Ionospheric loss from Mars as predicted by hybrid particle simulations

Stephen H. Brecht, Bay Area Research Corp. P.O. Box 366, Orinda CA. 94563 USA

Stephen A. Ledvina, Space Sciences Laboratory, UC Berkeley, 7 Gauss Way, Berkeley, CA, USA

Stephen W. Bougher, Climate and Space Sciences and Engineering Department, Space Research Building, University of Michigan, 2455 Hayward St., Ann Arbor, Michigan, 48109-2143 USA

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Key Points: Hybrid simulation results are found to match data. The inclusion of 3-D neutral atmospheres with the associated winds causes an increase in the ion loss rate from Mars.

Abstract: This paper reports the results of hybrid simulations of the Mars-solar wind interaction. The focus is on the loss rates of $O^+$ and $O_2^+$ from the Martian ionosphere while examining the importance of including 3-D dimensional neutral atmospheres with their associated neutral winds. The simulation loss rates are found to be in excellent agreement with loss rates reported by Lundin et al. [2013]. Further, the results follow the functional form of the loss rates vs. solar EUV as determined by Lundin et al. [2013]. This paper will discuss numerical issues as well as the implementation of 3-D neutral atmospheres, including neutral winds and co-rotation flows.

Index terms and Key Words: 0343, 0545, 0654, 2152, 1739, Numerical simulation, Solar wind interaction with Mars, Ionospheric loss from Mars

1.0 Introduction:

Was Mars a cold dry planet billions of years ago? Alternatively, was it a wet warm planet? This point is still under debate. Recent missions to Mars (Curiosity rover) [cf: Martin-Torres et al., 2015] and Mars Reconnaissance Orbiter, MRO, [cf: Ojha, et al., 2015] have found evidence of
water on the Martian surface. Phobos 2, Mars Express (MEX), now MAVEN [cf. Jakosky et al., 2015] have directly measured ionospheric loss of oxygen ions suggesting this as a mechanism for water loss from Mars. The geological evidence suggests that at one time Mars had a substantial amount of water on its surface. The presence of water on Mars and the suggestion that there were significant amounts of water at earlier epochs drives several questions: Did Mars at one time support life, as we would recognize it? Where did all of the water go? These two related questions are driving a significant portion of the Mars exploration.

It is thought that Mars may have had a surface pressure of 1 bar (10^5 Pa) but loss of the atmosphere has reduced the surface pressure to its present value of 6-10 mbar (10^2 Pa). One of the more complete papers concerning this topic is by Lammer et al. [2003]. In this paper, the authors discuss the various mechanisms for water loss. Zahnle [2015] discusses estimates of the water inventory on Mars now and in the past. Estimates of the current water inventory suggest that melting of the polar ice would cover the Martian surface with up to 30 m of water. He reports that the estimates reach approximately 60-90 m of water 3 billion years ago. Based on D/H ratios, he points out that there seems to be a mismatch between the amounts of H found in the atmosphere versus O. This apparent mismatch suggests that oxygen escape processes may be different for the hydrogen escape. It is thought that most of the hydrogen escapes via thermal processes, while the oxygen escapes via three-body recombination and in ionized form via electromagnetic fields from the solar wind.
The ion removal process (often called scavenging, stripping, ion escape, ion pickup, etc.) involves a series of interactions leading to the final result: loss of ionospheric ions from Mars to space. Briefly, the interactions are as follows: The neutral atmosphere is irradiated by the incoming EUV and other solar radiation. This radiation creates an ionosphere by activating a variety of chemical reactions plus photo-ionization. The ionosphere is then subject to time varying electric and magnetic fields transported by the solar wind through the shock and into the ionosphere. Strong evidence of the influence of the convection electric field’s role in ionospheric loss is seen experimentally [cf. Dubinin et al., 2008; Y. Dong, 2014]. The ions respond to these electromagnetic fields by accelerating, eventually reaching solar wind velocity in the solar wind.

The hybrid particle code, HALFSHEL, simulations of Mars have over the years continued to increase in complexity and resolution and are now providing loss rates that are consistent with the data being reported. Figure 1 is taken from Lundin et al. [2013] and shows a compendium of loss rates for a range of years and missions; Phobos-2 and MEX. The loss rates were estimated based on measurements of ion fluxes with energies between 10 eV and 300 eV to make them consistent across instruments. The loss rates predicted by HALFSHEL for this energy range (red) are plotted with results published by Lundin et al. [2013]. One sees very good agreement with regard to the value of the loss rates and the functional dependence on solar EUV flux. This

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comparison indicates that the simulations have reached a sufficient level of complexity and resolution to permit exploration into parameter spaces representative of earlier epochs of Mars. Note, there was no effort made to match the data. Inputs for the simulations were taken from previous Martian studies found in the literature [cf. Brecht and Ledvina, 2012 and references therein]. The simulations shown and discussed in this paper were performed to examine parameter variations only one of which was the EUV. It should be clear that we could have selected solar wind variables, crustal magnetic field orientations, Ls, etc. to better match the curves, but that was not done.

The remainder of the paper will provide the reader insight into how these simulations were performed and what improvements in the models were required. It will further elucidate the results reported by Brecht and Ledvina [2014]. In the next section, a discussion of the HALSHEL hybrid code is presented followed by a section discussing the implementation of the 3-D neutral atmospheres. Section 4 will display and discuss the results obtained as a function of solar EUV flux, crustal magnetic field orientation, and the full loss rates with no energy limits placed on the escaping ions. Section 5 will discuss some numerical tests made to check the implementation of the crustal magnetic fields. Finally, Section 6 will discuss and summarize the results.
2.0 Numerical Approach

Scientists have employed two distinct numerical approaches to estimate the global loss of oxygen from Mars. One is the MHD formalism \([\text{cf: Liu et al., 2001; Ma et al., 2002; Ma et al., 2004; Ma and Nagy, 2007; Harnett and Winglee, 2006; C. Dong et al., 2014}]\). The second is the kinetic formalism, specifically the hybrid particle code \([\text{cf: Harned, 1982; Brecht and Thomas, 1988; Brecht, 1990; Brecht and Ferrante, 1991; Kallio and Janhunen, 2002; Bößwetter et al., 2004; Modolo et al., 2005; Chanteur, et al., 2009; Holmström and Wang, 2015}]\). In addition to these two fundamental approaches an ion tracking approach using MHD electromagnetic fields has also been employed \([\text{cf: Cravens et al., 2002; Fang et al., 2010 a,b; Curry et al., 2014}]\). The ion tracking approach is an attempt to capture some of the kinetic behavior not found in the MHD code. This method has the disadvantage that the particle motion and fields are not self-consistent. A detailed discussion of the equations and assumptions applied in these approaches is contained in \text{Ledvina et al., [2008]}.\)

The hybrid model treats all ion species (the model can carry as many as one wishes) as kinetic particles. A simple Lorentz force equation is used to advance the particle positions and velocities. Electrons are treated as a massless charge neutralizing fluid. The electromagnetic fields are calculated self-consistently from the ion motion (current) using Ampère’s law and a
generalized Ohm’s law. Electromagnetic plasma waves with frequencies up to and including a portion of the whistler wave spectrum are self-consistently produced in the code. Collisionless shock formation physics is included in this code therefore no assumptions or numerical techniques are needed to capture the shock.

The basic hybrid model equations are:

**Ampere’s law**

\[ \nabla \times \mathbf{B} = (4\pi/c) \mathbf{J} \] (1)

**Faraday’s law**

\[ c \nabla \times \mathbf{E} = -\partial \mathbf{B} / \partial t \] (2)

the ion particle equations of motion

\[ m_i \frac{dv_i}{dt} = q_i \mathbf{E} + q_i \mathbf{v}_i \times (\mathbf{B} + \mathbf{B}_0)/c - q_i \eta \mathbf{J} \] (3)

\[ dx_i / dt = v_i \] (4)

the inertialess electron momentum equation

\[ 0 = -e n_e \mathbf{E} + \mathbf{J}_e \times \mathbf{B}/c - \nabla p_e + e n_e \eta \mathbf{J} \] (5)

where \( \mathbf{J}_e = \nabla \times \mathbf{B} - \mathbf{J}_i \)
and the requirement of quasi-neutrality
\[ n_e = n_i . \tag{6} \]

The electron temperature is evolved by solving the following equation
\[ \frac{\partial T_e}{\partial t} = - \mathbf{u}_e \cdot \nabla T_e - \frac{3}{2} T_e \nabla \cdot \mathbf{u}_e + \frac{2}{3} \eta J^2 / n_e \tag{7} \]

where \( \mathbf{u}_e \) is the electron fluid flow velocity and \( \eta \) is the plasma resistivity.

Use of equation 5 allows direct calculation of the electric field via the electron momentum equations. This equation also points out the need for three different current systems. The total current, \( J \), calculated from Eq. (1), the ion current, \( J_i \), is obtained from the particles motion, and the electron currents, \( J_e \), obtained by subtracting the ion currents from the total currents. Note that the crustal magnetic fields, \( \mathbf{B}_0 \), only show up in Eq. (3), the ion equation of motion.

The reason for the crustal field only manifesting itself in this one place will be discussed in section 5 of the paper.

Development and use of hybrid particle codes began in the 1970’s [cf: Chodura, 1975; Sgro and Nielsen, 1976]. These papers address collisionless shocks and 1-D radial calculations in cylindrical geometry for studying implosion phase of theta pinches. They solved an energy
equation for the electron heating and used an anomalous resistivity model to explain the large amount of electron heating observed.

In 1980's hybrid code became a common tool for large scale kinetic simulations. Hewett et al. [1980], performed 2-D (r-z) simulations of theta pinch implosions. Harned, [1982] developed an energy conserving predictor-corrector method. This method was used for the first 2 1/2 - D shock simulations [Brecht and Thomas, 1988; Thomas and Brecht, 1986a,b, 1987, 1988] and the first 3-D hybrid simulations of an AMPTE release [Brecht and Thomas, 1987]. During this time frame many 1-D shock simulations were performed [cf. Winske and Quest, 1988; Quest, 1989]. Brecht, [1990] was the first to point out the existence of shock asymmetry due to diamagnetic effects. The 3-D hybrid code, HALFSHEL, was then used to simulate Venus and Mars without an ionosphere [Brecht and Ferrante, 1991 and Brecht et al., 1993].

The present version of the hybrid particle code, HALFSHEL [cf. Brecht and Ledvina, 2006, 2010, 2012, 2014 and references therein], was used for this research. The simulations used the appropriate 3-D neutral atmosphere model results from the University of Michigan Mars Thermospheric General Circulation Model (MTGCM) [cf: Bouger et al., 1999a,b, 2000, 2002, 2004, 2006, and 2008]. These models and their implementation are discussed in section 3 of this paper.
2.1 Models operating with HALFSHEL

Accurate simulation of the solar wind interaction with the Martian ionosphere requires a suite of models for important processes. In the next subsections, these models are briefly discussed.

2.1.1 The photochemistry model

The photochemical chemistry model produces and maintains the ionosphere in the simulations. The ion-neutral chemical reactions (photochemistry) used in HALFSHEL are available in Brecht and Ledvina, [2012]. The reaction set is similar to those reported by [Liu et al., 2001; Ma et al., 2002, 2004]. The chemistry equations are solved on a high resolution spherical grid surrounding the planet, with radial resolution of 10 km and 1.4° angular resolution. Each numerical particle has a density associated with it and the density is modified by the ion-neutral chemistry using the combined ion densities from particles within a spherical grid cell. New particles are created if the ion production rate exceeds the loss rates within each spherical cell. Otherwise, existing particles have their density decreased by chemical processes. Unlike a fluid code, a particle code uses an Euler-Lagrangian approach. Therefore, a particle code can include multiple overlaid grids for differing purposes because the particle location and velocities are independent of a grid.

2.1.2 The collisional model
The collisional model addresses species by species collisions using the high resolution grid. The HALFSHEL code treats the ion drag by individually colliding the $\text{H}^+$, $\text{O}^+$, and $\text{O}_2^+$ particles with $\text{CO}_2$ and $\text{O}$ using their respective collision cross-sections. Currently, heating of the particles, (randomization of their trajectories) is not included. The interaction is simply an energy loss (drag) from the moving particles. This is a “conservative” approach for examining ion loss because it over estimates the energy deposited in the neutrals but underestimates the ion energy. The neutral profiles are untouched, thus the energy transfer to the neutrals is not accounted for in the simulations, although the ions energy can be augmented via neutral winds. The electron-ion collision frequencies are calculated from Spitzer [1962]. The electron-oxygen (neutral) and electron-$\text{CO}_2$ (neutral) collision frequencies were taken from Strangeway [1996]. The ion-neutral collision frequencies were taken from the expressions in Shunk & Nagy [2000] using the neutral polarizability (Table 1).

2.1.3 The conductivity model

Hall and Pedersen conductivities are included in the electric field solutions. The generalized electric field including the Hall and Pedersen terms comes from a text by Mitchner and Kruger [1973] and replaces equation 5 with a more complex form to encompass the conductivity tensor. The generalized electric field [Mitchner and Kruger, 1973] is:
\[ E = (J + \beta_e J \times B + s(B+B_0) \times (J \times (B+B_0))/\sigma - \nabla pe / \varepsilon \] (8)

where the \( \sigma \) is the electron conductivity defined as, \((n_e e^2)/(m_e v_{eH})\), \(v_{eH}\) are the electron collision frequencies (electron-neutral and electron-ion), \(J\) is the current density, \(\beta_e\) is the electron Hall parameter, \((\omega_{en}/v_{eH})\) with \(\omega_{en} = eB/cm_e\), the electron cyclotron frequency. \(B\) is the evolving magnetic field and \(B_0\) is the crustal magnetic fields. The “ion slip factor”, \(s\), is \((\rho_n/\rho)^2 \beta_e \beta_i\) where \(\rho_n\) is the neutral mass density, \(\rho\) is the total mass density (ion + neutral), and \(\beta_i\) is the ion Hall parameter \((\omega_{in}/v_{in})\). In the limit that the collision frequencies go to zero, this equation returns to the normal electric field equation, Eq. (5).

The plasma resistivity for the electron Hall and Pedersen terms are computed from the local spherical grid quantities of electron density, ion density, neutral density, and magnetic field at each time step. The ion contribution comes from the ion-neutral collision frequency and the ion cyclotron frequency calculated locally at each spherical grid point, and the electron-ion collision frequency.

2.1.4 Crustal magnetic field model
The crustal magnetic field model from Purucker et al. [2000] is embedded in the code. This model returns magnetic field components for altitudes ranging from near surface to beyond 2 Rₘ. The Martian geological location, the surface longitude and latitude, specifies the crustal magnetic field orientation. The subsolar point of the crustal field models is specified by the MTC, where MTC = 0 is longitude 0° at the Airy crater. The code carries the full 3-D crustal field at the resolution of the code. The code includes planetary rotation and inclination, thus the crustal magnetic fields co-rotate with the neutral atmosphere. Note that the Purucker model or the other crustal field models available [cf. Cain et al., 2003] are based on data collected at 400 km by MGS. The accuracy of the models in the subsolar regions is somewhat suspect because the data collected is from the night side only. Recall that 1° = 59.25 km on the surface and 1.69° = 100 km. Many simulations use resolution in this parameter range but it is not clear if the crustal field models are accurate enough at much finer resolution. In section 5 a discussion of this issue will be presented.

2.1.5 A neutral atmosphere model

The code includes a full 3-D neutral atmosphere and associated neutral winds. The neutral atmosphere is the source of the photo-chemically driven ionosphere within the code. Details of the implementation of the neutral atmosphere are found in Sec. 3. The neutral winds modify the ion-neutral drag as well as provide the initial velocity for newly created ions. The neutral
models used in these simulations are the results of the Mars Thermospheric General Circulation Model, MTGCM, [e.g. Bougher et al., 1988, 1999, 2000, 2004, 2006, and 2008]. A hot O corona based on Chaufray et al. [2007] is also included. Each atmosphere is created with a specific Martian solar longitude and solar fluxes obtained at various points throughout the solar cycle. The solar longitude, Ls, is the location of Mars in its elliptical orbit about the Sun, where spring equinox where Ls=0. Ls=90 thus corresponds to summer solstice, just as Ls=180 marks the autumnal equinox and Ls=270 the winter solstice (all relative to the northern hemisphere).

2.2 Numerical tests

The HALFSHEL code and its DoD/DoE version have been tested extensively over the years. During the 1990’s the HALFSHEL code simulated a variety of experiments. One of them was a laser target experiment where structure seen in the experiment was compared to hybrid simulations [Brecht and Gladd, 1992]. A fast opening plasma switch was simulated during this time period. Not only was the magnetic data from the experiment mimicked by the simulations, the simulations provided the key understanding into the physics of this switches opening; the m=1 kink instability.

The code was used for simulating shocks where the results were compared to the results of spacecraft measurements of shock encounters. It is important to capture the shock physics
correctly because the Martian shock sits within the exosphere and very near the ionosphere. One of the data sets for shock comparison was the Voyager 2 encounter with Uranus [Bagenal et al. 1987]. In the mid-1990’s, such a test was performed to illustrate the kinetic behavior (overshoot regions and waves) of a high Alfvén Mach shock and check models such as the electron temperature equation (Eq. 7). The Uranian bow shock has an Alfvén Mach number of 22 with the expected strong overshoot region that reaches a level of roughly 20 [Russell et al, 1982].

HALFSHEL results were compared to the ion density, the magnetic field, and the electron temperature as reported by Bagenal et al. [1987]. Figure 2 shows the magnetic structure of a portion of the Uranian shock as simulated by HALFSHEL. Several features are of note. One, the overshoot region is at the appropriate level with large Alfvén Ion Cyclotron, AIC, wave propagation along the shock surface [cf: Ambrosiano and Brecht [1987]. Two, behind the shock overshoot, one sees the elevated magnetic field with considerable wave activity. Also due to the nature of the AIC wave, the density and magnetic field oscillation are out of phase. Figure 3 shows the data from Voyager 2 as reported by Bagenal et al. [1987]. The term R-H on the plot by Bagenal et al. [1987] is the Rankine-Hugoniot solution and is used for comparison to the results actually measured. The solid thick line on each of the plots is the result of the simulations averaged along the shock front direction. It is clear choosing an optimal path through the shock would represent the data even better. However, it was felt that comparison to the average would produce the least complex comparison. Comparison of electron temperature, the ion density, and
the magnetic field shows that the simulation results are in good agreement with the data and verified the general accuracy of the code; particularly of the solution of the electron temperature equation, Eq. 7. This comparison proved that not only was the plasma electrodynamics of a collisionless shock well represented by the HALFSHEL formulation, but the electron heating equation produced credible results. This is important for Mars where the shock is very close to the ionosphere and regions where impact ionization and collisions are sensitive to electron temperature. One might question: Why not perform such a simulation of the Martian shock? The reason is that until MAVEN missions to Mars did not sample the subsolar region, and carried either a magnetometer or an ion plasma instrument, not both.

More recently, the HALFSHEL code has been used to simulate a laser target experiment being performed on the large plasma device, LAPD, at UCLA [Larson et al., 2014] where the wave propagation speeds measured and simulated agreed to a very high degree.

The Cartesian grid resolution used for the Martian simulations has been tested. Changing the grid from 150 km to 100 km resolution produced the same loss rates. Other features changed slightly but the loss rate remained the same. This is lack of sensitivity to the Cartesian grid resolution occurs because the chemistry is performed on a much finer grid (the spherical grid) and the particles are loaded consistent with the production rates calculated on this finer grid (10 km radial resolution). It should also be noted that in a particle code the fields are linearly
interpolated from the cell corners to the particles, thus particles within a Cartesian cell are not accelerated with the same force. The spherical grid overlays the Cartesian grid; particles quantities (density, current, charge) are accumulated on either grid as needed.

The checking and verification of the code continues and nowhere is this more important than in checking the photochemistry model. The results [Brecht and Ledvina, 2012] match Viking data [e.g. Hansen et al. 1977]. However, it was found that to achieve accurate answers one needed to check and use proper spatial resolution and temporal resolution.

The first check on the chemistry determined the time step, Δt, needed for an accurate resolution of the chemistry equations. Fig. 4 shows the ratio of highly converged solution to other solutions produced as a function of integration time step. The error is computed against the converged solution using Δt = 0.002 s. When the ratio goes to zero, as is the case for the O⁺ (solid line), often the calculated density has gone negative meaning that the solution to the equations has gone unstable. The electron density, ne, is the summation of all of the ion species and thus represents the overall error. Fig. 4a displays the solution for neutral densities at 150 km altitude during solar maximum. One needs to use an integration time step of roughly 0.2 s or less for accurate convergence. A more conservative time step of 0.05 s is used in the full simulations. As the altitude increases, the reactions slow down. Fig. 4b shows the ratios for a solar maximum case at the altitude of 200 km. The solutions go unstable at Δt = 13 s. It was found and reported earlier [cf. Brecht and Ledvina, 2012] that one needs to integrate the chemistry out roughly
20,000 s real time before photo-chemical equilibrium is achieved at 400 km altitude and the plasma dynamics can be started in the simulation. Results from the simulation and testing show that the advection of the plasma is often faster than the photochemical production, thus the two processes are not in equilibrium. This is particularly true at altitudes near or above 250 km altitude. The simulations start out in photochemical equilibrium to an altitude of 400 km, the plasma dynamics then start up and erode the ionosphere until the plasma advection is balanced by the ion production resulting in the final ionospheric density profile.

Additional tests were performed to check implementation of the chemistry in HALFSHEL. The error here is not one of solution of the coupled set of chemistry equations. It is a test of solving for loss rates and production rates on the spherical grid, interpolating them to particles within the spherical grid cell, then interpolating the density back to the grid and solving the chemistry equations until there is convergence. A comparable test for a fluid or MHD code would entail solving the chemistry on differing grid sizes and then comparing the error in the derivatives of the density as required by fluid equations.

Figure 5 shows the results of performing sensitivity tests as one changed the size of the radial zone, $\Delta r$, used to integrate the chemistry. In this case we addressed the altitude of 200 km. Here one see that an error of less than 1% is made using a $\Delta r = 10$ km and $\Delta t = 0.002s$. The error is
stronger for the $O_2^+$ and can reach unacceptable levels if the chemistry is not resolved to 20 km or less.

In the simulations reported in this paper each new atmosphere required that the time step and spatial step tests be performed before the simulations were begun. In the next section, we discuss the neutral atmospheres used in these simulations.

3. The Neutral Atmosphere Model.

Past research has determined that the chemistry and its response to advection is a crucial part of understanding the ionospheric dynamics and the subsequent loss rates from Mars [Brecht and Ledvina, 2012]. In the research reported here a full 3-D neutral atmosphere has been placed within the hybrid code, HALFSHEL. The HALFSHEL code has the ability to make use of the full 3-dimensional neutral dynamics and couple it to the ionosphere dynamics. However, the coupling is only one way at this point with the neutral density and flows not being affected by the ionospheric dynamics. The neutral atmospheres used here were produced by the MTGCM code. The density profiles have been extrapolated above the nominal altitude (250 km) used as an upper boundary for the MTGCM code.

3.1 A Brief Description of the Neutral Model.
The MTGCM is a finite difference primitive equation model that self-consistently solves for time-dependent neutral temperatures, neutral-ion densities, and three component neutral winds over the Mars globe (e.g., Bougher et al., 1999a,b, 2000, 2002, 2004, 2006, and 2008; Bell et al., 2007).

The MTGCM is driven from below by the NASA Ames Mars MGCM code [Haberle et al., 1999, 2003] at the 1.32-μbar level (near 60-80 km). This detailed coupling allows both the migrating and non-migrating tides to cross the MTGCM lower boundary and the effects of the expansion and contraction of the Mars lower atmosphere (due to dust heating) to extend to the thermosphere. The impacts of lower atmosphere dynamics upon the upper atmosphere are dominant and most important for reproducing observed thermospheric densities and temperatures [see Bell et al., 2007].

The specific details of the model used are as follows: MTGCM output is for Equinox (Ls = 180°) and solar maximum (F10.7 = 200) conditions and Ls = 270° and solar median activity (F10.7 = 130). The F10.7 is a proxy for the solar EUV flux at Earth. The actual EUV fluxes represented by this proxy are then adjusted for Mars. The heliocentric distance provides a 1/R^2.0 scaling of solar EUV UV fluxes at Mars for this season. In addition to the neutral densities for CO2 and O up to 250 km, the neutral models also have the velocity fields for the neutral species. These
fields are provided in the co-rotational frame of Mars. As will be discussed later, to work in the HALFSHEL code the co-rotational velocities must be included.

Figure 6 shows a typical set of neutral atmosphere parameters produced at 200 km when the proxy F10.7 is 130. The plots are latitude versus local time. Fig. 6a shows the temperature with horizontal velocity vectors superimposed. Fig. 6b shows the Log10 of the CO2 density and Fig. 6c shows the Log10 of the O density. As can be seen in all three of these plots the flows and densities are not symmetric about the subsolar point. One of the more interesting features is that there seems to be a large amount of O accumulated on the night side of the planet. This increase in the O density will affect the drag on ions transiting the night side but since there is little ionization on the night side it will not substantially affect the night side ionospheric production. Further, the CO2 has its highest densities in the subsolar region, while the O has its highest densities on the night side; showing that the assumption of a symmetric homogeneous neutral atmosphere is not correct. This structure coupled with the structure of the crustal magnetic fields means that the solar wind interaction will be more complex than one might have originally envisioned.

3.2 Implementation of Realistic Neutral Atmospheres
The data from the MTGCM fits easily within the HALFSHEL code. However, a variety of issues had to be addressed. In the following subsection these issues and subsequent tests will be discussed.

### 3.2.1 Extrapolation to higher altitudes

The MTGCM vertical coordinate is in pressure coordinates and has an upper altitude of ~250 km. These coordinates are Lagrangian and thus move. The hybrid code uses a spherical grid for chemistry and drag calculations. The MTGCM results are provided in spherical coordinates. Therefore, the neutral atmospheres and velocity fields fit seamlessly into the HALFSHEL code. The spherical chemistry grid has a comparable radial resolution and a finer angular resolution than the neutral models.

However, there were “holes” where the MTGCM top pressure level sank below the nominal 250 km altitude surface. Furthermore, the neutral density must be extended to much higher altitudes. Diffusive equilibrium was used to extend the neutral grid to 1000 km. The diffusive equilibrium approach was tested by taking the neutral atmospheres up to 150 km and then comparing the diffusive equilibrium results with the outputs from MTGCM. As can be seen in Fig. 7, the diffusive equilibrium approximation seems to be valid. The solid curve is the extrapolation from 150 km to 250 km and the symbols are the MTGCM values. The match means that within the
MTGCM code region the extrapolated results for higher altitude will be a smooth continuation from the MTGCM results.

While diffusive equilibrium is probably not a great assumption, the following rational was used in deciding to apply this approximation.

The traditional exobase being located around (~200 ± 20 km) is not the most recent understanding of the transition region between collisional and collisionless regions in the Martian atmosphere. Detailed DSMC kinetics models [Valeille et al. 2010a,b; Lee et al. 2015] reveal that the transition from a collisionally dominated region to a completely kinetic region (e.g. for neutral O) seems to happen over ~200-300 km (topside depending on Mars season). The MTGCM fluid assumptions are for a completely collisional region, which also transitions over this altitude range. It is reasonable in this transition region to assume diffusive equilibrium, since the transition to the exosphere (kinetic environment) is gradual (~200-300 km) and not sharp (at a fixed altitude near 200 km).

For the HALFSHEL plasma code most of the chemistry occurs at or below 300 km. However, there is still photoionization occurring at higher altitudes requiring a reasonable representation of the neutral atmosphere at these higher altitudes. The neutral atmosphere is extended upward from 250 km using the assumption of diffusive equilibrium so ionization regions have no sharp
discontinuities that can induce electric fields and motion where none should be found. In short, the goal is to avoid introducing artificial sources of energy by having a gradual and natural transition between collisional and non-collisional regions and this assumption meets the criterion while being “reasonable.” Finally, most of the ion removal is occurring in the region between 200 km and 250 km altitude which is in applicable range of MTGCM and thus no assumption of diffusive equilibrium is applied meaning whatever the deficiencies of the diffusive equilibrium assumption, the loss rates not strongly affected by the assumption.

### 3.2.2 Electron temperature

The electron temperatures from MTGCM were used for a more accurate chemistry calculation as several of the reaction rates are sensitive to the electron temperature. These temperatures were taken from a standard formulation based upon Viking measurements typically used in 1-D calculations (e.g. Fox, 1993). Figure 8 shows the Shinagawa and Cravens [1989] electron temperature profile used in previous simulations and that used from the MTGCM model. The MTGCM electron temperature is easily merged into the Shinagawa and Cravens [1989] temperature model at high altitudes. The electron temperature profile is held constant below 500 km, while Eq. 7, the electron temperature equation, is solved above this altitude. The altitude for the transition could be moved to a lower altitude, but the decision was made not to modify it. Recall that the electrons are a fluid and much of the physics to accurately calculate the electron
The MTGCM neutral models assume the atmosphere co-rotates with the planet. The simulations reported here do not make that assumption. Therefore, the co-rotation is added to the neutral flows provided from the MTGCM model. The equatorial co-rotational velocity of Mars ranges from roughly 245 m/s at the surface to slightly more than 280 m/s at 500 km. The MTGCM model indicates vertical winds can reach 30 m/s while the zonal winds reach velocities (400 m/s) which are in excess of the co-rotational velocities. The ions created by photochemical processes are given the neutral velocity values at their location as provided by the MTGCM neutral atmosphere plus the correction for co-rotation velocity. The presence of the co-rotation velocity will reduce drag on particles being accelerated toward the east but increase it for those going westward. With the presence of the neutral flow fields, the imposed E&M fields from the solar wind, and the rotating crustal fields it is unlikely that the ionosphere is locked into co-rotation but that will be determined self-consistently.
3.2.4 Comments about the 1-D and 3-D neutral atmosphere.

Research performed using the HALFSHEL code previous to and including Brecht and Ledvina, [2014] used 1-D symmetric fits to the neutral atmosphere. The full 3-D neutral atmosphere is employed for the research reported in this paper. Before the results of the simulations are discussed, it was felt that a comparison between the 1-D neutral profiles previously used and the 3-D MTGCM neutral atmospheres be provided. The most significant comparison simply integrated the entire neutral atmosphere loaded into the HALFSHEL code from 140 km altitude to 1000 km altitude. The results were as follows: for the 1-D atmosphere, the total integrated mass was 5.64 x 10^{10} kg for the O and 3.91 x 10^{12} kg for the CO₂. In the case of the 3-D neutral atmosphere, the results were 4.74 x 10^{10} kg for the O and 1.32 x 10^{12} kg for the CO₂. The 1-D atmosphere had more the mass in O than the 3-D atmosphere and roughly three (3) times the mass in CO₂ as the 3-D atmosphere. It will be shown later in the paper that the mass difference resulted in a slight difference in the ion loss rates.

4.0 Results of the simulations

The simulations used the following numerical parameters. The spatial resolution in the Cartesian grid was 100 km. The spherical grid where chemistry and collisions are calculated employed 10 km radial resolution and 1.4° in angular resolution. The time resolution was 0.02 s for the
plasma advection and the magnetic field evolution and 0.05 s for the chemistry equation solutions. This allowed accurate solution of the chemistry equations for all cases; solar minimum to solar maximum. It also allowed accurate solutions over the range of neutral density variations found in the MTGCM model.

The simulations reported in this paper used a uniform set of solar wind parameters. The solar wind parameters were as follows: The solar wind speed was 485 km/s, the IMF was 3 nT with a Parker spiral angle of 56°, and the solar wind density was 2.7 H⁺/cm³. The rotational axis of the planet is tipped at 25.19° with the orientation determined by the Ls of the simulation. Three different solar EUV levels were used representing solar minimum, a median value commensurate with the solar activity at the time of the MAVEN arrival, and solar maximum. As represented by the F₁₀.₇ proxy at Earth, these levels were F₁₀.₇ = (70, 130, 200). The EUV levels represented by the F₁₀.₇ proxy are then adjusted for Mars using 1/R² scaling to the appropriate location of Mars according to its solar longitude, Ls.

The results reflect that the choice of neutral atmosphere affects the loss rates from Mars. In the solar maximum case neutral atmospheres represented by 1-D spherically symmetric models, 3-D models with no winds, and 3-D models with winds were used in simulations. In the solar maximum case with full neutral wind and co-rotation included a series of simulations were performed with the simulations starting at MTC of 0°, 90°, 180°, and 270°. In each case, the
planet was rotating and the simulations were carried out until the loss rate of each ion species reached a steady state (~30 minutes). Thirty minutes represents only about 7° of rotation. Ls was 180° in the solar maximum and minimum cases. In the $F_{10.7} = 130$ case a full 3-D neutral model with neutral winds and co-rotation was used. In this case the Ls was 270° and the MTC was 180°.

The final arbitrator of code behavior and accuracy is comparison to data wherever possible. Fig. 1 of this paper showed such a comparison. Note that the data used by Lundin et al. [2013] is an average over solar wind conditions and planetary position in its orbit, Ls. This averaging is one reason why we compare differing Ls and even MTCs. Further, Lundin et al. [2013] also made some limiting assumptions about the homogeneity of ion loss over space in the tail region of Mars. The HAFSHELL simulations very clearly show that the density of ionospheric ions escaping is not homogeneous and is in fact time varying; see Fig. 9 and 10. These figures display three cuts through the 3-D simulation results for the $O_2^+$ and $O^+$ densities. One cut is in the tail section of the simulation, the others are in the equatorial plane and the meridional plane. There is a plume region [Dubinin et al., 2008; Y. Dong et al., 2015] where the convection electric field is directed away from the planet. It is clear that the larger gyroradius of the $O_2^+$ leads to a more extensive plume while the $O^+$ spirals back toward the tail region. It can be stated with some confidence that the estimates using the 10 eV to 300 eV energy band is an underestimate (i.e. a wider energy range would capture important lower energy ions that are
escaping). However, the percentage of the underestimate made by the spacecraft measurements is difficult to assess. The simulation results offer insight into the potential error and will be discussed later, but the error bars associated with the spacecraft measurements are not assessed.

For the purposes of this research the ions were considered to have escaped if they passed outward through a virtual box in the simulations set at 2 $R_M$. As each particle passes through this virtual box, its location, velocity, and density weight is recorded. This allows us to not only estimate the ion loss, but also assemble distribution functions, higher moments, and time dependent behavior in any region on the box. It also allows the imposition of energy bands permitting direct comparisons to the experimental results. Thus, discussion of the loss rates will include all energies, and the 10 eV to 300 eV range separately.

4.1 Loss Rates as a function neutral atmosphere

As discussed earlier, simulations were performed with 1-D and 3-D neutral atmospheres. In addition, the 3-D atmospheres also had neutral winds included. While the 1-D neutral atmosphere had more mass than the comparable 3-D atmosphere, the 3-D neutral atmosphere with the neutral winds led to greater loss rates. Table 1 offers tabulated results of all of the simulations. Fig. 11 shows the results for the $F_{10.7} = 70, 130, 200$ proxy with neutral winds and co-rotation where available. This choice represents the nominal results although one could have
chosen results that were even closer to the fit of Lundin et al. [2013]. The circles represent the total loss rate while the stars represent the loss rates in the energy band of 10 eV to 300 eV.

<table>
<thead>
<tr>
<th>Solar Activity</th>
<th>MTC</th>
<th>Type of Atmosphere</th>
<th>Type of Atmosphere</th>
<th>O⁺ Loss Rate</th>
<th>O₂⁺ Loss Rate</th>
<th>10ev – 300ev Loss Rate</th>
<th>Total Loss Rate</th>
</tr>
</thead>
<tbody>
<tr>
<td>200</td>
<td>180°</td>
<td>0°</td>
<td>3-D wind</td>
<td>1.1 x 10^{25}</td>
<td>3.6 x 10^{25}</td>
<td>3.3 x 10^{25}</td>
<td>4.7 x 10^{25}</td>
</tr>
<tr>
<td>200</td>
<td>180°</td>
<td>0°</td>
<td>3-D no wind</td>
<td>5.6 x 10^{24}</td>
<td>2.5 x 10^{25}</td>
<td>2.6 x 10^{25}</td>
<td>3.1 x 10^{25}</td>
</tr>
<tr>
<td>200</td>
<td>180°</td>
<td>0°</td>
<td>1-D wind</td>
<td>2.7 x 10^{24}</td>
<td>3.6 x 10^{25}</td>
<td>1.4 x 10^{25}</td>
<td>3.9 x 10^{25}</td>
</tr>
<tr>
<td>130</td>
<td>270°</td>
<td>180°</td>
<td>3-D wind</td>
<td>2.7 x 10^{24}</td>
<td>2.0 x 10^{25}</td>
<td>1.5 x 10^{25}</td>
<td>2.3 x 10^{25}</td>
</tr>
<tr>
<td>70</td>
<td>180°</td>
<td>0°</td>
<td>1-D no wind</td>
<td>3.0 x 10^{23}</td>
<td>3.4 x 10^{24}</td>
<td>1.5 x 10^{24}</td>
<td>3.8 x 10^{24}</td>
</tr>
</tbody>
</table>

The solar maximum case was chosen for our comparison between neutral models because the ultimate interest is in conditions where solar EUV fluxes are significantly higher (i.e. a situation expected in earlier Mars epochs). Examining Table 1 one can see that the total loss rates for the 1-D model is lower than the 3-D model with neutral winds but it is higher than the 3-D model without the neutral winds. Recall that the 1-D model has more mass than the 3-D model. While the 1-D atmosphere had more mass, the 3-D case with neutral winds has more energy. The ions created with the neutral wind velocity interact with the crustal magnetic fields to create...
both Lorentz forces and electric fields of sufficient strength to accelerate oxygen ions to escape velocity if the ion remains in the region of the crustal field for a sufficiently long time. It is clear that the inclusion of the 3-D neutral atmosphere with neutral winds produces a result more in keeping with the MEX/ASPERA data. Recall that only the starred values are appropriate for comparison to the Lundin et al. curve. Again, the results are in good agreement with the fit and the data. Not too surprisingly, the full loss rates are above the data fit by Lundin et al. [2013] as they should be. It should be noted that the ratio of F₁₀.₇ fluxes are: 1.86 for F₁₀.₇ 70 to 130, 1.54 for F₁₀.₇ 130 to 200, and 2.86 for F₁₀.₇ 70 to 200. However, the ratios of the loss rates are ~ 6.18, 2., and 22. for the respective flux ratios. This suggests that the system is not linearly dependent on the EUV although we would argue that solar wind-Mars interaction is a photochemical interaction. The data, see Fig.1, also indicates this same non-linear behavior.

4.2 The role of crustal field orientation

Focusing on the solar maximum case the effect of having different planetary orientations (MTC) facing the solar wind was examined. In this situation, the rotating planet covers about 7° during the time it takes the ionospheric loss rate to come to steady state. Four simulations were performed each with a different MTC, Fig. 12. The MTC was set to 0°, 90°, 180°, and 270°. It should be recalled that for MTC = 0° the large crustal fields are at the back of the planet near local midnight. At MTC = 180° the large crustal magnetic fields are located in the subsolar
region. Fig. 12 reveals less than a 50% change in the loss rates from the lowest to the highest loss rates. However, it is interesting to note that the lowest rates occur when MTC is either 0° or 270° while the highest is found at MTC = 90° and 180°. The average/median rates are close to the fit from Lundin et al. [2013] noting that for our simulations average and median are similar. These results are for the solar maximum case where the effect of the crustal magnetic fields is somewhat reduced [Brecht and Ledvina, 2014]. Solar minimum or a more moderate solar activity, as well as a different choice of Ls, might lead to differing results.

4.3 The relative loss as a function of species

Table 1 reveals some interesting results. The smallest ratio between O$_2^+$ and O$^+$ is found in the solar maximum case that has the neutral winds included. The other solar maximum cases have larger ratios suggesting that the neutral dynamics plays a role in the ratio of the O$_2^+/O^+$. The O$^+$ loss rate is significantly increased as more realistic atmospheres were used.

In all of the simulations it was found that the O$_2^+$ was the dominate species lost. However, there are regions where the O$^+$ dominates. Figures 13, 14, and 15 demonstrate these regions. The simulation shown in these figures had a solar EUV index represented by $F_{10.7} = 130$, the MTC was 180°, the Ls was 270°; the north pole was tipped away from the sun. In Fig. 13 one sees the evolution of the ratio O$_2^+/O^+$ as a function of distance down the tail. The regions where the O$^+$
flux dominates moves somewhat as the particles make their way out of the Martian system. Figures 14a,b shows the fluxes of \( \text{O}_2^+ \) and \( \text{O}^+ \) at the 2 \( R_M \) tailward of Mars. One can see definite structure in both figures with a rather strange triangular shape to the regions. It is clear that overall the \( \text{O}_2^+ \) is the dominate loss species. Examining the ratio of the fluxes, Fig. 14c, reveals that there are indeed regions where the \( \text{O}^+ \) dominates the loss (blue). Note: the scale is log10. These regions reside mostly on the side of the planet where the convection electric field points toward the planet. The convection electric field points in the positive \( z \) direction.

Fränz et al. [2010] examined the loss rates measured by MEX at the terminator. Here they found regions where the \( \text{O}^+ \) flux dominated the \( \text{O}_2^+ \) flux. Cuts were made of the simulation through the terminator and displayed in Fig. 15. The planet is being viewed from the Sun. Fig. 15 (a) shows the \( \text{O}_2^+ \) flux and (b) shows the \( \text{O}^+ \). It is clear that once again the \( \text{O}_2^+ \) dominates just as in the tail. Consistent with Fig. 14c, figure 15c reveals areas in the \(-z\) region of the planet where the \( \text{O}^+ \) flux dominates. Note: the scale is in log10. However, one also sees small patches where the \( \text{O}^+ \) flux dominates on the dusk side of the planet as well. This implies that orbits will be found where the measured \( \text{O}^+ \) flux will dominate the \( \text{O}_2^+ \) flux but typically the loss rates will be lower in these regions.

While the fluxes appear similar, Fig. 14 and 15, the actual densities are very different. Examination of Fig. 9 and 10 show that the \( \text{O}_2^+ \) is the dominate density, but it is moving at a
slower velocity. Hence the flux has regions where the O\(^+\) dominates. One should also keep in mind that the results shown here include ions of all energies, while the MEX results were limited to ions with energies between 10-300 eV.

5.0 Discussion of crustal field model implementation

In section 2 it was stated that the crustal magnetic field only entered the calculation via Eq. 3 the particle motion or momentum equation and the conductivity, Eq. 8. This choice was based on both numerical and physical reasoning. The magnetic field models [cf: Purucker et al., 2000; Cain et al., 2003] are high order fits to the MGS magnetometer data taken primarily on the night side at 400 km altitude. As such, the validity of the field models below or above is not very well constrained. This leads to the physical and numerical reasons for caution. On the physical side the reasoning is as follows. The sources of the crustal fields are within the surface of the planet, and thus are unaffected by currents set up in the ionosphere. Any measured changes would then be the vector sum of the crustal magnetic fields and the induced fields created by ionospheric currents. In short, the crustal magnetic fields themselves will not change. Hence, they cannot be part of equation (5) which defines the electric field and subsequent magnetic field change via Faraday’s law, Eq. 2. The crustal magnetic fields will deflect, rotate, and mirror flowing plasma as it encounters them. This will lead to changes in ion and electron currents then changes in electromagnetic fields, and thus modification of plasma behavior.
The numerical issues are more straightforward. A decision was made that the crustal fields could not be a source of energy; they could not produce current indefinitely (recall the fields themselves cannot be changed) therefore, \( \nabla \times \mathbf{B}_0 = 0 \) must be maintained. This is accomplished by not including the crustal fields in the total current used in electric field equation, Eq. 5. Therefore the total current, \( \nabla \times \mathbf{B} = (4\pi/c) \mathbf{J}_T \) only includes the induced current from the IMF.

Another feature that one would like to avoid is the presence of magnetic monopoles, \( \nabla \cdot \mathbf{B}_0 \neq 0 \). There is no reason to suspect or believe that the crustal field models, as complex as they are, will be either divergence free or curl free especially as implemented onto the code’s grid. So again putting \( \mathbf{B}_0 \) into Eq. 5 makes little sense. One could “divergence clean” the fields by computing a vector potential and then a new magnetic field from the vector potential, but then the fields would not be the crustal fields as prescribed by model.

One could argue that the electric field equation should contain a \( \mathbf{v}_e \times \mathbf{B}_0 \) term. The removal of this term from Eq. 5 is not obvious. Considering Faraday’s law, Eq. (2), and substituting in the \( \mathbf{v}_e \times \mathbf{B}_0 \) term, where we use the identities of \( \mathbf{J}_e = -\mathbf{J}_i \) and \( \nabla \cdot \mathbf{B}_0 = 0 \), one finds terms such as the following:

\[
\frac{\partial \mathbf{B}}{\partial t} \propto 2(\mathbf{J}_i) \cdot \nabla \mathbf{B}_0 + \nabla (\mathbf{J}_i) \cdot \mathbf{B}_0 - (\mathbf{B}_0 \cdot \nabla) \mathbf{J}_i.
\]
If one has concerns about the $\mathbf{\nabla} \times \mathbf{B}_0$ and $\mathbf{\nabla} \cdot \mathbf{B}_0 \neq 0$ terms then one could have some concern about the errors in the $\partial \mathbf{B} / \partial t$ relation. However, it is not obvious that removal of these terms leads to correct answers. If the plasma was simply co-rotating with the crustal fields then the $\mathbf{v}_e \times \mathbf{B}_0$ term would be zero or very small. However, it is clear that the ionospheric flow is not simply co-rotating given the neutral winds models placed in the code and the effect of the solar wind driven fields on the upper ionosphere. Several simulations were performed with the $\mathbf{v}_e \times \mathbf{B}_0$ term included in the code. The simulations included the $F_{10.7} = 130$ case and a $F_{10.7} = 200$ case. Appropriate neutral atmospheres were used. The results are tabulated in Table 2.

Table 2: Loss Rates with $\mathbf{v}_e \times \mathbf{B}_0$ included

<table>
<thead>
<tr>
<th>Simulation</th>
<th>Type of Atmos.</th>
<th>$\mathbf{O}^+$ Loss Rate</th>
<th>$\mathbf{O}_2^+$ Loss Rate</th>
<th>Total Loss Rate</th>
</tr>
</thead>
<tbody>
<tr>
<td>$F_{10.7} = 130$</td>
<td>3-D wind</td>
<td>$6.0 \times 10^{24}$</td>
<td>$2.1 \times 10^{25}$</td>
<td>$2.7 \times 10^{25}$</td>
</tr>
<tr>
<td>$F_{10.7} = 200$</td>
<td>3-D wind</td>
<td>$8.5 \times 10^{24}$</td>
<td>$2.1 \times 10^{25}$</td>
<td>$3.0 \times 10^{25}$</td>
</tr>
</tbody>
</table>

One can see that the loss rates have changed from the rates shown in Fig. 11 and Table 1. This in itself is not bad. However, one notes that the $F_{10.7} = 130$ case is now higher than before and the $F_{10.7} = 200$ case is lower. Moreover, the $\mathbf{O}_2^+$ is the same for both cases. While the $\mathbf{O}^+$ goes up for the $F_{10.7} = 130$ case and down for the 200 case. The total loss rates are now very similar. It is
disturbing that the EUV dependence has been lost. Since data is the final arbitrator of numerical design decisions, it is clear that it was a mistake to include the $v_e \times B_0$ term in the simulations. The fears about the implementation of the magnetic crustal field model were well founded.

As a parenthetical comment, one notes that in many of the MHD simulations [cf. C. Dong et al., 2014] and some of the hybrid simulations there does not seem to be a strong EUV dependence as seen in the data. C. Dong et al. [2014] reported loss rates of $2.5 \times 10^{24}$ for solar minimum and $6.6 \times 10^{24}$ for solar maximum. One wonders if it is possible that the implementation of the crustal magnetic fields is causing this lack of sensitivity. We have no knowledge of how these models are implemented in other codes but it is now clear that care must be taken. Finally, one last consideration should be addressed. In the situation where there is no solar wind, and the atmosphere/ionosphere has no velocity, the inclusion of the crustal magnetic fields should lead to no motion. As HALFSHEL is configured that is precisely the result obtained.

6.0 Conclusions and Discussion

The goal of this research was to address the issue of water loss and specifically the testing and inclusion of improved models necessary for accurate simulation of the loss of $O^+$ and $O_2^+$. The comparison of the results with the fits published by Lundin et al. [2013] strongly suggests that the goal has been achieved. The research revealed that inclusion of the 3-D neutral atmosphere
modified the loss rates. The ion loss rates increased to a maximum when the neutral winds and
the co-rotation velocity of the neutral atmosphere were present in HALFSHEL. The presence of
the neutral winds and co-rotation velocity forced the inclusion of a rotating planet because of the
crustal magnetic fields.

It is believed that the HALFSHEL code is ready to examine earlier epochs to determine if
removal of the Martian ionosphere by the solar wind is truly a viable water loss mechanism. It
should be noted that the loss rate of $10^{26}$ particles/cm$^3$ will only remove about 1.18 m of water in
2 GY, while it is now estimated that the planet had enough water to cover the entire planet
surface in $> 40$ m of water. Therefore, the modern loss rates as measure by Phobos-2, Mars
Express, and now MAVEN [Brain et al., 2015] will not explain the loss by ion removal in earlier
epochs. It remains to be seen if an increase in atmospheric density coupled with higher solar
EUV, higher solar wind density, and roughly the same velocity fields will lead to the necessary
order of magnitude or two increases in ion escape from Mars. In Brecht and Ledvina [2012] it
was found that while the results with the crustal magnetic fields increased with EUV flux, the
simulations with no crustal fields actually showed a slight decrease in loss rate with increased
EUV. As the simulations address earlier epochs (after the magnetic dynamo died $\sim 4$ Gy) with
more extensive atmospheres that shield the crustal magnetic fields from the direct interaction
with solar wind driven fields, will the loss rate still trend upward with increased EUV and solar
wind density?
To compare to the data it was found that using energy bins consistent with the instruments on the spacecraft was crucial and that there is a significant portion of the lost ions at energies below 10 eV and above 300 eV. It was also found that increasing the EUV flux as represented by heightened production frequencies and differing neutral atmospheres increased the loss rate of ionospheric ions, as one would expect. As explained in Brecht and Ledvina [2014], the crustal magnetic fields make a significant difference in the loss rate and as shown in this paper the implementation of the crustal magnetic field model must be performed with care.

During the course of this investigation a variety of tests were performed. The sensitivity of the loss rate to the neutral model was tested and it was found that adding the non-isotropic neutral atmosphere with neutral winds led to a higher loss rate and better agreement with the data discussed in this paper. It was also shown that careful testing of the integration time step and the spatial resolution of the neutral atmosphere was also very important to obtaining converged accurate solutions.

It is clear from the results that changes in the EUV flux is not a direct proxy for the ion loss rates from Mars or even the ion production rates. Mars is a complicated non-linear system were differing neutral atmospheres per EUV level, actual EUV photoionization, density dependent ion-neutral photo-chemistry (electron impact ionization, recombination), solar wind driven ion
dynamics and neutral wind dynamics via ion-neutral collisions all play critical connected roles in
determining the ionospheric loss to space.

In summary, the testing of each component of the HALFSHEL code has been time consuming
but very educational. The simulated global loss rates agree very well with current data. There
are issues remaining to be addressed. One of them is the ratio of $O_2^+$ to $O^+$. As reported in this
paper it is found that $O_2^+$ dominates the loss. However, earlier MEX data [cf. Nilsson et al,
2011; Carlsson et al., 2006] report loss rates where the two species are close to equal. However,
Nilsson et al comments “We have used the lowest energy data (up to 50eV) where the mass
separation works the best to estimate the relative amount of each species…” This limited energy
range does not allow for a determination of the dominate species. MAVEN data as published by
Benna et al. [2015] and Ergun et al., [2016] show equal amounts of $O_2^+$ to $O^+$ at altitudes up to
500 km... which is very interesting because simple photo-chemical results show the $O_2^+$ rapidly
dropping to zero above 300 km. Initial comparisons with HALFSHEL results, show very similar
results to Benna et al.[2015] and Ergun et al., [2016]. However, the complexity of the
comparison prevents further discussion in this paper. Finally, detailed comparison against
MAVEN data [cf. Jakosky et al, 2015] as it becomes available should add further credence to the
simulation results and/or illuminate areas where the modeling must be improved.
ACKNOWLEDGEMENTS:

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Bougher, S. W., S. Engel, D.P. Hinson, J.R. Murphy (2004),, MGS Radio Science electron density profiles: Interannual variability and implications for the Martian neutral...


FIGURE CAPTIONS:

Figure 1: Plots from Lundin et al. [2013] showing both the median escape rates (a) and the average escape (b) rates as a function of EUV (F10.7 proxy). In red are the HALFSHEL loss rates in the same 10 eV to 300 eV energy range.

Figure 2: The magnitude of B in Gauss from the 2-1/2 D hybrid simulation of the Uranus bow shock. Note: the overshoot region produces a jump of 20 and is highly structured. The inflow conditions were the solar wind conditions reported by Bagenal et al. [1987].

Figure 3: Comparison of the simulation results with the data reported by Bagenal et al. [1987]. The solid line represents the simulation results. The vertical line is the end of the simulation coverage. Note the excellent agreement with the electron temperature as well as with the proton density.

Figure 4. (a) The ratio of individual ion species density to a converged solution at 150 km is shown. (b) The ratio of individual ion species density to a converged solution at 200 km is shown. The converged solution was created using Δt = 0.002s.

Figure 5: The error in chemistry as a function of the size of Δr in km. The solid line is O2+ and the dashed line is O+.

Figure 6: Maps of the neutral atmosphere of Mars at 200 km altitude. The subsolar is at 12 o’clock and the EUV indicator is F10.7 = 130. (a) Shows the neutral temperature and velocity vectors in the horizontal plane (the largest vector is 523m/s). (b) Shows the Log10 of the CO2 neutral density. (c) Shows the Log10 of the O neutral density.

Figure 7: The left plot is of the test with CO2. The right plot is the test with O.

Figure 8: Electron temperature profile as a function of altitude. The continuous line is the fit from Shinagawa and Cravens and the symbols are from the MTGCM model.

Figure 9: The O2+ ions as they escape Mars’ ionosphere.

Figure 10: Plot of the O+ ions as they escape from Mars’ ionosphere.
Figure 11. Plot of the two scaling relations from Lundin et al. [2013] and the results of various simulations and energy bands. The circles are the total loss rates including all energy bands.

Figure 12. Loss rates as a function of MTC or sub-solar longitude. The full circles are the total loss rates, the stars are the loss rates for the 10eV to 300 eV energy band. Note that the variation fits better to the median (dashed) fit rather than the mean (solid). The average/median values of the loss rate are slightly higher than the fit. There is less than a 50% variation from minimum to maximum loss rate suggesting that the crustal field orientation is not a major factor in determining the loss rate.

Figure 13. The ratio of O$_2^+$/$O^+$ at the terminator, 2 R$_M$, and 4 R$_M$. The scale is in log10.

Figure 14. The loss flux of both O$_2^+$ (a) and O$^+$ (b) as measured at 2 R$_M$ downstream of Mars. (c) The ratio of flux is for O$_2^+$ and O$^+$ at 2 R$_M$ in the tail.

Figure 15. The anti-sun flux in the +x direction at the terminator of Mars as seen from the Sun (a,b). The ratio of O$_2^+$ / O$^+$ is shown in (c).