

NON-LINEARITIES IN GENETIC ADAPTIVE SEARCH

by

Daniel Raymond Frantz

September 1972

Technical Report No. 138

with assistance from:

National Science Foundation
Grant No. GJ-29989X
Washington, D.C.

and

Department of Health, Education, and Welfare
National Institutes of Health
Grant No. GM-12236
Bethesda, Maryland

THE UNIVERSITY OF MICHIGAN
ENGINEERING LIBRARY

Engn
UMR
1485

ABSTRACT

NON-LINEARITIES IN GENETIC ADAPTIVE SEARCH

by

Daniel Raymond Frantz

Chairman: John H. Holland

Methods of adaptive search must contain, at least implicitly, the ability to detect and act upon non-linearities in their environments (i.e., in the functions to be optimized). If such knowledge can be made explicit, this information may be of value in constructing models of the environment and may lead to faster and more successful adaptation.

One method of adaptive search, based on genetics, is called the Reproductive Plan, due to Holland. Requirements for its use are:

1) description of the environment must be in terms of a set of parameters; 2) the quantity to be optimized (the payoff) must be a function of these parameters; 3) there must be an initial population of parameter sets. The parameters are listed as a string of values, called a chromosome.

The environments used in this research had twenty-five parameters, each of which could take two values. Dependent groups of up to nine parameters were used.

In this variation of the Reproductive Plan new points to be tested are generated by a two step process: 1) Two parents are randomly selected from the current population with the selection biased according

to payoff. 2) The two parents are combined by operators to form an offspring, the new point; these operators are similar to the genetic versions of crossover, inversion, and mutation.

The operation of the Reproductive Plan suggests two ways by which functional dependencies in the environment may be detected. Groups of parameters which interact non-linearly may have their frequencies of combination different from that predicted by the individual parameter frequencies. This is testable by a multi-dimensional chi-squared contingency table. Another characteristic suggests that position of parameters on the chromosome may be important in the rate of evolution or on the equilibrium point of the population payoff. If there is an adaptive advantage in position, a genetic operator such as inversion should be able to produce chromosomes with better permutations of parameters. Computer experiments were performed to test these hypotheses.

Multi-dimensional chi-squared contingency table tests showed that most groups of parameters were statistically dependent, a by-product of the Reproductive Plan, but non-linear payoff groups were definitely distinguishable from linear payoff groups. Analyses were then performed to detect the dependent groups when no prior information existed: contingency table values for all pairs of parameters were calculated. The pairs from non-linear groups showed higher association indices. Thus, dependent groups are detectable since all their pairs have much higher associations.

Studies of the equilibrium level of the population payoff average did not show any consistent position effect, although there were some positive results. However, investigation of the rate of evolution showed that populations in which groups of dependent parameters are close

together significantly and consistently outperform populations in which the groups are spread apart on the chromosome. Populations with spread groups often did not achieve optimum or near-optimum points in the most complex environments.

Experiments using the inversion operator were unable to demonstrate its ability to capitalize on the position effect. The advantage due to the position effect lasts for too short a time in the environments used. The role of inversion is open for further study since it may be shown effective in more complex environments with longer adaptation times.

ACKNOWLEDGEMENTS

I would like to thank those who made this research not only possible but also worthwhile and enjoyable: foremost among all, my thesis chairman, John H. Holland, who introduced me to Reproductive Plans and kept me on the paths of righteousness while investigating them; my committee members Bernard P. Zeigler, Larry K. Flanigan, and Julian P. Adams, as well as W.J. Schull, a member during the early stages; the Logic of Computers Group (and its director Arthur W. Burks) which supported me financially, provided the computing equipment upon which all the experimentation took place, and whose members provided intellectual stimulation of all sorts; Monna Whipp and Karen Vora who helped type many of the tables; especially our secretary, Janet McDougall, who saw this document through several drafts with outstanding competence and cheerfulness; and finally my wife, Mary, who, often more than I, had faith that I would finish.

This research was supported by the National Science Foundation, Grant No. GJ-29989X and the National Institutes of Health, Grant No. GM-12236.

TABLE OF CONTENTS

	<u>Page</u>
CHAPTER ONE: A Different Use for Adaptive Search	1
Device Composition	1
Non-linearity (Dependence of Components)	2
Hierarchical Models	4
The Representation Problem	6
Summary	7
 CHAPTER TWO: The Reproductive Plan	 8
Definition of the Genetic Algorithm	8
Implications of Reproductive Plan for Dependencies	11
Frequency of Gene Combinations	12
Position Effect	15
 CHAPTER THREE: The Experimental Basis	 18
The Environment	18
Non-linearity	18
Discreteness	21
Functional Form.	23
The Payoff Function	26
Environments Used	26
The Adaptive Program	42
Genes, Alleles, and Chromosomes	42
Population Size	44
Mating and the Genetic Operators	45
Inversion	48
Crossover	51
Mutation	52
Migration	52
Selection	53
Monte Carlo Methods	54
Program Description	55
 CHAPTER FOUR: Position Effects	 59
Equilibrium Populations	60
Experimental Procedure	60
A Simple Adaptive System	62
The Problem of Homogeneity	65
Variance by Mutation	67
Variance by Decreased Selection	68
Variance by Migration	70
Best/Worst Tests	74
Summary	77

TABLE OF CONTENTS (Cont'd)

Evolving Populations	79
Best/Worst Evolution	80
Approach to the Optimum	98
Inversion Experiments	101
Probabilities of Permutations	103
Experimental Protocol	105
Equilibrium Test	113
Evolving Tests	115
Summary	119
CHAPTER FIVE: Frequency Effects	122
Existence of a Frequency Effect	122
Chi-Squared Analysis	122
Multiple-Gene Tests	124
Summary	143
Detecting Dependent Groups	145
Pair Analysis	146
Analysis at the End of Runs	146
Cumulative Analysis	148
CHAPTER SIX: Conclusions	163
APPENDIX: Ten Random Permutations of Twenty-five Genes	168
BIBLIOGRAPHY	169

LIST OF TABLES

<u>Table</u>	<u>Page</u>
4.1: Experiment A1. Gene Positions and Results	63
4.2: Experiment C1. Gene Positions and Results	65
4.3: Experiments in Mutation Rates	68
4.4: Experiments in Reduced Selection	70
4.5: Experiments in Migration	72
4.6: Best/Worst Equilibrium Results	76
4.7: Summary of Best/Worst Evolution Experiments	97
4.8: Best Individuals vs. Population Payoff	100
4.9: Probability of Dispersion of Genes on a Chromosome	104
4.10: Inversion/Equilibrium Experiments	114
4.11: Inversion/Evolution Experiments (cont'd)	117
4.11: Inversion/Evolution Experiments	118
5.1(a): Multi-gene χ^2 Tests: Experimental Parameters	125
5.1(b): Multi-gene χ^2 Tests: Results of First Runs (cont'd)	126
5.1(b): Multi-gene χ^2 Tests: Results of First Runs	127
5.1(c): Multi-gene χ^2 Tests: Results of Second Runs	128
5.2: Selected Points of the χ^2 Distribution	129

LIST OF FIGURES

<u>Figure</u>	<u>Page</u>
2.1: Research Schema	17
3.1: Environment 1	27
3.2(a): Payoff Group A	28
3.2(b): Environment 2	28
3.3(a): Payoff Group B	29
3.3(b): Environment 3	29
3.4: Environment 4	30
3.5(a): Payoff Group C	31
3.5(b): Environment 5	31
3.6(a): Payoff Group D	32
3.6(b): Environment 6	32
3.7(a): Payoff Group E	33
3.7(b): Payoff Group F	34
3.7(c): Environment 7	34
3.8: Environment 8	35
3.9(a): Payoff Group G (cont'd)	36
3.9(a): Payoff Group G	37
3.9(b): Environment 9	37
3.10(a): Payoff Group H (cont'd)	38
3.10(a): Payoff Group H (cont'd)	39
3.10(a): Payoff Group H (cont'd)	40
3.10(a): Payoff Group H	41
3.10(b): Environment 10	41
3.11: Generation of a New Population (cont'd)	57
3.11: Generation of a New Population	58
4.1: Output from Experiment D1	81
4.2: Output from Experiment D3 (cont'd)	82
4.2: Output from Experiment D3	83
4.3: Output from Experiment D5 (cont'd)	84
4.3: Output from Experiment D5 (cont'd)	85
4.3: Output from Experiment D5	86
4.4: Output from Experiment D6 (cont'd)	87
4.4: Output from Experiment D6 (cont'd)	88
4.4: Output from Experiment D6	89
4.5: Output from Experiment D7 (cont'd)	90
4.5: Output from Experiment D7 (cont'd)	91
4.5: Output from Experiment D7	92
4.6: Output from Experiment D8 (cont'd)	93
4.6: Output from Experiment D8 (cont'd)	94
4.6: Output from Experiment D8	95
4.7: Output from Experiment MH3/4	111

LIST OF FIGURES (Cont'd)

5.1(a): Sample χ^2 Multi-gene Test-Experiment J1	130
5.1(b): Sample χ^2 Multi-gene Test-Experiment J4	131
5.2(a): Sample χ^2 Multi-gene Test-Experiment L5	132
5.2(b): Sample χ^2 Multi-gene Test-Experiment L5	133
5.3: Pair Chi-squared Values for Experiment H1	150
5.4: Pair Chi-squared Values for Experiment H2	151
5.5: Pair Chi-squared Values for Experiment H6	152
5.6: Pair Chi-squared Values for Experiment H8	153
5.7(a): Pair Chi-squared Values for Experiment I3	154
5.7(b): Pair Chi-squared Values for Experiment I3 (8 Generations)	155
5.8: Pair Chi-squared Values for Experiment J5	156
5.9(a): Pair Chi-squared Values for Experiment K7	157
5.9(b): Pair Chi-squared Values for Experiment K8	158
5.10(a): Pair Chi-squared Values for Experiment L5	159
5.10(b): Pair Chi-squared Values for Experiment L6	160
5.11: Cumulative PCVs for ENV 7	161
5.12: Cumulative PCVs for ENV 8	162

CHAPTER ONE

A DIFFERENT USE FOR ADAPTIVE SEARCH

Device Composition

Many problems in adaptive search can be viewed as the creation of an optimal device from components, each of which have several possible instances. If either the number of components or the number of instances for each component is large, then the size of the search space is usually quite large, requiring the use of adaptive algorithms rather than enumeration to perform the job in a reasonable amount of time. Adaptive search is made feasible by the decomposition or coordination of the device: if the device were not made up of subunits but was instead a monolithic whole, no regularity in the makeup of the solution could be exploited and the only method of search would be to enumerate each of the possible devices.

Examples of this kind of structure in an adaptive framework are numerous. In control theory the components are continuous control parameters (e.g., voltage levels, flow rates) and the optimum device is one which specifies values for the parameters yielding a minimum error in a selected subset of the dependent variables. In a pattern recognition device the components may be the weights attached to feature detectors, specifying the importance of that feature in picking out a particular pattern class. The optimum is that set of weights which discriminates perfectly. Similarly in Samuel's checker player (15), the components are the weights attached to parameters which measure some feature of the board. The optimum is that set of weights which predicts the value of a board in the same manner as a minimax strategy

for the game. Other examples can be found in genetics, economic planning, etc.

The representation of the device in terms of the particular components chosen to describe it may be more or less adequate with respect to the overall problem of which adaptive search is only a small part. In economic theory, the choice of which activities to include in a mix may be a matter of opinion, but once those activities have been chosen, there is no doubt that the optimum obtained with respect to that base set is a solution to the problem posed. That is, the representation or coordination is adequate by design. The choice of activities is a value decision which cannot be decided or explored by adaptive search. On the other hand, if the set of detectors for the checker player is inadequate, the optimum with respect to those parameters will still not approach minimax. Thus, adequacy of the base set of components for the overall task (the so-called "representation problem") is in large part separable from the problem of adaptive search which merely optimizes with respect to a given set of components.

Once a representation is determined the search space is well-defined. Different representations may lead to different "shaped" spaces for essentially the same problem, but any one representation yields a definite space.

Non-linearity (Dependence of Components)

Difficult optimization problems are those which are highly non-linear with respect to the parameters or components. In its most difficult sense, "non-linear" means that the optimal setting for a

particular parameter (i.e., that setting yielding a global maximum) depends on the setting of one or more other parameters. The resulting dependence makes it impossible to optimize the solution component by component. Combinations of parameter values are more important than individual values. When there are a finite number of parameter values there are many more combinations than there are individual values and this is where adaptive search enters. Somehow combinations must be tried, the results remembered, and new combinations tried on the basis of previous information.

The opposite of non-linearity (or dependence) is linearity or independence. Two parameters are independent of each other (are relatively linear) if the effect a value for one has on the optimum is not influenced by the value of the other.

It is entirely possible for every component to depend on every other component. In this case, unless there is some regularity in the interaction, the search algorithm may have as hard a time as if it were dealing with a non-coordinated system: it may break down and only be able to do an enumerative search. Most non-linear groups of components have regularities with respect to the component values; in functional optimization this is similar to stating that the function is at least piece-wise continuous. So even non-linear groups provide "handles" for an adaptive plan. If there are groups of parameters which are internally dependent but independent of other groups, the search algorithm has an easier time since it can optimize the groups independently (which at worst is an enumeration over much smaller spaces) and sum the results of the individual optima.

For any particular adaptive search algorithm to operate well it must take cognizance of the non-linearities of the system. A generally applicable algorithm must be able to handle non-linearities of any type or order. Thus any adaptive algorithm must be able to build up within itself, at least implicitly (as part of its state or data), information about the non-linearities of the search space. Even search algorithms which contain little explicit memory (such as some of the gradient methods which keep only one point in the space) can be considered to contain or generate this implicit information. No matter how it is achieved, selection of the next point to be tested must depend on knowledge of the space. Ultimately, the trajectory of points through the space may be used as clues to the structure. As the search progresses over more samples from the space, more complete and certain knowledge must be gained. (Since plans operate with finite memory, it is reasonable that knowledge about bad sections of the space may be lost--only information affecting good points will be kept.)

Despite having this information about the non-linearity of the space implicit within themselves, as normally formulated, optimization or search procedures have only one result: the optimum point (or at least a good point). It is the intention of this thesis to show how knowledge of dependencies resides in at least one class of search algorithms, the Holland Reproductive Plans (9,10,11). In addition, we intend to show that this implicit information can be made explicit in some cases.

Hierarchical Models

Concern over the form of a procedure's method of exploiting functional

dependency arises for two reasons. The first comes directly from the definition of a procedure and the nature of science. Each adaptive algorithm has a justification of its efficacy; part of this justification is an explanation of how the algorithm treats non-linearities. Proof of the value of the plan must include verification of such treatment (to eliminate chance or other factors). While previous researches into Holland Reproductive Plans have performed a verification of efficiency with respect to other plans, this paper is the first full-scale explicit investigations into the internal workings of the algorithm, an intrinsically interesting topic.

The second, more significant, reason for investigation is the importance of learning something about the spaces one is searching. (The class of spaces we shall investigate is described in Chapter Three.) This is directly related to modelling theory with respect to the usefulness of a level of description of a system. In terms of both human preference and mathematical tractability it is advantageous to explain complex systems in terms of a small number of factors. Interaction of components beyond a certain number or level of non-linearity becomes incomprehensible to the human mind; the mathematics of such systems is often incapable of closed solution. If at all possible, scientists will aggregate variables or describe the system at a level which can be handled easily. If necessary, several levels of abstraction or aggregation may be employed to achieve a description appropriate to a particular purpose.

This process is called model building via hierarchy. Dependent groups of coordinates or variables are identified and then treated as a single, well-understood quantity on a higher level. In the ideal

case, aggregation may eventually lead to a linear system, which both humans and mathematics can treat most easily. In other cases, assuming the reduction preserves the structure of the system, a hierarchical model still has great intuitive explanatory powers.

Thus, determining the dependencies among components in a particular environment is an aid to model building. Extracting information from an adaptive algorithm regarding non-linearities may be no more of an aid than merely pointing out that some components are dependent without giving specific information as to what the dependence is. However, if that knowledge reduces the number of parameters from a hundred to six, the reduction of the modelling problem is one of several orders of magnitude.

The Representation Problem

The modelling procedure is one aspect of the representation problem previously mentioned. The "problem" resides in the uncertainty of which information in the environment is relevant to the task at hand. Ordinarily in artificial intelligence work there is such an abundance of data available that some reduction (or selection) must be made (by a human intermediary) before the programmed learning can occur.

Although we do not wish to stress this issue, being able to detect dependencies may eventually be of use in the solution of this problem. By feeding all of the potentially useful information into an adaptive program we may obtain information not only about good points in the search space but also about the dependencies. Most likely the oversupply of parameters, some of which may be irrelevant or redundant, will make for

slow adaptation--i.e., the representation is not the most useful. But by means of the dependency knowledge gained on this first attempt it may be possible to obtain a better representation, leading to faster adaptation and so forth. Thus, not only is the creation of hierarchical models useful for human understanding but, practically, it may also lead to the increased adaptive efficiency of the man-machine system.

Summary

When faced with a complex search space two kinds of information are important: the optimum achievable in the space and the "shape" or dependencies in the space. Knowledge of dependencies is important for the building of hierarchical models of the space. Rather than do a completely independent analysis of the space for the model building it would be advantageous to be able to use the adaptive search procedure to determine dependencies also. Since the adaptive program must build up within itself some knowledge of the space in order to find the optimum it is reasonable to try to make this knowledge explicit. Even if it cannot be made explicit in every case, it is valuable to verify that the adaptive search procedure contains the information in the manner expected so that it builds models implicitly.

CHAPTER TWO
THE REPRODUCTIVE PLAN

Reproductive Plans are a class of adaptive algorithms based on genetics. Holland has given theoretical justifications for the use of such plans in terms of their efficiency (11). Previous simulation work (Bagley, Cavicchio, Hollstien, Bosworth (1,3,122)) has shown the actual superiority of such algorithms over other search procedures. Since much has been written on the basis of Reproductive Plans (see the above references), we will include here only a summary of its salient points.

Definition of the Genetic Algorithm

Problem solving with the Reproductive Plans requires an environment (i.e., the problem area to be solved) with two properties:

1. There must be a device decomposition as discussed in Chapter One. The solution must be expressed in terms of a list of parameters with admissible substitutions for each parameter completely defining the search space. We shall thus refer to a device alternately as a string or an individual. (No order to the parameters is implied by use of the word "string"; some order must be chosen for convenience).
2. There must be a "payoff" (or goodness, fitness, utility) associated with each device described by the parameters, and this payoff is the quantity to be maximized.

Briefly, then, the main features of a reproductive plan are the following:

1. A "population" of devices forms the memory of the system at any point in time.
2. A new population is formed from the old population by the following two-step process:
 - a) An intermediate population is formed by reproducing each member of the old population a number of times proportional to its payoff. For example, if two devices (strings of parameters) S_1 and S_2 have payoffs 3 and 7, respectively, then 3 copies of S_1 and 7 copies of S_2 will enter the intermediate population.
 - b) The new population is then formed by randomly choosing members of the intermediate population and modifying them by "operators". These operators are strictly string operators and are largely independent of the environment.

The most important feature of a Reproductive Plan is 2a: emphasizing strings in proportion to their payoff. Thus, the proportion of better strings increases exponentially with respect to the average of the population.

The choice of operators (2b) is critical. Previous work by Friedberg (8) and Fogel (6) failed precisely because they did not appreciate the importance of analyzing what the operators did, so that they destroyed the advantages of proportional reproduction. Choice of operators determines the exact form of the adaptive algorithm within the class of Reproductive Plans.

Since many of the ideas embodied in the rest of this report are taken from genetics we will summarize the applicable genetic vocabulary

in terms of the ideas already presented:

A *gene* is a functional unit--it corresponds to our notion of parameter. An *allele* is a particular instance of a gene: a value for the parameter. A *chromosome* is a string of genes (a one-dimensional list). A *locus* is a position on a chromosome (e.g., the first position from the left hand end).

All the genetic operators are probabilistic in their effects; that is, there is a certain probability associated with their application in forming members of the new population. Although there are many string operators possible and although there are many operators recognized by biochemical geneticists, we shall investigate only the operators mutation, crossover, and inversion. *Mutation* changes an allele into another allele with some (small) probability. Its main function is to supply variability to the population by maintaining at least a small proportion of each allele.

Crossover takes two chromosomes from the old population (parents) and interchanges parts of them, producing two new individuals. For example, for chromosomes of length seven, crossover might operate by exchanging exactly one portion in the following manner:

$$\begin{array}{ccc} \text{AbcDEFg} & & \text{AbcDefg} \\ \updownarrow & \longrightarrow & \\ \text{abCDefg} & & \text{abCDEFg} \end{array}$$

It thus serves two functions. First, it preserves a large measure of association between the alleles in the parent chromosomes. In the example, the combinations in the first four and last three positions were preserved. If there were any interactions among these genes (i.e., any advantage in being together in those combinations), that

interaction or advantage is preserved. Since application of the operator is probabilistic it may cross over at other points also, allowing other interacting gene combinations to be preserved. Secondly, by interchanging portions of the chromosomes, crossover generates tests of entirely new combinations of genes. In fact, crossover is recognized by geneticists as the most important search factor in natural adaptation.

The *inversion* operator randomly inverts a section of a chromosome, thereby changing the distance between genes. For example,

$$\begin{array}{c} \text{A b c d e F G} \\ \uparrow \quad \uparrow \\ \text{A e d c b F G} \end{array}$$

Since inversion does not change alleles but rather associations between genes it cannot directly affect the payoff of an individual as can crossover and mutation. The role of inversion is explored below under "Position Effect".

The exact form of the Reproductive Plan used and variations on the operators are given in Chapter Three.

Implications of Reproductive Plan for Dependencies

The above brief analysis is a justification for the use of the crossover and inversion operators. As such it is a claim as to how the Reproductive Plan (with these operators) takes advantage of non-linearities. Let us investigate these two statements: 1) Combinations of genes which contribute to high payoff are increased in the population; 2) When inversion is used dependent genes tend to congregate together on the chromosome.

Frequency of Gene Combinations

In the basic reproductive step (2a) increasing the frequency of an above average string in the population according to its relative payoff increases the frequency of all the substrings contained in that string. If combinations are not too greatly disturbed by the operators in changing from the intermediate population to a new population (2b), then the frequency of above average combinations tends to increase in the population. Holland suggests that the change is more rapid than might be predicted on an individual gene basis. Let us consider a set of dependent genes, S , and a set of instances, S_0, S_1, \dots, S_n , in which S_0 has the above average payoff. The combination S_0 is increased at the expense of the other combinations, but the others are still present. Since S_0 is increased, it may also be that the frequency of the alleles of the individual genes in the combination are also increased. We can then ask whether the combination increases faster than the individual alleles.

Consider the following simple model: A chromosome is made up of two genes, a and b , each with alleles 0 and 1. Let there be N strings in the population divided evenly among the four combinations 00, 01, 10, and 11. Let the payoffs be according to the following table

<u>string</u>	<u>payoff</u>
00	1
01	1
10	1
11	1+S

where S is the selection coefficient, a quantity greater than zero.

Let

$$f_a = \text{frequency of 1 alleles for gene a} = \frac{1}{2}$$

$$f_b = \text{frequency of 1 alleles for gene b} = \frac{1}{2}$$

$$f_{ij} = \text{frequency of the combination } ij \text{ (} i = 0,1; j = 0,1\text{).}$$

$$= \frac{1}{4}$$

Thus, in the initial population $f_{00} = (1-f_a)(1-f_b)$, $f_{11} = f_a f_b$, etc.; that is, the individual gene frequencies perfectly predict the combinations.

Now, carrying out only the reproductive step of the genetic algorithm we obtain the following population.

<u>type</u>	<u>number</u>
00	$(Nf_{00})(1) = \frac{N}{4}$
01	$(Nf_{01})(1) = \frac{N}{4}$
10	$(Nf_{10})(1) = \frac{N}{4}$
11	$(Nf_{11})(1+S) = \frac{N(1+S)}{4}$

With the total number of individuals in the intermediate population being

$$N' = \frac{N}{4}(4+S)$$

Recalculating the frequencies of combination and of individual genes in the new population we obtain:

$$f'_{00} = f'_{01} = f'_{10} = \frac{N/4}{N'} = \frac{N/4}{(N/4)(4+S)} = \frac{1}{4+S}$$

$$f'_{11} = \frac{(N/4)(1+S)}{(N/4)(4+S)} = \frac{1+S}{4+S}$$

$$f'_a = f'_{10} + f'_{11} = \frac{2+S}{4+S}$$

$$f'_b = \frac{2+S}{4+S}$$

But now attempting to predict f'_{11} from $f'_a f'_b$ we obtain

$$f'_a f'_b = \left(\frac{2+S}{4+S} \right)^2 \neq \frac{1+S}{4+S} = f'_{11}$$

To find the difference we calculate that

$$f'_{11} - f'_a f'_b = \frac{S}{(4+S)^2} > 0$$

$$\text{i.e., } f'_{11} > f'_a f'_b$$

which says that the frequency of combination cannot be accurately predicted by the individual gene frequencies: they underpredict.

Other factors enter into this calculation in more general cases. The non-linearity we have given is not the only type possible; however, we are hampered by not having a well-developed theory of non-linearity for reference. In addition, different initial conditions and more genes leads us into a morass of analytic difficulties. Population geneticists treat this problem under the heading of "linkage disequilibrium". Finally, operators (mutation and crossover) depress the effect and further complicate the analysis. In any case, the same simple calculation shows that a linear (additive) payoff leads to overprediction of the combination, i.e., $f'_{11} < f'_a f'_b$.

The statistical concept of contingency tables uses the chi-square criterion for determining dependencies of factors. As such it may be useful for determining that a population has evolved under the influence of non-linearities. It is well known as a *post hoc* analytic aid in genetics; Crow and Kimura include the chi-square analysis as an appendix to their introductory textbook *An Introduction to Population Genetics Theory* (4). But even such basic knowledge has not been heretofore used for the purposes we intend.

The important point to note is that the reproductive plan inherently produces this effect as a means of dealing with the environment. Chapter Five contains descriptions of experiments designed to verify the effect and to make the knowledge contained in the population explicit to the experimenter.

Position Effect

Fisher (5) first argued that chromosomes on which dependent genes are close together have an adaptive advantage at equilibrium over chromosomes on which the genes are farther apart. Again under the banner of linkage disequilibrium, the population geneticists have proposed models to deal with this conjecture. It seems fairly well proved for most two-gene models, but there is room for doubt in three (or more) gene models. Turner (16) provides a general discussion of diploid models of this sort. At any rate, most models discuss only the equilibrium conditions and not conditions of changing populations. For example, an equilibrium level might be low due to a particular distance, but that gene distance may have caused faster evolution.

The intuitive explanation to support the hypothesis is that proximate genes are less likely to be separated by crossover. If the crossover separates genes which are independent, no harm results since the payoff associated with a gene is independent of the value of the other genes. On the other hand, if the genes involved are dependent on each other, a good combination broken up results in more of a loss.

The important point to note is that position does not contribute directly to the payoff of a single chromosome--the payoff depends

strictly on the alleles present. However, position does enter into the ability of an individual to pass its good combinations to its descendants, and thus into the ability to produce good descendants. Chromosomes with good permutations of genes are more likely to have descendants in future generations than chromosomes with bad permutations. This constitutes an adaptive advantage.

Chapter Four describes computer experiments performed to determine whether the position effect actually exists in some class of environments and whether it can be detected. Briefly, there are two ways of approaching this problem: with populations in equilibrium and with evolving populations. Populations in equilibrium (under the normal artificial conditions used) have the rather difficult property that they tend towards homogeneity (i.e., all members tend to be alike). This presents a problem (as described in Chapter Four) so that we introduce methods of increasing population variance at equilibrium to help bring out the position effect. Using evolving populations we study the rate at which populations evolve as a function of position.

Figure 2.1 summarizes the types of experiments run to test the effects of dependencies in the environments and to try to discover these dependencies.

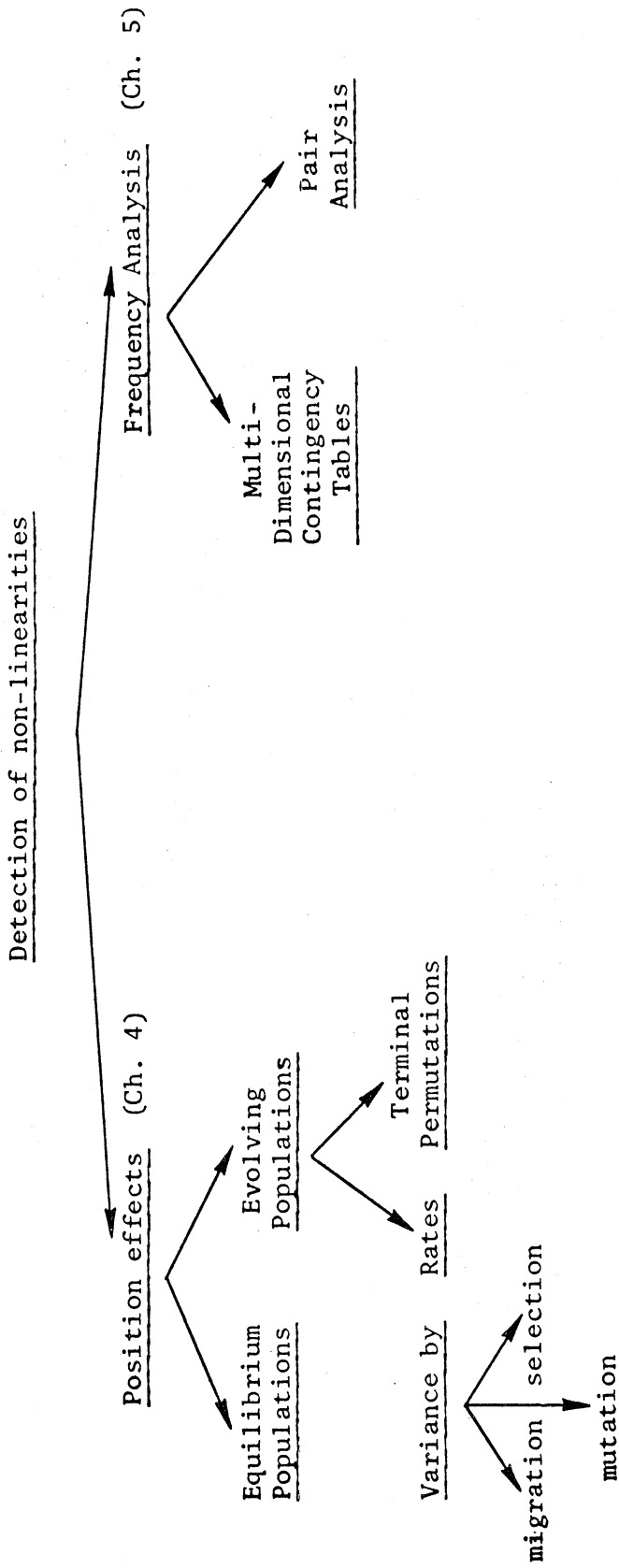


Figure 2.1: Research Schema.

CHAPTER THREE
THE EXPERIMENTAL BASIS

The Environment

The problem of deciding which environments to use in proving our point is both difficult and simple. We wish to test the reproductive plan on environments which have both linear and non-linear components, trying to separate the two effects. The difficulty is that "linear" is well-defined while "non-linear" is defined by the statement: "everything else". In all of computability theory there is little attempt to formalize or classify types of non-linearity. In functional optimization work, again, linearity is considered trivial and non-linearity is so complicated that only a few examples of non-linear environments are mentioned, mainly as benchmarks for the testing of new optimization techniques. These environments are either complicated analytic functions of a few arguments, or simple quadratic functions of many arguments. Bagley's (1) work on the "Meta-Environment" is one of the few developments directed to this area - and it was done for much the same reason we need it.

Thus, the simple part of choosing environments to search is that we have almost a free hand to select the definition of non-linearity we like, a freedom we shall definitely exercise.

Non-linearity

Although it is certainly not our intention to create a theory of

non-linearity, a few prefatory remarks are in order. (Much of the following development is similar to Bagley.)

A *linear function* of several arguments is one in which the value of the function is obtained by summing functions each of which is of, at most, one argument, for example:

$$f(x,y,z) = g(x)+h(y)+e(z).$$

Other ways of stating linearity are to say that the arguments are orthogonal or independent (relative to the function f).

One interesting property of linear functions is that they are unimodal if the component functions are unimodal, that is, they have only one maximum, no false maxima. This suggests the following procedure for maximizing linear functions, as described in Bagley (p. 43):

- 1) Choose an argument and select arbitrary values for all the other arguments.
- 2) Vary the values of the chosen argument to obtain the relative maximum.
- 3) Hold the chosen argument at the value which achieved that maximum and choose another argument which has not been previously chosen.
- 4) Go to Step 2 and repeat the process until all arguments have been assigned values.

The resulting argument values will then maximize the function. Even if component functions are multi-modal, this procedure will still find a (non-unique) optimum.

Non-linear functions are all those functions which are not linear, i.e., not able to be expressed as sums of functions of only one argument. Such functions may be

unimodal, as are some linear functions; for example,

$$f(x,y) = (x+y)^2 \quad 0 \leq x \leq 10, 0 \leq y \leq 10,$$

has its only maximum at $(x = 10, y = 10)$. On the other hand,

$$g(x,y) = (x-y)^2 \quad 0 \leq x \leq 10, 0 \leq y \leq 10,$$

has maxima at $(x = 10, y = 0)$ and $(x = 0, y = 10)$.

In summary, unimodal functions may be either linear or non-linear; but a multi-modal function must be non-linear or linear with multi-modal components. In this research arguments may take on only two values (see below). Consequently, when the total function is multi-modal it must then be non-linear.

In the case of unimodal, non-linear functions, it is possible to use the same search algorithm as for linear functions. Unimodality is all that is required for its success. These kinds of functions are very similar to linear functions because of unimodality. Consider the two functions:

$$f(x,y) = (x+y)^2 \quad \begin{array}{l} x = 1,2 \\ y = 1,2 \end{array} \quad g(x,y) = x+y \quad \begin{array}{l} x = 1,8 \\ y = 1,8 \end{array}$$

x	y	f(x,y)
1	1	4
1	2	9
2	1	9
2	2	16

x	y	g(x,y)
1	1	2
1	8	9
8	1	9
8	8	16

Both functions have only one maximum, are very close in their range of values, and yet one is linear and the other non-linear. Although we are certainly not claiming that a linear function can be found to match any unimodal, non-linear function as closely as in this case, unimodal, non-linear functions may be difficult in general to separate in their effects from linear functions.

For this reason, most of the non-linear environments we will study

will be multimodal; if we cannot detect unimodal non-linearity we will not consider it too great a loss since such environments do have simple optimization procedures (e.g., gradient or the above). We consider it sufficient to specify environments of interest merely as non-linear, multimodal for the purpose of this research.

Discreteness

The environments we shall use are discrete; that is, arguments to the function will have a finite number of substitution instances (alleles); in our case this finite number is two, and the values taken by the arguments may be 0 or 1. This is done strictly for convenience' sake in this research (which is designed to prove a point, not show all possible implementations of reproductive plans). Reporting gene frequencies is much easier with just two alleles (only one number specifies both frequencies), table look-up and compilation of tables is easier, and solution times are shorter than for cases in which more alleles are used.

This is no restriction on the kinds of environments which can be used in real problems. Hollstien (12) implemented the concept of polygene to use binary alleles in the representation of many-valued arguments. Eight genes, each having two alleles, were used to specify a Real (as compared to Integer) argument in the range 0-100, with an accuracy of ± 0.5 . These genes took part in the genetics of his system independently of each other, but at payoff calculation time they were interpreted jointly as a single number to plug into the function evaluation. The alternative to this coding is to use a single gene with 200 alleles,

all of which are adaptively significant. With this large number of alleles, adaptation is driven largely by mutation rather than by recombination, so that the advantages of search by recombination are lost.

Since we are using discrete functions we must define what is meant by "local maximum" since we intend it slightly different than in the continuous case.

If f is a function of n (discrete) arguments, then $m = f(a_1, a_2, \dots, a_n)$ is a local maximum if

$$m > f(a'_1, a_2, \dots, a_n) \quad \text{and}$$

$$m > f(a_1, a'_2, \dots, a_n) \quad \text{and}$$

$$\vdots$$

$$m > f(a_1, a_2, \dots, a'_n)$$

where

$$a_1 \neq a'_1, \dots, a_n \neq a'_n, (a'_i - a_i) \text{ sufficiently small.}$$

In coding theory this might be stated as: if m is calculated from f by the argument list A , then m is a local maximum if $m > f(A')$ for every A' which is separated from A by a Hamming distance of one. It is a reasonable definition since it states that m is a local maximum if it is greater than every value that can be reached by making the smallest possible change in the argument list.

A global maximum (or just plain maximum) is a local maximum which is at least as great as every other local maximum. Local maxima are also called peaks, and a false peak is a local maximum which is not a global maximum.

Thus far we have specified that the functions we shall search will

have binary arguments. We shall study functions with up to 25 such arguments; therefore the size of the space we must search is about 33,000,000 points. While not overly large, the space is large enough to provide a variety of possible functions and to show the power of the plan.

Functional Form

In specifying the payoff function, a table look-up procedure will be used. This has one very strong advantage: any function of the arguments may be specified without trying to find an expression for it. An analytic form is not particularly useful since all we are interested in is non-linearity. In addition, table look-up is fast. Obviously, we do not plan to use a thirty-three million place table.

We define two types of functional forms. In the first, we will divide the arguments into four groups of six, six, six, and seven arguments apiece, providing table look-ups for each group; the result of the function will be the sum of the four subfunctions. That is, for the argument list a_1, \dots, a_{25} .

$$\begin{aligned} f(a_1, \dots, a_{25}) = & g_1(a_1, a_2, a_3, a_4, a_5, a_6) \\ & + g_2(a_7, a_8, a_9, a_{10}, a_{11}, a_{12}) \\ & + g_3(a_{13}, a_{14}, a_{15}, a_{16}, a_{17}, a_{18}) \\ & + g_4(a_{19}, a_{20}, a_{21}, a_{22}, a_{23}, a_{24}, a_{25}). \end{aligned}$$

Obviously, this restricts the non-linearity of the system to at most a function of seven arguments, a (sub-) space of 128 points. Below, we describe functional forms of eight and nine arguments, spaces of 512 points. Once again, this should be sufficient for our needs; it seems to be a reasonable compromise between experimental and design contingencies.

Note that the table for a group need not be non-linear in its effects; may tabulate a linear function, a function which is non-linear in four genes and linear in two, etc. In addition, there is the element of linearity built into the final composition of f , the sum of four (possibly) non-linear functions.

In the experimental work later on, we will wish to describe the space being searched. Since all environments will be sums of groups, we need only specify the groups. A group which is strictly linear in its effects is specified, for example, by

$$g_2: L(v_0^7, v_1^7; v_0^8, v_1^8; v_0^9, v_1^9; v_0^{10}, v_1^{10}; v_0^{11}, v_1^{11}; v_0^{12}, v_1^{12})$$

where v_0 is the contribution due to a zero value for an argument and v_1 is that due to a one value. For example,

$$g_2: L(3,4;3,4;5,6;3,4;5,6;3,4)$$

specifies that group two is linear and that zero-valued arguments for genes 7,8,10, and 12 contribute three and one-valued arguments contribute four; for genes 9 and 11 the values are 5 and 6. Group four, of course, requires seven argument values.

Non-linear groups will be exactly specified by a table as in Figure 3.2; in shorthand we will specify

$$g_1: NL(A)$$

where A is a table of argument combinations and associated function values. We will summarize the table for convenience by

$$A: (\text{comb:value}, \text{comb:value}, \dots)$$

where the "comb:value" pairs describe the argument combination which forms a local maximum for the function and the value of the function at that point. For example:

$$B: (110110:24, 001001:13)$$

summarizes a table with two local maxima, one at 110110 with a function

value of 24 and the other at 001001 with a function value of 13. Since these two points are local maxima, there is a trough between them. The depth and slope of the trough is of lesser interest than the number of peaks, although some experimentation may be done on those variables also.

Thus a complete specification of the environment may appear as

ENV 3:

g_1 :NL(A)

g_2 :L(2,4;6,6;0,0;2,7;7,1;9,0)

g_3 :L(0,1;1,0;1,0;0,0;1,0;0,1)

g_4 :NL(B).

Group one is specified by table A and group four by table B. Groups two and three are linear with the contribution due to argument values as given. Note that arguments 8,9 and 16 (the second and third arguments in group two and the fourth in group three) make no distinction between their possible values. In genetic terms, these arguments are selectively neutral; it makes no difference which value they take on.

The second functional form for specifying payoff is similar to the first with the exception that there are only three additive groups, containing 8, 8, and 9 genes each. This form allows for more complex interactions between genes and makes it more unlikely that the optimum for a group will appear in an initial population by chance. We shall call these three groups g_5 , g_6 , and g_7 . Figure 3.9a is an example of this functional form.

The Payoff Function

Given the specification of the environment, then, it is easy to state the goal of a reproductive plan facing it: members of the population will attempt to specify argument values corresponding to the peaks of the environment. The payoff will be the actual environmental function value resulting from the arguments contained in an individual chromosome.

Environments Used

Following is a list of the environments used in the rest of this research. As stated above, we are limited by not having a theory of non-linearity for reference so that we cannot claim universality for the environments chosen. Those used range from completely linear to one with a simple five-gene non-linear group to one with a very complex nine-gene group. The differences among the environments are discussed in the chapters on the experimental work.

ENV 1:

$g_1 : L(0,1;0,1;0,1;0,1;0,1;0,0)$

$g_2 : L(0,0;0,0;0,0;0,0;0,0;0,0)$

$g_3 : L(0,0;0,0;0,0;0,0;0,0;0,0)$

$g_4 : L(0,0;0,0;0,0;0,0;0,0;0,0;0,0)$

Figure 3.1: Environment 1.

Payoff group A:

000000	3	010000	2	100000	2	110000	1
000001	3	010001	2	100001	2	110001	1
000010	2	010010	1	100010	1	110010	1
000011	2	010011	1	100011	1	110011	1
000100	2	010100	1	100100	1	110100	1
000101	2	010101	1	100101	1	110101	1
000110	1	010110	1	100110	1	110110	2
000111	1	010111	1	100111	1	110111	2
001000	2	011000	1	101000	1	111000	1
001001	2	011001	1	101001	1	111001	1
001010	1	011010	1	101010	1	111010	2
001011	1	011011	1	101011	1	111011	2
001100	1	011100	1	101100	1	111100	2
001101	1	011101	1	101101	1	111101	2
001110	1	011110	2	101110	2	111110	3
001111	1	011111	2	101111	2	111111	3

Summary: A:(00000:3, 11111:3)
 (Note that the sixth gene is neutral)

Figure 3.2(a): Payoff Group A.

ENV 2: $g_1:NL(A)$
 $g_2:L(0,0;0,0;0,0;0,0;0,0;0,0)$
 $g_3:L(0,0;0,0;0,0;0,0;0,0;0,0)$
 $g_4:L(0,0;0,0;0,0;0,0;0,0;0,0)$

Figure 3.2(b): Environment 2.

Payoff group B

000000	3	010000	5	100000	5	110000	7
000001	6	010001	3	100001	3	110001	5
000010	6	010010	3	100010	3	110010	5
000011	8	010011	6	100011	6	110011	3
000100	5	010100	7	100100	7	110100	9
000101	3	010101	5	100101	5	110101	7
000110	3	010110	5	100110	5	110110	7
000111	6	010111	3	100111	3	110111	5
001000	6	011000	3	101000	3	111000	5
001001	8	011001	6	101001	6	111001	3
001010	8	011010	6	101010	6	111010	3
001011	10	011011	8	101011	8	111011	6
001100	3	011100	5	101100	5	111100	7
001101	6	011101	3	101101	3	111101	5
001110	6	011110	3	101110	3	111110	5
001111	8	011111	6	101111	6	111111	3

Summary: B:(001011:10, 110100:9)

Figure 3.3(a): Payoff Group B.

ENV 3: $g_1:NL(B)$
 $g_2:L(0,1;0,1;0,1;0,1;0,1;0,1)$
 $g_3:L(0,1;0,1;0,1;0,1;0,1;0,1)$
 $g_4:L(0,1;0,1;0,1;0,1;0,1;0,1)$

Figure 3.3(b): Environment 3.

ENV 4:

g_1 :L(9,10;9,10;9,10;9,10;9,10;0,0)

g_2 :L(0,0;0,0;0,0;0,0;0,0;0,0)

g_3 :L(0,0;0,0;0,0;0,0;0,0;0,0)

g_4 :L(0,0;0,0;0,0;0,0;0,0;0,0)

Figure 3.4: Environment 4.

Payoff group C:

000000	8	010000	7	100000	7	110000	6
000001	8	010001	7	100001	7	110001	6
000010	7	010010	6	100010	6	110010	6
000011	7	010011	6	100011	6	110011	6
000100	7	010100	6	100100	6	110100	6
000101	7	010101	6	100101	6	110101	6
000110	6	010110	6	100110	6	110110	7
000111	6	010111	6	100111	6	110111	7
001000	7	011000	6	101000	6	111000	6
001001	7	011001	6	101001	6	111001	6
001010	6	011010	6	101010	6	111010	7
001011	6	011011	6	101011	6	111011	7
001100	6	011100	6	101100	6	111100	7
001101	6	011101	6	101101	6	111101	7
001110	6	011110	7	101110	7	111110	8
001111	6	011111	7	101111	7	111111	8

Summary: C:(00000:8, 11111:8)

Figure 3.5(a): Payoff Group C.

ENV 5:

- g_1 :NL(C)
- g_2 :L(0,0;0,0;0,0;0,0;0,0;0,0)
- g_3 :L(0,0;0,0;0,0;0,0;0,0;0,0)
- g_4 :L(0,0;0,0;0,0;0,0;0,0;0,0;0,0)

Figure 3.5(b): Environment 5.

Payoff group D:

000000	13	010000	15	100000	15	110000	17
000001	16	010001	13	100001	13	110001	15
000010	16	010010	13	100010	13	110010	15
000011	18	010011	16	100011	16	110011	13
000100	15	010100	17	100100	17	110100	19
000101	13	010101	15	100101	15	110101	17
000110	13	010110	15	100110	15	110110	17
000111	16	010111	13	100111	13	110111	15
001000	16	011000	13	101000	13	111000	15
001001	18	011001	16	101001	16	111001	13
001010	18	011010	16	101010	16	111010	13
001011	20	011011	18	101011	18	111011	16
001100	13	011100	15	101100	15	111100	17
001101	16	011101	13	101101	13	111101	15
001110	16	011110	13	101110	13	111110	15
001111	18	011111	16	101111	16	111111	13

Summary: D:(001011:20, 110100:19)

Figure 3.6(a): Payoff Group D.

ENV 6: $g_1^{NL(D)}$
 $g_2:L(0,1;0,1;0,1;0,1;0,1;0,1)$
 $g_3:L(0,1;0,1;0,1;0,1;0,1;0,1)$
 $g_4:L(0,1;0,1;0,1;0,1;0,1;0,1;0,1)$

Figure 3.6(b): Environment 6.

Payoff group E:

000000	9	010000	10	100000	11	110000	10
000001	12	010001	7	100001	8	110001	7
000010	7	010010	8	100010	9	110010	8
000011	6	010011	7	100011	8	110011	7
000100	7	010100	8	100100	9	110100	8
000101	6	010101	7	100101	8	110101	7
000110	6	010110	7	100110	8	110110	7
000111	8	010111	10	100111	10	110111	9
001000	10	011000	11	101000	10	111000	9
001001	7	011001	8	101001	7	111001	6
001010	8	011010	9	101010	8	111010	7
001011	7	011011	8	101011	7	111011	13
001100	8	011100	9	101100	8	111100	7
001101	7	011101	8	101101	7	111101	6
001110	7	011110	13	101110	7	111110	6
001111	9	011111	10	101111	9	111111	8

Summary: E: (000001:12, 011110:13, 111011:13,
011000:11, 100000:11, 011000:11)

Group E is made up of the two non-linear subgroups

E1:

000	3
001	4
010	4
011	5
100	5
101	4
110	4
111	3

E2:

000	6
001	3
010	4
011	3
100	4
101	3
110	3
111	5

E1: (011:5, 100:5) E2: (000:6, 111:5)

which add linearly except for the points

000001	12
011110	13
111011	13

Figure 3.7(a): Payoff Group E.

Payoff Group F:

Made up of the two non-linear subgroups F1 and F2,
which add linearly.

F1:	000	6	F2:	0000	5	1000	4
	001	5		0001	4	1001	5
	010	5		0010	4	1010	5
	011	4		0011	5	1011	6
	100	5		0100	6	1100	5
	101	4		0101	5	1101	4
	110	4		0110	5	1110	4
	111	5		0111	4	1111	5
F1:	(000:6,111:5)		F2:	(0100:6,1011:6)			

Figure 3.7(b): Payoff Group F.

ENV 7:

g_1 :NL(B)

g_2 :NL(A)

g_3 :NL(E)

g_4 :NL(F)

Figure 3.7(c): Environment 7.

ENV 8:

g_1 :NL(B)

g_2 :NL(B)

g_3 :NL(B)

g_4 :L(0,1;0,1;0,1;0,1;0,1;0,1;0,1)

Figure 3.8: Environment 8.

Payoff group G.

00000000	4	01000000	4	10000000	6	11000000	4
00000001	4	01000001	5	10000001	5	11000001	5
00000010	4	01000010	4	10000010	5	11000010	5
00000011	4	01000011	4	10000011	4	11000011	4
00000100	5	01000100	6	10000100	5	11000100	4
00000101	4	01000101	4	10000101	5	11000101	4
00000110	5	01000110	4	10000110	4	11000110	5
00000111	4	01000111	4	10000111	4	11000111	5
00001000	4	01001000	6	10001000	4	11001000	5
00001001	4	01001001	4	10001001	4	11001001	5
00001010	5	01001010	5	10001010	5	11001010	5
00001011	5	01001011	4	10001011	5	11001011	5
00001100	6	01001100	8	10001100	4	11001100	6
00001101	5	01001101	6	10001101	4	11001101	4
00001110	5	01001110	6	10001110	4	11001110	4
00001111	5	01001111	4	10001111	4	11001111	5
00010000	6	01010000	6	10010000	7	11010000	6
00010001	4	01010001	5	10010001	6	11010001	5
00010010	5	01010010	4	10010010	6	11010010	5
00010011	5	01010011	4	10010011	4	11010011	4
00010100	5	01010100	4	10010100	6	11010100	5
00010101	4	01010101	4	10010101	5	11010101	5
00010110	4	01010110	4	10010110	5	11010110	4
00010111	4	01010111	5	10010111	4	11010111	5
00011000	4	01011000	4	10011000	6	11011000	5
00011001	4	01011001	4	10011001	5	11011001	5
00011010	4	01011010	4	10011010	5	11011010	5
00011011	4	01011011	5	10011011	5	11011011	5
00011100	4	01011100	6	10011100	4	11011100	4
00011101	5	01011101	5	10011101	5	11011101	5
00011110	4	01011110	4	10011110	4	11011110	4
00011111	4	01011111	5	10011111	5	11011111	8
00100000	6	01100000	6	10100000	7	11100000	6
00100001	5	01100001	5	10100001	6	11100001	5
00100010	4	01100010	5	10100010	6	11100010	4
00100011	5	01100011	4	10100011	5	11100011	4
00100100	5	01100100	5	10100100	6	11100100	4
00100101	4	01100101	4	10100101	5	11100101	5
00100110	5	01100110	4	10100110	5	11100110	5
00100111	5	01100111	5	10100111	4	11100111	4
00101000	5	01101000	4	10101000	6	11101000	4
00101001	5	01101001	5	10101001	5	11101001	5
00101010	4	01101010	5	10101010	4	11101010	4
00101011	4	01101011	5	10101011	5	11101011	5
00101100	4	01101100	6	10101100	4	11101100	4
00101101	5	01101101	5	10101101	5	11101101	4

Figure 3.9(a): Payoff Group G.
(Cont'd)

00101110	5	01101110	5	10101110	4	11101110	4
00101111	4	01101111	4	10101111	5	11101111	8
00110000	7	01110000	6	10110000	8	11110000	7
00110001	6	01110001	6	10110001	7	11110001	6
00110010	6	01110010	6	10110010	7	11110010	6
00110011	5	01110011	4	10110011	6	11110011	4
00110100	6	01110100	6	10110100	7	11110100	6
00110101	4	01110101	4	10110101	6	11110101	4
00110110	4	01110110	5	10110110	6	11110110	4
00110111	4	01110111	5	10110111	5	11110111	8
00111000	6	01111000	6	10111000	7	11111000	6
00111001	5	01111001	5	10111001	6	11111001	4
00111010	5	01111010	5	10111010	6	11111010	5
00111011	5	01111011	4	10111011	5	11111011	8
00111100	5	01111100	5	10111100	6	11111100	4
00111101	5	01111101	5	10111101	4	11111101	8
00111110	5	01111110	4	10111110	5	11111110	8
00111111	4	01111111	8	10111111	8	11111111	9

Summary: $G:(11111111:9, 10110000:8, 01001100:8)$

Neighbors of the first peak pay 8. Neighbors of the second peak pay 7 and their neighbors pay 6. Neighbors of the third peak pay 6. All other points pay 4 or 5 randomly.

Figure 3.9(a): Payoff Group G.

ENV 9: $g_5:NL(G)$
 $g_6:L(0,1;0,1;0,1;0,1;0,1;0,1;0,1;0,1)$
 $g_7:L(0,1;0,1;0,1;0,1;0,1;0,1;0,1;0,1;0,1)$

Figure 3.9(b): Environment 9.

Payoff group H:

00000000	8	01000000	6	10000000	6	11000000	3
00000001	6	01000001	3	10000001	5	11000001	5
00000010	6	01000010	5	10000010	4	11000010	3
00000011	4	01000011	5	10000011	3	11000011	3
00000100	6	01000100	4	10000100	5	11000100	3
00000101	4	01000101	4	10000101	4	11000101	3
00000110	5	01000110	3	10000110	4	11000110	3
00000111	4	01000111	4	10000111	5	11000111	4
00001000	6	010001000	4	100001000	5	110001000	3
00001001	4	010001001	5	100001001	4	110001001	3
00001010	5	010001010	4	100001010	5	110001010	4
00001011	4	010001011	3	100001011	5	110001011	4
00001100	3	010001100	5	100001100	4	110001100	4
00001101	5	010001101	3	100001101	5	110001101	5
00001110	4	010001110	5	100001110	5	110001110	4
00001111	5	010001111	4	100001111	3	110001111	4
000010000	6	010010000	3	100010000	4	110010000	4
000010001	3	010010001	5	100010001	5	110010001	3
000010010	5	010010010	3	100010010	5	110010010	5
000010011	4	010010011	5	100010011	3	110010011	5
000010100	4	010010100	5	100010100	5	110010100	4
000010101	3	010010101	4	100010101	5	110010101	5
000010110	4	010010110	5	100010110	3	110010110	4
000010111	3	010010111	3	100010111	3	110010111	5
000011000	4	010011000	4	100011000	5	110011000	5
000011001	3	010011001	5	100011001	5	110011001	5
000011010	4	010011010	3	100011010	4	110011010	5
000011011	5	010011011	5	100011011	5	110011011	4
000011100	5	010011100	3	100011100	4	110011100	4
000011101	3	010011101	5	100011101	4	110011101	5
000011110	5	010011110	3	100011110	3	110011110	4
000011111	5	010011111	4	100011111	3	110011111	4

Figure 3.10(a): Payoff Group H.
(Cont'd)

000100000	6	010100000	3	100100000	5	110100000	3
000100001	5	010100001	4	100100001	5	110100001	4
000100010	3	010100010	5	100100010	5	110100010	3
000100011	5	010100011	3	100100011	5	110100011	3
000100100	5	010100100	3	100100100	5	110100100	3
000100101	5	010100101	3	100100101	5	110100101	5
000100110	4	010100110	5	100100110	5	110100110	4
000100111	5	010100111	4	100100111	4	110100111	5
000101000	3	010101000	5	100101000	3	110101000	5
000101001	5	010101001	3	100101001	5	110101001	4
000101010	5	010101010	3	100101010	4	110101010	3
000101011	3	010101011	5	100101011	4	110101011	5
000101100	6	010101100	5	100101100	4	110101100	4
000101101	4	010101101	3	100101101	3	110101101	5
000101110	5	010101110	5	100101110	5	110101110	5
000101111	4	010101111	5	100101111	4	110101111	5
000110000	5	010110000	5	100110000	5	110110000	5
000110001	5	010110001	4	100110001	5	110110001	3
000110010	4	010110010	4	100110010	3	110110010	3
000110011	3	010110011	4	100110011	5	110110011	4
000110100	5	010110100	5	100110100	5	110110100	4
000110101	3	010110101	5	100110101	3	110110101	5
000110110	4	010110110	3	100110110	3	110110110	4
000110111	3	010110111	3	100110111	3	110110111	5
000111000	5	010111000	4	100111000	3	110111000	4
000111001	3	010111001	5	100111001	5	110111001	3
000111010	4	010111010	3	100111010	3	110111010	3
000111011	4	010111011	5	100111011	5	110111011	3
000111100	4	010111100	3	100111100	5	110111100	3
000111101	5	010111101	5	100111101	5	110111101	3
000111110	3	010111110	5	100111110	5	110111110	4
000111111	3	010111111	5	100111111	5	110111111	8
001000000	6	011000000	4	101000000	5	111000000	3
001000001	4	011000001	3	101000001	3	111000001	4
001000010	5	011000010	5	101000010	3	111000010	3
001000011	3	011000011	4	101000011	3	111000011	5
001000100	3	011000100	5	101000100	5	111000100	4
001000101	3	011000101	5	101000101	4	111000101	5
001000110	4	011000110	5	101000110	4	111000110	3
001000111	3	011000111	4	101000111	5	111000111	4
001001000	3	011001000	3	101001000	5	111001000	3
001001001	4	011001001	4	101001001	3	111001001	4
001001010	5	011001010	5	101001010	3	111001010	3
001001011	4	011001011	5	101001011	5	111001011	4
001001100	6	011001100	3	101001100	4	111001100	4
001001101	4	011001101	4	101001101	4	111001101	3
001001110	3	011001110	3	101001110	3	111001110	4
001001111	5	011001111	4	101001111	5	111001111	4

Figure 3.10(a): Payoff Group H.
(Cont'd)

001010000	5	011010000	4	101010000	3	111010000	5
001010001	3	011010001	4	101010001	5	111010001	4
001010010	5	011010010	4	101010010	3	111010010	4
001010011	4	011010011	3	101010011	5	111010011	5
001010100	4	011010100	4	101010100	3	111010100	3
001010101	4	011010101	3	101010101	4	111010101	4
001010110	3	011010110	3	101010110	4	111010110	5
001010111	3	011010111	3	101010111	3	111010111	5
001011000	4	011011000	4	101011000	3	111011000	5
001011001	3	011011001	4	101011001	5	111011001	3
001011010	5	011011010	3	101011010	4	111011010	4
001011011	4	011011011	4	101011011	5	111011011	5
001011100	5	011011100	3	101011100	5	111011100	4
001011101	4	011011101	5	101011101	5	111011101	3
001011110	3	011011110	5	101011110	4	111011110	4
001011111	5	011011111	5	101011111	5	111011111	8
001100000	5	011100000	3	101100000	4	111100000	3
001100001	4	011100001	4	101100001	5	111100001	4
001100010	4	011100010	4	101100010	5	111100010	4
001100011	3	011100011	5	101100011	4	111100011	4
001100100	6	011100100	4	101100100	4	111100100	3
001100101	5	011100101	3	101100101	3	111100101	5
001100110	5	011100110	5	101100110	4	111100110	4
001100111	3	011100111	3	101100111	4	111100111	3
001101000	6	011101000	4	101101000	5	111101000	3
001101001	5	011101001	5	101101001	3	111101001	4
001101010	4	011101010	4	101101010	5	111101010	5
001101011	5	011101011	4	101101011	6	111101011	3
001101100	8	011101100	6	101101100	3	111101100	5
001101101	6	011101101	5	101101101	3	111101101	5
001101110	6	011101110	3	101101110	3	111101110	4
001101111	3	011101111	4	101101111	3	111101111	5
001110000	3	011110000	5	101110000	5	111110000	3
001110001	3	011110001	5	101110001	5	111110001	3
001110010	3	011110010	4	101110010	5	111110010	4
001110011	3	011110011	3	101110011	3	111110011	3
001110100	3	011110100	3	101110100	5	111110100	4
001110101	5	011110101	4	101110101	5	111110101	5
001110110	4	011110110	3	101110110	4	111110110	4
001110111	5	011110111	4	101110111	5	111110111	8
001111000	5	011111000	4	101111000	3	111111000	5
001111001	4	011111001	4	101111001	3	111111001	5
001111010	3	011111010	4	101111010	5	111111010	5
001111011	3	011111011	3	101111011	5	111111011	8
001111100	6	011111100	3	101111100	3	111111100	4
001111101	3	011111101	5	101111101	3	111111101	5
001111110	5	011111110	4	101111110	5	111111110	5
001111111	3	011111111	4	101111111	4	111111111	9

Figure 3.10(a): Payoff Group H.
(Cont'd)

Summary: H:(111111111:9, 000000000:8, 001101100:8)

Neighbors of the second and third peaks pay 6. Only four neighbors of the first peak pay 8:110111111, 111011111, 111110111, and 111111011. All other points pay 3,4, or 5 randomly.

Figure 3.10(a): Payoff Group H.

ENV 10: g_5 :NL(G) .

g_6 :NL(G)

g_7 :NL(H)

Figure 3.10(b): Environment 10.

The Adaptive Program

Every researcher who uses the reproductive algorithm has many choices to make, among them:

- 1) What are the "genes"? How many are there in a chromosome?
How many alleles should there be?
- 2) What operators should be used? With what parameter settings?
- 3) What size should the population be?

One choice he does not have is that of selection, at least if he is going to use Holland's (11) theory in its exact form to attain the efficiency it guarantees: selection of parents for the next generation must be according to payoff.

Genes, Alleles, and Chromosomes

A researcher's decision on genes and alleles depends on his knowledge of the environment and on the level at which he wishes to model it. In general this may be a very difficult question as discussed in Chapter Two, but for our purposes it is much easier. We are facing an artificial environment in which there may be as many as 25 parameters which affect the payoff; each parameter may take on one of two values. (We do not wish to minimize the difficulty involved in complex gene encodings such as used by others (3 and 12). It's just that once an encoding is determined it induces a function and it is the induced function that we wish to investigate.)

Thus, each of 25 genes will correspond to one argument in the environment and will have two possible alleles, 0 and 1. Our goal is

then to match every gene to the argument value in the environment which maximizes the environmental function value. Because a gene may occupy any position on a chromosome, it is "tagged"; every position on the chromosome has two numbers associated: the number of the gene occupying that position and the allele of that gene represented. A chromosome might be represented as the following:

$$(13,1)(2,1)(22,0),\dots$$

At the leftmost of 25 positions is gene 13, represented by allele 1. At the second position is gene 2 with allele 1; the fact that gene 2 occupies position 2 is purely accidental. Every gene is represented exactly once in the chromosome.

The individuals in our population are haploid chromosomes; that is, an individual is specified by a single string of 25 genes. (We will use the terms individual, member of the population, string, and chromosome interchangeably.) Facing other environments we might have chosen chromosomes to be diploid (composed of two strings of genes), as are the chromosomes of most of the "higher" animals and plants. Diploidy and the associated concept of dominance seem to be optimal for living organisms because of their requirements in adapting to very complex, changing environments. In artificial systems of the sort we are dealing with the environment is stationary so that the population need not change after it has reached the stable optimum. Hollstien (12) has achieved some success in diploidy and modifiable dominance facing a cyclically changing environment. (In populations made up of diploid individuals, a single string of genes is called a gamete. In our case, then, we have one gamete chromosomes.)

Population Size

Cavicchio (3) and Hollstien (12) did not use the strict form of selection required by Holland's theory. Their small populations made it mandatory to use breeding plans to keep a high level of performance, once achieved, and to make special efforts to maintain the variability of the population. The disadvantages of their modifications are large: loss of the efficiency guaranteed by the theory and excessive programming of tricks and special cases with consequent loss of the easy attribution of credit for success. The advantages lie in the small number of payoff evaluations per generation, reduced computer running time, and less storage required to run their programs.

We are not interested in minimizing payoff evaluations since we are taking as a premise that the Holland Reproductive Plan is efficient and we do not need to compare it to anything else to justify its use. Cavicchio and Hollstien have done that. Besides, it is not clear that small populations actually reduce the evaluations needed in very complex environments. Small populations are much more likely to be subject to genetic drift and get hung up on a false peak. While the reproductive plan's stochastic operators provide a method for getting off such peaks, it is likely to take quite a while to do so. The inherently larger variability of large populations make it less likely that this will happen. Finally, in this sort of artificial system, there is much force in the argument that it is not a good population that we want, but a single, good individual from the population; and the fastest way to search the space is to have a large number of individuals with a lot of mixing.

One of Cavicchio's biggest problems was maintaining population variance. Because of his small populations, good alleles were often lost before their effects could make themselves known. He ultimately tried three or four kinds of mutation operators and special selection techniques strictly to maintain variance. In population genetics this problem goes by the name of genetic drift: the variance in frequency of occurrence of alleles due to stochastic effects. If the mutation rate is small enough, an allele might be fixed randomly: In a simple one gene, two allele model of a haploid population in which the rates of mutation from one allele to the other are identical, and in which there is no advantage in either allele, "if the mutation rates are half the reciprocal of the population size the gene frequency is equally likely to have any value between 0 and 1" (P.A.P. Moran, p. 125). Thus, we can keep the mutation rate down to a reasonable size, say .005 (which means that mutation is doing its proper job of just providing variability - not searching the space) and still get by with a population of 100. Actually we do not require as much variability as Moran suggests we will get with this size population and mutation. All that is required is that some alleles of every sort will normally be available in the population, not that we will have a lot. However, since we will be performing selection and since our model includes more than one gene, we will use this approximation (100 members and mutation rate of .005) as a starting point in our investigation.

Mating and the Genetic Operators

A new population is generated from the old, one individual at a time, by means of "genetic" operators. First, two parents are selected

from the old population. (Selection is discussed in the next section.) The operators are then applied to these two chromosomes to produce a new individual. During the course of this research several versions of mating schemes and the operators are used; the description of an experiment will indicate which methods were used. Some of the methods were suggested by experience after experimentation but all are described here for completeness' sake. Many are artificial--not genetic.

The exact order of operator application is dependent on the methods being used to handle the homology/inversion problem. The problem is that when two chromosomes are non-homologous (the order of genes on the chromosome is not identical), crossover between them may produce individuals with a surplus of some genes and a lack of others. Four mating methods may be used to avoid such aberrant offspring: strict-homology, viability, any-pattern, and best-pattern.

The *strict-homology mating* rule requires the two parents to be strictly homologous for them even to be considered for crossover. If they are not, no offspring is produced and two more parents are chosen. The *viability mating* allows crossover to take place between any two parents, but only those offspring containing exactly one of each gene will be allowed to join the new population. To illustrate the difference between these two methods, consider the two eight-gene chromosomes C_1 and C_2 , under consideration as possible parents:

Position	1	2	3	4	5	6	7	8
C_1	A	B	C	D	E	F	G	H
C_2	A	E	D	C	B	F	G	H

where the capital letters A-H indicate the gene function, not alleles. These chromosomes are not homologous (the genes in positions 2-5 do not

match exactly) and so would be rejected as parents by the strict-homology mating rule. Under the viability rule, crossover would first take place and the resulting chromosome examined. If crossover takes place between positions 2-3, 3-4, or 4-5, the resultant chromosomes will be inviable; that is they will be deficient in one or more genes. For example, crossover between positions 2 and 3 results in the chromosomes

A B D C B F G H

A E C D E F G H

the first lacking gene E and the second lacking gene B. If, however, crossover takes place between positions 6 and 7 (among other possibilities), the two resulting chromosomes are viable; that is, they each have one of the eight genes. (The term inviable is a reflection of the genetic situation in which a gene usually specifies enzymes needed to carry out a particular cellular function. If the enzymes are missing, the cell does not have the capability to maintain its own existence long enough to reproduce. In our case, a missing gene means that not all arguments of the environment are being specified, a situation in which the payoff function is not well defined.)

The *best-pattern mating* rule (2) handles non-homologies by choosing the pattern of the resultant chromosome to be the pattern of that parent with the highest payoff. (If the payoffs are equal, one is chosen at random.) The rationale for this method is that if the pattern of genes on the chromosome contributes at all to the value of the chromosome, then on the average, better chromosomes are better because of the pattern, and that pattern should be rewarded. In the above example, if the particular alleles present in C_2 yielded a higher payoff than the

alleles of C_1 , then the pattern of the result would be that of C_2 . (This point will be discussed further in Chapter Four.) This method does not correspond to anything in genetics but is an attempt to reward patterns directly. Every pair of parents can yield offspring under this method.

As an example, suppose that we have the two chromosomes

$$C_3 (1,0) (3,0) (2,1) (4,0) (5,1) (6,1)$$

$$C_4 (1,1) (2,0) (6,0) (5,1) (4,1) (3,0),$$

that C_3 has a higher payoff than C_4 , and that crossover is to take place between positions 3 and 4. Then the pattern of genes to be used is the pattern of C_3 (i.e., 1,3,2,4,5,6). One possible crossover result would then take the alleles for genes 1,3, and 2 from C_3 , and the alleles for 4,5, and 6 from C_4 , yielding:

$$(1,0) (3,0) (2,1) (4,1) (5,1) (6,0)$$

and the other possible result is

$$(1,1) (3,0) (2,0) (4,0) (5,1) (6,1).$$

Any-pattern mating is similar to best-pattern with the exception that the parent from which to take the pattern is chosen randomly.

Inversion

We shall use two ways of choosing inversion points: linear and linear+end. In the *linear inversion* method, two positions are chosen randomly (i.e., each position has an equally likely probability of being chosen) and all genes between and including these positions are inverted. For example, if the chromosome

A B C D E F G H

is to be inverted between positions 2 and 5, the resulting individual

is:

A E D C B F G H.

Since inversions are attempts to change the adjacencies of genes we would hope that an inversion rule would produce all adjacencies with equal probability to facilitate testing. One way to approach this goal (which is desirable, not necessary) is to ask that every position in the string be equally likely to be included in an inversion. However, using the linear algorithm described above, this is not the case. Positions close to the center of the string have a much greater chance to be moved by an inversion (i.e., be in an inverted segment) than positions near the end. The exact form is a quadratic in m , the position in the string. If N is the number of positions on the string, then the probability of any position being inverted is:

$$(2/N^2)(m(N+1)-m^2-1),$$

or for $N = 25$,

$$(2/625)(26m-m^2-1)$$

In this case the central position is almost seven times more likely to be included in an inversion than either of the two ends, making it difficult for any gene starting out in the end position to be tested close to a gene on the other end.

The *linear+end inversion* method was designed to alleviate this problem. In choosing positions, it does the same choice as the linear method three-quarters of the time; with probability one-eighth it does an inversion between position one and a position randomly chosen between two and thirteen; also with probability one-eighth it does an inversion between position twenty-five and a position randomly chosen between thirteen and twenty-four. The probabilities then for a position to be

included in an inverted segment are much more nearly equal, with all but positions 1,2,24, and 25 having nearly identical probabilities and those positions differing by a factor of less than one-half. Since our goal was only to attain reasonable mixing, no further refinement will be attempted.

Inversions may be introduced into the population in the following two manners. In the *continuous inversion* method, as every individual is created it has a probability of undergoing inversion. Two positions are selected (as above) and the genes between the two points are inverted. Every chromosome undergoing inversion has a probability of having different sections inverted. For example, if a population has only one pattern, and if six new individuals undergo inversion, it is highly likely that there are six new, different patterns in the new population. This certainly presents a problem in homology and we would expect this method to work well only with the viability, any-pattern, or best-pattern mating rules. Combining it with the strict-homology rule yields the same kind of system as Bagley used and the same kinds of problems: any chromosome which has undergone inversion has a very small probability of finding another chromosome with the same pattern.

The *mass inversion* method was designed to overcome the problems of the strict-homology mating rule, but may easily be used with either of the other three rules. No inversion is performed until an entire new population has been generated. At that time, with a given probability exactly half of the population undergoes exactly the same inversion. (The half chosen is the odd-numbered individuals. No bias is introduced because all individuals are generated independently.) For example, if an inversion is to be performed on an entirely homologous population of

100 individuals, then there would result two patterns in the population, each represented by 50 individuals. There is then a fairly high probability ($1/2$) that any two members chosen to be parents will be homologous.

Crossover

In the course of this research two different methods of selecting recombination points are used. The first, *one-crossover*, chooses exactly one point on the chromosome at which to perform crossover. This was used for most of the experiments except those in which we decided that slightly more mixing was desired. It operated as follows. One of the 24 points of connection was chosen randomly, each point being equiprobable. All the genes to the left of this point on one of the parent chromosomes became the left hand part of the new chromosome and all the genes to the right of this point on the other parent became the right hand side of the new chromosome. (It does not matter which of the parents contributes to the right or left since they are selected independently of each other.) Problems involving non-homology are handled by the mating rules. One alteration to this scheme is necessary under best-pattern mating, as described above.

Multiple-crossover is used where slightly more mixing of the two parents is desired. The leftmost gene of a new individual is supplied by one of the parents, say C_1 . There is then a probability, P_{cross} , that the second position on the new chromosome will be filled from the other parent, C_2 . Correspondingly, with probability $1 - P_{\text{cross}}$ the next gene will come from the second position of C_1 . Once a switch has been made to supplying genes from C_2 , there is then the probability P_{cross}

that the next position will come from C_1 , and so on. This corresponds to a random walk down the two parents with probability P_{cross} of shifting to the other parent. There is a finite probability, $(1-P_{\text{cross}})^{24}$, that no crossover will take place as a result of this method. If this is the case, the individual is regenerated via the one-crossover method.

Mutation

Mutation is a simple operator. After a new individual is generated, every allele is changed (from 0 to 1 or from 1 to 0) with probability P_{mut} . Ordinarily P_{mut} will be very small.

Migration

In genetics, migration is the actual physical movement of organisms from outside an otherwise closed population (a deme) into that deme. In the usual sense of the word it is applied to situations in which the deme under question is adapted to its environment and the migrating individuals, while members of the same species and containing many of the same genes, are adapted to another environment. The migrating individuals thus contain different alleles or, at least, their frequency of allelic occurrences are different. The effect of migration on a deme (if continuous) is to increase the variability of the population and to keep it from becoming too specialized. The use of migration is further explained and justified in Chapter Four, "Variance by Migration".

The migration rate per generation is determined as a variable of the experiment: N_{mig} individuals enter the population as immigrants.

The genetic constitution of an immigrant must be similar to that of the deme to ensure that it is sufficiently adapted to contribute to the next generation. To this end, an immigrant will be created as follows: A chromosome is selected in the same manner as parents are selected (i.e., according to relative payoff). The same gene pattern is used for the immigrant but one-third of the alleles in the "parent" are mutated. If the inversion time is continuous, the new individual undergoes inversion with the given probability. The immigrant then enters the population differing from some member of the parent population by an average of eight alleles and possibly an inversion.

Selection

Selection of parents randomly with sampling probability in proportion to relative payoff is the method by which Holland's theory guarantees efficiency. This research will follow the theory exactly. Since the previous work in this area has not done so, it is worth while considering the Monte Carlo algorithm actually used.

The members of the parent population are denoted by C_i , $i = 1, \dots, 100$. PAY_i is the payoff for individual i ; all payoffs are integer (i.e., whole valued) numbers. We form the array CUM_i ($i = 1, \dots, 100$) as follows:

$$CUM_i = \sum_{j=1}^i PAY_j.$$

CUM is similar to the concept of cumulative probability distribution, except that it is not normalized to 1.0.

To select a parent we first generate a uniformly distributed random integer in the range $(0, CUM_{100})$; call it RN. The index of the parent

selected is then the least i such that $CUM_i > RN$.

In ALGOL terms this might appear as:

```
for i: 1 step 1 until 100 do
  if CUM[i] > RN then goto done;
```

The probability that individual i is selected is then

$$\frac{PAY_i}{\sum_{j=1}^{100} PAY_j}$$

as required by the theory.

Monte Carlo Methods

The random numbers mentioned here are, of course, members of a pseudo-random number sequence, generated algorithmically. The particular generator used in this work is

$$\mu = \mu(2^{14}-3) \text{Mod } 2^{28}$$

a multiplicative congruential method as described in *CACM*, January 1967, p. 40, Algorithm #294. The subroutine RAND! called with an integer parameter, N , uses this method to return a number in the range $(0, N-1)$, such that each number in the range has probability $1/N$ of being selected. Without discussing the well-known problems introduced by subtle biases in such pseudo-random sequences, we shall accept this generator as sufficiently random for our purposes. There is a definite advantage in the technique of being able to start the random number sequence at exactly the same place at the beginning of an experiment for debugging purposes. Suitable randomization of initial conditions must be used to avoid biases.

Many of the experimental variables used are probabilities. These are usually expressed as positive integers in the program, the interpretation being that the fraction represented is 1/1000 that of the integer. Testing whether an event occurs (for example, mutation) is merely a matter of asking whether $RAND!(1000)$ is less than P_{mut} . The reason for using integer representations for probabilities is that REAL (i.e., fractional) arithmetic on the computer employed in these experiments takes significantly longer than integer arithmetic. No loss in "randomness" is experienced; the only loss is in a restriction of resolving power to one part in a thousand.

Each complete specification of the adaptive program parameters is dignified with a separate number (called the *case* number) for identification purposes. Each case runs for a given number of generations. To try to separate random fluctuations from the effects of the program parameters we can reinitialize the adaptive system with the same population but with the random number generator starting at a different point. Each start with the same population and parameters is called a *run* of the case. Typically we will use from 5 to 10 runs for every experiment and use some statistical measure based on these runs. A series of cases will sometimes be identified by a letter and number (as A1) for convenience.

Program Description

Now that all the pieces have been presented, we can give a general description of the whole process. The language used in the program is CESSL (7), a procedure oriented language similar to ALGOL and FORTRAN; it was developed locally for other purposes but lends itself admirably

to our needs. Since it is available only at this one research installation we shall not include any of the actual programs used, but only algorithms, given in flow charts or by a sort of ALGOL notation.

At the start of an experiment the entire population receives the same pattern of genes on the chromosome; each allele is set randomly to 0 or 1. The payoff PAY_i is then calculated for each member and the CUM array formed from PAY.

Creation of a new population proceeds as follows. Two parents are selected from the old population, as described above. A new individual is formed by crossover using one of the three mating methods. (If there is a homology or viability problem, two new parents are first selected.) If the inversion time is "continuous", the new individual undergoes inversion with a certain probability. Every gene then is mutated according to the given probability. The individual thus formed enters the new population, and the next individual is started. If there is migration, this continues until 100 less the number of migrating individuals are formed; the remaining slots in the population are then filled by migration. If the inversion time is "mass", then, with a given probability, exactly half the population undergoes an inversion. The calculation for one generation is given in somewhat more detail in Figure 3.11.

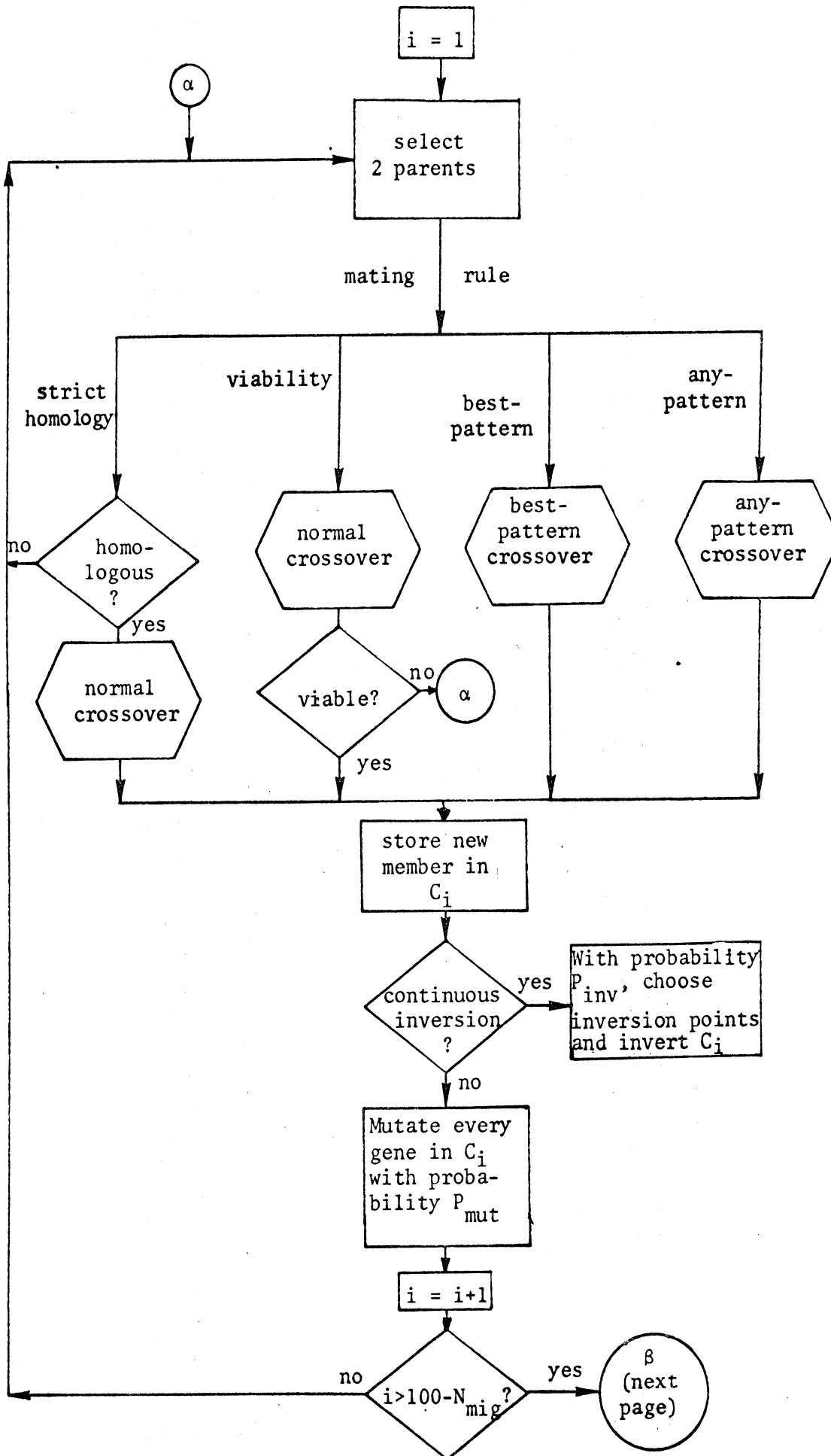


Figure 3.11: Generation of a New Population.
(Cont'd)

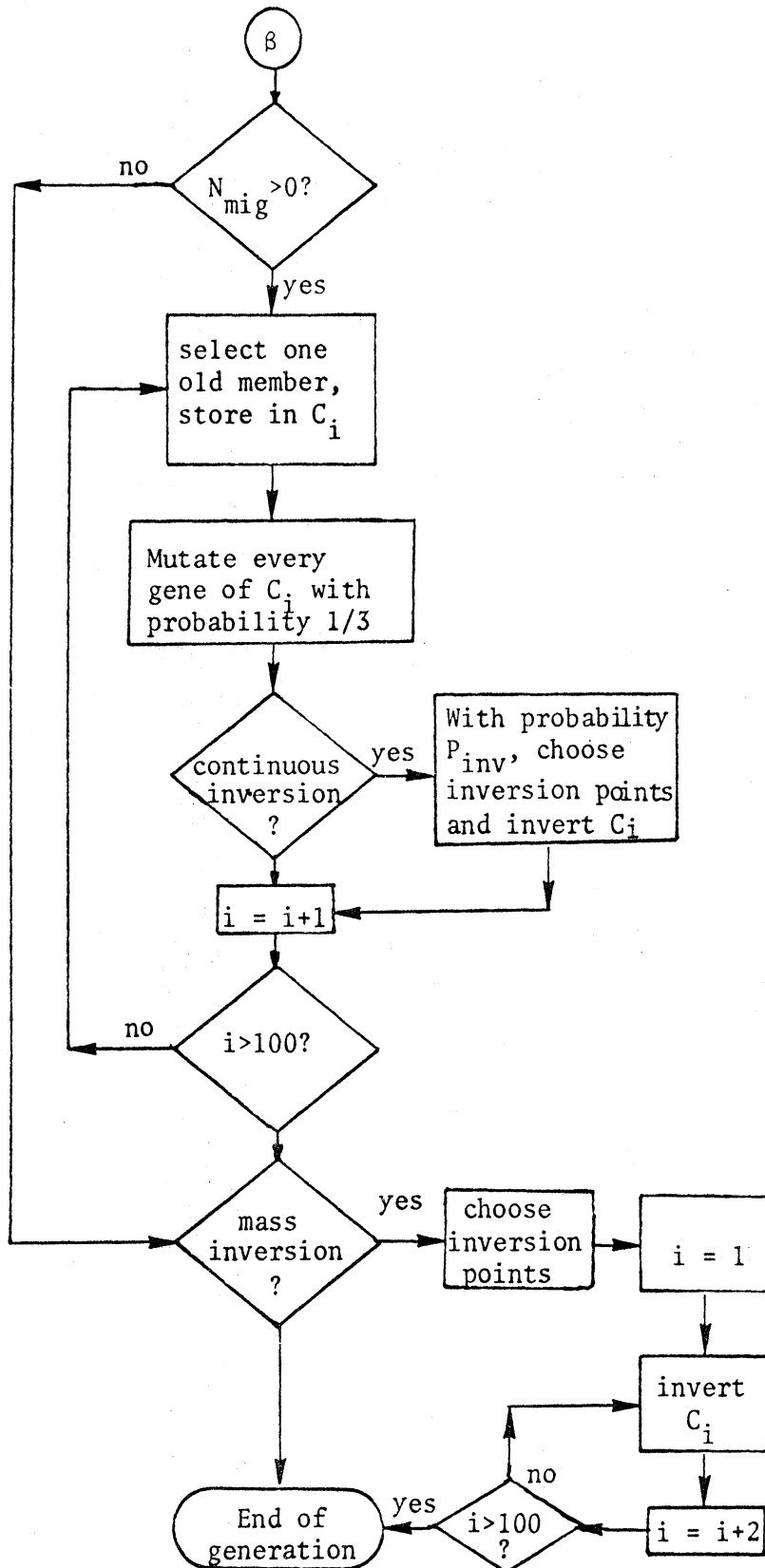


Figure 3.11: Generation of a New Population.

CHAPTER FOUR
POSITION EFFECTS

This chapter discusses a series of experiments which investigate the effect of position on populations evolving under the reproductive plan.

Recalling the argument in Chapter Two concerning the nearness hypothesis, we note that clumping does not contribute to the payoff of an individual chromosome--the payoff depends strictly on the alleles present. We expect to find, however, that clumping does contribute to the ability of a chromosome to pass good combinations of alleles to its descendants. There are two ways in which we (and the reproductive plan through use of the inversion operator) may reasonably gain information based on this expectation: 1) from populations which are already adapted to their environment (i.e., there is no significant evolution or improvement in performance going on); 2) from populations which are still evolving. Experiments based on these possibilities require quite different designs and yield quite a different class of results.

Working with populations in equilibrium has the advantage that time or speed of evolution does not need to be considered; any effects are presumed to be a property of the equilibrium state no matter how rapidly or slowly it was reached. On the other hand, it may well be argued that the important of position is in aiding the speed of evolution, so that studies of evolving populations may be of more interest albeit possibly more difficult. The remainder of this chapter is divided into three parts, corresponding to these two sources of information and on experiments using this information.

Equilibrium Populations

In this chapter we shall call a population *in equilibrium* (or *in steady state*) when it has reached a level of adaptation such that no significant further evolution (of the population as a whole) will take place. This does not necessarily describe a population in which all the genes are fixed; mutation or other mechanisms may contribute to variability. Equilibrium can only be defined in terms of averages--not only individuals but also populations will fluctuate about the equilibrium point due to stochastic effects. Individuals may be produced which are much better than the average but the population has pressures (mutation, etc.) which keep the average down.

It is in this sense of equilibrium that we hope to detect differences in the "equilibrium population average" due to position effects. Specifically, we expect that populations in which dependent genes are clumped (are close together) will have higher steady state points (higher population averages) than those in which the genes are a long way apart. If this is indeed the case, then it is possible for the reproductive plan itself to detect these differences and capitalize on them, favoring small distances in the affected genes. But, first we must convince ourselves that there really is a position effect.

Experimental Procedure

In order to detect differences in the equilibrium point we will perform experiments along the following general lines. There is a set of genes which we wish to investigate with respect to position. We shall collect data from several cases (specifications of experimental

parameters) differing only in the positions of the distinguished genes on the chromosomes. For each case we run the experiment many times from an initial random population. A run of many generations without inversion allows any position effects to be expressed in the fitness of the descendants. These differences in the equilibrium point will ordinarily be small and the variance over runs large so that we will be forced to employ statistical techniques. We restate the hypothesis as follows: the average payoff achieved by a population depends on the distance between the distinguished genes. Distance is a controlled factor and payoff a random factor. We shall undertake two lines of analysis. In the first we will attempt to fit a straight line to the data produced (by linear regression) and expect to find a negative slope (smaller payoff for large distances).

Using standard techniques, we can test for significance by an upper one-sided Student's t-test with $n-2$ degrees of freedom (where n is the number of points), under the null hypothesis that the slope is zero, hoping to reject the hypothesis in favor of a negative slope. The t-test requires normal distribution and equal variance over the range of the distance, although it is quite robust to departures from these requirements, especially when the number of points is fairly large. We will usually have on the order of 50-70 points (5-7 different distances with 10 samples at each distance) so that we feel confident of any results. Difficulties will be discussed in the appropriate experiments. Our normal acceptance level is 95%; we will usually state a P-value if much larger than 95%.

The second analysis measures only the best and worst cases: when the genes in a dependent group are clumped and when they are completely

spread out. For this type of experiment we will obtain twenty different sample points for each of the two gene permutations. Each run starts with a different initial population. The statistical analysis is the Student's t-test for difference between means. We shall perform two-sided tests.

Analysis for a negative slope is performed in the hope that distance effects are fairly smooth. The distance is well defined for environments which have only one set of non-linear genes; more than one set makes it difficult to determine what shall be called distance for this purpose. Best/worst testing is well defined in all environments (genes from a group are either adjacent or they are not). In addition, the increased number of sample points taken in this test sharpens the power of our statistical tools. (We might mention that these experiments take a considerable amount of computer time so that it is infeasible to obtain large numbers of sample points for all possible experimental parameters.)

A Simple Adaptive System

We start with an experiment involving a simple environment and a simple adaptive system. The environment is ENV 1 (Figure 3.1).

The only functional genes in ENV 1 are 1-5, linearly combined such that zero alleles are worth nothing and one alleles are worth one. The remaining genes contribute nothing to payoff. If the concept of clumping is correct for dependent (non-linear) genes, among other independent (linear) genes, then we may find it to be true also of functional genes (linear or non-linear) among non-functional genes. In any case, this environment should serve as a control on later ones.

We try this kind of environment first because this reduces (to zero) the "noise" from the remaining 20 genes, an advantage in a first step.

The adaptive system used has no inversion and no migration. Since there is no inversion and since the population starts out completely homologous (i.e., all individuals have the same gene pattern), no special mating rule is needed. Single crossover is used (i.e., exactly one crossover point generates a new individuals from two parents). The probability of mutation and the pattern of genes on the chromosomes are the only variables of interest.

Experiment A1 consists of five cases (1-5), in which the initial population and all parameters are identical ($P_{mut} = .005$), the only difference being in the position of the five functioning genes on the chromosomes in the five cases. These positions are given in Table 4.1. The distance figure in the table is the distance from the leftmost distinguished gene to the rightmost. This is the controlled value in the linear regression.

Case	Position of gene:					Distance	Ave pay for 10 runs
	1	2	3	4	5		
1	1	2	3	4	5	4	4.89
2	1	3	6	8	10	9	4.88
3	1	4	8	12	15	14	4.87
4	1	6	11	15	20	19	4.91
5	1	7	13	19	25	24	4.88

Table 4.1: Experiment A1. Gene Positions and Results.

Each case had ten runs of eighty generations apiece. It took about sixty generations for the population to reach a steady state at about 4.89. The actual runs had a variation in average population payoff from 4.74 to 4.97; the numbers in Table 4.1 were the average

of the ten runs for each case--they are not used in the analysis and are included only to give an intuitive feel of the range to the reader. The raw data consisted of 50 points, 48 degrees of freedom, requiring a negative slope and $t = 1.68$ for 95% confidence. The slope obtained from the regression was $+0.0003$ with a t -value of $t_0 = .30$, not enabling us to reject the hypothesis that there is no dependence of payoff on distance.

Experiment B1 used ENV 2 which also involved 20 non-functional and 5 functional genes, but the five functional genes were non-linear in their effects according to Figure 3.2(a). Only genes 1-5 out of group 1 were functional, the payoff being the highest (3) at all ones or all zero, dropping to 2 with one allele different (four 1's and one 0, and four 0's and one 1) and to 1 for combinations containing three of one allele and two of the other. This experiment was run under exactly the same set of conditions as experiment A1-5 cases, 80 generations, 10 runs; the patterns for each case were as given in Table 4.1. Any problems due to the strict linearity of ENV 1 should not affect this experiment.

Again, no significant slope was found; the population average over all 50 runs was 2.93, the slope was $+0.0002$, and $t_0 = .35$.

Experiment C1 used ENV 3, in which every gene is functional and group one is non-linear according to Figure 3.3. Non-linear group B (6 genes) has a peak of 10 at combination 001011 and 9 at the competing peak of 110100, with a trough extending to 3 between them. The maximal points over the whole environment are at 28 and 29.

Table 4.2 contains a summary of the experimental parameters for the 5 cases, including the position of the distinguished genes in each

case. The mutation rate was again .005.

Case	Position of gene:						Distance	Ave pay, 10 runs at gen. 120
	1	2	3	4	5	6		
11	1	2	3	4	5	6	5	25.30
12	1	3	5	7	9	11	10	25.46
13	1	4	7	10	13	16	15	25.35
14	1	5	9	13	17	21	20	25.89
15	1	6	11	16	21	25	24	25.38

Table 4.2: Experiment C1. Gene Positions and Results.

The overall average was 25.47, the slope was +0.013, and $t_0 = .94$.

Again, no significance.

The Problem of Homogeneity

The results of these three experiments force us to conclude that there is no advantage in clumping, at least for these particular sets of experimental parameters and environments. A close look at the equilibrium populations in the three experiments indicates a probable reason for this result: most of the individuals were "perfect" with respect to the genes of interest. In experiments A and B about 90% of the individuals population had all the alleles right and in experiment C, anywhere from 50% to 90% of the population had all the correct alleles. Actual allelic frequencies were approximately 90-100%. Thus, the populations are very homogeneous, at least with respect to the genes of interest. When crossover occurs between two parents the distinguished genes may be split up, but because of this homogeneity it is unlikely that the resulting individual will have different alleles substituted for the good combinations in the parents.

In retrospect this makes sense, for the position-induced behavior is predicted on the basis of *keeping* good combinations together so that

they will not be lost when split up. But if the good alleles are almost universal in the population it makes no difference whether the genes are split or not. The reproductive plan tends to lead the whole population to the optimal point once it has been reached and the only reason for the variance observed is mutation.

If we expect to determine dependencies using position effects in stable populations, then, we must ensure that the steady state populations we produce are not too homogeneous. In population genetics theory there are several reasons offered for the large variety observed in natural populations:

- 1) Non-linear effects due to diploidy, e.g., overdominance and epistasis. Obviously, this does not help haploid populations; in addition, the extent of this effect is being questioned by population geneticists.
- 2) The population is not in equilibrium; i.e., some gene or group of genes is in the process of moving from one steady state point to another due to a change in the environment or the discovery of a new local maximum. This reason is contrary to our assumption of equilibrium.
- 3) Neutralism. This theory states that most of the observed differences are selectively neutral; the characteristics have nothing to do with fitness or payoff. Again, this reason does not help us for we wish to investigate the effects of selectively important genes.
- 4) "High" mutation rates.
- 5) Low selection with respect to mutation rates.

- 6) Migration from one deme (closed population) into another when the two are facing different environments.

These last three reasons are the only possible sources of variation we can use to revise the equilibrium point of a population downward to a limited amount of homogeneity. They will be taken up one at a time.

Note that we are not using these methods to aid the reproductive plan. On the contrary, we expect them to fight the natural tendency of the reproductive plan to find the optimum. Our interest in this research is not the optimum but rather dependencies in the environment in the vicinity of the optimum. For this we need some variety in the population when it is "in equilibrium". We might hope that the increased difficulty in natural or real environments would automatically lead to a higher degree of variance which we are providing artificially.

We will first describe the experiments and results and then make our conclusions.

Variance by Mutation

We expect increasing the mutation rate to shift the equilibrium point of a population undergoing selection. Population geneticists have worked out formulas to express the relation for only very simple cases (e.g., one or two genes, two alleles, diploid chromosomes). Our environments are so much more complex that we can expect little from this previous work except direction: higher mutation, more variance. Our main problem may be that in order to get enough variance we may have to increase mutation so much that it destroys the work of selection.

In experiments A1, B1, and C1, the mutation levels were set at .005. Two higher levels were tried: .025 and .100, in experiments identified as A2, A3, B2, B3, C2, and C3. All that was observed was a lowering of the average population payoff according to Table 4.3.

Experiment	Environment	Mutation rate	Range in payoff	Population average over 50 runs	Slope	Confidence of t-test
A1	1	.005	0-5	4.89	+.0003	.62
A2	1	.025	0-5	4.45	+.0011	.68
A3	1	.100	0-5	3.54	+.0022	.75
B1	2	.005	1-3	2.93	+.0002	.64
B2	2	.025	1-3	2.65	+.0017	.89
B3	2	.100	1-3	1.94	+.0022	.86
C1	3	.005	3-29	25.47	+.0133	.82
C2	3	.025	3-29	20.04	-.0052	.61
C3	3	.100	3-29	16.14	-.0043	.66

Table 4.3: Experiments in Mutation Rates.

Since there is no indication that the addition in variance gives rise to the expected position effect, experiments along these lines were discontinued. The highest mutation level used (.1) caused a large degradation in performance: in experiment C3, the population average produced was not much greater than that expected by chance (16.14 vs. 14.72). These mutation levels are too high to permit effective adaptation. Intermediate levels also did not produce the desired effect.

Variance by Decreased Selection

Expressions obtained by theorists indicate that the equilibrium point for one gene, two allele systems depends not only on the mutation rates but also on the selection coefficient, that is, on the relative

number of offspring expected due to an allele; the lower the selection, the higher the variance expected. In our terms this corresponds to the ratio of the direct "payoffs" or function values of the chromosomes involved. For example, in ENV 3 the best chromosome had a value of 29 and the worst a value of 3. Thus, the best was approximately ten times as likely to serve as a parent as the worse.

Again, generalizing from the single gene model to a multiple gene model leads to currently unsolvable mathematics so that direction is the only inference we can draw. Our method of testing this as a possible source of variance is merely to translate the payoffs of every chromosome upward by some fixed amount. The selection coefficient (i.e., the ratio of best to worst) is thus reduced, leading to a downward shift in the performance level of the population due to the increased ability of "non-optimal" genes and combinations to enter into determination of the next generation.

In terms of the specification of the environment we have been using, this is actually realized by the definition of a new environment which has the appropriate characteristics. ENV 4 is merely ENV 1 with each zero allele paying 9 and each one allele paying 10. Similarly, ENV 5 is ENV 2 with each functional group of alleles shifted by 5 (so that the payoffs are 8,7,6,7,8) and ENV 6 is ENV 3 with all of group 1 shifted by 10 (so that the payoffs for group 1 range from 13 to 20, and the payoffs for a single chromosome can range from 13 to 39). If this technique is useful it would be a simple matter to adjust the selection rate to a "standard" range as part of the adaptive system. For the present, we will adjust the payoffs manually by changing the environments.

Using the altered environments as defined above, experiments A4, B4, and C4 were performed, with a mutation rate of .005, yielding the results of Table 4.4.

Experiment	Environment	Range in payoff	Population average over 50 runs	Adjusted	Slope	Confide of t-te
A4	4 ("1"+45)	45-50	48.45	3.45	+0.0044	.64
B4	5 ("2"+5)	6-8	7.80	2.80	+0.003	.89
C4	6 ("3"+10)	13-39	34.14	24.14	+0.022	.83

Table 4.4: Experiments in Reduced Selection.

The population averages are indeed depressed in comparison to the averages of experiments A1, B1, and C1, which used the same mutation rates. The results seem to be comparable to or slightly worse than experiments A3, B3, and C3 which used a .1 mutation rate. But as before, the results are not significant, nor even indicative (the slope is in the wrong direction).

Variance by Migration

Migration is the last method by which we shall try to increase the variance of a population at its equilibrium point. Migration is the movement of an organism from outside a closed, interbreeding population (deme) into that deme. If two demes are stable and face different environments, their genotypic constitutions will be different, so that mixing them via migration will tend to force the population away from the optimum for either environment.

In single gene analysis theoretical population geneticists treat migration exactly the same as mutation: introduction of alternate

alleles according to a particular probability distribution. But in the multiple gene case we expect differences in the effects for the following reason. Although immigrants must be of the same species (i.e., they are basically similar) they are different in many of their genes. Thus the immigrant may contain many non-adapted alleles *in one chromosome*. When it mates with an individual of the deme many non-adapted alleles are transferred at once. Members of the deme which do not breed with immigrants do not receive this high dose of new alleles and so their offspring can maintain their adaptation. This is different in effect from a comparable relatively high mutation rate where the adaptation of every individual in the deme is threatened by the mutation.

As described in Chapter Three, migration is simulated by creating immigrants which differ from some individual already in the population by about a third of the genes in its chromosome. The actual proportion of changed genes could have been an experimental parameter if the experiments described below had been more positive in their results.

Table 4.5 describes the experiments which were run with migration and the analyses performed.

Experiment A5 with ENV 1 showed mixed results. Analysis of the population average at generation 70 gave rise to our first significant regression line. However, analysis of the population average at generation 80 was not significant, definitely a disappointment. Looking a bit more closely at the population at generation 80 to perform a different analysis of the data, we counted the number of "perfect" chromosomes (chromosomes whose five functional genes contained the right alleles for maximum

Exp	ENV	Mut	Migr	Regression Variable**	Mean	Slope	Confidence	VEBR***
A5	1	.005	25%	PA70	3.81	-.006	.99	11%
				PA80	3.87	+.00002	-	-
				NP80	33.51	-.27	.98	9%
A6*	1	.005	25%	PA80	3.86	-.005	.98	10%
A7	1	.005	30%	PA80	3.66	-.0002	-	-
				NP80	24.40	-.016	-	-
B5	2	.005	25%	PA80	2.24	-.004	.99	11%
				NP80	46.12	-.30	.98	9%
C5	3	.005	5%	PA120	22.53	+.026	-	-
C6	3	.002	10%	PA120	20.76	-.005	-	-
				TF120	26.26	-.011	-	-
C7	3	.005	25%	PA120	16.60	-.025	.995	10%
				TF120	22.45	-.016	-	-

*Gene positions: four together, one spread apart.

**PA = Population Average at generation ...

NP = Number Perfect chromosomes at generation ...

TF = Top Five average at generation ...

***Percent Variance Explained by Regression which is 95% significant.

Table 4.5: Experiments in Migration

payoff), and performed a regression on distance with respect to this random variable. About one-third of the populations were made up of perfect chromosomes. The regression showed significance, with the average number of perfect chromosomes for the least distance (4) being 36.22 and for the greatest distance (24) being 30.82. The reason that the population average did not reflect this difference is in the distribution of the non-perfect chromosomes. For some reason, populations with a lot of perfect individuals also had a lot of very bad individuals.

Experiment A6 was run with a slightly different arrangement of genes on the chromosomes. Instead of spreading the genes evenly as for the other experiments up to this point (described in Table 4.1), four of the genes were clumped at one end of the string (positions 1,2,3 and 4) and the remaining gene was placed on the string at five different distances (at positions 5,10,15,20 and 25). This constitutes a different test of the position effect. The results were significant.

Experiment A7 was run at a migration rate of 30% but showed no significance of the population average at generation 80. The number of perfect chromosomes likewise failed to achieve significance.

Experiment B5 (with ENV 3) was run at a 25% migration level on environment 2 and produced significant position effects both in the population average and the number of perfect chromosomes.

Experiments C5, C6, and C7 were attempts to define the effective range of the migration operator on environment 3. Rates of 5% and 10% were ineffective at producing the position effect, but a rate of 25% produced a significant regression line on the population average. An alternate analysis of experiments C6 and C7 was tried: the average of the top five individuals in the population versus distance. This is

a measure of how the best part of the population is doing and may be a more reasonable choice for analysis than the number of perfect chromosomes since perfect chromosomes are usually rare (or non-existent) in complex environments. (In addition knowledge of the optimum is often lacking.) In the case of ENV 3, a perfect chromosome pays 29 and the top five averages for the two experiments were 26.26 (C6) and 22.45 (C7), indicating that few really good chromosomes were produced. The results of this top five analysis were not significant, even in experiment C7 in which the whole population average showed the position effect. The interpretation is that while the increased migration rate creates enough variance in the whole population to show the effect, it does not create much variance in the best part of the population (which by definition is that part closest to the optimum and so much more identical).

Best/Worst Tests

The results obtained thus far are not too encouraging. Only by artificial means are we able to show a position effect. It may be that seeking a linear relationship between distance and average payoff is expecting too much. The relationship may not be very smooth. Testing just the best and worst cases (i.e., genes adjacent and genes most spread) should overcome some of this difficulty (if indeed there is a distance effect). In addition, the experiments described in this section obtain more sample points for each permutation than in the previous experiments, allowing the statistical tests to be more certain. Finally, we will test a wider range of, and much more complex, environments via this method.

The adaptive system used involved no migration, no inversion, no special mating rule (since there was no inversion), single crossover, and a mutation rate of .005. The results are stated in Table 4.6. For each experiment two different permutations of genes were used: the best possible, where dependent genes are adjacent and the worst possible, where all genes from dependent groups were as far away from each other as possible. For each permutation twenty different initial populations were run to equilibrium at some number of generations. The population average at that point was used in a Student's t-test for difference of means with 38 degrees of freedom. The table indicates which permutation produced the best populations and whether the difference between the populations was significant at the 95% or 99% level for a two-sided t-test.

Environments 7,8,9, and 10 are newcomers. They are all somewhat more complex than the previous ones encountered. We can briefly summarize them as follows. ENV 7 contains five non-linear groups, the first of order 6, the second of order 5, the third of order 6, the fourth of order 3, and the fifth of order 4. ENV 8 contains three non-linear groups of order 6, each group similar to the single non-linear group of ENV 3; the remaining 7 genes are linear. ENV 9 contains a non-linear group of order 8, containing two false peaks; good points in the payoff function are much sparser than in the previous environments. The remaining genes pay linearly. ENV 10 repeats the 8-group of ENV 9 twice and also has a very sparse group of 9 genes with two false peaks in addition to the true peak. It is an important point that optimum combinations (within groups) appear infrequently in random initial populations of ENV 9 and ENV 10.

Exp	ENV	# Gens	Best (near) Mean	Direction	Worst (far) Mean	Significance (if any)
D1	2	75	2.93	<	2.94	
D2	5	150	7.77	=	7.77	
D3	3	150	25.23	<	25.35	
D4	6	250	34.15	<	34.52	
D5	7	250	32.99	>	32.07	99%
D6	8	250	31.91	<	32.36	
D7	9	250	22.87	>	22.51	95%
D8	10	250	22.50	>	21.46	99%

Table 4.6: Best/Worst Equilibrium Results.

We note that the only significant results in Table 4.6 are in the direction we desired, i.e., the permutation in which genes were adjacent performed better than permutations in which they were far apart. Of the more complex environments, only ENV 8 failed to show this direction. We point out that experiments D2 and D4 are lowered-selection versions of D1 and D3, and are comparable to B4 and C4. None of these four showed significance or even any movement in the right direction.

We observe that the means in experiments D5 and D8 differed by more than one, corresponding to a full allele's difference in the payoff or possibly to a false peaking paying one less than the true peak.

Summary

In general, the results above are mixed. In the earliest, linear regression experiments, of the three methods used to introduce population variance at the stable point only migration showed any effectiveness at unmasking the position effect with respect to the population average. Analyses of other population data, number of perfect chromosomes and top five average, were inconsistent. (These latter two analyses were also tried on some previous experiments but did not show significance.)

Perhaps of most interest in the migration experiments which showed significant position effects are the steepness of the slope and the variance explained by the regression line (formally defined as the square of the coefficient of linear regression). The steepness of the slopes in the regressions on population average were small, on the order of 4% of the average payoff from one end of the range to the other. The variance explained by the regression is only about 10% of the total

variance observed. While these differences are small, the nature of the reproductive plan is such that it could indeed take advantage of them. Population geneticists are very comfortable working with selection factors on the order of 1.04. Stochastic effects on small populations (genetic drift, etc.), however, may confound the ability of a single short run to show these effects. Any investigation in which genetic operators (e.g., inversion) are used to explain the effect will require a great many runs and a lot of statistical analysis to show any significance.

Another problem lies in the level of the migration needed to observe the effect. (It may be that the reproductive plan could do the detection at lower levels, but this is not verified by the experiments above.) The environments used to this point have been fairly simple. Nonetheless, the best chromosomes observed in experiment C7 usually differed by 3 to 5 genes from the optimum. In a very complex environment with many false peaks, it may not be possible for even the best individual to reach the optimum point because of the migration pressure. This could destroy our confidence of the meaningfulness of the result. We want information about the environment near the optimum.

However, we will perform some investigation on the effects of the inversion operator on populations using migration, both at the 25% level observed to have a distance effect and lower levels. Such populations maintain the variability needed over long spans of time for the inversion operators to have effect. In much more complex classes of environments than those in this research this desired variability automatically exists--it just plain takes longer to home in on the maximum

The best/worst analysis yielded a bit more information. It appears that the expected position effect shows up in more complex environments, although not perfectly, as witness the failure of experiment D6. Although these results are significant, there is the distinct possibility that they are due to effects earlier in evolution, rather than strict equilibrium considerations. This question is considered in the next section.

Evolving Populations

The usefulness of a "correct" permutation of genes in evolving populations is almost impossible to show analytically. Turner's paper on a three gene model is the most complex analysis available on linkage, and that involves an "equilibrium", diploid population. There are few analyses of populations on the move.

The intuitive analysis of the position effect in evolving populations is much the same as for populations in equilibrium with the following difference: "good" combinations of genes are likely to be rare in an evolving population. If an instance of a good combination is encountered via recombination and then (subsequently) broken up by recombination it is very unlikely to be reconstructed soon. Thus, there is a sort of "discovery" problem. When a combination appears for the first time it is more likely to make its presence known if it is not broken up easily, i.e., if it is in a good permutation. Clearly this implies that good permutations lead to faster evolution than do poor permutations. This is exactly the basis on which we will examine the position hypothesis in this section.

By faster evolution we do not mean instantaneous rates of change with attendant difficulties of definition. We merely intend to measure the average population payoff at each generation and make comparisons on this basis. There is a distinct non-independence of sampling between generations: if population A is greater than population B at time t , then it is also likely to be greater than population B at time $t+1$. But if there are no selective differences between the populations, then, on the average, no population should predominate all the time, and more importantly, the difference should not be statistically significant.

Best/Worst Evolution

The experimental conditions for testing the faster evolution hypothesis are exactly the same as for the best/worst-equilibrium experiments. (As a matter of fact, the data for the best-worst experiments come from the terminal conditions of the computer runs used in this section.) Briefly, the experiments involved no migration, no inversion, no special mating rule (since there was no inversion), single crossover, and a mutation rate of .005. For each experiment two different permutations of genes were used: the best possible, where all genes from dependent groups were adjacent, and the worst possible, where all genes from dependent groups were as far away from each other as possible. For each permutation twenty different initial populations were run to equilibrium for some number of generations. We report on experiments D1-D8 as given in Table 4.6.

The analysis performed was simple. At each generation the means of the twenty samples for the two permutations were calculated and a

GEN	NEAR MEAN	FAR MEAN	DIR	SIG				
					44	2.93	2.93	>
					45	2.93	2.94	<
					46	2.93	2.93	<
					47	2.92	2.93	<
					48	2.93	2.93	<
					49	2.92	2.93	<
					50	2.91	2.92	<
					51	2.90	2.93	<
					52	2.91	2.93	<
					53	2.93	2.93	<
					54	2.93	2.93	<
					55	2.92	2.93	<
					56	2.92	2.92	>
					57	2.92	2.92	<
					58	2.93	2.93	<
					59	2.92	2.93	<
					60	2.93	2.93	<
					61	2.94	2.95	<
					62	2.93	2.94	<
					63	2.93	2.94	<
					64	2.92	2.94	<
					65	2.92	2.93	<
					66	2.92	2.91	>
					67	2.92	2.91	>
					68	2.91	2.91	>
					69	2.92	2.92	>
					70	2.92	2.90	>
					71	2.91	2.91	>
					72	2.92	2.92	>
					73	2.93	2.92	>
					74	2.92	2.92	>
					75	2.93	2.94	<
0	1.45	1.44	>					
1	1.67	1.57	>					
2	1.87	1.66	>					
3	2.03	1.77	>					
4	2.21	1.85	>					
5	2.32	1.95	>					
6	2.40	2.10	>					
7	2.48	2.21	>					
8	2.56	2.34	>					
9	2.63	2.44	>					
10	2.64	2.57	>					
11	2.67	2.65	>					
12	2.69	2.72	<					
13	2.71	2.79	<					
14	2.75	2.82	<					
15	2.76	2.86	<					
16	2.77	2.87	<					
17	2.78	2.90	<					
18	2.78	2.91	<					
19	2.80	2.92	<					
20	2.82	2.91	<					
21	2.82	2.92	<					
22	2.83	2.92	<					
23	2.84	2.92	<					
24	2.85	2.94	<					
25	2.84	2.94	<					
26	2.85	2.94	<					
27	2.85	2.93	<					
28	2.86	2.93	<					
29	2.85	2.92	<					
30	2.87	2.93	<					
31	2.89	2.92	<					
32	2.91	2.93	<					
33	2.91	2.93	<					
34	2.90	2.92	<					
35	2.90	2.92	<					
36	2.90	2.93	<					
37	2.91	2.93	<					
38	2.90	2.92	<					
39	2.91	2.93	<					
40	2.91	2.92	<					
41	2.91	2.92	<					
42	2.91	2.92	<					
43	2.92	2.92	<					

ENV 2

Figure 4.1: Output from Experiment D1.

GEN	NEAR MEAN	FAR MEAN	DIR	SIG			
					50	24.20	23.93 >
					51	24.17	24.05 >
					52	24.25	24.09 >
0	14.71	14.68	>		53	24.25	24.15 >
1	15.18	15.06	>		54	24.32	24.20 >
2	15.52	15.55	<		55	24.40	24.21 >
3	15.97	15.82	>		56	24.50	24.29 > *
4	16.38	16.05	>		57	24.48	24.37 >
5	16.74	16.43	>		58	24.52	24.41 >
6	17.01	16.71	>		59	24.45	24.47 <
7	17.35	16.89	>	*	60	24.51	24.46 >
8	17.74	17.16	>	**	61	24.59	24.58 >
9	18.05	17.48	>	**	62	24.62	24.56 >
10	18.46	17.58	>	**	63	24.72	24.57 >
11	18.66	17.81	>	**	64	24.77	24.65 >
12	18.87	18.10	>	**	65	24.77	24.63 >
13	19.23	18.36	>	**	66	24.76	24.65 >
14	19.51	18.51	>	**	67	24.81	24.65 >
15	19.78	18.86	>	**	68	24.79	24.72 >
16	20.07	19.11	>	**	69	24.78	24.78 <
17	20.28	19.28	>	**	70	24.82	24.79 >
18	20.51	19.49	>	**	71	24.89	24.84 >
19	20.67	19.70	>	**	72	24.89	24.82 >
20	20.88	19.87	>	**	73	24.84	24.84 >
21	21.03	20.08	>	**	74	24.86	24.83 >
22	21.10	20.22	>	**	75	24.82	24.88 <
23	21.25	20.42	>	**	76	24.82	24.95 <
24	21.38	20.58	>	**	77	24.88	24.95 <
25	21.68	20.84	>	*	78	24.92	25.01 <
26	21.86	21.07	>	**	79	24.85	25.03 <
27	21.98	21.29	>	**	80	24.80	25.04 < **
28	22.10	21.41	>	**	81	24.86	25.03 <
29	22.31	21.44	>	**	82	24.88	24.99 <
30	22.40	21.53	>	**	83	24.91	25.00 <
31	22.63	21.62	>	**	84	24.89	24.95 <
32	22.75	21.74	>	**	85	24.83	24.91 <
33	22.95	21.86	>	**	86	24.87	24.93 <
34	23.08	21.99	>	**	87	24.95	24.94 >
35	23.15	22.11	>	**	88	24.92	24.96 <
36	23.31	22.13	>	**	89	24.94	24.91 >
37	23.35	22.23	>	**			
38	23.45	22.40	>	**			
39	23.58	22.60	>	**			
40	23.57	22.68	>	**			
41	23.64	22.85	>	**			
42	23.68	22.99	>	**			
43	23.72	23.16	>	*			
44	23.80	23.27	>				
45	23.81	23.40	>				
46	23.89	23.52	>				
47	23.97	23.66	>				
48	24.09	23.76	>	**			
49	24.20	23.85	>				

ENV 3

Figure 4.2: Output from Experiment D3.
(Cont'd)

90	24.97	24.98	<	117	25.27	25.45	<
91	24.98	24.93	>	118	25.21	25.49	<
92	25.06	24.92	>	119	25.23	25.44	<
93	25.11	24.99	>	120	25.24	25.47	< *
94	25.17	25.10	>	121	25.28	25.51	<
95	25.16	25.18	<	122	25.29	25.53	<
96	25.13	25.23	<	123	25.26	25.49	<
97	25.15	25.25	<	124	25.26	25.47	<
98	25.16	25.24	<	125	25.25	25.44	< **
99	25.11	25.25	<	126	25.23	25.47	<
100	25.09	25.28	<	127	25.27	25.43	<
101	25.12	25.33	< **	128	25.26	25.49	<
102	25.15	25.37	<	129	25.25	25.51	<
103	25.15	25.31	<	130	25.27	25.53	<
104	25.13	25.24	<	131	25.27	25.58	<
105	25.16	25.23	<	132	25.26	25.54	< **
106	25.15	25.23	<	133	25.21	25.52	<
107	25.24	25.29	<	134	25.18	25.47	<
108	25.23	25.30	<	135	25.19	25.42	<
109	25.28	25.31	<	136	25.21	25.43	<
110	25.31	25.32	<	137	25.21	25.41	<
111	25.26	25.33	< **	138	25.21	25.45	<
112	25.23	25.39	<	139	25.19	25.41	<
113	25.25	25.42	<	140	25.16	25.42	< **
114	25.23	25.38	<	141	25.19	25.44	<
115	25.22	25.38	<	142	25.20	25.43	<
116	25.23	25.40	<	143	25.17	25.42	< *
				144	25.24	25.41	<
				145	25.26	25.39	<
				146	25.30	25.36	<
				147	25.29	25.30	<
				148	25.27	25.32	<
				149	25.24	25.34	<
				150	25.23	25.35	<

Figure 4.2: Output from Experiment D3.

GEN	NEAR MEAN	FAR MEAN	DIR	SIG					
					50	30.40	29.78	>	*
					51	30.52	30.11	>	
					52	30.48	30.13	>	
					53	30.53	30.28	>	
					54	30.58	30.42	>	
					55	30.69	30.55	>	
					56	30.74	30.47	>	
					57	30.81	30.59	>	
					58	30.77	30.62	>	
					59	30.81	30.67	>	
					60	30.90	30.76	>	
					61	30.93	30.78	>	
					62	31.00	30.76	>	
					63	31.06	30.77	>	
					64	31.17	30.82	>	
					65	31.14	30.86	>	**
					66	31.18	30.97	>	
					67	31.17	31.08	>	
					68	31.25	31.12	>	
					69	31.29	31.19	>	
					70	31.27	31.30	<	
					71	31.30	31.31	<	
					72	31.35	31.37	<	
					73	31.37	31.42	<	
					74	31.42	31.43	<	
					75	31.53	31.38	>	
					76	31.44	31.43	>	
					77	31.48	31.54	<	
					78	31.57	31.45	>	
					79	31.61	31.47	>	
					80	31.62	31.39	>	
					81	31.69	31.45	>	
					82	31.82	31.53	>	
					83	31.79	31.58	>	**
					84	31.69	31.46	>	
					85	31.79	31.52	>	
					86	31.79	31.64	>	
					87	31.82	31.62	>	
					88	31.78	31.67	>	
					89	31.81	31.75	>	
					90	31.76	31.66	>	
					91	31.77	31.54	>	
					92	31.76	31.56	>	
					93	31.87	31.64	>	
					94	31.85	31.62	>	
					95	31.96	31.66	>	
					96	31.87	31.71	>	
					97	31.87	31.73	>	
					98	31.86	31.74	>	
					99	31.76	31.75	>	
0	24.34	24.43	<						
1	24.57	24.59	<						
2	24.68	24.68	<						
3	24.93	24.76	>						
4	25.16	24.88	>						
5	25.43	24.84	>	**					
6	25.61	24.88	>	**					
7	25.85	25.01	>	**					
8	25.95	25.22	>	**					
9	26.16	25.22	>	**					
10	26.36	25.25	>	**					
11	26.47	25.31	>	**					
12	26.59	25.42	>	**					
13	26.62	25.51	>	**					
14	26.67	25.65	>	**					
15	26.78	25.84	>	**					
16	26.95	25.86	>	**					
17	27.19	26.04	>	**					
18	27.19	26.16	>	**					
19	27.40	26.23	>	**					
20	27.59	26.38	>	**					
21	27.70	26.61	>	**					
22	27.84	26.74	>	**					
23	27.82	26.87	>	**					
24	27.88	26.94	>	**					
25	27.99	27.09	>	**					
26	28.09	27.23	>	**					
27	28.22	27.40	>	**					
28	28.28	27.62	>	**					
29	28.40	27.82	>	**					
30	28.52	27.86	>	**					
31	28.58	27.89	>	**					
32	28.64	27.95	>	*					
33	28.77	28.14	>						
34	28.81	28.11	>	*					
35	28.82	28.19	>						
36	28.89	28.38	>	**					
37	28.90	28.35	>						
38	29.06	28.46	>	**					
39	29.21	28.67	>	*					
40	29.34	28.83	>	*					
41	29.45	28.95	>	*					
42	29.54	29.06	>	*					
43	29.68	29.13	>	*					
44	29.87	29.21	>	*					
45	29.91	29.27	>						
46	30.02	29.47	>	*					
47	30.11	29.63	>						
48	30.23	29.73	>	*					
49	30.31	29.81	>						

ENV 7

Figure 4.3: Output from Experiment D5.
(Cont'd)

100	31.85	31.82	>	150	32.35	31.86	>	*
101	31.84	31.80	>	151	32.38	31.78	>	*
102	31.72	31.80	<	152	32.40	31.74	>	*
103	31.71	31.75	<	153	32.42	31.77	>	*
104	31.75	31.77	<	154	32.40	31.67	>	**
105	31.82	31.67	>	155	32.41	31.74	>	*
106	31.90	31.81	>	156	32.36	31.73	>	
107	31.91	31.85	>	157	32.43	31.68	>	
108	31.92	31.83	>	158	32.38	31.82	>	
109	32.02	31.90	>	159	32.40	31.71	>	*
110	32.09	31.88	>	160	32.34	31.69	>	
111	32.15	31.92	>	161	32.38	31.81	>	
112	32.17	32.09	>	162	32.38	31.83	>	*
113	32.31	32.12	>	163	32.40	31.76	>	**
114	32.28	32.14	>	164	32.38	31.80	>	**
115	32.23	32.05	>	165	32.31	31.83	>	*
116	32.21	31.99	>	166	32.34	31.93	>	
117	32.16	32.00	>	167	32.38	32.05	>	**
118	32.27	31.97	>	168	32.36	32.18	>	
119	32.37	31.90	>	169	32.33	32.08	>	
120	32.32	32.00	>	170	32.33	32.02	>	
121	32.33	32.02	>	171	32.36	32.01	>	
122	32.31	31.94	>	172	32.30	31.96	>	
123	32.20	31.93	>	173	32.26	31.97	>	
124	32.13	31.99	>	174	32.33	31.89	>	
125	32.13	32.01	>	175	32.29	31.82	>	
126	32.25	32.08	>	176	32.32	31.83	>	*
127	32.20	32.10	>	177	32.33	31.83	>	
128	32.07	32.07	<	178	32.30	31.78	>	
129	32.13	32.09	>	179	32.36	31.77	>	
130	32.10	32.00	>	180	32.34	31.80	>	*
131	32.15	32.02	>	181	32.32	31.89	>	
132	32.14	31.95	>	182	32.36	31.84	>	
133	32.12	31.98	>	183	32.36	31.90	>	*
134	32.11	32.00	>	184	32.42	31.86	>	**
135	32.16	32.10	>	185	32.36	31.86	>	*
136	32.17	32.09	>	186	32.31	31.83	>	
137	32.22	32.02	>	187	32.31	31.81	>	
138	32.20	31.99	>	188	32.39	31.91	>	
139	32.22	31.99	>	189	32.42	32.00	>	
140	32.22	31.96	>	190	32.39	31.98	>	
141	32.22	32.05	>	191	32.34	31.99	>	
142	32.18	32.06	>	192	32.40	32.01	>	
143	32.27	31.96	>	193	32.47	31.93	>	**
144	32.26	31.91	>	194	32.51	31.94	>	**
145	32.32	31.81	>	195	32.59	32.01	>	
146	32.34	31.85	>	196	32.60	32.05	>	
147	32.33	31.81	>	197	32.57	32.02	>	
148	32.38	31.71	>	198	32.52	32.04	>	
149	32.39	31.77	>	199	32.47	32.02	>	*

Figure 4.3: Output from Experiment D5.
(Cont'd)

200	32.52	32.05	>		237	32.98	32.05	>	**
201	32.55	32.05	>	*	238	33.06	31.94	>	**
202	32.54	32.15	>		239	33.03	31.87	>	**
203	32.56	32.15	>		240	33.06	31.89	>	**
204	32.66	32.16	>		241	33.01	31.97	>	**
205	32.68	32.17	>	**	242	33.06	32.03	>	**
206	32.62	32.21	>		243	33.05	32.01	>	**
207	32.68	32.13	>	*	244	33.07	32.01	>	**
208	32.76	32.09	>	*	245	33.07	31.94	>	**
209	32.70	32.05	>	**	246	32.99	31.95	>	**
210	32.71	32.04	>	**	247	32.94	32.04	>	**
211	32.66	32.03	>	*	248	32.96	32.07	>	**
212	32.65	31.98	>		249	32.97	32.10	>	**
213	32.64	32.00	>	*	250	32.99	32.07	>	**
214	32.61	32.10	>						
215	32.70	32.10	>	**					
216	32.80	32.09	>	*					
217	32.83	32.11	>	**					
218	32.80	32.23	>	**					
219	32.74	32.16	>	**					
220	32.77	32.19	>						
221	32.87	32.16	>	**					
222	32.94	32.23	>	*					
223	32.88	32.13	>	*					
224	32.88	32.10	>	**					
225	32.93	32.06	>	**					
226	32.99	32.00	>	**					
227	33.11	32.00	>	**					
228	33.05	31.99	>	**					
229	33.08	31.91	>	**					
230	33.07	31.96	>	**					
231	33.01	31.86	>	**					
232	32.99	31.97	>	**					
233	33.04	31.91	>	**					
234	33.05	31.83	>	**					
235	33.06	31.91	>	**					
236	33.02	31.98	>	**					

Figure 4.3: Output from Experiment D5.

GEN	NEAR MEAN	FAR MEAN	DIR	SIG					
0	19.25	19.33	<		50	30.06	29.36	>	*
1	19.77	19.50	>		51	30.10	29.47	>	
2	20.10	19.85	>		52	30.05	29.52	>	*
3	20.52	20.01	>	*	53	30.15	29.55	>	*
4	20.89	20.22	>	**	54	30.28	29.66	>	
5	21.36	20.51	>	**	55	30.31	29.75	>	
6	21.58	20.69	>	**	56	30.33	29.84	>	
7	21.98	20.89	>	**	57	30.41	30.02	>	
8	22.21	21.21	>	**	58	30.48	29.98	>	*
9	22.41	21.45	>	**	59	30.66	29.97	>	**
10	22.73	21.75	>	**	60	30.58	29.99	>	
11	23.01	22.02	>	**	61	30.65	30.09	>	
12	23.26	22.27	>	**	62	30.63	30.15	>	*
13	23.57	22.51	>	**	63	30.77	30.23	>	
14	23.88	22.80	>	**	64	30.82	30.25	>	*
15	24.11	23.02	>	**	65	30.87	30.34	>	**
16	24.31	23.14	>	**	66	30.84	30.35	>	*
17	24.53	23.31	>	**	67	30.92	30.49	>	
18	24.78	23.84	>	**	68	30.97	30.55	>	
19	24.99	24.10	>	**	69	31.10	30.66	>	
20	25.40	24.38	>	**	70	31.19	30.67	>	**
21	25.67	24.59	>	**	71	31.15	30.77	>	
22	25.89	24.74	>	**	72	31.15	30.76	>	
23	26.06	24.87	>	**	73	31.22	30.76	>	**
24	26.40	25.12	>	**	74	31.39	30.88	>	**
25	26.61	25.31	>	**	75	31.35	30.85	>	*
26	26.81	25.50	>	**	76	31.35	30.85	>	*
27	26.94	25.68	>	**	77	31.38	30.99	>	
28	27.15	26.02	>	**	78	31.44	31.05	>	
29	27.28	26.19	>	**	79	31.49	30.96	>	*
30	27.47	26.29	>	**	80	31.49	30.97	>	
31	27.78	26.66	>	**	81	31.53	31.01	>	
32	27.95	26.95	>	**	82	31.60	31.00	>	**
33	28.10	27.12	>	**	83	31.70	30.99	>	*
34	28.19	27.32	>	**	84	31.63	31.01	>	*
35	28.32	27.33	>	**	85	31.62	31.15	>	**
36	28.50	27.54	>	**	86	31.62	31.26	>	
37	28.68	27.68	>	**	87	31.55	31.31	>	
38	28.76	27.77	>	**	88	31.56	31.39	>	
39	28.97	27.99	>	**	89	31.59	31.38	>	
40	29.11	28.13	>	**	90	31.58	31.50	>	
41	29.10	28.37	>	**	91	31.53	31.46	>	
42	29.13	28.39	>	**	92	31.57	31.46	>	
43	29.21	28.51	>	*	93	31.54	31.48	>	
44	29.37	28.66	>	**	94	31.56	31.50	>	
45	29.51	28.80	>	*	95	31.55	31.49	>	
46	29.58	28.84	>	**	96	31.65	31.54	>	
47	29.63	28.99	>	*	97	31.65	31.65	<	
48	29.73	28.97	>	**	98	31.63	31.70	<	
49	29.95	29.09	>	**	99	31.68	31.66	>	

ENV 8

Figure 4.4: Output from Experiment D6.
(Cont'd)

100	31.76	31.65	>	150	31.92	32.00	<		
101	31.84	31.73	>	151	31.86	32.05	<		
102	31.80	31.76	>	152	31.87	31.96	<		
103	31.83	31.80	>	153	31.94	31.94	<		
104	31.65	31.84	<	154	31.89	31.97	<		
105	31.64	31.85	<	**	155	31.78	32.00	<	
106	31.69	31.88	<	156	31.68	31.98	<		
107	31.75	31.92	<	157	31.60	31.93	<		
108	31.82	31.79	>	158	31.52	31.87	<		
109	31.77	31.83	<	159	31.56	31.90	<		
110	31.82	31.82	>	160	31.51	31.87	<		
111	31.72	31.82	<	161	31.51	31.98	<		
112	31.88	31.88	<	162	31.49	32.05	<		
113	31.89	31.89	>	163	31.60	32.03	<		
114	31.92	31.84	>	164	31.65	32.07	<		
115	31.90	31.73	>	165	31.68	32.08	<		
116	31.88	31.68	>	166	31.64	32.09	<		
117	31.90	31.81	>	167	31.60	32.15	<	**	
118	31.86	31.88	<	168	31.60	32.18	<	*	
119	31.81	31.90	<	169	31.61	32.13	<	*	
120	31.69	31.91	<	170	31.54	32.14	<		
121	31.64	31.95	<	171	31.63	32.06	<	**	
122	31.68	32.00	<	172	31.55	31.90	<	*	
123	31.55	31.96	<	173	31.58	32.00	<	**	
124	31.55	31.94	<	*	174	31.60	32.01	<	
125	31.52	31.85	<	175	31.68	32.09	<		
126	31.53	31.87	<	176	31.70	32.14	<		
127	31.54	31.86	<	177	31.68	32.18	<		
128	31.55	31.89	<	178	31.68	32.21	<		
129	31.54	31.91	<	179	31.64	32.12	<		
130	31.60	31.92	<	180	31.57	32.14	<		
131	31.56	31.87	<	181	31.57	32.13	<		
132	31.66	31.85	<	182	31.64	32.13	<		
133	31.62	31.85	<	183	31.60	32.14	<		
134	31.55	31.82	<	184	31.55	32.17	<	*	
135	31.54	31.81	<	185	31.67	32.20	<		
136	31.56	31.89	<	186	31.67	32.13	<		
137	31.55	31.92	<	187	31.68	32.04	<		
138	31.50	31.90	<	188	31.81	32.05	<		
139	31.60	31.92	<	**	189	31.83	32.06	<	
140	31.64	31.98	<	190	31.86	32.13	<		
141	31.67	31.96	<	191	31.89	32.12	<		
142	31.70	31.90	<	192	31.92	32.14	<		
143	31.70	31.96	<	193	31.92	32.12	<		
144	31.72	31.95	<	194	31.91	32.09	<	*	
145	31.75	32.00	<	195	31.95	32.07	<		
146	31.80	32.01	<	196	31.83	32.11	<		
147	31.85	32.01	<	197	31.80	32.06	<		
148	31.87	31.98	<	198	31.81	32.12	<		
149	31.86	32.07	<	199	31.82	32.08	<		

Figure 4.4: Output from Experiment D6.
(Cont'd)

200	31.74	32.23	<	
201	31.79	32.24	<	**
202	31.84	32.27	<	
203	31.82	32.26	<	
204	31.84	32.23	<	
205	31.84	32.19	<	
206	31.78	32.13	<	
207	31.76	32.18	<	
208	31.79	32.08	<	**
209	31.76	31.95	<	
210	31.76	31.96	<	
211	31.73	31.96	<	
212	31.72	32.01	<	
213	31.68	32.04	<	
214	31.65	32.02	<	**
215	31.67	32.07	<	**
216	31.73	32.08	<	
217	31.63	32.02	<	
218	31.64	32.10	<	
219	31.59	32.03	<	
220	31.65	32.07	<	
221	31.72	32.01	<	
222	31.68	32.01	<	
223	31.77	32.01	<	
224	31.73	32.10	<	**
225	31.69	32.08	<	**
226	31.73	32.10	<	
227	31.72	32.10	<	**
228	31.71	32.09	<	**
229	31.77	32.12	<	
230	31.79	32.17	<	**
231	31.72	32.12	<	**
232	31.67	32.12	<	
233	31.61	32.10	<	
234	31.67	32.12	<	
235	31.70	32.10	<	**
236	31.65	32.17	<	
237	31.74	32.15	<	*
238	31.79	32.14	<	
239	31.81	32.19	<	
240	31.74	32.21	<	
241	31.74	32.20	<	
242	31.79	32.23	<	
243	31.84	32.30	<	
244	31.84	32.23	<	
245	31.78	32.27	<	
246	31.74	32.31	<	
247	31.74	32.26	<	
248	31.77	32.26	<	
249	31.82	32.27	<	
250	31.91	32.36	<	

Figure 4.4: Output from Experiment D6.

GEN	NEAR MEAN	FAR MEAN	DIR	SIG				
					50	20.85	20.73	>
					51	20.94	20.79	>
					52	21.04	20.82	>
					53	21.02	20.85	>
					54	21.07	20.97	>
					55	21.15	21.03	>
					56	21.19	21.11	>
					57	21.17	21.15	>
					58	21.24	21.16	>
					59	21.34	21.26	>
					60	21.38	21.34	>
					61	21.38	21.40	<
				**	62	21.45	21.44	>
					63	21.43	21.50	<
				**	64	21.50	21.52	<
				**	65	21.51	21.59	<
				*	66	21.59	21.62	<
				**	67	21.55	21.63	<
					68	21.62	21.69	<
					69	21.66	21.67	<
					70	21.67	21.67	<
					71	21.66	21.68	<
					72	21.66	21.67	<
					73	21.71	21.72	<
				**	74	21.77	21.77	>
					75	21.77	21.78	<
					76	21.79	21.79	>
					77	21.81	21.77	>
					78	21.85	21.84	>
					79	21.80	21.94	<
				*	80	21.78	21.90	<
				*	81	21.83	21.93	<
					82	21.85	21.89	<
					83	21.91	21.90	>
					84	21.82	21.85	<
					85	21.88	21.92	<
					86	21.89	21.93	<
					87	21.95	21.94	>
				*	88	21.92	21.99	<
					89	21.96	22.02	<
					90	21.91	22.00	<
					91	21.95	22.03	<
				*	92	22.01	22.06	<
				**	93	21.94	22.10	<
				*	94	21.97	22.06	<
				**	95	22.07	22.03	>
				**	96	22.04	22.12	<
					97	21.99	22.15	<
					98	22.02	22.16	<
					99	22.01	22.20	<
0	13.44	13.46	<					
1	13.77	13.73	>					
2	14.06	14.06	<					
3	14.37	14.37	<					
4	14.69	14.65	>					
5	14.92	14.95	<					
6	15.24	15.28	<					
7	15.48	15.47	>					
8	15.75	15.72	>					
9	15.93	15.86	>					
10	16.25	16.10	>	**				
11	16.45	16.34	>					
12	16.64	16.45	>					
13	16.84	16.63	>	**				
14	17.09	16.84	>					
15	17.39	16.99	>	*				
16	17.60	17.24	>	**				
17	17.76	17.47	>					
18	17.78	17.63	>					
19	17.84	17.80	>					
20	18.01	17.90	>					
21	18.15	18.05	>					
22	18.31	18.17	>	**				
23	18.40	18.32	>					
24	18.54	18.49	>					
25	18.59	18.64	<					
26	18.62	18.69	<					
27	18.69	18.86	<					
28	18.75	18.97	<	*				
29	18.86	19.08	<	*				
30	18.98	19.17	<					
31	19.06	19.25	<					
32	19.14	19.39	<					
33	19.16	19.42	<					
34	19.30	19.53	<					
35	19.34	19.65	<					
36	19.43	19.79	<	*				
37	19.55	19.84	<					
38	19.64	19.84	<					
39	19.79	19.90	<					
40	19.88	20.10	<	*				
41	19.91	20.12	<	**				
42	20.06	20.23	<	*				
43	20.15	20.35	<	**				
44	20.27	20.43	<	**				
45	20.33	20.48	<					*
46	20.45	20.46	<					
47	20.56	20.52	>					
48	20.66	20.64	>					
49	20.79	20.68	>					

ENV 9

Figure 4.5: Output from Experiment D7.
(Cont'd)

100	22.05	22.17	<	150	22.64	22.45	>
101	22.10	22.17	<	151	22.64	22.50	>
102	22.10	22.17	<	152	22.68	22.54	> *
103	22.14	22.21	<	153	22.77	22.60	>
104	22.14	22.15	<	154	22.78	22.58	>
105	22.15	22.10	>	155	22.81	22.51	>
106	22.14	22.12	>	156	22.80	22.55	>
107	22.13	22.19	<	157	22.76	22.56	> *
108	22.10	22.26	<	158	22.68	22.54	>
109	22.16	22.29	<	159	22.62	22.50	>
110	22.15	22.31	<	160	22.56	22.44	>
111	22.14	22.40	<	161	22.55	22.43	> **
112	22.18	22.47	< *	162	22.54	22.44	>
113	22.21	22.55	< **	163	22.52	22.45	>
114	22.33	22.49	< **	164	22.55	22.42	>
115	22.35	22.47	<	165	22.56	22.47	>
116	22.36	22.43	<	166	22.59	22.42	>
117	22.38	22.48	<	167	22.57	22.48	>
118	22.41	22.45	<	168	22.56	22.48	>
119	22.41	22.45	<	169	22.51	22.44	>
120	22.42	22.45	<	170	22.51	22.49	>
121	22.48	22.50	<	171	22.52	22.52	>
122	22.48	22.52	<	172	22.48	22.53	<
123	22.47	22.40	>	173	22.52	22.59	<
124	22.46	22.43	>	174	22.53	22.66	< *
125	22.43	22.46	<	175	22.57	22.69	<
126	22.50	22.41	>	176	22.57	22.68	<
127	22.51	22.41	>	177	22.61	22.68	<
128	22.46	22.42	>	178	22.64	22.60	>
129	22.42	22.46	<	179	22.57	22.58	<
130	22.43	22.41	>	180	22.53	22.55	<
131	22.45	22.43	>	181	22.50	22.56	<
132	22.42	22.40	>	182	22.45	22.49	<
133	22.39	22.37	>	183	22.45	22.47	<
134	22.46	22.37	>	184	22.54	22.51	>
135	22.42	22.43	<	185	22.54	22.48	>
136	22.46	22.43	>	186	22.48	22.37	>
137	22.43	22.44	<	187	22.57	22.35	>
138	22.51	22.45	>	188	22.62	22.41	>
139	22.53	22.55	<	189	22.61	22.38	>
140	22.51	22.54	<	190	22.60	22.37	>
141	22.45	22.54	<	191	22.60	22.35	> *
142	22.46	22.54	<	192	22.55	22.43	>
143	22.48	22.53	<	193	22.57	22.41	>
144	22.48	22.47	>	194	22.57	22.40	>
145	22.52	22.45	>	195	22.59	22.47	>
146	22.53	22.46	>	196	22.61	22.46	>
147	22.55	22.44	>	197	22.57	22.48	>
148	22.58	22.46	>	198	22.57	22.42	>
149	22.57	22.45	>	199	22.56	22.42	>

Figure 4.5: Output from Experiment D7.
(Cont'd)

200	22.59	22.38	>	
201	22.61	22.38	>	
202	22.55	22.40	>	
203	22.57	22.40	>	
204	22.66	22.41	>	
205	22.67	22.45	>	
206	22.71	22.44	>	
207	22.71	22.44	>	*
208	22.72	22.39	>	
209	22.73	22.40	>	*
210	22.69	22.42	>	**
211	22.65	22.47	>	**
212	22.68	22.42	>	
213	22.75	22.38	>	**
214	22.78	22.44	>	*
215	22.81	22.46	>	*
216	22.80	22.48	>	*
217	22.80	22.40	>	**
218	22.84	22.39	>	**
219	22.83	22.46	>	
220	22.89	22.48	>	*
221	22.91	22.48	>	*
222	22.91	22.44	>	*
223	22.88	22.45	>	**
224	22.86	22.48	>	**
225	22.78	22.50	>	
226	22.85	22.48	>	
227	22.90	22.55	>	*
228	22.92	22.58	>	*
229	22.95	22.58	>	**
230	22.97	22.55	>	*
231	22.98	22.57	>	*
232	22.95	22.55	>	**
233	22.91	22.55	>	
234	22.93	22.54	>	
235	22.88	22.52	>	**
236	22.92	22.56	>	*
237	22.95	22.58	>	
238	22.99	22.58	>	*
239	23.00	22.61	>	
240	22.96	22.63	>	
241	22.92	22.64	>	*
242	22.92	22.60	>	
243	22.95	22.59	>	
244	22.93	22.57	>	
245	22.94	22.56	>	*
246	22.87	22.54	>	
247	22.87	22.49	>	**
248	22.90	22.54	>	
249	22.89	22.54	>	*
250	22.87	22.51	>	*

Figure 4.5: Output from Experiment D7.

GEN	NEAR MEAN	FAR MEAN	DIR	SIG					
					50	19.05	18.01	>	**
					51	19.11	18.09	>	**
0	14.10	14.15	<		52	19.22	18.18	>	**
1	14.28	14.27	>		53	19.39	18.26	>	**
2	14.43	14.33	>		54	19.50	18.28	>	**
3	14.49	14.37	>		55	19.59	18.28	>	**
4	14.58	14.48	>		56	19.67	18.48	>	**
5	14.71	14.53	>	*	57	19.77	18.44	>	**
6	14.83	14.51	>	**	58	19.88	18.53	>	**
7	15.02	14.66	>		59	19.99	18.59	>	**
8	15.10	14.70	>	*	60	20.01	18.73	>	**
9	15.17	14.79	>	*	61	20.03	18.82	>	**
10	15.21	14.89	>	*	62	20.14	18.86	>	**
11	15.32	14.99	>	**	63	20.14	18.91	>	**
12	15.36	15.11	>		64	20.23	18.98	>	**
13	15.52	15.17	>	**	65	20.22	19.08	>	**
14	15.66	15.16	>	*	66	20.22	19.02	>	**
15	15.79	15.25	>	**	67	20.26	19.11	>	**
16	15.88	15.37	>	*	68	20.30	19.10	>	**
17	15.98	15.51	>	*	69	20.36	19.13	>	**
18	16.04	15.50	>	**	70	20.44	19.08	>	**
19	16.05	15.64	>	*	71	20.48	19.13	>	**
20	16.21	15.66	>	*	72	20.58	19.19	>	**
21	16.35	15.71	>	**	73	20.65	19.17	>	**
22	16.46	15.77	>	**	74	20.71	19.23	>	**
23	16.56	15.84	>	**	75	20.74	19.27	>	**
24	16.64	15.93	>	**	76	20.76	19.27	>	**
25	16.69	16.06	>	**	77	20.90	19.39	>	**
26	16.69	16.08	>	**	78	20.95	19.49	>	**
27	16.82	16.16	>	**	79	21.06	19.43	>	**
28	16.93	16.19	>	**	80	21.08	19.53	>	**
29	17.09	16.24	>	**	81	21.08	19.53	>	**
30	17.14	16.27	>	**	82	21.05	19.58	>	**
31	17.22	16.38	>	**	83	21.07	19.63	>	**
32	17.35	16.51	>	**	84	21.19	19.64	>	**
33	17.42	16.62	>	**	85	21.16	19.61	>	**
34	17.56	16.74	>	**	86	21.16	19.66	>	**
35	17.68	16.72	>	**	87	21.28	19.72	>	**
36	17.72	16.90	>	**	88	21.28	19.71	>	**
37	17.87	17.04	>	**	89	21.36	19.76	>	**
38	17.92	17.09	>	**	90	21.39	19.78	>	**
39	17.99	17.18	>	**	91	21.44	19.78	>	**
40	18.14	17.28	>	**	92	21.46	19.76	>	**
41	18.29	17.31	>	**	93	21.48	19.79	>	**
42	18.45	17.50	>	**	94	21.50	19.81	>	**
43	18.52	17.52	>	**	95	21.49	19.88	>	**
44	18.55	17.56	>	**	96	21.51	19.79	>	**
45	18.64	17.63	>	**	97	21.54	19.73	>	**
46	18.73	17.73	>	**	98	21.53	19.74	>	**
47	18.77	17.82	>	**	99	21.60	19.82	>	**
48	18.81	17.84	>	**					
49	18.91	17.97	>	**					

ENV 10

Figure 4.6: Output from Experiment D8.
(Cont'd)

100	21.56	19.96	>	**	150	22.21	21.01	>	**
101	21.56	20.05	>	**	151	22.23	21.04	>	**
102	21.65	20.08	>	**	152	22.21	21.11	>	**
103	21.68	20.15	>	**	153	22.33	21.17	>	**
104	21.66	20.15	>	**	154	22.36	21.19	>	**
105	21.66	20.22	>	**	155	22.27	21.17	>	**
106	21.69	20.24	>	**	156	22.28	21.18	>	**
107	21.74	20.31	>	**	157	22.25	21.13	>	**
108	21.71	20.32	>	**	158	22.19	21.11	>	**
109	21.77	20.33	>	**	159	22.29	21.09	>	**
110	21.76	20.42	>	**	160	22.24	21.02	>	**
111	21.87	20.42	>	**	161	22.27	21.03	>	**
112	21.91	20.43	>	**	162	22.22	21.03	>	**
113	21.91	20.56	>	**	163	22.23	20.93	>	**
114	21.84	20.52	>	**	164	22.19	20.95	>	**
115	21.91	20.53	>	**	165	22.27	20.96	>	**
116	21.85	20.50	>	**	166	22.39	20.96	>	**
117	21.92	20.57	>	**	167	22.40	21.00	>	**
118	22.02	20.61	>	**	168	22.38	21.01	>	**
119	22.05	20.65	>	**	169	22.39	20.97	>	**
120	22.09	20.65	>	**	170	22.37	20.96	>	**
121	22.14	20.69	>	**	171	22.30	21.07	>	**
122	22.10	20.67	>	**	172	22.27	20.98	>	**
123	22.07	20.69	>	**	173	22.38	21.03	>	**
124	22.12	20.64	>	**	174	22.36	21.11	>	**
125	22.15	20.58	>	**	175	22.24	21.12	>	**
126	22.07	20.66	>	**	176	22.25	21.06	>	**
127	22.08	20.67	>	**	177	22.27	21.02	>	**
128	22.08	20.68	>	**	178	22.19	21.00	>	**
129	22.05	20.71	>	**	179	22.21	20.96	>	**
130	21.99	20.77	>	**	180	22.14	20.96	>	**
131	21.90	20.85	>	**	181	22.14	20.95	>	**
132	21.89	20.80	>	**	182	22.11	20.97	>	**
133	21.91	20.80	>	**	183	22.13	20.99	>	**
134	21.87	20.81	>	**	184	22.21	20.98	>	**
135	21.92	20.78	>	**	185	22.21	20.98	>	**
136	21.94	20.81	>	**	186	22.20	20.96	>	**
137	21.92	20.85	>	**	187	22.14	21.02	>	**
138	22.01	20.90	>	**	188	22.11	21.08	>	**
139	22.03	20.89	>	**	189	22.10	21.12	>	**
140	22.08	20.88	>	**	190	22.13	21.14	>	**
141	22.05	20.92	>	**	191	22.05	21.12	>	**
142	22.10	20.88	>	**	192	22.11	21.20	>	**
143	22.01	20.96	>	**	193	22.16	21.26	>	**
144	22.00	20.90	>	**	194	22.23	21.17	>	**
145	22.05	20.92	>	**	195	22.25	21.19	>	**
146	22.17	20.87	>	**	196	22.28	21.25	>	**
147	22.12	20.88	>	**	197	22.31	21.28	>	**
148	22.18	20.88	>	**	198	22.31	21.28	>	**
149	22.21	20.96	>	**	199	22.30	21.31	>	**

Figure 4.6: Output from Experiment D8.
(Cont'd)

200	22.36	21.22	>	**	237	22.57	21.36	>	**
201	22.40	21.22	>	**	238	22.52	21.40	>	**
202	22.43	21.18	>	**	239	22.54	21.33	>	**
203	22.43	21.15	>	**	240	22.52	21.28	>	**
204	22.37	21.21	>	**	241	22.43	21.27	>	**
205	22.31	21.23	>	**	242	22.41	21.29	>	**
206	22.44	21.17	>	**	243	22.41	21.28	>	**
207	22.55	21.21	>	**	244	22.52	21.31	>	**
208	22.55	21.23	>	**	245	22.44	21.34	>	**
209	22.46	21.35	>	**	246	22.44	21.38	>	**
210	22.33	21.30	>	**	247	22.51	21.47	>	**
211	22.31	21.27	>	**	248	22.49	21.40	>	**
212	22.31	21.24	>	**	249	22.53	21.45	>	**
213	22.34	21.21	>	**	250	22.50	21.46	>	**
214	22.38	21.26	>	**					
215	22.29	21.26	>	**					
216	22.37	21.17	>	**					
217	22.41	21.15	>	**					
218	22.40	21.08	>	**					
219	22.41	21.08	>	**					
220	22.42	21.11	>	**					
221	22.42	21.15	>	**					
222	22.44	21.20	>	**					
223	22.40	21.23	>	**					
224	22.35	21.23	>	**					
225	22.34	21.32	>	**					
226	22.38	21.30	>	**					
227	22.48	21.34	>	**					
228	22.48	21.36	>	**					
229	22.44	21.32	>	**					
230	22.40	21.36	>	**					
231	22.30	21.29	>	**					
232	22.31	21.29	>	**					
233	22.28	21.35	>	**					
234	22.38	21.36	>	**					
235	22.42	21.40	>	**					
236	22.38	21.40	>	**					

Figure 4.6: Output from Experiment D8.

t-test performed to detect a significant difference. The results of these experiments are best shown by the computer output. In these figures (4.1-4.6) the column labeled "NEAR MEAN" gives the average population payoff for the permutation with all dependent genes adjacent and the column labeled "FAR MEAN" gives the average for the worst case payoff. The column labeled "DIR" shows the direction of the difference (< means NEAR<FAR, and > means NEAR>FAR). The column labeled "SIG" shows whether the difference between the two values is significant. One asterisk (*) means the difference is significant at the 95% level and two asterisks (**) indicates significance at the 99% level.

Figure 4.1 shows the results for experiment D1, ENV 2. At no time is the difference between the two populations significant and the direction of the difference is not consistently in either direction. With some confidence we can say there is no position effect in ENV 2, our simplest non-linear environment. The lowered selection experiment, D2, showed significance in the right direction at some points.

Figure 4.2 shows the results for experiment D3, ENV 3. It is of considerable interest that the direction of difference between means is in the desired direction quite consistently through 74 generations, and that the difference is significant at the 99% level for generations 8 through 42. After generation 74 the sense of the difference wanders but settles down after generation 95 to "<" up to generation 150, with the difference only occasionally significant. There is a definite difference in the rate of evolution early in time with the adjacent combinations performing best. Afterwards the separated permutations catch up and exceed the adjacent ones, although not usually significantly. Experiment D4, the lowered selection version of D3, showed somewhat

Exp	ENV	Early	Equilibrium
D1	2	> Not Sig	< Not Sig
D2	5	> Sometimes Sig	=
D3	3	> Sig	< Not Sig
D4	6	> Sometimes Sig	< Not Sig
D5	7	> Sig	> Sig
D6	8	> Sig	< Sometimes Sig
D7	9	> Sometimes Sig	> Sig
D8	10	> Sig	> Sig

Table 4.7: Summary of Best/Worst Evolution Experiments.

different behavior in that while the difference was ">" much of the time in the early stages, it was only sometimes significant.

Experiments D5 (ENV 7), D6 (ENV 8), and D8 (ENV 10) all showed early significant differences favoring the adjacent permutations. In D5 and D8 there was also a significant difference at the equilibrium state. In D7 the earliest trend (while not always significant) again favored the adjacent permutations.

Table 4.7 summarizes the differences in means for experiments D1-D8 in their early and late stages of evolution. Out of the eight different environments four show significant early differences favoring the adjacent permutations, three show consistent, sometimes significant differences in the right direction, and only one never shows significance, although its earliest direction is still correct. It is important to note that of the three environments containing more than one dependent group (7,8, and 10), all three showed significant early differences. This strongly implies that the more complex the environment, the more important is the permutation.

Approach to the Optimum

We shall undertake another analysis to show the importance of position in early evolution. We noted that experiments D5, D7, and D8 all had significantly greater population averages at the end of twenty runs for the best permutation. However, population average doesn't tell us everything there is to know. We can, in addition, look at the maximum payoff attained in each run. Not all populations attained the maximum possible payoff value; many got hung up on false peaks. It may be that permutations have something to do with this. Although

we do not have enough data to make authoritative conclusions in this regard, the analysis below is strongly supportive of the belief that good permutations in early evolution are important.

In each of the three above-mentioned experiments we count the number of populations (out of the 20 obtained) in which a particular peak was attained at the end of the run. For example, in ENV 7, the best individuals in the populations ended up on peaks paying 34, 35, 36, and 37, as well as on the true maximum of 38. We then take the average of all the populations which have achieved a particular peak. This is done for populations using both the best and the worst permutations. The results are tabulated in Table 4.8 for the three experiments. It is clear that the population average associated with a particular peak reflects the magnitude of the peak. (But it may be that at the particular point in time that data was taken, a peak had just appeared in or disappeared from the population, so that the population average does not reflect the peak shown. As a matter of fact, we often note in the source data that there are only one or two adherents to a peak. However, these are standard problems in sampling and we must take the data as is. Taking more sample points is the only way of solving this problem.)

A two-sided t-test for difference between means was performed for those peaks which showed up in two or more samples in both the best and worst permutation runs. The direction of the difference most often favored the adjacent permutations, but never significantly (i.e., at the 95% level or more). This leads us to believe that once a population has homed in on a peak the permutation makes no difference, as many of our previous experiments indicate. In simple environments

Exp	Best indiv.	Best Permutation		Worst Permutation		DIR	SIG
		Number populations	Ave. Pay	Number populations	Ave. Pay		
D5	34	1	31.63	2	30.67		
	35	3	31.48	7	31.02	>	
	36	4	32.58	2	31.66	>	
	37	7	33.11	3	32.14	>	
	38	5	34.33	6	33.85	>	
D7	24	0		3	21.47		
	25	9	22.45	11	22.34	>	
	26	11	23.22	6	23.35	<	
D8	23	1	20.21	2	20.42		
	24	1	20.10	8	21.38		
	25	6	22.07	8	21.60	>	
	26	8	22.83	2	22.92	<	
	27	4	23.68	0			

Table 4.8: Best Individuals vs. Population Payoff.

nearly all populations find the true optimum, even given the worst permutation of genes on their chromosomes. More complex environments, however, are more likely to trap a population on a false peak so that sampling the equilibrium point obtains more false peaks, possibly yielding a significant difference in sampled overall means, as in this case. We note especially that experiment D8, which used our most complex and sparsest payoff function, ENV 10, failed to attain the optimum point at all in twenty runs with the worst gene permutation, while the optimum was attained four times with the most favorable permutation. Other comparisons are similar.

The important lesson to be gained from all this is that sparse payoff functions require close permutations if a good point is to be maintained once it is found; otherwise, random effects are enough to overcome a true peak's advantage in selection and drive the population to any of the numerous false peaks in an environment.

Inversion Experiments

To determine whether inversion has any effect as a genetic operator we can do two things: look at the population average when inversion is and is not in use; and investigate the actual gene permutations in the populations. The first method was that chosen by Cavicchio (3) and Bosworth (2). Its greatest failing is that it does not completely verify the hypothesis; that is, it may be that the inversion operator effects the payoff average by means other than bringing together interacting genes.

In fact, Cavicchio's inversion experiments are subject to an entirely different analysis. Briefly, Cavicchio's chromosomes consisted

of many copies of the same gene--a gene which had a very large number of alleles. If there were two copies of the same allele on one chromosome (an *a priori* unlikely event) the effect of that allele would be increased--unlike our system in which only one allele is allowed to appear for a gene. His system did not need to check for homology since all genes were the same. Any two individuals could always mate. The alternate analysis of the effectiveness of inversion then states the following. For exactly the same reason that we need mating rules when inversion is used in our system (i.e., to avoid missing or multiple copies of a gene), it is likely that an inversion followed by a mating with the parent or a sibling will produce individuals with multiple copies of some alleles. Multiple copies of a good allele would then increase payoff. Since Cavicchio did not study the micro-structure of his populations we do not have any evidence on which to accept one explanation over the other.

If we were to make Cavicchio's claim (i.e., comparison of population averages) on our kinds of experiments, the claim would be easier to accept since our protocol does not allow for this alternate hypothesis. It does, however, allow for the possibility that dependent genes work best farther apart and that inversion helps attain a large distance. Further verification would be needed.

Bosworth makes this sort of claim (that inversion is effective in bringing epistatic genes together) but presents no proof in (2). However, in discussions with him, it appears that he has unanalyzed data that might prove the point for a two gene case.

The experiments in the first two parts of this chapter are first attempts to show that inversion can work as advertised: indeed, under

certain circumstances the position of genes on a chromosome is important. Formally, it is easy to show that an operator such as inversion can produce any possible permutation of genes. Thus, as in a classic crime case, we can show motive (adaptive advantage), means (the ability to produce any permutation), and opportunity (inversion is a part of our adaptive system). However, in this case we need an eyewitness: hence the experiments.

Probabilities of Permutations

In order to state that genes are actually being pushed closer on a chromosome, we need some idea of how distant a set of genes is likely to be under random assignment.

Let the length of the chromosome be m and let the number of genes in the set, N , be n ($2 \leq n \leq m$). Assume that every permutation of m genes (of which there are $m!$) is equally likely. For any permutation define L to be the position of the leftmost gene from the set N and R to be the position of the rightmost gene from the set N . For convenience we define the distance, D , to be $R-L+1$. Thus the maximum distance is m and the minimum distance for a set of two genes is two (when they are adjacent).

Now, the total number of different permutations of n genes on a chromosome of length m is $\binom{m}{n}$. Thus, for any distance, we have

$$P(D=d) = (\text{Number permutations with } D=d) / \binom{m}{n}.$$

The numerator of this expression is just

$$(m-d+1) \binom{d-2}{n-2}$$

$$P(D=d) = \frac{(m-d+1) \binom{d-2}{n-2}}{\binom{m}{n}} \quad 2 \leq n \leq d \leq m$$

where m = length of chromosome

n = size of group

d = distance

Numbers below are for $m = 25$.

d	2		5		6		8	
	P(D=d)	P(D≤d)	P(D=d)	P(D≤d)	P(D=d)	P(D≤d)	P(D=d)	P(D≤d)
2	.080	.080						
3	.077	.157						
4	.073	.230						
5	.070	.300	.000	.000				
6	.067	.367	.002	.002	.000	.000		
7	.063	.430	.004	.005	.001	.001		
8	.060	.490	.007	.012	.002	.002	.000	.000
9	.057	.547	.011	.023	.003	.006	.000	.000
10	.053	.600	.017	.040	.006	.012	.001	.001
11	.050	.650	.024	.064	.011	.023	.001	.002
12	.047	.697	.032	.096	.017	.039	.003	.004
13	.043	.740	.040	.136	.024	.063	.006	.010
14	.040	.780	.050	.186	.034	.097	.010	.020
15	.037	.817	.059	.245	.044	.141	.017	.038
16	.033	.850	.069	.313	.057	.198	.028	.065
17	.030	.880	.077	.391	.069	.267	.042	.107
18	.027	.907	.084	.475	.082	.349	.059	.166
19	.023	.930	.090	.564	.094	.443	.080	.246
20	.020	.950	.092	.657	.104	.547	.103	.349
21	.017	.967	.091	.748	.109	.657	.125	.475
22	.013	.980	.086	.834	.109	.766	.143	.618
23	.010	.990	.075	.909	.101	.867	.151	.769
24	.007	.997	.058	.967	.083	.950	.138	.907
25	.003	1.000	.033	1.000	.050	1.000	.093	1.000
	Mean = 9.67		Mean = 18.34		Mean = 19.56		Mean = 21.22	

Table 4.9: Probability of Dispersion of Genes on a Chromosome.

That is, there are $(m-d+1)$ ways of positioning the outermost two genes at distance d , leaving the interior $(d-2)$ positions to be filled by the $(n-2)$ remaining genes. The cumulative distribution is

$$P(D \leq d) = \binom{d}{n} \binom{nm-nd+d}{d} / \binom{m}{n}$$

which is obtained after a page of not very interesting manipulation.

Table 4.9 contains the probabilities for distances on a chromosome of length 25 of groups of size 2,5,6, and 8. We note particularly that for 2 genes the median and mean distances are between 8 and 9; for 5 genes they are between 18 and 19; for 6 genes they are between 19 and 20, and for 8 genes they are between 21 and 22. Any reference to "good" permutations will have to be measured against these figures.

Experimental Protocol

All the experiments in the rest of this chapter have the following protocol. Each experiment consists of 5 or 10 runs from an initial, random population. Each population begins with all its individuals having the same gene permutation, but that permutation is different for each run. The ten random permutations used are listed in the Appendix. (These random permutations were obtained by generating 25 random numbers and sorting them. The i 'th random number then ends up in position j , defining a random permutation of the numbers 1-25.) Each experiment involves a particular combination of an inversion operator and a mating scheme.

At the end of each run three sets of data are collected. The first concerns the distance D , as defined above, for a given set of genes: the distance between the left- and right-most positions of genes from

that set. D is calculated for every chromosome in the population, 100 samples in all. At the end of 5 or 10 runs there are 500 or 1000 samples of D , falling into at most 25 different cells. The data collected is then the number of chromosomes which have distance $D(2 \leq D \leq 25)$.

The other two sets of data concern the distance between all possible pairs of genes. There are $\binom{25}{2} = 300$ such pairs. For each of the 300 pairs two items are collected over the 500 or 1000 samples: the average distance, and the number of chromosomes in which the distance is 9 or less.

The analysis to be performed is a comparison of these values against the values predicted by the probability distribution calculated above to determine whether the inversion/mating combination has produced permutations which are different from chance, specifically, whether particular sets of genes have moved closer together on the chromosomes. (Details are given below.) Immediately we are faced with an ancient problem in statistics. Any statistical test requires that all sample points be obtained independently. But in each of the 10 runs all 100 chromosomes start out with the same permutation, not 100 different random permutations. Presumably, the random inversion will tend to alter the initial permutations, but the danger exists that the chromosomes will still look like the initial permutation after some number of generations. In addition, even if the initial permutation has been changed by inversion so that it bears no more than a chance resemblance to some terminal chromosome, it is quite likely that all the chromosomes in a terminal population resemble each other. These problems are of great importance and would cause serious difficulties if we wished to perform strict statistical analyses. It is our hope, however, that

the results will be sufficiently outstanding that such a procedure is not required. We will take the data as it is to see if statistical analysis is warranted and then worry about whether it is feasible.

There are many possible combinations of the genetic operators and mating rules concerned with inversion described in Chapter Three. We list them below for convenience.

<u>Inversion type</u>	<u>Inversion time</u>	<u>Mating rule</u>
Linear	Continuous	Strict-homology
Linear+end	Mass	Viability
		Any-pattern
		Best-pattern

We do not report in detail any of the experiments attempted using the linear inversion type (i.e., just picking two inversion points at random). As mentioned in Chapter Three, this method of selecting pivot points yields a small probability for the end points to be moved in an inverted segment. Early experiments indicated that there was a very strong tendency for the end genes to stay in place over many generations. We stopped using "linear" and all the remaining experiments were run using the linear+end operator.

Of the eight possible inversion time/mating rule combinations which might be tested for usefulness we immediately knock out continuous/strict-homology. Bagley (1) reported that this combination caused great difficulty because the individual inversions were almost all different so that few were able to discover homologous mates. As a result the system was slowed down by the necessity of making several selections of parents for one member of the new population; and, we

presume, most of the offspring thus tended to be of the initial permutation, since there were more of these in the parent generation. We are thus left with seven possibilities, all of which we will try. For each of these combinations, the level of the inversion probability is another variable. We will try these combinations at two or three levels only.

For convenience we will identify experiments by two letters specifying the inversion type and mating scheme, followed by a number specifying the inversion operator probability level, followed by a number specifying the experiment of this type. For example, MH3/2 means the second experiment using the combination Mass/Homology/0.3. The experiment designations are as follows.

<u>Inversion type</u>	<u>Mating scheme</u>	<u>Operator level.</u>	<u>Designation</u>
Mass	Viability	0.2	MV2
Mass	Viability	0.3	MV3
Mass	Homology	0.2	MH2
Mass	Homology	0.3	MH3
Mass	Any	0.2	MA2
Mass	Any	0.3	MA3
Mass	Best	0.2	MB2
Mass	Best	0.3	MB3
Continuous	Viability	0.1	CV1
Continuous	Biability	0.2	CV2
Continuous	Any	0.05	CA05
Continuous	Any	0.1	CA1
Continuous	Any	0.2	CA2
Continuous	Best	0.1	CB1
Continuous	Best	0.2	CB2

Not all combinations will be tried with all environments or at different generation times.

Experimental results are given in tables such as Table 4.10.

While most of the table heading are obvious, the last three require explanation, being the basis for judging the results of the experiment.

Each of the environments listed (See Figures 3.2-3.10) has its first group of genes non-linear. For example, in environments 3,7, and 8, genes 1-6 are non-linear, and in environment 2, genes 1-5 are dependent. For each experiment facing these environments, the D-value for these groups of genes is calculated, yielding the number of chromosomes observed with the various D-values. The column labeled "Prop \leq M" is the proportion of chromosomes observed whose D value was M or less, where M is 19 for environments 2-8 and 21 for environments 9 and 10. Consulting Table 4.9 we note that for 5 genes, the proportion of chromosomes expected randomly to assume D-values of 19 or less is .564; for 6 genes the proportion is .443; for 8 genes the proportion of D-values of 21 or less is .475. If there is any movement of genes together we expect these proportions to be exceeded in the data collected. As an example, see Figure 4.7(b) which shows the results of experiment MH3/4: the number of chromosomes taking on various D-values. If we were so inclined we could do a chi-squared goodness-of-fit test to see if the distribution of D-values observed were close to that predicted. Failing that, we might perform a binomial probability test to see whether the proportion observed at 19 or less was significantly more than the proportions (i.e., binomial probabilities) mentioned above. We did not perform either of these tests. We merely point out in the table (by an asterisk next to the value) those experiments in which the proportion observed was greater than the proportion expected. We follow this course rather than that of the more sophisticated statistics

for two reasons: non-independence of sampling makes the statistics suspect, and, as we note below, the results do not seem to be very positive, obviating the need for subtle analysis.

The column labeled "# \geq .547" refers to the pair-data collected. By Table 4.9 we observe that the probability that a pair is randomly at a distance of 9 or less is 0.547. For convenience, we shall call a distance of 9 or less "close". One of the pieces of data collected for each pair of genes is the number of chromosomes in which the D-value for the pair is observed to be close. On the average then, we expect 54.7% of the pair D-values observed to be close. Further, there is a 0.5 probability that we will observe a pair whose close count is greater than 54.7%. Now in a dependent group of size n there are $\binom{n}{2}$ pairs of genes from that group; e.g., for groups of size 6 there are 15 pairs and for groups of size 5 there are 10 pairs. If genes are positioned randomly we expect half the pairs to have large counts. If there is any tendency for genes to move together, there will be a tendency for there to be more chromosomes with $D \leq 9$ and a greater than .5 chance for a pair to have a close count larger than 54.7%, so that we would expect that more than 50% of the pairs from a congregating group to have large close counts. The column "# \leq .547" refers to the number of pairs which have large (i.e., a proportion larger than .547) close counts. It sounds a bit complicated, but an example will probably (P=.8) help. Figure 4.7(a) shows a portion of the printout from the computer program which yields this data for experiment MH3/4. The upper portion of the matrix contains the close counts (i.e., the number of chromosomes observed with D-values less than or equal to 9). This experiment had 10 runs, obtaining 1000 sample

	1	2	3	4	5	6	7	8	9	10	11	12	13
1	-	770	368	365	637	596	627	712	691	368	632	359	639
2	65	-	473	544	738	375	642	731	211	132	463	346	385
3	100	97	-	485	524	816	561	800	668	653	396	303	498
4	111	92	91	-	748	753	592	405	626	493	332	586	656
5	83	56	84	66	-	673	616	561	214	449	518	502	560
6	72	95	66	74	71	-	506	612	768	611	510	514	977
7	69	67	76	78	66	84	-	677	529	415	577	443	605
8	82	71	69	98	86	57	74	-	501	306	468	198	609
9	86	125	100	78	105	53	88	79	-	811	515	485	759
10	106	143	88	85	107	73	86	99	55	-	520	654	815
11	76	97	103	110	90	74	79	97	80	96	-	657	705
12	106	125	115	81	90	84	98	132	99	73	66	-	680
13	79	106	77	75	75	35	85	82	57	59	69	77	-
14	92	74	63	74	57	69	71	56	98	108	81	92	84
15	69	110	102	93	92	58	99	101	52	72	64	94	44
16	75	83	95	81	78	94	55	69	77	84	87	98	100
17	83	93	82	114	100	86	57	74	88	81	73	102	83
18	92	74	90	100	88	106	75	90	121	112	93	74	97
19	104	121	81	82	95	64	87	82	79	75	108	89	74
20	83	127	104	87	96	76	91	113	74	66	120	81	82
21	85	62	114	73	50	95	76	101	123	119	86	83	98
22	68	93	93	106	87	84	66	91	82	69	64	91	79
23	100	101	77	87	80	58	75	73	61	71	78	86	70
24	93	92	54	108	102	92	59	60	107	90	100	108	96
25	116	97	72	83	102	86	88	81	101	106	112	98	89

Closeness count (upper triangular matrix)

Average distance times 10 (lower triangular matrix)

(a)

Distribution of group distance

D	count	D	count
≤10	0	18	60
11	142	19	169
12	0	20	252
13	0	21	74
14	0	22	0
15	49	23	31
16	33	24	6
17	126	25	58

(b)

Figure 4.7: Output from Experiment MH3/4.

chromosomes. Of the 10 pairs from the set (1,2,3,4,5), four are greater than 547: (1,2) is 770, (1,5) is 637, (2,5) is 738, and (4,5) is 748; the other six pairs have lower than average values. The entry in the "# \geq .547" column is thus 4/10.

A sophisticated analysis of this information would use the binomial distribution to test the significance of the close count's excess over .547 and the excess of pairs (over 50%) having large close counts. (We realize that the pairs are not independent samples, but this approach might still have value.) However, such manipulation would only be useful for our purposes if a clearcut trend were to be observed. Instead, we only indicate when a value is in the right direction (greater than a half) by putting an asterisk next to it in the table.

The column "# \leq 8.67" again refers to pair data, this time to the average distance between pairs over all samples in the experiment. In this case, we are using D' as the distance where $D'=D-1=L-R$, for convenience. The lower half of the matrix in Figure 4.7(a) gives this average distance. Again, we count the number of pairs (from a group) whose average distance is less than the *expected* distance of 8.67. The average distance between pairs in a group should go down if the group is congregating, so that the number of pairs with distance less than 8.67 should be large if inversion is working. As postulated in the previous column, we indicate that a value is in the right direction by an asterisk.

Clearly, these last two columns are related: the more chromosomes that have a D-value less than the average, the lower the average distance. We include both measures to see if one is any better predictor.

(As the reader will note, not all experiments collected pair data. Those experiments were run at a time before this data collection was programmed. In general, the results do not seem interesting enough to do a rerun.)

The reason we bother collecting data on pairs is the following. If we determine that genes really do move closer together, we will still be faced with finding a method of determining which genes constitute a group when we do not have any *a priori* knowledge of the environment. If, at the same time, all pairs of genes in a congregating group show distances much smaller than predicted by chance, it may be possible to construct a group merely by examining the pair matrix to find pairs with abnormal values.

Equilibrium Tests

We recall that the first part of this chapter showed migration to be an effective means of prolonging variance in the population such that small differences in distance became a significant determinant in average population payoff. Table 4.10 summarizes the experiments performed to test the effect of the inversion/mating/operator-level combinations for populations in equilibrium under migration pressure. Several environments and run lengths were tried, along with two different migration levels. Since most of the runs were 500 generations or more we anticipate that any long term effect should have time to make itself felt.

Recalling that asterisks next to a value indicate that the value is in the direction of showing clumping, we observe that the asterisks

INV/ MATE/ LEVEL	ID	MIGR %	ENV	# RUNS	# GENS	Prop \leq M	# \geq .547	# \leq 8.6
MV2	1	25	3	10	500	.516*		
	2	25	3	10	2000	.412		
	3	25	2	10	250	.628*	5/10	3/10
	4	25	2	10	500	.552	5/10	4/10
MV3	1	15	8	5	500	.562*	9/15*	8/15
	2	15	7	5	500	.408	6/15	7/15
MH2	1	25	3	10	500	.298		
MH3	1	25	3	10	500	.771*		
	2	25	3	10	2000	.325		
	3	25	2	10	250	.460	2/10	3/10
	4	25	2	10	500	.579*	4/10	5/10
	5	15	8	5	500	.242	4/15	5/15
	6	15	7	5	500	.402	9/15*	9/15
MA2	1	25	3	10	500	.522*		
	2	25	3	10	2000	.436		
	3	25	2	10	2000	.552	5/10	6/10
	4	25	2	10	2000	.591*	5/10	5/10
MA3	1	25	3	10	500	.354		
MB2	1	25	3	5	500	.322	6/15	6/15
	2	25	2	5	500	.638*	7/10*	7/10
MB3	1	25	3	5	500	.722*	12/15*	11/15
	2	25	2	5	500	.730*	5/10	5/10
	3	15	7	5	500	.578*	9/15*	9/15
	4	15	8	5	500	.404	7/15	6/15
CV1	1	25	3	10	500	.260		
	2	15	7	5	500	.410	9/15*	7/15
	3	15	8	5	500	.388	8/15*	8/15
CA05	1	25	3	10	500	.332		
CA1	1	25	3	10	500	.391		
CA2	1	25	3	10	500	.463*		
CB1	1	25	3	5	500	.508*	9/15*	7/15
	2	25	2	5	500	.664*	10/10*	9/10
	3	15	7	5	500	.280	6/15	8/15
	4	15	8	5	500	.456*	6/15	8/15

See text for explanation of headings

Table 4.10: Inversion/Equilibrium Experiments.

appear next to 34 out of 78 entries in the table. (We might expect slightly less than 39 asterisks randomly.) This is the bad news which makes it unnecessary for us to perform any more sophisticated analysis. We conclude that over all the possible combinations of inversion tried, there is no distinct movement of genes together on the chromosome. The combinations mass/best/0.3 and continuous/best/0.1 are much more positive in their effects than others, but they are not consistent. If we were to explore further it would certainly be with these parameters. However, the pair data for those combinations is weak, destroying whatever hope we might cherish of being able to detect movement when we did not know what we were looking for. In particular, although the counts and average distances exceed the thresholds set for them, they do not exceed them by much, certainly not by as much as many other samples do.

Since the table speaks for itself, and since the results are not too positive, we will mercifully cut short any further analysis and end this section, saving discussion for the end of the chapter.

Evolving Tests

In the section of this chapter entitled "Evolving Populations" we showed that although differences in payoff due to gene distances did not always show up in the equilibrium state, they did show up consistently, very often significantly, in the early stages of evolution. In addition, the goodness of a permutation had an important effect on how close the population could get to the true maximum.

With this in mind we report here on a set of experiments which test combinations of the mating/inversion operators to see if any of them have effect on permutations early in evolution. Picking a time at which to measure distances is a difficult task. Clearly, if there is a distance effect early, but not later, running too long will destroy any adaptation on permutations due to the early effect. The values chosen (50,150, and 250 generations for the various environments) seem to be reasonable. If the effect is there, but only to be observed at particularly special instants of time, it does not do us much good, since it is unlikely that we would discover this time accidentally. We do not wish to do an exhaustive search: we need a strong effect.

Table 4.11 reports on these efforts. Most of the trials were allocated to the combinations involving the "best-pattern" mating rule since these had shown the most promise in the previous trials. Again, mass/best/0.3 showed well; but continuous/best/0.1 did not fare well and continuous/best/0.2 did only average (4 of 8 trials showed movement in the right direction). For MB3, 7 of 8 trials showed movement of the total group D-value in the right direction but experiments 14,15, and 16 exceeded the expected proportion of .433 by .008, .013, and .011, hardly significant differences. In addition the result for ENV 2 must be viewed with caution since our previous experiments show little reason to expect success with this, the simplest of all our non-linear environments. Even counting ENV 2, the four positive experiments (MB3/10,11,12, and 17) may well be significant, but they represent success on only four of the six environments. A final source of discouragement is that the pair data do not reveal any reason to believe that detection of a group would be easy under these circumstances.

INV/ MATE/ LEVEL	ID	ENV	# GENS	Prop \leq M	# \geq .547	# \leq 8.67
MV2	10	9	150	.642*	11/28	13/28
	11	10	250	.429	14/28	12/28
MV3	10	9	150	.439	12/28	10/28
	11	10	250	.411	15/28*	13/28
MH2	10	9	150	.600*	11/28	13/28
	11	10	250	.457	8/28	8/28
MH3	10	9	150	.450	12/28	7/28
	11	10	250	.748*	19/28*	19/28*
MA2	10	9	150	.455	11/28	13/28
	11	10	250	.482*	11/28	10/28
MA3	10	9	150	.539*	19/28*	18/28*
	11	10	250	.454	15/28*	11/28
MB2	10	9	150	.240	12/28	10/28
	11	10	250	.418	13/28	13/28
MB3	10	9	150	.535*	10/28	11/28
	11	10	250	.644*	18/28*	16/28*
	12	2	50	.692*	7/10*	7/10*
	13	2	150	.488	5/10	5/10
	14	3	50	.451*	7/15	7/15
	15	3	150	.456*	9/15*	10/15*
	16	7	150	.454*	9/15*	7/15
	17	8	150	.561*	10/15*	9/15*

Table 4.11: Inversion/Evolution Experiments.
(Cont'd)

INV/ MATE/ LEVEL	ID	ENV	# GENS	Prop \leq M	# \geq .547	# \leq 8.67
CV1	10	9	150	.322	12/28	16/28*
	11	10	250	.387	11/28	14/28
CV2	10	9	150	.297	13/28	14/28
	11	10	250	.328	11/28	12/28
CA1	10	9	150	.554*	10/28	8/28
	11	10	250	.454	19/28*	17/28*
CA2	10	9	150	.459	14/28	11/28
	11	10	250	.549*	16/28	18/28*
CB1	10	9	150	.531*	13/28	15/28*
	11	10	250	.349	13/28	10/28
	12	2	50	.561	5/10	5/10
	13	2	150	.472	3/10	3/10
	14	3	50	.441	8/15*	9/15*
	15	3	150	.418	8/15*	8/15*
	16	7	150	.392	6/15	7/15
	17	8	150	.505*	7/15	6/15
CB2	10	9	150	.446	8/28	7/28
	11	10	250	.423	14/28	11/28
	12	2	50	.602*	6/10*	6/10*
	13	2	150	.625*	8/10*	8/10*
	14	3	50	.451*	11/15*	9/15*
	15	3	150	.467*	6/15	8/15*
	16	7	150	.358	7/15	6/15
	17	8	150	.400	6/15	5/15

Table 4.11: Inversion/Evolution Experiments.

Summary

Much as we would like to claim confirmation of our hypothesis that dependent genes move together under the influence of inversion, we do not feel confident in doing so on the basis of the evidence garnered in this chapter. Of all the experiments performed involving combinations of the inversion operators and the mating rules, it appears that the combination of mass/best/0.3 is by far the best in approaching the behavior we sought. It produced possibly significant movement in three out of the four environments used in the migration equilibrium experiments and four out of six environments used in the early evolution experiments. But the failure of inversion in general to be stronger where it did move correctly, its failure to be universally successful, and the outstanding failure of the pair data to be useful, all contributed enough negative output to discourage us from trying to overcome the difficulties in producing meaningful statistics from these highly non-independent samples. The MB3 data may show a trend or even be significant, but if so the significance is of low order and the results are not likely to be of great interest. Our efforts are best devoted elsewhere.

However, the results of the early evolution experiments must still be accounted successful. We can state with some confidence that position is an important factor in the rate at which populations advance from starting conditions far from the optimum (which is certainly likely to be the type of starting condition encountered in artificial work). More importantly, position can affect the system's likelihood of achieving the maximum value in a space.

That we cannot demonstrate the ability of inversion to take advantage of these conditions is regrettable. Two possible explanations for this failure come to mind, two explanations which suggest conditions under which inversion may work better. The first is that we are working with chromosomes which are too short. Consider a non-linear group of order six. Given a single crossover operator and a random positioning of genes on a chromosome of length twenty-five, the average distance between the left- and right-most genes of the group is about nineteen, so that crossover will occur within the group with probability .8 or so. If inversion manages to reduce the spread by a third to a distance of 12 or less (which has an *a priori* probability of .04), the probability of crossover splitting the group is still one-half. It may be that our experiments did not work because this reduction does not provide sufficient selective advantage to overcome the stochastic effects of the adaptive system. If so, problems with much longer chromosomes might find inversion more useful. This suggests an experiment in which many superfluous genes are added to the chromosome to provide enough length so that groups have a very wide range of probabilities of being split in different permutations.

The second possible reason for inversion's non-effectiveness is the shortness of the length of time in which inversion has to act while position is important in early evolution. In our experiments this was anywhere from 25 to at most 150 generations. Considering the mass inversion operator at a level of 0.3, only 45 different inversions occur, on the average, in 150 generations. If even a third are advantageous and if three-quarters of those are able to overcome the stochastic effects of the system, there are only 11 advantageous permu-

tations in that time. From our experience this is not enough to do the job. Inversion may be effective only in systems in which significant adaptation continues for a very long time. Such systems may be very much more complicated in terms of number of genes and alleles, they may be diploid with dominance adding to the adaptive problem, or the environment may be non-stationary. All these possibilities suggest a whole new series of experiments. At any rate, the subject is not closed; the early evolution experiments are too positive for that.

CHAPTER FIVE
FREQUENCY EFFECTS.

Existence of a Frequency Effect

The complete analysis of frequency effects for a simple two gene model (given in Chapter Two) is difficult to extend to a complex environment and a complex adaptive system involving stochastic genetic operators. Most work to this point merely assumes that effects demonstrated for two genes do indeed generalize to the more complicated case. ("It is intuitively obvious that") However, if we hope to detect evidence of non-linearities using this idea, it would be well to establish the fact--which we shall call the IFC (Increased Frequency of Combination) effect.

Chi-Squared Analysis

The chi-squared goodness-of-fit statistic is a simple test to determine how well a set of observations of a random variable agrees with a probability distribution. The distribution defines classes (or ranges) of the random variable called cells and the observations are assigned to those cells. When the classification is the cross product of two or more independent criteria, the cells are arranged in a table and the test is then called the chi-squared contingency test. The degrees of freedom in any chi-squared test is equal to the number of cells, minus the number of parameters estimated from the data, minus one. Thus, in a 2 x 2 table in which the probability of occurrence of each class is estimated from the data there are

$2 \times 2 - 2 - 1 = 1$ degrees of freedom. Similarly in a $2 \times 2 \times 2 \times 2 \times 2$ table (which we will call a five-way table) there are 26 degrees of freedom.

The nature of the contingency table test is to detect any departure from linearity--the hypothesis is that the frequency of the cross-product classification can be predicted by the estimated frequency of the individual classes. The statistic

$$\sum_{\text{over all cells } i} \frac{(\text{Expected}_i - \text{Observed}_i)^2}{\text{Expected}_i}$$

is then distributed according to the chi-squared distribution with the appropriate degrees of freedom. If the statistic exceeds the given confidence level we may reject the hypotheses of linearity: there is some interaction between the classes.

In addition to being a statistical test the observed chi-squared value may be used as a measure of association among the variables. That is, the magnitude of the statistic calculated above may serve as a ranking on the degree of association.

A key point in the chi-squared test, as in most statistical work, is that the observations are required to be independent samples of the random variable. We will immediately run into difficulty on this account. Another important point which will be a source of difficulty is that, for the test to have validity, authorities recommend that the expected number of items per cell be at least five for 80% of the cells and never less than one (14).

Multiple-Gene Tests

In applying contingency table analysis to our situation we find that a gene is a component class and that alleles are the possible values for the class. In determining whether there is interaction among n genes, we use an n -way contingency table, i.e., a table with 2^n cells and $2^n - n - 1$ degrees of freedom. We shall call the resulting statistic a Group Chi-squared Value (GCV) or an association index.

Now, if each of the alleles were to have a frequency of 0.5, in order to satisfy the requirement that each cell has an expected value of 5, we would need (on the average) 5×2^n samples. In the case of $n = 5$ this is 160. If some of the allelic frequencies are lower we need a correspondingly higher number of samples. In any event, in order to calculate the chi-squared statistic for more than 3 or 4 genes at a time we require more samples than are available from our basic 100-individual population. To handle this requirement and to satisfy the requirements of randomness as much as possible we will adopt the following experimental protocol:

1. Under a given set of parameters, 10 populations will be run to a terminal state, producing 1000 samples.
2. To minimize the effects of the starting condition a new population (i.e., a new set of alleles for each individual) will be generated at the beginning of each run.
3. In some experiments, to minimize the effects of the original gene permutation, a new initial permutation of genes will be generated at the beginning of each run.

Table 5.1(a) displays the parameters used in the H,I,J,K, and L

EXP	ENV	# Generations	Crossover*	Gene Permutations across runs**
H1	2	8	One	All Same
H2	2	8	One	Random
H3	2	8	.100	Random
H4	2	8	.250	Random
H5	2	8	.500	Random
H6	5	8	.100	Random
H7	5	25	.100	Random
H8	5	50	.100	Random
I1	1	4	One	All Same
I2	1	4	One	Random
I3	1	4	.100	Random
I4	1	4	.250	Random
I5	1	4	.500	Random
J1	3	16	One	All Same
J2	3	16	One	Random
J3	3	16	.100	Random
J4	3	16	.250	Random
J5	3	16	.500	Random
J6	6	16	.100	Random
J7	6	25	.100	Random
K1	7	25	One	Random
K2	7	25	.100	Random
K3	7	25	.250	Random
K4	7	25	.500	Random
K5	7	50	.167	Random
K6	7	16	.167	Random
K7	7	100	One	Random
K8	7	150	One	Random
L1	8	8	.167	Random
L2	8	16	.167	Random
L3	8	25	.167	Random
L4	8	16	One	All Same
L5	8	50	One	Random
L6	8	100	One	Random

Mutation = .005

Inversion = None

Migration = None

*One => One-crossover. A number => probabilistic crossover with given probability.

**All same => Permutation (1,2,...,24,25) used in all 10 runs.

Random => A different random permutation used in each of 10 runs (See Appendix B).

Table 5.1(a): Multi-gene χ^2 Tests: Experimental Parameters.

Genes Tested	Degrees of Freedom	Experimental χ^2 Observed**							
		H1	H2	H3	H4	H5	H6	H7	H8
*1,2,3,4,5	26	7225	5899	3336	3681	2209	86	2760	15786
21,22,23,24,25	26	91	84	49	32	32	62	73	86
10,11,12,13,14	26	104	158	62	36	32	27	68	151
6,10,15,20,25	26	41	93	44	62	55	42	51	61
1,7,13,19,25	26	86	44	122	86	32	36	81	94
		I1	I2	I3	I4	I5			
1,2,3,4,5	26	98 ⁺	55 ⁺	23 ⁺	39 ⁺	21 ⁺			
21,22,23,24,25	26	60	21	34	42	20			
10,11,12,13,14	26	105	56	39	26	33			
6,10,15,20,25	26	48	53	53	38	42			
1,7,13,19,25	26	33	51	60	30	28			
		J1	J2	J3	J4	J5	J6	J7	
*1,2,3,4,5,6	57	1026 ⁺	833 ⁺	324 ⁺	395	1013	210	1338	
20,21,22,23,24,25	57	190 ⁺	117	65 ⁺	77 ⁺	82	108	61	
10,11,12,13,14,15	57	214 ⁺	136 ⁺	97	87 ⁺	62	94	97	
1,6,10,15,20,25	57	116	179 ⁺	110	129	125	107	228	

Table 5.1(h): Multi-gene χ^2 Tests: Results of First Runs. (Cont'd)

Genes Tested	Degrees of Freedom	Experimental χ^2 Observed**							
		K1	K2	K3	K4	K5	K6	K7	K8
*1,2,3,4,5,6	57	1313	380	320	130	7581	79	212759 ⁺	63103 ⁺
*7,8,9,10,11	26	69	70	112	177	58	51	1212	1032
*13,14,15,16,17,18	57	384	104	160	82	504	89	2455	3166
*19,20,21	4	1	62	29	2	90	12	78	17
*22,23,24,25	11	65	44	112	83	62	63	628	677
1,7,13,19,25	26	84	79	86	70	231	58	283	404
2,8,14,20,24	26	107	50	136	45	128 ⁺	62	157	433
1,2,7,8,13,14	57	296	100	252	140	354 ⁺	135	1867	2196
		L1	L2	L3	L4	L5	L6		
*1,2,3,4,5,6	57	158	176	621	775	2426 ⁺	23036 ⁺		
*7,8,9,10,11,12	57	98	89	491	811	4808 ⁺	15894 ⁺		
*13,14,15,16,17,18	57	220	379 ⁺	616 ⁺	1137	21396 ⁺	16401 ⁺		
19,20,21,22,23,24	57	57	120 ⁺	160 ⁺	214	86 ⁺	174 ⁺		
1,7,13,19,22,25	57	86	75	141 ⁺	152	369 ⁺	231 ⁺		
2,9,18,20,21,23	57	81	125	188 ⁺	110	210 ⁺	480 ⁺		
3,12,15,19,21,24	57	95	101	154	114	188 ⁺	151		

*Dependent group of genes

**1000 Sample points (10 runs) each experiment

+Failed χ^2 cell size requirements

Table 5.1(b): Multi-gene χ^2 Tests: Results of First Runs.

Genes Tested	Degrees of Freedom	Experimental χ^2 Observed**					
		H1'	H2'	H3'	H4'	H5'	H6'
*1,2,3,4,5	26	5804	2908	3120	3268	4771	87
21,22,23,24,25	26	80	68	53	27	41	61
10,11,12,13,14	26	84	62	58	41	27	27
6,10,15,20,25	26	41	69	68	53	43	39
1,7,13,19,25	26	62	47	94	64	45	50
		I1'	I2'	I3'	I4'	I5'	
1,2,3,4,5,	26	91 ⁺	47 ⁺	22 ⁺	50 ⁺	37 ⁺	
21,23,23,24,25	26	78	28	35	43	42	
10,11,12,13,14	26	59	34	27	21	28	
6,10,15,20,25	26	22	45	53	37	24	
1,7,13,19,25	26	44	59	72	26	30	
		J1'	J2'	J3'	J4'	J5'	J6'
*1,2,3,4,5,6	57	1708	158 ⁺	328	384	140	263
20,21,22,23,24,25	57	176 ⁺	167 ⁺	98 ⁺	74	75 ⁺	138
10,11,12,13,14,15	57	234 ⁺	101 ⁺	98 ⁺	107 ⁺	60 ⁺	99
1,6,10,15,20,25	57	216 ⁺	140 ⁺	106	147	67	99
		K1'	K2'	K3'	K4'	K5'	K6'
*1,2,3,4,5,6	57	336	486	240	385	8214	106
*7,8,9,10,11	26	112	84	114	48	114	53
*13,14,15,16,17,18	57	253	120	214	164	424 ⁺	91
*19,20,21	4	11	56	54	26	92	16
*22,23,24,25	11	33	78	101	13	84	41
1,7,13,19,25	26	94	83	130	74	188	55
2,8,14,20,24	26	52	58	128	44	122	55
1,2,7,8,13,14	57	261	108	214	146	300 ⁺	133
		L1'	L2'	L3'	L4'		
*1,2,3,4,5,6	57	161	214	750 ⁺	949		
*7,8,9,10,11,12	57	112	92 ⁺	463	678		
*13,14,15,16,17,18	57	184	266	420	1414		
19,20,21,22,23,24	57	69	100 ⁺	153 ⁺	267 ⁺		
1,7,13,19,22,2	57	90	84	159 ⁺	190		
2,9,18,20,21,23	57	85	115	239 ⁺	234		
3,12,15,19,21,24	57	96	121 ⁺	130 ⁺	147		

Table 5.1(c): Multi-gene χ^2 Tests: Results of Second Runs.

Degrees of Freedom	$\chi^2_{.50}$	$\chi^2_{0.95}$	$\chi^2_{0.99}$	$\chi^2_{0.9995}$
1	0.46	3.84	6.64	12.12
4	3.36	9.49	13.28	20.00
11	10.34	19.68	24.73	33.14
26	25.34	38.89	45.64	56.41
57	56.34	75.61	84.71	98.75

Table 5.2: Selected Points of the χ^2 Distribution.

CASE 393
01:17, 06/23/72

ANALYSIS AT END OF 16 GENERATIONS
SAME PERMUTATION EACH RUN

COPIES= 10

GENES: 1 2 3 4 5 6
FREQS: .42 .44 .51 .42 .56 .48

COMB	EXP	OBS	COMB	EXP	OBS
000000	19.20	5	100000	13.96	15
000001	19.15	5	100001	13.20	3
000010	27.06	33	100010	19.68	2
000011	25.59	43	100011	18.61	13
000100	14.42	21	100100	10.49	19
000101	13.64	7	100101	9.92	12
000110	20.33	9	100110	14.73	9
000111	19.23	6	100111	13.98	10
001000	20.22	9	101000	14.70	17
001001	19.12	17	101001	13.90	11
001010	28.51	68	101010	20.73	17
001011	26.95	91	101011	19.60	40
001100	15.19	16	101100	11.05	5
001101	14.37	8	101101	10.45	2
001110	21.42	6	101110	15.57	2
001111	20.25	31	101111	14.73	7
010000	15.15	11	110000	11.01	15
010001	14.32	1	110001	10.41	8
010010	21.35	6	110010	15.52	22
010011	20.19	15	110011	14.68	13
010100	11.38	53	110100	8.27	59
010101	10.76	12	110101	7.82	17
010110	16.04	3	110110	11.66	11
010111	15.17	11	110111	11.03	18
011000	15.95	1	111000	11.60	12
011001	15.09	5	111001	10.97	0
011010	22.49	13	111010	16.35	4
011011	21.26	36	111011	15.46	20
011100	11.99	18	111100	8.72	26
011101	11.33	2	111101	8.24	3
011110	16.90	0	111110	12.29	7
011111	15.98	17	111111	11.62	2

CHISQUARE = 1026.23
DEGREES OF FREEDOM = 57

The underlined points are the peaks of the environment.

Figure 5.1(a): Sample χ^2 Multi-gene Test-Experiment J1.

CASE 404
01:43, 06/23/72

ANALYSIS AT END OF 16 GENERATIONS
NEW PERMUTATION EACH RUN

COPIES= 10

GENES: 1 2 3 4 5 6
FREQS: .48 .50 .57 .39 .55 .55

COMB	EXP	OBS	COMB	EXP	OBS
000000	12.27	5	100000	11.79	8
000001	15.55	11	100001	14.94	19
000010	15.62	10	100010	15.00	10
000011	19.79	25	100011	19.02	21
000100	8.15	9	100100	7.83	12
000101	10.32	4	100101	9.92	5
000110	10.37	5	100110	9.96	10
000111	13.14	13	100111	12.63	6
001000	16.87	11	101000	16.21	14
001001	21.39	21	101001	20.55	14
001010	21.48	16	101010	20.63	23
001011	27.22	76	101011	26.15	40
001100	11.20	12	101100	10.76	10
001101	14.20	7	101101	13.64	11
001110	14.26	7	101110	13.70	10
001111	18.07	28	101111	17.36	17
010000	12.77	9	110000	12.27	27
010001	16.19	8	110001	15.55	9
010010	16.25	14	110010	15.62	15
010011	20.60	13	110011	19.79	10
010100	8.48	26	110100	8.15	41
010101	10.75	9	110101	10.32	19
010110	10.79	9	110110	10.37	20
010111	13.68	11	110111	13.14	8
011000	17.56	13	111000	16.87	21
011001	22.26	22	111001	21.39	16
011010	22.35	19	111010	21.48	17
011011	28.33	43	111011	27.22	21
011100	11.66	12	111100	11.20	11
011101	14.78	16	111101	14.20	8
011110	14.84	6	111110	14.26	9
011111	18.81	20	111111	18.07	8

CHISQUARE = 394.87
DEGREES OF FREEDOM = 57

The underlined points are the peaks of the environment.

Figure 5.1(b): Sample χ^2 Multi-gene Test-Experiment J4.

CASE 418, 06:16, 07/10/72

ANALYSIS AT END OF 50 GENERATIONS, NEW PERMUTATION EACH RUN,
10 Runs

GENES:	7	8	9	10	11	12
FREQS:	.14	.13	.80	.18	.70	.76

COMB	EXP	OBS	COMB	EXP	OBS
000000	7.97	5	100000	1.36	1
000001	26.40	13	100001	4.51	3
000010	19.43	11	100010	3.32	1
000011	64.31	49	100011	10.99	4
000100	1.85	4	100100	.32	37
000101	6.11	6	100101	1.04	8
000110	4.50	4	100110	.77	12
000111	14.89	5	100111	2.55	3
001000	32.71	19	101000	5.59	10
001001	108.28	105	101001	18.51	10
001010	79.69	71	101010	13.62	6
001011	263.81	377	101011	45.10	15
001100	7.57	5	101100	1.29	4
001101	25.07	13	101101	4.29	3
001110	18.45	11	101110	3.15	8
001111	61.08	45	101111	10.44	1
010000	1.20	3	110000	.21	2
010001	3.98	9	110001	.68	1
010010	2.93	3	110010	.50	0
010011	9.70	5	110011	1.66	1
010100	.28	0	110100	.05	2
010101	.92	0	110101	.16	1
010110	.68	0	110110	.12	1
010111	2.24	2	110111	.38	0
011000	4.93	2	111000	.84	0
011001	16.32	19	111001	2.79	2
011010	12.01	3	111010	2.05	1
011011	39.77	58	111011	6.80	3
011100	1.14	0	111100	.20	1
011101	3.78	3	111101	.65	0
011110	2.78	1	111110	.48	4
011111	9.21	3	111111	1.57	1

CHISQUARE = 4807.74

DEGREES OF FREEDOM = 57

The underlined points are the peaks of the environment. This set of data does not satisfy the χ^2 test requirement.

Figure 5.2(a): Sample χ^2 Multi-gene Test-Experiment L5.

CASE 418, 06:19, 07/10/72

ANALYSIS AT END OF 50 GENERATIONS, NEW PERMUTATION EACH RUN,
10 Runs

GENES:	3	12	15	19	21	24
FRECS:	.73	.76	.67	.81	.81	.70

COMB	EXP	OBS	COMB	EXP	OBS
000000	.20	0	100000	.56	1
000001	.48	0	100001	1.35	2
000010	.89	2	100010	2.48	7
000011	2.13	1	100011	5.94	17
000100	.89	0	100100	2.48	8
000101	2.13	1	100101	5.94	13
000110	3.92	1	100110	10.94	10
000111	9.38	5	100111	26.15	38
001000	.42	0	101000	1.16	1
001001	.99	0	101001	2.77	0
001010	1.83	0	101010	5.11	3
001011	4.38	0	101011	12.22	14
001100	1.83	1	101100	5.11	9
001101	4.38	3	101101	12.22	5
001110	8.08	7	101110	22.52	18
001111	19.30	16	101111	53.81	49
010000	.67	3	110000	1.87	0
010001	1.60	6	110001	4.46	1
010010	2.95	1	110010	8.22	9
010011	7.05	10	110011	19.65	9
010100	2.95	4	110100	8.22	8
010101	7.05	14	110101	19.65	8
010110	12.99	16	110110	36.22	35
010111	31.05	48	110111	86.55	49
011000	1.38	1	111000	3.84	5
011001	3.29	1	111001	9.18	14
011010	6.07	1	111010	16.92	16
011011	14.50	13	111011	40.44	47
011100	6.07	5	111100	16.92	9
011101	14.50	11	111101	40.44	51
011110	26.74	18	111110	74.54	96
011111	63.90	75	111111	178.14	184

CHISQUARE = 187.94
DEGREES OF FREEDOM = 57

This group of genes is linear with respect to payoff. The data do not satisfy the χ^2 test requirement.

Figure 5.2(b): Sample χ^2 Multi-gene Test-Experiment L5.

series of experiments analyzed below. In all experiments the mutation rate was .005, there was no migration, and no mating rule was needed since there was no inversion. Single crossover is indicated by "One" and probabilistic crossover is indicated by the probability used. An initial gene permutation of (1,2,3,...,24,25) for each run is indicated by "All same" and "Random" indicates that a different, random initial permutation was used for each run. The 10 random permutations used may be found in the Appendix. In each series there were several groups of genes tested for their association indices after a given number of generations. (Figures 5.1 and 5.2 are sample outputs from the program which calculates the chi-squared value.) Most experiments were run twice (with different random number starters)--the GCV results are given in Tables 5.1(b) and 5.1(c). The analysis below refers specifically to the first run (5.1(b)) but the second run results are qualitatively the same. Table 5.2 contains selected values of the chi-squared distribution for reference.

The first set of experiments involved ENV 2 (Figure 3.2). H1 used one-crossover and the initial permutation of genes in numeric order (1,2,...,24,25). Analyses were made of five combinations involving five genes each--the one combination of dependent genes and four control combinations of independent genes. The degrees of freedom for a five way table are 26 and $\chi^2_{.99}(26) = 45.64$. Clearly the observed chi-squared value of 7225 for the combination (1,2,3,4,5) is significant, as expected. However, the gene combinations (21,22,23,24,25), (10,11,12,13,14), (6,10,15,20,25), and (1,7,13,19,25), in spite of having much lower chi-squared values, are also significant at the 99% level although the second last was not significant at the 99.95% level.

The high degree of significance even among non-interacting genes points out our violation of the requirement of independence of sampling. Each member of generation n is formed by a (limited) mixing of the genes from two parents of generation $n-1$. Since selection of parents is biased (by the reproductive scheme) towards those individuals with high payoff, many individuals in the next generation automatically bear a resemblance to the parents with highest payoff. This effect is desired and expected as the means of exploiting non-linearities. What is surprising is its magnitude. Genes other than 1,2,3,4, and 5 are non-adaptive (neutral) and may be expected to assort randomly. However, other effects of the experimental parameters (one crossover and every individual having the same gene permutation) are such that large portions of the chromosomes vary together. We note that genes 10-14 and 21-25, which are adjacent on the chromosome (and thus are split infrequently by the one-crossover operator), have a larger chi-squared value (association index) than do the other two control combinations, parts of which are separated practically every crossover.

Two steps were taken to reduce the association of non-interacting genes while at the same time (hopefully) maintaining that of the truly interacting genes. In experiment H2, each of the ten runs from the initial random population was made with a different permutation of genes. (Ten random permutations were used. See Appendix.) The intention is to reduce the adjacency effect. The result was to lower somewhat the association of genes 1-5; but the association of the other gene combinations was not changed greatly: three of the four remained significant at the 99.95% level.

The second step, in experiments H3, H4, and H5 was to use the

probabilistic crossover operator at levels 0.100, 0.250 and 0.500, again to reduce the adjacency effect by reducing the length of the portions of the chromosome which were taken from one parent at any time. As can be seen in Table 5.1(b), the effect of the probabilistic crossover can be seen in most of the groups. The interacting group's chi-squared value is lowered to about 30% of its previous (H2) value at $P_{\text{cross}} = 0.5$ in experiment H5. Crossover values of 0.1 and 0.25 seemed to have some effect on the non-interacting combinations but a value of 0.5 finally reduced the GCV for three of them to below the 95% point and the fourth was below 99.95%.

As a further experiment in this series, H6 used ENV 5, which is the same as ENV 2, but with reduced selection (the payoff range is 6-8 instead of 1-3). H6 also used probabilistic crossover, $P_{\text{cross}} = 0.1$. The reduction in the GCV for the interacting genes is dramatic. The value is still well above the values for non-interacting genes, but the association is still a factor of 25-90 below previous values, which may be cause for difficulty in more complex environments. Inspecting the data from H6 more carefully, we observe that because of the decreased selection there has not been much evolution: the average tendency toward fixation (difference from 50%) is 3% for the 5 dependent genes. Experiment H3, which had comparable parameters but which used the higher selection rate, averaged over 5% fixation tendency. Comparing the runs directly (adjusting for the different selection factors), populations in experiment H6 had an average payoff of 1.62 at the end of 8 generations while those in experiment H3 averaged 2.25. H6 did not approach H3's payoff average until it was allowed to continue to about 30 generations.

Accordingly, experiments H7 and H8 were run at lengths of 25 and 50

generations, otherwise keeping the same parameters as H6. Table 5.1(b) again shows positive results (increased GCVs for the dependent group). Because selection alters the rate of evolution, we must take care in choosing the times at which to make our analysis. Gene frequencies may guide us in this regard (tendency toward fixation may mean that significant evolution has occurred), although population averages may be better.

In summary, the H series shows that chi-squared values are always higher for the non-linear group than for others, and usually much higher.

Before going on to more complex environments, we shall go to one simpler yet, ENV 1, which has only 5 linearly acting genes (1-5). We use this as a basis of comparison to see if the observed chi-squared values for the H-series were merely the result of selection on the only adaptive genes, or whether the non-linear interaction is what caused the effect. Experiments I1-I5 follow exactly the same course as H1-H5 and the same gene combinations were analyzed.

(Note that these experiments continued for only four generations rather than the eight generations of the H-series. The linearity of ENV 1 allowed such rapid adaptation that gene frequencies approached 1.0 much more quickly, making the chi-squared analysis less accurate due to the reduced size of the expected values in each cell. Doing the analysis earlier catches the frequencies before they get too low. Although we have already noted that some associations do not become apparent until a longer period of evolution has taken place, we can feel reasonably confident that we are not losing information in this case. When the gene frequencies tend to fixation so fast, combinations

involving the other alleles will not have much effect, even later. We automatically suspect linearity when we observe this behavior.)

The results are positive: *all* the associations observed are in the same order of magnitude and the values for the adaptive genes (1-5) are often lower than the values for the non-adaptive combinations. In addition, the lowering of the association index across the experiments designed to do just that seems to follow the same course as in the H-series. In general the associations are below the values in the H-series even though the selection is greater, perhaps indicating that some of the non-adaptive combinations in H were affected by something we might call a "tag-along" effect: selection of better chromosomes emphasizes the non-adaptive gene combinations on the chromosome as well as the adaptive gene combinations. While much of this should be smoothed by random effects over time it is probably present at every instant. Another possibility is that the smaller number of generations did not allow as much build-up of associations. Most of the association values ended up less than statistically significant. In any case, a linear payoff does not present the same behavior as a non-linear payoff.

The J-series of experiments used ENV 3 (ENV 6 in the reduced selection experiment J6), which consists of 6 dependent genes and 19 genes producing a linear payoff. As such it differs from ENV 2 by having a larger dependent group and by having the remaining genes all adaptive; it also has reduced selection on the dependent group because of the larger number of genes contributing to payoff. J1-J7 followed exactly the same course as H1-H7, producing somewhat similar results. J1 produced a huge association index for the dependent genes which were adjacent on the chromosome, and much smaller associations for adjacent, independent

genes. Use of random initial permutations (J2) and lower selection (J6) reduced the associations, as did use of probabilistic crossover; longer runs increased the association (J7). The J-series did not have the same nice progression as H3-H5 in the reduction of the association with larger recombination values. This deserves some comment. We recall that the intention in using probabilistic crossover was to decrease the direct association between adjacent genes by splitting them up more often than in the one-crossover case. However, it still remains the case that when a split (crossover) occurs, the next gene is taken from the other parent. When this happens twice, the source for genes for the new chromosome is again the new parent. In the extreme case of crossover probability 1.0, every other gene is taken from the same parent. Given an initial gene permutation of $(1,2,\dots,25)$, the result is the same as if the permutation were $(1,3,5,7,\dots,23,25,2,4,\dots,22,24)$, and there were again exactly one crossover, but always between positions 13 and 14 (genes 25 and 2). Thus, higher values for the probability of crossover actually reduce the disassociation desired. In addition, to allow the inversion operator to produce permutations which are advantageous, crossover must be fairly low.

No matter what the means of mixing genes, there will always be a residue of association caused by using only two parents as sources. Since we are not interested in finding optimum setting for parameters we will not attempt to determine which value of crossover might be "best" for this particular purpose; use of probabilistic rather than one-crossover might well be indicated for longer chromosomes. At any rate, the optimum setting might depend on the number of genes in a

dependent group, on the selection coefficients, or any number of other factors. By inspection of the data for the H,J, and K experiments, it appears that levels around 0.1 seem to be effective, and are probably low enough to allow inversion to work, so that we would recommend levels on this order in future work.

In the next set of experiments, K1-K4 follow the pattern of H2-H5 and J2-J5, producing somewhat similar results again, using ENV 7, our most complex environment. The five dependent groups mostly show large association indices, but the two groups of five mutually independent genes, (1,7,19,25) and (2,8,14,20,24) are not consistently larger or smaller than the comparable dependent group, (7,8,9,10,11). These groups contain one gene from each of the dependent groups. While we expect the groups to vary independently since payoff is additive among them, we should not be too surprised if one group dominates the others (in terms of selective pressure), leading to a strong tag-along effect at specific times of evolution. The group (1,2,7,8,13,14) contains 2 genes each from 3 dependent groups. It shows higher indices than the independent groups and often exceeds the dependent groups in strength of association. These somewhat clouded results give some idea of the difficulty involved in very complex environments.

Actually, even after 25 generations, the degree of improvement from the initial random population was not great. (We do not reproduce the data here.) Because of the large amount of interaction, the population average did not advance very rapidly, and the best strings produced were much below the optimum. As a measure of the amount of adaptation, the tendency toward fixation of all the individual gene frequencies (i.e., difference from 50%) at the end of 25 generations, averaged

across the 10 runs for experiment K2, was only about 8%. To get some feel for the possible effects of greater adaptation, K5 continued for 50 generations. A higher degree of adaptation was seen (gene frequency fixation averaged 11%) and the associations were much larger (compared to K2 or K3 which had similar crossover probabilities). One factor making the associations larger was the additional non-independence of sampling provided by the longer evolution times, as evidenced by the increase even among the independent groups. K6 measured the associations at only 16 generations where gene frequency fixation averaged 6%. As expected the associations were mostly lower, with the two completely independent groups falling in the same range as the comparable dependent group. K7 and K8 continued for 100 and 150 generations. Here the dependent group clearly dominated the two control groups (in K7, 1212 versus 283 and 157). The groups of six dependent genes also dominated the control group of six and the group of four dependent genes dominated even the control groups of five which could be expected to be higher. It seems that increasing the lengths of runs (at least in this range) definitely alters the relative association indices.

Short runs may be better for detecting differences in smaller groups, although the evidence is inconclusive, observing the failure in the small group (19,20,21). In longer runs the small groups may be almost completely adapted and thus contribute less to the payoff. They thus have higher gene frequencies and fewer members searching false peaks so that the chi-squared calculation appears to yield smaller association indices.

The K-series used an environment in which every gene but one was included in a dependent group, so that it was difficult to get an idea of the relative magnitude of the associations in dependent and independent

groups. In the last series of experiments on this topic, L1, L2, and L3, used ENV 8 which consists of three groups of 6 dependent genes, each group identical to the dependent group of the J-series. The remaining 7 genes are linear, allowing plenty of independent gene groupings. Random permutations and probabilistic crossover were used. The three experiments show the results of the analysis at the end of 8, 16, and 25 generations. By the end of 8 generations there has not been enough time for all associations to build up, but by generation 16 they are more plainly there, and at the end of 25 generations they are unmistakable. The five control groups are well below the dependent groups, and associations in these five groups seem to increase with a larger number of generations, as indicated by the K-series. L4 again returned to one-crossover and numeric order for the genes: all dependent groups had their genes adjacent for the 10 runs. The ratio of association between the dependent and independent groups was very large, as expected.

Experiments L5 and L6, with single crossover and random permutations, continued for 50 and 100 generations, producing even larger ratios than L4. As noted in Table 5.1(b), every GCV calculated violated the strict rules for the statistical test. A large degree of adaptation took place even by generation 50, producing a large tendency to gene fixation, resulting in expected gene frequencies of combination below 1.0 for the cells in the contingency table. Such cells contribute inordinately to the GCV, ruling out its use as a pure statistic. However, we note that the GCV ratio is still large in exactly the manner we had anticipated, indicating that use of the GCV is still valuable in this situation. Examination of the particulars of such a table is

often valuable for determining the importance of such deviance from strict form. See Figures 5.2(a) and 5.2(b) for two such tables, one for a dependent group and one for an independent group.

Summary

The results of the experiments described in this section are extremely satisfying. First, they verify the generalization of the simple two gene model prediction of frequencies to a complex multi-gene model with genetic operators. Secondly, the K and L experiments indicate that when there is more than one group of dependent genes, the groups tend to vary independently, emphasizing their own best combinations simultaneously. This bodes well for the ability of this analysis to handle even more complex, real-world problems. Another pleasant result is that the Increased Frequency of Combination (IFC) effect manifests itself to a significant degree very rapidly. Twenty-five generations were enough to show it even in some of the complex cases tested. This means analysis need not take an unreasonable length of time--certainly no more than adaptation itself takes.

One somewhat disappointing result is that we are not able to use the chi-squared contingency test as a pure statistical method of detecting non-linearities. The experimental data obtained violate the requirements of independence in spite of all our efforts in manipulating parameters and initial conditions. This is a direct consequence (and intended operation of) the Reproductive Plan. Independent groups will always show strong associations with respect to statistical significance. On the other hand, using the chi-squared statistic as an index of

association appears to be a completely adequate discriminator.

One extremely important result is that the association ratios observed between dependent and independent groups were highest when the genes in the groups were closest together. Figures 5.1(a), 5.1(b), and 5.2(a) show that the reason for a high association index is that there are many individuals on or near *both* of the peaks of the environment. When a (linear) prediction of combinations from individual gene frequencies yields a high value for one combination, it must necessarily give a lower value for other combinations. When there are two peaks and individuals cluster on both, the chi-squared value grows large from the contributions of at least one of the peaks. In the cases shown here (which are completely typical), the observed count on both peaks considerably outdistanced the predicted count, and the disparity was larger for the case where the genes were adjacent. The only possible conclusion is that very good combinations are separated and destroyed much less often when the genes are closest. As a result the search concentrates around local maxima in the environment. This is important supporting evidence of the potential value of inversion in promoting favorable permutations.

Since efforts to create conditions satisfying the chi-squared independence requirement were a failure, and since such efforts reduced the association ratios of dependent to independent groups, it appears that the best discrimination (and probably best adaptation) can be made using the single crossover operator (or at least low probabilities of the probabilistic crossover operator for larger chromosomes) and permutations in which suspected genes are adjacent.

Given a particular hypothesis about which genes are dependent we can then suggest the following experimental procedure. Form several

control groups with the same number of genes as in the suspected group; choose these groups from known (or thought to be) independent genes. Use the reproductive plan with low mutation, single crossover, and multiple runs each with the same permutation of genes such that all genes from a single group are adjacent on the chromosome. Perform runs of various lengths. Comparing the chi-squared values from the "independent" groups with the value for the suspected groups, we can accept the hypothesis of dependence if there is a large (say, order of magnitude) difference.

Detecting Dependent Groups

From the results of the last section we are now certain that the association indices of dependent groups of genes are much larger than indices for comparable, independent groups of genes. However we are still faced with a large problem: how to form hypotheses about which groups of genes to test in environments about which we know little. Even in the relatively simple (25 gene) environments used in this research, if we are looking for groups of size 6, there are $\binom{25}{6} = 177,100$ possible groups. Obviously some screening method must be used. One such method might be the experimenter's knowledge or hunches about the environment. Other screening methods are discussed below.

But first a note of warning. The process of hypothesis formation (induction) on scanty data is an arcane art at best. Even 500 generations of 100 individuals sample at most 0.15% of the total payoff points in our environments of size $2^{25} = 33,554,432$. It is unlikely we shall be able to discover every interaction. But then, any information we can discover is more than is otherwise available.

Pair Analysis

Although testing every combination of 5, 6, or 7 genes requires an unreasonable amount of analysis, calculating contingency tables for every pair does not; there are only $\binom{25}{2} = 300$ pairs of genes on a 25-gene chromosome. This immediately suggests an interesting possibility. Consider a group of 5 interacting genes. There are $\binom{5}{2} = 10$ pairs of genes from this group. If the group has a relatively high chi-squared value, it might be that every one of the pairs does also. If indeed these pairs have unusually high chi-squared values when compared to control pairs, we have a valuable screening tool. The intended usage is as follows: from the 300 pairs of values it may be possible to select a group of n genes, all of whose $\binom{n}{2}$ Pair Chi-squared Values (PCVs) are comparatively large. Then, using the techniques suggested in the previous section of this chapter, we may test the hypotheses that these genes do interact as a group by means of an n -dimensional contingency table, obtaining the GCV, and making the final decision based on this value.

Analysis at the End of Runs

The most obvious method for detecting interacting pairs follows the experimental procedure of the last section exactly. Ten runs of each experiment were performed, under the experimental parameters of Table 5.1(a). A chi-squared contingency table analysis was performed on each of the 300 pairs of genes over the 1000 sample points.

The result of the analysis for experiment H1 is shown in Figure 5.3. Genes 1-5 are known to be interacting and the average of the 10 PCVs

in this group (in the triangle) is 481 while the average for the remaining 290 pairs is 7. Clearly this is positive confirmation of our hopes. There is no doubt about which genes should be tested for 5-way interaction. Such a test is probably not even required. Of course, H1 was run with genes 1-5 adjacent, a piece of prior knowledge known to increase the IFC effect. But analyses of experiments H2-H5 yielded very similar results; although the numbers were slightly smaller, there was still no difficulty in determining the correct set to try (Figure 5.4 gives the results of experiment H2.) These results match well with the GCVs obtained in Tables 5.1(b) and 5.1(c).

Figure 5.5, stating the results of experiment H6, has a different tale to tell. The average chi-squared value for the 10 pairs known to be interacting is 6.9 and the average value for all other pairs is 2.1 so that again our hypothesis is confirmed: high GCVs are reflected in high PCVs. But alas, mere inspection of the data does not yield the best information on which genes to try. It would be easy to choose a set of five genes whose pair associations averaged higher than 6.9; for example the group (8,10,14,17,23) has an average PCV of 7.6. Thus, the decreased GCV ratio shown in Table 5.16 definitely reflects itself in the PCVs. Again, more evolution is called for.

Figure 5.6 shows the pair analysis at generation 50. The results, under these conditions, are just as positive as for the previous experiments.

Figure 5.7(a) contains the pair analysis for experiment I3, ENV 1, a typical representative of the completely linear environment. As expected, no set of genes stands out. Figure 5.7(b) contains the analysis for 8 generations with similar results. We include Figure 5.8

analyzing J5, ENV 3 as a typical output of the six gene dependent group series. The effect is clear, and longer runs make it stand out even more.

Figures 5.9(a), 5.9(b), 5.10(a), 5.10(b) contain the PCV analysis for experiments K7, K8, L5, and L6. Pair analysis of ENV 7 (K-series) on shorter runs was not very successful: only the group (1,2,3,4,5,6) stood out much--probably because it had the widest selection range. Genes (7,8,9,10,11) showed up slightly by generation 50, but as can be seen in Figure 5.9, they are not completely consistent even at generations 100 and 150. Similarly, the three other groups were standouts at some instants but not at others. ENV 8 (L-series) showed a like inclination to emphasize one or another group at runs of various lengths.

Cumulative Analysis

We are thus faced with the problem of different groups having more or less influence at particular instants of time and thus being more or less detectable in a pair analysis matrix. To overcome this effect we must perform pair analyses at different instants in time and try to pick groups from each analysis for testing via GCV. An alternate method which proves to be quite good is based on the observation that when PCVs stand out, they are quite a bit larger than the linear, essentially random PCVs. Thus, if a PCV is abnormally high at some instant and only in the random range at another, the average of the two will still be quite high and may be large enough to stand out and deserve our attention. We establish the following experimental protocol: perform PCV analyses at a number of different generations and sum the

values obtained at each instant.

Figure 5.11 shows the results for ENV 7 (K-series) and Figure 5.12 shows results for ENV 8 (L-series). The experimental parameters used were the same as for experiments K8 and L6, except that the analyses were done at the instants of time stated in the figures. As expected, the results are unmistakable in both instances, with the exception of the small group (19,20,21) in ENV 7. Small dependent groups may be difficult to pick out especially if their selection factors are low as in the current case.

CASE 395, 23:10, 07/10/72

ANALYSIS AT END OF 4 GENERATIONS, NEW PERMUTATION EACH RUN, 10 RUNS

PERCENT OF '1' ALLELES
 73 77 75 77 78 56 49 52 54 49 48 47 39 53 43 49 47 57 49 43 54 52 51 52 50

CHI-SQUARED VALUES (TIMES 0.1) FOR PAIRS
 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25

1	0																									
2	0	0																								
3	0	0	0																							
4	0	0	0	0																						
5	0	0	0	0	0																					
6	0	1	0	0	0	1																				
7	0	0	0	0	0	0	0																			
8	0	0	0	0	0	0	0	0																		
9	0	0	0	1	0	0	1	0	0																	
10	0	0	0	0	0	1	0	0	0	0																
11	0	0	0	0	0	0	0	0	0	0	0															
12	0	0	0	0	0	0	0	0	0	0	0	0														
13	1	1	0	0	0	0	0	0	0	0	0	0	0													
14	1	0	0	0	0	0	0	0	0	0	0	0	0	0												
15	1	1	0	0	0	0	0	0	0	0	0	0	0	0	0											
16	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0										
17	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0									
18	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0								
19	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0							
20	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0						
21	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0					
22	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0				
23	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0			
24	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		
25	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

AVE.= 2.03

Figure 5.7(a): Pair Chi-squared Values for Experiment I3.

CASE 413, 01:10, 07/10/72

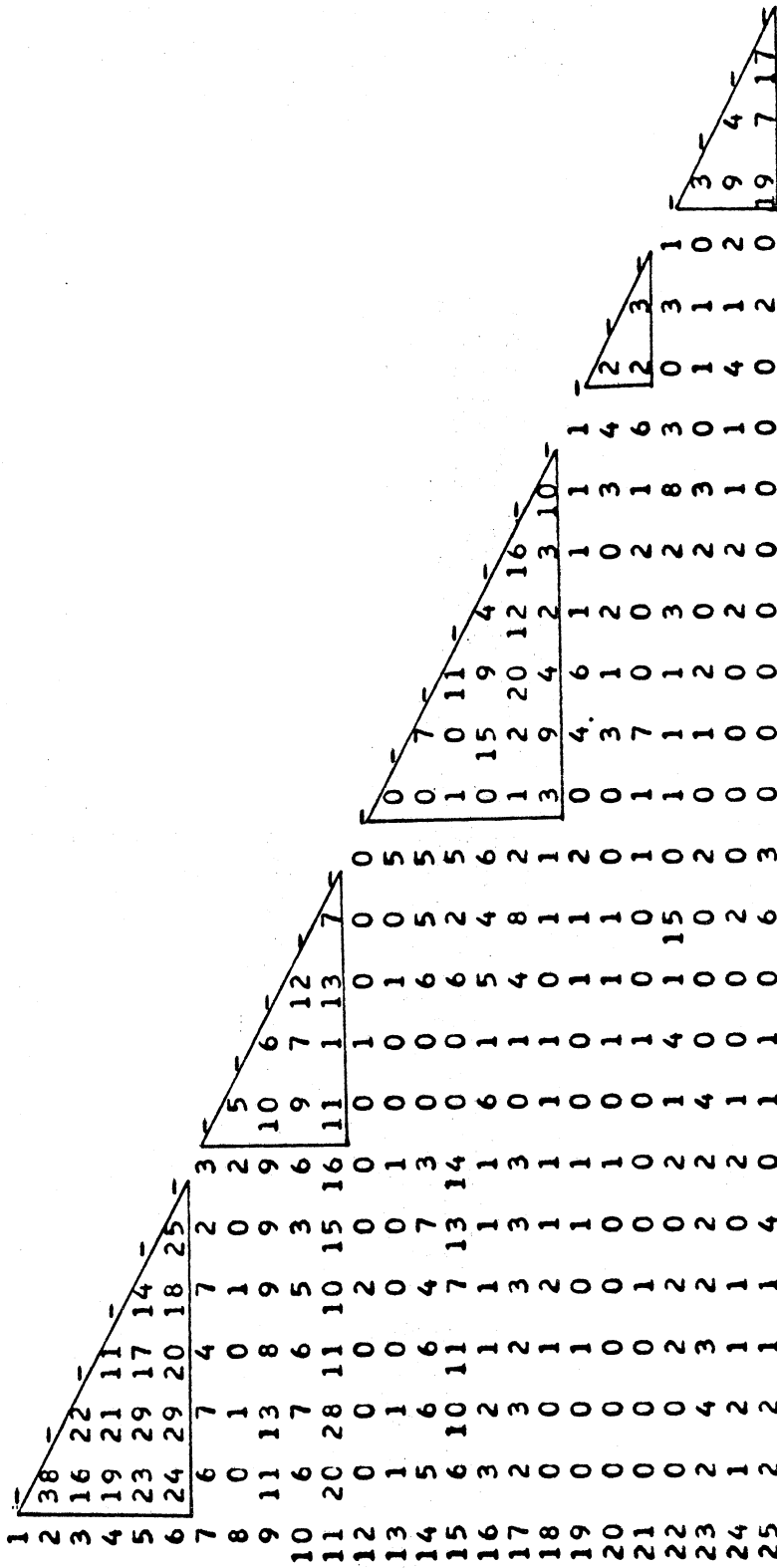
ANALYSIS AT END OF 100 GENERATIONS, NEW PERMUTATION EACH RUN, 10 RUNS

PERCENT OF '1' ALLELES

16 14 79 16 85 84 66 62 64 49 75 59 54 59 71 24 38 23 22 23 24 62 41 49 65

CHI-SQUARED VALUES (TIMES 0.1) FOR PAIRS

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25



AVE= 40.66

Figure 5.9(a): Pair Chi-squared Values for Experiment K7.

CASE 413, 01:48, 07/10/72

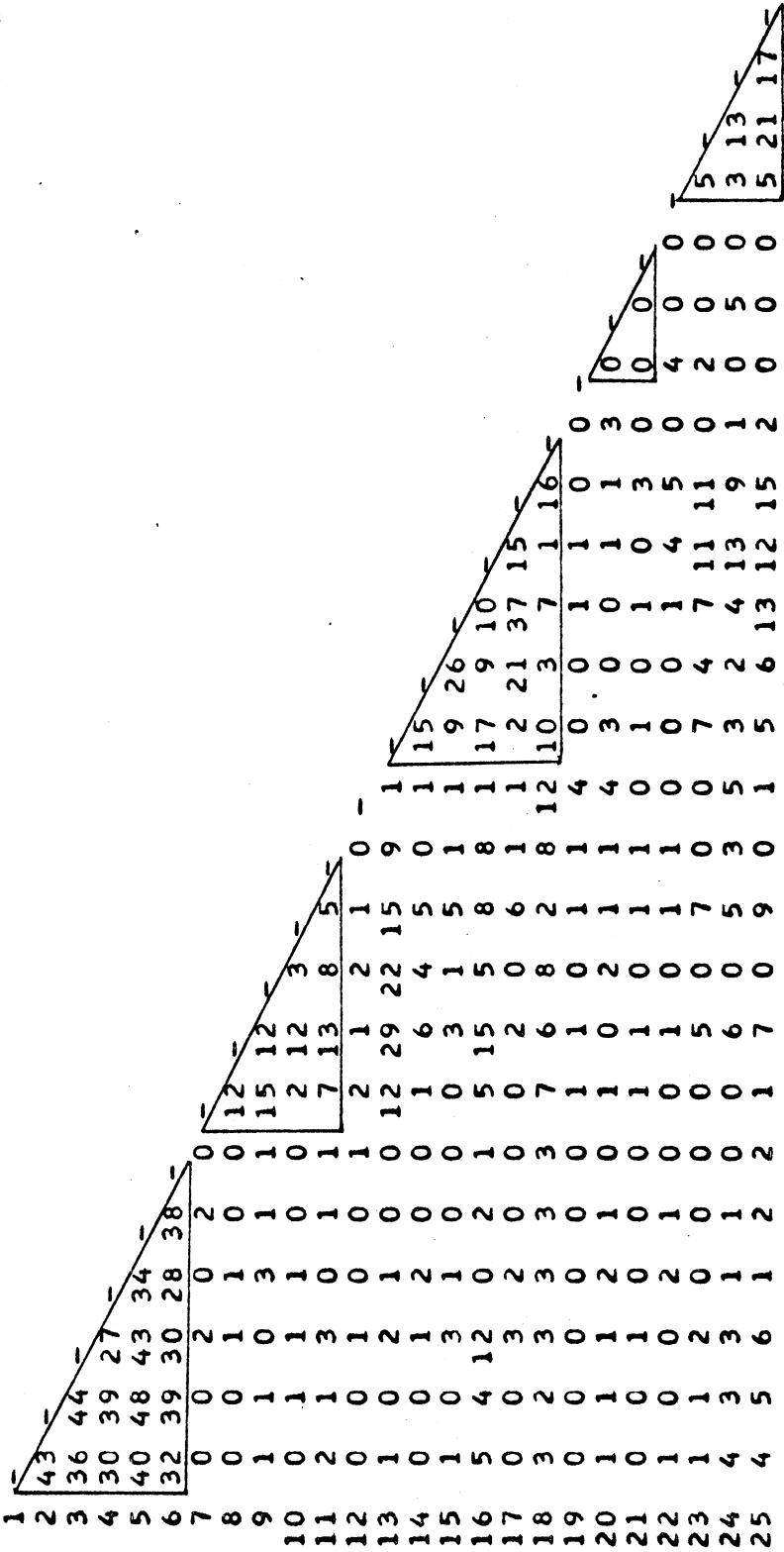
ANALYSIS AT END OF 150 GENERATIONS, NEW PERMUTATION EACH RUN, 10 RUNS

PERCENT OF '1' ALLELES

26 21 76 30 78 73 48 50 52 57 59 53 57 62 56 30 43 26 38 21 16 44 58 37 35

CHI-SQUARED VALUES (TIMES 0.1) FOR PAIRS

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25



AVE.= 49.85

Figure 5.9(b): Pair Chi-squared Values for Experiment K8.

CASE 418, 22:48, 07/11/72

ANALYSIS AT END OF 100 GENERATIONS, NEW PERMUTATION EACH RUN, 10 RUNS

CUMULATIVE CHISQUARED VALUES (TIMES 0.1) FOR PAIRS

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	
1	43																									
2	69	78																								
3	52	36	92																							
4	59	41	84	51																						
5	57	64	80	58	52																					
6	8	11	7	20	9																					
7	8	4	13	4	23	6	56																			
8	9	8	14	9	24	8	72	61																		
9	14	16	20	10	28	19	90	64	75																	
10	17	15	20	14	29	14	66	50	58	77																
11	13	16	16	12	26	16	94	73	79	102	83															
12	3	4	2	3	3	7	13	2	3	15	2	9														
13	1	5	6	5	2	6	12	3	6	14	4	12	38													
14	4	2	9	11	7	2	6	2	5	6	1	4	32	29												
15	2	10	9	3	3	2	10	4	4	9	3	6	34	44	17											
16	2	4	4	8	4	3	13	3	4	12	2	7	44	48	33	38										
17	3	4	3	3	3	2	10	4	6	16	3	7	29	46	17	32	38									
18	2	3	5	2	1	3	4	3	3	4	3	2	2	4	2	7	1	5								
19	1	4	1	2	3	1	9	4	6	6	2	6	2	3	9	2	3	6	2							
20	2	3	1	3	3	2	0	1	1	2	2	1	4	3	2	3	4	6	1	1						
21	4	4	2	3	3	3	5	3	3	7	3	5	4	1	3	3	1	3	1	3	0					
22	13	22	16	12	13	14	3	5	9	10	11	7	2	3	3	4	2	2	1	3	3	1				
23	2	1	2	2	1	2	1	2	3	1	1	2	1	1	1	1	2	0	2	2	1	1	5	1		
24	4	2	1	0	2	3	3	3	1	3	2	1	1	1	1	1	1	1	1	1	1	1	0	2	0	
25																										

AVE = 130.02

Values calculated at generations 25,50,75,100.

Figure 5.12: Cumulative PCVs for ENV8.

CHAPTER SIX

CONCLUSIONS

Methods of adaptive search must contain, at least implicitly, the ability to detect and act upon non-linearities in their environments (i.e., in the functions to be optimized). If such knowledge can be made explicit, this information may be of value in constructing models of the environment and may lead to faster and more successful adaptation.

We define a function to be linear (or independent) with respect to its arguments (or parameters) if it may be expressed as a sum of sub-functions of at most one argument. If the function cannot be expressed as such a sum, it is called non-linear. Those parameters which appear as the only arguments for sub-functions are called independent parameters. A set of parameters which appear as arguments in a non-linear sub-function are called dependent or non-linear parameters. For example, consider the total function f :

$$f(x,y,z) = g(x)+h(y,z)$$

where h is non-linear (cannot be expressed as a sum of functions containing only y and z). The set $\{y,z\}$ is a dependent group of parameters and x is an independent parameter. Our goal is to detect dependent groups of parameters.

The environments studied had twenty-five arguments, each of which could take on two values. For the case of only two parameter values non-linearity is insured if the payoff for a group of parameters is multimodal (has more than one maximum). These environments contained from one to five dependent groups of parameters, where the groups ranged in size from three to nine.

The adaptive plan used was a Holland Reproductive Plan (10,11), a method inspired by genetics. Briefly, the state of the adaptive system resides in a "population" of many "individuals" or "chromosomes", each of which consists of a specification of a point in the function space, i.e., each chromosome contains a parameter value for each of the twenty-five arguments. The next state of the system is obtained by a two step process: 1) two individuals are randomly selected from the current population with the selection biased according to the payoffs (function value) of the old population; 2) these two "parents" are combined by operators to form an offspring, a new point in the function space. The operators used are similar to (but not necessarily identical to) the genetic versions of crossover, inversion, and mutation. Crossover selects portions of the chromosome from different parents, mutation randomly changes the parameter values, and inversion changes the order in which parameters are listed in the string defining an individual.

The experimental work set out to prove two things: that the reproductive plan adapts to non-linear sets of environmental parameters in different ways than it adapts to linear sets, and that the difference allows the detection of such non-linear effects without prior knowledge, thus supplying additional information to the experimenter. Two differences tested in the behavior of non-linear sets concerned the effects of distance along a string and the frequency-of-combination of parameter values.

In both cases we have shown that the differences do exist and are important. But only in the frequency-of-combination effect were we able to use this information in detecting non-linear sets of parameters.

Of course, all these conclusions are limited to the specific environments tested. However, these environments are definitely non-linear and, for lack of any theory of non-linearity, we must assume that the results will generalize to other environments with similar properties: a small number of parameter values and multiple peaks in the environment. There are many problems in artificial intelligence with these characteristics so that we can foresee some usefulness for this method.

More specifically we have shown:

Position Effect:

- 1) The position effect (i.e., distance between genes in a dependent group) is very important during the period of time a population is undergoing the most rapid evolution. Smaller distances between genes leads to a faster convergence in payoff average. This seems to be directly related to the ability of the population to keep good combinations of alleles together once they have been found. Bad permutations of genes may make it unlikely that a population will ever find the true optimum.
- 2) The position effect has not been demonstrated at equilibrium under normal operation of the reproductive plan. The only instances in which a population with a good permutation performed better were those in which the early evolution effect enabled populations to find better peaks before reproduction fixed the gene frequencies. This seems to be constant over a wide range of experimental parameters.
- 3) Introducing migration as an artificial means of increasing variance

into the population leads to a fairly smooth position effect, albeit at a population performance level much lower than is acceptable.

- 4) Experiments using inversion failed to take advantage of the position effect with any consistency, and certainly not in a manner which we might be expected to use in detecting dependent groups of genes.
- 5) Although inversion failed in our experiments, we were able to propose conditions under which it might perform better.

Frequency Effect:

- 6) Non-linear groups of genes have different behavior than linear groups in the combinations in which they are observed. A linear prediction of gene combinations from individual gene frequencies fails in most cases (in the sense of a chi-squared contingency table test for independence), but the association index calculated for non-linear groups is often an order of magnitude higher, a consistently observable difference.
- 7) It is possible to pick out dependent groups of genes via use of chi-squared tests even when there is no *a priori* knowledge of the environment.
- 8) Investigation of several multi-dimensional contingency tables indicate that the reason for the greatly increased association indices of non-linear groups lies in the large excess (over predictions) of sample points which inhabit peaks of the environment. This excess increases as the genes in the group are brought closer together on the chromosomes, indicating that close permutations more effectively sample the payoff function near the peaks.

This is further confirmation of the hypothesized position effect.

Although we have not been able to demonstrate that an inversion operator works to produce beneficial permutations, we have shown that position can be extremely important in searching the space. One experiment using a bad permutation, for example, failed to achieve the true optimum of the space even after twenty runs. We expect similar happenings with yet more complex environments. Ideally we would prefer some reordering operator, such as inversion, automatically to rearrange the genes to minimize this difficulty. In some cases this might occur but even with our current environments--in which inversion failed to operate as desired--there is an alternative. Using the results from a chi-squared pair analysis of the same twenty runs, we, as experimenters, can hypothesize (with some degree of confidence) which genes are dependent and thus which permutations are best. We can then intervene in the initial conditions of the experiment to arrange such a permutation. The result is an increased probability of finding the true optimum of the space.

Thus not only can we gather additional information about the form of the environment, but by so doing we can increase the probability that the adaptive system will achieve the true mean--an unanticipated bonus of the analysis suggested in this research.

Appendix

Ten Random Permutations of Twenty-five Genes

10, 8, 4, 9, 7, 3, 15, 1, 14, 18, 2, 6, 25, 12, 16, 5, 23, 11, 22, 21, 13, 20, 17, 19, 24
7, 15, 21, 13, 22, 6, 11, 23, 5, 14, 12, 20, 24, 9, 10, 18, 19, 25, 1, 8, 2, 4, 3, 16, 17
20, 9, 10, 13, 1, 18, 21, 25, 23, 19, 15, 16, 7, 6, 22, 8, 4, 3, 24, 11, 12, 2, 14, 17, 5
21, 9, 1, 24, 8, 19, 6, 20, 25, 18, 13, 10, 16, 14, 23, 15, 7, 5, 3, 11, 12, 4, 2, 17, 22
9, 22, 1, 24, 11, 20, 23, 13, 25, 12, 3, 5, 10, 16, 4, 7, 2, 15, 19, 21, 8, 14, 17, 18, 6
25, 8, 15, 10, 3, 11, 4, 14, 2, 9, 21, 17, 16, 6, 23, 5, 18, 19, 13, 20, 22, 12, 7, 1, 24
20, 10, 15, 5, 3, 9, 18, 2, 13, 17, 16, 22, 8, 21, 12, 14, 23, 4, 1, 25, 24, 6, 11, 19, 7
3, 4, 12, 20, 22, 5, 2, 25, 8, 16, 23, 21, 14, 18, 11, 6, 15, 9, 10, 1, 17, 7, 19, 13, 24
1, 17, 12, 24, 18, 7, 9, 8, 4, 22, 13, 5, 20, 14, 25, 19, 2, 3, 16, 23, 11, 21, 6, 10, 15
23, 7, 1, 11, 25, 15, 12, 4, 8, 9, 16, 14, 22, 2, 13, 21, 20, 6, 24, 5, 10, 18, 3, 19, 17

BIBLIOGRAPHY

1. Bagley, John D., *The Behavior of Adaptive Systems Which Employ Genetic and Correlation Algorithms*, Doctoral Thesis, Department of Computer and Communication Sciences, The University of Michigan, 1967
2. Bosworth, Jack; Norman Foo, and Bernard P. Zeigler, *Comparison of Genetic Algorithms with Conjugate Gradient Methods*, Technical Report 003120-1-T, Department of Computer and Communication Sciences, The University of Michigan, 1972
3. Cavicchio, Daniel J. Jr., *Adaptive Search Using Simulated Evolution*, Doctoral Thesis, Department of Computer and Communication Sciences, The University of Michigan, 1970
4. Crow, James F; and Motoo Kimura, *An Introduction to Population Genetics Theory*, Harper and Row, New York, 1970
5. Fisher, Ronald A., *The Genetical Theory of Natural Selection*, Dover, New York, 1958
6. Fogel, L.J.; A.J. Owen; and M.F. Walsh, *Artificial Intelligence Through Simulated Evolution*, Wiley, New York, 1966
7. Frantz, Daniel R., and Ronald F. Brender, *The CESSL Programming Language*, Technical Report 012520-5-T, Department of Computer and Communication Sciences, The University of Michigan, 1971
8. Friedberg, R.M., "A Learning Machine, Part I", *IBM Journal*, January 1968
9. Holland, John H., "Nonlinear Environments Permitting Efficient Adaptation", in *Computer and Information Sciences-II*, pp. 147-164, Academic Press, New York, 1967
10. _____, "Processing and Processors for Schemata", in *Associative Information Techniques* (E.L. Jacks, ed.), Elsevier, New York, 1971, pp. 127-146
11. _____, "Genetic Algorithms and the Optimal Allocation of Trials", (to be published)
12. Hollstien, Roy B., *Artificial Genetic Adaptation in Computer Control Systems*, Doctoral Thesis, Department of Computer Information and Control Engineering, The University of Michigan, 1971
13. Moran, P.A.P., *The Statistical Processes of Evolutionary Theory*, Clarendon Press, Oxford, 1962

14. Remington, Richard D., and M.A. Schork, *Statistics with Applications to the Biological and Health Sciences*, Prentice Hall, Englewood Cliffs, New Jersey, 1970
15. Samuel, A.L., "Some Studies in Machine Learning Using the Game of Checkers", *IBM Journal of Research and Development*, 3, No. 3, 1959, pp. 210-229.
16. Turner, John R.G., "Why Does the Genotype not Congeal?", *Evolution* 21, No. 4, pp. 645-656, December, 1967

