling effort
164 strongly underestimates the number of links and degree of generalization but does not
165 necessarily affect higher-order network properties such as nestedness. This results mostly
166 because the averaging of processes for higher-order function minimizes the effects of outliers.
167 Consequently, a robust characterization of higher-order properties of networks is still possible
168 even when true interactions are under-sampled (Morales-Castilla et al. 2015, Jordano 2016).

169 ***3) Can we predict interactions among species based on species traits and abundances?***

170 Building on the knowledge generated by studies analyzing properties of the binary
171 structure, recent models are predicting the occurrence of interactions based on species traits and
172 abundances (Vázquez et al. 2009b, Eklöf et al. 2013, Gravel et al. 2013, Morales-Castilla et al.
173 2015, Bartomeus et al. 2016, Crea et al. 2016, Fründ et al. 2016). For example, Bartomeus et al.
174 (2016) use a Bayesian block-model approach (Clauset et al. 2008) in which the probability of an
175 interaction between co-occurring species depends on their traits. Such models can also account
176 for species abundances by making the trait distribution dependent on abundances. Using
177 maximum likelihood, the authors fit the model parameters to three empirical datasets ranging
178 from predator-prey to mutualistic interactions, and use the parameterized models to predict
179 species interactions and estimate unobserved traits for each dataset. As another example,
180 Morales-Castilla et al. (2015) sequentially remove species interactions based on constraining
181 mechanisms (e.g., spatial or temporal decoupling) and estimate the interaction probabilities for
182 the residual links. These types of models advance the discipline of ecological networks by
183 producing predictions of specific interactions that can be tested against empirical data, which can
184 further describe the relative effects of different mechanisms (i.e., species traits constraining
185 interaction formation, species abundances, and incomplete sampling) on the structure of
186 mutualistic networks.

187 Finally, related to predicting interactions based on species traits, **phylogenetic signal** has
188 been detected in the structure of mutualistic networks (Rezende et al. 2007, Peralta 2016). This
189 suggests that the evolutionary history encoded in species phylogenies may have influenced the
190 assembly of mutualistic networks. In a seminal paper detecting phylogenetic signal in mutualistic
191 networks, Rezende et al. (2007) find that phylogenetically related species tend to interact with a
192 similar set of species and exhibit similar numbers of interactions. Explanatory mechanisms for
193 this ‘conservatism of interactions’ (Peralta 2016) still need to be evaluated, but one plausible
194 mechanism is that species may have inherited their traits involved in mutualistic interactions
195 from common ancestors. Thus, related species exhibit similar traits and, therefore, a similar set
196 of mutualistic partners (Eklöf et al. 2013). Other research detecting phylogenetic signal in
197 mutualistic networks (reviewed by Peralta 2016) shows that modularity might depend on the
198 clustering of phylogenetically related species in a network (Dupont & Olesen 2009) and on trait
199 convergence such as pollination syndromes (Corbet 2000). However, more research is required
200 to evaluate causation in the correlations reported between network structure and phylogenetic

201 trees. For example, network assembly models show that nested or modular structures fail to
202 emerge when simulating phylogenetic relatedness (Perazzo et al. 2014, Ponisio & M'Gonigle
203 2017). Without such key cause-effect connections, much of the phylogenetic signal of networks
204 remains speculative (but see Raimundo et al. 2018). Moreover, most studies investigating
205 phylogenetic signal in networks use taxonomic instead of phylogenetic trees, which represent
206 important challenges including underestimating evolutionary differences and arbitrarily
207 assigning branch lengths (Peralta 2016).

208 In summary, research on mutualistic networks has provided answers to the three
209 questions examined in this subsection. First, general properties including high nestedness,
210 moderate connectance, and heterogeneous degree distribution are common to most observed
211 networks. Second, biological mechanisms including trait (miss)matching and phenological
212 (de)coupling together with incomplete sampling have proven to determine those properties. In
213 particular, incomplete sampling strongly diminish detection of specific interactions but less
214 strongly affects network-wide measures of structure. Third, the theoretical (*a priori*) predictions
215 of network structure are improving, mainly due to iterative comparisons with empirical datasets,
216 but understanding the causal relationships between empirical properties (e.g., phylogenetic
217 similarity) and network structure (e.g., modularity) remain a challenge.

218

219 **B. Predicting interaction strengths**

220 The distribution of interaction strengths among species strongly influences the dynamics
221 of communities (McCann et al. 1998, Wootton & Emmerson 2005, Bascompte et al. 2006,
222 Okuyama & Holland 2008). Therefore, predicting the distribution of interaction strengths in
223 mutualistic networks provides important information for predicting their dynamics. This sub-
224 section emphasizes the need to distinguish per-capita effects from interaction frequencies when
225 defining interaction strengths (e.g., standardizing by species abundances). This is to avoid
226 predicting (e.g., Bascompte et al. 2006) that abundant species (usually generalists) provide
227 higher per-capita benefits to their mutualistic partners than do rare species (usually specialists),
228 which contradicts empirical (Vázquez et al. 2005, Gómez & Zamora 2006) and theoretical
229 (Valdovinos et al. 2016, Benadi & Gegear 2018) evidence showing that specialists tend to
230 provide higher per-capita benefits than generalists.

231 One of the most used definitions of interaction strength is **per-capita effect**, defined as
232 the direct effect of an average individual of one species on the average individual of another
233 species (Wootton & Emmerson 2005, Vázquez et al. 2015). Bascompte et al. (2006) proposed to
234 estimate per-capita effects in mutualistic networks (α_{ij}^A and α_{ji}^P in Eqs. 2-3 of Box 2) by using
235 the frequency of interaction between plant and animal species (i.e., frequency of contact or
236 visits). More specifically, the authors proposed to estimate those per-capita effects as the
237 **dependence** of a species on their mutualistic partners (Box 1), which effectively measures the
238 relative frequency of interaction between species. However, this approach potentially confounds
239 per-capita effects with species abundances. The metric of dependence results in species
240 depending more strongly on species with whom they interact more often, which is highly
241 correlated with species abundance (see above, Vázquez et al. 2007). That is, Bascompte et al.
242 (2006) predict that a visit by an average individual of an abundant species provides higher
243 benefits to their mutualistic partners than a visit by an average individual of a rare species, which
244 contradicts empirical data (Vázquez et al. 2005, Morris et al. 2010, Aizen et al. 2014). The meta-
245 analysis conducted by Vázquez et al. (2005) ‘confirms findings of previous studies suggesting
246 that the most abundant animal mutualists are not necessarily the most effective ones on a per
247 visit basis’. Paradoxically, Bascompte et al. (2006) based their prediction on Vázquez et al.
248 (2005), which is reiterated in Bascompte & Jordano (2014) as: ‘Once again, we assume that
249 dependence is a good surrogate for per-capita effect, which is justified both in mathematical
250 terms and as observed in empirical studies (Vázquez, Morris, et al. 2005a; see Chap. 4)’.
251 Unfortunately, such justification cannot be found in the cited reference. Vázquez et al. (2005)
252 found the frequency of interactions as good surrogate for **total effects** on populations but not for
253 **per-capita** effects.

254 To my knowledge, the only way to use the frequency of interaction to predict **per-capita**
255 **effects** is to know the relationship among frequency of interaction, species abundance, fitness
256 components (e.g., seed production, survival of different stages), and per-capita growth rates
257 (Vázquez et al. 2015). Moreover, the frequency of mutualistic interactions does not always
258 estimate well the **total effects** of mutualisms on populations. An increase in such frequency can
259 also negatively affect the interacting populations when the costs of the mutualisms exceed their
260 benefits (see below; Morris et al. 2010). For example, alien pollinators may increase the
261 reproduction success of native plants when moderately abundant but decrease the plant

262 reproduction when highly abundant (Aizen et al. 2014, Valdovinos et al. 2018). In addition,
263 saturating functional responses (Eq. 4 in Box 2) and adaptive foraging (Benadi & Gegeer 2018)
264 can make the net effects of mutualisms independent of the interaction frequency.

265 Another approach to conceptualizing the strength of mutualistic interactions is to
266 calculate **net effects** resulting from the **benefits** minus **costs** incurred by the interacting
267 organisms (Bronstein 1994, 2001, 2006). As defined by Holland et al. 2002, ‘benefits are goods
268 and services that organisms cannot obtain affordably, or at all, in the absence of their partner(s)’.
269 Benefits obtained through mutualistic interactions include food, transportation, and protection.
270 Costs ‘include investments in structures to attract mutualists, substances to reward them, and the
271 energy and time spent obtaining those rewards’ (Holland et al. 2002). Importantly, benefits and
272 costs of mutualisms vary depending on the abundance of the mutualistic partners as well as
273 through time and across space (Bronstein 1994, 2006), which ultimately determines the net
274 effects of a mutualism in a particular time and location. Holland et al. (2002) build on this
275 conceptualization of mutualisms to develop ecological theory that incorporates the density-
276 dependent nature of benefits and costs. More specifically, the authors develop functional
277 responses of mutualisms (i.e., per-capita benefit as a function of the abundance of the mutualistic
278 partner) as net effects resulting from different density-dependent functions (linear, unimodal,
279 saturating) of benefits and costs. Using the resultant functional responses, the authors evaluate
280 the effects of the different density-dependent functions of benefits and costs on the dynamics of
281 mutualistic systems composed by two interacting species.

282 In summary, predicting interaction strengths needs to distinguish per-capita effects
283 adjusted for species abundance from the total effects of mutualisms on populations. In addition,
284 better estimations of benefits and costs are one approach to a more clear understanding of
285 interaction strengths.

286

287 **II. Towards predicting the dynamics of mutualistic networks**

288 Research reviewed in the past section shows that species traits and abundances influence
289 the structure of mutualistic networks. This section reviews models predicting the dynamics of
290 those abundances and the effect of network structure on network dynamics. The first subsection

291 describes the assumptions and predictions of the two general frameworks used for modeling
292 population dynamics in mutualistic networks. The second subsection reviews research modeling
293 the plasticity of species interactions determined by the ability of animals to change their
294 interactions in response to changes in their resource availability.

295 **A. Population dynamics models and their predictions**

296 This subsection synthesizes the assumptions of **Lotka-Volterra type** (Fig. 1A, Box 2)
297 and **consumer-resource** (Fig. 1B, Box 3) models and explains how different assumptions
298 produce contrasting predictions on the effect of network structure on network stability (Table 1).

299 Because of their simplicity and mathematical convenience, Lotka-Volterra type models
300 have been the most commonly used models of population dynamics to study mutualistic
301 networks (Fig. 1A, Box 2). These comprise the Lotka-Volterra model of mutualism and all its
302 extensions (Boucher 1985), including replacing the linear positive effects of mutualisms (Type I
303 functional response) by saturating positive effects (Type II functional response, see Box 2).
304 Those models represent mutualistic relationships as net positive effects between species using a
305 positive term in the growth equation of each mutualist that depends on the population size of the
306 partner. However, by phenomenologically assuming net positive effects between mutualistic
307 partners, those models (a) disregard important biological processes associated with plant-animal
308 interactions that can result in negative net effects on the interacting populations (Bronstein 1994,
309 Holland et al. 2002), and (b) produce very different dynamic outputs for populations and
310 communities compared to models where the net effects are described mechanistically (Holland &
311 DeAngelis 2010, Valdovinos et al. 2016). Key processes ignored by these models include
312 visitation, feeding, and reproductive mechanisms that determine how direct interactions between
313 mutualistic partners vary through time and across densities or total abundances of the interacting
314 species (Abrams 1987, Holland & DeAngelis 2010, Valdovinos et al. 2013, Box 3).

315 Lotka-Volterra type models predict that structural properties including species richness,
316 connectance, nestedness, the asymmetry of interaction frequencies, and modularity (Box 1)
317 affect the stability of mutualistic networks. However, studies analyzing the effects of those
318 properties on network stability show contrasting results on the direction of the effects (Box 4),
319 especially for nestedness and connectance. Extensive analyses performed by Pascual-Garcia &
320 Bastolla (2017) explained the contrasting results by demonstrating that connectance always

321 increases network stability for saturating mutualisms, while the effect of nestedness depends on
322 the level of inter-specific competition among plants and animals (hereafter **intra-guild**
323 **competition**), and whether mutualisms are facultative or obligate (i.e., species persist or go
324 extinct when their partners are absent). The authors demonstrate that: 1) saturating mutualisms
325 (Eq. 4) are necessary for the system to be stable (i.e., **feasible**, Box 1), 2) *without* intra-guild
326 competition, saturating mutualisms are always stable and their **feasibility** only requires
327 mutualisms to be facultative (i.e., $r_i > 0$ in Eqs. 2-3 with Eq. 4), and 3) *with* intra-guild
328 competition, the feasibility of saturating mutualisms requires that the intrinsic growth rates (r_i in
329 Eqs. 5-6) negatively correlate with the species' number of mutualistic interactions and that the
330 ratio between plant and animal abundances (density, biomass) is higher than $2 \cdot 10^5$. In summary,
331 under the assumptions of Lotka-Volterra type models, highly connected networks of saturating
332 and facultative mutualisms exhibiting the lowest intra-guild competition are the most stable.

333 The extensive analysis conducted by Pascual-Garcia & Bastolla (2017, see above) shows
334 that nestedness is a weaker predictor for network stability than connectance, intra-guild
335 competition, and whether mutualisms are facultative or obligate, which resolves discrepancies
336 among previous studies using Lotka-Volterra type models. For example, Bastolla et al. (2009)
337 and Rohr et al. (2014) find that nestedness increases **structural stability** (Box 1) of networks
338 with saturating mutualisms and intra-guild competition because the authors assumed fully
339 connected networks and low intra-guild competition (both stabilizing), respectively. In contrast,
340 James et al. (2012) find that nestedness decreases species persistence because the authors adopt
341 similar intrinsic growth rates for all species, which is destabilizing for networks with intra-guild
342 competition (see point 3 above).

343 A more mechanistic alternative to the Lotka-Volterra type models is the consumer-
344 resource approach to mutualisms (Holland & DeAngelis 2010, Holland et al. 2005, Valdovinos
345 et al. 2013, 2016, 2018). This approach decomposes net effects assumed always positive by
346 Lotka-Volterra models (Fig. 1A) into the biological mechanisms producing those effects (Fig.
347 1B). While this approach has been applied to study pairwise interactions (Holland et al. 2005,
348 Holland & DeAngelis 2010) to my knowledge only Valdovinos et al. (2013, 2016, 2018) have
349 developed a consumer-resource model for mutualistic networks. The key advance of Valdovinos
350 et al.'s model is separating the dynamics of the plant vegetative biomass from the dynamics of

351 the plant rewards (Fig. 1B, Box 3). This separation allows: i) tracking the depletion of plant
352 rewards, ii) evaluating exploitative competition among animal species visiting the same plant
353 species, and iii) incorporating adaptive foraging (i.e., behavioral responses to resource
354 availability). Another advance of this model is incorporating the dilution of conspecific pollen
355 carried by animals, which tracks the competition among plants for the animals' pollination
356 services. That is, pollinator species assigned visits to many different plant species carry more
357 diluted conspecific pollen, which also works as a proxy for quality of visits (σ_{ij} of Eq. 8 in Box 3,
358 Fig. 1D). This model predicts that highly nested but moderately connected networks will exhibit
359 the highest **species persistence** when animals are adaptive foragers (Valdovinos et al. 2016).
360 Without adaptive foraging, however, nestedness decreases and connectance increases species
361 persistence. This is because increasing nestedness increases niche overlap among animal (Fig.
362 1C) and plant (Fig. 1D) species, and increasing connectance increases the number of food
363 sources for animals. Introducing adaptive foraging (Eq. 11 in Box 3) allows generalist pollinators
364 to partition most of their foraging effort to specialist plants (with high availability of rewards,
365 compare Figs. 2B and 2A). This partitioning stabilizes the highly nested and moderately
366 connected networks by releasing the rewards of generalist plants to specialist pollinators, and
367 increasing the quantity and quality of visits received by the specialist plants. The results and
368 equations of this model can be extended to other plant-animal mutualisms (e.g., frugivory) by
369 assuming that plant rewards represent fruits instead of floral rewards and by assuming dilution of
370 seed-dispersal services instead of dilution of pollination services.

371 In summary, Lotka-Volterra type models predict that highly connected networks of
372 saturating and facultative mutualisms exhibiting the lowest intra-guild competition are the most
373 stable, while a consumer-resource model predicts that highly nested but moderately connected
374 networks will exhibit the highest stability when animals are adaptive foragers.

375 **B. Predicting the plasticity of interactions**

376 The previous subsection synthesized two frameworks to model population dynamics, one
377 assuming static interactions (i.e., Lotka-Volterra type models) while the other allowing plastic
378 interactions (i.e., consumer-resource model by Valdovinos et al. type). This subsection
379 synthesizes studies that provide further understanding of the highly plastic nature of mutualistic
380 interactions (CaraDonna et al. 2017, Ponisio et al. 2017).

381 The plasticity of mutualistic interactions was first modeled topologically as ‘interaction
382 rewiring’, that is, by algorithmically defining which, when, and how species interactions were
383 rewired to new species (Kaiser-Bunbury et al. 2010, Ramos-Jiliberto et al. 2012). This modeling
384 was first developed to evaluate the network responses to species extinctions (see next section).
385 Kaiser-Bunbury et al. (2010) simulated interaction rewiring based on all the potential
386 interactions observed for pollinator species during a flowering season in two representative sites
387 on Mauritius Island. The authors analyzed the **robustness** to species removals (Box 1) and the
388 subsequent topological co-extinctions of 12 consecutive snapshots (2-week periods) that depicted
389 the plant-pollinator interactions recorded bi-weekly over the flowering season. The whole-season
390 network (i.e., 12 snapshots combined) was assumed to record all the potential interactions of
391 each pollinator species. That is, if a pollinator species interacted with a particular plant species in
392 the whole-season network, but was not observed visiting such species within a particular
393 snapshot, the pollinator species was assumed able to rewire any of its observed interactions to
394 that plant species. The interaction rewiring was then simulated within each of the 12 snapshots as
395 the response of pollinators to the extinction of their plant partners by reassigning those
396 interactions to the persistent plant species with which they can potentially interact (determined
397 by the whole-season network). As expected, the authors find that this rewiring algorithm
398 increases the robustness of the networks to species extinctions.

399 Ramos-Jiliberto et al. (2012) take a step forward towards predicting the plasticity of
400 mutualistic interactions by incorporating both interaction rewiring and population dynamics into
401 the analysis of the network responses to extinctions. To model population dynamics, a meta-
402 community model developed by Fortuna & Bascompte (2006, Eqs. 13-14) was used to evaluate
403 the effects of different rewiring algorithms (which and how interactions rewire) on network
404 **robustness** to species removals (Box 1). They found that interaction rewiring increases the
405 network robustness to species extinctions especially when specialist pollinators are more likely
406 to rewire their interactions, and when the rewired interactions are more likely to be connected to
407 plant species with the highest proportion of patches occupied per animal interaction. Valdovinos
408 et al. (2013) take another step forward towards predicting the plasticity of mutualistic
409 interactions by not only combining population dynamics with interaction plasticity but also more
410 explicitly modeling adaptive foraging (see previous section, Eq. 11 in Box 3). Moreover, in

411 Valdovinos et al.'s model, the plasticity of foraging efforts not only determines the presence or
412 absence of interactions but also their strength.

413 Zhang et al. (2011) also combined population dynamics and interaction rewiring but to
414 evaluate the emergence of nestedness as a consequence of adaptive foraging. The authors used a
415 Lotka-Volterra type model of saturating mutualisms without intra-guild competition (Eqs. 2-4),
416 assuming facultative mutualists (specifically with r_i between 0 and 1). Interaction rewiring was
417 implemented in each time step by randomly choosing a pollinator species that will rewire its
418 interaction with the lowest per-capita positive effect to a randomly chosen species. This model
419 starts with random networks having the species richness and connectance of empirical networks
420 as initial conditions, and converges to stable nested networks that successfully predict the
421 nestedness levels found in empirical networks. This model also predicts the asymmetry of
422 interaction frequencies, the heterogeneous degree distribution, and the positive relationship
423 between species' degree and total impacts commonly found in empirical networks (Box 1). Note
424 that these results are a reflection of previous results of Lotka-Volterra type models assuming
425 saturating facultative mutualisms without intra-guild competition (see section 3, Box 4). When
426 those types of mutualisms are assumed, nested, heterogeneous, and asymmetric networks are
427 expected to emerge with adaptive foraging because those structures are the ones providing the
428 highest benefits per species. Suweis et al. (2013) confirm this result using an optimization
429 principle that maximizes species abundance. The authors demonstrate analytically and
430 numerically that because of the assumed positive net effects between mutualistic species,
431 increasing the abundance of a particular species increases both the networks' nestedness and the
432 total species abundance. In fact, their optimization algorithm also predicts the emergence of
433 nested networks.

434 In summary, research modeling interaction plasticity as responses to resource availability
435 shows that plastic interactions stabilize mutualistic networks and may predict their structure.

436

437 **III. Towards predicting the responses of networks to global change**

438 Global environmental changes threatening mutualistic networks include species
439 extinctions, climate change, habitat loss, and species invasions (Goulson et al. 2015, Ollerton

2017). This final section synthesizes recent research that uses knowledge of the network structure and dynamics reviewed in the last two sections for predicting the response of networks to global environmental changes.

A. Species extinctions and topological co-extinctions

Memmott et al. (2004) simulated species extinctions by removing the respective nodes from networks and evaluated the subsequent co-extinctions caused by those extinctions based only on the binary structure of the networks, but ignoring species abundances, population dynamics, and interaction plasticity. The authors used this approach to evaluate the effect of the structure of two empirical plant-pollinator networks on their **robustness** against species extinctions (Box 1). The authors simulated pollinator extinctions by removing the corresponding nodes from the network, with the consequent loss of plant species that only interacted with the removed pollinator species. Such models assume that species completely depend on their mutualistic partners to persist and that organisms of those species do not respond to the extinction of their mutualistic partners by rewiring their mutualistic interactions to other species.

This topologically-determined approach to co-extinctions inevitably shows that increasing **connectance** increases the robustness of mutualistic networks to species extinctions due to an increased redundancy of interactions. In addition, increasing **nestedness** consistently increases network robustness to random extinctions and the extinction of the most specialist (i.e., least connected) species. The former is explained by the latter because random extinctions will more likely draw on specialist than on generalist species given that specialists are more frequent than generalists in the nested networks observed for empirical systems (Bascompte & Jordano 2007, 2014). Nested networks are robust to the extinction of specialist species because in those networks specialist species tend to interact with the most generalist (i.e., most connected) species that usually will not go extinct after the extinction of one of their specialist partners. Nested networks, however, are very fragile to the extinction of the most connected species, which usually produces the co-extinction of many specialist species.

B. Species extinctions and stochastic co-extinctions

An alternative approach to the one used by Memmott et al. relaxes the assumption that co-extinctions require the loss of all mutualistic partners (Vieiria et al. 2013). Vieira and

469 coworkers proposed a stochastic model for determining the probability of species i going extinct
470 following the extinction of species j , $P_{ij} = R_i d_{ij}$, as the product between the intrinsic dependence
471 of species i on mutualisms to persist, R_i , and the realized **dependence** of species i on species j , d_{ij}
472 (Box 1). Under this model, species can go extinct even when still connected with persistent
473 species. As a result, increasing connectance decreases network robustness to extinctions by
474 increasing the pathways for the effects of primary extinctions to propagate (Vieiria et al. 2013,
475 Vieiria & Almeida-Neto 2015).

476 **C. Species extinctions and population dynamics**

477 A more mechanistic approach considers population dynamics to evaluate the co-
478 extinctions caused by species removals. For example, Ramos-Jiliberto et al. (2009) simulated the
479 extinction of different plant and animal species of an empirical plant-pollinator network by
480 removing the respective nodes and evaluated the impact of those extinctions on the dynamics of
481 the remaining species. In another example, Valdovinos et al. (2009) simulated the removal of all
482 alien plant species from an empirical network, finding that such a restoration practice could
483 actually harm the native species when alien species are well integrated in the network. In those
484 two examples, as in the ‘stochastic co-extinctions’ (see previous sub-section), the co-extinctions
485 caused by the species removals could occur even when all the mutualistic partners of a species
486 did not go extinct. When simulating population dynamics, co-extinctions can also happen when
487 the benefits of the mutualisms do not compensate for the mortality rates of the interacting
488 populations.

489 **D. Species extinctions and plastic interactions**

490 Overall, studies modeling the plasticity of interactions (see previous section) predict that
491 such plasticity increases the robustness of networks to species extinctions in comparison to the
492 case of fixed interactions (Kaiser-Bunbury et al. 2010, Ramos-Jiliberto et al. 2012, Valdovinos et
493 al. 2013). Those studies reached the same conclusion even when their approaches were very
494 different. Kaiser-Bunbury et al. (2010) simulated interaction rewiring based on all the potential
495 interactions observed for pollinator species during a flowering season, but disregarded species
496 abundances and population dynamics. Therefore, co-extinctions only occurred when all the
497 mutualistic partners of a species went extinct, which overestimates network robustness. Ramos-
498 Jiliberto et al. (2012) incorporated both interaction rewiring and population dynamics into the

499 analysis of the network responses to extinctions, which makes co-extinctions more realistic.
500 Finally, Valdovinos et al. (2013) also incorporated population dynamics, but took a consumer-
501 resource approach (Box 3) in which the plasticity of foraging efforts determined the weights of
502 the links (i.e., interaction strengths), as opposed to the binary approach taken in modeling the
503 rewiring of interactions.

504 **E. Climate change**

505 Memmott et al. (2007) evaluated the potential effect of phenological shifts caused by
506 climate change on mutualistic networks by simulating early first flowering and onset of the flight
507 season of plant and pollinator species, respectively, predicted as responses to increased
508 temperatures. The authors evaluated the effect of those phenological shifts on the availability of
509 flowers and pollinator activity for a highly resolved empirical network, predicting that 17-50% of
510 pollinator species would exhibit temporal gaps in their food supply because of the increased
511 temperatures. The authors proposed that this reduction in temporal overlap between flowers and
512 active pollinators will increase the extinction risk of the species in the network, particularly for
513 the more specialized pollinators with small diet breadths. It would be interesting to re-evaluate
514 those predictions assuming interaction plasticity.

515 **F. Habitat loss**

516 Fortuna & Bascompte (2006) evaluated the response of mutualistic networks to habitat
517 loss by developing a metacommunity model that simulates habitat loss as the destruction rate of
518 available patches (parameter d in Eq. 13 of Box 3). The authors calculated the fraction of extinct
519 species caused by increasing levels of such destruction rate on nested and random networks.
520 Their model predicts that nested networks would be less resistant to habitat loss (i.e., exhibit
521 higher fractions of extinct species) than random networks at lower rates of patch destruction, but
522 more resistant than the random networks at higher rates of patch destruction.

523 **G. Species invasions**

524 Valdovinos et al. (2018) use the consumer-resource model (Box 3) to develop a
525 mechanistic framework to predict the invasion success of pollinator introductions and the
526 networks' responses to pollinator invasions. We introduced pollinator species with different
527 foraging traits (i.e., level of generality, foraging efficiency, and fixed vs adaptive foragers) into

528 networks with different levels of species richness, connectance, and nestedness. Among 31
529 factors tested for the 43200 simulated introductions, we found that aliens with high foraging
530 efficiency were the most successful invaders, while networks with higher diet overlap between
531 alien and native pollinators were more impacted by invaders. In terms of the response of the
532 native pollinators exhibiting adaptive foraging, we predict that those pollinators will persist in
533 lower abundances by reassigning their visits to plants that are not visited by the invader, while
534 native pollinators without alternative resources will go extinct (Fig. 3).

535 **H. Perturbations altering interaction strengths**

536 The studies described above explicitly modeled the type of perturbation affecting
537 networks. For example, node removals and introductions modeled species extinctions and
538 invasions, respectively. Phenological shifts simulated the effect of climate change, while patch
539 destruction simulated habitat loss. In contrast, Saavedra et al. (2013) evaluated the general
540 response of mutualistic networks to any type of perturbation that alters the interaction strength of
541 mutualisms. Specifically, they simulated changes in interaction strengths by systematically
542 varying the values of the parameters defining those strengths (i.e., b_{ij}^A and b_{ji}^P of Eq 5-6 in Box
543 2) in the Lotka-Volterra type model with direct intra-guild competition and saturating
544 mutualisms. The networks' response to such perturbation was quantified as the amount of change
545 in interaction strength that each species was able to sustain before going extinct. The authors also
546 evaluated whether the tolerance of species to such change correlated with species degree and
547 contribution to nestedness (Box 1), without finding any significant relation. Species' tolerance
548 was very sensitive to the sign of the change in interaction strength and to the trade-offs between
549 the number of partners and the strength of the interactions (Eq. 7 in Box 2).

550

551 **Discussion**

552 Qualitative predictions made by mathematical models have shaped much of our
553 understanding in Ecology. This started with predictions made by the simple Lotka-Volterra
554 model on competitive exclusion (Gause 1932) and predator-prey cycles (Solomon 1949),
555 followed by the paradoxes of enrichment (Rosenzweig 1971) and biological control (Luck 1990,
556 Arditi & Berryman 1991) predicted by the Rosenzweig-MacArthur (1963) model. Later

557 predictions included indirect effects in trophic interactions such as apparent competition (Holt
558 1977) and the stabilizing effect of weak interactions in food webs (McCann et al. 1998). Finally,
559 more recent predictions are made by the Allometric Trophic Network model on predator-prey
560 body size ratios (Brose et al. 2006), interaction strengths (Berlow et al. 2009), and the relative
561 biomasses of species in a lake (Boit et al. 2012). These predictions have guided much empirical
562 research and provided general understanding that ecologists use to explain how ecological
563 systems behave and would respond to perturbations including global change. Notoriously, most
564 of those predictions concern antagonistic interactions, leaving mutualistic interactions
565 understudied, which is unfortunate given the relevance of mutualisms for terrestrial biodiversity
566 (Thompson 1994) and human food security (Potts et al. 2016, Ollerton 2017). In this work, I
567 describe predictions in the ecological literature of mutualistic interactions with a particular focus
568 on mutualistic networks.

569 Table 1 summarizes the qualitative predictions reviewed in this work together with the
570 type of empirical data already used (or to be collected) to test those predictions. I find that
571 models incorporating biological mechanisms that empirical research has shown to determine
572 mutualistic interactions produce predictions that can be better tested against empirical data,
573 compared to the more phenomenological models (e.g., Lotka-Volterra type). Those mechanisms
574 include trait matching (Jordano 2016, Bartomeus et al. 2016), the consumption of resources
575 provided by the mutualisms (Holland & DeAngelis 2010, Valdovinos et al. 2013, 2016),
576 adaptive foraging, and the dynamics of reproductive services (Valdovinos et al. 2013, 2016,
577 Benadi & Gegeer 2018). For example, trait matching can predict who interacts with whom given
578 species co-occurrence (Bartomeus et al. 2016), while adaptive foraging can predict the effort that
579 an average individual of a population partitions to each of those interactions (Valdovinos et al.
580 2016). Moreover, modeling benefits and costs of mutualisms can predict the functional responses
581 of mutualistic interactions (Holland et al. 2002, Morris et al. 2010). I also find that several
582 modeled mechanisms or potential biases (i.e., incomplete sampling, species abundances and
583 traits, Table 1) successfully predict the observed **structure** of mutualistic networks. Therefore,
584 further empirical research (including manipulative experiments) is needed to disentangle the
585 actual mechanisms versus the artefacts producing those structures. For example, measurements
586 of species abundances independent of visitation data (e.g., Brosi & Briggs 2013, Valdovinos et
587 al. 2016) can distinguish the relative effects of incomplete sampling, individuals' foraging

588 preferences, and species traits. In addition, measuring species traits more systematically and
589 analyzing their effects on species interactions (number and identity) can distinguish between the
590 effects of species traits and incomplete sampling in structuring mutualistic networks (Fründ et al.
591 2016).

592 Producing empirical data to test model predictions on network **dynamics**, however, is
593 more challenging. In particular, testing model predictions on the effect of network structure on
594 the stability of ecological systems (e.g., species persistence, local stability, resilience, see Box 1)
595 seems difficult unless working with very long-term data-sets or systems with very fast generation
596 times (Table 1). In fact, this difficulty of collecting empirical data to answer questions on long-
597 term dynamics is one of the main reasons for using mathematical models in ecology because
598 models can provide those answers where most empirical data cannot. Nevertheless, there is a
599 way to connect short-term (hours/days/months) empirical data with long-term
600 (decades/centuries) model predictions. More mechanistic models (e.g., Valdovinos et al. 2016,
601 Benadi & Gegeer 2018) not only make predictions of long-term processes such as stability but
602 also of short-term processes that can be assessed empirically. Then, the specifics of those
603 processes empirically tested can be linked back to network stability using the mathematical
604 model. For example, Valdovinos et al. (2016) predict that generalist pollinators (per-capita)
605 behaviorally prefer specialist plants, which was empirically corroborated with a plant-pollinator
606 system in the Colorado Rockies. Then, such preferences were shown to determine the long-term
607 stability of networks via partitioning niches between generalists and specialists for both animal
608 and plant species.

609 A key to this research is the use of networks to study ecological systems. Networks
610 provided tractability to the study of complex, multi-species systems of several tens to hundreds
611 of interacting species. That is, the early descriptive metrics on network structure (reviewed in
612 Dunne 2006, Bascompte & Jordano 2007) provided a general picture of how species interactions
613 are organized in complex communities. From that picture, we can model the population
614 dynamics of each species dependent on the interactions described by the network structure and
615 further ask about the dynamic consequences of such structure. This earned tractability in the study
616 of complex multi-species systems substantially advances our ability to predict ecological
617 dynamics. Ecology has learned much from studying modules of a few interacting species in

618 isolation from their entangled bank, but we also need to understand the dynamics of the
619 entangled bank itself, especially if we want to predict the response of ecological systems to
620 global change.

621 One of the main limitations of ecological networks, however, is a need for large amounts
622 of empirical data to parameterize models and test their predictions. Nevertheless, there are some
623 ways around this limitation. For example, Brose et al. (2004) used the bioenergetic model of
624 Yodzis & Innes (1992) and its parameterization based on allometric scaling to successfully
625 parametrize complex food webs of several tens of species. Then, Boit et al. (2012) used such
626 model and parameterization to successfully predict the relative biomasses of 25 trophic groups in
627 Lake Constance, leveraging 20 years of empirical data on abiotic and biotic factors including
628 species biomasses. In mutualistic networks, much needs to be done to parameterize models based
629 on empirical data. We still need to find those empirical patterns like the allometric scaling in
630 aquatic food webs to parameterize our models. As discussed above, more mechanistic models
631 can also help in this endeavor by connecting short-term processes that can be measured in the
632 field with long-term processes that can be investigated using models. In addition, our discipline
633 requires more centralized, systematic empirical data across long-enough temporal series,
634 allowing for cross-model comparison.

635 Based on 20 years of theoretical advances reviewed here, I think the most promising path
636 to develop theory capable of predicting (Houlahan et al. 2017) how networks respond to global
637 change is incorporating the key biological mechanisms determining mutualistic interactions. In
638 particular, I propose that theory based on species traits can predict the potential structure of the
639 networks (fundamental niche) while theory based on the dynamics of species abundances,
640 rewards, foraging preferences and reproductive services can predict the extremely dynamic
641 realized structures of networks and may successfully predict their responses to perturbations.
642 Recent work proposes a similar approach for the study of restoration ecology (Raimundo et al.
643 2018), where ‘adaptive network models’ combined with ‘phylogenetically-structured network
644 data’ could play an important role in predicting the outcome of restoration practices based on the
645 interplay among rapid trait evolution, species abundances, and species interactions. Key to the
646 development of such predictive theory is a deep integration between empirical and theoretical
647 research. Theoretically-oriented empirical work should provide biological mechanisms and

648 parameter values to inform mathematical models, while the predictions of empirically-informed
649 mathematical models should be tested with new empirical data.

650

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658

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877 **Table 1. Summary of modeling approaches and predictions reviewed in this study.** Includes empirical data needed or already
 878 used to test the models' predictions. The abbreviations **long-time/short-gen*** and **already-tested*** stands for “requires data at very
 879 long time scales or system with very short generational time” and “already tested against empirical data”, respectively.

Modeling approach	Prediction	Empirical data needed	References
<i>First section: Predicting network structure</i>			
Interaction constraint models	Network structure is the product of various interaction constraints, e.g., temporal/spatial uncoupling, trait mismatches, physiological/ biochemical barriers.	Already-tested*: interaction constraints predict absence of interactions between specialists, heterogeneous degree distribution, and moderate network connectance. <u>Still</u> research is needed to more systematically relate species traits with network structure.	Santamaría & Rodríguez-Gironés 2007. e.g., Bartomeus et al. 2016.
Neutral (sampling artefact): incomplete sampling of interactions, skewed abundances, and fully generalized systems	Network structure results from incomplete sampling effort failing to record the interactions of rare species. Network structure is independent of species differences in traits.	Already-tested*: incomplete sampling of interactions, skewed species abundances, and fully generalized systems produce observed structure. <u>Still</u> needs to be tested with independent measures of plant and animal abundances (i.e., not estimated from interaction frequencies).	Blüthgen et al. 2007, 2008 e.g., Brosi & Briggs 2014, Valdovinos et al. 2016.

Niche-based: disentangles species' abundances and generality level (i.e., number of interactions)	Sampling bias overestimates specialization in generalized networks but not necessarily in more specialized networks.	Already-tested*: model distinguishes the relative effects of species abundances and trait differences on predicting network structure. <u>Still</u> needs to be tested with independent measures of abundances and systematic analysis of species traits.	Fründ et al. 2016
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Second section: Predicting network dynamics

Lotka-Volterra type models	Highly connected networks of facultative mutualisms exhibiting the lowest within-guild competition will be the most stable networks. Effect of nestedness on stability depends on the parameter values assumed.	Long-time/short-gen* . Might be tested with time-series of plant and animal population across decades. Their assumptions (e.g., functional responses, Box 2) <u>still</u> need to be tested with empirical data.	Pascual-Garcia & Bastolla 2017
Consumer-resource: floral rewards dynamics, adaptive foraging, conspecific pollen dilution.	Adaptive foraging reverses the destabilizing effect of nestedness on species persistence and the stabilizing effect of connectance by partitioning niches among plant species (pollination	<u>Species persistence:</u> long-time/short-gen* . <u>Niche partitioning</u> (short-term): already tested with data on foraging efforts. <u>Still</u> needs to be tested with data on pollination	Valdovinos et al. 2013, 2016, 2018.

	services) and among animal species (floral rewards).	success, floral rewards, functional responses and benefit accruals.	Valdovinos et al. 2016
	On a per-capita (plant and animal) basis, generalist pollinator species prefer specialist plant species.	Already-tested* with empirical foraging efforts standardized by abundance of plants and animals	
Interaction plasticity based on adaptive foraging	Interaction plasticity increases network robustness against species extinctions in comparison to the case of fixed interactions	Behavioral responses at short time scales. Can be tested using manipulative experiments in the field.	Kaiser-Bunbury et al. 2010, Ramos-Jiliberto et al. 2012, Valdovinos et al. 2013.
	Nestedness emerges as a result of adaptive foraging	Long-time/short-gen*	Zhang et al. 2011, Suweis et al. 2013.
Functional responses as net effects: benefits minus costs experienced by the interacting organisms	How benefits/costs of mutualisms vary with species density will affect their stability. Net effects likely follow a saturating or unimodal function with species density.	Already fitted net-benefit curves to measures of plant reproductive success. <u>Still</u> need curves to be fitted to measures of animal reproductive success.	Holland et al. 2002, Morris et al. 2010, Vázquez et al. 2012

Individual based model: adaptive foraging, pollen transfer and floral rewards	Adaptive foraging favors pollination of the least-abundant plant species at high flower abundances. Least-abundant plant species will benefit more from offering higher levels of floral rewards than the most-abundant plant species.	<u>Still</u> needs to be tested with independent measures of population abundances, reproductive success, and floral rewards offered by an average plant of each population.	Benadi & Gegear 2018
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Third section: Predicting network responses to global change

Species extinctions and <u>topological</u> co-extinctions	Nested networks are robust to specialists' but fragile to generalists' extinctions. Increasing connectance <u>increases</u> network robustness to extinctions.	Long-time/short-gen*	Memmott et al. 2004
Species extinctions and <u>stochastic</u> co-extinctions	Increasing connectance <u>decreases</u> network robustness to extinctions.	Long-time/short-gen* . To be tested with independent measures of total impacts of mutualisms.	Vieiria et al. 2013, Vieiria & Almeida-Neto 2015.
Species extinctions and <u>dynamic</u> co-extinctions	Extinction of trees or hymenopterans will make the studied pollination network collapse.	Long-time/short-gen*	Ramos-Jiliberto et al. 2009

	Removal of all alien plants harm native species when the alien plants are well integrated into the network.	<u>Still</u> needs to be tested by cutting the flowers of alien plants and evaluating the response of native pollinators	Valdovinos et al. 2009
Phenological shifts driven by climate change	17-50% of pollinator species would exhibit temporal gaps in their food supply due to increased temperatures	<u>Still</u> needs to be tested with phenological data of plants and pollinators across several years in a particular system.	Memmott et al. (2007)
Habitat loss as patch destruction	Nestedness decreases network resistance to habitat loss at low patch destruction but increases it at high patch destruction rates.	Long-time/short-gen*	Fortuna & Bascompte (2006)
Species invasions as node introduction	Highly efficient foragers will likely invade networks, while networks with higher diet overlap between aliens and natives will be highly impacted by invaders.	The impact on natives <u>still</u> needs to be tested by measuring the distribution of floral rewards and visits in systems with and without invasive pollinators.	Valdovinos et al. (2018)
Altering interaction strengths in Lotka-Volterra type model with direct intra-guild competition, saturating	Species' tolerance to changing in interaction strengths not determined by species' degree or contribution to nestedness. Species' tolerance very sensitive to the sign of the change in	Highly phenomenological. Difficult to infer what to measure in the field to test predictions of this type of modeling.	Saavedra et al. (2013)

mutualisms, and trade-offs interaction strength and to the trade-offs
(Eq. 7 in Box 2) between the number of partners and the
strength of the interactions.

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881 **Figure legends**

882 **Figure 1. Illustration of Lotka-Volterra type (A) and Valdovinos et al.'s consumer-resource**

883 **(B) models.** **A** illustrates the key assumption of Lotka-Volterra type models (Box 2), i.e.,
 884 mutualist partners always positively affect each other (indicated by a circled 1, in a linear Eqs. 2-
 885 3 or saturating Eq. 4 way), which results in species of the same guild benefiting each other
 886 indirectly via sharing the same mutualistic partners (indicated by 2). Some models also
 887 incorporate direct competition (independent of mutualistic interactions) among all species of the
 888 same guild (i.e., intra-guild competition in plants or animals indicated by 3, Eqs. 5-6). **B**
 889 illustrates how Valdovinos et al. model (Box 3) decomposes net effects of mutualisms into two
 890 key mechanisms: consumption of floral rewards (indicated by 'Consumption', Eqs. 9 and 10)
 891 and pollination services (indicated by 'Pollination', Eq. 8). The model separates the dynamics of
 892 the plant vegetative biomass (Eq. 8) from the dynamics of floral rewards (red rectangles, Eq. 9),
 893 connecting them by the plant production of rewards (indicated by 'Production', parameter β of
 894 Eq. 9). Adaptive foraging (Eq. 11) allows pollinators to assign higher foraging effort (thicker
 895 arrow) to plant species with higher floral rewards (larger rectangle). **C** illustrates the high niche
 896 overlap among pollinator species that share floral rewards (follow thicker lines) of the most-
 897 generalist plant species (indicated by the red arrow) in a nested network. **D** illustrates the high
 898 niche overlap among plant species that share pollination services (follow thicker lines) of the
 899 most-generalist pollinator species (indicated by the red arrow) in a nested network. This model
 900 also assumes that the conspecific pollen is diluted in the body of generalist pollinators (see
 901 function σ_{ij} in Eq. 8).

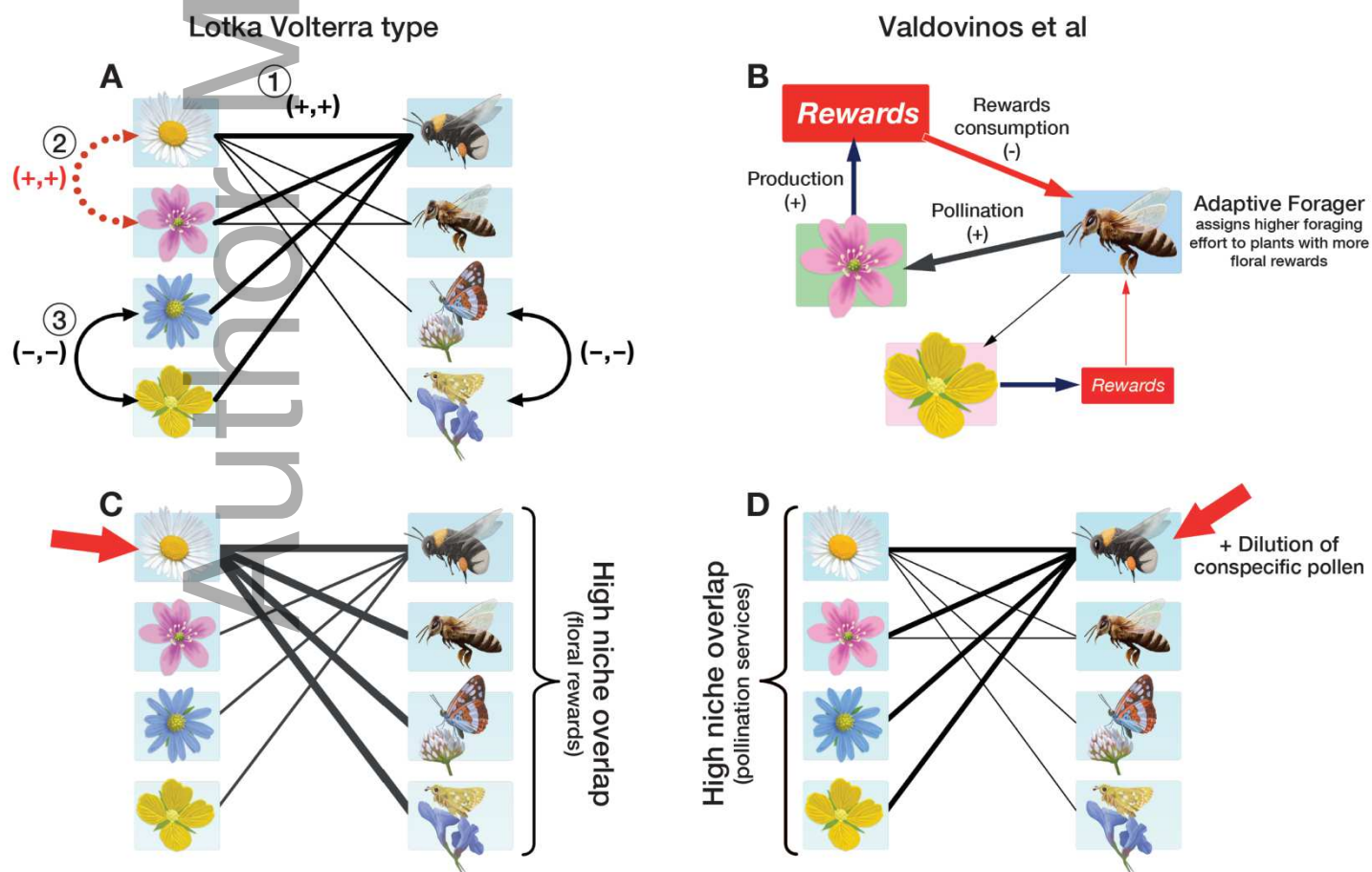
902 **Figure 2. Results of Valdovinos et al. consumer-resource model for nested networks. A**

903 without adaptive foraging, pollinator species partition the same foraging effort to each of their
 904 plant species (follow the width of the lines for each pollinator species, see Eq. 12 in Box 3),
 905 which results in generalist plant species (top right) receiving more visits than specialists (bottom
 906 right). This results in generalist plants having lower floral rewards than specialists do (red bars).
 907 In this scenario, specialist plant and animal species can go extinct because specialist plants
 908 receive very few and low quality visits while specialist pollinators have access to very low floral
 909 rewards and starve. **B** with adaptive foraging, generalist pollinator species (top left) partition
 910 higher foraging effort on specialist plant species (bottom right, follow thick line) which releases

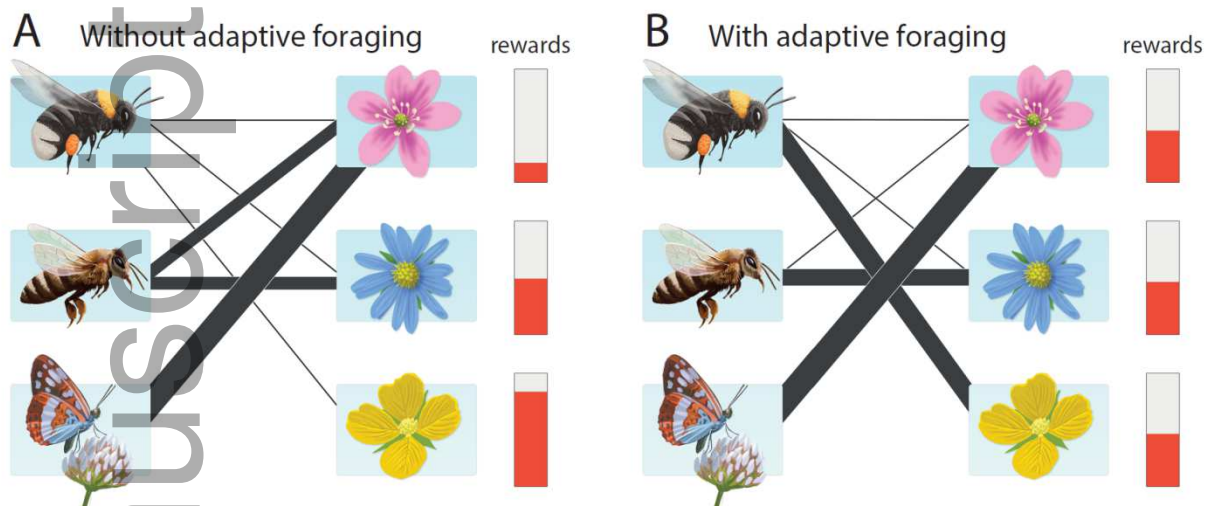
911 the rewards of generalist plant species now consumed by the specialist pollinators. In this
 912 scenario, specialist species persist because specialist plants receive more and higher quality of
 913 visits by generalist pollinators and specialist pollinators have enough food to persist.

914 **Figure 3. Predicting the response of mutualistic networks to species invasions** (results of
 915 Valdovinos et al. 2018). On the left panel, an alien pollinator species invades a plant-pollinator
 916 network and forages on the most generalist (top right) and most specialist (bottom right) plant
 917 species. This invasion drives extinct the native pollinator species (bottom left) that only forages
 918 on resources shared with the invasive pollinator, in this case, the most-generalist plant species.
 919 On the right panel, native pollinator species that have alternative resources (blue flower in the
 920 middle, not shared with the alien) can persist by shifting their foraging efforts to the plant species
 921 not visited by the alien. These native pollinators, however, decrease in abundance (smaller
 922 animal size) because they are obligated to forage on a less preferred resource (i.e., less
 923 profitable).

924 **Figure 1**



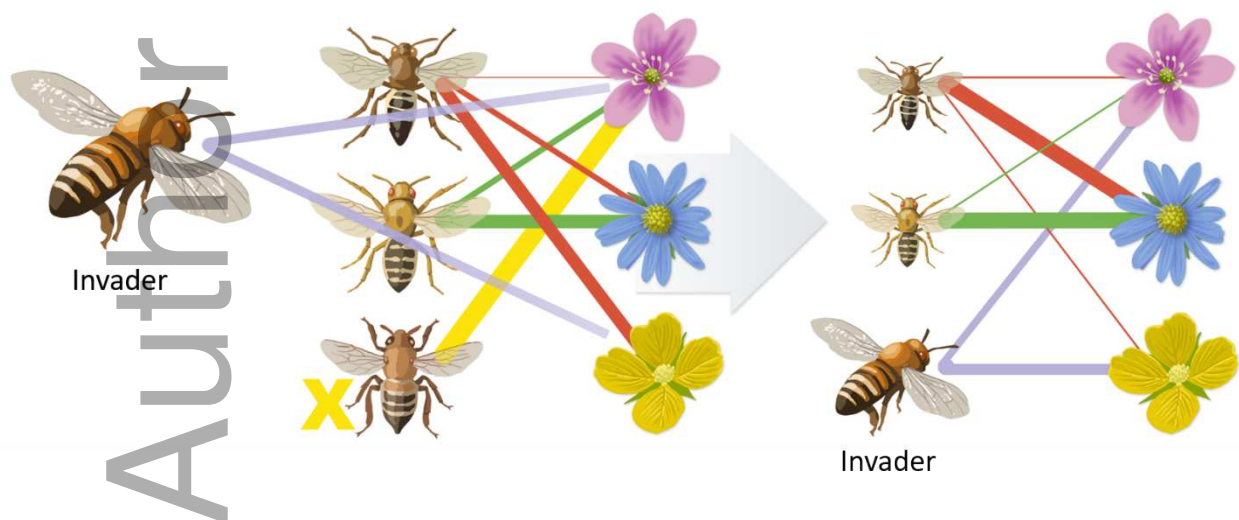
925

926 **Figure 2.**

927

928

929

930 **Figure 3.**

931

932 **Box 1: Glossary of terms commonly used in the study of mutualistic networks**

933 **Mutualistic network:** Ecological network in which one class of nodes represents one type of
 934 species (e.g., plants) and the other class represents another type of species (e.g., pollinators),

935 while links connecting nodes of the two different classes represent the mutualistic interactions
 936 (e.g., pollination, Fig. 1A).

937 **Binary structure** (also called **network topology**): Set of species (represented by nodes) and the
 938 architecture of species interactions (represented by links connecting the interacting species).

939 **Species richness (S)**: Total number of species in the network, $S = P + A$, where P and A are total
 940 number of plant and animal species, respectively.

941 **Connectance (C)**: Fraction of potential interactions that are realized, $C = L / (P * A)$ where L is
 942 the number of realized interactions (links connecting species).

943 **Degree**: The total number of interactions for a single species

944 **Heterogeneous degree distribution**: Most species have one or a few interactions (specialists)
 945 and a few species have most of the interactions in the network (hyper-generalists).

946 **Nestedness**: Tendency of the interactions of the most specialist species to be subsets of the
 947 interactions of the most generalist species. Also defined as the tendency of species with fewer
 948 interactions (specialists) to interact with subsets of the mutualistic partners of species with more
 949 interactions (generalists).

950 **Interaction asymmetry**: Tendency of the interaction pairs between species that contain one
 951 strong interaction strength to be accompanied by a weak interaction strength.

952 **Modularity**: Network compartmentalization into modules, whose species interact more among
 953 them than with species belonging to other modules.

954 **Dependence**: Measure of the relative dependence of one species (i) on another (j) calculated as
 955 the fraction of i 's total interactions with species j . For example, if a pollinator species only visits
 956 one plant species, the pollinator's dependence on that plant species is 1 (complete), but the plant
 957 species depends less on that pollinator species if the plant species is also visited by other
 958 pollinator species.

959 **Feasibility**: All species exhibit stationary abundances that are non-zero and positive, i.e., none of
 960 the species in the network go extinct (complete species persistence).

961 **Local equilibrium:** State at which all abundances stay the same unless perturbed.
 962 Mathematically, species abundances at which all the dynamic equations are 0 (no change in
 963 abundance).

964 **Local stability:** Measures the tendency of a system to return to equilibrium after small
 965 perturbations. Mathematically, an equilibrium point is stable if all the eigenvalues of the
 966 corresponding Jacobian matrix evaluated at the equilibrium point have negative real parts.

967 **Structural stability:** Local stability with respect to modifications in the parameters of a dynamic
 968 model. A system is more structurally stable if it can endure larger changes in parameter values
 969 without exhibiting species extinctions. Usually represented as the volume in parameter space
 970 compatible with positive abundances at the equilibrium point.

971 **Resilience:** Return rates to an equilibrium point following a perturbation.

972 **Robustness:** Network resistance to the loss of species caused by species extinctions.

973 **Species persistence:** Fraction of initial species that persist until the end of a simulation. In
 974 systems exhibiting equilibrium, persistence is the fraction of initial species surviving after the
 975 system has reached its equilibrium.

976

977

978 **Box 2. Lotka-Volterra-type models of mutualistic networks**

979 The Lotka-Volterra type models of mutualistic networks can be organized along a
 980 continuum of complexity. The first type of model in ascending order of complexity does not
 981 simulate population dynamics but uses a ‘community matrix’ \mathbf{A} (the Jacobian matrix evaluated at
 982 an equilibrium point) to describe and analyze a system of n interacting species. The $n \times n$
 983 elements of \mathbf{A} , α_{ij} , characterize the effect of species j on species i near an equilibrium. This
 984 approach analyzes the stability of such an equilibrium using the Taylor series in its neighborhood
 985 (May 1973), characterized by the equation:

$$986 \quad \frac{d\mathbf{N}}{dt} = \mathbf{A}\mathbf{N} \quad (1)$$

987 where N is the $n \times 1$ vector of species populations. The system (Eq. 1) is locally stable if all the
 988 eigenvalues of A have negative real parts. In locally unstable systems, even infinitesimal
 989 perturbations cause the system to move away from equilibrium, potentially leading to the loss of
 990 species (May 1973). Allesina & Tang (2012) extended the stability criterion proposed by May
 991 through constructing community matrices that represent more defined interactions (e.g.,
 992 predator-prey, mutualistic, or competitive; in contrast to interaction signs drawn completely at
 993 random) and more realistic network structures (i.e., reflecting some of the properties observed in
 994 empirical networks).

995 The community matrix (Eq. 1) is also a linearization of the Lotka-Volterra model at an
 996 equilibrium point (Kot 2001), such as the model used by Bascompte et al. (2006):

$$997 \quad \underbrace{\frac{dN_i^P}{N_i^P dt}}_{\text{per-capita growth of plant sp } i} = \underbrace{r_i^P - s_i^P N_i^P}_{\text{intrinsic asymptotic growth}} + \underbrace{\sum_{j=1}^n \alpha_{ij}^A N_j^A}_{\text{gain from mutualistic interactions}}$$

998 (2)

$$999 \quad \underbrace{\frac{dN_j^A}{N_j^A dt}}_{\text{per-capita growth of animal sp } j} = \underbrace{r_j^A - s_j^A N_j^A}_{\text{intrinsic asymptotic growth}} + \underbrace{\sum_{i=1}^m \alpha_{ji}^P N_i^P}_{\text{gain from mutualistic interactions}}$$

1000 (3)

1001 which defines the per-capita population growth rate of each plant (P) species i and animal (A)
 1002 species j as function of their intrinsic growth rate, r_i^P and r_j^A , intraspecific competition, s_i^P and s_j^A ,
 1003 and gain from each mutualistic interaction, respectively. This model assumes that the average
 1004 individual of one mutualistic partner always benefits an average individual of the other
 1005 mutualistic partner (indicated by 1 in Fig. 1A) at the same magnitude, α_{ij}^A or α_{ji}^P , regardless of
 1006 the abundance of the interacting populations. In other words, mutualistic species linearly increase
 1007 their abundance with the increase in abundance of their mutualistic partners (i.e., Type I
 1008 functional response).

1009 Next in model complexity, Holland et al. (2005) and Okuyama & Holland (2008)
 1010 incorporated nonlinear functional responses to the model used by Bascompte et al. (2006), in
 1011 which the beneficial effects of one species on another (i.e., α_{ij}^A and α_{ji}^P in Eqs. 2 and 3,
 1012 respectively) saturate with increasing population size of the mutualistic partners as:

1013
$$\alpha_{ij}^A = \frac{b_{ij}}{1 + h_{ij}b_{ij}N_j^A}, \quad \alpha_{ji}^P = \frac{b_{ji}}{1 + h_{ij}b_{ji}N_i^P} \quad (4)$$

1014 where h_{ij} is the handling time of the Type II functional response. Modeling saturating benefits of
 1015 mutualistic interactions (as opposed to linear benefits) constitutes an advance in biological
 1016 realism of the model (Holland et al. 2005, Morris et al. 2010). Bastolla et al. (2009) added intra-
 1017 guild competition to the saturated mutualisms model (indicated by 3 in Fig. 1A), where each
 1018 species competes with all other species in its guild (plants or animals), as follows:

1019
$$\underbrace{\text{per-capita growth of plant sp } i}_{\frac{dN_i^P}{N_i^P dt}} = \underbrace{\text{asymptotic growth} - \text{intra.guild.competition}}_{r_i^P - \sum_{k=1}^m s_{ik}^P N_k^P} + \underbrace{\text{gain from mutualism}}_{\sum_{j=11}^n \frac{b_{ij}^A N_j^A}{1 + h_{ij}b_{ij}N_j^A}}$$

1020 (5)

1021
$$\underbrace{\text{per-capita growth of animal sp } j}_{\frac{dN_j^A}{N_j^A dt}} = \underbrace{\text{asymptotic growth} - \text{intra.guild.competition}}_{r_j^A - \sum_{k=1}^n s_{jk}^A N_k^A} + \underbrace{\text{gain from mutualism}}_{\sum_{i=11}^m \frac{b_{ji}^P N_i^P}{1 + h_{ij}b_{ji}N_i^P}}$$

1022 (6)

1023 where s_{ik}^P (s_{jk}^A) is the interspecific competition coefficient that defines the negative effect of
 1024 species k on species i (j) which also defines the intraspecific competition when $k = i$ ($k = j$). The
 1025 last variation to this Lotka-Volterra type model was made by Rohr et al. (2014) who modified
 1026 the parameters b_{ij}^A and b_{ji}^P in Eqs. 5-6 to:

1027
$$b_{ij}^A = b_{ji}^P = \frac{b_0 y_{ij}}{k_i^\delta} \quad (7)$$

1028 where $y_{ij} = 1$ if species i and j interact and zero otherwise, k_i is the number of interactions of
 1029 species i , b_0 represents the level of mutualistic strength, and δ corresponds to the mutualistic
 1030 trade-off. The mutualistic trade-off modulates the extent to which a species that interacts with
 1031 few other species does it strongly, whereas a species that interacts with many partners does it
 1032 weakly.

1033

1034 **Box 3. Valdovinos et al.'s consumer-resource model and Fortuna & Bascompte's**
 1035 **metacommunity model.**

1036 The Valdovinos et al. (2013) model recognizes a common characteristic of all
 1037 mutualisms: the gathering of resources by organisms of one species through the interaction with
 1038 organisms of another species that benefit from the interaction. The key advance of this model is
 1039 separating the dynamics of the plants' vegetative biomass from the dynamics of the plants'
 1040 rewards (Fig. 1B). This separation allows tracking the rewards depletion by animal consumption
 1041 (indicated by 'Consumption' in Fig. 1B) separately from the animal contribution to plants'
 1042 population via reproductive services (indicated by 'Pollination' in Fig. 1B). Focusing on plant-
 1043 pollinator networks, this model tracks plant population growth separate from floral-rewards
 1044 dynamics as:

$$1045 \quad \begin{array}{l} \text{population growth of plant sp } i \\ \frac{dp_i}{dt} \end{array} = \begin{array}{l} \text{reproduction reduced by plants' competition} \\ \gamma_i \sum_{j=1}^n e_{ij} \sigma_{ij} V_{ij} \end{array} - \begin{array}{l} \text{mortality loss} \\ \mu_i^P p_i \end{array} \quad (8)$$

$$1046 \quad \begin{array}{l} \text{floral-rewards dynamics of plant sp } i \\ \frac{dR_i}{dt} \end{array} = \begin{array}{l} \text{saturated production of rewards} \\ \beta_i p_i - \varphi_i R_i \end{array} - \begin{array}{l} \text{consumption by pollinators} \\ \sum_{j=1}^n V_{ij} b_{ij} \frac{R_i}{p_i} \end{array} \quad (9)$$

1048
 1049 where $V_{ij} = \alpha_{ij} \tau_{ij} a_j p_i$ defines the frequency of visits by animal species j to plant species i , which
 1050 increases the population growth of plant i (Eq. 8., 'Pollination' in Fig. 1B) but decreases its floral
 1051 rewards (Eq. 9, 'Consumption' in Fig. 1B). Those visits are determined by the adaptive
 1052 preference (thickness of pollinator's arrows in Fig. 1B) of animal j for rewards of plant i (α_{ij} , see
 1053 below), the pollinator's visitation efficiency on plant i (τ_{ij}), and the population densities of animal
 1054 j (a_j) and plant i (p_i).

1055 In Eq. 8, only a fraction $\sigma_{ij} = \frac{\varepsilon_i V_{ij}}{\sum_{k \in P} \varepsilon_k V_{kj}}$ of j 's visits successfully pollinates plant i , which
 1056 accounts for dilution of plant i 's pollen when j visits other plant species (indicated by the red
 1057 arrow in Fig. 1D). A fraction e_{ij} of those pollination events produces seeds. Among those seeds, a
 1058 fraction $\gamma_i = g_i (1 - \sum_{l \neq i \in P} u_l p_l - w_i p_i)$ recruit to adults, where g_i is the maximum fraction of i -
 1059 recruits subjected to both inter-specific (u_l) and intra-specific (w_i) competition. The population
 1060 dynamics of animal species j is defined as:

$$1061 \quad \begin{array}{l} \text{population growth of animal sp } j \\ \frac{da_j}{dt} \end{array} = \begin{array}{l} \text{recruit to adults from rewards consumption} \\ \sum_{i=1}^m c_{ij} V_{ij} b_{ij} \frac{R_i}{p_i} \end{array} - \begin{array}{l} \text{mortality loss} \\ \mu_j^A a_j \end{array} \quad (10)$$

1062

1063 where c_{ij} represents the per-capita efficiency of j converting plant i 's floral resources into j 's
 1064 births. b_{ij} is the efficiency of j extracting plant i 's floral resources (R_i , Eq. 9).

1065 Another key advance of this model accounts for the widely observed adaptive foraging of
 1066 pollinators (Fig. 1B) by modeling the adaptation of animal species j 's foraging preference on i as:

1067

$$1068 \quad \frac{d\alpha_{ij}}{dt} = G_j \alpha_{ij} \left(\frac{\text{R consumption from plant } i}{c_{ij} \tau_{ij} b_{ij} R_i} - \frac{\text{average R consumption from all } j\text{'s plants}}{\sum_{k=1}^m \alpha_{kj} c_{kj} \tau_{kj} b_{kj} R_k} \right) \quad (11)$$

1069

1070 with $\sum_{i=1}^m \alpha_{ij} = 1$ (i.e., animal j 's total preferences sum 1 over all plant species it visits). The preference
 1071 α_{ij} increases when the resources obtained from i exceed the resources obtained from the other
 1072 plants in j 's diet (defined by the network), and decreases when resources obtained from i are
 1073 lower than the resources obtained from the other plants (follow thicker pollinator's arrow in Fig.
 1074 1B). When adaptive foraging is not considered, pollinator foraging efforts are fixed to:

$$1075 \quad \alpha_{ij} = 1/m_j \quad (12)$$

1076 where m_j is the number of plant species visited by pollinator species j .

1077 Fortuna & Bascompte (2006) recognizes that populations are not homogenously
 1078 distributed but structured in space. The authors developed a metacommunity model for
 1079 mutualistic networks following the patch dynamics model for two species generated by
 1080 Amarasekare (2004). In this model, p_i^P and p_j^A represent the fraction of patches occupied by
 1081 plant and animal species i and j , modeled as functions of colonization and extinction rates for
 1082 plants (c_{ij}^P and e_i^P) and animals (c_{ji}^A and e_j^A), the fraction of patches lost by the habitat
 1083 destruction rate, d , and the total number of available patches for animals Ω_j , as follows:

$$1084 \quad \frac{dp_i^P}{dt} = \sum_{j=1}^n \left(c_{ij}^P \frac{p_i^P p_j^A}{\Omega_j} \right) (1 - d - p_i^P) - e_i^P p_i^P \quad (13)$$

$$1085 \quad \frac{dp_j^A}{dt} = c_{ji}^A p_j^A (\Omega_j - p_j^A) - e_j^A p_j^A \quad (14)$$

1086

1087 **Box 4. Stability analysis of Lotka-Volterra type models of mutualistic networks.**

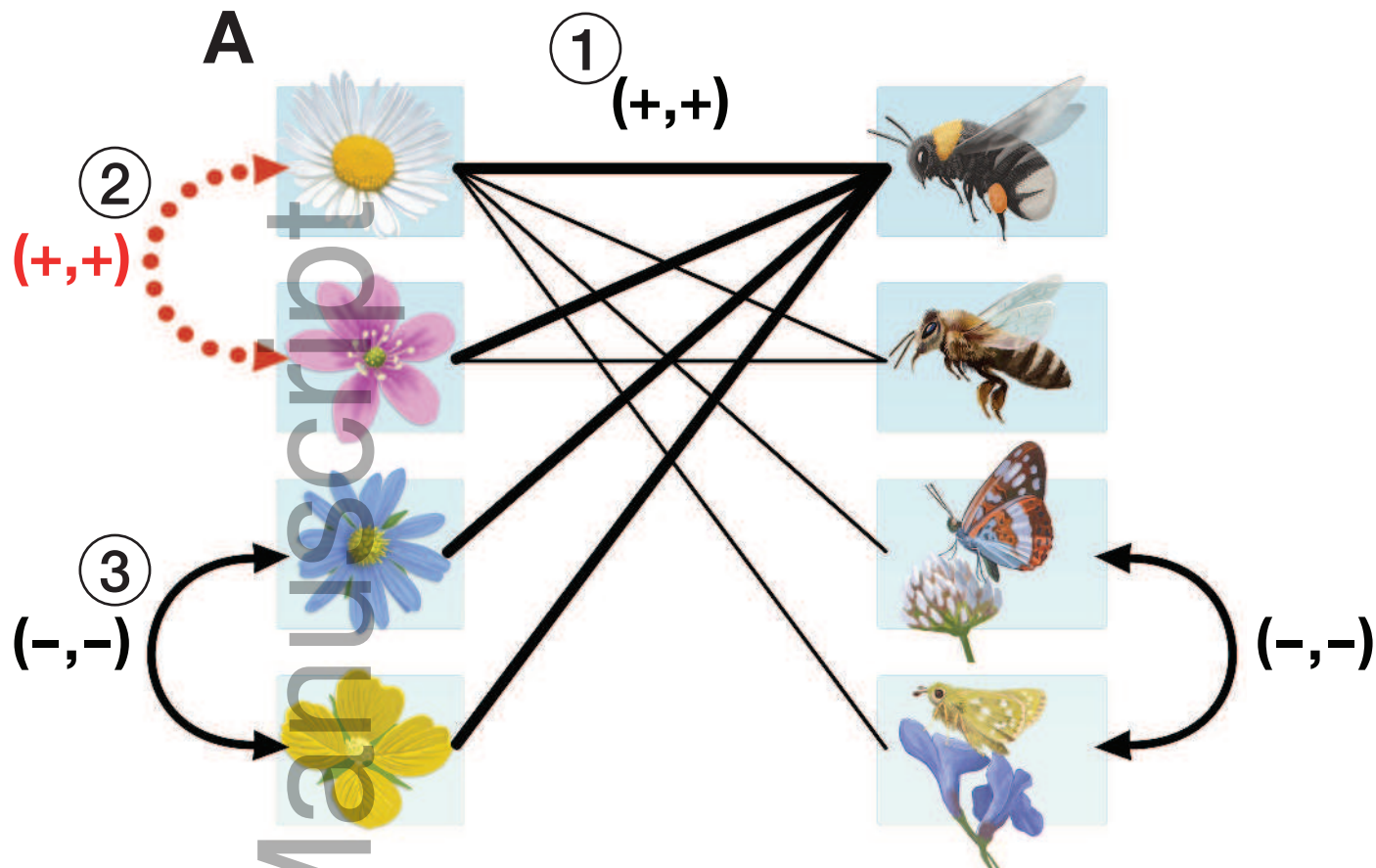
1088 Studies using the simplest model with linear mutualisms differ in how they analyze **local**
1089 **stability**. Bascompte et al. (Eqs. 2-3) assume a fully connected network in which all plants
1090 interact with all animals and all species are equivalent. By this assumption, the authors simplify
1091 the model to find four equilibrium points (i.e., species abundances at which $dN^P/dt = 0$ and
1092 $dN^A/dt = 0$), among which one is **feasible**. This procedure shows that weak or asymmetric per-
1093 capita effects between plant and animal species increase the **local stability** of the **feasible**
1094 **equilibrium**. By contrast, Allesina & Tang (2012) assume the existence of a feasible equilibrium
1095 without finding it. This strong assumption allows the authors to evaluate the local stability of
1096 different community matrices (Eq. 1) representing distinct interaction types (i.e., mutualistic,
1097 trophic, competitive) and network structures (e.g., nestedness, modularity) without restricting
1098 their exploration to a feasible equilibrium nor to a ‘fully connected network’.

1099 Okuyama & Holland (2008) used computer simulations to show that a model with
1100 nonlinear functional responses (Eq. 4) does not require weak or asymmetric interaction strengths
1101 for species coexistence. The authors find that strong symmetric interactions stabilize network
1102 dynamics in terms of resilience. Additionally, contrary to Allesina & Tang (2012), Okuyama &
1103 Holland find that mutualisms are very stable and that increasing levels of species richness,
1104 nestedness, and connectance increase resilience of the networks. Moreover, the authors used
1105 resilience as their only measure of stability because all networks they simulated (order of
1106 thousands) were locally stable and fully **persistent**. Thèbault & Fontaine (2010) computationally
1107 analyzed Okuyama & Holland’s model to evaluate the effects of species richness, connectance,
1108 nestedness, and modularity on species persistence and resilience of mutualistic and trophic
1109 networks. In accordance with Okuyama & Holland, Thèbault & Fontaine found for mutualistic
1110 networks that: i) nestedness increases resilience, ii) species richness strongly increases both
1111 resilience and species persistence, and iii) connectance slightly increases species persistence. But
1112 contrary to Okuyama & Holland, Thèbault & Fontaine found that nestedness slightly decreases
1113 species persistence and connectance decreases the resilience of mutualistic networks (all results
1114 depicted in Thèbault & Fontaine’s Fig. 2A, C). Thèbault & Fontaine did not emphasize their
1115 result of nestedness slightly decreasing species persistence of mutualistic networks because that

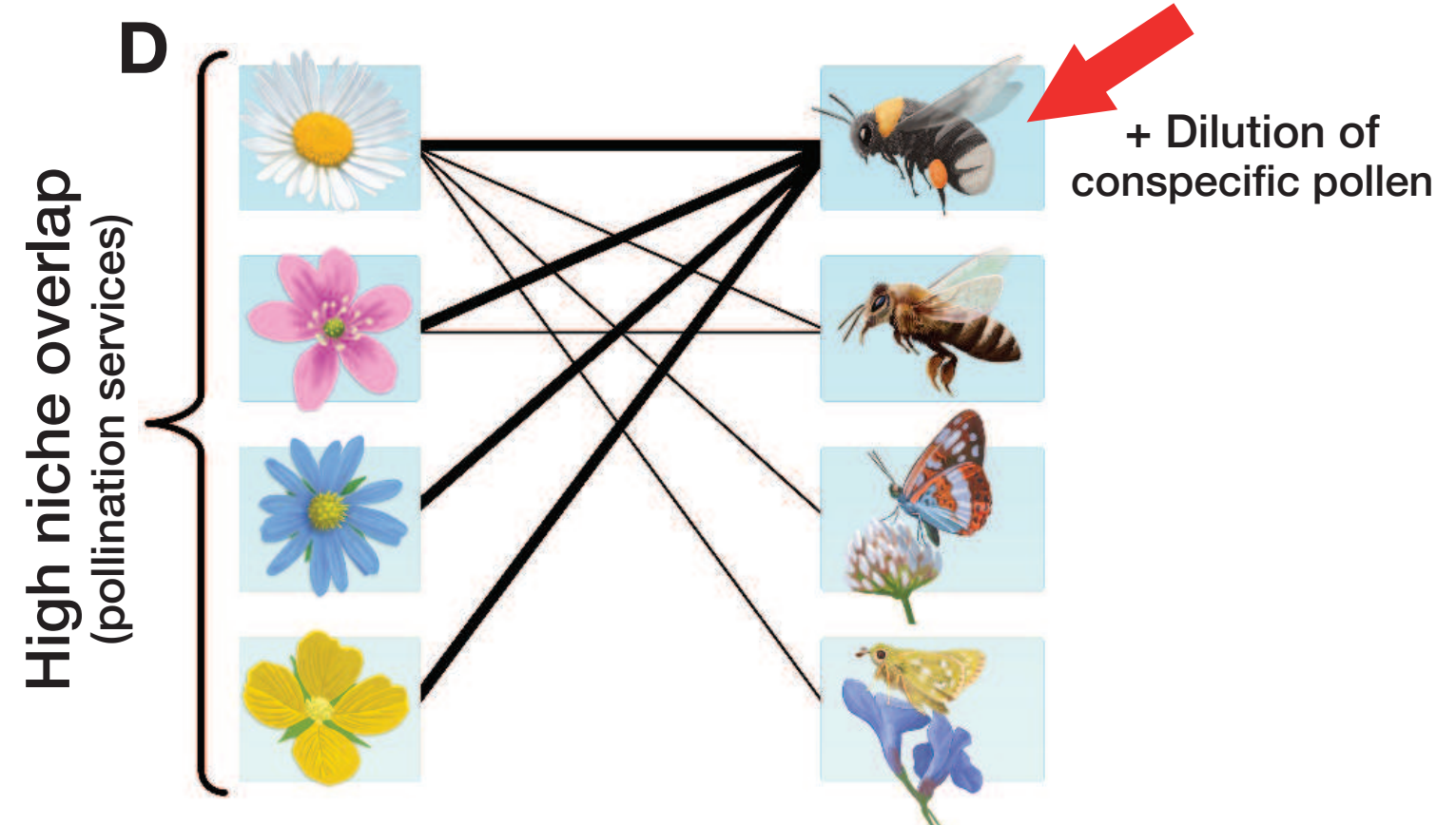
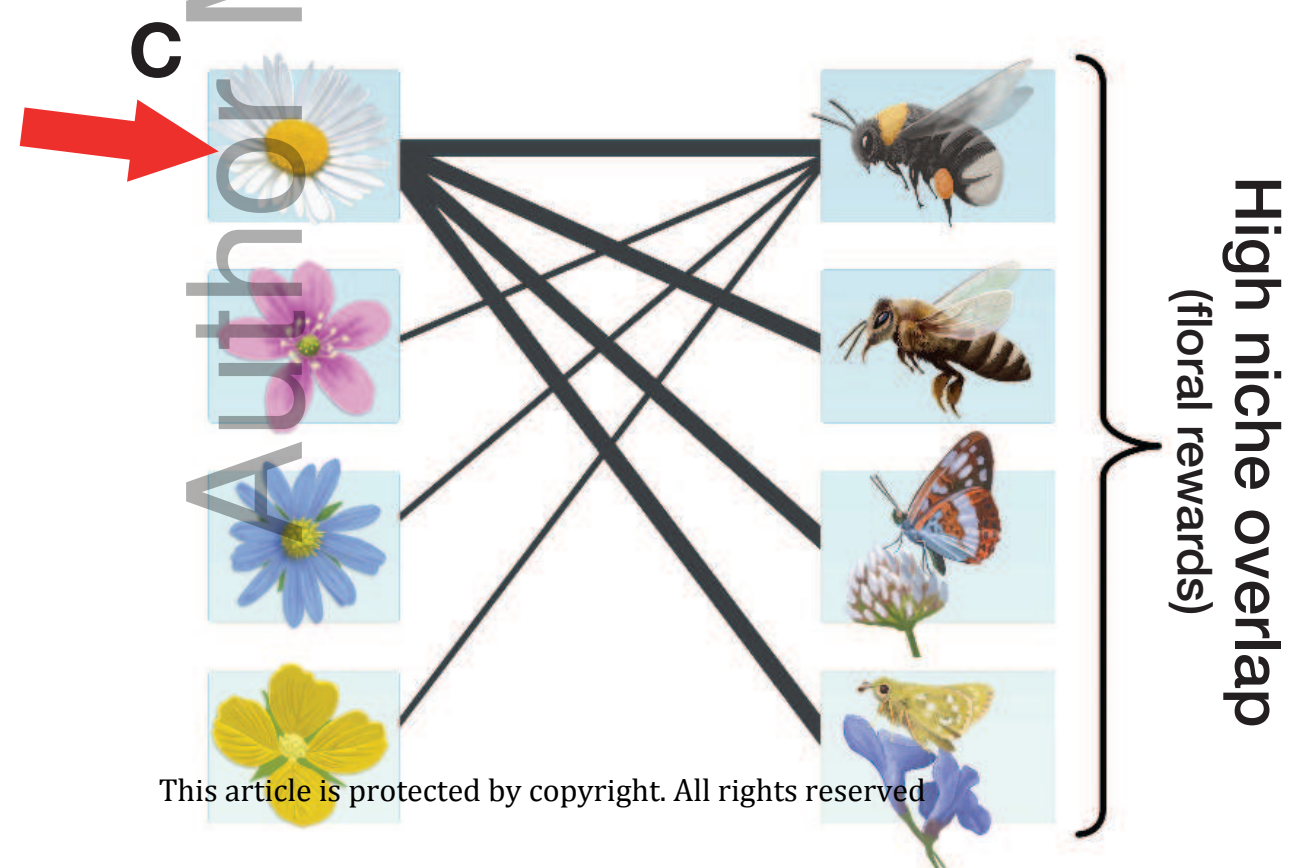
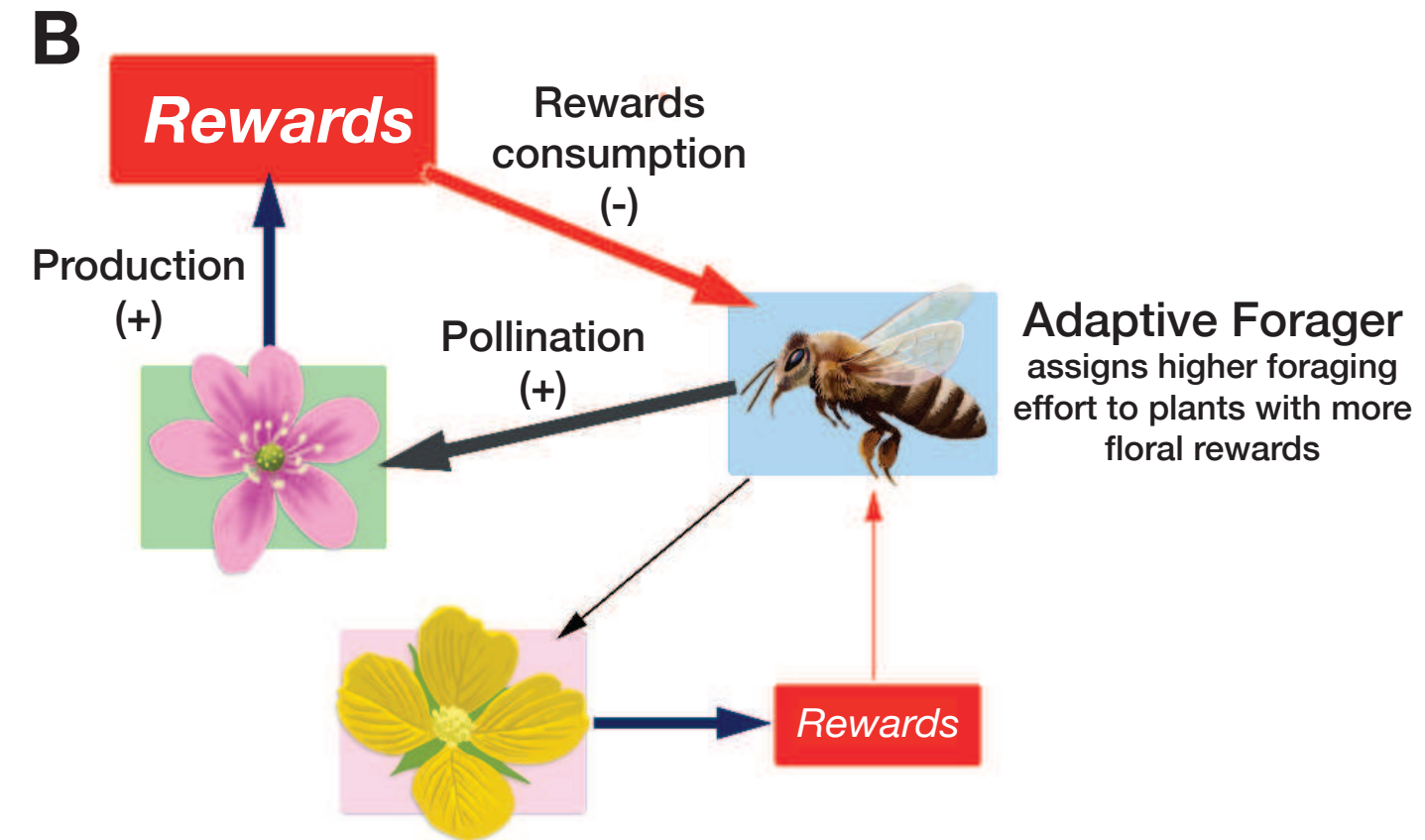
1116 result strongly depended on parameter values (E. Thèbault personal communication). The
1117 differences between the results of Okuyama & Holland and Thèbault & Fontaine can be
1118 explained by the parameter values of the intrinsic growth rate, r^P_i and r^A_j (Eqs. 2-3). Okuyama &
1119 Holland assumed positive values while Thèbault & Fontaine assumed negative values for
1120 intrinsic growth rates, which can be interpreted as facultative and obligate mutualism,
1121 respectively. Thus, with saturated benefits, facultative mutualisms are more stable than obligate
1122 mutualisms.

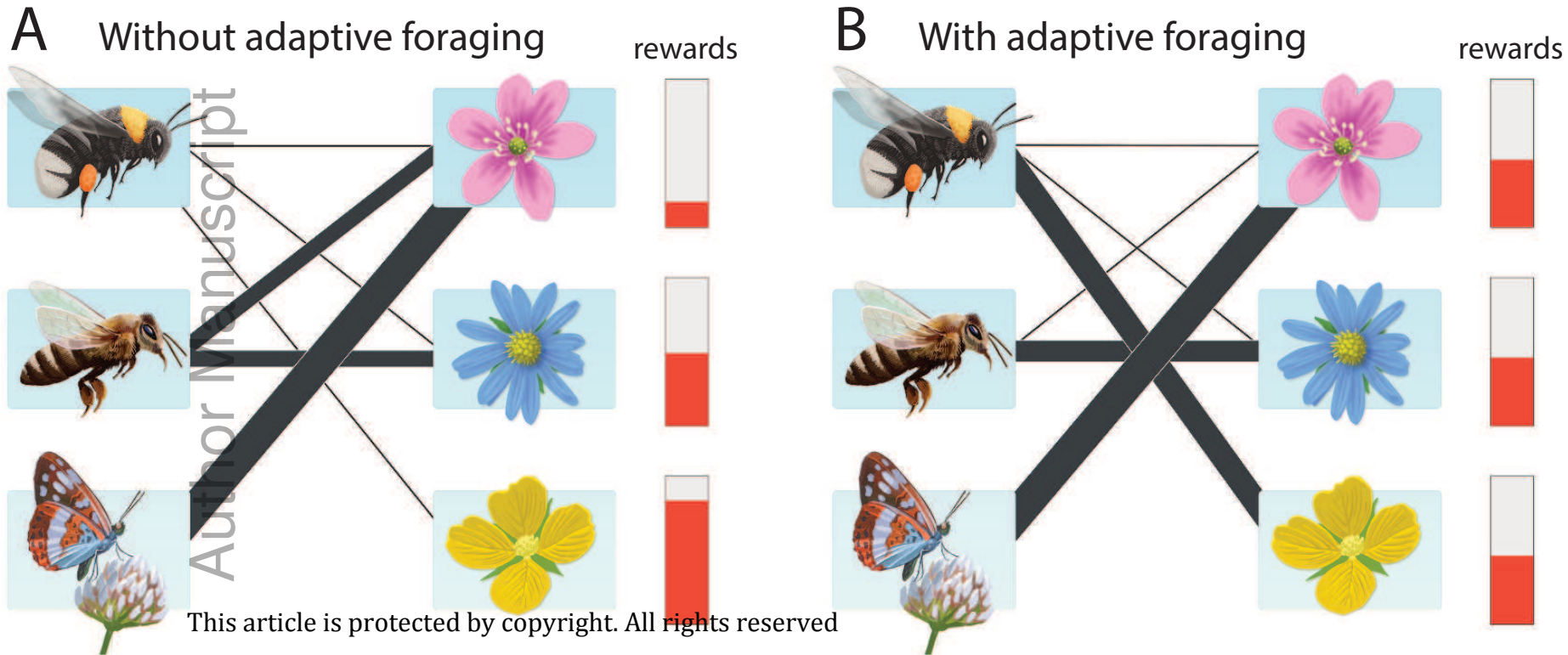
1123 Bastolla et al. (2009) added competition among all species in the same guild to the model
1124 of saturated mutualisms (Eqs. 5-6). By using **structural stability** analysis (Box 1), the authors
1125 showed that nestedness stabilizes mutualistic networks by reducing effective interspecific
1126 competition (see main text). James et al. (2012) used computer simulations to contradict Bastolla
1127 et al.'s results by showing that nestedness does not stabilize the networks in terms of **species**
1128 **persistence**. As mentioned above, Thèbault & Fontaine (2010) also found that nestedness
1129 decreases species persistence but that result strongly depended on parameter values. However,
1130 Saavedra & Stouffer (2013) argue that species persistence in the James et al. (2012) study was a
1131 result of changes in degree distribution and not in nestedness. James et al. (2013) responded to
1132 such criticism arguing that nested networks exhibit higher species persistence only in comparison
1133 to random networks of the same size, connectance, and degree distribution. Therefore, to the
1134 question of which network structures explain species persistence in the Bastolla et al. (2009)
1135 model, James et al. (2013) affirms that nestedness is less important than network size,
1136 connectance, degree distribution, intrinsic growth rates, competition coefficients, and the
1137 strength of the mutualistic interaction. Rohr et al. (2014) corroborates Bastolla et al.'s result that
1138 nestedness maximized the network **structural stability**, and proposed that the contradictory
1139 results on the effect of nestedness in different studies arise if the necessary conditions for a
1140 **feasible equilibrium** are not met (e.g., Allesina & Tang 2012), or because of sensitivity to
1141 model parameterization in computer simulations (e.g., James et al. 2012). However, Pascual-
1142 Garcia & Bastolla (2017) demonstrate how the discrepancies among results are better explained
1143 by the different ways in which each study incorporated competition among species of the same
1144 guild (main text).

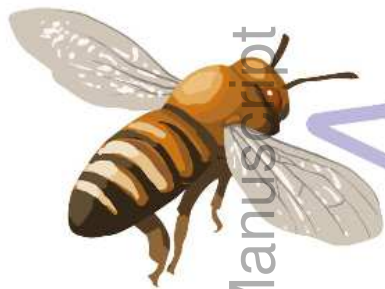
Lotka Volterra type



Valdovinos et al

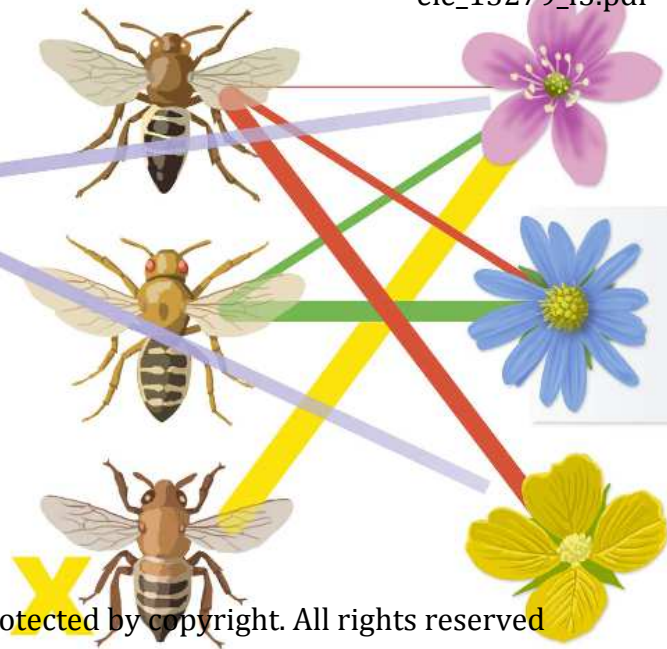




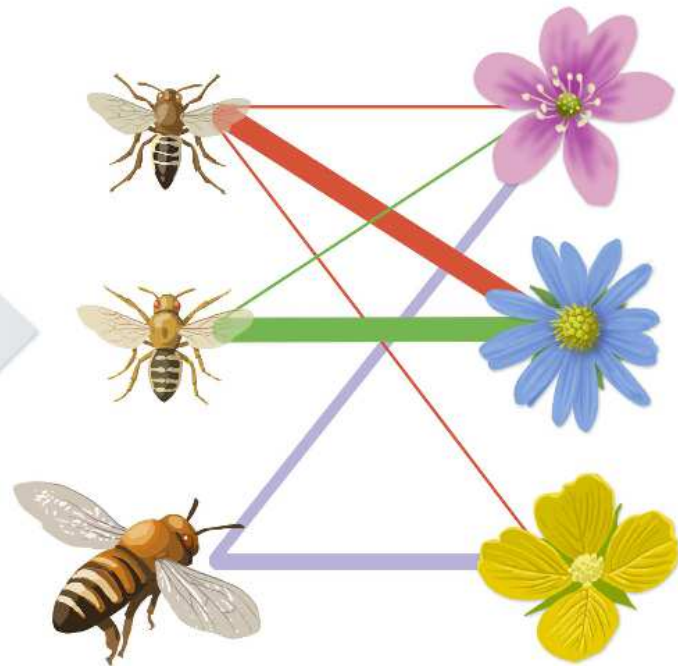


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