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Intelligent Vehicle-Highway Systems

# Review of Traffic Simulations for Intelligent Vehicle-Highway System Evaluation

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IVHS Technical Report-90-10

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## Introduction

This report compares and evaluates eight traffic simulation models for their potential application for designing intelligent vehicle-highway systems (IVHS) implementations. The evaluation focuses on those models that are relatively well known and/or that have particular characteristics that may be useful for IVHS applications. The models are:

Name	General Use
<i>TRANSYT</i>	Optimization of signalized network
<i>NETSIM</i>	Microscopic (vehicle level) simulation of traffic operations used to evaluate sophisticated signal control and transportation systems management improvements
<i>FREQ8PE</i>	Freeway corridor simulation with ramp metering optimization
<i>CORFLO (FREFLO)</i>	Freeway corridor simulation that is part of the FREFLO package of models
<i>NETFLO</i>	Simulation of urban arterials used to evaluate traffic control and geometric improvements
<i>CONTRAM</i>	Simulation of signalized urban arterials used to design traffic management schemes
<i>SATURN</i>	Simulation of signalized urban arterials used to design traffic management schemes
<i>INTEGRATION</i>	Simulation of integrated freeway corridor and signalized arterial network used to evaluate traffic control and in-vehicle guidance strategies

The review is based on descriptions of the models from technical reports and the published literature. The comparison did not involve testing of the models or review of the program code.

Of all the models reviewed the INTEGRATION simulation model appears to be the most suitable for evaluating the impacts of advanced driver information system (ADIS) and advanced traffic management systems (ATMS). The model was designed specifically for these purposes and incorporates both traffic flow and traffic assignment capabilities. It is also one of the few models that integrates both freeway and arterial simulation in a single package. The primary limitations of the model are (1) it does not account for platoon behavior in the signalized network, (2) it does not route or assign the vehicles on the basis of predicted traffic flows, (3) it is relatively computationally intensive, and (4) it is still in the early application stage of development.

Table 1. Overview of Traffic Simulation Packages

Characteristics	TRANSYT-7F	TRAF-NETSIM	FREQ8PE	CORFLLO (NETFLLO)	CONTRAM	SATURN	INTEGRATION
Network scope	Urban arterial	Urban arterial	Directional freeway	Urban arterial	Urban arterial	Urban arterial	Freeway corridor and arterial networks
Level of detail	macroscopic	microscopic	macroscopic	macroscopic	quasi-microscopic (mesoscopic) vehicles in packets	quasi-microscopic (mesoscopic) Cyclic flow profile	microscopic
Package structure	atomic	atomic	molecular	molecular	atomic	deterministic	atomic
Model type(s)	optimization of signalized network	simulation of traffic operations	simulation	optimization of signalized network, simulation of assigned traffic in the network, no signal coordination	signalized network operation, optimization of assigned traffic in network, both isolated and coordinated control	stochastic	Simulation of dynamic integrated freeway/traffic signal network
Traffic behavior	deterministic	stochastic, time-varying	deterministic	deterministic, traffic varying over time	deterministic	deterministic	
Traffic flow algorithms	Platoon dispersion (i.e., minimize stops and delays for system); Represents the traffic stream in terms of movement-specific statistical histograms.	Deterministic car following logic.	Merging, weaving and speed-volume in accordance with HCM; compressible fluid theory for queuing	This aggregate variable model of freeway traffic uses a fluid-flow analogy to traffic operations. An equilibrium speed-density relationship is incorporated into a dynamic speed equation. The model consists of a set of conservation equations for vehicles. Flow is represented by flow past boundaries, density, and space-mean-speed in section.	Three types of links: signal controlled, give-way, and uncontrolled. Specify lengths, free-running times, saturation flow, and turning movements. Demands as O-D flow rates. Capacity restrained equilibrium.	Traffic flow is represented as a cyclic flow profile as in TRANSYT. Junction delays are estimated on the basis of 4 profiles which represent the upstream inflow pattern, the platoon dispersion downstream arrival pattern, the pattern during which vehicles are allowed movement, and the pattern leaving the intersection. The model accounts for delays caused by opposing flows, platoons, signal phases, and lane capacities.	Link flow characteristics are represented by inflow rate, outflow rate, and vehicle concentration. Travel times are based on the level of saturation. When undersaturated uniform delay is a function of traffic volume. When oversaturated queuing effects are factored in. Dynamic signal timing and ramp metering can be included. Platoon dispersion is not included in model.
Traffic assignment algorithms	no	no	Diversion of ramp queue	Interfaces with TRAFIC equilibrium assignment model (Nogayen, 1974).	Equilibrium assignment; succession of all-or-nothing assignments (Dow & Van Vliet, 1979). Intersection simulation finds delays for zero flow, current flow, capacity. Iteration between assignment and simulation.	Equilibrium assignment; all-or-nothing, Dial-like, assignment. See Dial (1971). Individual vehicles are assigned to updated shortest path at intersections.	Effective reduction in the number of lanes for specified duration. This can be introduced during the simulation.
Incidents and diversion	no	no	yes	yes	no	no	
Traffic signals and signal optimization	Time scan optimization "hill climbing." Hill climbing is accomplished by varying offsets and splits in steps and calculating the resulting effects.	no	no	no	Three different models: 1. As blockage, diversion policy 2. As blockage 3. No diversion	no	Cycle length, phasing, split are represented. Signal coordination is allowed. Lost time, stage number, cycle times, stage duration are specified. Traffic signal timings are optimized.
Queueing	no	yes	no	no	Three different models: 1. Queue discharge distrib. 2. Queue histogram. 3. No queue effects	no	Dynamic growth and decay of queues within time slice. Also queue spillback.
Ramp metering	no	no	no	Linear programming for ramp metering, time scan	yes	no	Ramp metering rate is not simulated.
						no	Traffic signal with appropriate rate

Table 2. History and Support for Traffic Simulation Packages

Characteristics	TRANSYT-7F	TRAFF-NETSIM	FREQ8PE	CORFLO (FREFLO)	CORFLO (NETFLO)	CONTRAM	SATURN	INTEGRATION
<b>Model origins</b>	(original)	UTCS-1, TRANS, DYNET	(original)	MACK	1. SDC, TRANS, NETSIM, SCOT-Q 2. TRANSYT, SIGOP-II 3. WEBSTER	(original)	(original)	(original)
<b>Original year</b>	1967	1969 (DYNET)	1970	1971	1980	1978	1978	1986
<b>Developers</b>	TRRL, Robertson	KLD, Lieberman, Wicks, Bruggeman, Wornal	May, Blankenborn, et al.	KLD, Nguyen, James, Lieberman, Andrews, Payne & Associates (FREFLO)	KLD, Nguyen, James, Lieberman, Andrews, Payne & Associates (FREFLO)	Louard, Tough, Bagley	Bolland, Williamson, Hall, Van Vliet	Van Arde, Yager
<b>Current developer</b>	TRRL & FHWA	FHWA	ITS	FHWA (KLD)	FHWA (KLD)	TRRL	Institute for Transport Studies at Leeds	MTO, Queens University
<b>Selected publications</b>	Shebandon, et al (1988), Al-Deek, et al. (1988)	Lieberman (1969), Blankenborn & May (1972), Al-Deek, et al. (1988)	Payne (1972), Payne, et al. (1973), Lieberman, et al. (1980), JFT Assoc. (1989)	Lieberman, et al. (1980), Payne (1972), Payne, et al. (1973), Lieberman, et al. (1980), JFT Assoc. (1989)	Lieberman, et al. (1980), Payne (1972), Payne, et al. (1973), Lieberman, et al. (1980), JFT Assoc. (1989)	Louard, Tough, & Bagley (1978); Tough (1978)	Bolland, Van Vliet & Williamson (1978); Hall, Van Vliet, & Williamson (1980)	Van Arde (1965) Van Arde & Yager (1988), Rakha, et al. (1989), Van Arde, Voss, et al. (89), Van Arde & Rakha (1989)
<b>Distribution</b>	McTrans, PC Trans	FHWA (TRAF)	ITS	FHWA (TRAF)	FHWA (TRAF)	TRRL	Institute for Transport Studies at Leeds	MTO
<b>User Guide</b>	Wallace, et al (1988)	Yedlin, et al. (1988)	Imada & May (1985)	Yedlin, et al (1988)	Leonard & Gower (1982)	Van Vliet & Hall (1987)	Van Arde & Voss (1988)	
<b>Support</b>	McTrans	FHWA	ITS	FHWA for Beta test	FHWA for Beta test	Under development	not known	MTO for Beta tests
<b>Microcomputer</b>	yes	yes	yes	Under development	yes	yes	yes	yes

**Table 3.** Description of Simulation Functions

Characteristics	TRANSYT-7F	TRAF-NETSIM	FREQ8PE	COREFLO (FREFLO)	CORFLO (NETFLO)	CONTRAM	SATURN	INTEGRATION
<b>Primary purpose</b>	Develop signal timing plans for arterials and grid networks. The objective is to minimize stops and delays for the system as a whole rather than maximizing the arterial bandwidth.	Evaluation of alternative urban intersection, arterial, or arterial network control strategies, with particular emphasis on sophisticated signal control and TSM improvements.	Evaluate priority lanes (PL) or priority entry (PE) strategies on directional freeways.	Evaluate the effect of adding freeway lanes, using fixed time ramp metering strategies, and the effects of incidents. Traffic assignment makes it useful for planning. It is used with NETFLO for corridor analysis.	Evaluate traffic control strategies and geometric improvements on surface streets. It is useful as a planning tool with its traffic assignment component. It is used with FREFO for corridor analysis.	To evaluate network of signalized junctions. It was developed to design traffic management schemes in urban areas.	To evaluate network of signalized junctions. It was developed to design traffic management schemes in urban areas.	Evaluate traffic control strategies and in-vehicle guidance strategies on integrated freeway/traffic signal networks. It may also be useful as the basis for a real-time route guidance system.
<b>Use and application</b>	Optimize signal timing, sign controlled intersections, bottlenecks, and impacts of major TSM strategies.	TSM (signal installation and timing, changes in intersection control, real-time surveillance and control systems, left-turn restrictions/reversible lanes), impact design (road widening, remove parking, etc., optimize ramp metering, evaluate diversion strategies		Three models: 1. Install signals at intersections, preterm signals, left-turn restrictions, bus service, reversible lanes. 2. Preterm signals, left-turn restrictions, bus service, reversible lanes.				
<b>How does it operate?</b>	A platoon dispersion model is used in conjunction with a "hill climbing" optimization mode.	Interval-scanning simulation moves each vehicle each second according to car-following logic and in response to traffic controls. Relation to other vehicles, and kinematic properties are determined for each vehicle.		(1) The simulation sub-model is a macroscopic deterministic model that predicts traffic performance as a function of freeway design and demand O-D patterns. (2) The optimization sub-model has a linear programming formulation designed to determine the entry control strategies (metering rates and priority cut-off level) that maximizes the passengers' objective function.				
<b>Data requirements</b>				Link lengths, number of lanes, capacities, ramp locations, design speeds, truck percentages, ramp O-D matrix, existing traffic on alternatives	Link lengths, number of lanes, capacities, ramp locations, freeflow speeds, truck percentages, zonal O-D matrix or turning percentages, entry volumes for each link and time slice.	Link lengths, number of lanes, capacities, ramp locations, freeflow speeds, truck percentages, zonal O-D matrix or turning percentages, entry volumes for each link and time slice.	Link flows, queues and turn-moving movements, % saturation and blocking back, journey time and distance, fuel consumption, average point-to-point O-D speeds, vehicle route information, and summary file for input to UFPASC.	Performance summaries of MOEs on integrated arterial street system by link and for total system including: total vehicle hours, travel time, fuel consumption, vehicle emissions, etc.
<b>Output</b>					(1) Performance summaries of MOEs on freeway and alternative route by link and by time slice. (2) Optional outputs include contour diagrams of speeds, densities, queue lengths, fuel consumption, emissions, noise.	(1) Traffic performance summary tables: degree of saturation, travel times, delays, stops, queues, link occupancies, degree of saturation, cycle failures, fuel consumption, vehicle emissions, etc. (2) Signal timing tables (phase and interval offset). (3) Calibration data		Performance summaries of MOEs on signalized arterial street system by link and for total system including: total trip time, travel time, speed, saturation, flow, V/C ratio.

Table 4. Evaluation of Simulations for IVHS Applications

Characteristics	TRANSYT-TF	TRAFF-NETSIM	FREQ8PE	CORFLO (NETFLO)	CONTRAM	SATURN	INTEGRATION
<b>General problems</b>	(1) Does not explicitly optimize cycle length or phase sequences; (2) Assumes no traffic enters the network at a constant uniform rate; (3) Volumes and proportions of turns remain constant; (4) Dispersion is assumed to be uniform (i.e., assumed to be uniform from one signal to another); (5) Emphasizes offset (delay) from one signal to another.	(1) Computer inextricable; (2) Limited output ability; (3) Extensive data requirements; (4) Freeways cannot be modeled; (5) No signal optimization; (6) No modeling.	(1) Dispersion not same as saturation; (2) Limited output ability; (3) Only one iterative route can be modeled; (4) Assumes constant O-D demand.	(1) No route considerations; (2) Large data requirements.	(1) Freeways and arterial routes are not integrated to store all vehicle packet routes.	(1) Lacks freeway routes; (2) Over-saturation of traffic signals is not an accurate representation of traffic flow; (3) Need signal control strategies; (4) No queue spillback; (5) Cyclic flow routes are incompatible with traffic flow dynamics.	(1) No phasor dispersion; (2) (3)
<b>Problems for evaluation of route guidance</b>	(1) Macroscopic simulations have treat traffic flow as a fluid. They simulate vehicles in groups (platoons) and report measures of effectiveness (e.g., delay) consecutively. This makes it impossible to isolate the same drivers from the "main" drivers. (2) No traffic assignment.	(1) Freeway facilities cannot be modeled. (2) Present vehicles in the network are not possible. (3) No traffic assignment.	(1) Microscopic simulations treat traffic flow as a fluid. They simulate vehicles in groups (platoons) and report measures of effectiveness (e.g., delay) consecutively. This makes it impossible to isolate the same drivers from the "main" drivers. (2) No traffic assignment.	(1) Macroscopic simulations treat traffic flow as a fluid. They simulate vehicles in groups (platoons) and report measures of effectiveness (e.g., delay) consecutively. This makes it impossible to isolate the same drivers from the "main" drivers. (2) No traffic assignment.	(1) Traffic assignment is not anticipated so simulation cannot be used to optimize route guidance.	(1) Traffic assignment is not anticipated so simulation cannot be used to optimize route guidance; (2) Microscopic analysis is does not allow for routing of individual vehicles.	(1) Traffic assignment is not anticipated so simulation cannot be used to optimize route guidance.
<b>Advantages</b>	(1) Complements FRIBQ in freeway corridor analysis	(1) Dynamically controlled real-time traffic control; (2) traffic signal demand and traffic control signals; traffic detection, surveillance, parking	(1) Easiest to use; (2) Optimization of ramp metering, priority lanes; (3) Linear programming optimization, priority entry.	(1) Provides a very detailed analysis of the traffic signal network in a single mode; (2) Provides signal optimization and other traffic management tools.	(1) Provides dynamic traffic assignment technique that considers multi-directional traffic patterns of a network, traffic signal are modeled with microscopic vehicle assignment space and time; (2) Detailed modelling of traffic signals in a network, considering of traffic signal assignment space and time; (3) Considers the platoon structure of vehicles arriving at signalized intersections; (4) Symmetric O-D generation; (5) Extensively tested.	(1) Integrates freely and easily into an urban area's network in a single mode; (2) Provides optimization of integrating signal optimization and other traffic management tools; (3) A geographic analysis without interference given the nature of using externally generated signal; (4) Microscopic model enables separation of vehicle types (e.g., those receiving route guidance and those that do not); (6) Unique dynamic traffic assignment does not require iteration; (7) Based on time-series O-D generation; (8) Symmetric O-D generation.	

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