

Parallel MR Image Reconstruction Using Augmented Lagrangian Methods

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Abstract—Magnetic resonance image (MRI) reconstruction using SENSitivity Encoding (SENSE) requires regularization to suppress noise and aliasing effects. Edge-preserving and sparsity-based regularization criteria can improve image quality, but they demand computation-intensive nonlinear optimization. In this paper, we present novel methods for regularized MRI reconstruction from undersampled sensitivity encoded data—SENSE-reconstruction—using the augmented Lagrangian (AL) framework for solving large-scale constrained optimization problems. We first formulate regularized SENSE-reconstruction as an unconstrained optimization task and then convert it to a set of (equivalent) constrained problems using *variable splitting*. We then attack these constrained versions in an AL framework using an *alternating minimization* method, leading to algorithms that can be implemented easily. The proposed methods are applicable to a general class of regularizers that includes popular edge-preserving (e.g., total-variation) and sparsity-promoting (e.g., ℓ_1 -norm of wavelet coefficients) criteria and combinations thereof. Numerical experiments with synthetic and *in vivo* human data illustrate that the proposed AL algorithms converge faster than both general-purpose optimization algorithms such as nonlinear conjugate gradient (NCG) and state-of-the-art MFISTA.

Index Terms—Augmented Lagrangian, image reconstruction, parallel magnetic resonance imaging (MRI), regularization, sensitivity encoding (SENSE).

I. INTRODUCTION

PARALLEL MR imaging (pMRI) exploits spatial sensitivity of an array of receiver coils to reduce the number of required Fourier encoding steps, thereby accelerating MR scanning. SENSitivity Encoding (SENSE) [1], [2] is a popular pMRI technique where reconstruction is performed by solving a linear system that explicitly depends on the sensitivity maps of the coil array. While efficient reconstruction methods have been devised for SENSE with Cartesian [1], as well as non-Cartesian k -space trajectories [2], they inherently suffer from SNR degradation in the presence of noise [1] mainly due to k -space undersampling and instability arising from correlation in sensitivity maps [3].

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Regularization is an attractive means of restoring stability in the reconstruction mechanism where prior information can also be incorporated effectively [3]–[9]. Tikhonov-like quadratic regularization [3]–[6] leads to a closed-form solution (under a Gaussian noise model) that can be numerically implemented efficiently. However, with the advent of compressed sensing (CS) theory, sparsity-promoting regularization criteria (e.g., ℓ_1 -based regularization) have gained popularity in MRI [10]. The basic assumption underlying CS-MRI is that many MR images are inherently sparse in some transform domain and can be reconstructed with high accuracy from significantly undersampled k -space data by minimizing transform-domain sparsity-promoting regularization criteria subject to data-consistency. The CS framework is apt for pMRI [11] with undersampled data. This paper investigates the problem of regularized reconstruction from sensitivity encoded data—SENSE-reconstruction—using sparsity-promoting regularizers. We formulate regularized SENSE-reconstruction as an unconstrained optimization problem where we obtain the reconstructed image, $\hat{\mathbf{x}}$, by minimizing a cost function, $J(\mathbf{x})$, composed of a regularization term, $\Psi(\mathbf{x})$, and a (negative) log-likelihood term corresponding to the noise model. For Ψ , we consider a general class of functionals that includes popular edge-preserving (e.g., total-variation) and sparsity-promoting (e.g., ℓ_1 -norm of wavelet coefficients) criteria and combinations thereof. Such regularization criteria are “non-smooth” (i.e., they may not be differentiable everywhere) and they require solving a nonlinear optimization problem using iterative algorithms.

This paper presents accelerated algorithms for regularized SENSE-reconstruction using the augmented Lagrangian (AL) formalism. The AL framework was originally developed for solving constrained optimization problems [12]; one combines the function to be minimized with a Lagrange multiplier term and a penalty term for the constraints, and minimizes it iteratively (while taking care to update the Lagrange parameters) to solve the original constrained problem. This combination overcomes the shortcomings of the Lagrange multiplier method and penalty-based methods for solving constrained problems [12]. To use the AL formalism for regularized SENSE-reconstruction, we first convert the unconstrained problem in to an equivalent constrained optimization problem using a technique called *variable splitting* where auxiliary variables take the place of linear transformations of \mathbf{x} in the cost function J . Then, we construct a corresponding AL function and minimize it alternately with respect to one auxiliary variable at a time—this step forms the key ingredient as it decouples the minimization process and simplifies optimization. We investigate different variable-splitting approaches and correspondingly design different AL algorithms for solving the original unconstrained

SENSE-reconstruction problem. We also propose to use a diagonal weighting term in the AL formalism to induce suitable balance between various constraints because the matrix-elements associated with Fourier encoding and the sensitivity maps can be of different orders of magnitude in SENSE. The proposed AL algorithms are applicable for regularized SENSE-reconstruction from data acquired on arbitrary non-Cartesian k -space trajectories. Based on numerical experiments with synthetic and real data, we demonstrate that the proposed AL algorithms converge faster (to an actual solution of the original unconstrained regularized SENSE-reconstruction problem) compared to general-purpose optimization algorithms such as NCG (that has been applied for CS-(p)MRI in [10] and [11]), and the recently proposed state-of-the-art monotone fast iterative shrinkage-thresholding algorithm (MFISTA) [13].

The paper is organized as follows. Section II formulates the regularized SENSE-reconstruction problem (with sparsity-based regularization) as an unconstrained optimization task. Next, we concentrate on the development of AL-based algorithms. First, Section III presents a quick overview of AL framework. Then, Section IV applies the AL formalism to regularized SENSE-reconstruction in detail. Here, we discuss various strategies for applying variable splitting and develop different AL algorithms for regularized SENSE-reconstruction. Section V is dedicated to numerical experiments and results. Section VI discusses possible extensions of the proposed AL methods to handle some variations of SENSE-reconstruction such as that proposed in [14]. Finally, we draw our conclusions in Section VII.

II. PROBLEM FORMULATION

We consider the discretized SENSE MR imaging model given by

$$\mathbf{d} = \mathbf{F} \mathbf{S} \mathbf{x} + \boldsymbol{\varepsilon} \quad (1)$$

where \mathbf{x} is a $N \times 1$ column vector containing the samples of the unknown image to be reconstructed (e.g., a 2-D slice of a 3-D MRI volume), \mathbf{d} and $\boldsymbol{\varepsilon}$ are $ML \times 1$ column vectors corresponding to the data-samples from L coils and noise, respectively, \mathbf{S} is a $NL \times N$ matrix given by $\mathbf{S} = [\mathbf{S}_1^H \dots \mathbf{S}_L^H]^H$, \mathbf{S}_l is a $N \times N$ (possibly complex) diagonal matrix corresponding to the sensitivity map of the l th coil, $1 \leq l \leq L$, $(\cdot)^H$ represents the Hermitian-transpose, \mathbf{F} is a $ML \times NL$ matrix given by $\mathbf{F} = \mathbf{I}_L \otimes \mathbf{F}_u$, \mathbf{F}_u is a $M \times N$ Fourier encoding matrix, \mathbf{I}_L is the identity matrix of size L and \otimes denotes the Kronecker product. The subscript “u” in \mathbf{F}_u signifies the fact that the k -space may be undersampled to reduce scan time, i.e., $M \leq N$.

Given an estimate of the sensitivity maps \mathbf{S} , the SENSE-reconstruction problem is to find \mathbf{x} from data \mathbf{d} . Since regularization is an attractive means of reducing aliasing artifacts and the effect of noise in the reconstruction (by incorporating prior knowledge), we formulate the problem in a penalized-likelihood setting where the reconstruction is obtained by minimizing a cost criterion

$$\mathbf{P0} : \hat{\mathbf{x}} = \arg \min_{\mathbf{x}} \left\{ J(\mathbf{x}) = \frac{1}{2} \|\mathbf{d} - \mathbf{F} \mathbf{S} \mathbf{x}\|_{\mathbf{K}_{ML}}^2 + \Psi(\mathbf{x}) \right\} \quad (2)$$

where \mathbf{K}_{ML} is the inverse of the $ML \times ML$ noise covariance matrix, $\|\mathbf{u}\|_{\mathbf{K}_{ML}}^2 = \mathbf{u}^H \mathbf{K}_{ML} \mathbf{u}$, and Ψ represents a suitable regularizer. We have included \mathbf{K}_{ML} in the data-fidelity term to account for the fact that noise from different coils may be correlated [1], [2]. Assuming that noise is wide-sense stationary and is correlated only over space (i.e., coils) and not over k -space, \mathbf{K}_{ML} can be written as $\mathbf{K}_{ML} = \mathbf{K}_s \otimes \mathbf{I}_M$, where \mathbf{K}_s is a $L \times L$ matrix that corresponds to the inverse of the covariance matrix of the spatial component of noise (from L coils).

The weighting matrix \mathbf{K}_{ML} can be eliminated from J in (2) by applying a noise-decorrelation procedure [2]: Since \mathbf{K}_s is generally positive definite, we write $\mathbf{K}_s = \tilde{\mathbf{K}}_s^H \tilde{\mathbf{K}}_s$, and $\mathbf{K}_{ML} = \tilde{\mathbf{K}}_{ML}^H \tilde{\mathbf{K}}_{ML}$, where $\tilde{\mathbf{K}}_{ML} = \tilde{\mathbf{K}}_s \otimes \mathbf{I}_M$. Then, because of the structures of $\tilde{\mathbf{K}}_{ML}$ and \mathbf{F} , we have that [2]

$$\begin{aligned} \tilde{\mathbf{K}}_{ML} \mathbf{F} &= (\tilde{\mathbf{K}}_s \otimes \mathbf{I}_M)(\mathbf{I}_L \otimes \mathbf{F}_u) = (\tilde{\mathbf{K}}_s \mathbf{I}_L \otimes \mathbf{I}_M \mathbf{F}_u) \\ &= (\mathbf{I}_L \tilde{\mathbf{K}}_s \otimes \mathbf{F}_u \mathbf{I}_N) = (\mathbf{I}_L \otimes \mathbf{F}_u)(\tilde{\mathbf{K}}_s \otimes \mathbf{I}_N) = \mathbf{F} \tilde{\mathbf{K}}_{NL} \end{aligned}$$

where $\tilde{\mathbf{K}}_{NL} \triangleq \tilde{\mathbf{K}}_s \otimes \mathbf{I}_N$. Letting

$$\tilde{\mathbf{d}} \triangleq \tilde{\mathbf{K}}_{ML} \mathbf{d} \quad (3)$$

$$\tilde{\mathbf{S}} \triangleq \tilde{\mathbf{K}}_{NL} \mathbf{S} \quad (4)$$

we therefore get that

$$\frac{1}{2} \|\mathbf{d} - \mathbf{F} \mathbf{S} \mathbf{x}\|_{\mathbf{K}_{ML}}^2 = \frac{1}{2} \|\tilde{\mathbf{d}} - \mathbf{F} \tilde{\mathbf{S}} \mathbf{x}\|_2^2 \quad (5)$$

which is an equivalent unweighted data-fidelity term¹ with a new set of sensitivity maps $\tilde{\mathbf{S}}$ obtained by weighting the original sensitivity maps \mathbf{S} with $\tilde{\mathbf{K}}_{NL}$. In the sequel, we use the right-hand side of (5) for data-fidelity and drop the \sim for ease of notation. In the numerical experiments, we used (3) and (4).

We consider sparsity-promoting regularization for Ψ based on the field of compressed sensing for MRI—CS-MRI [10], [11]. We focus on the “analysis form” of the reconstruction problem where the regularization is a function of the unknown image \mathbf{x} . Specifically, we consider a general class of regularizers that use a sum of Q terms given by

$$\Psi(\mathbf{x}) = \sum_{q=1}^Q \lambda_q \sum_{n=1}^{N_q} \Phi_{qn} \left(\sum_{p=1}^{P_q} |[\mathbf{R}_{pq} \mathbf{x}]_n|^{m_q} \right) \quad (6)$$

where q indexes the regularization terms, the parameter $\lambda_q > 0$ controls the strength of the q th regularization term, and $[\mathbf{x}]_n$ or x_n represents the n th element of the vector \mathbf{x} . The $N_q \times N$ matrices \mathbf{R}_{pq} , $p = 1, \dots, P_q \forall q$, represent sparsifying operators. We focus on shift-invariant operators for \mathbf{R}_{pq} (e.g., tight frames, finite-differencing matrices), but the methods can be applied to shift-variant ones such as orthonormal wavelets with only minor modifications. Typically, $P_q \ll M, N \forall q$ (as seen in the examples below). We consider that the values of m_q and the choice of potential functions $\Phi_{qn} \forall q$ and n are such that Ψ is composed of nonquadratic convex regularization terms.

The general class of regularizers (6) includes popular sparsity-promoting regularization criteria such as follows.

¹The right-hand side of (5) automatically includes the special case of $\mathbf{K}_{ML} = \mathbf{I}_{ML}$ with $\tilde{\mathbf{S}} = \mathbf{S}$ and $\tilde{\mathbf{d}} = \mathbf{d}$.

- 1) ℓ_1 -norm of wavelet coefficients: $Q = 1$, $P_1 = 1$, $m_1 = 1$, $\mathbf{R}_{11} = \mathbf{W}$ is a wavelet transform (orthonormal or a tight frame), and $\Phi_{1n}(x) = x$ where n indexes the rows of \mathbf{R}_{11} .
- 2) Discrete isotropic total-variation (TV) regularization [15]: $Q = 1$, $P_1 = 2$, $m_1 = 2$, \mathbf{R}_{11} and \mathbf{R}_{21} represent horizontal and vertical finite-differencing matrices, respectively, and $\Phi_{1n}(x) = \sqrt{x}$, where n indexes the rows of \mathbf{R}_{11} .
- 3) Discrete anisotropic total-variation (TV) regularization [15]: $Q = 1$, $P_1 = 2$, $m_1 = 1$, \mathbf{R}_{11} and \mathbf{R}_{21} represent horizontal and vertical finite-differencing matrices, respectively, and $\Phi_{1n}(x) = x$, where n indexes rows of \mathbf{R}_{11} .

The general form (6) also allows the use of a variety of potential functions for Φ . We consider such a generalization because combinations of wavelet- and TV-regularization have been reported to be preferable [10]. The proposed methods can be easily generalized for synthesis-based formulations [16].

The minimization in (2) is a nontrivial optimization task, even for only one regularization term. Although general purpose optimization techniques such as the nonlinear conjugate gradient (NCG) method or iteratively reweighted least squares can be applied to differentiable approximations of $\mathbf{P0}$, they may either be computation-intensive or exhibit slow convergence. This paper describes new techniques based on the augmented Lagrangian (AL) formalism that yield faster convergence per unit computation time.

The basic idea is to break down $\mathbf{P0}$ in to smaller tasks by introducing “artificial” constraints that are designed so that the subproblems become decoupled and can be solved relatively rapidly [15], [17]–[20]. We first briefly review the AL method and then discuss some strategies for applying it to $\mathbf{P0}$.

III. CONSTRAINED OPTIMIZATION AND AUGMENTED LAGRANGIAN (AL) FORMALISM

Consider the following optimization problem with linear equality constraints:

$$\hat{\mathbf{u}} = \arg \min_{\mathbf{u} \in \Omega^N} f(\mathbf{u}) \text{ subject to } \mathbf{C}\mathbf{u} = \mathbf{b} \quad (7)$$

where Ω is \mathbb{R} or \mathbb{C} , f is a real convex function, \mathbf{C} is a $M \times N$ (real or complex) matrix that specifies the constraint equations, and $\mathbf{b} \in \Omega^M$. In the augmented Lagrangian (AL) framework (also known as the multiplier method [12]), an AL function is first constructed for problem (7) as

$$\mathcal{L}(\mathbf{u}, \boldsymbol{\gamma}, \mu) = f(\mathbf{u}) + \boldsymbol{\gamma}^H(\mathbf{C}\mathbf{u} - \mathbf{b}) + \frac{\mu}{2} \|\mathbf{C}\mathbf{u} - \mathbf{b}\|_2^2 \quad (8)$$

where $\boldsymbol{\gamma} \in \Omega^M$ represents the vector of Lagrange multipliers, and the quadratic term on the right-hand side of above equation is called the “penalty” term² with penalty parameter³ $\mu > 0$. The

²A more general version of AL allows for the minimization of nonconvex functions subject to nonlinear equality and/or inequality constraints with non-quadratic “penalty” terms [12].

³For nonconvex problems, there may exist a positive lower bound on the possible values of μ for establishing convergence [12, Prop. 1], [21, p. 519].

AL scheme [12] for solving (7) alternates between minimizing $\mathcal{L}(\mathbf{u}, \boldsymbol{\gamma}, \mu)$ with respect to \mathbf{u} for a fixed $\boldsymbol{\gamma}$ and updating $\boldsymbol{\gamma}$, i.e.,

$$\mathbf{u}^{(j+1)} = \arg \min_{\mathbf{u}} \mathcal{L}(\mathbf{u}, \boldsymbol{\gamma}^{(j)}, \mu), \quad (9)$$

$$\boldsymbol{\gamma}^{(j+1)} = \boldsymbol{\gamma}^{(j)} + \mu(\mathbf{C}\mathbf{u}^{(j+1)} - \mathbf{b}) \quad (10)$$

until some stopping criterion is satisfied.

So-called “penalty methods” [12] correspond to the case where $\boldsymbol{\gamma} = \mathbf{0}$ and (9) is solved repeatedly while increasing $\mu \rightarrow \infty$. The AL scheme (9)–(10) also permits the use of increasing sequences of μ -values, but an important aspect of the AL scheme is that convergence may be guaranteed without the need for changing μ [12].

The AL scheme is also closely related to the Bregman iterations [15, Eq. (2.6)–(2.8)] applied to problem (7)

$$\mathbf{u}^{(j+1)} = \arg \min_{\mathbf{u}} D_f(\mathbf{u}, \mathbf{u}^{(j)}, \boldsymbol{\rho}^{(j)}) + \frac{\mu}{2} \|\mathbf{C}\mathbf{u} - \mathbf{b}\|_2^2 \quad (11)$$

$$\boldsymbol{\rho}^{(j+1)} = \boldsymbol{\rho}^{(j)} - \mu \mathbf{C}^H(\mathbf{C}\mathbf{u}^{(j+1)} - \mathbf{b}) \quad (12)$$

where $D_f(\mathbf{u}, \mathbf{v}, \boldsymbol{\rho}) = f(\mathbf{u}) - f(\mathbf{v}) - \boldsymbol{\rho}^H(\mathbf{u} - \mathbf{v})$ is called the “Bregman distance” [15] and $\boldsymbol{\rho}$ is a $N \times 1$ vector in the subgradient of f at \mathbf{u} . The connection between AL method and Bregman iterations is readily established if $\boldsymbol{\rho} = -\mathbf{C}^H \boldsymbol{\gamma}$ [22]. Then, $D_f(\mathbf{u}, \mathbf{u}^{(j)}, \boldsymbol{\rho}^{(j)}) + (\mu/2) \|\mathbf{C}\mathbf{u} - \mathbf{b}\|_2^2$ is identical to $\mathcal{L}(\mathbf{u}, \boldsymbol{\gamma}^{(j)}, \mu)$ (up to constants irrelevant for optimization) and (9) and (10) become equivalent to (11)–(12) as noted in [22], [23].

The AL function \mathcal{L} in (8) can be rewritten by grouping together the terms involving $\mathbf{C}\mathbf{u} - \mathbf{b}$ as

$$\mathcal{L}(\mathbf{u}, \boldsymbol{\eta}, \mu) = f(\mathbf{u}) + \frac{\mu}{2} \|\mathbf{C}\mathbf{u} - \boldsymbol{\eta}\|_2^2 + C_{\boldsymbol{\gamma}} \quad (13)$$

where $\boldsymbol{\eta} \triangleq \mathbf{b} - (1/\mu)\boldsymbol{\gamma}$, and $C_{\boldsymbol{\gamma}}$ is a constant independent of \mathbf{u} that we ignore henceforth. The parameter $\boldsymbol{\gamma}$ can then be replaced by $\boldsymbol{\eta}$ in (10) which results in the following version of AL algorithm for solving (7).

Algorithm AL

1. Select $\mathbf{u}^{(0)}$, $\boldsymbol{\eta}^{(0)}$, and $\mu > 0$; set $j = 0$

Repeat

2. $\mathbf{u}^{(j+1)} = \arg \min_{\mathbf{u}} \{f(\mathbf{u}) + (\mu/2) \|\mathbf{C}\mathbf{u} - \boldsymbol{\eta}^{(j)}\|_2^2\}$

3. $\boldsymbol{\eta}^{(j+1)} = \boldsymbol{\eta}^{(j)} - (\mathbf{C}\mathbf{u}^{(j+1)} - \mathbf{b})$

4. Set $j = j + 1$

Until stop-criterion is met

It has been shown in [15, Theorem 2.2] that the Bregman iterations (11)–(12)—equivalently, the AL algorithm under above mentioned conditions—converge to a solution of (7) whenever the minimization in (11)—in turn, Step 2 of the AL algorithm—is performed exactly. However, this step may be computationally expensive and is often replaced in practice by an inexact minimization [12], [15], [17]. Numerical evidence in [15] suggests that inexact minimizations can still be effective in the Bregman/AL scheme.

IV. PROPOSED AL ALGORITHMS FOR REGULARIZED SENSE-RECONSTRUCTION

Our strategy is to first transform the unconstrained problem **P0** into a constrained optimization task as follows. We replace linear transformations of \mathbf{x} ($\mathbf{F}\mathbf{S}\mathbf{x}$, and $\mathbf{R}_{pq}\mathbf{x}$) in J with a set of auxiliary variables $\{\mathbf{u}_l\}$. Then, we frame **P0** as a constrained problem where J is minimized as a function of $\{\mathbf{u}_l\}$ subject to the constraint that each auxiliary variable, \mathbf{u}_l , equals the respective linear transformation of \mathbf{x} . We handle the resulting constrained optimization task (that is equivalent to **P0**) in the AL framework described in Section III.

The technique of introducing auxiliary variables $\{\mathbf{u}_l\}$ is also known as *variable splitting*; it has been employed, for instance, in [15], [18]–[20] for image deconvolution, in-painting and CS-MRI with wavelets- and TV-based regularization in a Bregman/AL framework and in [17] for developing a fast penalty-based algorithm for TV image restoration. The purpose of variable splitting is to make the associated AL function \mathcal{L} amenable to alternating minimization methods [15], [17], [24]–[26] which may decouple the minimization of \mathcal{L} with respect to the auxiliary variables. This makes (9) easier to accomplish compared to directly solving the original unconstrained problem **P0**.

The splitting procedures used in [15], [17], [19] introduce auxiliary variables only for decoupling the effect of regularization. In this work, in addition to splitting the regularization, we also propose to use one or more auxiliary variables to separate the terms involving \mathbf{F} and \mathbf{S} (see Section IV-B). The AL-based techniques in [18], [20] also use auxiliary variables for the data-fidelity term, but they pertain to problems of the form

$$\min_{\mathbf{u}, \mathbf{v}} f(\mathbf{v}) \text{ subject to } \mathbf{v} = \mathbf{C}\mathbf{u}$$

where \mathbf{C} is a “tall,” i.e., block-column matrix and are not directly applicable to (7) with some instances of \mathbf{C} investigated in this paper (see Sections IV-B and VI-C). Furthermore, in general, different splitting mechanisms yield different algorithms as they attempt to solve constrained optimization problems (that are equivalent to **P0**) with different constraints. In this paper, we investigate two splitting schemes for **P0**, described below.

A. Splitting the Regularization Term

In the first form, we split the regularization term by introducing $\mathbf{u}_1 = \mathbf{R}\mathbf{x} \in \mathbb{C}^R$, where $\mathbf{R} = [\mathbf{R}_{11}^H \cdots \mathbf{R}_{P_q Q}^H]^H$ and R is the number of rows in \mathbf{R} . This form is similar to the split-Bregman scheme proposed in [15, Sec. 4.2]. The resulting constrained formulation of **P0** is given by

$$\mathbf{P1} : \min_{\mathbf{u}_1, \mathbf{x}} J_1(\mathbf{x}, \mathbf{u}_1) \text{ subject to } \mathbf{u}_1 = \mathbf{R}\mathbf{x}$$

where

$$J_1(\mathbf{x}, \mathbf{u}_1) \triangleq \frac{1}{2} \|\mathbf{d} - \mathbf{F}\mathbf{S}\mathbf{x}\|^2 + \sum_{q=1}^Q \lambda_q \sum_{n=1}^{N_q} \Phi_{qn} \left(\sum_{p=1}^{P_q} |[\mathbf{u}_{1pq}]_n|^{m_q} \right)$$

and $\mathbf{u}_{1pq} = \mathbf{R}_{pq}\mathbf{x}$, $p = 1, \dots, P_q \forall q$. Problem **P1** can be written in the general form of (7) with

$$\mathbf{u} = \begin{bmatrix} \mathbf{u}_1 \\ \mathbf{x} \end{bmatrix}, f(\mathbf{u}) = J_1(\mathbf{x}, \mathbf{u}_1), \mathbf{C} = [\mathbf{I}_R - \mathbf{R}], \mathbf{b} = \mathbf{0}.$$

The associated AL function (8) is therefore

$$\mathcal{L}_1(\mathbf{u}, \boldsymbol{\gamma}_1, \mu) = J_1(\mathbf{x}, \mathbf{u}_1) + \boldsymbol{\gamma}_1^H \mathbf{C}\mathbf{u} + \frac{\mu}{2} \|\mathbf{C}\mathbf{u}\|_2^2.$$

The AL function \mathcal{L}_1 can be written in the form of (13) (ignoring irrelevant constants) as

$$\mathcal{L}_1(\mathbf{u}, \boldsymbol{\eta}_1, \mu) = J_1(\mathbf{x}, \mathbf{u}_1) + \frac{\mu}{2} \|\mathbf{C}\mathbf{u} - \boldsymbol{\eta}_1\|^2 \quad (14)$$

where $\boldsymbol{\eta}_1 = -(1/\mu)\boldsymbol{\gamma}_1$. Applying the **AL** algorithm to **P1** requires the joint minimization of \mathcal{L}_1 with respect to \mathbf{u}_1 and \mathbf{x} at Step 2. Since this can be computationally challenging, we apply an (inexact) alternating minimization method [15], [17], [19]. We alternatively minimize \mathcal{L}_1 with respect to one variable at a time while holding others constant. This decouples the individual updates of \mathbf{u}_1 and \mathbf{x} and simplifies the optimization task. Specifically, at the j th iteration, we perform the following individual minimizations, taking care to use updated variables for subsequent minimizations [15], [17]:

$$\mathbf{u}_1^{(j+1)} = \arg \min_{\mathbf{u}_1} \mathcal{L}_1(\mathbf{u}_1, \mathbf{x}^{(j)}, \boldsymbol{\eta}_1^{(j)}, \mu) \quad (15)$$

$$\mathbf{x}^{(j+1)} = \arg \min_{\mathbf{x}} \mathcal{L}_1(\mathbf{u}_1^{(j+1)}, \mathbf{x}, \boldsymbol{\eta}_1^{(j)}, \mu). \quad (16)$$

1) *Minimization With Respect to \mathbf{x}* : The minimization in (16) is straightforward since the associated cost function is quadratic. Ignoring irrelevant constants, we get that

$$\begin{aligned} \mathbf{x}^{(j+1)} &= \arg \min_{\mathbf{x}} \left\{ \frac{1}{2} \|\mathbf{d} - \mathbf{F}\mathbf{S}\mathbf{x}\|_2^2 + \frac{\mu}{2} \|\mathbf{u}_1^{(j+1)} - \mathbf{R}\mathbf{x} - \boldsymbol{\eta}_1^{(j)}\|_2^2 \right\} \\ &= \mathbf{G}_\mu^{-1} [\mathbf{S}^H \mathbf{F}^H \mathbf{d} + \mu \mathbf{R}^H (\mathbf{u}_1^{(j+1)} - \boldsymbol{\eta}_1^{(j)})] \end{aligned} \quad (17)$$

where⁴

$$\mathbf{G}_\mu = \mathbf{S}^H \mathbf{F}^H \mathbf{F} \mathbf{S} + \mu \mathbf{R}^H \mathbf{R}. \quad (18)$$

Although (17) is an analytical solution, computing \mathbf{G}_μ^{-1} is impractical for large N . Therefore, we apply a few iterations of the conjugate-gradient (CG) algorithm with *warm starting*, i.e., the CG algorithm is initialized with the estimated \mathbf{x} from the previous **AL** iteration.

2) *Minimization With Respect to \mathbf{u}_1* : Writing out (15) explicitly (ignoring constants independent of \mathbf{u}_1), we have that

$$\mathbf{u}_1^{(j+1)} = \arg \min_{\mathbf{u}_1} \left\{ \sum_{q=1}^Q \lambda_q \sum_{n=1}^{N_q} \Phi_{qn} \left(\sum_{p=1}^{P_q} |[\mathbf{u}_{1pq}]_n|^{m_q} \right) + \frac{\mu}{2} \|\mathbf{u}_1 - \mathbf{R}\mathbf{x}^{(j)} - \boldsymbol{\eta}_1^{(j)}\|_2^2 \right\}. \quad (19)$$

While (19) is a large-scale problem by itself, the splitting variable \mathbf{u}_1 decouples the different regularization terms so that (19) can be decomposed into smaller minimization tasks as follows. Let $\mathbf{r}^{(j)} = \mathbf{R}\mathbf{x}^{(j)}$; for each q and n , we collect $\mathbf{v}_{qn} = \{u_{1pqn}\}_{p=1}^{P_q}$, $\boldsymbol{\rho}_{qn}^{(j)} = \{r_{pqn}^{(j)}\}_{p=1}^{P_q}$, and $\boldsymbol{\beta}_{qn}^{(j)} = \{\eta_{1pqn}^{(j)}\}_{p=1}^{P_q}$, so that $\mathbf{v}_{qn}, \boldsymbol{\rho}_{qn}^{(j)}, \boldsymbol{\beta}_{qn}^{(j)} \in \mathbb{C}^{P_q}$. Then, (19)

⁴We design the regularization Ψ such that the nontrivial null-spaces of $\mathbf{R}^H \mathbf{R}$ and $\mathbf{S}^H \mathbf{F}^H \mathbf{F} \mathbf{S}$ are disjoint. Then, \mathbf{G}_μ is nonsingular for $\mu > 0$.

separates for each q and n as

$$\begin{aligned} & \mathbf{v}_{qn}^{(j+1)} \\ &= \arg \min_{\mathbf{v}_{qn}} \left\{ \frac{\lambda q}{\mu} \Phi_{qn} \left(\|\mathbf{v}_{qn}\|_{m_q}^{m_q} \right) + \frac{1}{2} \left\| \mathbf{v}_{qn} - (\boldsymbol{\rho}_{qn}^{(j)} + \boldsymbol{\beta}_{qn}^{(j)}) \right\|_2^2 \right\}. \end{aligned} \quad (20)$$

This is basically a P_q -dimensional denoising problem with $\boldsymbol{\rho}_{qn}^{(j)} + \boldsymbol{\beta}_{qn}^{(j)}$ playing the role of the data and where $\|\cdot\|_p$ denotes the ℓ_p -norm. Often (20) has a closed-form solution as discussed below. Otherwise, a gradient-descent-based algorithm such as NCG with warm starting can be applied for obtaining a partial update for $\mathbf{v}_{qn}^{(j+1)}$. Before proceeding, it is useful to compute the gradient of the cost function in (20). Ignoring the indices q and n and setting the gradient of the cost function in (20) to zero, we get for $\mathbf{v} \neq \mathbf{0}$ that

$$(\boldsymbol{\Theta}(\mathbf{v}) + \mathbf{I}_P)\mathbf{v}|_{\mathbf{v}=\mathbf{v}^{(j+1)}} = \boldsymbol{\rho}^{(j)} + \boldsymbol{\beta}^{(j)} \quad (21)$$

where

$$\boldsymbol{\Theta}(\mathbf{v}) \triangleq \text{diag} \left\{ \frac{\lambda m}{\mu} \Phi'(\|\mathbf{v}\|_m^m) |v_k|^{m-2} \right\} \quad (22)$$

and Φ' is the first derivative of Φ , and v_k is the k th component of \mathbf{v} . The main obstacles to obtaining a direct solution of (20) are the coupling introduced between different components of \mathbf{v} , i.e., $\Phi'(\|\mathbf{v}\|_m^m)$, and the presence of the $|v_k|^{m-2}$ in $\boldsymbol{\Theta}(\mathbf{v})$. Below we analyze some special cases of practical interest where this problem can be circumvented to obtain simple solutions.

3) *Case of ℓ_1 -Regularization:* For ℓ_1 -type regularization in (6) we set $m = 1$, $\Phi(x) = x$. Consequently, (21) further decouples in terms of the components of \mathbf{v} as

$$\left(\frac{\lambda}{\mu|v_k|} + 1 \right) v_k = \rho_k^{(j)} + \beta_k^{(j)}$$

where $v_k \neq 0$, $k = 1, 2, \dots, P$. The minimizer of (20) in this case is given by the shrinkage rule [27]

$$v_k^{(j+1)} = \text{shrink} \left\{ \rho_k^{(j)} + \beta_k^{(j)}, \frac{\lambda}{\mu} \right\} \quad \forall k,$$

where $\text{shrink}\{d, \lambda\} = (d/|d|)\max\{|d| - \lambda, 0\}$.

4) *Case of $P = 1$:* In this case, (20) reduces to 1-D minimization that can be easily achieved numerically for a general Φ or analytically for $m = 1$ and some specific instances of Φ listed in [28, Sec. 4].

5) *Case of $m = 2$ and A General Φ :* For $m = 2$, the solution of (20) is in general determined by a vector-shrinkage rule as explained below. Setting $m = 2$ in (21), we get that

$$\underbrace{\left(\frac{2\lambda}{\mu} \Phi'(\|\mathbf{v}\|_2^2) + 1 \right)}_{\chi(\|\mathbf{v}\|_2)} \mathbf{v} = \boldsymbol{\rho}^{(j)} + \boldsymbol{\beta}^{(j)}. \quad (23)$$

The bracketed term on the left-hand side is a nonnegative scalar (cf. Φ is nondecreasing), so that (23) corresponds to shrinking $\boldsymbol{\rho}^{(j)} + \boldsymbol{\beta}^{(j)}$ by an amount prescribed by $\chi(\|\mathbf{v}\|_2)$ for $\mathbf{v} \neq \mathbf{0}$.

The exact value of $\chi(\|\mathbf{v}\|_2)$ depends on \mathbf{v} and in general, there is no closed form solution to (23). Nevertheless, for given λ and μ values, (23) can be solved numerically⁵ by using a look-up table for Φ' to find the value for the shrinkage factor $\chi(\|\mathbf{v}\|_2)$ such that (23) is satisfied.

6) *Case of TV-Type Regularization:* To obtain a TV-type regularization in (6) we set $m = 2$ and $\Phi(x) = \sqrt{x}$. Correspondingly, (21) becomes

$$\chi(\|\mathbf{v}\|_2)\mathbf{v} = \boldsymbol{\rho}^{(j)} + \boldsymbol{\beta}^{(j)} \quad (24)$$

where $\chi(\|\mathbf{v}\|_2) = ((\lambda/\mu)\|\mathbf{v}\|_2 + 1)$ for $\mathbf{v} \neq \mathbf{0}$. In this case, an exact value for χ can be found as shown below. Taking ℓ_2 -norm of the vectors on both sides of (24) and manipulating, we get that $\|\mathbf{v}\|_2|_{\mathbf{v}=\mathbf{v}^{(j+1)}} = \|\boldsymbol{\rho}^{(j)} + \boldsymbol{\beta}^{(j)}\|_2 - \lambda/\mu$, and

$$\chi(\|\mathbf{v}^{(j+1)}\|_2) = \left(\frac{\|\boldsymbol{\rho}^{(j)} + \boldsymbol{\beta}^{(j)}\|_2}{\|\boldsymbol{\rho}^{(j)} + \boldsymbol{\beta}^{(j)}\|_2 - \frac{\lambda}{\mu}} \right)$$

which leads to the following vector-shrinkage rule [15], [17], [22]

$$\mathbf{v}^{(j+1)} = \text{shrink}_{\text{vec}} \left\{ \boldsymbol{\rho}^{(j)} + \boldsymbol{\beta}^{(j)}, \frac{\lambda}{\mu} \right\}$$

where $\text{shrink}_{\text{vec}}\{\mathbf{d}, \lambda\} \triangleq (\mathbf{d}/\|\mathbf{d}\|_2) \max\{\|\mathbf{d}\|_2 - \lambda, 0\}$. It is also possible to derive closed-form solutions of (20) for $m = 2$ for some instances of Φ listed in [28, Sec. 4]. In summary, the minimization problem (20) is fairly simple and fast typically.

7) *AL Algorithm for Problem P1:* Combining the results from Sections IV-A1 to IV-A6, we now present the first AL algorithm (that is similar to the split-Bregman scheme [15]) for solving the constrained optimization problem **P1**, formulated as a tractable alternative to the original unconstrained problem **P0**.

AL-P1: AL Algorithm for solving problem P1

1. Select $\mathbf{x}^{(0)}$ and $\mu > 0$
 2. Precompute $\mathbf{S}^H \mathbf{F}^H \mathbf{d}$; set $\boldsymbol{\eta}_1^{(0)} = \mathbf{0}$ and $j = 0$
- Repeat:**
3. Obtain an update $\mathbf{u}_1^{(j+1)}$ using an appropriate technique as described in **Sections IV-A2 to IV-A6**
 4. Obtain an update $\mathbf{x}^{(j+1)}$ by running few CG iterations on (17)
 5. $\boldsymbol{\eta}_1^{(j+1)} = \boldsymbol{\eta}_1^{(j)} - (\mathbf{u}_1^{(j+1)} - \mathbf{R}\mathbf{x}^{(j+1)})$
 6. Set $j = j + 1$
- Until** stop-criterion is met

The most complex step of this algorithm is using CG to solve (17). We now present an alternative algorithm that simplifies computation further.

⁵Taking the ℓ_2 -norm of the vectors on both sides of (23), we see that (23) entails solving a 1-D problem of the form $(\lambda\Phi'(x^2) + 1)x = d$, for x .

B. Splitting the Fourier Encoding and Spatial Components in the Data-Fidelity Term

Since the data-fidelity term is composed of components (\mathbf{S} and \mathbf{F}) that act on the unknown image in different domains (spatial and k -space, respectively) it is natural to introduce auxiliary variables to split these two components. Specifically, we now consider the constrained problem

$$\mathbf{P2} : \min_{\mathbf{u}_0, \mathbf{u}_1, \mathbf{u}_2, \mathbf{x}} J_2(\mathbf{u}_0, \mathbf{u}_1) \text{ subject to} \\ \mathbf{u}_0 = \mathbf{S}\mathbf{x}, \mathbf{u}_1 = \mathbf{R}\mathbf{u}_2 \text{ and } \mathbf{u}_2 = \mathbf{x}$$

where $\mathbf{u}_0 \in \mathbb{C}^{NL}$, $\mathbf{u}_1 \in \mathbb{C}^R$, $\mathbf{u}_2 \in \mathbb{C}^N$, and

$$J_2(\mathbf{u}_0, \mathbf{u}_1) \triangleq \frac{1}{2} \|\mathbf{d} - \mathbf{F}\mathbf{u}_0\|^2 + \sum_{q=1}^Q \lambda_q \sum_{n=1}^{N_q} \Phi_{qn} \left(\sum_{p=1}^{P_q} |[\mathbf{u}_1]_{pq}|^n \right)^{m_q}.$$

Clearly, $\mathbf{P2}$ is equivalent to $\mathbf{P0}$. The new variable \mathbf{u}_2 simplifies the implementation by decoupling \mathbf{u}_0 and \mathbf{u}_1 . In terms of the general AL formulation (7), $\mathbf{P2}$ is written as

$$\mathbf{u} = \begin{bmatrix} \mathbf{u}_0 \\ \mathbf{u}_1 \\ \mathbf{u}_2 \\ \mathbf{x} \end{bmatrix}, \quad f(\mathbf{u}) = J_2(\mathbf{u}_0, \mathbf{u}_1), \quad \mathbf{C} = \mathbf{A}\mathbf{B}, \quad \mathbf{b} = \begin{bmatrix} \mathbf{0} \\ \mathbf{0} \\ \mathbf{0} \\ \mathbf{0} \end{bmatrix}$$

where

$$\mathbf{A} = \begin{bmatrix} \mathbf{I}_{NL} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \sqrt{\nu_1} \mathbf{I}_R & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \sqrt{\nu_2} \mathbf{I}_N \end{bmatrix} \\ \mathbf{B} = \begin{bmatrix} \mathbf{I}_{NL} & \mathbf{0} & \mathbf{0} & -\mathbf{S} \\ \mathbf{0} & \mathbf{I}_R & -\mathbf{R} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{I}_N & -\mathbf{I}_N \end{bmatrix}.$$

We have introduced a diagonal weighting matrix \mathbf{A} in the constraint equation whose purpose will be explained below. Using \mathbf{A} does not alter problem $\mathbf{P2}$ as long as $\nu_{1,2} > 0$. The associated AL function (8) is given by

$$\mathcal{L}_2(\mathbf{u}, \boldsymbol{\gamma}_2, \mu) = J_2(\mathbf{u}_0, \mathbf{u}_1) + \boldsymbol{\gamma}_1^H \mathbf{A}\mathbf{B}\mathbf{u} + \frac{\mu}{2} \|\mathbf{B}\mathbf{u}\|_{\mathbf{A}}^2$$

where $\boldsymbol{\gamma}_2 = [\boldsymbol{\gamma}_{20}^H \ \boldsymbol{\gamma}_{21}^H \ \boldsymbol{\gamma}_{22}^H]^H$, one component for each row of \mathbf{B} . Then, we write \mathcal{L}_2 in the form of (13) (without irrelevant constants) as

$$\mathcal{L}_2(\mathbf{u}, \boldsymbol{\eta}_2, \mu) = J_2(\mathbf{u}_0, \mathbf{u}_1) + \frac{\mu}{2} \|\mathbf{B}\mathbf{u} - \boldsymbol{\eta}_2\|_{\mathbf{A}}^2 \quad (25)$$

where $\boldsymbol{\eta}_2 \triangleq [\boldsymbol{\eta}_{20}^H \ \boldsymbol{\eta}_{21}^H \ \boldsymbol{\eta}_{22}^H]^H = -(1/\mu)\mathbf{A}^{-1}\boldsymbol{\gamma}_2$. From (25), we see that \mathbf{A} specifies the relative influence of the constraints individually while μ determines the overall influence of the constraints on \mathcal{L}_2 . Note again that the final solution of $\mathbf{P2}$ does not depend on any of μ , ν_1 , or ν_2 .

We again apply alternating minimization to (25) (ignoring irrelevant constants) to obtain the following subproblems:

$$\mathbf{u}_0^{(j+1)} = \arg \min_{\mathbf{u}_0} \left\{ \frac{1}{2} \|\mathbf{d} - \mathbf{F}\mathbf{u}_0\|^2 + \frac{\mu}{2} \|\mathbf{u}_0 - \mathbf{S}\mathbf{x}^{(j)} - \boldsymbol{\eta}_{20}^{(j)}\|_2^2 \right\} \quad (26)$$

$$\mathbf{u}_1^{(j+1)} = \arg \min_{\mathbf{u}_1} \left\{ \sum_{q=1}^Q \lambda_q \sum_{n=q}^{N_q} \Phi_{qn} \left(\sum_{p=1}^{P_q} |[\mathbf{u}_1]_{pq}|^n \right)^{m_q} + \frac{\mu\nu_1}{2} \|\mathbf{u}_1 - \mathbf{R}\mathbf{u}_2^{(j)} - \boldsymbol{\eta}_{21}^{(j)}\|_2^2 \right\} \quad (27)$$

$$\mathbf{u}_2^{(j+1)} = \arg \min_{\mathbf{u}_2} \left\{ \frac{\mu\nu_1}{2} \|\mathbf{u}_1^{(j+1)} - \mathbf{R}\mathbf{u}_2 - \boldsymbol{\eta}_{21}^{(j)}\|_2^2 + \frac{\mu\nu_2}{2} \|\mathbf{u}_2 - \mathbf{x}^{(j)} - \boldsymbol{\eta}_{22}^{(j)}\|_2^2 \right\} \quad (28)$$

$$\mathbf{x}^{(j+1)} = \arg \min_{\mathbf{x}} \left\{ \frac{\mu}{2} \|\mathbf{u}_0^{(j+1)} - \mathbf{S}\mathbf{x} - \boldsymbol{\eta}_{20}^{(j)}\|_2^2 + \frac{\mu\nu_2}{2} \|\mathbf{u}_2^{(j+1)} - \mathbf{x} - \boldsymbol{\eta}_{22}^{(j)}\|_2^2 \right\}. \quad (29)$$

The minimization in (27) is exactly same as the one in (19) except that we now have $\mathbf{R}\mathbf{u}_2$ instead of $\mathbf{R}\mathbf{x}$ in the quadratic part of the cost. Therefore, we apply the techniques described in Sections IV-A2 to IV-A6 to solve (27).

1) *Minimization With Respect to $\mathbf{u}_{0,2}$ and \mathbf{x}* : The cost functions in (26), (28), and (29) are all quadratic and thus have closed-form solutions as follows:

$$\mathbf{u}_0^{(j+1)} = \mathbf{H}_\mu^{-1} [\mathbf{F}^H \mathbf{d} + \mu(\mathbf{S}\mathbf{x}^{(j)} + \boldsymbol{\eta}_{20}^{(j)})] \quad (30)$$

$$\mathbf{u}_2^{(j+1)} = \mathbf{H}_{\nu_1\nu_2}^{-1} \left[\mathbf{R}^H (\mathbf{u}_1^{(j+1)} - \boldsymbol{\eta}_{21}^{(j)}) + \frac{\nu_2}{\nu_1} (\mathbf{x}^{(j)} + \boldsymbol{\eta}_{22}^{(j)}) \right] \quad (31)$$

$$\mathbf{x}^{(j+1)} = \mathbf{H}_{\nu_2}^{-1} \left[\mathbf{S}^H (\mathbf{u}_0^{(j+1)} - \boldsymbol{\eta}_{20}^{(j)}) + \nu_2 (\mathbf{u}_2^{(j+1)} - \boldsymbol{\eta}_{22}^{(j)}) \right] \quad (32)$$

where

$$\mathbf{H}_\mu = \mathbf{F}^H \mathbf{F} + \mu \mathbf{I}_{NL} \quad (33)$$

$$\mathbf{H}_{\nu_1\nu_2} = \mathbf{R}^H \mathbf{R} + \frac{\nu_2}{\nu_1} \mathbf{I}_N \quad (34)$$

$$\mathbf{H}_{\nu_2} = \mathbf{S}^H \mathbf{S} + \nu_2 \mathbf{I}_N. \quad (35)$$

We show below that these matrices can be inverted efficiently thereby avoiding the more difficult \mathbf{G}_μ^{-1} in (17). We have proposed using \mathbf{A} to ensure suitable balance between the various constraints (equivalently, the block-rows of \mathbf{B}) since the block-rows of \mathbf{B} may be of different orders of magnitude. We can adjust $\nu_{1,2}$ to regulate the condition numbers of $\mathbf{H}_{\nu_1\nu_2}$, and \mathbf{H}_{ν_2} to ensure stability of the inverses in (31) and (32). Using general positive definite diagonal matrices in place of weighted identity matrices inside \mathbf{A} is possible but would complicate the structure of the matrices $\mathbf{H}_{\nu_1\nu_2}$, and \mathbf{H}_{ν_2} in (34) and (35), respectively.

2) *Implementing the Matrix Inverses*: When the k -space samples lie on a Cartesian grid, \mathbf{F}_u corresponds to a sub-sampled DFT matrix in which case we solve (30) exactly using FFTs. For non-Cartesian k -space trajectories, computing $\mathbf{u}_0^{(j+1)}$ requires an iterative method. For example, a CG-solver (with warm starting) that implements products with $\mathbf{F}^H \mathbf{F}$ using gridding-based techniques [29] can be used for (30). Alternatively, we can exploit the special structure of $\mathbf{F}^H \mathbf{F}$ (of size $NL \times NL$) to implement (30) using the technique proposed in [30]. We have that

$$\mathbf{F}^H \mathbf{F} = \mathbf{Z}^H \mathbf{Q} \mathbf{Z} \quad (36)$$

where \mathbf{Z} is a $2NL \times NL$ zero-padding matrix and \mathbf{Q} is a $2NL \times 2NL$ circulant matrix [31]. Then, we write \mathbf{H}_μ as

$$\mathbf{H}_\mu = \left(\mathbf{Z}^H \mathbf{Q}_1 \mathbf{Z} + \frac{\mu}{2} \mathbf{I}_{NL} \right)$$

where $\mathbf{Q}_1 = \mathbf{Q} + (\mu/2)\mathbf{I}_{2NL}$. We have split the factor $\mu\mathbf{I}_{NL}$ in \mathbf{H}_μ because \mathbf{Q} may have a nontrivial null-space and therefore may not be invertible. Letting \mathbf{w} denote the quantity within the brackets on the right-hand side of (30), we apply the

Sherman–Morrison–Woodbury matrix inversion lemma (MIL) to \mathbf{H}_μ^{-1} in (30) and obtain

$$\mathbf{u}_0^{(j+1)} = \mathbf{H}_\mu^{-1} \mathbf{w} = \frac{2}{\mu} \mathbf{w} - \frac{4}{\mu^2} \mathbf{Z}^H \boldsymbol{\tau} \quad (37)$$

where $\boldsymbol{\tau}$ must be obtained by solving

$$\left(\mathbf{Q}_1^{-1} + \frac{2}{\mu} \mathbf{Z} \mathbf{Z}^H \right) \boldsymbol{\tau} = \mathbf{Z} \mathbf{w}. \quad (38)$$

Since \mathbf{Q}_1 is circulant and $\mathbf{Z} \mathbf{Z}^H$ is a diagonal matrix containing either ones or zeros (due to the structure of \mathbf{Z}) [30], we use a circulant preconditioner of the form $(\mathbf{Q}_1^{-1} + \alpha \mathbf{I}_{2NL})^{-1}$ (with $\alpha \approx 0$) to quickly solve (38) using the CG algorithm. The advantage here is that the matrices in the left-hand side of (38) and the preconditioner are either circulant or diagonal, which simplifies CG-implementation.

When the regularization matrices, \mathbf{R}_{pq} , $p = 1, \dots, P_q \forall q$, are shift-invariant (or circulant), $\mathbf{R}^H \mathbf{R}$ is also shift-invariant. Then, we compute $\mathbf{H}_{\nu_1 \nu_2}^{-1}$ efficiently using FFTs. In the case where a \mathbf{R}_{pq} is not shift-invariant (e.g., an orthonormal wavelet transform), we apply a few CG iterations with warm-starting to solve (31). Finally, since $\mathbf{S}^H \mathbf{S}$ is diagonal, we see that \mathbf{H}_{ν_2} is also diagonal and is therefore easily inverted.

Splitting the k -space and spatial (i.e., \mathbf{F} and \mathbf{S} , respectively) components in the data-fidelity term has led to separate matrix inverses— \mathbf{H}_μ^{-1} and $\mathbf{H}_{\nu_2}^{-1}$ involving the components $\mathbf{F}^H \mathbf{F}$ and $\mathbf{S}^H \mathbf{S}$, respectively. Without \mathbf{u}_0 , one would have ended up with a term $\mathbf{S}^H \mathbf{F}^H \mathbf{F} \mathbf{S}$ (as in \mathbf{G}_μ) that is more difficult to handle using MIL compared to $\mathbf{F}^H \mathbf{F}$. Using \mathbf{u}_2 decouples the terms $\mathbf{R}^H \mathbf{R}$ and $\mathbf{S}^H \mathbf{S}$, thereby replacing a numerically intractable matrix inverse of the form $(\mathbf{S}^H \mathbf{S} + \alpha \mathbf{R}^H \mathbf{R})^{-1}$ with tractable ones such as $\mathbf{H}_{\nu_1 \nu_2}^{-1}$ and $\mathbf{H}_{\nu_2}^{-1}$.

3) *AL Algorithm for Problem P2*: Combining the results from Sections IV-B1 and IV-B2, we present our second AL algorithm that solves problem P2, and thus P0.

AL-P2: AL Algorithm for solving problem P2

1. Select $\mathbf{x}^{(0)}$, $\mathbf{u}_2^{(0)} = \mathbf{x}^{(0)}$, $\nu_{1,2} > 0$, and $\mu > 0$
2. Precompute $\mathbf{F}^H \mathbf{d}$; set $\boldsymbol{\eta}_{20,21,22}^{(0)} = \mathbf{0}$ and $j = 0$

Repeat:

3. Compute $\mathbf{u}_0^{(j+1)}$ from (30) using FFTs on (37)
4. Compute $\mathbf{u}_1^{(j+1)}$ using an appropriate technique as described in Section IV-A2 to IV-A6 for problem (27)
5. Compute $\mathbf{u}_2^{(j+1)}$ using (31)
6. Compute $\mathbf{x}^{(j+1)}$ using (32)
7. $\boldsymbol{\eta}_{20}^{(j+1)} = \boldsymbol{\eta}_{20}^{(j)} - (\mathbf{u}_0^{(j+1)} - \mathbf{S} \mathbf{x}^{(j+1)})$
8. $\boldsymbol{\eta}_{21}^{(j+1)} = \boldsymbol{\eta}_{21}^{(j)} - (\mathbf{u}_1^{(j+1)} - \mathbf{R} \mathbf{u}_2^{(j+1)})$
9. $\boldsymbol{\eta}_{22}^{(j+1)} = \boldsymbol{\eta}_{22}^{(j)} - (\mathbf{u}_2^{(j+1)} - \mathbf{x}^{(j+1)})$

10. Set $j = j + 1$

Until stop-criterion is met

With the possible exception of Steps 3 and 4, all updates in AL-P2 are exact (for circulant $\{\mathbf{R}_{pq}\}$) unlike AL-P1 because of the way we split the variables in P2.

Although Steps 2–4 of AL-P1 and Steps 2–6 of AL-P2 do not exactly accomplish Step 2 of AL, we found in our experiments that both AL-P1 and AL-P2 work well, corroborating the numerical evidence from [15].

C. Choosing μ - and ν -Values for the AL Algorithms

Although μ - and ν -values do not affect the final solution to P0, they can affect the convergence rate of AL-P1 and AL-P2. For AL-P2, we set the parameters μ , ν_1 , and ν_2 so as to achieve condition numbers— $\kappa(\mathbf{H}_\mu)$, $\kappa(\mathbf{H}_{\nu_1 \nu_2})$, and $\kappa(\mathbf{H}_{\nu_2})$ of \mathbf{H}_μ , $\mathbf{H}_{\nu_1 \nu_2}$, and \mathbf{H}_{ν_2} , respectively—that result in fast convergence of the algorithm. Because of the presence of identity matrices in (33)–(35), $\kappa(\mathbf{H}_\mu)$, $\kappa(\mathbf{H}_{\nu_1 \nu_2})$, and $\kappa(\mathbf{H}_{\nu_2})$ are decreasing functions of μ , ν_2/ν_1 , and ν_2 , respectively. Choosing μ such that $\kappa(\mathbf{H}_\mu) \rightarrow 1$ would require a large μ and accordingly, the influence of self-adjoint component $\mathbf{F}^H \mathbf{F}$ in \mathbf{H}_μ diminishes— \mathbf{H}_μ becomes “over-regularized;” we observed in our experiments that this phenomenon would result in slow convergence of AL-P2. On the other hand, taking $\mu \rightarrow 0$ would increase $\kappa(\mathbf{H}_\mu)$ making \mathbf{H}_μ^{-1} numerically unstable (because $\mathbf{F}^H \mathbf{F}$ may have a nontrivial null-space). The same trend also applies to $\kappa(\mathbf{H}_{\nu_1 \nu_2})$ and $\kappa(\mathbf{H}_{\nu_2})$ as functions of ν_2/ν_1 and ν_2 , respectively. We found empirically that choosing μ , ν_1 , and ν_2 such that $\kappa(\mathbf{H}_\mu)$, $\kappa(\mathbf{H}_{\nu_1 \nu_2})$, $\kappa(\mathbf{H}_{\nu_2}) \in [10, 36]$ generally provided good convergence speeds for AL-P2 in all our experiments.

In the case of AL-P1, the components $\mathbf{S}^H \mathbf{F}^H \mathbf{F} \mathbf{S}$ and $\mathbf{R}^H \mathbf{R}$ balance each other in preventing \mathbf{G}_μ (18) from having a nontrivial null-space—the condition number $\kappa(\mathbf{G}_\mu)$ of \mathbf{G}_μ therefore exhibits a minimum for some $\mu_{\min} > 0$: $\mu_{\min} = \arg \min_{\mu} \kappa(\mathbf{G}_\mu)$. It was suggested in [15] that μ_{\min} can be used for split-Bregman-like schemes such as AL-P1 for ensuring quick convergence of the CG algorithm applied to (17) (Step 4 of AL-P1). However, we observed that selecting $\mu = \mu_{\min}$ did not consistently yield⁶ fast convergence of the AL-P1 algorithm in our experiments (see Section VI-B). So, we resorted to a manual selection of μ for AL-P1 for reconstructing one slice of a 3-D MRI volume, but applied the same μ -value for reconstructing other slices.

V. EXPERIMENTS

A. Experimental Setup

In all our experiments, we considered k -space samples on a Cartesian⁷ grid, so \mathbf{F}_u corresponds to an undersampled version of the DFT matrix. We used Poisson-disk-based sub-sampling [32] which provides random, but nearly uniform sampling that is advantageous for CS-MRI [33].

We compared the proposed AL methods to NCG (which has been used for CS-(p)MRI [10], [11]) and to the recently proposed MFISTA [13]—a monotone version of the state-of-the-art fast iterative shrinkage-thresholding algorithm (FISTA) [34].

⁶A possible explanation for this phenomenon is presented in a supplementary downloadable material available at <http://ieeexplore.ieee.org>.

⁷The proposed algorithms also apply to non-Cartesian k -space trajectories.

TABLE I
COMPUTATION TIME PER OUTER ITERATION OF VARIOUS
ALGORITHMS FOR THE EXPERIMENTS IN SECTION V

Algorithm	Time Taken (in seconds)	
	(Section V-B)	(Section V-C)
AL-P1-4	0.21	0.17
AL-P1-6	0.27	0.22
AL-P1-10	0.35	0.30
AL-P2	0.15	0.12
NCG-1	0.21	0.17
NCG-5	0.30	0.26
MFISTA-1	0.22	0.18
MFISTA-5	0.53	0.43
MFISTA-20	1.51	1.18

For the minimization step [13, Eq. (5.3)] in MFISTA, we applied the Chambolle-type algorithm developed in [35] that accommodates general regularizers of the form (6). We used the line-search described in [36] for NCG that guarantees monotonic decrease of $J(\mathbf{x})$. NCG also requires a positive “smoothing” parameter, ϵ (as indicated in [10, Appendix A]) to round-off “corners” of nonsmooth regularization criteria; we set $\epsilon = 10^{-8}$ which seemed to yield good convergence speed for NCG without compromising the resulting solution too much (see Section VI-A). We implemented the following algorithms in MATLAB.

- **MFISTA- N** with N iterations of [35, Eq. (6)];
- **NCG- N** with N line-search iterations;
- **AL-P1- N** with N CG iterations at Step 4;
- **AL-P2**.

We conducted the experiments on a dual quad-core Mac Pro with 2.67 GHz Intel processors. Table I shows the per-iteration computation time of the above algorithms for each experiment.

Since our goal is to minimize the cost function J (which determines the image quality), we focused on the speed of convergence to a solution of **P0**. For all algorithms, we quantified convergence rate by computing the normalized ℓ_2 -distance between $\mathbf{x}^{(j)}$ and the limit $\mathbf{x}^{(\infty)}$ (that represents a solution of **P0**) given by

$$\xi(j) = 20 \log_{10} \left(\frac{\|\mathbf{x}^{(j)} - \mathbf{x}^{(\infty)}\|_2}{\|\mathbf{x}^{(\infty)}\|_2} \right). \quad (39)$$

We obtained $\mathbf{x}^{(\infty)}$ in each experiment by running thousands of iterations of **MFISTA-20** because our implementation of MFISTA (with Chambolle-type inner iterations [35]) does not require rounding the corners of nonsmooth regularization unlike NCG, and therefore converges to a solution of **P0**. Since the algorithms have different computational loads per outer-iteration, we evaluated $\xi(j)$ as a function of algorithm run-time⁸ t_j (time elapsed from start until iteration j). We used the square-root of sum of squares (SRSoS) of coil images (obtained by taking inverse Fourier transform of the undersampled data after filling the missing k -space samples with zeros) as our initial guess $\mathbf{x}^{(0)}$ for all algorithms. For the purpose of illustration, we selected the regularization parameters $\{\lambda_q\}$ such that minimizing the corresponding J in (2) resulted in a visually appealing solution $\mathbf{x}^{(\infty)}$. In practice, quantitative methods such as the discrepancy principle or cross-validation-based schemes

⁸In timing MFISTA, we ignored the computation time spent on estimating the maximum eigenvalue of $\mathbf{S}^H \mathbf{F}^H \mathbf{F} \mathbf{S}$ necessary for its implementation.

may be used for automatic tuning [37] of regularization parameters. We adjusted μ for **AL-P1** and (ν_1 and ν_2) for **AL-P2** as described in Section IV-C. In particular, we universally set

$$\kappa(\mathbf{H}_\mu) = 24, \quad \kappa(\mathbf{H}_{\nu_1 \nu_2}) = 12 \quad (40)$$

$$\kappa(\mathbf{H}_{\nu_2}) = \min\{0.9\kappa(\tilde{\mathbf{S}}^H \tilde{\mathbf{S}}), 12\} \quad (41)$$

for **AL-P2** in all our experiments, which provided good results for different undersampling rates and regularization settings (such as ℓ_1 -norm of wavelet coefficients, TV and their combination) as demonstrated next.

B. Experiments With Synthetic Data

We considered a noise-free 256×256 T2-weighted MR image obtained from the Brainweb database [38]. We used a Poisson-disk-based sampling scheme where we fully sampled the central 8×8 portion of the k -space; the resulting sampling pattern [shown in Fig. 1(b)] corresponded to 80% undersampling of the k -space. We simulated data from $L = 4$ coils whose sensitivities were generated using the technique developed in [39] [SoS of coil sensitivities is shown in Fig. 1(c)]. We added complex zero-mean white Gaussian noise (with a $1/r$ -type correlation between coils) to simulate noisy correlated coil data of 30 dB SNR. This setup simulates data acquisition corresponding to one 2-D slice of a 3-D MRI volume where the k -space sampling pattern in Fig. 1(b) is in the phase-encode plane.

We utilized the true sensitivities and inverse noise covariance matrix (i.e., those employed for simulating data generation) to compute $\tilde{\mathbf{S}}$ in (4). We chose $\Psi(\mathbf{x}) = \|\mathbf{W} \mathbf{x}\|_{\ell_1}$, where \mathbf{W} represents two levels of the undecimated Haar-wavelet transform (with periodic boundary conditions) excluding the “scaling” coefficients. Using ℓ_1 -regularization has reduced aliasing artifacts and restored most of the fine structures in the regularized reconstruction $\mathbf{x}^{(\infty)}$ [Fig. 1(e)] compared to the SRSoS image [Fig. 1(d)]. Fig. 2 compares NCG, MFISTA and the proposed **AL-P1** and **AL-P2** schemes in terms of speed of convergence to $\mathbf{x}^{(\infty)}$, showing $\xi(j)$ as a function of t_j for the above algorithms. Both AL methods converge significantly faster than NCG and MFISTA.

C. Experiments With In Vivo Human Brain Data

In our next experiment, we used a 3-D *in vivo* human brain data-set acquired from a GE 3T scanner ($T_R = 25$ ms, $T_E = 5.172$ ms, and voxel-size = $1 \times 1.35 \times 1$ mm³), with a 8-channel head-coil. The k -space data corresponded to $256 \times 144 \times 128$ uniformly-spaced samples in the k_x and k_y (phase-encode plane), and k_z (read-out) directions, respectively. We used the iFFT-reconstruction of fully-sampled data collected simultaneously from a body-coil as a reference for quality. Two slices—Slice 38 and 90—(along x - y direction) of the reference body-coil image-volume are shown in Fig. 3(a) and Fig. 4(a), respectively. To estimate the sensitivity maps \mathbf{S} corresponding to a slice, we separately optimized a quadratic-regularized least-squares criterion (similar to [40]) that encouraged smooth maps which “closely” fit the body-coil image to the head-coil images. We estimated the inverse of noise covariance matrix \mathbf{K}_s from data collected during a

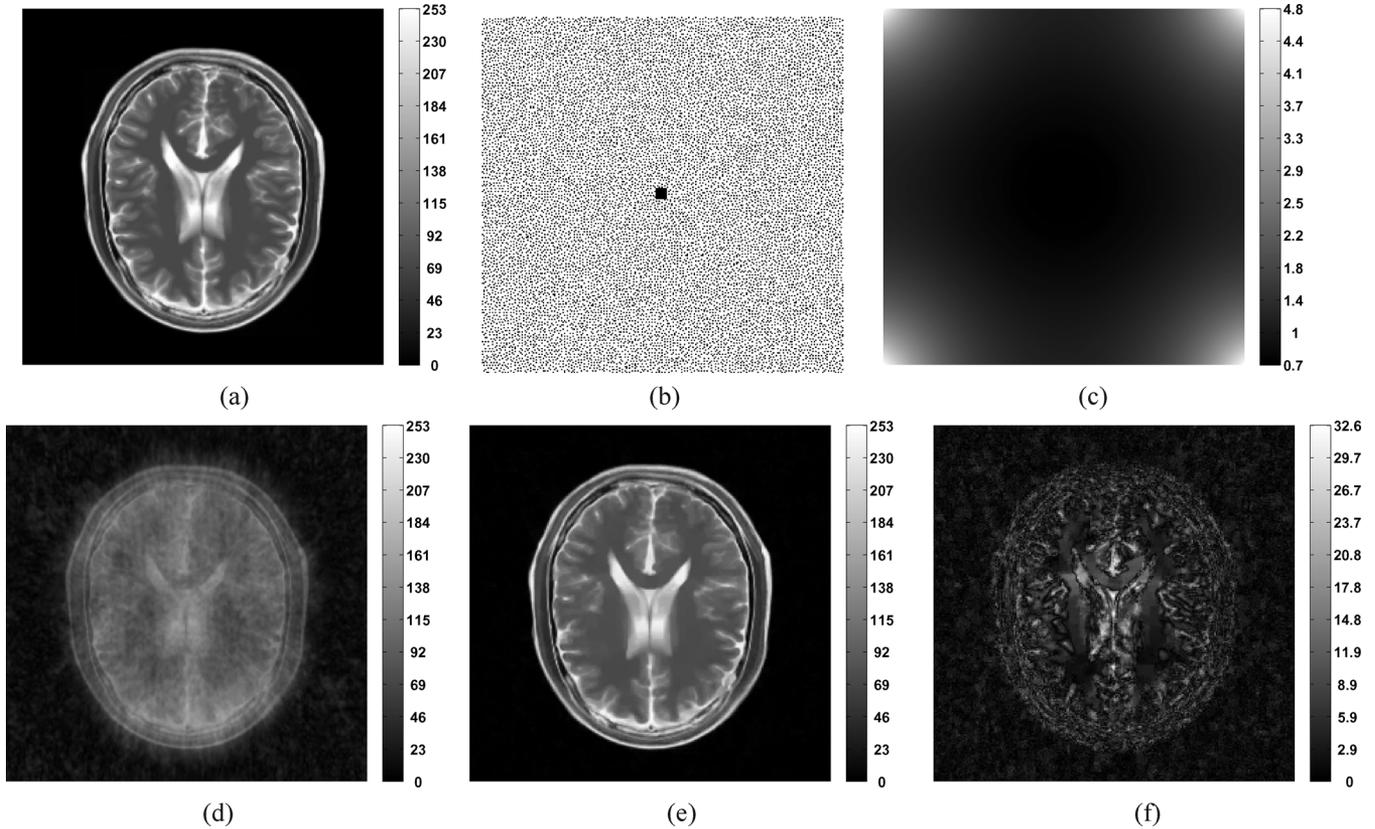


Fig. 1. Experiment with synthetic data: (a) Noise-free T2-weighted MR image used for the experiment; (b) Poisson-disk-based sampling pattern (on a Cartesian grid) in the phase-encode plane with 80% undersampling (black spots represent sample locations); (c) SoS of sensitivity maps ($S^H S$) of coils; (d) Square-root of SoS of coil images (SNR = 9.52 dB) obtained by taking inverse Fourier transform of the undersampled data after filling the missing k -space samples with zeros (also the initial guess $\mathbf{x}^{(0)}$); (e) the solution $\mathbf{x}^{(\infty)}$ (SNR = 24.52 dB) obtained by running MFISTA-20; (f) Absolute difference between (a) and (e). The goal of this work is to converge to the image $\mathbf{x}^{(\infty)}$ in (e) quickly.

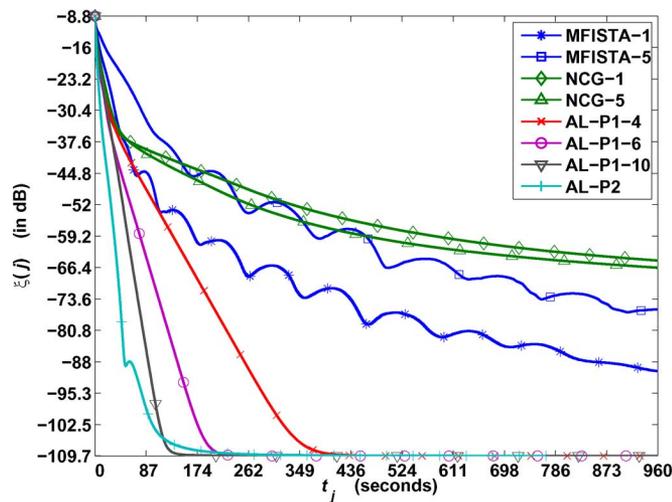


Fig. 2. Experiment with synthetic data: Plot of $\xi(j)$ as a function of time t_j for NCG, MFISTA, and AL-P1 and AL-P2. Both AL algorithms converge much faster than NCG and MFISTA.

dummy scan where only the static magnetic-field (and no RF excitations) was applied and computed \hat{S} using (4).

We then performed regularized SENSE-reconstruction of 2-D slices (x - y plane)—Slice 38 and 90—from undersampled phase-encodes: For experiments with both slices, we applied

the Poisson-disk-sampling pattern in Fig. 3(b) (corresponding to 16% of the original 256×144 k -space samples) in the phase-encode plane and used a regularizer that combined ℓ_1 -norm of two-level undecimated Haar-wavelet coefficients (excluding the “scaling” coefficients) and TV-regularization. The reconstructions, $\mathbf{x}^{(\infty)}$, corresponding to Slice 38 and 90 were obtained by running several thousands of iterations of MFISTA-20 and are shown in Fig. 3(d) and Fig. 4(c), respectively. Aliasing artifacts and noise have been suppressed considerably in the regularized reconstructions compared to corresponding SRSoS images [Fig. 3(c) and Fig. 4(b), respectively]. We manually adjusted μ for AL-P1 for reconstructing Slice 38 and used the same μ -value for reconstructing Slice 90 using AL-P1. For AL-P2, we used the “universal” setting (40) and (41) for reconstructing both slices. We also ran NCG and MFISTA in both cases and computed ξ . Fig. 5(a) and (b) plot $\xi(j)$ for all the algorithms as a function of t_j . The AL algorithms converge faster than NCG and MFISTA in both cases. These figures also illustrate that choosing μ , ν_1 and ν_2 using the proposed condition-number-setting (40) and (41) provides agreeably fast convergence of AL-P2 for reconstructing multiple slices of a 3-D volume. We also obtained results (not shown) in favor of AL-P2 similar to those in Figs. 3–5 when we repeated the above experiment (with Slices 38 and 90) with the same sampling and regularization setup but using sensitivity maps estimated from low-resolution body-coil and head-coil

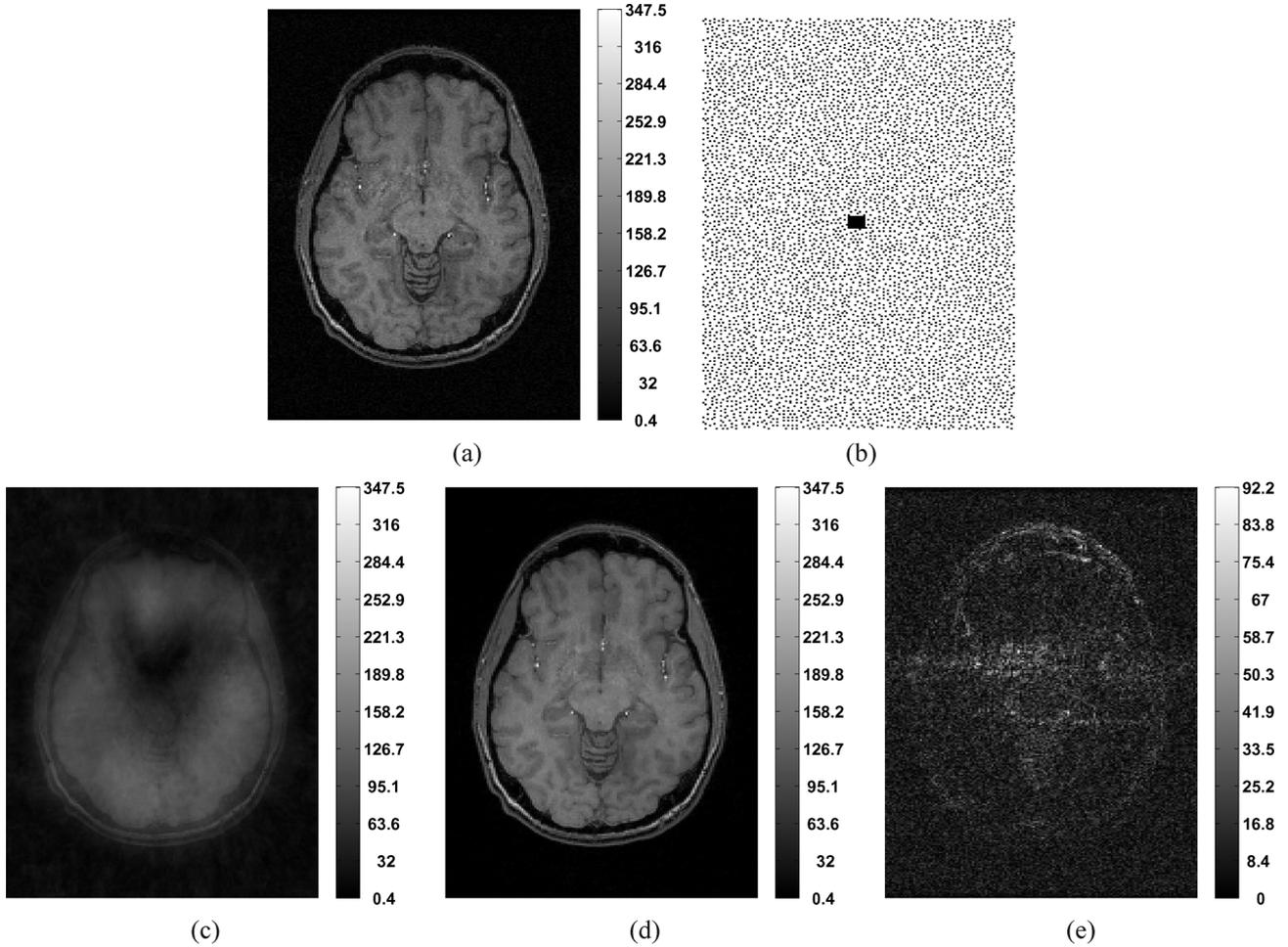


Fig. 3. Experiment with *in vivo* human brain data (Slice 38). (a) Body-coil image corresponding to fully-sampled phase-encodes. (b) Poisson-disk-based k -space sampling pattern (on a Cartesian grid) with 84% undersampling (black spots represent sample locations). (c) Square-root of SoS of coil images obtained by taking inverse Fourier transform of the undersampled data after filling the missing k -space samples with zeros (also the initial guess $\mathbf{x}^{(0)}$). (d) The solution $\mathbf{x}^{(\infty)}$ to $\mathbf{P0}$ in (2) obtained by running MFISTA-20. (e) Absolute difference between (a) and (d) indicates that aliasing artifacts and noise have been suppressed considerably in the reconstruction (d).

images obtained from iFFT-reconstruction of corresponding central 32×32 phase-encodes.

VI. DISCUSSION

A. Influence of Corner-Smoothing Parameter on NCG

Section V-A mentioned that implementing NCG requires a parameter $\epsilon > 0$ to round-off the “corners” of nonsmooth regularizers. While ϵ is usually set to a “small” value in practice, we observed in our experiments that varying ϵ over several orders of magnitude yielded a trade-off (results not shown) between the convergence speed of NCG and the limit to which it converged. Smaller ϵ yielded slow convergence speeds, probably because $\|\nabla J\|_2$ [norm of the gradient of the cost function in (2)] is large for nonsmooth regularization criteria with sparsifying operators and correspondingly, many NCG-iterations may have to be executed before a satisfactory decrease of $\|\nabla J\|_2$ can be achieved. For sufficiently small ϵ , running numerous NCG-iterations would approach a solution of $\mathbf{P0}$. On the other hand, increasing ϵ accordingly decreases the gradient-norm thereby accelerating convergence. However, for larger ϵ -values, the gradient no longer corresponds to the actual ∇J and NCG con-

verges to something that is not a solution of $\mathbf{P0}$ (e.g., Fig. 5). In our experiments, we found that $\epsilon \in [10^{-8}, 10^{-4}]$ provided reasonable balance in the above trade-off. No such ϵ is needed in MFISTA and AL methods.

B. AL-P1 Versus AL-P2

Increasing the number of CG iterations, N in $\mathbf{AL-P1-N}$, leads to a more accurate update $\mathbf{x}^{(j+1)}$ at Step 4 of $\mathbf{AL-P1}$ thereby decreasing $\mathbf{AL-P1}$'s run-time to convergence [e.g., Fig. 2 and Fig. 5(a)]. However, at some point the computation load dominates the accuracy gained resulting in longer run-time to achieve convergence—this is illustrated in Fig. 5(b) where $\mathbf{AL-P1-6}$ is slightly faster than $\mathbf{AL-P1-10}$.

Selecting $\mu = \mu_{\min}$ did not consistently provide fast convergence of the split-Bregman-like $\mathbf{AL-P1}$ algorithm in our experiments as remarked in Section IV-C. Our understanding of this phenomenon is that μ_{\min} can be extremely large or small whenever the elements of $\tilde{\mathbf{S}}^H \mathbf{F}^H \tilde{\mathbf{F}} \tilde{\mathbf{S}}$ and $\mathbf{R}^H \mathbf{R}$ in $\mathbf{G}_\mu(18)$ are of different orders of magnitude (because $\tilde{\mathbf{S}}$ can vary arbitrarily depending on the scanner or noise level). Correspondingly, λ_q / μ_{\min} in (20) becomes very small or large, which does not favor the convergence speed of $\mathbf{AL-P1}$.

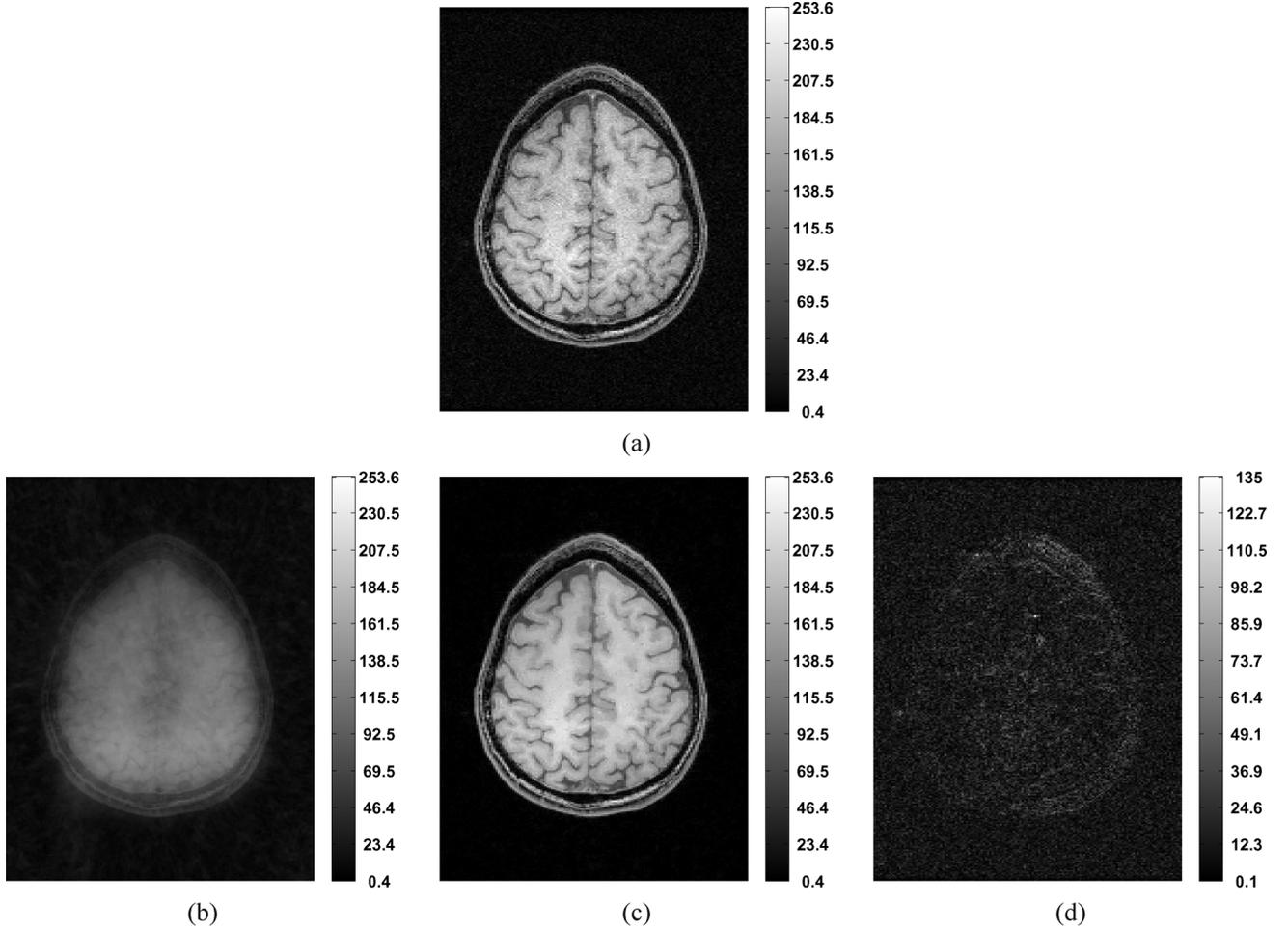


Fig. 4. Experiment with *in vivo* human brain data (Slice 90). (a) Body-coil image corresponding to fully-sampled phase-encodes. (b) Square-root of SoS of coil images obtained by taking inverse Fourier transform of the undersampled data after filling the missing k -space samples with zeros (also the initial guess $\mathbf{x}^{(0)}$). (c) The solution $\mathbf{x}^{(\infty)}$ to $\mathbf{P0}$ in (2) obtained by running MFISTA-20. (d) Absolute difference between (a) and (c) indicates that aliasing artifacts and noise have been suppressed considerably in the reconstruction (c).

In devising **AL-P2**, we circumvented the above problem by introducing additional splitting variables that lead to simpler matrices \mathbf{H}_μ , $\mathbf{H}_{\nu_1\nu_2}$, and \mathbf{H}_{ν_2} whose condition numbers $\kappa(\mathbf{H}_\mu)$, $\kappa(\mathbf{H}_{\nu_1\nu_2})$, and $\kappa(\mathbf{H}_{\nu_2})$, can be adjusted individually to account for differing orders of magnitude of \mathbf{F} , \mathbf{R} , and $\tilde{\mathbf{S}}$, respectively. Choosing (μ, ν_1, ν_2) based on condition numbers (40) and (41) provided good convergence speeds for **AL-P2** in our experiments (including those in Sections V-B and V-C) with different synthetic data-sets and a real breast-phantom data-set acquired with a Philips 3T scanner (results not shown). Furthermore, almost all the steps of **AL-P2** are exact which makes it more appealing for implementation. With proper code-optimization, we believe the computation-time of **AL-P2** can be reduced more than that of **AL-P1**.

C. Constraint Involving the Data

Recently, Liu *et al.* [14] applied a Bregman iterative scheme to TV-regularized SENSE-reconstruction, which converges to a solution of the constrained optimization problem

$$\min_{\mathbf{x}} \Psi(\mathbf{R}\mathbf{x}) \text{ subject to } \mathbf{F}\mathbf{S}\mathbf{x} = \mathbf{d} \quad (42)$$

for some regularization Ψ . Although this paper has focused on faster algorithms for solving the unconstrained problem ($\mathbf{P0}$), we can extend the proposed approaches to solve (42) by including a constraint involving the data. For instance, (42) can be reformulated as

$$\min_{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{x}} \Psi(\mathbf{u}_2) \text{ subject to} \\ \mathbf{d} = \mathbf{F}\mathbf{u}_1, \mathbf{u}_1 = \mathbf{S}\mathbf{x}, \mathbf{u}_2 = \mathbf{R}\mathbf{u}_3, \text{ and } \mathbf{u}_3 = \mathbf{x} \quad (43)$$

where we have introduced auxiliary variables to decouple the data-domain components \mathbf{F} and \mathbf{S} , and the regularization component \mathbf{R} . The AL technique (Section III) can then be applied to (43) noting that it can be written in the general form of (7) as

$$\mathbf{u} = \begin{bmatrix} \mathbf{u}_1 \\ \mathbf{u}_2 \\ \mathbf{u}_3 \\ \mathbf{x} \end{bmatrix}, \mathbf{b} = \begin{bmatrix} \mathbf{d} \\ \mathbf{0} \\ \mathbf{0} \\ \mathbf{0} \end{bmatrix}, \mathbf{C} = \Lambda_1 \begin{bmatrix} \mathbf{F} & \mathbf{0} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{I}_{NL} & \mathbf{0} & -\mathbf{S} \\ \mathbf{0} & \mathbf{I}_R & -\mathbf{R} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{I}_N & -\mathbf{I}_N \end{bmatrix}$$

$f(\mathbf{u}) = \Psi(\mathbf{u}_2)$, where Λ_1 is a suitable weighting matrix similar to Λ administered in **P2**, respectively. The **AL** algorithm (Section III) applied to (43) will converge to a solution that satisfies the constraint in (42).

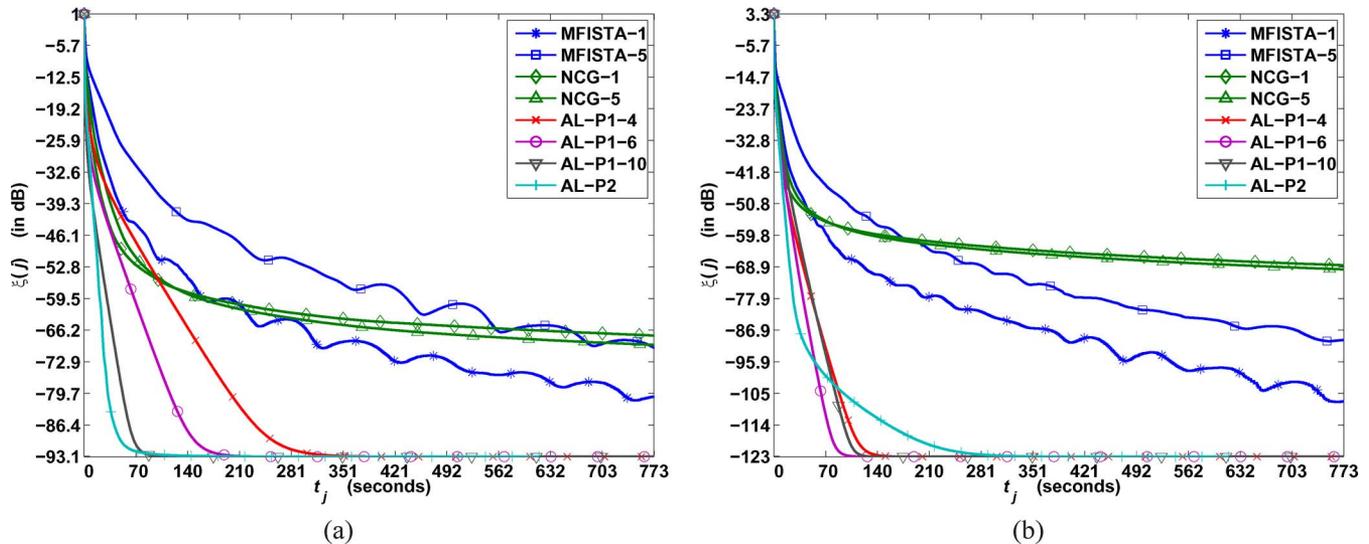


Fig. 5. Experiment with *in vivo* human brain data: Plot of $\xi(j)$ as a function of time t_j for NCG, MFISTA, AL-P1, and AL-P2 for the reconstruction of (a) Slice 38, and (b) Slice 90. The AL penalty parameter μ was manually tuned for fast convergence of AL-P1 for reconstructing Slice 38, while the same μ -value was used in AL-P1 for reconstructing Slice 90. For AL-P2, the “universal” setting (40) and (41) was used for reconstructing both slices. It is seen that the AL algorithms converge much faster than NCG and MFISTA in both cases. These results also indicate that the proposed condition-number-setting (40) and (41) provides agreeably fast convergence of AL-P2 for reconstructing multiple slices of a 3-D volume.

VII. SUMMARY AND CONCLUSION

The augmented Lagrangian (AL) framework constitutes an attractive class of methods for solving constrained optimization problems. In this paper, we investigated the use of AL-based methods for MR image reconstruction from undersampled data using sensitivity encoding (SENSE) with a general class of regularization functional. Specifically, we formulated regularized SENSE-reconstruction as an unconstrained optimization problem in a penalized-likelihood framework and investigated two constrained versions—equivalent to the original unconstrained problem—using variable splitting. The first version, **P1**, is similar to the split-Bregman approach [15] where we split only the regularization term. In the second version, **P2**, we proposed to split the components of the data-fidelity term as well. These constrained problems were then tackled in the AL framework. We applied alternating schemes to decouple the minimization of the associated AL functions and developed AL algorithms **AL-P1** and **AL-P2**, respectively, thereof.

The convergence speeds of the above AL algorithms is chiefly determined by the AL penalty parameter μ . Automatically selecting μ for fast convergence of **AL-P1** still remains to be addressed for regularized SENSE-reconstruction. This is a significant practical drawback of **AL-P1**. However, for **AL-P2** we provided an empirical condition-number-rule to select μ for fast convergence. In our experiments with synthetic and real data, the proposed AL algorithms—**AL-P1** and **AL-P2** (with μ determined as above)—converged faster than conventional (NCG) and state-of-the-art (MFISTA) methods. The algebraic developments and numerical results in this paper indicate the potential of using variable splitting and alternating minimization in the AL formalism for solving other large-scale constrained/unconstrained optimization problems.

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