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SCATTERING BY A NARROW GAP

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Abstract

For a plane wave incident on a cavity-backed gap in a perfectly conducting plane, the coupled integral equations for the induced currents have been solved numerically and the far field scattering computed. The results are compared with a quasi-analytic solution previously derived, and for a narrow gap the agreement is excellent for all cavity geometries and for all material fillings that have been tested.

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1. Introduction

A topic of some concern in radar cross section studies is the scattering from the gap or crack that may exist where two component parts of a target come together. Even if the crack is wholly or partially filled with a material, it can still provide a significant contribution to the overall scattering pattern of the target, and it is then necessary to develop methods for predicting the scattering.

One method for doing this was described recently [1]. For a plane wave of either principal polarization incident on a narrow ($kw \ll 1$) resistive strip insert in an otherwise perfectly conducting plane, the low frequency approximations to the integral equations for the currents induced in the strip were solved in a quasi-analytic manner, leading to expressions for the far zone scattered field that are accurate for almost any resistivity R of the insert. If, instead, the insert is characterized by a surface impedance η , the results differ only in having R replaced by $\eta/2$ and the scattered field doubled, and this suggests that for a narrow gap backed by a cavity, the scattered field can be obtained by identifying η with the impedance looking into the cavity.

An alternative approach is to use the equivalence principle [2] to develop coupled integral equations for the electric and magnetic currents which exist on the walls of the cavity and in the aperture, and this is the method employed here. For an incident plane wave either H- or E-polarized, the integral equations are derived for a cavity of arbitrary shape filled with a homogeneous material. The equations are solved by the moment method and data for a variety of simple cavities are presented. For gap widths which are electrically small the results are compared with those

obtained using the previous method. The agreement is excellent, and confirms the utility of the original method [1] as an accurate and simple design tool.

2. Formulation

The problem considered is the two-dimensional one shown in Figure 1. The plane $y = 0$ is perfectly conducting apart from the aperture A: $-w/2 < x < w/2$, which forms the entrance to a cavity whose walls S are also perfectly conducting. The cavity is filled with a homogeneous dielectric material of permittivity $\epsilon_1 = \epsilon_r \epsilon$ and permeability $\mu_1 = \mu_r \mu$, where the quantities without subscripts refer to free space. A plane wave of either principal polarization is incident on the surface $y = 0$ from above, and we choose

$$\bar{H}^i = \hat{z} e^{-ik(x \cos\phi_0 + y \sin\phi_0)} \quad (1)$$

for H-polarization, and

$$\bar{E}^i = \hat{z} e^{-ik(x \cos\phi_0 + y \sin\phi_0)} \quad (2)$$

for E-polarization, where k is the propagation constant in the free space region above the surface. A time factor $e^{-i\omega t}$ is assumed and suppressed.

In the far zone of the gap the scattered field can be written as

$$\bar{H}^s = \hat{z} \sqrt{\frac{2}{\pi k \rho}} e^{i(k\rho - \pi/4)} P_H(\phi, \phi_0)$$

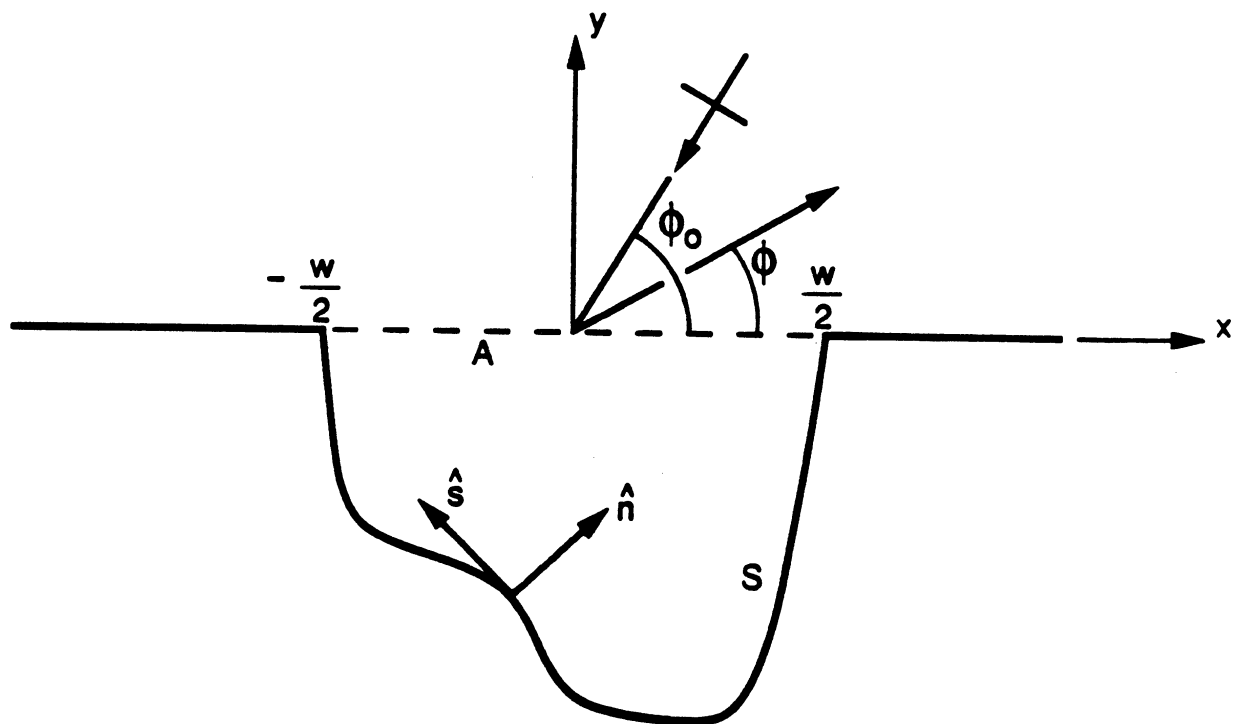


Fig. 1. Gap geometry.

for H-polarization, with a similar result for E-polarization, and the task is to determine the far field amplitudes $P_{H,E}(\phi, \phi_0)$ with particular emphasis on the case of a narrow gap ($kw \leq 1$).

2.1 H-Polarization

We consider first the free space region $y > 0$. Using Green's theorem in conjunction with the half space Green's function

$$G_1 = \frac{i}{4} \left\{ H_0^{(1)} \left(k \sqrt{(x-x')^2 + (y-y')^2} \right) + H_0^{(1)} \left(k \sqrt{(x-x')^2 + (y+y')^2} \right) \right\} ,$$

the scattered field can be attributed to a magnetic current $\vec{J}^* = -\hat{y} \times \vec{E}$ in the aperture, and the total magnetic field is then

$$H_z(x,y) = H_z^i(x,y) + H_z^r(x,y) - \frac{kY}{2} \int_{-w/2}^{w/2} J_z^*(x') H_0^{(1)} \left(k \sqrt{(x-x')^2 + y^2} \right) dx'$$

where

$$H_z^r = e^{-ik(x \cos \phi_0 - y \sin \phi_0)}$$

is the reflected plane wave and $Y (= 1/Z)$ is the intrinsic admittance of free space.

Hence,

$$P_H(\phi, \phi_0) = -\frac{kY}{2} \int_{-w/2}^{w/2} J_z^*(x') e^{-ikx' \cos \phi} dx' \quad (3)$$

and in the aperture

$$H_z(x,0) = 2e^{-ikx \cos \phi_0} - \frac{kY}{2} \int_{-w/2}^{w/2} J_z^*(x') H_0^{(1)}(k|x-x'|) dx' \quad (4)$$

We now turn to the region $y < 0$ occupied by the cavity. In accordance with the equivalence principle [2] it is assumed that the gap is closed with a perfect conductor, and that a magnetic current $-\bar{J}^*$ is placed just below, thereby ensuring the continuity of the tangential electric field in the open gap. The magnetic Hertz vector is therefore

$$\bar{\Pi}^*(x,y) = \frac{Y}{4k\mu_r} \int_{-w/2}^{w/2} \bar{J}^*(x') H_0^{(1)}\left(k_1 \sqrt{(x-x')^2 + y^2}\right) dx' \quad (5)$$

and since $\bar{J}^* = \hat{z} J_z^*$, the magnetic field produced is

$$\bar{H}^{(1)}(x,y) = \nabla \times \nabla \times \bar{\Pi}^* = \hat{z} \frac{kY}{4} \epsilon_r \int_{-w/2}^{w/2} J_z^*(x') H_0^{(1)}\left(k_1 \sqrt{(x-x')^2 + y^2}\right) dx'$$

where $k_1 = k \sqrt{\epsilon_r \mu_r}$ is the propagation constant. The electric current $\bar{J} = \hat{n} \times \bar{H}$

on the cavity walls S and in the (closed) aperture A also implies an electric Hertz vector

$$\bar{\Pi}(x,y) = -\frac{Z}{4k\epsilon_r} \int_{S+A} \bar{J}(s') H_0^{(1)}\left(k_1 \sqrt{(x-x')^2 + (y-y')^2}\right) ds' \quad (6)$$

and the corresponding magnetic field is

$$\begin{aligned}\bar{H}^{(2)}(x,y) &= -ikY \epsilon_r \nabla \times \bar{\Pi} \\ &= \frac{i}{4} \int_{S+A} \nabla H_0^{(1)} \left(k_1 \sqrt{(x-x')^2 + (y-y')^2} \right) \times \bar{J}(s') ds'\end{aligned}$$

where the tangential unit vector \hat{s} is such that $\hat{n}, \hat{s}, \hat{z}$ form a right-handed system with \hat{n} directed into the cavity. Clearly, $\bar{J}(s) = \hat{s} J_s(s)$, and in the aperture, $\hat{s} = \hat{x}$.

The total magnetic field is $\bar{H} = \bar{H}^{(1)} + \bar{H}^{(2)}$, and by allowing the observation point to approach the boundary of the closed cavity, we can construct an integral equation for the currents. We find

$$\begin{aligned}\bar{J}(s) &= (\hat{n} \times \hat{z}) \frac{kY}{4} \epsilon_r \int_{-w/2}^{w/2} J_z(x') H_0^{(1)} \left(k_1 \sqrt{(x-x')^2 + y^2} \right) dx' \\ &+ \lim_{(x,y) \rightarrow S+A} \hat{n} \times \frac{i}{4} \int_{S+A} J_s(s') \nabla H_0^{(1)} \left(k_1 \sqrt{(x-x')^2 + (y-y')^2} \right) \times \hat{s}' ds'\end{aligned}$$

giving

$$\begin{aligned}J_s(s) &= \frac{kY}{2} \epsilon_r \int_{-w/2}^{w/2} J_z(x') H_0^{(1)} \left(k_1 \sqrt{(x-x')^2 + y^2} \right) dx' \\ &+ \frac{ik_1}{2} \int_{S+A} J_s(s') \sin \gamma' H_1^{(1)} \left(k_1 \sqrt{(x-x')^2 + (y-y')^2} \right) ds'\end{aligned} \quad (7)$$

where

$$\sin \gamma' = \hat{z} \cdot \frac{(x-x') \hat{x} + (y-y') \hat{y}}{\sqrt{(x-x')^2 + (y-y')^2}} \times \hat{s}' \quad , \quad (8)$$

valid at all points of S and A.

The only remaining task is to enforce the continuity of H_z through the aperture.

When the observation point is in the aperture

$$H_z(x,0) = \frac{kY}{4} \epsilon_r \int_{-w/2}^{w/2} J_z(x') H_0^{(1)}(k_1 |x-x'|) dx' + \lim_{y \rightarrow 0} \hat{z} \frac{i}{4} \int_{S+A} J_s(s') \nabla H_0^{(1)}\left(k_1 \sqrt{(x-x')^2 + y^2}\right) \times \hat{s}' ds'$$

and therefore

$$H_z(x,0) = \frac{kY}{4} \epsilon_r \int_{-w/2}^{w/2} J_z(x') H_0^{(1)}(k_1 |x-x'|) dx' + \frac{1}{2} J_s(x) + \frac{ik_1}{4} \int_{S+A} J_s(s') \sin \gamma' H_1^{(1)}\left(k_1 \sqrt{(x-x')^2 + y^2}\right) ds' \quad (9)$$

When this is equated to the expression (4) for $H_z(x,0)$ on the outside of the gap, we

obtain

$$2 e^{-ikx \cos \phi_0} = \frac{kY}{2} \int_{-w/2}^{w/2} J_z(x') H_0^{(1)}(k |x-x'|) dx' + \frac{kY}{4} \epsilon_r \int_{-w/2}^{w/2} J_z(x') H_0^{(1)}(k_1 |x-x'|) dx' + \frac{1}{2} J_s(x) + \frac{ik_1}{4} \int_{S+A} J_s(s') \sin \gamma' H_1^{(1)}\left(k_1 \sqrt{(x-x')^2 + y^2}\right) ds' \quad (10)$$

valid for $-w/2 < x < w/2$. Since (7) is also valid in A, it can be used to simplify (10) by eliminating two of the integrals. The result is

$$J_s(x) = 2e^{-ikx \cos \phi_0} - \frac{kY}{2} \int_{-w/2}^{w/2} \dot{J}_z(x') H_0^{(1)}(k|x-x'|) dx' \quad (11)$$

valid for x in A , and (7) and (11) constitute a pair of coupled integral equations for $\dot{J}_z(x)$ and $J_s(s)$. These are the equations that will be used, and we note the similarity of (11) and (4).

When the maximum dimension of the cavity is electrically small, the Hankel function $H_0^{(1)}$ can be replaced by its logarithmic approximation, and though this does not significantly simplify the numerical solution of (7) and (11), the fact that $e^{-ikx \cos \phi_0}$ can also be replaced by unity shows that $\dot{J}_z(x)$ and $J_s(s)$ are aspect independent. The same approximation to (3) then leads to a far field amplitude which is independent of ϕ and ϕ_0 , and this is a feature of the low frequency situation.

2.2 E-Polarization

The procedure is similar to that given above. For the region $y > 0$ Green's theorem in conjunction with the Green's function

$$G_2 = \frac{i}{4} \left\{ H_0^{(1)} \left(k \sqrt{(x-x')^2 + (y-y')^2} \right) - H_0^{(1)} \left(k \sqrt{(x-x')^2 + (y+y')^2} \right) \right\}$$

gives

$$E_z = E_z^i + E_z^r + \frac{i}{2} \frac{\partial}{\partial y} \int_{-w/2}^{w/2} \dot{J}_x(x') H_0^{(1)} \left(k \sqrt{(x-x')^2 + y^2} \right) dx'$$

where $\vec{J} = \hat{x} \dot{J}_x$ is the assumed magnetic current in the gap and

$$E_z^r = -e^{-ik(x \cos \phi_0 - y \sin \phi_0)}$$

is the reflected plane wave. Hence

$$P_E(\phi, \phi_0) = -\frac{k}{2} \sin \phi \int_{-w/2}^{w/2} J_x(x') e^{-ikx' \cos \phi} dx' \quad (12)$$

and since $H_x = -\frac{iY}{k} \frac{\partial E_z}{\partial y}$, the tangential component of the magnetic field in the

aperture is

$$H_x(x, 0) = -2Y \sin \phi_0 e^{-ikx \cos \phi_0} - \frac{kY}{2} \left(1 + \frac{1}{k^2} \frac{\partial^2}{\partial x^2} \right) \int_{-w/2}^{w/2} J_x(x') H_0^{(1)}(k|x-x'|) dx' \quad (13)$$

In the region $y < 0$ occupied by the cavity, the field can be attributed to the magnetic Hertz vector (5) with $\bar{J} = \hat{x} J_x$ and the electric Hertz vector (6) with $\bar{J} = \hat{z} J_z$.

The magnetic field is therefore

$$\begin{aligned} \bar{H}(x, y) = & \nabla \times \nabla \times \frac{Y}{4k\mu_r} \int_{-w/2}^{w/2} \bar{J}(x') H_0^{(1)}\left(k_1 \sqrt{(x-x')^2 + y^2}\right) dx' \\ & + \frac{i}{4} \int_{S+A} \nabla H_0^{(1)}\left(k_1 \sqrt{(x-x')^2 + (y-y')^2}\right) \times \bar{J}(s') ds' \quad , \end{aligned}$$

and by allowing the observation point to approach the boundary of the closed cavity,

we obtain the integral equation

$$\begin{aligned}
J_z(s) = & \frac{Y}{2k\mu_r} (\hat{n} \cdot \nabla) \frac{\partial}{\partial y} \int_{-w/2}^{w/2} J_x(x') H_0^{(1)} \left(k_1 \sqrt{(x-x')^2 + y^2} \right) dx' \\
& + \frac{ik_1}{2} \int_{S+A} J_z(s') \sin \gamma H_1^{(1)} \left(k_1 \sqrt{(x-x')^2 + (y-y')^2} \right) ds'
\end{aligned} \tag{14}$$

where

$$\sin \gamma = \hat{z} \cdot \frac{(x-x') \hat{x} + (y-y') \hat{y}}{\sqrt{(x-x')^2 + (y-y')^2}} \times \hat{s} \tag{15}$$

valid at all points of S and A.

When the observation point is in the aperture,

$$\begin{aligned}
H_x(x,0) = & \frac{kY}{4} \epsilon_r \left(1 + \frac{1}{k_1^2} \frac{\partial^2}{\partial x^2} \right) \int_{-w/2}^{w/2} J_x(x') H_0^{(1)} (k_1 |x-x'|) dx' + \frac{1}{2} J_z(x) \\
& + \frac{ik_1}{4} \int_{S+A} J_z(s') \sin \gamma H_1^{(1)} \left(k_1 \sqrt{(x-x')^2 + y^2} \right) ds' ,
\end{aligned}$$

and on equating this to the expression (13) for the magnetic field on the outside of the gap, we obtain

$$\begin{aligned}
-2Y \sin \phi_0 e^{-ikx \cos \phi_0} = & \frac{kY}{2} \left(1 + \frac{1}{k^2} \frac{\partial^2}{\partial x^2} \right) \int_{-w/2}^{w/2} J_x(x') H_0^{(1)} (k |x-x'|) dx' \\
& + \frac{kY}{4} \epsilon_r \left(1 + \frac{1}{k_1^2} \frac{\partial^2}{\partial x^2} \right) \int_{-w/2}^{w/2} J_x(x') H_0^{(1)} (k_1 |x-x'|) dx' \\
& + \frac{1}{2} J_z(x) + \frac{ik_1}{4} \int_{S+A} J_z(s') \sin \gamma H_1^{(1)} \left(k_1 \sqrt{(x-x')^2 + y^2} \right) ds'
\end{aligned} \tag{16}$$

valid for x in A. This can be simplified using (14) and the result is

$$J_z(x) = -2Y \sin\phi_0 e^{-ikx \cos\phi_0} - \frac{kY}{2} \left(1 + \frac{1}{k} \frac{\partial^2}{\partial x^2} \right) \int_{-w/2}^{w/2} \dot{J}_x(x') H_0^{(1)}(k|x-x'|) dx' \quad (17)$$

for x in A in accordance with (13), and (14) and (17) constitute a pair of coupled integral equations for $\dot{J}_x(x)$ and $J_z(s)$.

There is a third integral equation that can be developed and this has some advantages for numerical purposes. In the region $y < 0$ the electric field produced by the electric and magnetic Hertz vectors is

$$\begin{aligned} \bar{E}(x,y) = & -\frac{kZ\mu_r}{4} \int_{S+A} J_z(s') H_0^{(1)}\left(k_1 \sqrt{(x-x')^2 + (y-y')^2}\right) ds' \hat{z} \\ & - \frac{i}{4} \frac{\partial}{\partial y} \int_{-w/2}^{w/2} \dot{J}_x(x') H_0^{(1)}\left(k_1 \sqrt{(x-x')^2 + y^2}\right) dx' \hat{z} , \end{aligned}$$

and when the boundary condition on the perfectly conducting surface is applied, we find

$$\begin{aligned} \dot{J}_x(x) = & \frac{i}{2} \int_{-w/2}^{w/2} \dot{J}_x(x') \frac{\partial}{\partial y} H_0^{(1)}\left(k_1 \sqrt{(x-x')^2 + y^2}\right) dx' \\ & + \frac{kZ\mu_r}{2} \int_{S+A} J_z(s') H_0^{(1)}\left(k_1 \sqrt{(x-x')^2 + (y-y')^2}\right) ds' \end{aligned} \quad (18)$$

valid on $S + A$. Of course, $\dot{J}_x(x)$ is non-zero only in A, and (17) and (18) are the pair of integral equations used to compute $\dot{J}_x(x)$ and $J_z(s)$.

3. Quasi-Analytical Solution

An alternative approach was proposed by Senior and Volakis [1]. In effect, the problem which they considered is a uniform impedance insert in an otherwise perfectly conducting plane. If η is the surface impedance, the integral equations for H- and E-polarizations are identical to (4) and (13) respectively, with

$$H_z(x,0) = \frac{1}{\eta} \dot{J}_z(x), \quad H_x(x,0) = -\frac{1}{\eta} \dot{J}_x(x) \quad (19)$$

at the insert. At low frequencies for which $kw \ll 1$ the integral equations can be simplified, and for H-polarization it is found that

$$\frac{1}{\pi} \int_{-1}^1 J_2(\zeta') \ln |\zeta' - \zeta| d\zeta' = 1 + a J_2(\zeta) \quad (20)$$

for $-1 < \zeta < 1$ with

$$a = \frac{2i}{kw} \frac{Z}{\eta} \quad (21)$$

$J_2(\zeta)$ is a modified current in terms of which

$$P_H(\phi, \phi_0) = i\pi \left\{ A + \frac{1}{K_H(a)} \right\}^{-1} \quad (22)$$

with

$$K_H(a) = \frac{1}{\pi} \int_{-1}^1 J_2(\zeta) d\zeta \quad (23)$$

and

$$A = \ln \frac{kw}{4} + \gamma - i \frac{\pi}{2}$$

where $\gamma = 0.5772157\dots$ is Euler's constant. We observe that $P_H(\phi, \phi_0)$ is independent of ϕ and ϕ_0 , and since $K_H(a)$ is real if a is,

$$\left| P_H(\phi, \phi_0) \right| \leq 2 \quad (24)$$

for real a .

Similarly, for E-polarization the low frequency approximation to the integral equation is

$$\frac{\partial^2}{\partial \zeta^2} \frac{1}{\pi} \int_{-1}^1 J_3(\zeta') \ln |\zeta' - \zeta| d\zeta' = 1 - b J_3(\zeta) \quad (25)$$

for $-1 < \zeta < 1$ with

$$b = -\frac{ikw}{2} \frac{Z}{\eta} \quad (26)$$

where the modified current $J_3(\zeta)$ is such that $J_3(\pm 1) = 0$. In terms of $J_3(\zeta)$

$$P_E(\phi, \phi_0) = -\frac{i\pi}{4} (kw)^2 \sin\phi \sin\phi_0 K_E(b) \quad (27)$$

with

$$K_E(b) = \frac{1}{\pi} \int_{-1}^1 J_3(\zeta) d\zeta, \quad (28)$$

and the angle dependence is explicit in the expression for $P_E(\phi, \phi_0)$.

Computer programs were written to solve (20) and (25) by the moment method and, hence, compute $K_H(a)$ and $K_E(b)$ for all complex a and b . From an examination of the results it was found that $K_H(a)$ can be approximated as

$$K_H(a) = - \frac{(a + 0.15)(a + 0.29)}{\left(\frac{\pi a}{2} + \ln 2\right)(a + 0.15)(a + 0.29) + 0.10a(a + 0.20)} \quad (29)$$

for all a apart from those in the immediate vicinity of the portion $-1.1 \leq a \leq 0.3$ of the real axis in the complex a plane. In this region an empirical expression for $K_H(a)$ is

$$K_H(a) = - \frac{1}{\frac{\pi a}{2} + \ln 2 + 0.1} \quad (30)$$

and since, for other a , (30) differs from (29) by no more than 3 percent, it is sufficient to use (30) for all a . Similarly, for E-polarization the approximation is

$$K_E(b) = \frac{0.62}{b + 1.15} \frac{(b + 4.08)(b + 7.26)(b + 10.37)(b + 13.43)(b + 16.46)}{(b + 4.27)(b + 7.37)(b + 10.45)(b + 13.49)(b + 16.50)}, \quad (31)$$

valid for all b not in the immediate vicinity of the negative real axis. For positive real b ,

$K_E(b) \leq 1/2$ and hence

$$\left| P_E(\phi, \phi_0) \right| \leq \frac{\pi}{8} (kw)^2 \sin\phi \sin\phi_0. \quad (32)$$

In their regions of validity, the estimated accuracy of (29) - (31) is about three percent.

To use these results to predict the scattering from a narrow gap, it was proposed that η be identified with the impedance looking into the gap, with η calculated using a simple transmission line (or other) model that takes into account the geometry and material filling of the gap. To show how this is done, consider a crack such as those illustrated in Figure 2. For H-polarization the cavity supports a variety of TE modes, but since the width w is small, the only mode which is not evanescent is the TEM mode, and this is the main contributor to the field in the gap. Under the assumption that this is the only mode that must be considered, the effective surface impedance η can be deduced from the input impedance Z_{1n} of a parallel plate transmission line. The voltage across the gap is

$$V = \int_{-w/2}^{w/2} E_x(x) dx \approx wE_x$$

and since the current I is proportional to the tangential magnetic field,

$$\eta = \frac{E_x}{H_z} = \frac{1}{w} \frac{V}{I} = \frac{Z_{1n}}{w} \quad (33)$$

For a parallel plate transmission line whose plate separation is w , the inductance and capacitance per unit length and width are $L = \mu_0\mu_r w$ and $C = \epsilon_0\epsilon_r/w$ respectively, and the characteristic impedance is $Z_c = Z_1 w$ with $Z_1 = Z \sqrt{\mu_r/\epsilon_r}$.

The L-shaped gap in Figure 2(b) can be viewed as two cascaded lines. The first line has length d_1 and characteristic impedance Z_c , whereas the second (of length

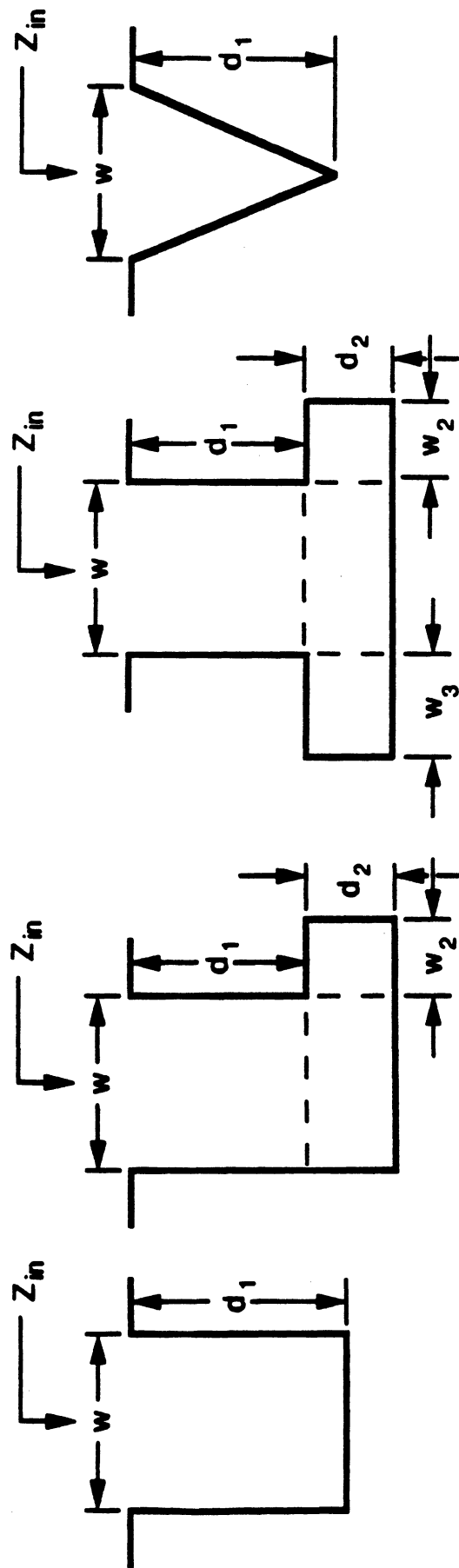


Fig. 2. Gap and cavity configurations. The cavity is filled with a homogeneous dielectric having relative permittivity ϵ_r and relative permeability μ_r .

w_2) has characteristic impedance $Z_c = Z_1 d_2$ and is shorted. As a load its impedance is

$$Z_L = -i Z_c \tan k_1 w_2 \quad (34)$$

The junction of these lines can be modelled as a lumped parameter pi-network whose reactance and susceptance elements are [3]

$$\begin{aligned} X &= k Z_1 w d_2 \\ B_1 &= \frac{k}{Z_1} \left(\frac{d_2}{d_2 + w} \right) \left(1 - \frac{2}{\pi} \ln 2 \right) \\ B_2 &= \frac{k}{Z_1} \left(\frac{w}{d_2 + w} \right) \left(1 - \frac{2}{\pi} \ln 2 \right) . \end{aligned}$$

The input impedance of the first line cascaded with the pi-network and the second line is then

$$Z_{1n} = Z_c \frac{Z_L - i Z_c \tan k_1 d_1}{Z_c - i Z_L \tan k_1 d_1} \quad (35)$$

where

$$Z_L = \frac{Z_L - iX (1 - iB_2 Z_L)}{(1 - B_1 X) (1 - iB_2 Z_L) - iB_1 Z_L} \quad (36)$$

Similarly, the T-shaped gap in Figure 2(c) can be treated as a transmission line loaded with two shorted lines in series. For the shorted lines of lengths w_2 and w_3 , the load impedance is

$$Z_L'' = -i Z_c' \left\{ \tan k_1 w_2 + \tan k_1 w_3 \right\} \quad (37)$$

The junction is modelled with a shunt susceptance and a series reactance in series with Z_L :

$$X_3 = 2kZ_1 w d_2$$

$$B_3 = \frac{k}{Z_1} \left(\frac{d_2}{d_2 + w} \right) 0.7822$$

where the constant was determined empirically, and the input impedance Z_{1n} is then given by (35) with

$$Z_L' = \frac{Z_L'' - i X_3}{1 - i B_3 (Z_L'' - i X_3)} \quad (38)$$

The rectangular gap is the special case $d_2 = 0$ of either of the above structures, and for this

$$Z_{1n} = -i Z_c \tan k_1 d_1 \quad (39)$$

Finally, for the V-shaped gap in Figure 2 (d), the inductance and capacitance per unit length of the line are functions of position, but when the coupled differential equations for the voltage and current are solved, we obtain

$$Z_{1n} = -i Z_c \frac{J_1(k_1 d_1)}{J_0(k_1 d_1)} \quad (40)$$

where J_0 and J_1 are Bessel functions.

For E-polarization all of the modes are evanescent, but if we again assume that the first mode dominates in the gap, simple formulas for the surface impedance can be found. In a parallel plate waveguide of width w

$$H_x = \frac{1}{ikZ\mu_r} \frac{\partial E_z}{\partial y} ,$$

and for the lowest order mode the propagation constant is ikp where

$$p = \left\{ \left(\frac{\lambda}{2w} \right)^2 - \epsilon_r \mu_r \right\}^{1/2} . \quad (41)$$

Since E_z/H_x is independent of position, a transmission line analogy can be made. The characteristic impedance of the line is $-iZ\mu_r/p$, which is also the impedance looking into the gap, and the results previously obtained for H-polarization are now applicable if k_1 is replaced by ikp and Z_1 by $-iZ\mu_r/p$. Thus, for a rectangular gap

$$Z_{1n} = -i \frac{Z\mu_r w}{p} \tanh kpd_1 , \quad (42)$$

and for a triangular gap

$$Z_{1n} = -i \frac{Z\mu_r w}{p} \frac{I_1(kpd_1)}{I_0(kpd_1)} , \quad (43)$$

where Z_{1n} and η are related via (33) and I_0 and I_1 are modified Bessel functions [4]. Formulas for L- and T-shaped cracks can be deduced in a similar manner, but since the modes are evanescent, the shape of the lower cavity has little or no effect on the impedance.

4. Numerical Results

The integral equation pairs (7), (11) and (17), (18) for H- and E-polarizations respectively were programmed for solution by the moment method, using pulse basis and point matching functions as described in Appendix A. In the case of (17), the derivative was applied to the kernel, and because of the order of the resulting singularity, the contributions from two cells on either side of the self cell were evaluated analytically, in addition to the contribution of the self cell itself. Comparison with the results of a finite element method [5] for H-polarization showed excellent agreement, and for purposes of comparison with the quasi-analytical solution, the moment method data will be regarded as exact. The computer program used to implement the expressions for the quasi-analytical solution is listed in Appendix B.

Considering first the results for H-polarization, Figure 3 shows the backscattering from a rectangular air-filled gap as a function of aspect for three gap widths. The aspect variation decreases with w . It is less than 4 percent for $w/\lambda = 0.15$, and since aspect independence is a feature of the quasi-analytic solution, we will henceforth confine attention to this case. It is then sufficient to take $\phi = \phi_0 = \pi/2$ corresponding to normal incidence backscatter.

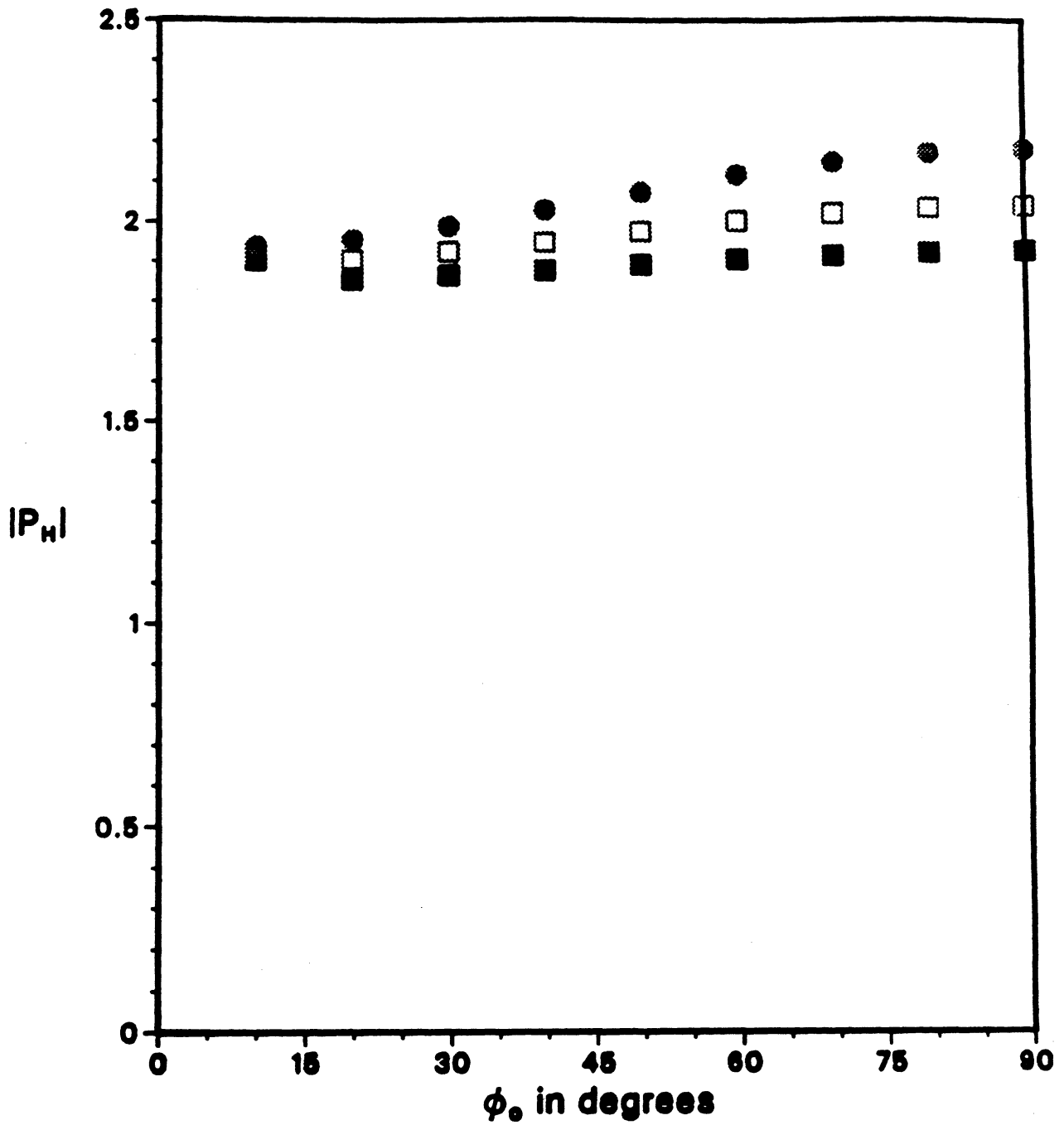


Fig. 3: Modulus of the far field amplitude P_H with respect to aspect ϕ_0 for a rectangular gap with $\phi = \pi/2$ and $d/\lambda = 0.2$: \blacksquare $w/\lambda = 0.15$, \square $w/\lambda = 0.2$, \bullet $w/\lambda = 0.25$.

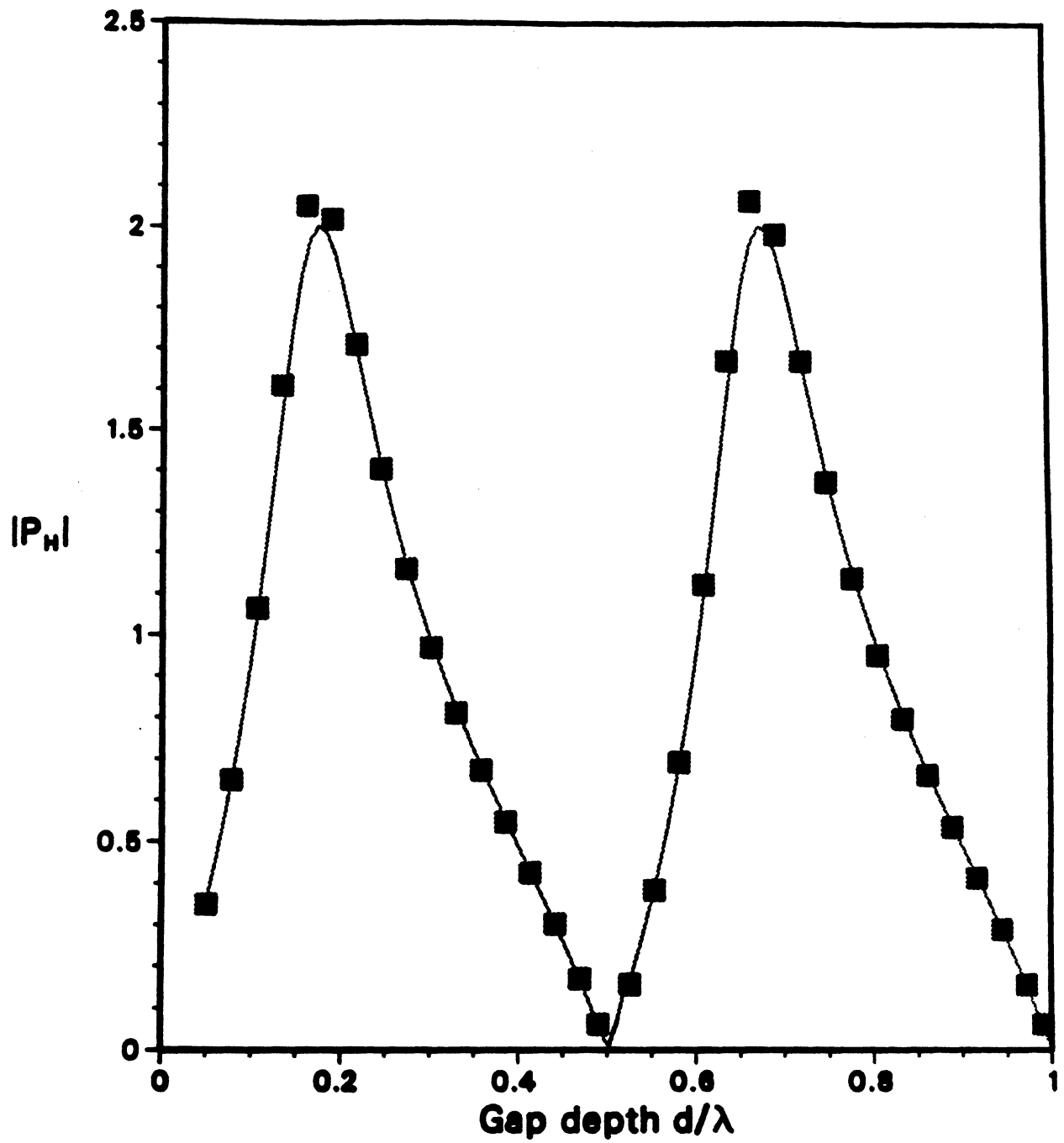


Fig. 4. Modulus of the far field amplitude P_H for a rectangular gap of varying depth $d_1 = d$ with $\phi = \phi_0 = \pi/2$ and $w/\lambda = 0.15$: ■ exact, — analytical.

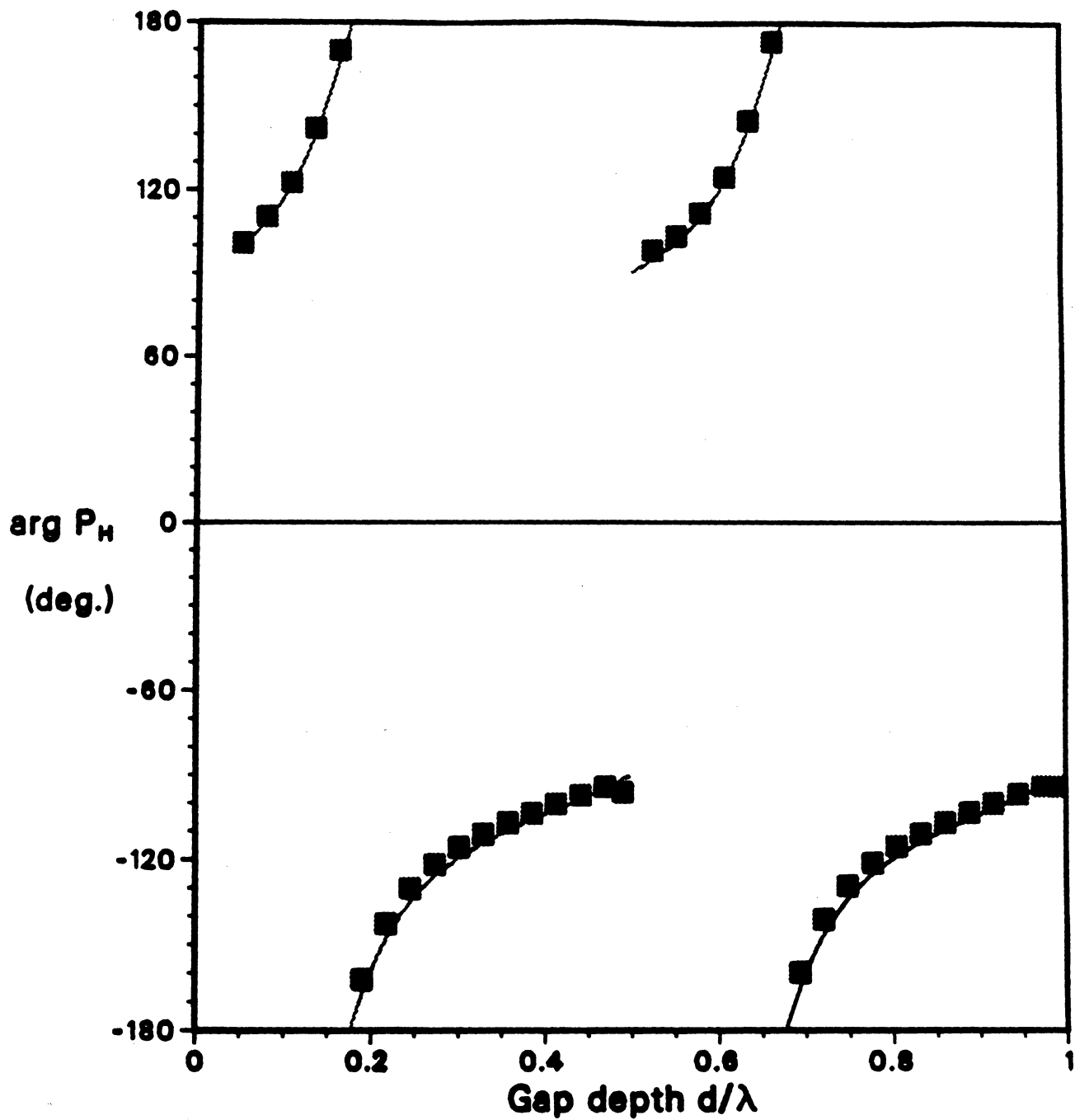


Fig. 5. Argument of the far field amplitude P_H for a rectangular gap of varying depth $d_1 = d$ with $\phi = \phi_0 = \pi/2$ and $w/\lambda = 0.15$: ■ exact, — analytical.

In Figures 4 and 5 the amplitude and phase of the far field amplitude $P_H(\pi/2, \pi/2)$ are shown as a function of depth for a rectangular air-filled gap of width $w/\lambda = 0.15$. We observe the cyclical behavior with zeros at $d/\lambda = 0, 0.5, 1.0, \dots$, resulting from the periodicity of the impedance looking into the gap. From (39) and (21) the corresponding a are real and vary from $-\infty$ to ∞ over each cycle. Over the entire range of d/λ the agreement between the quasi-analytic and moment method results is excellent, but in spite of this the computed aperture impedances do not agree. This is evident from Figure 6 where $|E_x/H_z|$ is plotted as a function of x for $w/\lambda = 0.15$ and $d/\lambda = 0.20$. The U-shaped behavior is in accordance with the edge condition

at $x = -w/2$, and the data fit the curve $C \left\{ 1 - \left(\frac{2x}{w} \right)^2 \right\}^{1/2}$ with $C = 860$ ohms. The

average value is therefore $\pi C/2 = 1350$ ohms, compared with which (36) gives

$|\eta| = 1160$ ohms. A similar discrepancy was found with all gap geometries.

Nevertheless, the quasi-analytic solution provides an excellent approximation to the far field, and this is illustrated in Figures 7 through 10 showing $|P_H|$ for a material-filled rectangular gap and for air-filled L-, T- and V-shaped gaps.

Turning now to E-polarization, Figures 11 and 12 show the amplitude and phase of $P_E(\pi/2, \pi/2)$ as functions of w/λ for a rectangular air-filled gap having $d/\lambda = 0.1$. The quasi-analytic and exact data diverge with increasing w/λ , but the difference is less than 4 percent in amplitude and 5 degrees in phase for $w/\lambda \leq 0.20$.

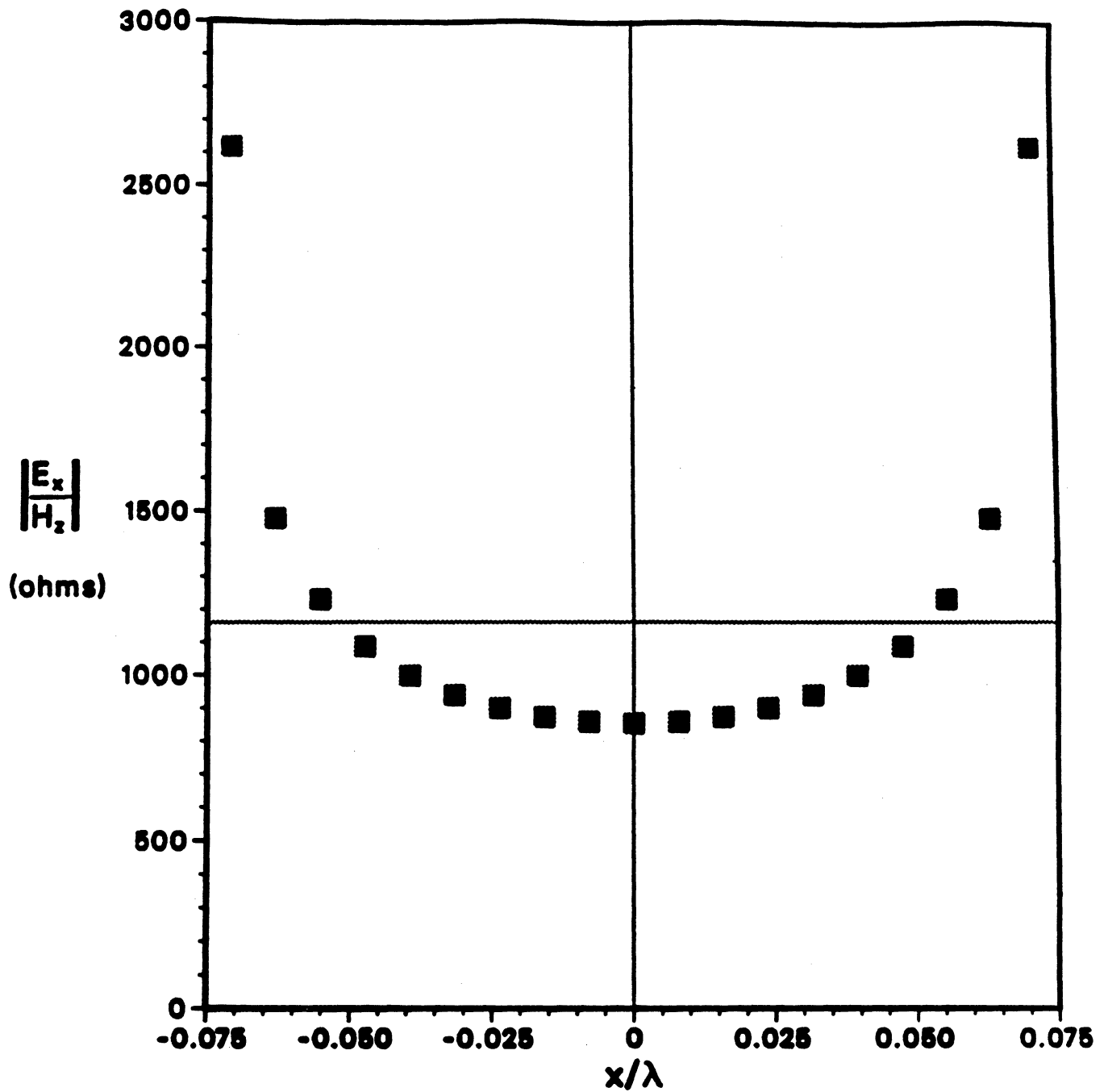


Fig. 6. Aperture impedance $|E_x/H_z|$ evaluated at $-w/2 < x < w/2$ and $y=0$ for a rectangular gap with $\phi = \phi_0 = \pi/2$, $w/\lambda = 0.15$, and $d/\lambda = 0.2$:
 ■ exact, — analytical.

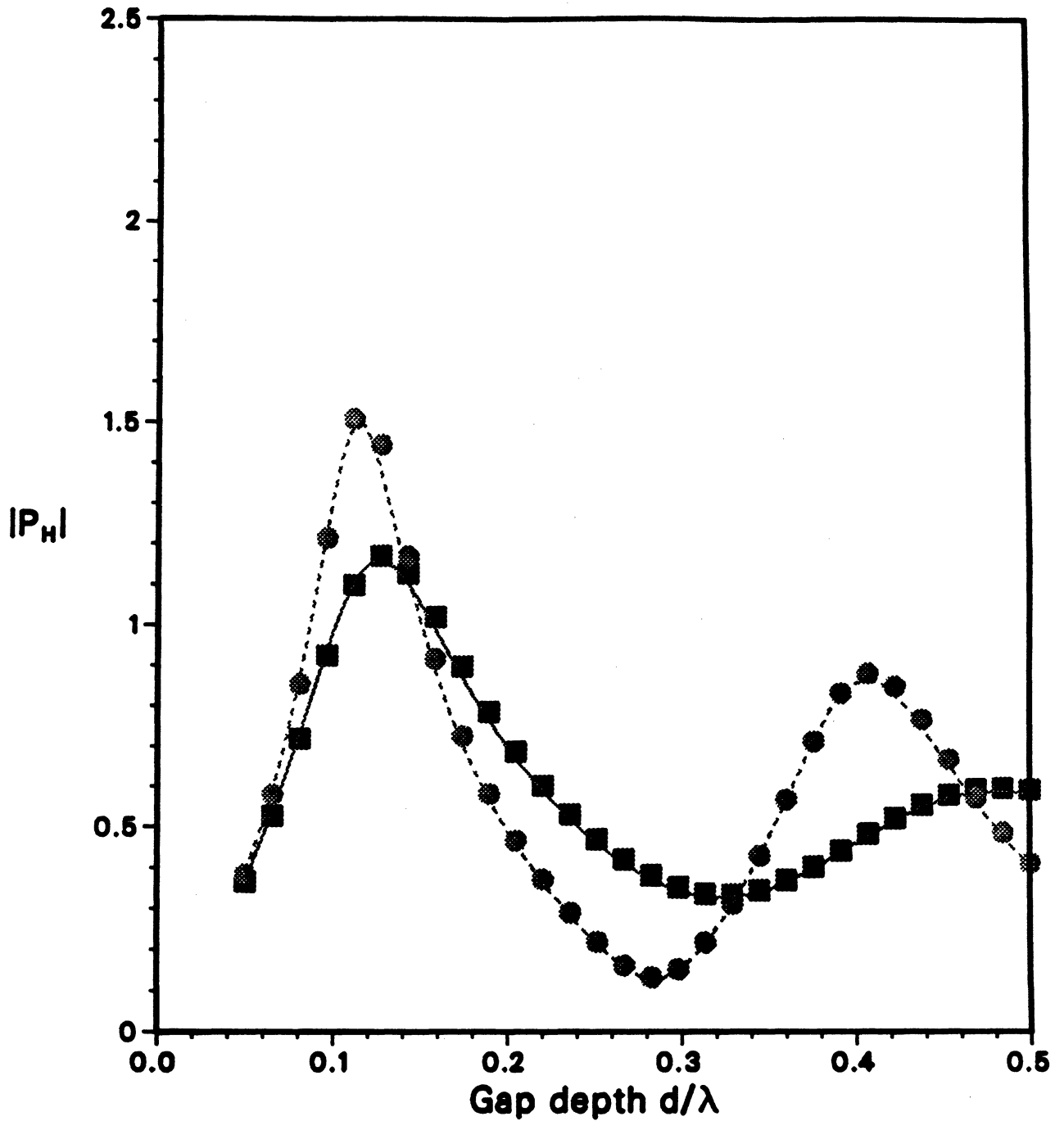


Fig. 7. Modulus of the far field amplitude P_H for a material-filled rectangular gap of varying depth $d_1 = d$ with $\phi = \phi_0 = \pi/2$, $w/\lambda = 0.15$, and $\mu_r = 1$:

$\epsilon_r = 2 + i1$ ■ exact, ——— analytical
 $\epsilon_r = 3 + i0.5$ ● exact, - - - - - analytical.

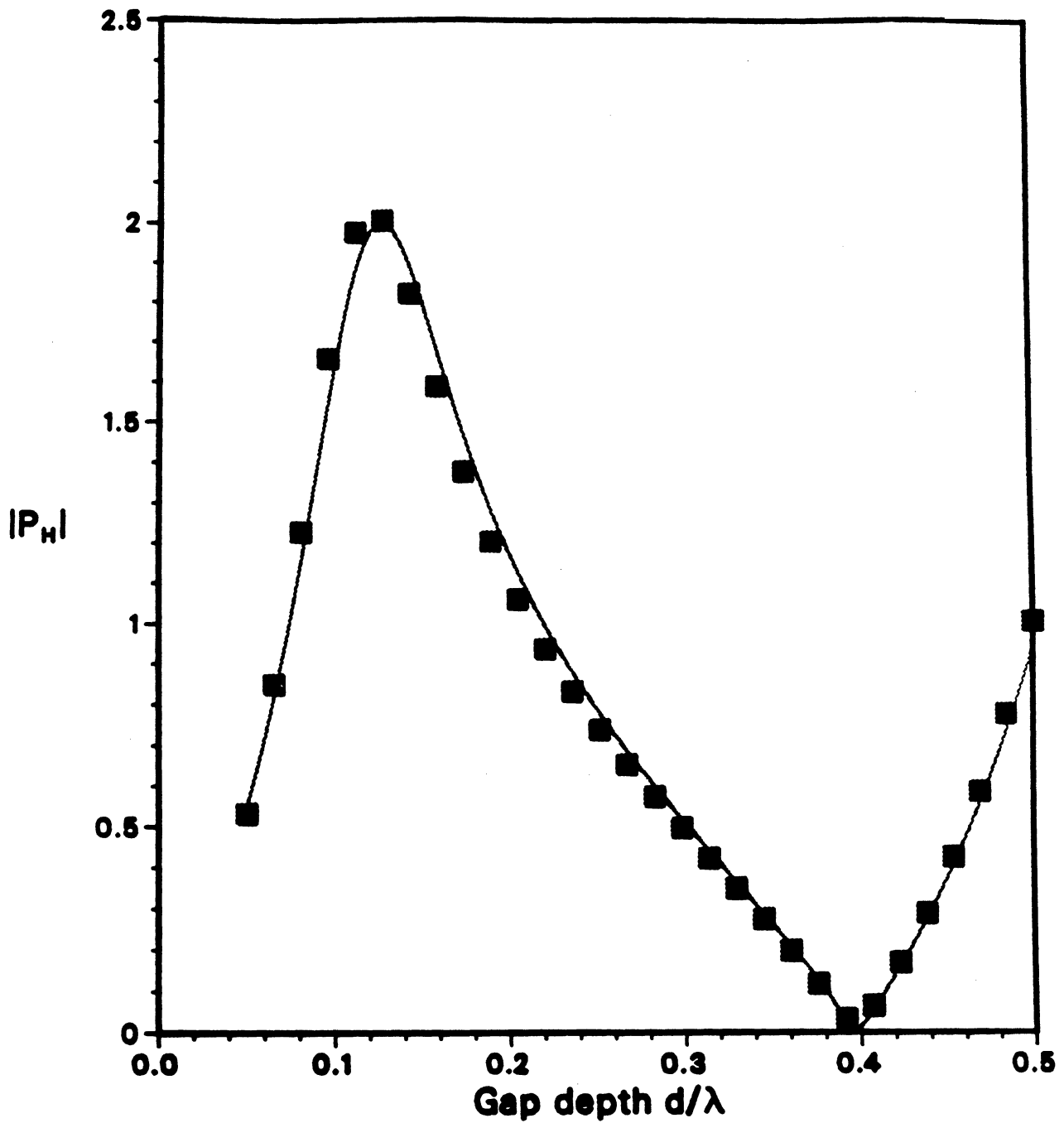


Fig. 8(a). Modulus of the far field amplitude P_H for an air-filled L-shaped gap of varying depth $d_1 + d_2 = d$ with $\phi = \phi_0 = \pi/2$, $w/\lambda = 0.15$, $w_2/\lambda = 0.15$, and $d_1/d_2 = 3$: ■ exact, — analytical.

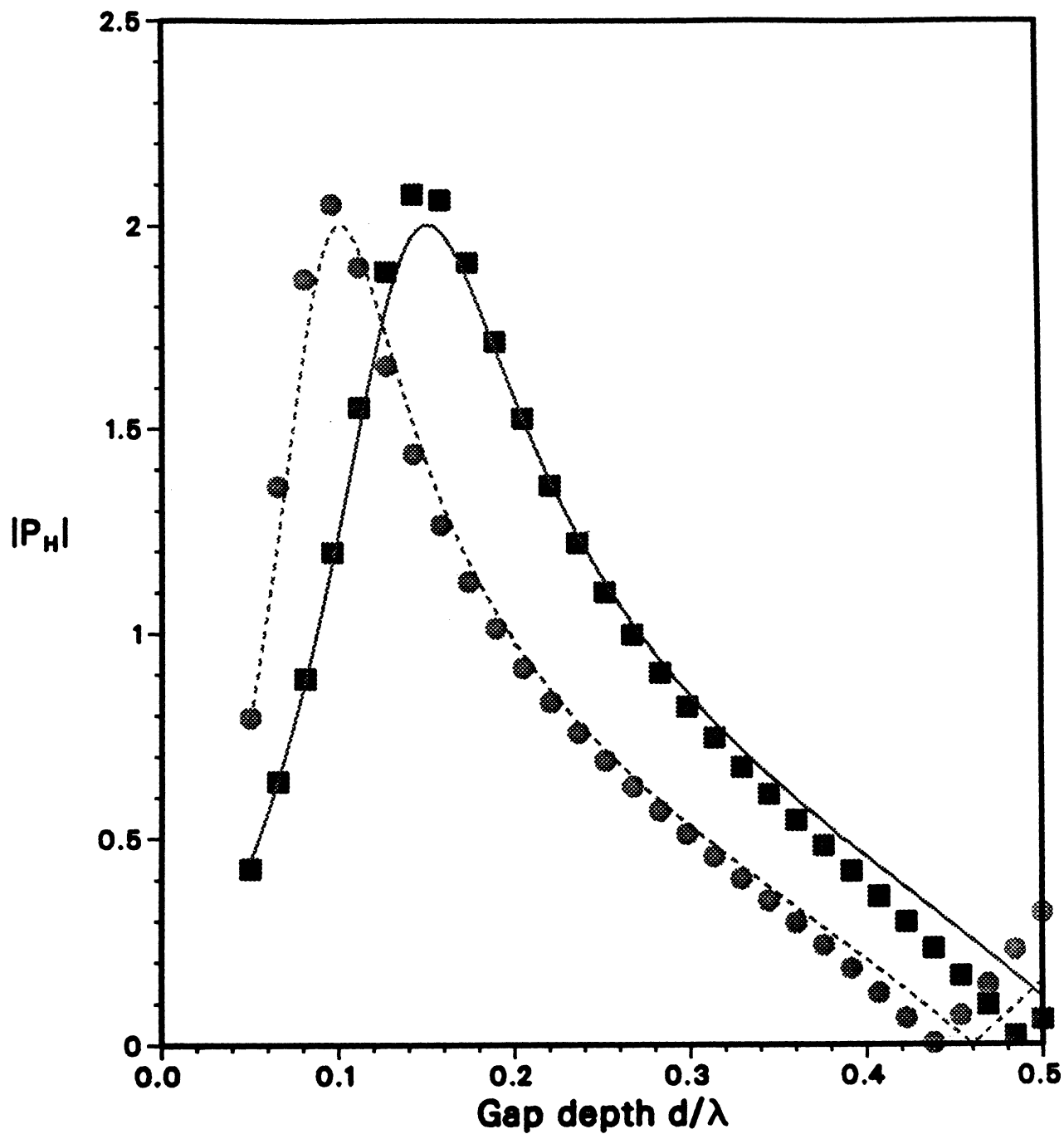


Fig. 8(b). Modulus of the far field amplitude, P_H , for an air-filled L-shaped gap of varying depth $d_1 + d_2 = d$ with $\phi = \phi_0 = \pi/2$, $w/\lambda = 0.15$, and $d_1/d_2 = 1$:

$w_2/\lambda = 0.05$ ■ exact, — analytical
 $w_2/\lambda = 0.15$ ● exact, - - - analytical.

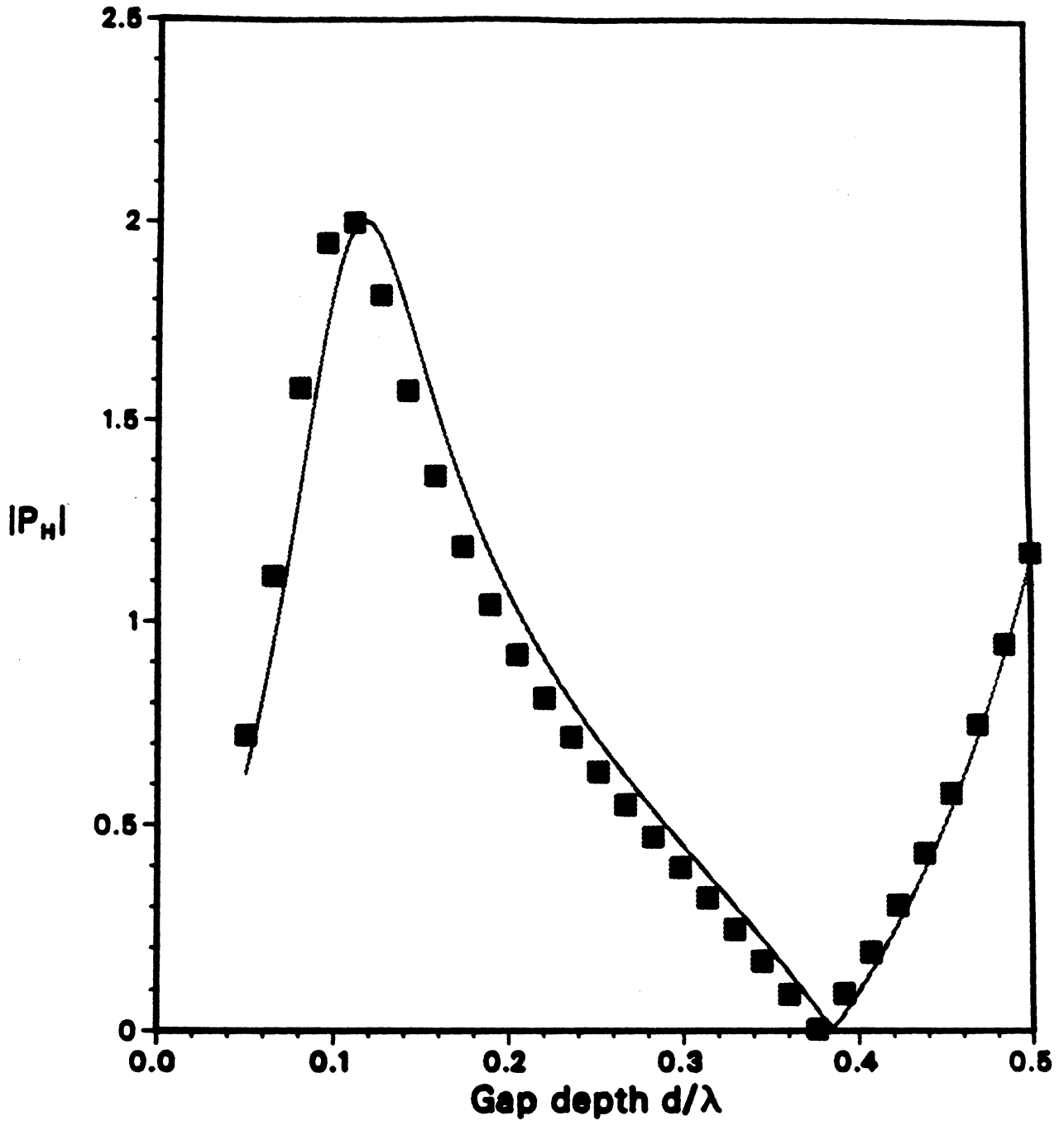


Fig. 9(a). Modulus of the far field amplitude P_H for an air-filled T-shaped gap of varying depth $d_1 + d_2 = d$ with $\phi = \phi_0 = \pi/2$, $w/\lambda = 0.15$, $w_2/\lambda = w_3/\lambda = 0.075$, and $d_1/d_2 = 3$: ■ exact, — analytical.

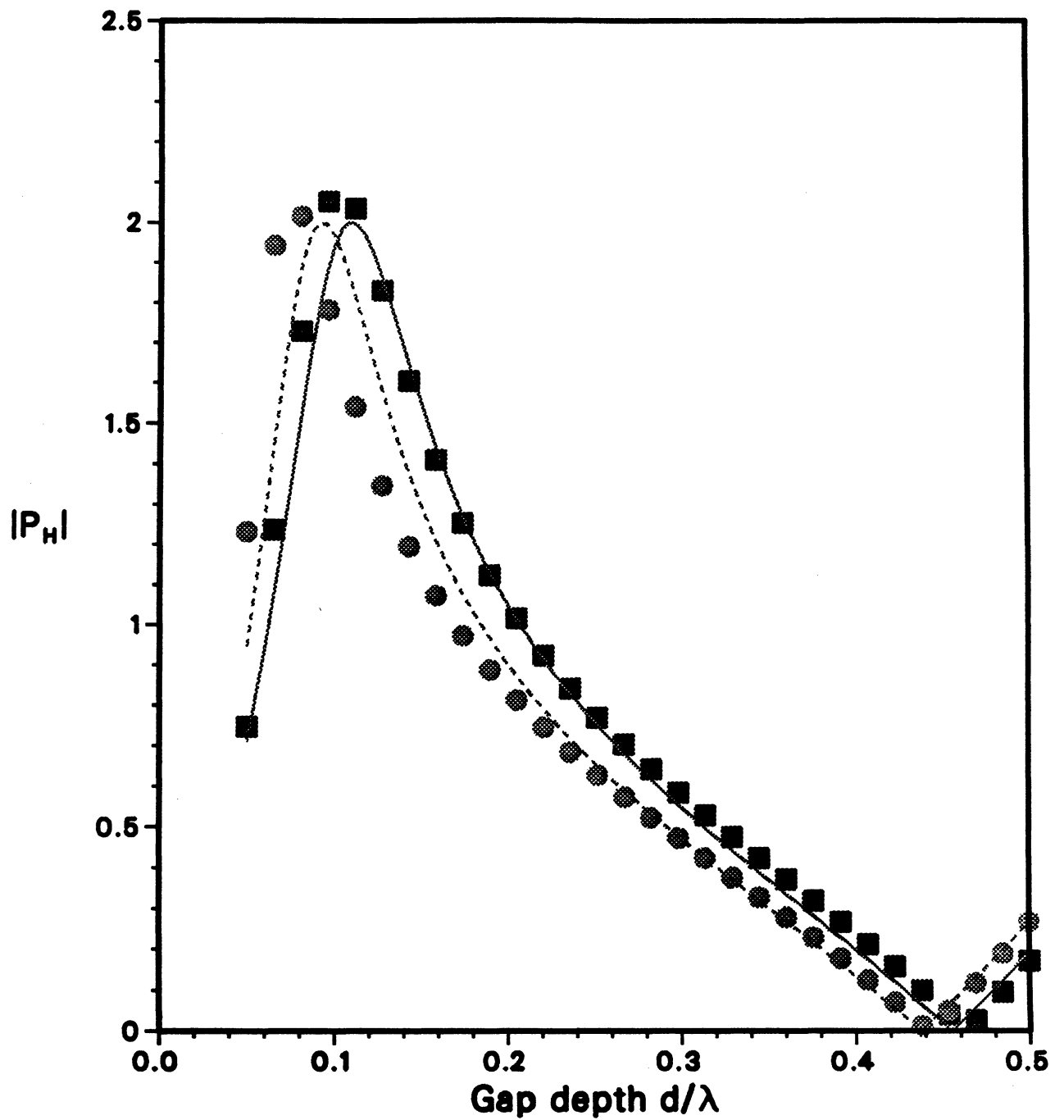


Fig. 9(b). Modulus of the far field amplitude, P_H , for an air-filled T-shaped gap of varying depth $d_1 + d_2 = d$ with $\phi = \phi_0 = \pi/2$, $w/\lambda = 0.15$, and $d_1/d_2 = 1$:

$$w_2/\lambda = w_3/\lambda = 0.025$$

■ exact, — analytical

$$w_2/\lambda = w_3/\lambda = 0.075$$

● exact, - - - analytical.

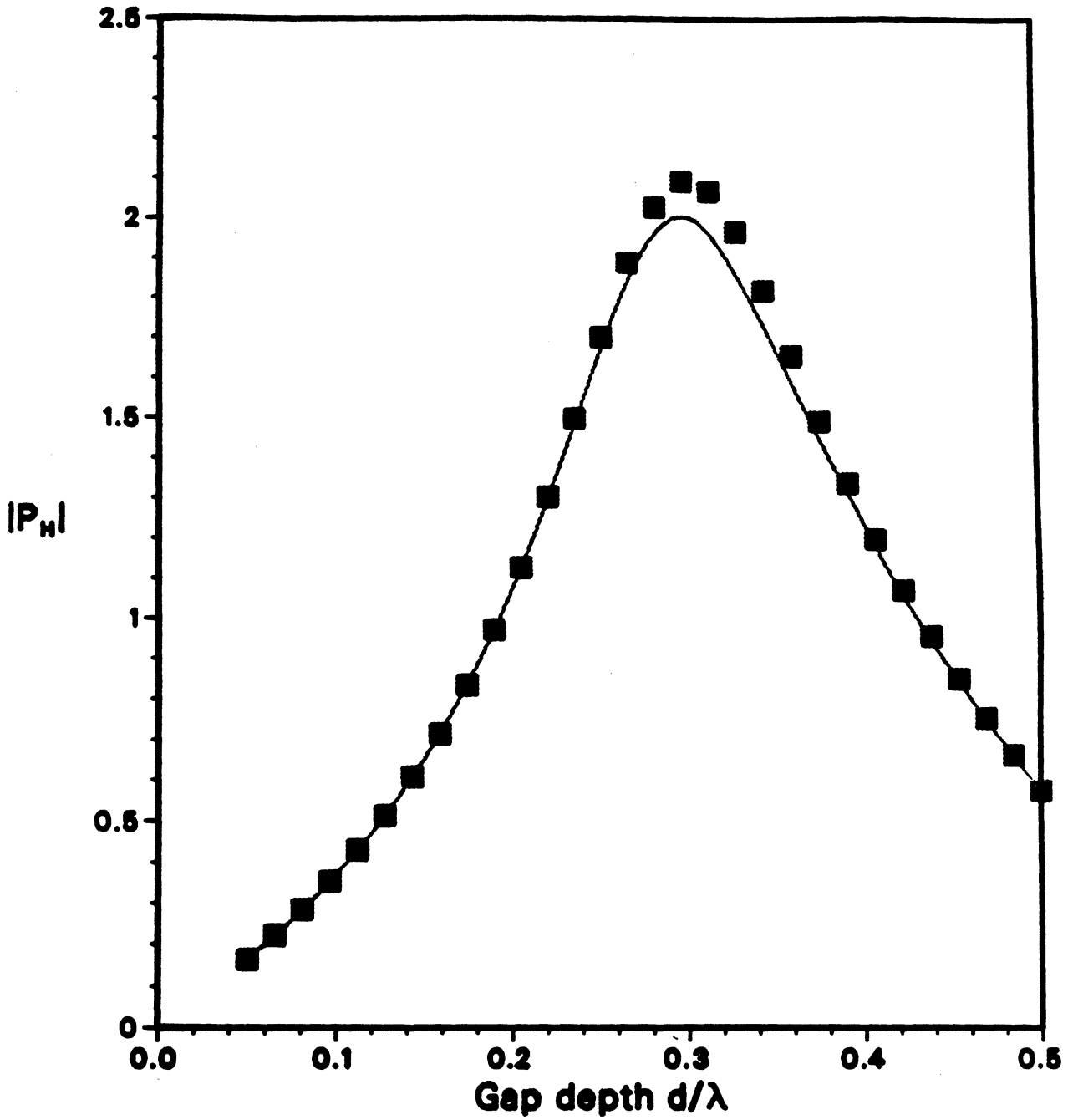


Fig. 10. Modulus of the far field amplitude P_H for an air-filled V-shaped gap of varying depth $d_1 = d$ with $\phi = \phi_0 = \pi/2$ and $w/\lambda = 0.15$:
 ■ exact, — analytical.

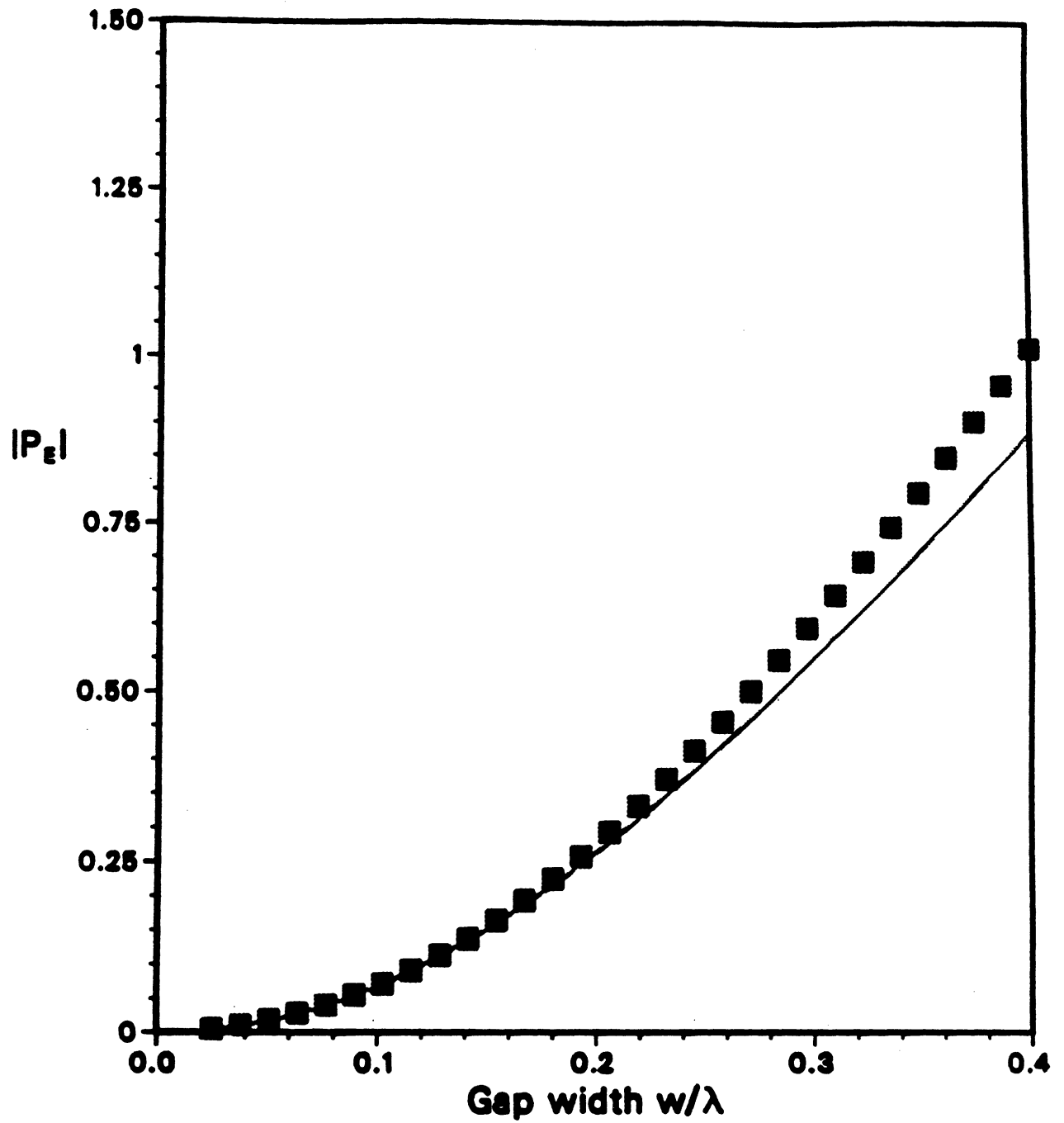


Fig. 11. Modulus of the far field amplitude P_E for an air-filled rectangular gap of varying width with $\phi = \phi_0 = \pi/2$ and $d/\lambda = 0.1$: ■ exact, — analytical

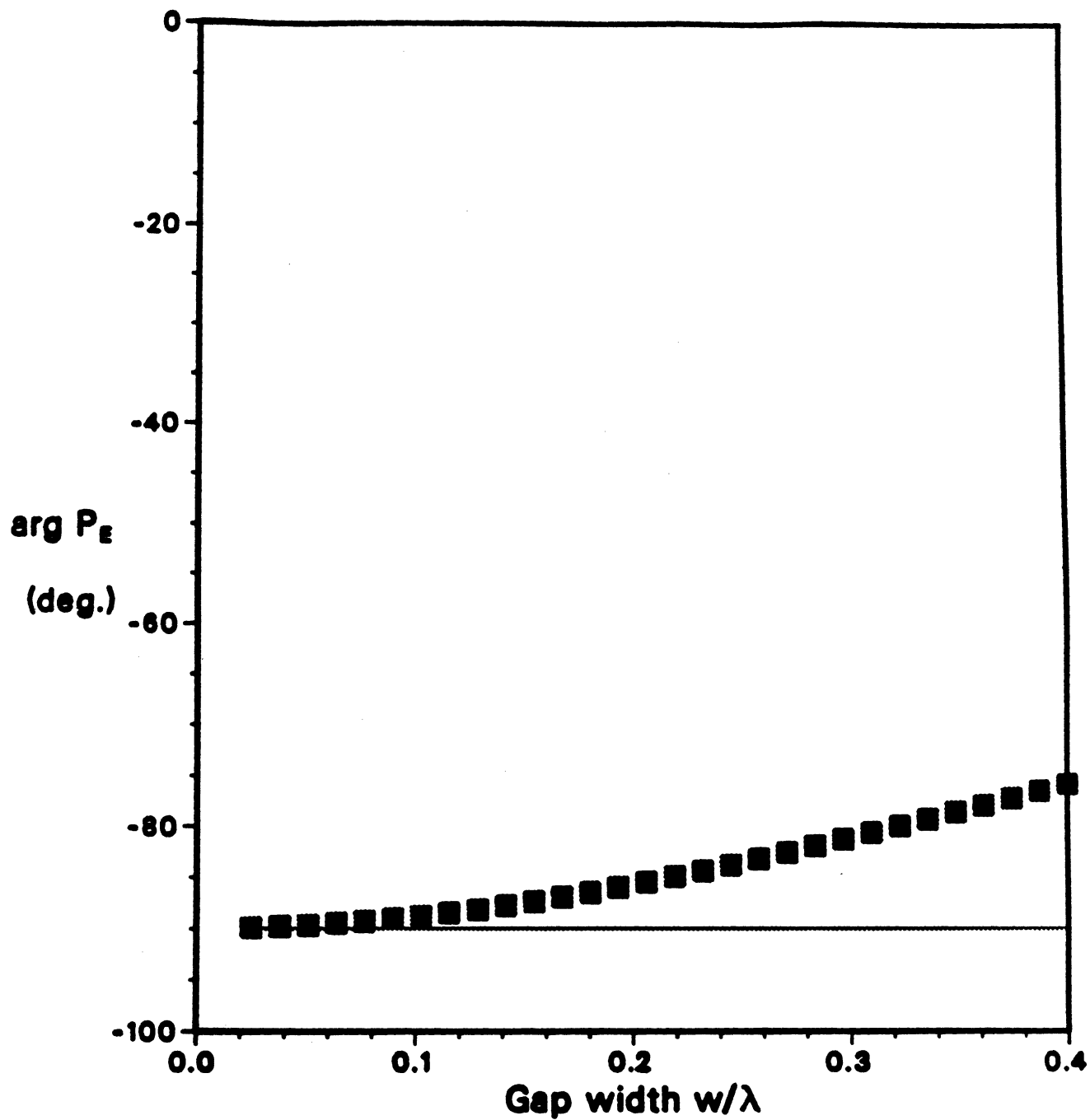


Fig. 12. Argument of the far field amplitude P_E for an air-filled rectangular gap of varying width with $\phi = \phi_0 = \pi/2$ and $d/\lambda = 0.1$: ■ exact, — analytical.

For a rectangular gap with $w/\lambda = 0.15$, the quasi-analytic and exact results for $\left| P_E \left(\frac{\pi}{2}, \frac{\pi}{2} \right) \right|$ as a function of d/λ are presented in Figure 13. The agreement is excellent, and as a consequence of the mode attenuation, the scattering is independent of the depth for $d/\lambda \geq 0.15$. A similar comparison for a triangular gap is given in Figure 14.

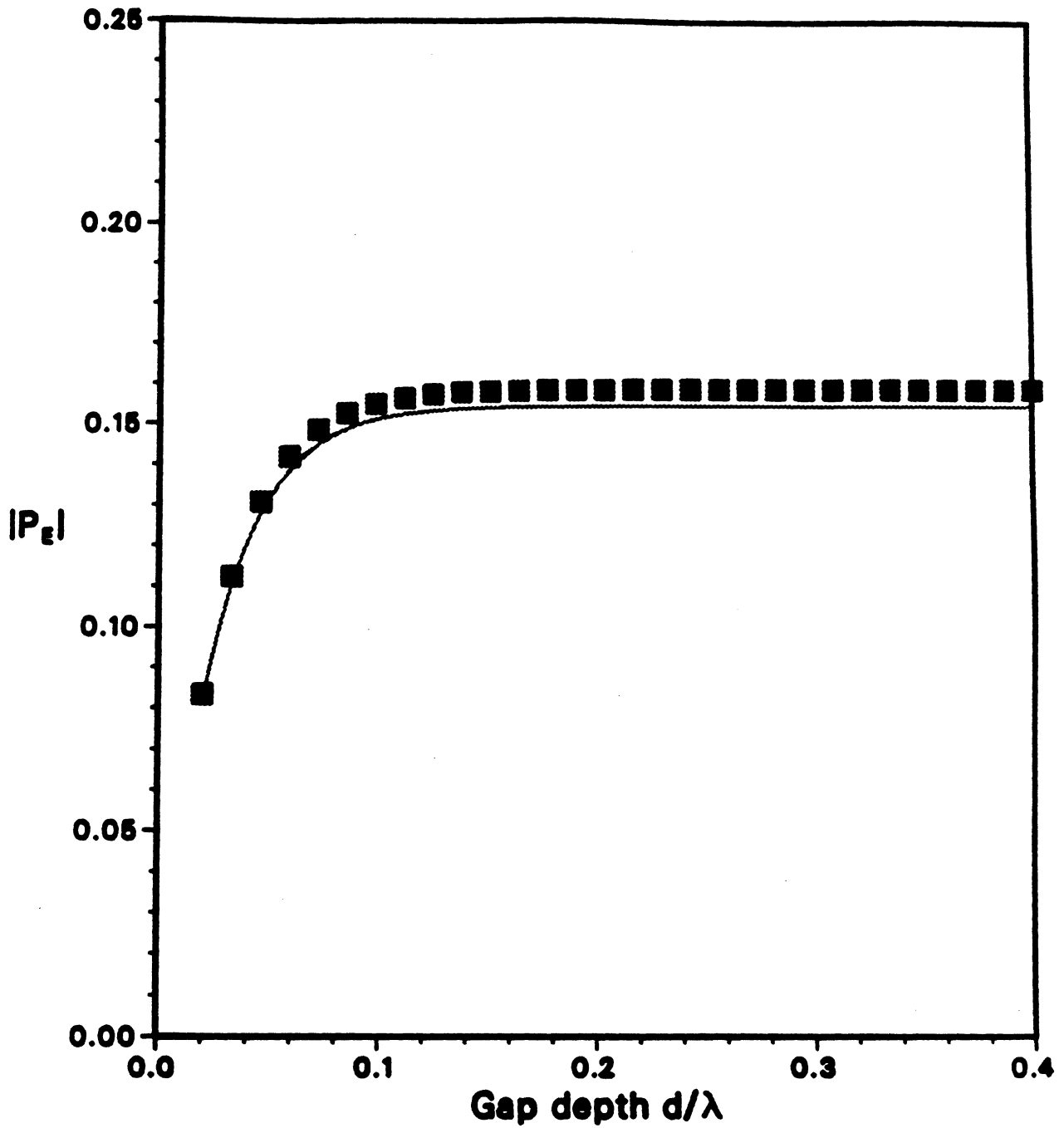


Fig. 13. Modulus of the far field amplitude P_E for an air-filled rectangular gap of varying depth $d_1 = d$ with $\phi = \phi_0 = \pi/2$ and $w/\lambda = 0.15$:
 ■ exact, — analytical.

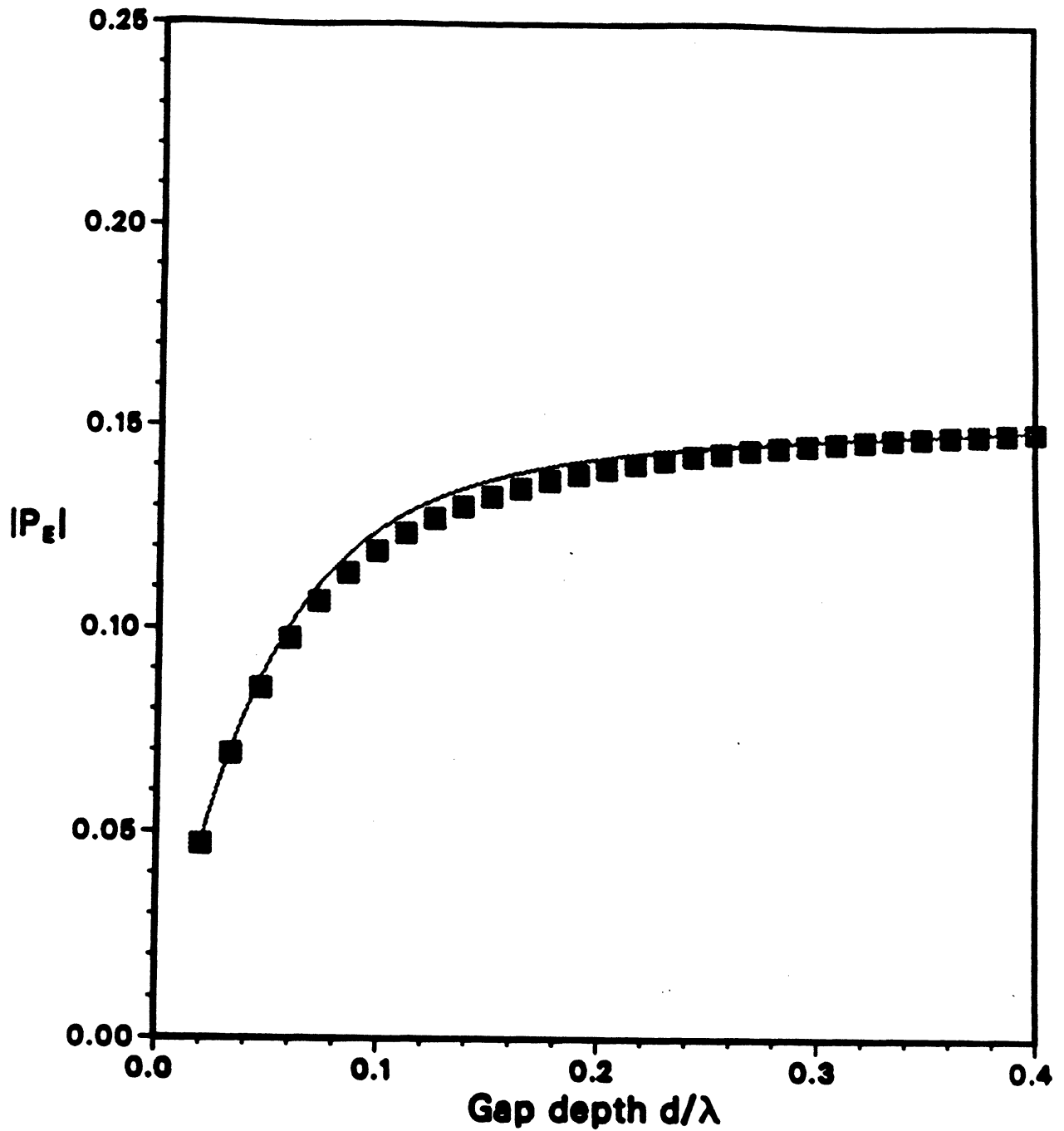


Fig. 14. Modulus of the far field amplitude P_E for an air-filled V-shaped gap of varying depth $d_1 = d$ with $\phi = \phi_0 = \pi/2$ and $w/\lambda = 0.15$:
 ■ exact, — analytical.

5. Conclusions

The quasi-analytic method described in [1] is based on the low frequency solution of the integral equations for a constant impedance insert in a perfectly conducting plane, and when used in conjunction with an estimate of the impedance looking into a gap, it provides a simple approximation to the far field scattering from the gap. To determine its accuracy, we have analyzed the problem of a plane wave incident on a gap backed by a cavity of arbitrary shape. The equivalence principle was used to develop coupled integral equations for the induced electric and magnetic currents, and the equations were then solved by the moment method. When the impedance looking into the cavity was determined using a transmission line model, it was found that for gap widths $w/\lambda \leq 0.15$ the quasi-analytic and moment method results for the scattered field were in excellent agreement for both polarizations and for all gap configurations that were tested. It therefore appears that the quasi-analytic method is an efficient and effective tool for predicting the scattering from the junction where two component parts of a target come together.

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- [4] G.N. Watson, "A Treatise on the Theory of Bessel Functions," Cambridge Univ. Press, Cambridge, 1948, p. 77.
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Appendix A Moment Method Solution of the Coupled Integral Equations

The integral equation pairs given by (7), (11) and (17), (18) are solved by the moment method. Using pulse basis functions in the moment method, the aperture A and the cavity walls S of Figure 1 are segmented into N cells of size Δs . The magnetic and electric currents are assumed to be constant over each of these segments. When the integrations of the coupled equations are taken over each segment, the current expressions can be removed as constants from the integrals. With the contour of integration discretized, the (x',y') coordinates become (x_i,y_i) , $i = 1, \dots, N$, which describe the location of each of the segments. The Hankel functions can then be expressed in terms of rotated coordinates (s,n) for the observation position and (s_i,n_i) for each segment or source position since the integration is with respect to the tangential vector \hat{s} as shown in Figure 1.

The expressions for the numerical solution of the coupled equations are developed in the following sections for the H- and E-polarization cases. Applying point matching, the magnetic and electric currents in the aperture and on the cavity walls are determined, and the far field amplitude is calculated.

A.1 H-Polarization

For the discretized contour of integration, (7) and (11) become

$$J_s(s,n) = \frac{kY}{2} \epsilon_r \sum_{i=1}^M J_z^*(s_i) \int_{\Delta s_i} H_0^{(1)} \left(k_1 \sqrt{(s-s_i)^2 + n^2} \right) ds_i \\ + \frac{ik_1}{2} \sum_{i=1}^N J_s(s_i,n_i) \int_{\Delta s_i} \sin \gamma_i H_1^{(1)} \left(k_1 \sqrt{(s-s_i)^2 + (n-n_i)^2} \right) ds_i \quad (A.1)$$

$$J_s(s) = 2e^{-iks \cos \phi_0} - \frac{kY}{2} \sum_{i=1}^M J_z(s_i) \int_{\Delta s_i} H_o^{(1)}(k|s-s_i|) ds_i \quad (A.2)$$

where M are the number of segments across the aperture and

$$\sin \gamma_i = \frac{(n-n_i)}{\sqrt{(s-s_i)^2 + (n-n_i)^2}} \quad (A.3)$$

Applying point matching over the N segments of the aperture and cavity walls,

$$\sum_{i=1}^N l_i \left[1 \Big|_{j=i} + \frac{ik_1}{2} \int_{\Delta s_i} \sin \gamma_{j,i} H_1^{(1)}(k_1 R_{j,i}) ds_i \right] + \frac{kY}{2} \epsilon_r \sum_{i=N+1}^{N+M} l_i \int_{\Delta s_i} H_o^{(1)}(k_1 R_{j,i}) ds_i = 0 \quad j = 1, \dots, N \quad (A.4)$$

$$\sum_{i=N+1}^{N+M} l_i \left[1 \Big|_{j=i} + \frac{kY}{2} \int_{\Delta s_i} H_o^{(1)}(k R_{j,i}) ds_i \right] = 2e^{-iks_j \cos \phi_0} \quad j = N+1, \dots, N+M \quad (A.5)$$

where

$$R_{j,i} = \sqrt{(s_j - s_i)^2 + (n_j - n_i)^2} \quad (A.6)$$

The coordinate (s_j, n_j) is the observation position at the midpoint of the j^{th} segment. Hence, for $i, j = 1, \dots, M, N+1, \dots, N+M$, the segments are located in the aperture, and for $i, j = M+1, \dots, N$, the segments are located on the cavity walls. l_i

in (A.4) and (A.5) are the electric currents, for $i = 1, \dots, N$, and the magnetic currents, $i = N+1, \dots, N+M$, to be determined.

In matrix form, (A.4) and (A.5) become

$$[Z_{j,i}] [I_i] = [V_j] \quad (\text{A.7})$$

The impedance matrix is given as

$$[Z_{j,i}] = \begin{bmatrix} Z_{e1} & \vdots & Z_{m1} \\ \dots & \vdots & \dots \\ Z_{e2} & \vdots & Z_{m2} \end{bmatrix} \quad (\text{A.8})$$

where the sets of elements are as follows:

$$Z_{e1} = \begin{cases} \frac{ik_1}{2} \int_{\Delta s_i} \sin \gamma_{j,i} H_1^{(1)}(k_1 R_{j,i}) ds_i & j \neq i \\ -1 & j = i \end{cases} \quad (\text{A.9})$$

for $i = 1, \dots, N$ and $j = 1, \dots, N$;

$$Z_{m1} = \begin{cases} \frac{kY}{2} \epsilon_r \int_{\Delta s_i} H_0^{(1)}(k_1 R_{j,i}) ds_i & j \neq i-N \\ \frac{kY}{2} \epsilon_r \left\{ \frac{i2}{\pi} \left[2(s_i - s_j) \ln(R_{j,i}) - (2 - A'(k_1)) (s_i - s_j) \right] \right\} & j = i-N \end{cases} \quad (\text{A.10})$$

for $i = N+1, \dots, N+M$ and $j = 1, \dots, N$;

$$Z_{e2} = \begin{cases} 0 & j \neq i+N \\ 1 & j = i+N \end{cases} \quad (\text{A.11})$$

for $i = 1, \dots, N$ and $j = N+1, \dots, N+M$;

$$Z_{m2} = \begin{cases} \frac{kY}{2} \int_{\Delta s_i} H_o^{(1)}(k R_{j,i}) ds_i & j \neq i \\ \frac{kY}{2} \left\{ \frac{i2}{\pi} \left[2(s_i - s_j) \ln(R_{j,i}) - (2 - A'(k)) (s_i - s_j) \right] \right\} & j = i \end{cases} \quad (\text{A.12})$$

for $i = N+1, \dots, N+M$ and $j = N+1, \dots, N+M$. In (A.10), the expression for A' is

$$A'(k_1) = 2 \left(\ln \frac{k_1}{2} + \gamma - i \frac{\pi}{2} \right) .$$

In (A.12), A' is a function of k . For the self-cells in (A.10) and (A.12), s_i is taken to be the endpoint of the i^{th} segment. The self-cell expressions were derived analytically, and a numerical integration is applied to the other segments.

In the case of the V-shaped gap, the adjacent cells needed to be evaluated in the vicinity of $y = -d$, for $R_{j,i}$ less than one cell size. The analytical expressions for the impedance elements of the adjacent cells are

$$Z_{e1} = \frac{i}{2} \left[-\frac{k_1^2}{2} (n_j - n_i) s_i + \frac{i2}{\pi} \frac{(n_j - n_i)}{|n_j - n_i|} \operatorname{atan} \left(\frac{s_i - s_j}{|n_j - n_i|} \right) \right] \quad i = j \pm 1 \quad (\text{A.13})$$

$$Z_{m1} = \frac{kY}{2} \epsilon_r \frac{i}{\pi} \left[2(s_i - s_j) \ln(R_{j,i}) - (2 - A'(k_1)) s_i + 2|n_j - n_i| \operatorname{atan} \left(\frac{s_i - s_j}{|n_j - n_i|} \right) \right]$$

$$i - N = j \pm 1 \quad (\text{A.14})$$

where s_i is evaluated at the endpoints of the i^{th} segment. The adjacent cell expression for Z_{m2} is given by (A.14) with $A'(k_1)$ replaced with $A'(k)$ for $i = j \pm 1$.

The source matrix is given by

$$V_j = \begin{cases} 0 & j = 1, \dots, N \\ 2e^{-iks_j \cos \phi_0} & j = N+1, \dots, N+M \end{cases} \quad (\text{A.15})$$

The currents I_j are determined by solving (A.7), given that $[Z_{j,i}]$ is nonsingular.

The aperture impedance is defined in terms of the total fields as

$$\eta_j = \frac{E_x(x_j, 0)}{H_z(x_j, 0)}$$

where the total electric field is equal to the magnetic current in the aperture, I_j for $j = N+1, \dots, N+M$, and from (4), the total magnetic field is now expressed as

$$H_z(x_j, 0) = 2e^{-ikx_j \cos \phi_0} - \frac{kY}{2} \sum_{i=N+1}^{N+M} I_i \int_{\Delta x_i} H_o^{(1)}(k|x_j - x_i|) dx_i \quad (\text{A.16})$$

for $j = N+1, \dots, N+M$. From (3), the far field amplitude at the angle ϕ is now

$$P_H(\phi, \phi_0) = -\frac{kY}{2} \sum_{i=N+1}^{N+M} I_i \int_{\Delta x_i} e^{-ikx_i \cos\phi} dx_i . \quad (\text{A.17})$$

A.2 E-Polarization

The integral equation pair given by (17) and (18) was solved in the same manner as described for the H-polarization case. The elements of the impedance matrix defined in (A.8) for the E-pol case are as follows:

$$Z_{e1} = \begin{cases} \frac{kZ}{2} \mu_r \int_{\Delta s_i} H_0^{(1)}(k_1 R_{j,i}) ds_i & j \neq i \\ 1 & j = i \end{cases} \quad (\text{A.18})$$

for $i = 1, \dots, N$ and $j = 1, \dots, N$;

$$Z_{m1} = \begin{cases} -\frac{ik_1}{2} \int_{\Delta s_i} \frac{y_j}{R_{j,i}} H_1^{(1)}(k_1 R_{j,i}) ds_i & j \neq i-N \\ -1 & j = i-N \end{cases} \quad (\text{A.19})$$

for $i = N+1, \dots, N+M$ and $j = 1, \dots, N$;

$$Z_{e2} = \begin{cases} 0 & j \neq i+N \\ -1 & j = i+N \end{cases} \quad (\text{A.20})$$

for $i = 1, \dots, N$ and $j = N+1, \dots, N+M$;

$$Z_{m2} = \begin{cases} -\frac{kY}{2} \int_{\Delta s_i} \frac{1}{k R_{j,i}} H_1^{(1)}(k R_{j,i}) ds_i & j \neq i \\ -\frac{kY}{2} \left\{ \frac{i2}{\pi} \left[2(s_i - s_j) \ln(R_{j,i}) - (2 - A'(k)) (s_i - s_j) \right] - \frac{2}{k} H_1^{(1)}(k |s_i - s_j|) \right\} & j = i \end{cases} \quad (\text{A.21})$$

for $i = N+1, \dots, N+M$ and $j = N+1, \dots, N+M$. As for the H-polarization case, in the self-cell expressions, s_i is evaluated at the endpoint of the i^{th} segment.

Because of the sensitivity of the impedance element Z_{m2} to the $1/R_{j,i}$ term for segments near the self-cell, the adjacent cells needed to be evaluated analytically, as follows:

$$Z_{m2} = \frac{kY}{2} \frac{i}{\pi} \left\{ \frac{8}{3k^2 \Delta s_i} + \left[2(s_i - s_j) \ln(R_{j,i}) - (2 - A'(k))s_i + 2|n_j - n_i| \operatorname{atan}\left(\frac{s_i - s_j}{|n_j - n_i|}\right) \right] \right\} \quad (\text{A.22})$$

for $i = j \pm 1$, where s_i is evaluated over the i^{th} segment.

The source matrix is given by

$$V_j = \begin{cases} 0 & j = 1, \dots, N \\ 2Y \sin \phi_0 e^{-iks_j \cos \phi_0} & j = N+1, \dots, N+M \end{cases} \quad (\text{A.23})$$

Given that $[Z_{j,i}]$ is nonsingular, the currents I_i can be calculated.

The aperture impedance for the E-polarization case is defined as

$$\eta_j = \frac{E_z(x_j, 0)}{H_x(x_j, 0)}$$

where the total electric field is equal to the magnetic current in the aperture, I_j for $j = N+1, \dots, N+M$, and from (13), the total magnetic field in the aperture is now expressed as

$$H_x(x_j, 0) = -2Y \sin\phi_o e^{-ikx_j \cos\phi_o} + \frac{kY}{2} \sum_{i=N+1}^{N+M} I_i \int_{\Delta x_i} \frac{1}{k|x_j - x_i|} H_1^{(1)}(k|x_j - x_i|) dx_i \quad (\text{A.24})$$

for $j = N+1, \dots, N+M$. From (12), the far field amplitude at the specified angle ϕ is now

$$P_E(\phi, \phi_o) = -\frac{k}{2} \sin\phi \sum_{i=N+1}^{N+M} I_i \int_{\Delta x_i} e^{-ikx_i \cos\phi} dx_i \quad (\text{A.25})$$

A.3 Program Listing

The expressions for the impedance and source matrices, the aperture impedance, and the far field amplitude were programmed for solution, as shown in the program listing of GAPSCAT.FTN below. The subroutines used in the program are contained in the file GAPSUB.FTN listed below also.

In running the program, the user is prompted for the polarization of the incident field, angle of incidence, angle of far field observation, and the relative permittivity ϵ_r of the gap cavity. For the relative permeability, it is assumed that $\mu_r = 1$, although this need not be the case. A menu is provided for the choice

of shapes as shown in Figure 2. The dimensions are requested according to those defined in Figure 2. An arbitrary shaped gap may also be evaluated by specifying the coordinates of its corner points. The user is also prompted for the maximum segment size Δs_i to be used for the pulse basis functions. A segment size of $\Delta s_i/\lambda = 0.01$ was used for the results of Figures 3 to 14.

The impedance matrix $[Z_{j,i}]$ is solved for the H- or E-polarization case using the expressions (A.9) to (A.14) or (A.18) to (A.22), respectively. The numerical integration is done for the appropriate segments using Simpson's three-point composite integration over each segment. With the source matrix $[V_j]$ calculated from (A.15) or (A.23), the electric and magnetic currents contained in $[I_j]$ can then be determined. As listed, the program calculates the far field amplitude as a function of the gap depth using (A.17) for H-polarization or (A.23) for E-polarization, where the number of iterations is specified. For one iteration, the program also outputs the aperture impedance calculated from the total fields in the aperture.


```

c...Prompting user for input data
call gaprom(iprg)

if(EorH .eq. 1) Epol=.true.
phio=phio*pi/180.0
phi=phi*pi/180.0
drat=dStp(1)/d
kl=k*csqrt(er)
A=2*(clog(kl/2)+gam-ci*pi/2)
if(aImag(er) .ne. 0.0) Lossy=.true.

dmin=0.025
if(Epol) dmin=0.025
dmax=d
if(noIter .ne. 1)then
  dstep=(dmax-dmin)/(noIter-1)
  d=dmin
endif
DO 700 iter=1,noIter

c...Determining coordinates of corner points given gap type
if(igap .eq. 1)then
c RECTANGULAR
  noS=3
  q(3,1)=w/2
  q(3,2)=-d
  q(4,1)=-w/2
  q(4,2)=-d
  else if(igap .eq. 2)then
c L-SHAPED
  noS=7
  dStp(1)=d*drat
  dStp(2)=d*(1-drat)
  q(3,1)=w/2
  q(3,2)=-dStp(1)
  q(8,1)=-w/2
  q(8,2)=-dStp(1)
  q(4,1)=w/2+wStp(2)
  q(4,2)=-dStp(1)
  q(7,1)=-w/2-wStp(3)
  q(7,2)=q(4,2)
  q(5,1)=q(4,1)
  q(5,2)=q(4,2)-dStp(2)
  q(6,1)=q(7,1)
  q(6,2)=q(5,2)
  else if(igap .eq. 3)then
c V-SHAPED
  noS=2
  q(3,1)=0.0
  q(3,2)=-d
  adj=0.75*maxC
  else if(igap .eq. 4)then
c T-SHAPED
  noS=5
  dStp(1)=d*drat
  dStp(2)=d*(1-drat)
  q(3,1)=w/2
  q(3,2)=-dStp(1)
  q(4,1)=w/2+wStp(2)
  q(4,2)=-dStp(1)
  q(5,1)=q(4,1)
  q(5,2)=q(4,2)-dStp(2)
  q(6,1)=-w/2
  q(6,2)=q(5,2)
endif
c...Corner points of gap at y=0
q(1,1)=-w/2
q(1,2)=0.0
q(2,1)=w/2
q(2,2)=0.0
q(noS+2,1)=-w/2
q(noS+2,2)=0.0

c*****
c***** Current segment locations (xl,yi) *****
c*****
N=0
do 175 l=1,noS+1
c...Size (length) of lth side of gap
szSd(l)=sqrt((q(l+1,1)-q(l,1))**2
+ (q(l+1,2)-q(l,2))**2)
c...Angle of rotation for each side with respect to x axis
if(q(l+1,1) .lt. q(l,1))then
  psi(l)=asin((q(l,2)-q(l+1,2))/szSd(l))
  neg(l)=.true.
else
  psi(l)=asin((q(l+1,2)-q(l,2))/szSd(l))
  neg(l)=.false.
endif

szN(l)=int(szSd(l)/maxC)+1
N=N+szN(l)
spaceX=(q(l+1,1)-q(l,1))/szN(l)
spaceY=(q(l+1,2)-q(l,2))/szN(l)
posiX=q(l,1)
posiY=q(l,2)

```

```

c...ENDPOINTS of each segment are p, MIDPOINTS are m in (x,y)
c  coordinates
      do 170 i=N-szN(1)+1,N
        p(i,1)=posiX
        p(i,2)=posiY
        m(i,1)=posiX+spaceX/2.0
        m(i,2)=posiY+spaceY/2.0
        posiX=posiX+spaceX
        posiY=posiY+spaceY
170    continue
175    continue
        p(N+1,1)=-w/2
        p(N+1,2)=0.0
c...Number of segments in the aperture
      gN=szN(1)
c...Number of current coefficients to be calculated
      NgN=N+gN
      print *, ' d = ',d,' N = ',N,' gN = ',gN
c...Initializing matrices to zero
      do 190 j=1,NgN
        do 180 i=1,NgN
          Z(j,i)=czero
180    continue
          Vj(j)=czero
190    continue

c*****
c***** Impedance, Source, *****
c***** and Current Matrices *****
c*****

C
C  VARIABLES:
C  H0o,H0 Hankel function of zero order in free
C         space and in material er, respectively.
C  H1o,H1 Hankel function of first order in free
C         space and in material er, respectively.
C  Green's Function integrals:
C  LH0 Integral of H0.
C  LH1 Integral of H1 for H-pol, of dH1/dy for
C         E-pol.
C  LH2 Integral of H0o for H-pol, of dH1o/dy
C         for E-pol.
C  aLH0 Analytical integral of H0o for evaluation
C        of adjacent cells for LH2, E-pol case.

C
C  The integration is done one side at a time, for j=1,...,N,
C  in the clockwise direction, starting at (x,y)=(-w/2,0).
C
      istsart=1
      istop=szN(1)
c...Source point is i of the lth side, observation point is j
      do 230 l=1,noS+1
        do 220 i=istsart,istop
          do 210 j=1,N
c          Coordinate rotation for observation point
            sj=m(j,1)*cos(psi(1))+m(j,2)*sin(psi(1))
            nj=m(j,1)*sin(psi(1))-m(j,2)*cos(psi(1))
            if(neg(1))then
              sj=-sj
              nj=-nj
            endif
c...Integration over ith segment
            LH0=czero
            LH1=czero
            LH2=czero
            aLH0=czero
c  Magnitude between midpoints Rm=|r-r'|
            Rm=sqrt((m(j,1)-m(i,1))**2+(m(j,2)-m(i,2))**2)
            if(j .eq. i .or. Rm .le. adj)then
c  SMALL ARGUMENT APPROXIMATION integral for self-cell
c  and adjacent cells
              do 200 ip=i+1,i,-1
c              Coordinate rotation for source segment points
                si=p(ip,1)*cos(psi(1))+p(ip,2)*sin(psi(1))
                ni=p(ip,1)*sin(psi(1))-p(ip,2)*cos(psi(1))
                if(neg(1))then
                  si=-si
                  ni=-ni
                endif
                R=sqrt((sj-si)**2+(nj-ni)**2)
                if(j .eq. i .or. abs(nj-ni) .eq. 0.0)then
                  tanf=pi/2
                  absf=1.0
                else
                  tanf=atan((si-sj)/abs(nj-ni))
                  absf=abs(nj-ni)
                endif
                LH1=-k1**2/2*(nj-ni)*si
                & +ci*2./pi*(nj-ni)/absf*tanf-LH1
                LH0=ci/pi*(2*(si-sj)*log(R)
                & -(2-A)*si+2.0*abs(nj-ni)*tanf)-LH0
                LH2=ci/pi*(2*(si-sj)*log(R)
                & -(2-Ao)*si+2.0*abs(nj-ni)*tanf)-LH2
                if(j .eq. i) GOTO 202
          enddo
        enddo
      enddo

```

```

200     continue
202     if(j .eq. i) then
        LH0=2*(LH0+ci/pi*(2-A)*sj)
        LH2=2*(LH2+ci/pi*(2-Ao)*sj)
        if(Epol) then
            krho=k*abs(sj-si)
            call Hankz1(krho,1,H0,H1)
            LH2=LH2-2./k*H1
        endif
    endif
    else
c     SIMPSON'S THREE POINT COMPOSITE INTEGRATION
        do 204 ip=i+1,i,-1
c         Coordinate rotation for source segment endpoints
            si=p(ip,1)*cos(psi(1))+p(ip,2)*sin(psi(1))
            ni=p(ip,1)*sin(psi(1))-p(ip,2)*cos(psi(1))
            if(neg(1)) then
                si=-si
                ni=-ni
            endif
            stepS=si
c         HANKEL FUNCTION evaluation at endpoints of segment
            R=sqrt((sj-si)**2+(nj-ni)**2)
            if(Lossy) then
                ckrho=k1*R
                call cHank(ckrho,2,H0,H1)
            else
                krho=Real(k1)*R
                call Hankz1(krho,2,H0,H1)
            endif
            krho=k*R
            call Hankz1(krho,2,H0o,H1o)

            LH0=H0+LH0
            if(Epol) then
                LH1=k1*m(j,2)/R*H1+LH1
                if(j .eq. (i-1) .or. j .eq. (i+1)) then
                    if(abs(nj-ni) .eq. 0.0) then
                        tanf=pi/2
                        absf=1.0
                    else
                        tanf=atan((si-sj)/abs(nj-ni))
                        absf=abs(nj-ni)
                    endif
                    aLH0=ci/pi*(2*(si-sj)*log(R)
                    &      -(2.0-Ao)*si+2.0*abs(nj-ni)*tanf)-aLH0
                else
                    LH2=H1o/k/R+LH2
                endif
            else
                LH1=k1*(nj-ni)/R*H1+LH1
                LH2=H0o+LH2
            endif
204     continue

c         Coordinate rotation for source segment midpoints
            si=m(i,1)*cos(psi(1))+m(i,2)*sin(psi(1))
            ni=m(i,1)*sin(psi(1))-m(i,2)*cos(psi(1))
            if(neg(1)) then
                si=-si
                ni=-ni
            endif
            stepS=abs(stepS-si)
            DelS=2*stepS
c         HANKEL FUNCTION evaluation at midpoint of segment
            R=sqrt((sj-si)**2+(nj-ni)**2)
            if(Lossy) then
                ckrho=k1*R
                call cHank(ckrho,2,H0,H1)
            else
                krho=Real(k1)*R
                call Hankz1(krho,2,H0,H1)
            endif
            krho=k*R
            call Hankz1(krho,2,H0o,H1o)
c         GREEN'S FUNCTION INTEGRALS
            LH0=stepS/3*(4*H0+LH0)
            if(Epol) then
                LH1=stepS/3*(4*k1*m(j,2)/R*H1+LH1)
                if(j .eq. (i-1) .or. j .eq. (i+1)) then
                    LH2=-ci*8./3/pi/k**2/(DelS)-aLH0
                else
                    LH2=stepS/3*(4*H1o/k/R+LH2)
                endif
            else
                LH1=stepS/3*(4*k1*(nj-ni)/R*H1+LH1)
                LH2=stepS/3*(4*H0o+LH2)
            endif
            endif
            if(i .ne. j .and. Rm .le. adj) then
                LH0=-LH0
            endif
c         if(Epol) then
c         E-POL IMPEDANCE MATRIX
            Z(j,i)=k*Zo*ur/2*LH0

```



```

        if(i .le. qN .and. j .ne. i)then
            Z(j,N+1)=-ci/2*LH1
        else if(i .le. qN .and. j .eq. i)then
            Z(j,N+1)=-1.
        endif

        if(j .le. qN)then
            if(j .ne. i)then
                Z(N+j,i)=czero
            else
                Z(N+j,i)=-1.
            endif
            if(i .le. qN)then
                Z(N+j,N+1)=-k*Yo/2*LH2
            endif
        endif
    else
c   H-POL IMPEDANCE MATRIX
        if(j .ne. i)then
            Z(j,i)=-ci/2*LH1
        else
            Z(j,i)=-1.
        endif
        if(i .le. qN)then
            Z(j,N+1)=k*Yo*er/2*LH0
        endif

        if(j .le. qN)then
            if(j .ne. i)then
                Z(N+j,i)=czero
            else
                Z(N+j,i)=1.
            endif
            if(i .le. qN)then
                Z(N+j,N+1)=k*Yo/2*LH2
            endif
        endif
210    continue

c...Incident Field (Source) matrix elements
        xj=m(i,1)
        yj=m(i,2)
        Vj(1)=czero
        if(i .le. qN)then
            if(Epol)then
c   E-POL INCIDENT FIELD Hx
                Vj(N+1)=2*Yo*sin(phio)*cexp(-ci*k*xj*cos(phio))
            else
c   H-POL INCIDENT FIELD Hz
                Vj(N+1)=2*cexp(-ci*k*xj*cos(phio))
            endif
        endif
220    continue
        istart=istop+1
        istop=istop+szN(1+1)
230    continue

c...Calling subroutines to calculate the current matrix
        call CGECO(Z,pn,NgN,ipvt,rc,wk)
        call CGESL(Z,pn,NgN,ipvt,Vj,0)

        print *, 'The condition number is ',rc
        do 310 i=1,NgN
c   CURRENT MATRIX
            Ii(i)=Vj(1)
310    continue

        if(noIter .eq. 1)then
c*****
c***** Aperture Impedance *****
c*****
            l=1
            do 500 j=1,qN
                Hs(j)=czero
                do 480 i=1,qN
                    sj=m(j,1)*cos(psi(1))+m(j,2)*sin(psi(1))
                    nj=m(j,1)*sin(psi(1))-m(j,2)*cos(psi(1))
                    if(neq(1))then
                        sj=-sj
                        nj=-nj
                    endif
                enddo
            enddo

c...Integration over lth segment
            LH2=czero
            aLH0=czero
            if(j .eq. 1)then
c   SMALL ARGUMENT APPROXIMATION integral for self-cell
c   and adjacent cells
                do 470 ip=i+1,i,-1
c   Coordinate rotation for source segment points
                    si=p(ip,1)*cos(psi(1))+p(ip,2)*sin(psi(1))
                    ni=p(ip,1)*sin(psi(1))-p(ip,2)*cos(psi(1))
                    if(neq(1))then
                        si=-si

```

```

        ni=-ni
    endif
    R=sqrt((sj-si)**2+(nj-ni)**2)
    if(j .eq. 1 .or. abs(nj-ni) .eq. 0.0) then
        tanf=0.0
        absf=1.0
    else
        tanf=atan((si-sj)/abs(nj-ni))
        absf=abs(nj-ni)
    endif
    LH2=ci/pi*(2*(si-sj)*log(R)
    &      -(2-Ao)*si+2.0*abs(nj-ni)*tanf)-LH2
    if(j .eq. 1) GOTO 472
470 continue
472 if(j .eq. 1) then
    LH2=2*(LH2+ci/pi*(2-Ao)*sj)
    if(Epol) then
        krho=k*abs(sj-si)
        call Hankz1(krho,1,H0o,H1o)
        LH2=LH2-2./k*H1o
    endif
    endif
    else
c SIMPSON'S THREE POINT COMPOSITE INTEGRATION
    do 474 ip=i+1,i,-1
c Coordinate rotation for source segment endpoints
    si=p(ip,1)*cos(psi(1))+p(ip,2)*sin(psi(1))
    ni=p(ip,1)*sin(psi(1))-p(ip,2)*cos(psi(1))
    if(neq(1)) then
        si=-si
        ni=-ni
    endif
    stepS=si
    R=sqrt((sj-si)**2+(nj-ni)**2)
    krho=k*R
    call Hankz1(krho,2,H0o,H1o)
    if(Epol) then
        if(j .eq. (i-1) .or. j .eq. (i+1)) then
            if(abs(nj-ni) .eq. 0.0) then
                tanf=pi/2
                absf=1.0
            else
                tanf=atan((si-sj)/abs(nj-ni))
                absf=abs(nj-ni)
            endif
            aLH0=ci/pi*(2*(si-sj)*log(R)
            &      -(2.0-Ao)*si+2.0*abs(nj-ni)*tanf)-aLH0
            else
                LH2=H1o/k/R+LH2
            endif
            else
                LH2=H0o+LH2
            endif
        continue
474 c Coordinate rotation for source segment midpoints
        si=m(1,1)*cos(psi(1))+m(1,2)*sin(psi(1))
        ni=m(1,1)*sin(psi(1))-m(1,2)*cos(psi(1))
        if(neq(1)) then
            si=-si
            ni=-ni
        endif
        stepS=abs(stepS-si)
        R=sqrt((sj-si)**2+(nj-ni)**2)
        krho=k*R
        call Hankz1(krho,2,H0o,H1o)
        if(Epol) then
            if(j .eq. (i-1) .or. j .eq. (i+1)) then
                LH2=-ci*8./3/pi/k**2/(2*stepS)-aLH0
            else
                LH2=stepS/3*(4*H1o/k/R+LH2)
            endif
            else
                LH2=stepS/3*(4*H0o+LH2)
            endif
        endif
c SCATTERED MAGNETIC FIELD IN THE APERTURE
        Hs(j)=k*Yo/2*Ii(N+1)*LH2+Hs(j)
480 continue
c ELECTRIC FIELD IN THE APERTURE
        E(j)=Ii(N+j)

        xj=m(j,1)
        yj=m(j,2)
c INCIDENT MAGNETIC FIELDS
        if(Epol) then
            Hi(j)=2*Yo*sin(phio)*cexp(-ci*k*xj*cos(phio))
        else
            Hi(j)=2*cos(k*yj*sin(phio))*cexp(-ci*k*xj*cos(phio))
        endif
c APERTURE IMPEDANCE
        eta(j)=E(j)/(Hi(j)+Hs(j))
500 write(2,*) m(j,1),cabs(eta(j))
        continue
    endif

```

```

c*****
c***** Far Field Amplitude *****
c*****
      Psca=czero
      DelX=w/qN/2
      do 600 i=1,qN
c...Simpson's three point composite integration over each
c  segment in the aperture
          Lsca=DelX/3*(cexp(-ci*k*p(i,1)*cos(phi))
          & +4*cexp(-ci*k*m(i,1)*cos(phi))
          & +cexp(-ci*k*p(i+1,1)*cos(phi)))
          Psca=Ii(N+i)*Lsca+Psca
600      continue
          if(Epol)then
              Psca=-k*sin(phi)/2*Psca
          else
              Psca=-k*Yo/2*Psca
          endif

          write(3,*) d,cabs(Psca)
          write(4,*) d,180/pi*(atan2(aImag(Psca),Real(Psca)))
          print *, ' Exact: |Psca| = ',cabs(Psca), ' arg Psca = ',
          & 180/pi*(atan2(aImag(Psca),Real(Psca)))

          d=d+dstep
700      continue

800      call exit
      END

```

```

C
C
C GAPSUB.FTN
C
C This file contains the subroutines and functions used by
C GAPSCAT.FTN and ANAGAP.FTN.
C *****
C SUBROUTINE GAPROM(IPRG)
C *****
C Called to prompt user for the input parameters.
C
C integer EorH,N,noS,qN
C real phi,phio,w,d,maxC,q(50,2)
C real dStp(50),wStp(50)
C complex er,ctemp
C common /prompts/ EorH,phio,phi,er,igap,wStp,dStp,w,d,noS,
C q,maxC,noIter
C
C 1 format(i1)
C 2 format(i5)
C 3 format(g16.8)
C 6 format(2g16.8)
C open(1,file='gapdat')
C print *,', '
C 20 write(*,25) EorH
C 25 format(/'Polarization of incident field:/'
C & ' 1) E- or 2) H-pol [',i1,']? ')
C read(*,1,err=20) itemp
C if(itemp .eq. 2) EorH=2
C
C 30 write(*,35) phio
C 35 format(/'Angle of incidence = ',g12.6,'degrees ')
C read(*,3,err=20) rtemp
C if(rtemp .ne. 0.0) phio=rtemp
C 36 write(*,37) phi
C 37 format(/'Angle of observation = ',g12.6,'degrees ')
C read(*,3,err=30) rtemp
C if(rtemp .ne. 0.0) phi=rtemp
C
C 38 write(*,39) er
C 39 format(/'Relative permittivity = (',g12.6,',',g12.6,',')')
C read(*,6,err=36) ctemp
C if(ctemp .ne. 0.0) er=ctemp
C print *,er
C
C 40 write(*,45)
C 45 format(/'Type of gap:/'
C & ' 1) rectangular, 2) T-shape, 3) triangular,/'
C & ' 4) L-shape, or 5) arbitrary ? ')
C read(*,1,err=20) igap
C
C if(igap .eq. 2 .or. igap .eq. 4)then
C   if(igap .eq. 2)then
C     now=3
C   else
C     now=2
C   endif
C   do 47 i=1,now
C     write(*,*) 'Enter width w',i
C     read(*,*) wStp(i)
C     if(i .ne. 3)then
C       write(*,*) 'Enter depth d',i
C       read(*,*) dStp(i)
C     endif
C 47 continue
C   w=wStp(1)
C   d=dStp(1)+dStp(2)
C   else if(igap .eq. 1 .or. igap .eq. 3 .or.
C   & (igap .eq. 5 .and. iprg .eq. 1))then
C 90 write(*,95) w
C 95 format(/'Gap width = ',g12.6,'wavelengths ')
C read(*,3,err=30) rtemp
C if(rtemp .gt. 0.0) w=rtemp
C
C 100 write(*,105) d
C 105 format(/'Gap depth = ',g12.6,'wavelengths ')
C read(*,3,err=90) rtemp
C if(rtemp .gt. 0.0) d=rtemp
C
C if(igap .eq. 5)then
C 110 write(*,115) noS
C 115 format(/'Number of sides (excluding aperture) = ',i2)
C read(*,*,err=30) rtemp
C if(rtemp .gt. 0.0) noS=int(rtemp)
C print *,'Enter the following coordinates, beginning '
C print *,' with (-w/2,0) and going cw: '
C do 127 i=1,noS+1
C 120 write(*,125) i
C 125 format(/'Corner ',i1,', (x,y) ')
C read(*,3,err=110) q(i,1)
C read(*,3,err=110) q(i,2)
C 127 continue
C noIter=1
C endif
C else
C GOTO 40

```

```

endif
if(iprg .eq. 1)then
130   write(*,135) maxC
135   format(/'Max segment size = ',g12.6,' wavelengths ')
      read(*,3,err=110) rtemp
      if(rtemp .gt. 0.0) maxC=rtemp
endif

if(igap .ne. 5)then
140   write(*,145) noIter
145   format(/'Number of iterations = ',i3,' ')
      read(*,*,err=130) rtemp
      if(rtemp .gt. 0.0) noIter=int(rtemp)
endif

c...Writing input data to file GAPDAT
write(1,2) EorH
write(1,3) phio
write(1,3) phi
write(1,6) er
write(1,2) igap
if(igap .eq. 2 .or. igap .eq. 4)then
do 150 i=1,2
write(1,3) wStp(i)
write(1,3) dStp(i)
150  continue
else
write(1,3) w
write(1,3) d
if(igap .eq. 5)then
write(1,2) noS
do 160 i=1,noS+1
write(1,6) q(i,1),q(i,2)
160  continue
endif
endif
if(iprg .eq. 1)then
write(1,3) maxC
endif
write(1,2) noIter
close(1)
return
end

C*****
C      COMPLEX FUNCTION CTAN(CARG)
C*****
C      Calculates the tangent given a complex argument
C
      complex ci,carg
      ci=cplx(0.,1)
      ctan=-ci*(cexp(ci*carg)-cexp(-ci*carg))
      & / (cexp(ci*carg)+cexp(-ci*carg))
      return
end

C*****C
C      SUBROUTINE HANKZ1 (R,N,HZERO,HONE)C
C*****C
C      Called to compute Hankel functions of the first kind
C      for orders one and zero. The argument is variable R
C      and must be positive.
C
C.....HANKEL FUNCTIONS ARE OF FIRST KIND--J+IY
C..... N=0 RETURNS HZERO (H-zero)
C..... N=1 RETURNS HONE (H-one)
C..... N=2 RETURNS HZERO AND HONE
C.....SUBROUTINE REQUIRES R>0
C.....SUBROUTINE ADAM MUST BE SUPPLIED BY USER
C
      DIMENSION A(7),B(7),C(7),D(7),E(7),F(7),G(7),H(7)
      COMPLEX HZERO,HONE
      DATA A,B,C,D,E,F,G,H/1.0,-2.2499997,1.2656208,-0.3163866,
&0.0444479,-0.0039444,0.00021,0.36746691,0.60559366,-0.74350384,
&0.25300117,-0.04261214,0.00427916,-0.00024846,0.5,-0.56249985,
&0.21093573,-0.03954289,0.00443319,-0.00031761,0.00001109,
&-0.6366198,0.2212091,2.1682709,-1.3164827,0.3123951,-0.0400976,
&0.0027873,0.79788456,-0.00000077,-0.0055274,-0.00009512,
&0.00137237,-0.00072805,0.00014476,-0.78539816,-0.04166397,
&-0.00003954,0.00262573,-0.00054125,-0.00029333,0.00013558,
&0.79788456,0.00000156,0.01659667,0.00017105,-0.00249511,
&0.00113653,-0.00020033,-2.35619449,0.12499612,0.0000565,
&-0.00637879,0.00074348,0.00079824,-0.00029166/
      IF (R.LE.0.0) GO TO 50
      IF (N.LT.0.OR.N.GT.2) GO TO 50
      IF (R.GT.3.0) GO TO 20
      X=R*R/9.0
      IF (N.EQ.1) GO TO 10
      CALL ADAM(A,X,BJ)
      CALL ADAM(B,X,Y)
      BY=0.6366198*ALOG(0.5*R)*BJ+Y
      HZERO=CMPLX(BJ,BY)
      IF (N.EQ.0) RETURN
10  CALL ADAM(C,X,Y)

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      BJ=R*Y
      CALL ADAM(D,X,Y)
      BY=0.6366198*ALOG(0.5*R)*BJ+Y/R
      HONE=CMPLX(BJ,BY)
      RETURN
20  X=3.0/R
      IF(N.EQ.1) GO TO 30
      CALL ADAM(E,X,Y)
      FOOL=Y/SQRT(R)
      CALL ADAM(F,X,Y)
      T=R+Y
      BJ=FOOL*COS(T)
      BY=FOOL*SIN(T)
      HZERO=CMPLX(BJ,BY)
      IF(N.EQ.0) RETURN
30  CALL ADAM(G,X,Y)
      FOOL=Y/SQRT(R)
      CALL ADAM(H,X,Y)
      T=R+Y
      BJ=FOOL*COS(T)
      BY=FOOL*SIN(T)
      HONE=CMPLX(BJ,BY)
      RETURN
50  WRITE(6,90) N,R
90  FORMAT(32HOSICK DATA IN HANKZ1 *QUIT* N=,I2,2X,2HR=,E11.3)
      CALL SYSTEM
      END
C*****C
C      SUBROUTINE ADAM(C,X,Y)C
C      C*****C
C      Called by subroutine HANKZ1 to compute the value of a 7th
C      order polynomial whose argument is X and coefficients are
C      contained in vector C.
C      DIMENSION C(7)
C      Y=X*C(7)
C      DO 10 I=1,5
C          Y=X*(C(7-I)+Y)
10  CONTINUE
C      Y=Y+C(1)
C      RETURN
C      END
C*****C
C      SUBROUTINE CHANK(Z,N,H0,H1)C
C      C*****C
C      CALCULATES HANKEL FUNCTIONS ZEROth AND FIRST ORDER
C      OF THE FIRST KIND OF COMPLEX ARGUMENT H0=J0+I*Y0, H1=J1+I*Y1.
C      THE ACCURACY IS VERY GOOD UP TO |Z|<10. ABOVE THAT THE
C      ACCURACY IS TO THE ORDER OF LARGE ARGUMENT EXPANSION.
C      N=0 RETURNS H0
C      N=1 RETURNS H1
C      N=2 RETURNS H0 AND H1
C      N=3 RETURNS J0 AND J1
C
C      COMPLEX J0,Y0,J1,Y1,Z,TERM
C      COMPLEX I,H0,H1
C      I=(0.0,1.0)
C      PI=4.*ATAN(1.)
C      IF(N.EQ.1)GOTO10
C      IF(CABS(Z).GT. 12.) THEN
C          J0=CSQRT(2/(PI*Z))*CCOS(Z-PI/4.)
C          Y0=CSQRT(2/(PI*Z))*CSIN(Z-PI/4.)
C      ELSE
C          AONE=1.
C          TERM=(1.0,0.0)
C          J0=(1.0,0.0)
C          Y0=(0.0,0.0)
C          SUM=0.0
C          M=0
100  M=M+1
C          SUM=SUM+1./FLOAT(M)
C          AONE=AONE*(-1.)
C          TERM=TERM*( (Z/2)/FLOAT(M) )**2
C          J0=J0+AONE*TERM
C          Y0=Y0+AONE*TERM*SUM
C          IF(M.LE.10 .OR. CABS(FLOAT(M)/(Z/2)).LT. 5)GOTO 100
C          Y0=2.*(J0*(CLOG(Z/2)+0.57721)-Y0)/PI
C      ENDIF
C      IF(N.EQ.3) THEN
C          H0=J0
C      ELSE
C          H0=J0+I*Y0
C      ENDIF
C      IF(N.EQ.0) RETURN
C      COMPUTATION OF J1 AND Y1
10  IF(CABS(Z).GT. 15.) THEN
C          J1=CSQRT(2/(PI*Z))*CCOS(Z-3.*PI/4.)

```

```

Y1=CSQRT(2/(PI*Z))*CSIN(Z-3.*PI/4.)
ELSE
AONE=1.
TERM=(1.0,0.0)
J1=(1.0,0.0)
Y1=(1.0,0.0)
SUM=0.0
M=0
200 M=M+1
SUM=SUM+1./FLOAT(M)
AONE=AONE*(-1.)
TERM=TERM*(Z/2)**2/(FLOAT(M)*FLOAT(M+1))
J1=J1+AONE*TERM
Y1=Y1+AONE*TERM*(1./FLOAT(M+1)+2.*SUM)
IF(M.LE.10 .OR. CABS(FLOAT(M)/(Z/2)).LT. 5)GOTO 200
J1=J1*Z/2.
Y1=(2.*J1*(CLOG(Z/2)+0.57721)-2./Z-Y1*Z/2.)/PI
ENDIF
IF(N.EQ.3)THEN
H1=J1
ELSE
H1=J1+I*Y1
ENDIF
RETURN
END
C*****
C
SUBROUTINE MODBESS(X,I0,I1)
C
C *****
C CALCULATES THE MODIFIED BESSEL FUNCTION OF THE
C ZEROTH AND FIRST ORDER. ARGUMENT X IS POSITIVE AND REAL.
C SEE PAGE 378 ABRAMOVITZ
C
REAL I0,I1
T=X/3.75
IF(T.LT.-1)THEN
PRINT *,'ERROR'
STOP
ELSE
ENDIF
IF(T.GE.-1 .OR. T.LE.1)THEN
I0=1+3.5156229*T**2+3.0899424*T**4+1.2067492*T**6+
& 0.2659732*T**8+0.0360768*T**10+0.0045813*T**12
I1=0.5+0.8789059*T**2+0.51498869*T**4+0.15084934*T**6+
& 0.02658733*T**8+0.00301532*T**10+0.00032411*T**12
I1=X*I1
ELSE
I0=0.39894228+0.01328592/T+0.00225319/T**2-0.00157565/T**3
& +0.00916281/T**4-0.02057706/T**5+0.02635537/T**6
& -0.01647633/T**7+0.00392377/T**8
I0=I0*EXP(X)*SQRT(1/X)
I1=0.39894228-0.03988024/T-0.00362018/T**2+0.00163801/T**3
& -0.01031555/T**4+0.02282967/T**5-0.02895312/T**6
& +0.01787654/T**7-0.00420059/T**8
ENDIF
RETURN
END
C*****
C
The following subroutines are standard LINPACK routines
C to perform L-U decomposition and back substitution on a
C single precision complex matrix. See CC-Memo 407 sec 2.1
C for documentation on these routines.
C
C *****
C
SUBROUTINE CGECO(A,LDA,N,IPVT,RCOND,Z)
C
C *****
C NAASA 2.1.042 CGECO FTN-A 05-02-78 THE UNIV OF MICH COMP CTR
C
INTEGER LDA,N,IPVT(1)
COMPLEX A(LDA,1),Z(1)
REAL RCOND
C
CGECO FACTORS A COMPLEX MATRIX BY GAUSSIAN ELIMINATION
AND ESTIMATES THE CONDITION OF THE MATRIX.
C
IF RCOND IS NOT NEEDED, CGEFA IS SLIGHTLY FASTER.
C TO SOLVE A*X = B , FOLLOW CGECO BY CGESL.
C TO COMPUTE INVERSE(A)*C , FOLLOW CGECO BY CGESL.
C TO COMPUTE DETERMINANT(A) , FOLLOW CGECO BY CGEDI.
C TO COMPUTE INVERSE(A) , FOLLOW CGECO BY CGEDI.
C
ON ENTRY
C
A COMPLEX(LDA, N)
THE MATRIX TO BE FACTORED.
C
LDA INTEGER
THE LEADING DIMENSION OF THE ARRAY A .
C
N INTEGER
THE ORDER OF THE MATRIX A .

```

```

C
C
C ON RETURN
C
C A AN UPPER TRIANGULAR MATRIX AND THE MULTIPLIERS
C WHICH WERE USED TO OBTAIN IT.
C THE FACTORIZATION CAN BE WRITTEN A = L*U WHERE
C L IS A PRODUCT OF PERMUTATION AND UNIT LOWER
C TRIANGULAR MATRICES AND U IS UPPER TRIANGULAR.
C
C IPVT INTEGER(N)
C AN INTEGER VECTOR OF PIVOT INDICES.
C
C RCOND REAL
C AN ESTIMATE OF THE RECIPROCAL CONDITION OF A .
C FOR THE SYSTEM A*X = B , RELATIVE PERTURBATIONS
C IN A AND B OF SIZE EPSILON MAY CAUSE
C RELATIVE PERTURBATIONS IN X OF SIZE EPSILON/RCOND .
C IF RCOND IS SO SMALL THAT THE LOGICAL EXPRESSION
C 1.0 + RCOND .EQ. 1.0
C IS TRUE, THEN A MAY BE SINGULAR TO WORKING
C PRECISION. IN PARTICULAR, RCOND IS ZERO IF
C EXACT SINGULARITY IS DETECTED OR THE ESTIMATE
C UNDERFLOWS.
C
C Z COMPLEX(N)
C A WORK VECTOR WHOSE CONTENTS ARE USUALLY UNIMPORTANT.
C IF A IS CLOSE TO A SINGULAR MATRIX, THEN Z IS
C AN APPROXIMATE NULL VECTOR IN THE SENSE THAT
C NORM(A*Z) = RCOND*NORM(A)*NORM(Z) .
C
C LINPACK. THIS VERSION DATED 07/14/77 .
C CLEVE MOLER, UNIVERSITY OF NEW MEXICO, ARGONNE NATIONAL LABS.
C
C SUBROUTINES AND FUNCTIONS
C
C LINPACK CGEFA
C BLAS CAXPY, CDOTC, CSSCAL, SCASUM
C FORTRAN ABS, AIMAG, AMAX1, CMLPX, CONJG, REAL
C
C INTERNAL VARIABLES
C
C COMPLEX CDOTC, EK, T, WK, WKM
C REAL ANORM, S, SCASUM, SM, YNORM
C INTEGER INFO, J, K, KB, KP1, L
C
C COMPLEX ZDUM, ZDUM1, ZDUM2, CSIGN1
C REAL CABS1
C CABS1(ZDUM) = ABS(REAL(ZDUM)) + ABS(AIMAG(ZDUM))
C CSIGN1(ZDUM1, ZDUM2) = CABS1(ZDUM1) * (ZDUM2/CABS1(ZDUM2))
C
C Compute 1-NORM of A
C
C ANORM = 0.0E0
C DO 10 J = 1, N
C ANORM = AMAX1(ANORM, SCASUM(N, A(1, J), 1))
10 CONTINUE
C
C Factor
C
C CALL CGEFA(A, LDA, N, IPVT, INFO)
C
C RCOND = 1/(NORM(A) * (ESTIMATE OF NORM(INVERSE(A)))) .
C ESTIMATE = NORM(Z)/NORM(Y) WHERE A*Z = Y AND CTRANS(A)*Y = E .
C CTRANS(A) IS THE CONJUGATE TRANSPOSE OF A .
C THE COMPONENTS OF E ARE CHOSEN TO CAUSE MAXIMUM LOCAL
C GROWTH IN THE ELEMENTS OF W WHERE CTRANS(U)*W = E .
C THE VECTORS ARE FREQUENTLY RESCALED TO AVOID OVERFLOW.
C
C SOLVE CTRANS(U)*W = E
C
C EK = CMLPX(1.0E0, 0.0E0)
C DO 20 J = 1, N
C Z(J) = CMLPX(0.0E0, 0.0E0)
20 CONTINUE
C DO 100 K = 1, N
C IF (CABS1(Z(K)) .NE. 0.0E0) EK = CSIGN1(EK, -Z(K))
C IF (CABS1(EK-Z(K)) .LE. CABS1(A(K, K))) GO TO 30
C S = CABS1(A(K, K))/CABS1(EK-Z(K))
C CALL CSSCAL(N, S, Z, 1)
C EK = CMLPX(S, 0.0E0)*EK
30 CONTINUE
C WK = EK - Z(K)
C WKM = -EK - Z(K)
C S = CABS1(WK)
C SM = CABS1(WKM)
C IF (CABS1(A(K, K)) .EQ. 0.0E0) GO TO 40
C WK = WK/CONJG(A(K, K))
C WKM = WKM/CONJG(A(K, K))
C GO TO 50
40 CONTINUE
C WK = CMLPX(1.0E0, 0.0E0)
C WKM = CMLPX(1.0E0, 0.0E0)
50 CONTINUE
C KP1 = K + 1
C IF (KP1 .GT. N) GO TO 90
C DO 60 J = KP1, N

```



```

        SM = SM + CABS1(Z(J)+WK*CONJG(A(K,J)))
        Z(J) = Z(J) + WK*CONJG(A(K,J))
        S = S + CABS1(Z(J))
60      CONTINUE
        IF (S .GE. SM) GO TO 80
        T = WKM - WK
        WK = WKM
        DO 70 J = KP1, N
            Z(J) = Z(J) + T*CONJG(A(K,J))
70      CONTINUE
80      CONTINUE
90      CONTINUE
        Z(K) = WK
100     CONTINUE
        S = 1.0E0/SCASUM(N,Z,1)
        CALL CSSCAL(N,S,Z,1)
C
CCC    Solve CTRANS(L)*Y = V
C
        DO 120 KB = 1, N
            K = N + 1 - KB
            IF (K .LT. N) Z(K) = Z(K) + CDOTC(N-K,A(K+1,K),1,Z(K+1),1)
            IF (CABS1(Z(K)) .LE. 1.0E0) GO TO 110
            S = 1.0E0/CABS1(Z(K))
            CALL CSSCAL(N,S,Z,1)
110     CONTINUE
            L = IPVT(K)
            T = Z(L)
            Z(L) = Z(K)
            Z(K) = T
120     CONTINUE
        S = 1.0E0/SCASUM(N,Z,1)
        CALL CSSCAL(N,S,Z,1)
C
        YNORM = 1.0E0
C
CCC    Solve L*V = Y
C
        DO 140 K = 1, N
            L = IPVT(K)
            T = Z(L)
            Z(L) = Z(K)
            Z(K) = T
            IF (K .LT. N) CALL CAXPY(N-K,T,A(K+1,K),1,Z(K+1),1)
            IF (CABS1(Z(K)) .LE. 1.0E0) GO TO 130
            S = 1.0E0/CABS1(Z(K))
            CALL CSSCAL(N,S,Z,1)
            YNORM = S*YNORM
130     CONTINUE
140     CONTINUE
        S = 1.0E0/SCASUM(N,Z,1)
        CALL CSSCAL(N,S,Z,1)
        YNORM = S*YNORM
C
CCC    Solve U*Z = V
C
        DO 160 KB = 1, N
            K = N + 1 - KB
            IF (CABS1(Z(K)) .LE. CABS1(A(K,K))) GO TO 150
            S = CABS1(A(K,K))/CABS1(Z(K))
            CALL CSSCAL(N,S,Z,1)
            YNORM = S*YNORM
150     CONTINUE
            IF (CABS1(A(K,K)) .NE. 0.0E0) Z(K) = Z(K)/A(K,K)
            IF (CABS1(A(K,K)) .EQ. 0.0E0) Z(K) = CMPLX(1.0E0,0.0E0)
            T = -Z(K)
            CALL CAXPY(K-1,T,A(1,K),1,Z(1),1)
160     CONTINUE
C
        MAKE ZNORM = 1.0
        S = 1.0E0/SCASUM(N,Z,1)
        CALL CSSCAL(N,S,Z,1)
        YNORM = S*YNORM
C
        IF (ANORM .NE. 0.0E0) RCOND = YNORM/ANORM
        IF (ANORM .EQ. 0.0E0) RCOND = 0.0E0
        RETURN
        END
C*****C
C
        SUBROUTINE CGEFA(A,LDA,N,IPVT,INFO)
C*****C
C
C NAASA 2.1.043 CGEFA FTN-A 05-02-78 THE UNIV OF MICH COMP CTR
C
        INTEGER LDA,N,IPVT(1),INFO
        COMPLEX A(LDA,1)
C
C CGEFA FACTORS A COMPLEX MATRIX BY GAUSSIAN ELIMINATION.
C
C CGEFA IS USUALLY CALLED BY CGECO, BUT IT CAN BE CALLED
C DIRECTLY WITH A SAVING IN TIME IF RCOND IS NOT NEEDED.
C (TIME FOR CGECO) = (1 + 9/N)*(TIME FOR CGEFA) .
C
C ON ENTRY

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C      A      COMPLEX(LDA, N)
C      THE MATRIX TO BE FACTORED.
C
C      LDA    INTEGER
C      THE LEADING DIMENSION OF THE ARRAY A .
C
C      N      INTEGER
C      THE ORDER OF THE MATRIX A .
C
C      ON RETURN
C
C      A      AN UPPER TRIANGULAR MATRIX AND THE MULTIPLIERS
C      WHICH WERE USED TO OBTAIN IT.
C      THE FACTORIZATION CAN BE WRITTEN A = L*U WHERE
C      L IS A PRODUCT OF PERMUTATION AND UNIT LOWER
C      TRIANGULAR MATRICES AND U IS UPPER TRIANGULAR.
C
C      IPVT   INTEGER(N)
C      AN INTEGER VECTOR OF PIVOT INDICES.
C
C      INFO   INTEGER
C      = 0 NORMAL VALUE.
C      = K IF U(K,K) .EQ. 0.0 . THIS IS NOT AN ERROR
C      CONDITION FOR THIS SUBROUTINE, BUT IT DOES
C      INDICATE THAT CGESL OR CGEDI WILL DIVIDE BY ZERO
C      IF CALLED. USE RCOND IN CGECO FOR A RELIABLE
C      INDICATION OF SINGULARITY.
C
C      LINPACK. THIS VERSION DATED 07/14/77 .
C      CLEVE MOLER, UNIVERSITY OF NEW MEXICO, ARGONNE NATIONAL LABS.
C
C      SUBROUTINES AND FUNCTIONS
C
C      BLAS CAXPY,CSCAL,ICAMAX
C      FORTRAN ABS,AIMAG,CMLPX,REAL
C
C      INTERNAL VARIABLES
C
C      COMPLEX T
C      INTEGER ICAMAX, J, K, KP1, L, NMI
C
C      COMPLEX ZDUM
C      REAL CABS1
C      CABS1(ZDUM) = ABS(REAL(ZDUM)) + ABS(AIMAG(ZDUM))
C
C      Gaussian elimination with partial pivoting
C
C      INFO = 0
C      NMI = N - 1
C      IF (NMI .LT. 1) GO TO 70
C      DO 60 K = 1, NMI
C      KP1 = K + 1
C
C      FIND L = PIVOT INDEX
C
C      L = ICAMAX(N-K+1,A(K,K),1) + K - 1
C      IPVT(K) = L
C
C      Zero pivot implies this column already triangularized
C
C      IF (CABS1(A(L,K)) .EQ. 0.0E0) GO TO 40
C
C      Interchange if necessary
C
C      IF (L .EQ. K) GO TO 10
C      T = A(L,K)
C      A(L,K) = A(K,K)
C      A(K,K) = T
C      CONTINUE
C
C      10
C      Compute multipliers
C
C      T = -CMPLX(1.0E0,0.0E0)/A(K,K)
C      CALL CSCAL(N-K,T,A(K+1,K),1)
C
C      Row elimination with column indexing
C
C      DO 30 J = KP1, N
C      T = A(L,J)
C      IF (L .EQ. K) GO TO 20
C      A(L,J) = A(K,J)
C      A(K,J) = T
C      20
C      CONTINUE
C      CALL CAXPY(N-K,T,A(K+1,K),1,A(K+1,J),1)
C      30
C      CONTINUE
C      GO TO 50
C      40
C      CONTINUE
C      INFO = K
C      50
C      CONTINUE
C      60
C      CONTINUE
C      70
C      CONTINUE
C      IPVT(N) = N
C      IF (CABS1(A(N,N)) .EQ. 0.0E0) INFO = N
C      RETURN
C      END
C
C

```

```

C*****C
C
C      SUBROUTINE CGESL(A,LDA,N,IPVT,B,JOB)
C*****C
C      NAASA 2.1.044 CGESL   FTN-A 05-02-78   THE UNIV OF MICH COMP CTR
C
C      INTEGER LDA,N,IPVT(1),JOB
C      COMPLEX A(LDA,1),B(1)
C
C      CGESL SOLVES THE COMPLEX SYSTEM
C      A * X = B OR CTRANS(A) * X = B
C      USING THE FACTORS COMPUTED BY CGECO OR CGEFA.
C
C      ON ENTRY
C
C          A      COMPLEX(LDA, N)
C                  THE OUTPUT FROM CGECO OR CGEFA.
C
C          LDA    INTEGER
C                  THE LEADING DIMENSION OF THE ARRAY A .
C
C          N      INTEGER
C                  THE ORDER OF THE MATRIX A .
C
C          IPVT   INTEGER(N)
C                  THE PIVOT VECTOR FROM CGECO OR CGEFA.
C
C          B      COMPLEX(N)
C                  THE RIGHT HAND SIDE VECTOR.
C
C          JOB    INTEGER
C                  = 0      TO SOLVE  A*X = B ,
C                  = NONZERO TO SOLVE  CTRANS(A)*X = B WHERE
C                               CTRANS(A) IS THE CONJUGATE TRANSPOSE.
C
C      ON RETURN
C
C          B      THE SOLUTION VECTOR X .
C
C      ERROR CONDITION
C
C          A DIVISION BY ZERO WILL OCCUR IF THE INPUT FACTOR CONTAINS A
C          ZERO ON THE DIAGONAL.  TECHNICALLY THIS INDICATES SINGULARITY
C          BUT IT IS OFTEN CAUSED BY IMPROPER ARGUMENTS OR IMPROPER
C          SETTING OF LDA .  IT WILL NOT OCCUR IF THE SUBROUTINES ARE
C          CALLED CORRECTLY AND IF CGECO HAS SET RCOND .GT. 0.0
C          OR CGEFA HAS SET INFO .EQ. 0 .
C
C      TO COMPUTE INVERSE(A) * C WHERE C IS A MATRIX
C      WITH P COLUMNS
C          CALL CGECO(A,LDA,N,IPVT,RCOND,Z)
C          IF (RCOND IS TOO SMALL) GO TO ...
C          DO 10 J = 1, P
C              CALL CGESL(A,LDA,N,IPVT,C(1,J),0)
C          10 CONTINUE
C
C      LINPACK. THIS VERSION DATED 07/14/77 .
C      CLEVE MOLER, UNIVERSITY OF NEW MEXICO, ARGONNE NATIONAL LABS.
C
C      SUBROUTINES AND FUNCTIONS
C
C      BLAS CAXPY,CDOTC
C      FORTRAN CONJG
C
C      INTERNAL VARIABLES
C
C      COMPLEX CDOTC,T
C      INTEGER K,KB,L,NM1
C
C      NM1 = N - 1
C      IF (JOB .NE. 0) GO TO 50
C
C      JOB = 0 , SOLVE A * X = B
C      FIRST SOLVE L*Y = B
C
C      IF (NM1 .LT. 1) GO TO 30
C      DO 20 K = 1, NM1
C          L = IPVT(K)
C          T = B(L)
C          IF (L .EQ. K) GO TO 10
C          B(L) = B(K)
C          B(K) = T
C      10 CONTINUE
C      CALL CAXPY(N-K,T,A(K+1,K),1,B(K+1),1)
C      20 CONTINUE
C      30 CONTINUE
C
C      NOW SOLVE U*X = Y
C
C      DO 40 KB = 1, N
C          K = N + 1 - KB
C          B(K) = B(K)/A(K,K)
C          T = -B(K)
C          CALL CAXPY(K-1,T,A(1,K),1,B(1),1)

```

```

40 CONTINUE
GO TO 100
50 CONTINUE
C
C
C
C     JOB = NONZERO, SOLVE CTRANS(A) * X = B
C     FIRST SOLVE CTRANS(U)*Y = B
C
DO 60 K = 1, N
  T = CDOTC(K-1,A(1,K),1,B(1),1)
  B(K) = (B(K) - T)/CONJG(A(K,K))
60 CONTINUE
C
C
C     NOW SOLVE CTRANS(L)*X = Y
C
IF (NMI .LT. 1) GO TO 90
DO 80 KB = 1, NMI
  K = N - KB
  B(K) = B(K) + CDOTC(N-K,A(K+1,K),1,B(K+1),1)
  L = IPVT(K)
  IF (L .EQ. K) GO TO 70
  T = B(L)
  B(L) = B(K)
  B(K) = T
70 CONTINUE
80 CONTINUE
90 CONTINUE
100 CONTINUE
RETURN
END
C
C*****C
C
SUBROUTINE CAXPY(N,CA,CX,INCX,CY,INCY)
C*****C
C
C NAASA 1.1.014 CAXPY   FTN-A 05-02-78   THE UNIV OF MICH COMP CTR
C
C     CONSTANT TIMES A VECTOR PLUS A VECTOR.
C     JACK DONGARRA, LINPACK, 6/17/77.
C
C     COMPLEX CX(1),CY(1),CA
C     INTEGER I,INCX,INCY,IX,IY,N
C
IF(N.LE.0)RETURN
IF (ABS(REAL(CA)) + ABS(AIMAG(CA)) .EQ. 0.0 ) RETURN
IF(INCX.EQ.1.AND.INCY.EQ.1)GOTO 20
C
C     Code for unequal increments or equal increments
C     Not equal to 1
C
IX = 1
IY = 1
IF(INCX.LT.0)IX = (-N+1)*INCX + 1
IF(INCY.LT.0)IY = (-N+1)*INCY + 1
DO 10 I = 1,N
  CY(IY) = CY(IY) + CA*CX(IX)
  IX = IX + INCX
  IY = IY + INCY
10 CONTINUE
RETURN
C
C     Code for both increments equal to 1
C
20 DO 30 I = 1,N
  CY(I) = CY(I) + CA*CX(I)
30 CONTINUE
RETURN
END
C
C*****C
C
COMPLEX FUNCTION CDOTC(N,CX,INCX,CY,INCY)
C*****C
C
C NAASA 1.1.012 CDOTC   FTN-A 05-02-78   THE UNIV OF MICH COMP CTR
C
C     FORMS THE DOT PRODUCT OF TWO VECTORS, CONJUGATING THE FIRST
C     VECTOR.
C     JACK DONGARRA, LINPACK, 6/17/77.
C
C     COMPLEX CX(1),CY(1),CTEMP
C     INTEGER I,INCX,INCY,IX,IY,N
C
CTEMP = (0.0,0.0)
CDOTC = (0.0,0.0)
IF(N.LE.0)RETURN
IF(INCX.EQ.1.AND.INCY.EQ.1)GOTO 20
C
C     Code for unequal increments or equal increments
C     Not equal to 1
C
IX = 1
IY = 1
IF(INCX.LT.0)IX = (-N+1)*INCX + 1
IF(INCY.LT.0)IY = (-N+1)*INCY + 1
DO 10 I = 1,N

```

```

        CTEMP = CTEMP + CONJG(CX(IX))*CY(IY)
        IX = IX + INCX
        IY = IY + INCY
10    CONTINUE
        CDOTC = CTEMP
        RETURN
C
CCC      Code for both increments equal to 1
C
20    DO 30 I = 1,N
        CTEMP = CTEMP + CONJG(CX(I))*CY(I)
30    CONTINUE
        CDOTC = CTEMP
        RETURN
        END
C
C*****C
C      SUBROUTINE  CSCAL(N,CA,CX,INCX)
C*****C
C
C      NAASA 1.1.019 CSCAL   FTN-A 05-02-78   THE UNIV OF MICH COMP CTR
C
C      SCALES A VECTOR BY A CONSTANT.
C      JACK DONGARRA, LINPACK, 6/17/77.
C
C      COMPLEX CA,CX(1)
C      INTEGER I,INCX,N,NINCX
C
C      IF(N.LE.0)RETURN
C      IF(INCX.EQ.1)GOTO 20
C
CCC      Code for increment not equal to 1
C
        NINCX = N*INCX
        DO 10 I = 1,NINCX,INCX
            CX(I) = CA*CX(I)
10    CONTINUE
        RETURN
C
CCC      Code for increment equal to 1
C
20    DO 30 I = 1,N
        CX(I) = CA*CX(I)
30    CONTINUE
        RETURN
        END
C
C*****C
C      SUBROUTINE  CSSCAL(N,SA,CX,INCX)
C*****C
C
C      NAASA 1.1.018 CSSCAL   FTN-A 05-02-78   THE UNIV OF MICH COMP CTR
C
C      SCALES A COMPLEX VECTOR BY A REAL CONSTANT.
C      JACK DONGARRA, LINPACK, 6/17/77.
C
C      COMPLEX CX(1)
C      REAL SA
C      INTEGER I,INCX,N,NINCX
C
C      IF(N.LE.0)RETURN
C      IF(INCX.EQ.1)GOTO 20
C
CCC      Code for increment not equal to 1
C
        NINCX = N*INCX
        DO 10 I = 1,NINCX,INCX
            CX(I) = CPLX(SA*REAL(CX(I)),SA*AIMAG(CX(I)))
10    CONTINUE
        RETURN
C
CCC      Code for increment equal to 1
C
20    DO 30 I = 1,N
        CX(I) = CPLX(SA*REAL(CX(I)),SA*AIMAG(CX(I)))
30    CONTINUE
        RETURN
        END
C
C*****C
C      INTEGER FUNCTION ICAMAX(N,CX,INCX)
C*****C
C
C      NAASA 1.1.021 ICAMAX   FTN-A 05-02-78   THE UNIV OF MICH COMP CTR
C
C      FINDS THE INDEX OF ELEMENT HAVING MAX. ABSOLUTE VALUE.
C      JACK DONGARRA, LINPACK, 6/17/77.
C
C      COMPLEX CX(1)
C      REAL SMAX
C      INTEGER I,INCX,IX,N
C      COMPLEX ZDUM

```

```

REAL CABS1
CABS1(ZDUM) = ABS(REAL(ZDUM)) + ABS(AIMAG(ZDUM))
C
ICAMAX = 1
IF(N.LE.1)RETURN
IF(INCX.EQ.1)GOTO 20
C
CCC   Code for increment not equal to 1
C
IX = 1
SMAX = CABS1(CX(1))
IX = IX + INCX
DO 10 I = 2,N
  IF(CABS1(CX(I)).LE.SMAX) GO TO 5
  ICAMAX = I
  SMAX = CABS1(CX(I))
5   IX = IX + INCX
10  CONTINUE
RETURN
C
CCC   Code for increment equal to 1
C
20  SMAX = CABS1(CX(1))
DO 30 I = 2,N
  IF(CABS1(CX(I)).LE.SMAX) GO TO 30
  ICAMAX = I
  SMAX = CABS1(CX(I))
30  CONTINUE
RETURN
END
C
C*****C
REAL FUNCTION SCASUM(N,CX, INCX)
C*****C
C
C NAASA 1.1.010 SCASUM   FTN-A 05-02-78   THE UNIV OF MICH COMP CTR
C
C TAKES THE SUM OF THE ABSOLUTE VALUES OF A COMPLEX VECTOR AND
C RETURNS A SINGLE PRECISION RESULT.
C JACK DONGARRA, LINPACK, 6/17/77.
C
C COMPLEX CX(1)
C REAL STEMP
C INTEGER I, INCX, N, NINCX
C
C SCASUM = 0.0E0
C STEMP = 0.0E0
C IF(N.LE.0)RETURN
C IF(INCX.EQ.1)GOTO 20
C
C CCC   Code for increment not equal to 1
C
C NINCX = N*INCX
C DO 10 I = 1, NINCX, INCX
C   STEMP = STEMP + ABS(REAL(CX(I))) + ABS(AIMAG(CX(I)))
10  CONTINUE
C SCASUM = STEMP
C RETURN
C
C CCC   Code for increment equal to 1
C
20  DO 30 I = 1, N
C   STEMP = STEMP + ABS(REAL(CX(I))) + ABS(AIMAG(CX(I)))
30  CONTINUE
C SCASUM = STEMP
C RETURN
C END

```

Appendix B Program Listing for the Quasi-Analytical Solution

The quasi-analytical solution proposed by Senior and Volakis [1] as described in Section 3 was programmed for solution, as listed in the program ANAGAP.FTN below. The subroutines used by this program are listed in GAPSUB.FTN in Appendix A.

As with the program for the exact solution GAPSCAT, the user is prompted for the following: the polarization of the incident field, angle of incidence, angle of far field observation, the relative permittivity ϵ_r of the gap cavity, the shape of the gap, and the number of iterations for calculating the far field amplitude versus gap depth. The choice of shapes and dimensions requested for the gap are according to Figure 2.

The input impedance of the gap as a parallel plate waveguide is calculated according to the specified shape. For the L- and T-shaped gaps, (35) is used, given the other necessary expressions as contained in Section 3. The input impedance of the rectangular gap is given by (39), and for the V-shaped gap, (40) is used. These expressions are for the H-polarization case. As mentioned previously, for the E-polarization case, the propagation constant k_1 is replaced by ikp and the characteristic impedance Z_1 by $-iZ\mu_r/\rho$, where ρ is given by (41). The desired effective surface impedance η is then calculated according to (33).

For H-polarization, the far field amplitude P_H is calculated from (22). P_H is a function of $K_H(a)$ given by (30). The argument a is a function of the effective surface impedance as given in (21). For the E-polarization, the far field amplitude P_E is calculated from (27), where $K_E(b)$ is given by (31). The argument b is a function of the effective surface impedance as given in (26).


```

if(Epol) dmin=0.025
dmax=d
if(noIter .ne. 1)then
  dstep=(dmax-dmin)/(noIter-1)
  d=dmin
endif

DO 700 iter=1,noIter
c*****
c***** Gap Impedance *****
c*****

c...Complex propagation constant k1 and characteristic impedance
c Z1 of the T-line model
  if(Epol)then
    k1=ci*k*csqrt((1./2/w)**2-er*ur)
    Z1=-ci*Zo*ur/csqrt((1./2/w)**2-er*ur)
  else
    Z1=Zo*csqrt(ur/er)
    k1=k*csqrt(ur*er)
  endif
  if(igap .eq. 1)then
c RECTANGULAR
    ETA=-ci*Z1*ctan(k1*d)
    else if(igap .eq. 2 .or. igap .eq. 4)then
      w=wStp(1)
      w2=wStp(2)
      w3=wStp(3)
      d1=d*drat
      d2=d*(1-drat)
c Propagation constant and characteristic impedance of
c the arms of the T- or L-shaped gaps
      if(Epol)then
        kc=ci*k*csqrt((1./2/d2)**2-er*ur)
        Zc=-ci*Zo*d2*ur/csqrt((1./2/d2)**2-er*ur)
      else
        Zc=Zo*d2*csqrt(ur/er)
        kc=k*csqrt(ur*er)
      endif
      if(igap .eq. 4)then
c L-SHAPED
        Z1=-ci*Zc*ctan(kc*w2)
        X=k*Zc*w1
        B1=k/Zc*d2*(d2/(d2+w1))*(1.-2./pi*log(2.))
        B2=k/Zc*d2*(w1/(d2+w1))*(1.-2./pi*log(2.))
        ZL=(Z1-ci*X*(1-ci*B2*Z1))
        & /((1-B1*X)*(1-ci*B2*Z1)-ci*B1*Z1)
      else
c T-SHAPED
        Z1=-ci*Zc*(ctan(kc*w2)+ctan(kc*w3))
        X=2*k*Zc*w1
        B1=k/Zc*d2*(d2/(d2+w1))*0.7822
        ZL=(Z1-ci*X)/(1-ci*B1*(Z1-ci*X))
      endif
      & ETA=Z1*(ZL-ci*Z1*w1*ctan(k1*d1))
      / (Z1*w1-ci*ZL*ctan(k1*d1))
    else if(igap .eq. 3)then
c TRIANGULAR
      if(Lossy)then
        carg=k1*d
        call cHank(carg,3,H0,H1)
        carg=1.
      else
        if(Epol)then
          rarg=Real(k1/ci)*d
          call ModBess(rarg,I0,I1)
          H0=I0
          H1=I1
          carg=ci
        else
          rarg=Real(k1)*d
          call Hankz1(rarg,2,H0,H1)
          carg=1.
        endif
      endif
      & ETA=-ci*Z1*Real(H1)/Real(H0)*carg
    endif
  endif
c write(2,*) d,cabs(ETA)

c*****
c***** Far Field Amplitude *****
c*****
  if(Epol)then
    b=-ci*k*w/2*Zo/ETA
    Ke=0.62/(b+1.15)*(b+4.08)*(b+7.26)*(b+10.37)
    & *(b+13.43)*(b+16.46)
    & /((b+4.27)*(b+7.37)*(b+10.45)*(b+13.49)
    & *(b+16.5))
    Psca=-ci*pi/4*(k*w)**2*sin(phi0)*sin(phi)*Ke
  else
    a=ci*2./k/w*Zo/eta
    Kh=-1/(pi/2*a+0.1*log(2.))
    Ao=log(k*w/4)+gam-ci*pi/2
    Psca=ci*pi*Kh/(1+Ao*Kh)
  endif

```

```

c...Outputting the far field magnitude and phase
print *, ' d = ', d
print *, ' Analytical: |Psca| = ', cabs(Psca),
& ' arg Psca = ', 180/pi*(atan2(aimag(Psca), Real(Psca)))
write(3,*) d, cabs(Psca)
write(4,*) d, 180/pi*(atan2(aimag(Psca), Real(Psca)))

      d=d+dstep
700  continue

      print *, ' Again (1=yes) ? '
      read(*,1)ians
      if(ians .eq. 1) GOTO 10

800  call exit
      END

```

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