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Cite articles as: Author names(s), Year. Title of article, Solstice: An Electronic Journal of Geography and Mathematics, Vol. XX, No. YY. Ann Arbor: Institute of Mathematical Geography



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## VOLUME XXVII, NUMBER 1; June, 2016

#### **Articles**

The word clouds (formed in Tagxedo, online) serve as a visual "abstract" of the adjacent article!

### **Symmetry Groups**

S\_3

#### William C. Arlinghaus

Professor Emeritus, Department of Mathematics and Computer Science
Lawrence Technological University
Southfield, Michigan
(with figures by Sandra L. Arlinghaus)

Tyger, tyger, burning bright, In the forest of the night; What immortal hand or eye, Dare frame thy fearful symmetry?

William Blake

People have always been interested in symmetry. The fact that human bodies have bilateral symmetry makes us think the face we see in the mirror is a true reflection. The fact that this symmetry is not perfect makes actors and actressess demand that they be photographed from their 'good' sides.

Mathematicians measure symmetry using group theory. The set of transformations which leaves a geometric figure unchanged forms an object called a 'group'.

For example, an equilateral triangle can be rotated through 120 or 240 degrees, rotated through an axis between a vertex and its opposite side, or just left alone without altering its appearance. Thus there are six symmetries of an equilateral triangle, which form a symmetric group called  $S_3$ .

Graph theory studies connections among objects. Thus, to a graph theorist, an equilateral triangle has the same connections, and hence the same symmetries, as any other triangle. Nonetheless, it is easier to notice the symmetries if the geometric representation of a graph exhibits some of the symmetry.

There are two related but different problems which are of interest by themselves.

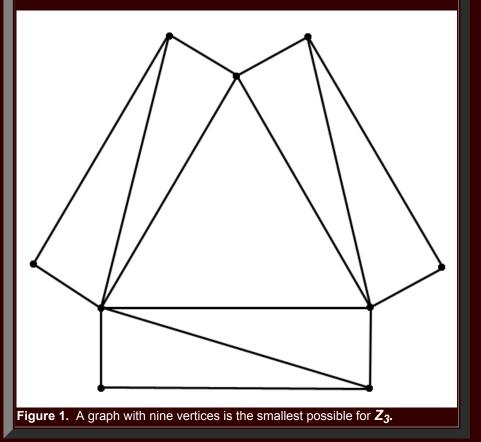
- 1) Given a graph, what are its symmetries?
- 2) Given a group of symmetries, what graph has a group of symmetries isomorphic to that group? In particular, how small a graph exists with that group of symmetries?

This article concentrates on the second part of the second problem, in particular for the groups of rotations of an equilateral triangle and of a square (cyclic groups of order 3 and 4, respectively).

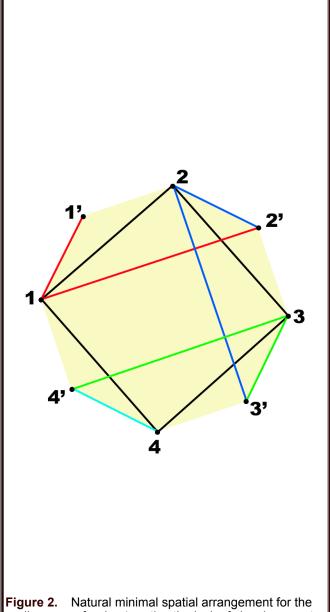
Frucht has shown that any group has a graph with that graph as its group of symmetries (1949), and Arlinghaus has investigated how small these graphs can be for finite abelian groups (1977; 1985). Much notation is used to describe these graphs. But this article concentrates on 'nice' pictures of the two groups mentioned above (denoted  $Z_3$  and  $Z_4$ , respectively).

For  $Z_3$ , one might start with an equilateral triangle, but that is known to have six symmetries, including the three extra rotations noted above. Eventually, one discovers that a graph with nine vertices is the smallest possible (Figure 1). It has a picture in which the rotations are visible.

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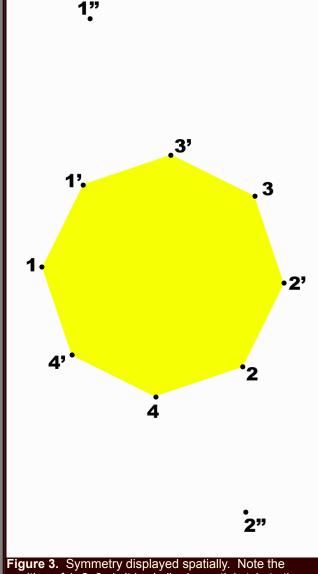


2'4')(1")(2") and  $g^3 = (1432)(1'4'3'2')(1"2")$ . Figure 2 shows an animation of one such arrangement; visual symmetry is not



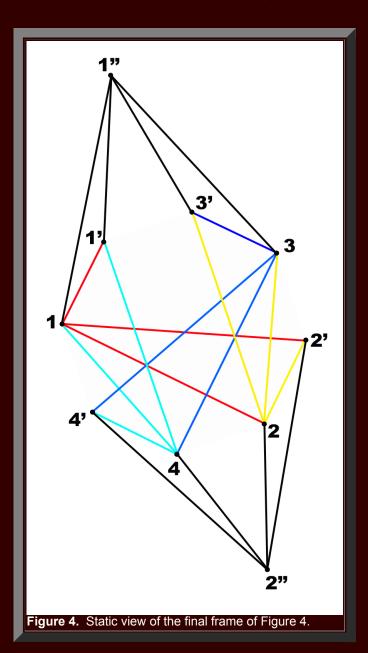
**Figure 2.** Natural minimal spatial arrangement for the cyclic group of order 4; notice the lack of visual symmetry portrayed in this correct representation of this symmetric group.

Figure 3 improves on Figure 2; it displays visual symmetry.



**Figure 3.** Symmetry displayed spatially. Note the position of 1, 2, 3, 4--it is similar in spatial style to the right-hand side of Figure 1.

Figure 4 shows the final frame of the animation, as a static view of the symmetric spatial arrangement.



As may often be the case, geometric views that become complex can be improved, in terms of comprehension, with animation. Older texts might be made to come alive (Harary, 1969); more recent ones can be brightened (Arlinghaus, Arlinghaus, and Harary, 2002; Arlinghaus and Kerski (eBook version), 2013); most important, animation can do more than enhance existing research--as it opens better or new vistas, it can guide it!

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#### Wikipedia

Graph Theory: <a href="https://en.wikipedia.org/wiki/Graph\_theory">https://en.wikipedia.org/wiki/Graph\_theory</a> Theory: <a href="https://en.wikipedia.org/wiki/Group\_theory">https://en.wikipedia.org/wiki/Group\_theory</a>

Wolfram, Math World

Isomorphic graphs: <a href="http://mathworld.wolfram.com/IsomorphicGraphs.html">http://mathworld.wolfram.com/IsomorphicGraphs.html</a>
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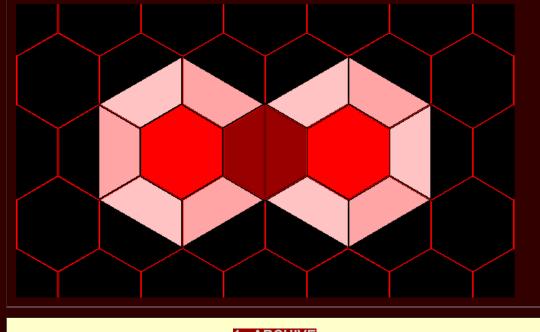


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- 1. Quaestiones Geographicae, Special Issue
- 2. Chene Street History Project.
- 3. *Spatial Mathematics: Theory and Practice Through Mapping*. Sandra L. Arlinghaus and Joseph Kerski, (2013), <a href="Mailto:CRC Press Linked video">CRC Press Linked video</a> Published July 2013,
- 4. The work above is the first volume in a series of books to be published by CRC Press in its series "Cartography, GIS, and Spatial Science: Theory and Practice." If you have an idea for a book to include, or wish to participate in some other way, please contact the series Editor, Sandra L. Arlinghaus.





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