



Inferring the Behavior of Distributed Energy Resources with Online Learning

Gregory S. Ledva, Laura Balzano, &
Johanna L. Mathieu

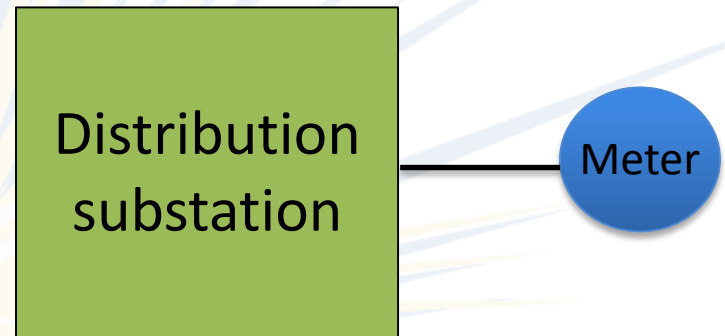
University of Michigan

Disaggregating substation load data

Power consumption of all the
loads/generators we care about



Power consumption of all the
loads/generators we DON'T care about



Why do we want to disaggregate resources at the feeder?

- Energy efficiency via conservation voltage reduction
- Contingency planning
- Optimal reserve contracting
- Demand response event signaling
- Demand response bidding
- Load coordination feedback

Disaggregation methods

e.g., [Berges et al. 2009; Kolter et al. 2010;
Dong et al. 2013]

- State estimation
 - Linear techniques require LTI system models
 - Nonlinear techniques can be computationally demanding
- Online learning
 - Optimization formulations
 - Model-free
- Hybrid approach: Dynamic Mirror Descent [Hall & Willet 2015]
 - Admits dynamic models of arbitrary forms
 - Optimization-based method to choose a weighted combination of the estimates of a collection of models

Outline

- Dynamic Mirror Descent
- Problem setting: Plant data/models
- Algorithm Models
- Results
- Next steps

Dynamic Mirror Descent

- Mirror Descent: online algorithm to estimate a fixed state
- Dynamic Mirror Descent: online algorithm to estimate a dynamic state using a *collection of models* [Hall & Willet 2015]
 1. Compute the error between the model predictions and the measured data (i.e., loss function)
 2. Update the state in the direction of the negative gradient of the loss function

$$\tilde{\theta}_t^i = \arg \min_{\theta \in \Theta} \eta_t \left\langle \nabla \ell_t(\hat{\theta}_t^i, y_t), \theta \right\rangle + D \left(\theta \parallel \hat{\theta}_t^i \right)$$

Dynamic Mirror Descent

3. Use the estimated states to evaluate the models for the next time step

$$\hat{\theta}_{t+1}^i = \Phi_t^i(\tilde{\theta}_t^i)$$

4. Compute a weighted version of the estimates

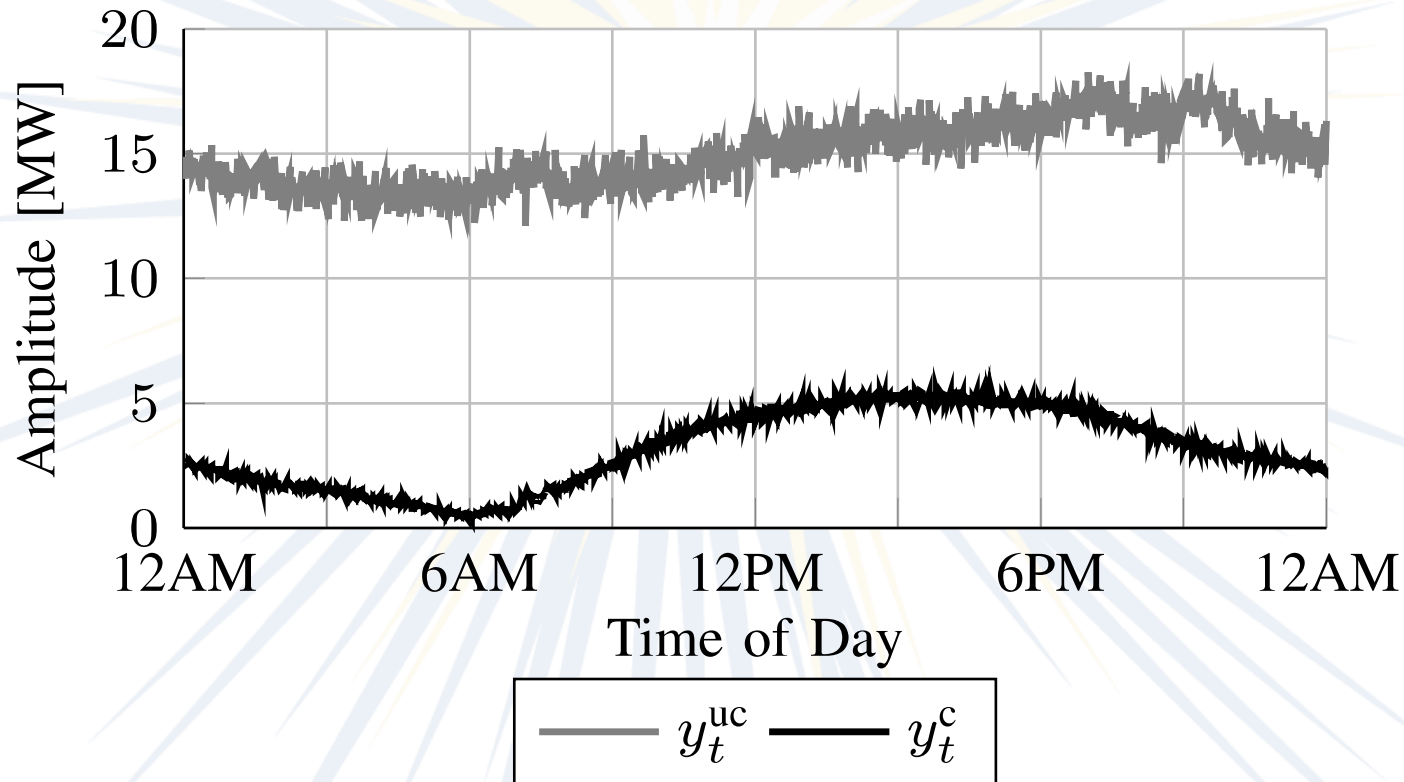
$$\hat{\theta}_{t+1} = \sum_{i=1}^{N^{\text{mdl}}} w_{t+1}^i \hat{\theta}_{t+1}^i.$$

5. Update the model weights

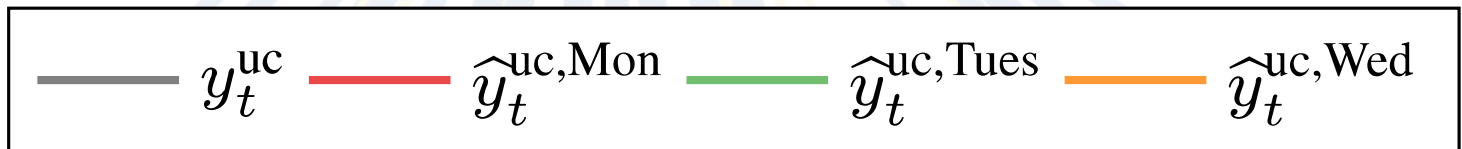
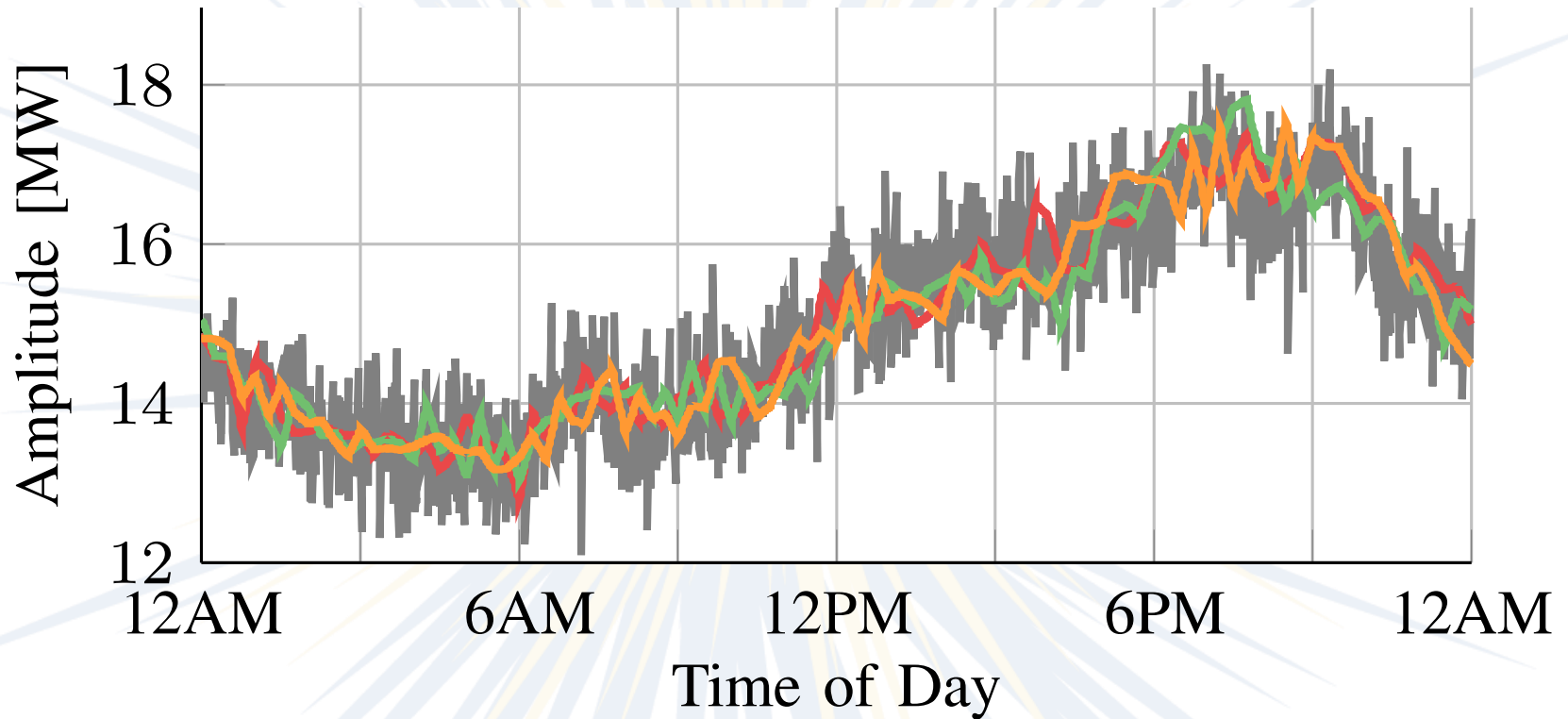
$$w_{t+1}^i = \frac{\lambda}{N^{\text{mdl}}} + (1 - \lambda) \frac{w_t^i \exp\left(-\eta^r \ell_t\left(\hat{\theta}_t^i, y_t\right)\right)}{\sum_{j=1}^{N^{\text{mdl}}} w_t^j \exp\left(-\eta^r \ell_t\left(\hat{\theta}_t^j, y_t\right)\right)}$$

Problem Setting: Plant Data/Models

- Uncontrollable loads: data from Pecan Street Inc. Dataport
- Controllable loads: equivalent thermal parameter (ETP) models of air conditioners [Sonderregger 1978]



Algorithm Models: Uncontrollable loads



Algorithm Models: Controllable loads

- Two-state hybrid models of air conditioners [Mortensen & Haggerty 1988]
 - Temperature and ON/OFF mode
- Sets of Linear Time Invariant (LTI) aggregate system models [Mathieu et al. 2013]

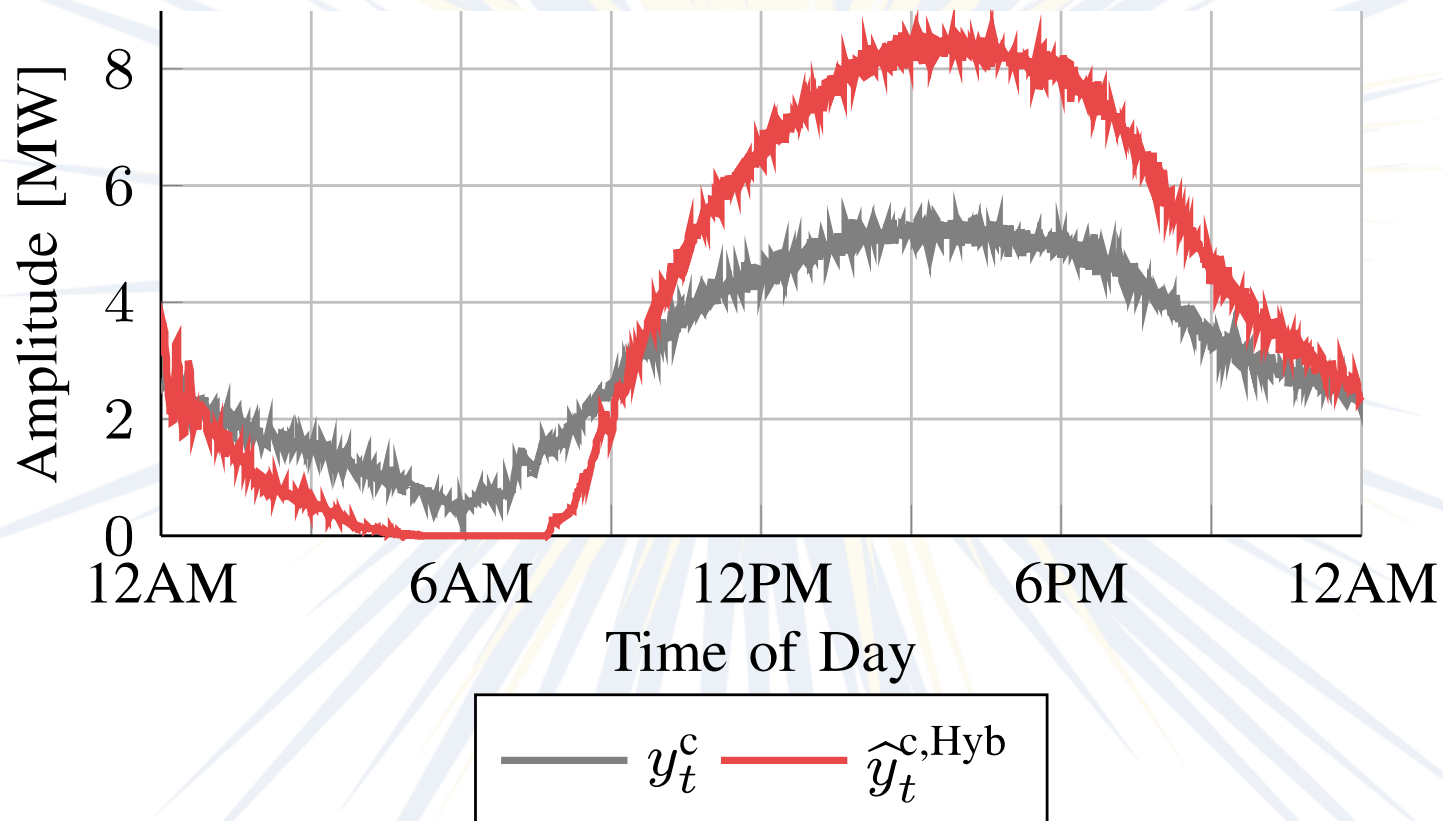
$$\begin{aligned}x_{t+1}^i &= A^i x_t^i & i \in \mathbb{N}^{\text{temps}} \\ \widehat{y}_t^{\text{c,LTI},i} &= C^i x_t^i & i \in \mathbb{N}^{\text{temps}}.\end{aligned}$$

- Sets of Linear Time Varying (LTV) aggregate system models

$$\begin{aligned}x_{t+1} &= A_t x_t \\ \widehat{y}_t^{\text{c,LTV}} &= C_t x_t.\end{aligned}$$

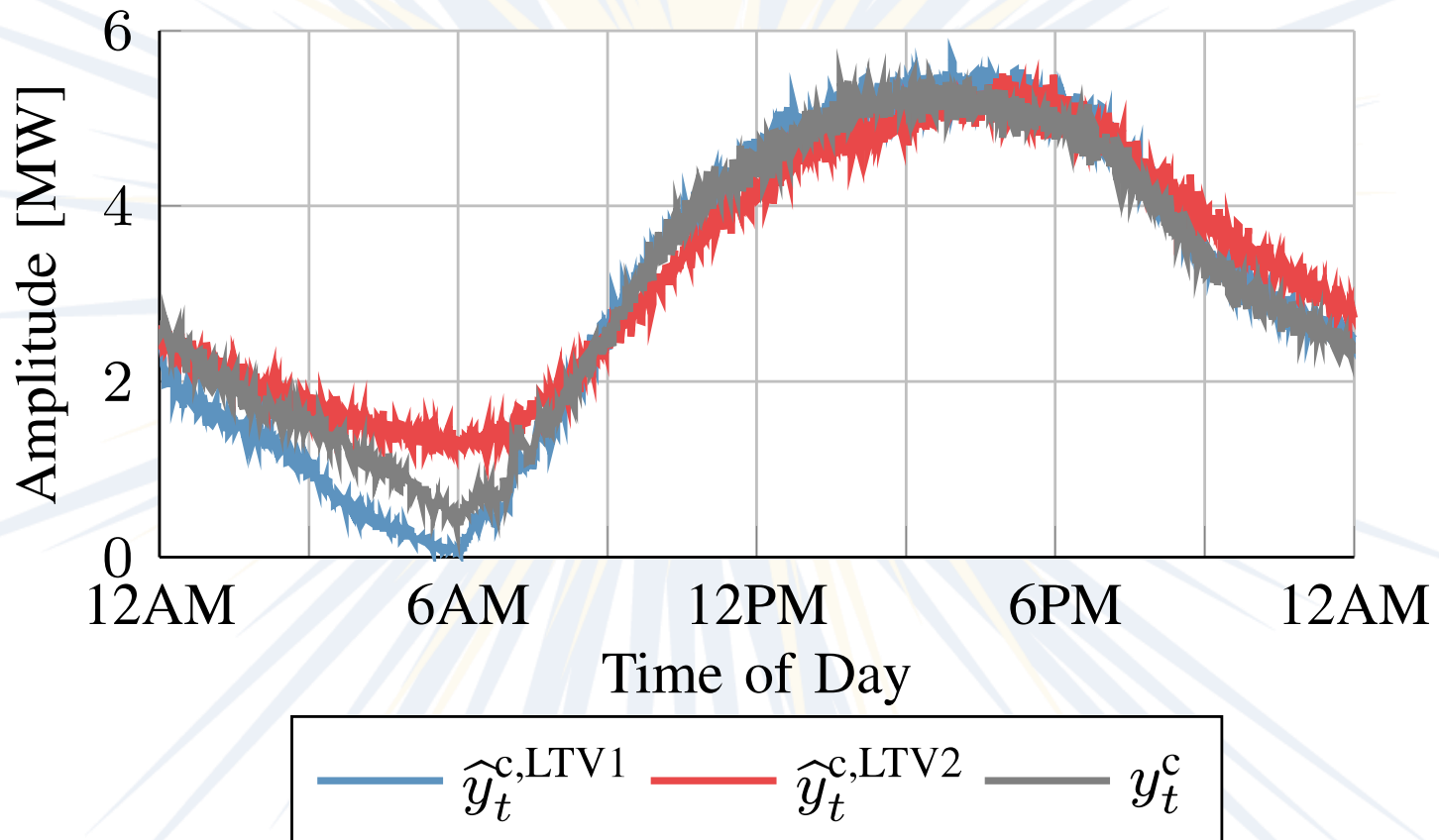
Algorithm Models: Controllable loads

- Two-state hybrid AC models do not work well.



Algorithm Models: Controllable loads

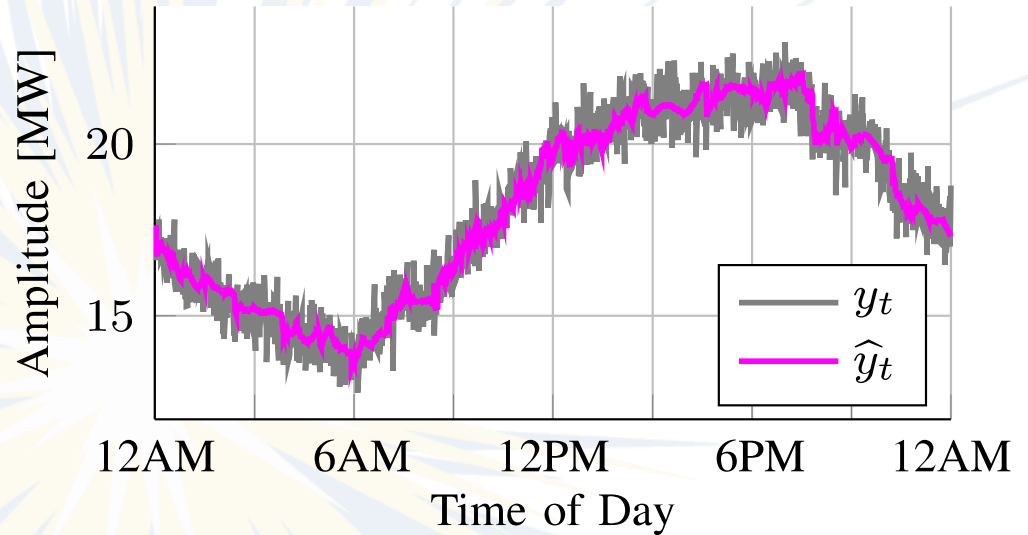
- LTV models work better.



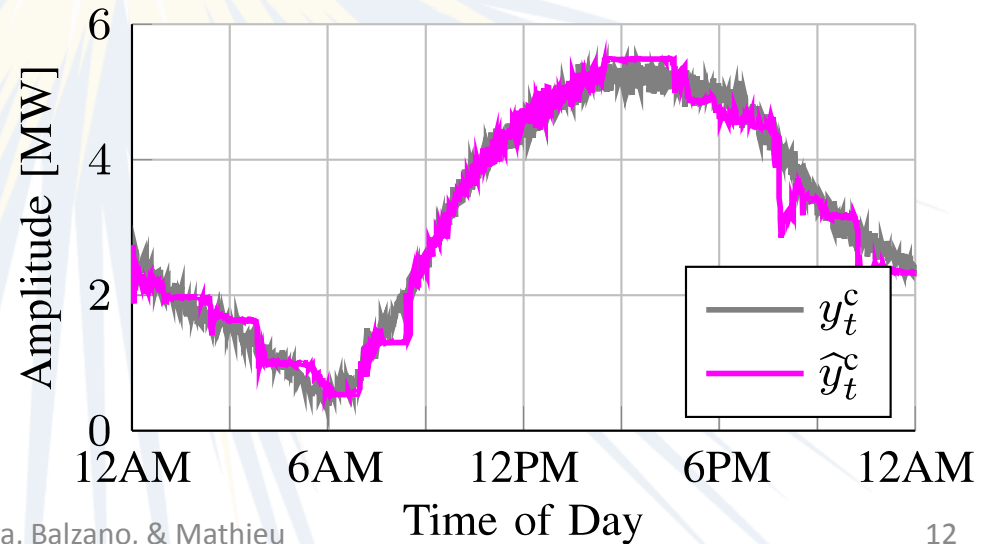
Results:

All combinations of models

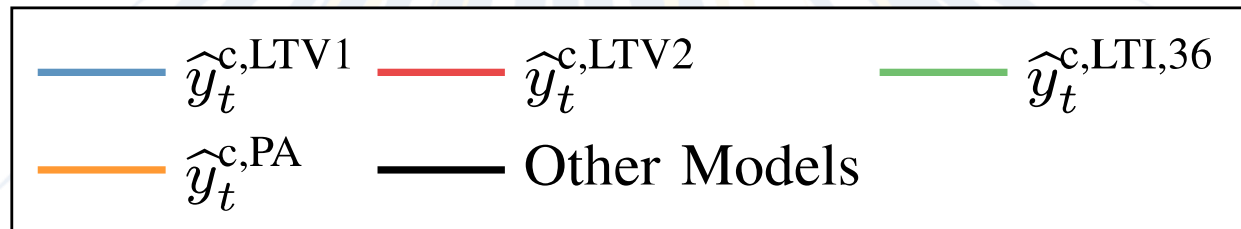
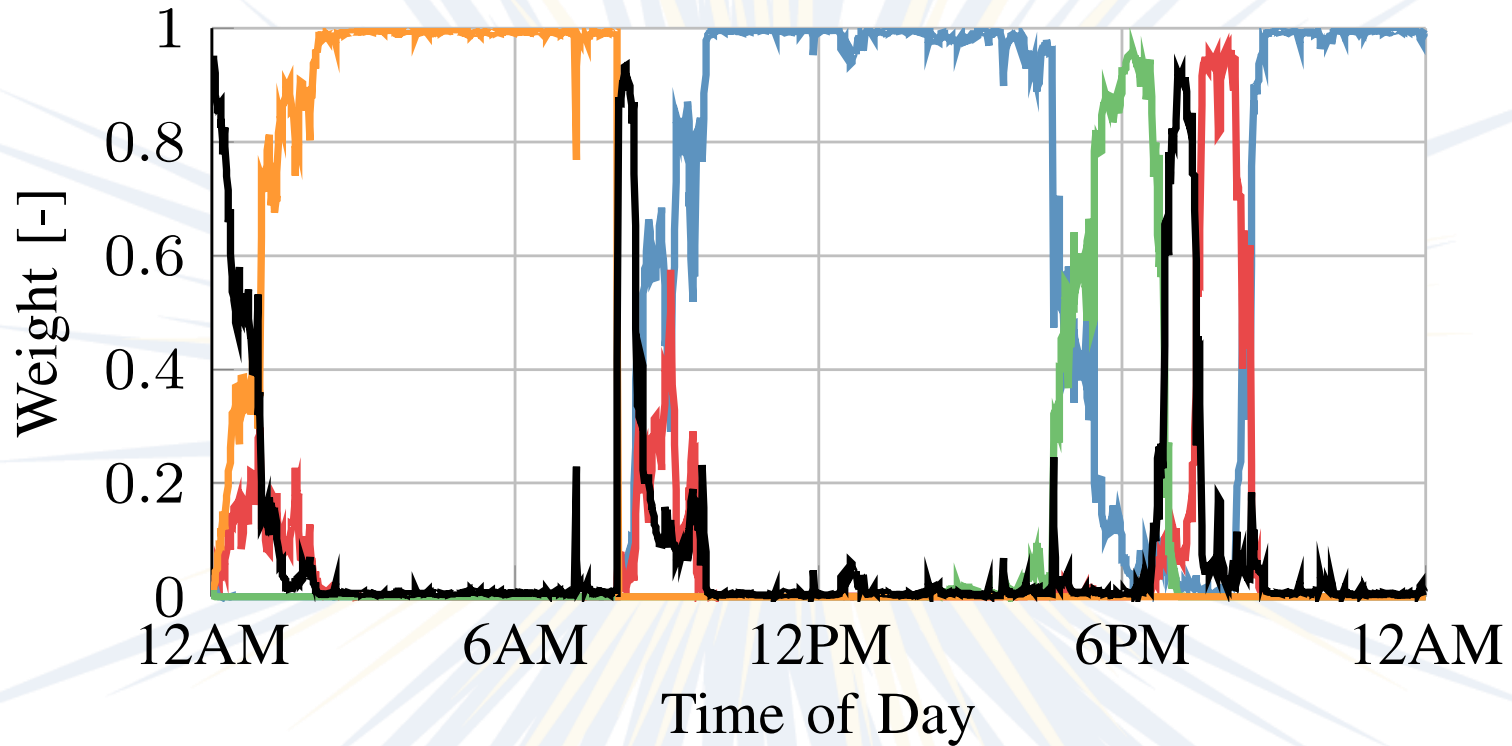
Total Load



Controllable Load

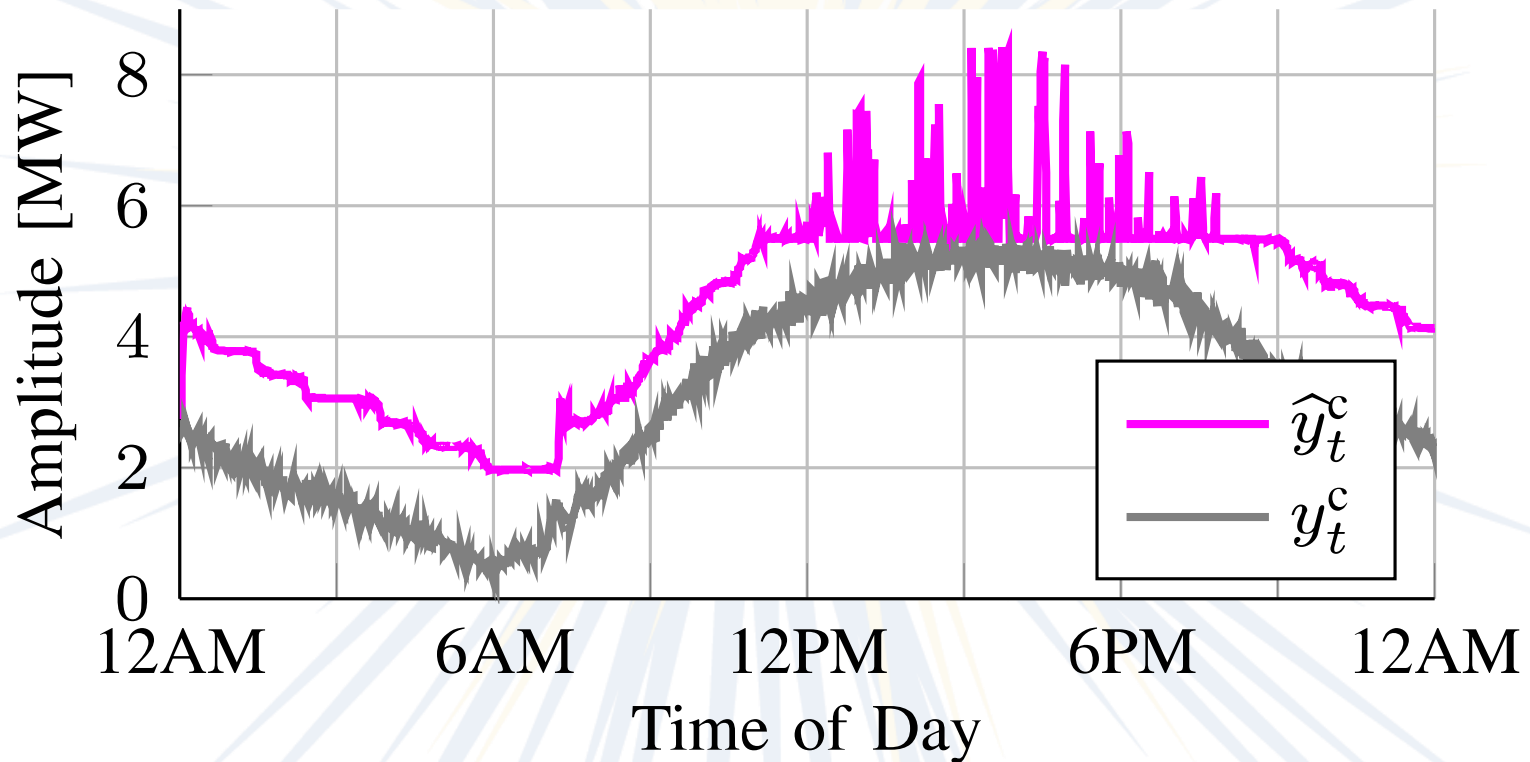


Results: Weightings



Results: Bad Models

- All uncontrollable load models are too low.

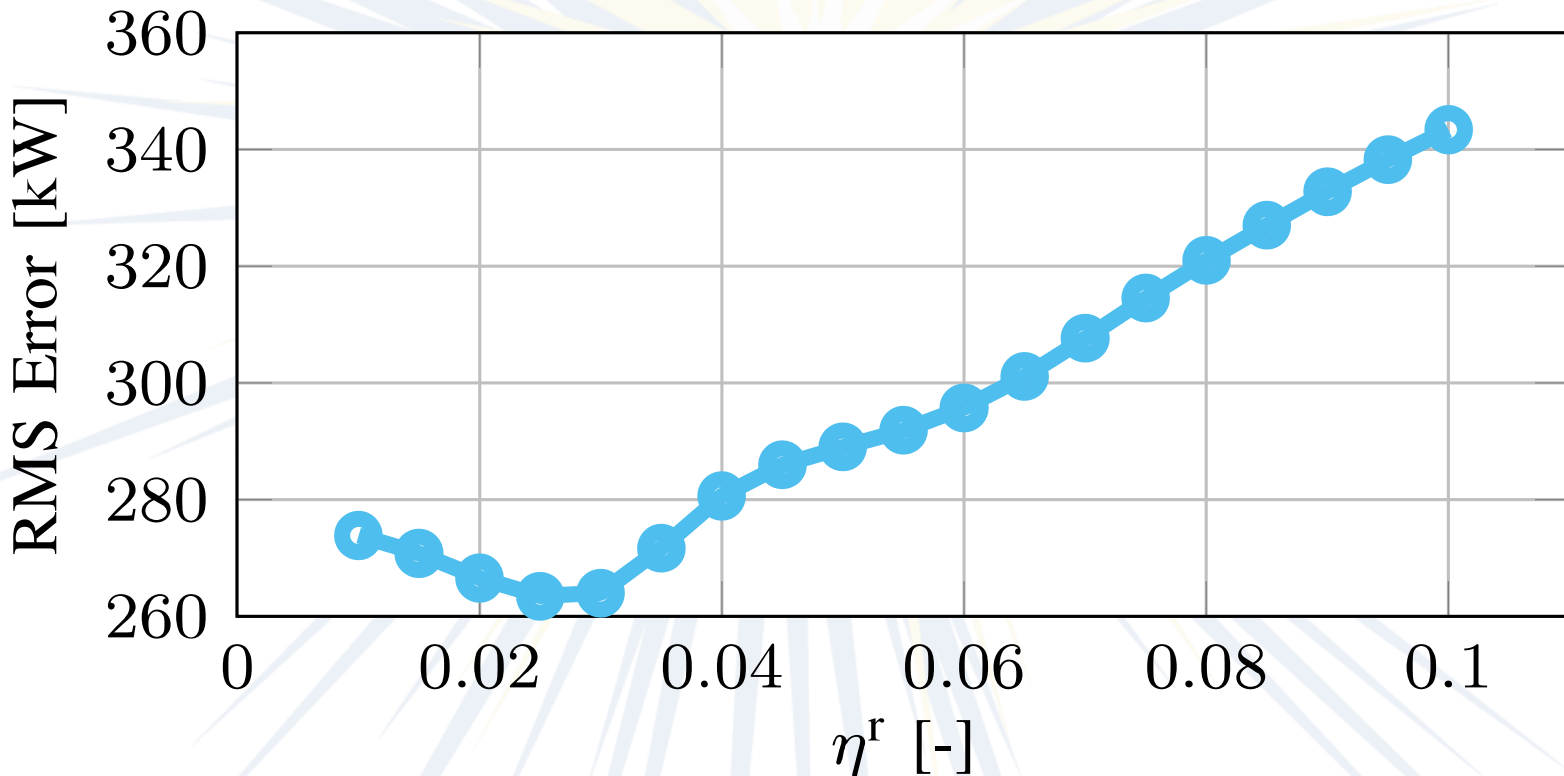


Results: Summary

Case	RMS Error (kW)
Benchmark: Use current outdoor temperature to evaluate simple controllable load model	738
DMD Case 1: Includes every combination of uncontrollable and controllable models	264
DMD Case 2: Case 1 models plus a smoothed version of the actual uncontrollable load	211
DMD Case 3: Case 2 models plus more accurate model of the controllable load over time periods where the other models are less accurate	175
DMD Case 4: Includes uncontrollable load models that underestimate the uncontrollable load	1392

Results: Varying Algorithm Parameters

Recall:
$$w_{t+1}^i = \frac{\lambda}{N^{\text{mdl}}} + (1 - \lambda) \frac{w_t^i \exp\left(-\eta^r \ell_t\left(\hat{\theta}_t^i, y_t\right)\right)}{\sum_{j=1}^{N^{\text{mdl}}} w_t^j \exp\left(-\eta^r \ell_t\left(\hat{\theta}_t^j, y_t\right)\right)}$$



Next steps

- Investigate more realistic settings (using more real data)
- Develop better load models
- Improve the algorithm, e.g., alternative weighting functions
- Investigate identifiability
- Incorporate additional measurements (reactive power, voltage) into the approach

Conclusions

- Dynamic Mirror Descent (DMD) enables us to solve the substation disaggregation problem leveraging dynamical models of arbitrary form
- DMD can work well (on simple examples); however, it is easy to find instances where it does not work well
- Many open questions!

Funded by NSF Grant ECCS-1508943 .