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Sequential imputation for models with latent variables assuming latent ignorability

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Summary

Models that involve an outcome variable, covariates, and latent variables are frequently the target for estimation and inference. The presence of missing covariate or outcome data presents a challenge, particularly when missingness depends on the latent variables. This missingness mechanism is called *latent ignorable* or *latent missing at random* and is a generalization of missing at random. Several authors have previously proposed approaches for handling latent ignorable missingness, but these methods rely on prior specification of the joint distribution for the complete data. In practice, specifying the joint distribution can be difficult and/or restrictive. We develop a novel sequential imputation procedure for imputing covariate and outcome data for models with latent variables under *latent ignorable missingness*. The proposed method *does not require a joint model*; rather, we use results under a joint model to inform imputation with less restrictive modeling assumptions. We discuss identifiability and convergence-related issues, and simulation results are presented in several modeling settings. The method is motivated and illustrated by a study of head and neck cancer recurrence.

Key words: multiple imputation; substantive model compatible imputation; chained equations; latent missing at random; latent ignorability

1. Introduction

Models that involve latent or partially latent variables in addition to an outcome variable and covariates are frequently the target for estimation and inference. For example, in the Cox proportional hazards mixture cure model, partially latent cure status describes whether individuals are at risk for the event of interest. Cure status is only partially latent because subjects with observed events are known to be non-cured. Another popular model with latent variables is the linear mixed model, where fully latent random effects account for correlation within clusters.

Additional considerations arise when dealing with missing covariates and/or outcomes

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Acknowledgment. The authors cite the many investigators in the University of Michigan Head and Neck Specialized Program of Research Excellence for their contributions to patient recruitment, specimen collection, and study conduct. This research was partially supported by the National Institutes of Health.

16 in the presence of latent variables. Many authors have explored the issue of missing data
17 for models with latent variables under assumptions that missingness is independent of the
18 latent variable given the observed data (e.g. Beesley et al. 2016). In this paper, we explore a
19 generalization of this missingness mechanism that allows covariate/outcome missingness to
20 depend on the latent variable, which is a *missing not at random* (MNAR) mechanism (Little
21 & Rubin 2002). Previous examples of such mechanisms are called *latent ignorable* or *latent*
22 *missing at random* (LMAR) missingness (Frangakis & Rubin 1999; Harel 2003; Harel &
23 Schafer 2009). For example, suppose we model a longitudinal outcome using a mixed model.
24 One common LMAR scenario in the literature relates dropout to the random effect, which
25 can be viewed as a measure of an individual's propensity to drop out.

26 In general, the underlying missingness mechanism can never be determined from
27 the data alone, and inference under MNAR may be sensitive to unverifiable assumptions
28 about the missingness mechanism. Additionally, inference under MNAR is susceptible to
29 underidentification or weak identification of the model parameters (Little 1995; Molenberghs,
30 Beunckens & Sotito 2008). In this paper, we consider a particular MNAR missingness
31 mechanism (LMAR) in which missingness depends on unknown information *only* through
32 the latent variable, which by assumption has a structured relationship with the observed
33 variables. Therefore, we may view LMAR missingness as a somewhat mild departure from
34 MAR. Still, we must keep these issues in mind when handling missing data under LMAR.

35 One approach for handling missing data is to analyze only the fully observed subset of
36 the data (complete case analysis). When missingness is LMAR, this approach will generally
37 produce biased results (Little & Rubin 2002). Several authors have discussed likelihood-
38 based approaches for linear mixed models with missingness dependent on the random effect
39 (e.g. Little 1995; Wu & Carroll 1988). These methods often involve an EM algorithm or a
40 likelihood that has integrated out the latent variable.

41 Multiple imputation is a common general approach for dealing with missing data.
42 One approach to multiple imputation requires one to specify a joint distribution for all
43 the variables and use that joint distribution for imputation, usually in a Gibbs sampling-
44 type algorithm. Each variable with missing values can be sequentially imputed using its
45 conditional distribution, which is determined by the joint distribution. The distribution of the
46 sampled parameters can then be used for inference. Several authors have proposed approaches
47 for handling latent ignorable missingness in specific joint modeling settings (Jung 2007;
48 Yang, Lu & Shoptaw 2008; Lu, Zhang & Lubke 2011). Harel (2003) proposes a non-iterative
49 imputation approach for dealing with general latent-dependent missingness under a joint
50 model.

51 Existing imputation methods under latent ignorability, however, are limited in their
52 applicability. The main drawback of the joint modeling approach to imputation is that

53 specification of the joint distribution may be difficult or too restrictive, particularly when
54 we have many covariates of different types. Indeed, Gelman (2004) argues that ‘having a
55 joint distribution in the imputation is less important than incorporating information from
56 other variables and unique features of the dataset (e.g. bounds, skip patterns, nonlinearity,
57 interactions, etc.).’ As such, there is a need to consider methods for imputing variables under
58 latent ignorability that incorporate less restrictive assumptions about the joint model.

59 Chained equations imputation is an alternative to joint modeling in which variables are
60 imputed iteratively in a series of univariate imputation steps (Raghunathan 2001; Van Buuren
61 et al. 2006). These steps are usually accomplished using standard regression models that
62 can incorporate additional features of the data, and these regressions as a set usually do not
63 correspond to a valid joint distribution. This approach is simple and flexible, but it is less
64 coherent than joint modeling and may not incorporate assumptions about the outcome model
65 directly. Most literature on chained equations assumes that missingness is independent of
66 all unobserved information, called *missing at random* (MAR) (Little & Rubin 2002), and
67 some authors have explored particular limited MNAR settings (e.g. Van Buuren 2007; Little
68 2009a; Giusti & Little 2011). An alternative approach proposed in Bartlett et al. (2014)
69 called substantive model compatible (SMC) imputation incorporates the outcome model
70 into the chained equations imputation procedure but does not require the user to specify a
71 valid joint distribution for the covariates, leading to improved properties over conventional
72 chained equations but additional flexibility over joint modeling. Similar findings are given
73 in White & Royston (2009) and Beesley et al. (2016). Beesley et al. (2016) explores SMC
74 imputation for a particular modeling setting with latent variables, but we have not found any
75 literature exploring chained equations or SMC imputation under latent ignorable missingness
76 in general.

77 In this paper, we develop a novel sequential imputation method that can handle MAR and
78 LMAR covariate and outcome missingness for models with latent or partially latent variables
79 and that *does not* require a joint model. The proposed method imputes the latent variable
80 as part of the missing data, allowing the latent variable to be directly used when imputing
81 the missing covariate/outcome values. We first consider the more restrictive setting where the
82 joint model is fully specified. We use results under a joint model to *inform the structure* of the
83 imputation distributions and the method for drawing parameters in the proposed algorithm
84 *without requiring specification of the joint model*. The proposed approach is very flexible
85 and can accommodate either a chained equations-type approach to imputation or a SMC
86 imputation approach that is more strongly informed by the outcome model.

87 Many works have explored MAR-based imputation in settings with latent variables
88 under a joint model (e.g. Schafer 1997; Schafer & Yucel 2002; Chung, Flaherty & Schafer
89 2006) or using less restrictive assumptions Beesley et al. (2016). While the proposed method

90 can be applied under MAR or LMAR, the primary novelty consists of the application to the
91 LMAR setting. Existing methods for handling missing data in the LMAR setting assume
92 there is a fully-specified joint model, and this work serves as an extension of these existing
93 methods with less restrictive modeling assumptions. This work develops novel statistical
94 methodology for handling latent ignorability *without requiring joint modeling assumptions*.
95 This is a departure from the existing literature in terms of allowing for much greater flexibility
96 in model specification over joint modeling while still allowing for the incorporation of the
97 outcome model structure into the imputation procedure. The SMC imputation approach to
98 imputation has been previously explored in the context of MAR covariate imputation in
99 Bartlett et al. (2014), but a general imputation algorithm for handling missingness in multiple
100 variables and particularly under MNAR assumptions has not previously been considered.
101 Additionally, the LMAR setting presents a range of identifiability-related difficulties that is
102 not present in the usual MAR setting.

103 This work is motivated by a study of cancer recurrence in patients treated for head
104 and neck cancer. In this study, many covariates of interest have substantial missingness; in
105 particular, HPV status (human papillomavirus) has roughly 50% missingness. Previous work
106 has explored imputation of these data under MAR assumptions (Beesley et al. 2016), but there
107 is a belief that an induced association between missingness in HPV status and an underlying
108 latent variable (cancer cure status) may be present. Existing statistical methods for latent-
109 dependent missingness are undesirable due to the emphasis on specification of a joint model
110 for the covariates, which in this setting is too restrictive. In particular, relationships between
111 the covariates may be difficult to capture in a standard joint model. As such, there is a need
112 to develop statistical methodology for performing imputation of the missing covariate values
113 under latent-dependent missingness without the restrictive joint modeling assumptions. While
114 this work is motivated by this particular problem, the statistical methods can be applied in a
115 wide range of modeling settings.

116 In Section 2, we define latent ignorability. In Sections 3 and 4, we describe the proposed
117 imputation approach. In Section 5, we present simulations that evaluate the performance of
118 our method under a variety of scenarios. In Section 6, we apply the proposed methods to the
119 motivating study of time to recurrence in patients with head and neck cancer. In Section 7,
120 we present a discussion.

121

2. Latent ignorability

Suppose that the goal is to make inference about a model for outcome Y given covariates X and a latent (or partially latent) mixing variable, L . For example, the outcome model may be a linear mixed model with a latent random intercept. We may also be interested in

the model for $L|X$. We restrict our attention to situations in which, if all of the covariate and outcome information were observed, the outcome model would be fully identified, and estimation using likelihood-based methods would be possible and lead to consistent parameter estimates. We consider missingness in X and/or Y , and we allow missingness to be related to the latent variable, L .

Let vector $\mathbf{D}_i^\top = (\mathbf{X}_i^\top, \mathbf{Y}_i^\top)$ represent the (possibly incomplete) data for subject i . We assume \mathbf{D}_i and L_i are independent across subjects. Let \mathbf{R}_i^D be a vector corresponding to whether each element of D_i is observed and R_i^L be an indicator for whether L_i is known (can be 0 for all subjects). Define $\mathbf{R}_i^\top = (\mathbf{R}_i^{D^\top}, R_i^L)$. For any vector \mathbf{V}_i , let $\mathbf{V}_i^{(\text{obs})}$ and $\mathbf{V}_i^{(\text{mis})}$ be the observed and missing elements of \mathbf{V}_i . Assume we have independence of (D, L, R) across i .

We assume that missingness in D_i is independent of $D_i^{(\text{mis})}$ and R_i^L such that

$$f(\mathbf{R}_i^D | D_i, L_i, R_i^L; \phi^D) = f(\mathbf{R}_i^D | D_i^{(\text{obs})}, L_i; \phi^D) \quad (1)$$

We assume that ϕ^D is distinct from all other model parameters. We call assumption (1) the *latent missing at random* (LMAR) or *latent ignorability* assumption. This missingness mechanism was first studied in Frangakis & Rubin (1999) and is a special case of latent ignorability explored in Harel (2003) and Harel & Schafer (2009). In longitudinal data analysis, a similar mechanism relating missingness in Y to latent random effects in a linear mixed model has been explored by many authors including Wu & Carroll (1988), Follmann & Wu (1995), Little (1995), and McCulloch, Neuhaus & Olin (2016). Since L_i is latent or partially latent by definition, the mechanism in (1) is a type of MNAR, and when (1) does not depend on L_i , the mechanism reduces to MAR. We can view LMAR as a generalization of MAR with less restrictive assumptions.

We now consider assumptions regarding missingness in L , which may be latent or partially latent. We make a subtle distinction between *partially latent* and *partially missing* variables. Latent variable L can be viewed as a modeling construct representing unobserved or perhaps unobservable quantities. The *observed* values of the partially latent L are just a function of the observed data, $D^{(\text{obs})}$, and therefore contain no additional information. For example, known values of the partially latent cure status in a Cox proportional hazards cure model are entirely determined by the event indicator and the event/censoring time for each subject. In this way, partially latent variables are different from partially missing variables, which may contain additional information in their observed values. However, we will treat latent and partially latent variables as if they were missing data for the purposes of this method.

When L_i is fully latent, we can view missingness in L_i as missing completely at random (MCAR) with probability of missingness equal to 1. When L_i is partially latent, we allow

missingness in L_i to depend on $D_i^{(obs)}$ (so L is MAR) such that

$$f(R_i^L | D_i, L_i, R_i^D; \phi^L) = f(R_i^L | D_i^{(obs)}; \phi^L) \quad (2)$$

122 Figure 1 shows the assumed relationships between variables. The arrows represent
 123 dependence. For example, R^L may depend on $X^{(obs)}$ and $Y^{(obs)}$.

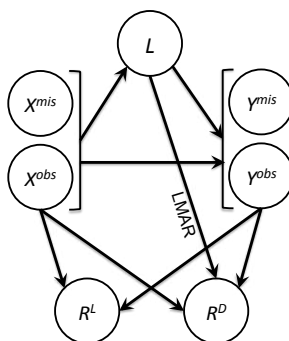


Figure 1. Variable relationships under latent ignorability

124 *Example 1, linear mixed model with a random intercept:* Suppose our model for
 125 multivariate outcome Y_i is a linear mixed model with a latent random intercept, b_i , and
 126 covariates X_i . This model is commonly used for longitudinal data, where the outcome is
 127 measured within individuals over time. In such a setting, outcome missingness is particularly
 128 common due to dropout. Many authors have described scenarios in which dropout may be
 129 related to the random effects (Wu & Carroll 1988; Little 1995; Yang, Lu & Shoptaw 2008,
 130 e.g.). In this example, b_i represents an individual's propensity to drop out. This is a LMAR
 131 mechanism with $L_i = b_i$. Covariate missingness may also be LMAR.

132 *Example 2, Cox proportional hazards mixture cure model:* The Cox proportional hazards
 133 (CPH) mixture cure model is used in event time analysis when some (cured) subjects are
 134 unable to experience the event of interest (Sy & Taylor 2000). For subjects with events,
 135 cure status is known, and it is unknown for censored subjects. Therefore, cure status is
 136 partially latent. Missingness in cure status is entirely determined by observed information,
 137 so its missingness can be viewed as MAR. Suppose we have covariate missingness. We
 138 can imagine scenarios in which covariate missingness may depend on the underlying cure
 139 status. For example, suppose covariate information is collected through a patient survey.
 140 Cured subjects may be more or less likely to answer certain survey questions, resulting in
 141 an association between missingness and cure status. Additionally, cure status may be related
 142 to an unmeasured confounder that is related to missingness. This will induce a dependence
 143 between missingness and cure status. We consider a similar LMAR mechanism in our data
 144 application.

145 *Example 3, mixture of generalized linear models:* Suppose our outcome Y is generated

146 from a mixture of K generalized linear models (GLMs). Let C_i be a fully latent mixing
 147 variable indicating which element of the mixture distribution generated the observation for
 148 subject i . Missingness in C_i can be viewed as MCAR with probability 1. If covariate or
 149 outcome missingness is related to C , missingness is LMAR. For example, suppose our data
 150 are collected using K different populations. For example, we may collect data and multiple
 151 different locations and not record the location. The covariate/outcome missingness rates may
 152 vary by population, resulting in LMAR missingness.

153 3. Imputation of missing data

154 In this section, we develop an imputation algorithm for dealing with ignorable and latent
 155 ignorable covariate and outcome missingness. First, we explore imputation under a joint
 156 model for all the variables. We treat the latent variable as part of the missing data, and we
 157 use the form of the joint model to determine how each variable with missing values should
 158 be imputed. In particular, we determine which variables need to be included as predictors for
 159 each imputation model and describe the components of the joint model (e.g. outcome model,
 160 missingness model, covariate model) that are used for imputing each variable. We then use
 161 these results to guide our choice of sequential imputation models when a joint model is not
 162 specified.

163 3.1. Imputation under a joint model

Suppose that the data are directly modeled using a fully-specified joint model as follows:

$$f(\mathbf{D}, L, \mathbf{R}; \nu) = \prod_{i=1}^n f(\mathbf{R}_i | Y_i, \mathbf{X}_i, L_i; \phi) f(Y_i | \mathbf{X}_i, L_i; \theta) f(L_i | \mathbf{X}_i; \omega) f(\mathbf{X}_i; \psi) \quad (1)$$

where $\nu = (\phi, \theta, \omega, \psi)$ is the set of all model parameters. We assume a flat prior for ν such that ϕ , θ , ω , and ψ are all a priori independent (so they are distinct). The factorization (1) is a form of shared parameter model, where the latent variable is related both to missingness and to the distribution for Y_i (Little & Rubin 2002).

We can impute missing values of \mathbf{D} and L by iteratively drawing the missing values from their posterior predictive distributions, $\mathbf{D}^{(\text{mis})} \sim f(\mathbf{D}^{(\text{mis})} | \mathbf{D}^{(\text{obs})}, L, \mathbf{R})$ and $L^{(\text{mis})} \sim f(L^{(\text{mis})} | \mathbf{D}, L^{(\text{obs})}, \mathbf{R})$. This leads to draws from the joint posterior predictive distribution, $f(\mathbf{D}^{(\text{mis})}, L^{(\text{mis})} | \mathbf{D}^{(\text{obs})}, L^{(\text{obs})}, \mathbf{R})$ (Little & Rubin 2002). Define $\rho = (\theta, \omega, \psi)$. In the Supplementary Materials, we formally show the following ignorability properties under a joint model:

Property 1: Under MAR and LMAR, we can ignore $\mathbf{R} = (\mathbf{R}^D, \mathbf{R}^L)$ when imputing \mathbf{D} from $f(\mathbf{D}^{(\text{mis})} | \mathbf{D}^{(\text{obs})}, L, \mathbf{R})$

Property 2: Under MAR (but not under LMAR), we can ignore $\mathbf{R} = (\mathbf{R}^D, \mathbf{R}^L)$ when

imputing L from $f(L^{(\text{mis})}|\mathbf{D}, L^{(\text{obs})}, \mathbf{R})$

Property 3: Suppose that missingness in subset S of $\{\mathbf{D}, L\}$ is MAR. Let \mathbf{R}^S denote the set of missingness indicators for S and \mathbf{R}^{-S} denote the missingness indicators for the remaining variables in $\{\mathbf{D}, L\}$. We can ignore \mathbf{R}^S when imputing L from $f(L^{(\text{mis})}|\mathbf{D}, L^{(\text{obs})}, \mathbf{R})$ provided a parameter distinctness property holds.

Rather than drawing $\mathbf{D}^{(\text{mis})}$ and $L^{(\text{mis})}$ from their posterior predictive distributions directly, we can instead impute each variable with missingness sequentially through a series of univariate imputation steps. Each time we impute a given variable, we treat the most recent imputations of the other variables as observed data. In practice, we specify the full conditional distribution of missing variable V given all other variables (with parameter v) and obtain a draw from the posterior predictive distribution of V by 1) drawing v from its posterior distribution and 2) drawing missing values of V from its full conditional distribution at the drawn v . After iteration, the imputations will approximate draws of $\mathbf{D}^{(\text{mis})}$ and $L^{(\text{mis})}$ from their posterior predictive distributions. Below, we present the form of the imputation distribution (step 1) for imputing different types of variables using the above ignorability properties.

Predictive distribution of the latent variable

Define \mathbf{R}^S and \mathbf{R}^{-S} as in *Property 3* and assume the distinctness property expressed in the Supplementary Materials holds. Then, we can ignore \mathbf{R}^S when imputing L . Using assumptions (1)–(2) and joint model (1) and treating terms that do not depend on L_i as constants, we have

$$f(L_i|\mathbf{X}_i, \mathbf{Y}_i, \mathbf{R}_i^{-S}; \nu) \propto f(\mathbf{R}_i^{-S}|\mathbf{Y}_i^{(\text{obs})}, \mathbf{X}_i^{(\text{obs})}, L_i; \phi^{-S}) \quad (2)$$

$$\times f(\mathbf{Y}_i|\mathbf{X}_i, L_i; \theta)f(L_i|\mathbf{X}_i; \omega)$$

Under MAR, (2) simplifies to

$$f(L_i|\mathbf{X}_i, \mathbf{Y}_i, \mathbf{R}_i^{-S}; \nu) \propto f(\mathbf{Y}_i|\mathbf{X}_i, L_i; \theta)f(L_i|\mathbf{X}_i; \omega) \propto f(L_i|\mathbf{X}_i, \mathbf{Y}_i; \rho)$$

When treated as a function of L_i , expression (2) is proportional to the desired imputation distribution. We will call the distribution known up to proportionality the kernel. The kernel in (2) involves the distribution of \mathbf{R}_i^{-S} under LMAR but not under MAR. In order to impute L_i under LMAR using (2), we need to specify a model for \mathbf{R}_i^{-S} .

In some particular settings (for example, when L_i is binary), we can use (2) to directly derive the full conditional distribution. When L_i is continuous, the distribution may only be known up to a proportionality constant. In this case, we may need to use more advanced techniques to impute L_i using (2). Many methods exist in the literature for drawing from a distribution knowing only the kernel. These include the Metropolis-Hastings algorithm and rejection sampling. For examples of such methods applied in the context of imputation, see Bartlett et al. (2014) and the Supplementary Materials.

Predictive distributions of covariates and outcome

In *Property 1*, we show that we can impute missing values of D ignoring the missingness mechanism under MAR and LMAR. We can similarly impute missing values of individual variables in D from their full conditional distributions without conditioning on R .

We first determine the distribution for imputing missing outcome values. We note that Y may be uni- or multivariate. Suppose that we are imputing the t^{th} element of Y_i , denoted $Y_i^{(t)}$. Let $Y_i^{(-t)}$ represent the terms in Y_i excluding $Y_i^{(t)}$. Using joint model (1), we can write the conditional distribution for imputing $Y_i^{(t)}$ under MAR and LMAR as

$$f(Y_i^{(t)} | Y_i^{(-t)}, X_i, L_i; \rho) \propto f(Y_i, X_i, L_i; \rho) \propto f(Y_i | X_i, L_i; \theta) \quad (3)$$

When $Y_i^{(t)} = Y_i$, the conditional distribution is equal to $f(Y_i | X_i, L_i; \theta)$.

Suppose that we are imputing the t^{th} covariate in X_i , denoted $X_i^{(t)}$. Let $f(X_i^{(t)} | X_i^{(-t)}; \psi)$ be the conditional distribution of $X_i^{(t)}$ given all other variables in X_i . Under joint model (1), we can write the conditional distribution for imputing $X_i^{(t)}$ under MAR and LMAR as

$$f(X_i^{(t)} | X_i^{(-t)}, Y_i, L_i; \rho) \propto f(Y_i | X_i, L_i; \theta) f(L_i | X_i; \omega) f(X_i^{(t)} | X_i^{(-t)}; \psi) \quad (4)$$

164 Expressions in (3) and (4) provide the kernels of the distributions we can use to impute
 165 outcomes and covariates in D . The kernels take the same form under MAR and LMAR, and
 166 they do not involve a model R directly. As with the latent variable imputation, distributions
 167 (3) and (4) may only be known up to proportionality, requiring more advanced statistical
 168 methods to draw imputations.

3.2. Relaxing the modeling assumptions

170 The imputation distributions derived previously were developed assuming a fully-
 171 specified joint model as in (1), but often we will not want to specify such a joint model
 172 in practice. Specification of the joint model may be particularly difficult or restrictive in
 173 the setting with missingness in covariates of different types. Rather than specifying an
 174 explicit joint distribution, we propose imputing missing values using (2)–(4) to *inform* the
 175 distributions we use in practice either used an SMC imputation-type approach or a chained
 176 equations-type approach. In practice, the resulting conditional distributions for either method
 177 may not together correspond to a valid joint distribution for all the variables.

178 Following SMC imputation proposed in Bartlett et al. (2014), we may specify only
 179 the modeling components needed for each imputation. Imputation of missing values of Y
 180 using (3) requires a model for $Y | X, L$, and imputation of missing L using (2) further
 181 requires a model for $L | X$ and, under LMAR, a model for missingness. Imputation of missing
 182 covariate $X_i^{(t)}$ using (4) requires us to specify $f(X_i^{(t)} | X_i^{(-t)}; \psi)$. This approach involves
 183 incorporating the outcome model structure (in this case, models for $Y | X, L$ and $L | X$

184 (and possibly missingness)) to do the imputation, but we can avoid specifying $f(\mathbf{X}|\psi)$ by
185 instead specifying $f(X_i^{(t)}|\mathbf{X}_i^{(-t)}; \psi)$ for covariates with missingness using simple regression
186 models. An additional appealing feature of SMC imputation is that it has additional flexibility
187 over joint modeling in terms of imputation model specification, and it also involves imputing
188 with a model that is congenial with the final analysis model. By uncongeniality, we mean
189 that the imputation model and the final data analysis model are incompatible (Meng 1994).
190 Since SMC imputation directly uses the final analysis model in the imputation procedure, it
191 is attractive from a congeniality point of view.

192 Imputation using SMC imputation may be difficult when distributions are known only
193 up to proportionality. An alternative, simpler chained equations imputation approach involves
194 using (2)–(4) solely to define what predictors are needed for each imputation. Specifically,
195 (2) suggests that some function of \mathbf{Y} , \mathbf{X} , and possibly \mathbf{R} (under LMAR) should be used
196 as predictors when imputing L . The expression in (3) suggests we need \mathbf{X} , L , and $\mathbf{Y}^{(-t)}$
197 when imputing $Y^{(t)}$, and (4) suggests we need \mathbf{Y} , L , and $\mathbf{X}^{(-t)}$ when imputing $X^{(t)}$. We
198 can then perform imputation (by specifying a regression model for imputing each variable)
199 using standard software for chained equations imputation (Raghunathan 2001; Van Buuren
200 et al. 2006). Such an approach would allow for increased flexibility in model specification
201 (for example, by including quadratic or interaction terms) while still allowing L to be used
202 in the imputation. We may view the *working* model actually used for imputation as an
203 approximation to the true conditional model as in (2)–(4). We recommend imputing L using
204 the kernel form in (2) if possible, and our proposed algorithm will use this method.

205 The imputation distributions, therefore, can be easily modified to accommodate settings
206 without a joint distribution. Indeed, Gelman (2004) argues that “having a joint distribution
207 in the imputation is less important than incorporating information from other variables and
208 unique features of the dataset (e.g. zero/nonzero features in income components, bounds, skip
209 patterns, nonlinearity, interactions).” The SMC imputation and chained equations approaches
210 allow these unique features of the data to be directly incorporated in the imputation models.
211 This approach allows for greater flexibility in the specification of the imputation distributions
212 compared to joint modeling.

213 When we replace the true predictive distributions under a joint model with a *working*
214 imputation model, the corresponding parameters may no longer correspond to the parameters
215 under the joint model. In the next section, we will describe how we can perform imputation
216 using these *working* imputation distributions in practice.

217 **3.3. Sequential imputation method**

We propose a sequential imputation method in which each variable with missingness is imputed one-by-one in an iterative algorithm. At each step, we obtain a single imputation of a variable V from the *working* posterior predictive distribution of V (with parameter v) by 1) drawing v from its posterior distribution and 2) drawing missing values of V from its full conditional distribution at the drawn v .

Just before the imputation step for each variable, we draw the parameters necessary for the imputation from a current estimate of the parameters' *working* posterior predictive distribution. Let $X^{(t)}$ and $Y^{(t)}$ be defined as before. Let \tilde{f} indicate a working distribution (usually a regression model) *used for imputation* that may not necessarily be equal to the distribution under a joint model. In the imputation step for each variable, we treat the most recent imputations of the other variables as observed. At each iteration, we draw missing data and parameters using one of the two following algorithms. An in-depth description and motivation for our proposed parameter draw methods is included in the Supplementary Materials. In describing how to perform the parameter draws, we assume flat priors for all parameters.

SMC imputation algorithm:

$$\begin{aligned} \text{Impute } L : \quad & [\theta, \omega] \sim f(\theta, \omega | \mathbf{D}, L^{(\text{obs})}) \quad \phi^{-S} \sim f(\phi^{-S} | \mathbf{D}, L, \mathbf{R}^{-S}) \quad (5) \\ & L_i^{(\text{mis})} \propto f(\mathbf{R}_i^{-S} | \mathbf{Y}_i^{(\text{obs})}, \mathbf{X}_i^{(\text{obs})}, L_i; \phi^{-S}) f(\mathbf{Y}_i | \mathbf{X}_i, L_i; \theta) f(L_i | \mathbf{X}_i; \omega) \\ \text{Impute } Y^{(t)} : \quad & \theta \sim f(\theta | \mathbf{D}, L) \quad Y_i^{(t, \text{mis})} \propto f(\mathbf{Y}_i | \mathbf{X}_i, L_i; \theta) \\ \text{Impute } X^{(t)} : \quad & [\theta, \omega] \sim f(\theta, \omega | \mathbf{D}, L) \quad \tilde{\psi}_t \sim \tilde{f}(\tilde{\psi}_t | \mathbf{X}) \\ & X_i^{(t, \text{mis})} \propto f(\mathbf{Y}_i | \mathbf{X}_i, L_i; \theta) f(L_i | \mathbf{X}_i; \omega) \tilde{f}(X_i^{(t)} | \mathbf{X}_i^{(-t)}; \tilde{\psi}_t) \end{aligned}$$

When imputing L , we can obtain a (approximate) draw $[\theta, \omega]$ by fitting our outcome model to a bootstrap sample of $[\mathbf{D}, L^{(\text{obs})}]$ using methods that treat L as latent. For example, suppose our outcome model is a linear mixed model. We can obtain this draw by fitting a linear mixed model to a bootstrap sample of the data. We can obtain a draw of ϕ^{-S} by fitting a model for $\mathbf{R}^{(-S)}$ to a bootstrap sample of the most recent imputed data (including imputed L). When imputing $Y^{(t)}$, we can obtain a draw of θ by fitting a model for $\mathbf{Y} | \mathbf{X}, L$ using a bootstrap sample of the most recently imputed data. When imputing $X^{(t)}$, we can obtain a draw of $\tilde{\psi}_t$ by fitting the corresponding model to a bootstrap sample of \mathbf{X} . In the Supplementary Materials, we provide details regarding how we can perform each of the imputation steps for the examples discussed Section 2.

Chained equations imputation algorithm:

$$\begin{aligned} \text{Impute } L : \quad & [\theta, \omega] \sim f(\theta, \omega | \mathbf{D}, L^{(\text{obs})}) \quad \phi^{-S} \sim f(\phi^{-S} | \mathbf{D}, L, \mathbf{R}^{-S}) \quad (6) \\ & L_i^{(\text{mis})} \propto f(\mathbf{R}_i^{-S} | \mathbf{Y}_i^{(\text{obs})}, \mathbf{X}_i^{(\text{obs})}, L_i; \phi^{-S}) f(\mathbf{Y}_i | \mathbf{X}_i, L_i; \theta) f(L_i | \mathbf{X}_i; \omega) \end{aligned}$$

$$\text{Impute } Y^{(t)} : \quad \tilde{\theta}_t \sim \tilde{f}(\tilde{\theta}_t | \mathbf{D}, L) \quad Y_i^{(t, \text{mis})} \propto \tilde{f}(\mathbf{Y}_i | \mathbf{X}_i, L_i; \tilde{\theta}_t)$$

$$\text{Impute } X^{(t)} : \quad \tilde{\psi}_t \sim \tilde{f}(\tilde{\psi}_t | \mathbf{X}, \mathbf{Y}, L) \quad X_i^{(t, \text{mis})} \propto \tilde{f}(X_i^{(t)} | \mathbf{X}_i^{(-t)}, \mathbf{Y}_i, L_i; \tilde{\psi}_t)$$

218 We can impute L as before. When imputing \mathbf{Y} and \mathbf{X} , we draw the parameters of interest by
219 fitting corresponding models to bootstrap versions of the most recently imputed data.

220 Iteration of the above algorithms is required even if we have only one variable in \mathbf{D}
221 with missing values. We can ignore the imputation steps for each fully observed variable. We
222 initialize the missing values for each variable in \mathbf{D} by drawing from the observed values with
223 equal probability. We can initialize missing L using the distribution $f(L | \mathbf{X})$ obtained from a
224 fit to the data with fully observed \mathbf{D} (using methods that treat L as latent).

225 For both of the above algorithms, we assume that missingness is LMAR. Suppose
226 instead that we know that missingness is MAR. We can apply the above algorithms but using
227 that $f(L_i | \mathbf{X}_i, \mathbf{Y}_i, \mathbf{R}_i^{-S}; \nu) \propto f(\mathbf{Y}_i | \mathbf{X}_i, L_i; \theta) f(L_i | \mathbf{X}_i; \omega)$ instead to impute L_i and without
228 drawing values for ϕ^{-S} . In this way, the above development also gives us an imputation
229 algorithm for dealing with missing data for models with latent variables under MAR.

230 We perform the imputation procedure m times to construct m filled-in datasets (with m
231 different initializations). We then estimate ρ by fitting our model of interest to each of the
232 imputed datasets *ignoring* \mathbf{R} . When we perform this analysis, we may choose to use only
233 imputed \mathbf{D} , only imputed L , or both. We can then use Rubin's combining rules to obtain a
234 single set of parameter estimates and errors from which we make the desired inference (Rubin
235 1987).

236 It is important to consider the impact of ignoring \mathbf{R} for each one of these final analysis
237 strategies. Harel & Schafer (2009) shows that when imputed L is included in the final
238 analysis, we can ignore \mathbf{R} . This result holds true under MAR and LMAR and whether or
239 not imputed \mathbf{D} is included in the final analysis. In *Properties 4–5* in the Supplementary
240 Materials, we explore the ignorability of \mathbf{R} when performing a final analysis using only the
241 imputed \mathbf{D} . We show that \mathbf{R} is ignorable under MAR and that such an analysis ignoring
242 \mathbf{R} under LMAR is valid but not fully efficient. Even with a potential loss of efficiency, we
243 may still choose to perform our final analysis ignoring the imputed L as this may provide
244 improved numerical stability of the algorithm and more robustness to misspecification of the
245 imputation models, and we may have little loss of efficiency in practice.

246

4. Identifiability and convergence

247 As with all missing data methods involving MNAR assumptions, one big concern is how
248 to model the missingness mechanism (which will be unverifiable) (Molenberghs, Beunckens
249 & Sotito 2008). Another concern is whether the resulting model parameters are identifiable
250 (Little 1995). Even when the parameters are technically identified, weak identifiability may
251 also have implications on the numerical convergence of the proposed imputation algorithm.
252 In this section, we briefly comment on some identifiability- and convergence-related issues
253 that arise in the application of the proposed imputation algorithm.

4.1. Modeling the missingness mechanism

254 Under LMAR, we must specify a model for R^D (or some subset R^{-S} following
255 *Property 3*). While we can conceive of many different models for R^D , the model parameter
256 $\nu = (\phi, \rho)$ may not always be identifiable. In some specific settings (e.g. Wu & Carroll
257 1988; Miao, Ding & Geng 2016), identifiability has been demonstrated analytically, but
258 exploring identifiability can be difficult in general. Wang, Shao & kwang Kim (2014) relates
259 identifiability to the existence of instrumental variables. We explore identifiability in several
260 particular modeling settings in the Supplementary Materials. In this paper, we will not attempt
261 to prove identifiability properties for general LMAR mechanisms. Instead, we will provide
262 some guidance for applying the proposed methods in the presence of possible identifiability
263 issues.
264

265 In order to reduce the potential for identifiability issues, many authors (e.g. Little
266 2009b) recommend that we avoid overburdening the missingness model with extra variables.
267 However, if we leave out variables that should be in the model, we may introduce bias in
268 estimating the parameter of interest as seen in our simulations. In our simulations, imputation
269 with LMAR *outcome* missingness tended to be more susceptible to identifiability problems
270 than *covariate* missingness. Some authors recommend performing a sensitivity analysis in
271 which we specify the form of the missingness model and carry out analysis using fixed
272 values for ϕ^D (e.g. Little 2009b). We can then perform the desired analysis many times
273 using different values for ϕ^D . This approach allows us to directly study the impact of ϕ^D
274 on inference and avoid estimating the parameters of the missingness model. Additionally,
275 MNAR missingness mechanisms are known to be particularly sensitive to assumptions about
276 the structure of the missingness mechanism, and we could perform a sensitivity analysis using
277 different missingness model structures (Little 1995). We take this approach in our head and
278 neck cancer example. These sensitivity approaches allow the proposed methods to be applied
279 while avoiding some of the pitfalls of MNAR settings.

280 4.2. A note on convergence

281 When the conditional models used for imputation correspond to a well-defined joint
282 distribution with identified parameters, our imputation algorithm is expected to converge to
283 draws of the joint posterior distribution for the missing data (Liu et al. 2013; Hughes et al.
284 2014; Bartlett et al. 2014). When the imputation models do not correspond to a valid joint
285 distribution (called incompatibility), our imputation method is not guaranteed to converge.
286 However, several works have demonstrated that we can often still obtain good inference under
287 incompatible imputation models (Van Buuren et al. 2006; Van Buuren 2007).

288 We will not attempt to prove convergence or consistency properties for the proposed
289 algorithm beyond what exists in the chained equations and SMC imputation literature.
290 Instead, we will use simulation and some minor analytical exploration to identify settings that
291 may be particularly susceptible to concerns about convergence. In particular, identifiability
292 concerns related to the missingness model have implications on the convergence of the
293 algorithm. When parameters are not identifiable (in terms of the observed data likelihood
294 having a unique maximiser), we may not expect the imputation algorithm to converge
295 properly. Even when the parameters are all identifiable, we may run into numerical issues
296 if the observed data likelihood is nearly flat. These issues appear to be of greater concern
297 for outcome missingness. We note that in our experience, even when we have numerical
298 convergence issues for ϕ (missingness model) and ω (model for $L|\mathbf{X}$), the draws for θ (model
299 for $\mathbf{Y}|\mathbf{X}, L$) may still converge to reasonable values. In such cases, the identifiability-related
300 numerical problems may not strongly impact the draws for the primary parameter of interest,
301 θ . It is important to monitor the convergence of all model parameters, and we may still be able
302 to make inference about θ in the presence of some mild identifiability-related convergence
303 issues for ϕ . We explore identifiability-related convergence issues further in Section 5 and
304 the Supplementary Materials.

305

5. Simulation study

306 In this section, we present a simulation study with four parts. In the first three parts,
307 we evaluated how the proposed algorithm performs in terms of bias, empirical variance,
308 and coverage for outcome model parameters in linear mixed models (Simulation 1), CPH
309 cure models (Simulation 2), and normal mixture models (Simulation 3). In Simulation 4,
310 we explored convergence under a variety of modeling scenarios. Details can be found in
311 the Supplementary Materials. A fifth/sixth set of simulations included in the Supplementary
312 Materials (1) explored the impact of including or ignoring the imputed L in the final analysis
313 and (2) assessed the impact of ignoring latent-dependent missingness in the CPH cure model

314 setting in more detail, but we will not discuss these simulations further here. Unless otherwise
315 specified, imputations were drawn using the SMC imputation method rather than the chained
316 equations method.

317 5.1. Simulations 1–3: exploring bias, variance, and coverage

318 In Simulation 1, we simulated 1500 datasets with 500 subjects each under a linear
319 mixed model with a random intercept. Each dataset contained two binary covariates, X_1
320 and X_2 . We drew random intercept $b_i \sim N(0, 1)$ for each individual and generated \mathbf{Y} for
321 each individual at each of three time-points using the model $Y_{ij} = \beta_{\text{Intercept}} + \beta_{X_1} X_{i1} +$
322 $\beta_{X_2} X_{i2} + \beta_{\text{Time}} \text{Time}_{ij} + b_i + e_{ij}$ for $j = 1, 2, 3$ with independent $N(0, 1)$ errors, $\beta_{\text{Intercept}} =$
323 $\beta_{X_1} = \beta_{X_2} = 0.5$, and $\beta_{\text{Time}} = 0.2$. Additional simulation details are available in the
324 Supplementary Materials. We imposed $\sim 50\%$ missingness in X_2 under four different
325 mechanisms: (A) MAR dependent on baseline outcome value Y_1 , (B) LMAR with moderate
326 dependence between missingness and the random intercept, (C) LMAR with strong
327 dependence on the random intercept, and (D) LMAR with dependence on the random
328 intercept and the baseline outcome value Y_1 .

329 We then imputed values of X_2 and b using methods discussed in this paper under various
330 working models. When we imputed under a LMAR working model, we modeled the covariate
331 missingness indicator R_i^D using a logistic regression with different functions of b , X_1 , and \mathbf{Y}
332 as predictors. When we assumed MAR, we imputed L ignoring the missingness mechanism.
333 For each simulated dataset, we created 10 imputed datasets. We then fit a linear mixed model
334 to each of the imputed datasets and use Rubin's rules to obtain a single set of parameter
335 estimates and their corresponding variances for each simulation. We then computed the bias,
336 empirical variance, and coverage rates across the 1500 simulations. To improve readability,
337 we list coverage rates in Table S1 in the Supplementary Materials. We note that the APPROX
338 simulations take a chained equations imputation approach in which we impute X_2 conditional
339 on X_1 , L and \mathbf{Y} using a logistic regression form, so the imputation distributions for X_2 and
340 L in this case do not correspond to a coherent joint distribution.

341 Table 1 shows the results for Simulation 1. Simulations 2–3 included in the
342 Supplementary Materials are similar. Simulations 1–3 generally demonstrated that the
343 proposed imputation approach can result in essentially unbiased estimates of outcome model
344 parameters with nominal (or perhaps slightly conservative) coverage when the working
345 missingness model contains the true model. We demonstrated that complete case analysis
346 and imputation assuming MAR can sometimes result in biased parameter estimates when
347 missingness is at least moderately associated with the latent variable. The bias created by
348 incorrectly assuming MAR appears larger when L is a fully latent compared to partially

Table 1. Linear mixed model estimates using proposed imputation methods.

Method	Contains Truth#	Parameters			Time Bias (Var)
		Intercept Bias (Var) †	X_1 Bias (Var)	X_2 Bias (Var)	
Full Data	-	0 (1.2)	0 (1.0)	0 (1.1)	0 (0.10)
Missingness in X_2 dependent on Y_1 and independent of b (Mechanism A)					
Complete Case	-	-78 (2.0)	-9 (1.8)	-9 (1.9)	19 (0.20)
MAR Imputation	Yes	0 (1.8)	0 (1.1)	0 (2.8)	0 (0.10)
LMAR Imputation: b^*	No	6 (1.4)	2 (1.1)	-9 (1.9)	0 (0.10)
LMAR Imputation: $b, X_1, b \times X_1$	No	6 (1.4)	1 (1.1)	-9 (2.0)	0 (0.10)
LMAR Imputation: b, Y_1	Yes	0 (1.8)	0 (1.1)	0 (2.8)	0 (0.10)
LMAR Imputation: $\mathbb{I}(b > 0), Y_1$	Yes	0 (1.9)	0 (1.1)	0 (2.8)	0 (0.10)
LMAR Imputation: $b, X_1, b \times X_1, Y_1$	Yes	0 (1.9)	0 (1.1)	0 (2.8)	0 (0.10)
LMAR Imputation: b, Y_2	No	7 (1.4)	2 (1.1)	-11 (1.8)	0 (0.10)
MAR APPROX Imputation	Yes	-1 (1.9)	0 (1.1)	0 (3.0)	0 (0.10)
LMAR APPROX Imputation: b	No	5 (1.5)	1 (1.1)	-8 (2.1)	0 (0.10)
Missingness in X_2 moderately dependent on b (Mechanism B)					
Complete Case	-	-24 (2.4)	0 (2.1)	0 (2.2)	0 (0.19)
MAR Imputation	No	-2 (1.7)	0 (1.1)	2 (2.4)	0 (0.10)
LMAR Imputation: b	Yes	0 (1.6)	0 (1.1)	0 (2.2)	0 (0.10)
LMAR Imputation: $b, X_1, b \times X_1$	Yes	0 (1.6)	0 (1.1)	0 (2.2)	0 (0.10)
LMAR Imputation: b, Y_1	Yes	0 (1.6)	0 (1.1)	0 (2.2)	0 (0.10)
LMAR Imputation: $\mathbb{I}(b > 0), Y_1$	No	0 (1.6)	0 (1.1)	0 (2.2)	0 (0.10)
LMAR Imputation: $b, X_1, b \times X_1, Y_1$	Yes	0 (1.6)	0 (1.1)	0 (2.2)	0 (0.10)
MAR APPROX Imputation	No	-3 (1.7)	0 (1.1)	3 (2.4)	0 (0.10)
LMAR APPROX Imputation: b	Yes	0 (1.6)	0 (1.1)	0 (2.2)	0 (0.10)
Missingness in X_2 strongly dependent on b (Mechanism C)					
Complete Case	-	-48 (2.5)	0 (1.8)	0 (2.0)	0 (0.22)
MAR Imputation	No	-7 (2.0)	0 (1.1)	8 (2.8)	0 (0.10)
LMAR Imputation: b	Yes	0 (1.5)	0 (1.1)	0 (2.0)	0 (0.10)
LMAR Imputation: $b, X_1, b \times X_1$	Yes	0 (1.5)	0 (1.1)	0 (2.0)	0 (0.10)
LMAR Imputation: b, Y_1	Yes	0 (1.6)	0 (1.1)	0 (2.1)	0 (0.10)
LMAR Imputation: $\mathbb{I}(b > 0), Y_1$	No	0 (1.6)	0 (1.1)	0 (2.1)	0 (0.10)
LMAR Imputation: $b, X_1, b \times X_1, Y_1$	Yes	0 (1.5)	0 (1.1)	0 (2.1)	0 (0.10)
MAR APPROX Imputation	No	-8 (2.0)	0 (1.1)	9 (2.8)	0 (0.10)
LMAR APPROX Imputation: b	Yes	0 (1.5)	0 (1.1)	0 (2.1)	0 (0.10)
Missingness in X_2 dependent on b and Y_1 (Mechanism D)					
Complete Case	-	-73 (2.0)	-5 (1.6)	-5 (1.6)	8 (0.21)
MAR Imputation	No	-8 (2.0)	-1 (1.1)	10 (2.8)	0 (0.10)
LMAR Imputation: b	No	3 (1.4)	0 (1.1)	-5 (1.7)	0 (0.10)
LMAR Imputation: $b, X_1, b \times X_1$	No	3 (1.4)	0 (1.1)	-5 (1.6)	0 (0.10)
LMAR Imputation: b, Y_1	Yes	0 (1.5)	0 (1.1)	0 (2.0)	0 (0.10)
LMAR Imputation: $\mathbb{I}(b > 0), Y_1$	No	0 (1.6)	0 (1.1)	0 (2.0)	0 (0.10)
LMAR Imputation: $b, X_1, b \times X_1, Y_1$	Yes	0 (1.6)	0 (1.1)	0 (2.0)	0 (0.10)
LMAR Imputation: b, Y_2	No	3 (1.4)	0 (1.1)	-6 (1.7)	0 (0.10)
MAR APPROX Imputation	No	-9 (2.1)	-1 (1.1)	11 (2.9)	0 (0.10)
LMAR APPROX Imputation: b	No	3 (1.4)	0 (1.1)	-4 (1.7)	0 (0.10)

*Variables after colon represent linear predictors in working model for R_i^D

† All values in table multiplied by 100. Var indicates empirical variance.

Indicates whether working missingness model contains true model.

APPROX: Imputation of X_2 uses a logistic regression with predictors X_1, b, Y_1, Y_2, Y_3 (instead of kernel (4))

Complete Case: Analysis excluding subjects with missing X_2

349 latent. Imputation under LMAR assumptions can correct this bias when we use a working
 350 model containing the truth and can sometimes reduce the bias compared to imputation

351 assuming MAR when the working model is *close* to the truth. When missingness was truly
352 MAR, simulations suggested that imputation under a LMAR model that did not contain
353 the true model can create bias. However, simulations showed that LMAR methods with
354 working models containing the true MAR model can still be applied with little or no loss
355 of efficiency (when the LMAR model is well-identified) in this setting. Very complicated
356 working missingness models can sometimes result in a loss of efficiency, but this loss was
357 generally small.

358 **5.2. Simulation 4: exploring identifiability and convergence**

359 Even if the model parameters are technically identifiable, one additional concern
360 is that the likelihood surface near the maximizer may be nearly flat, which can lead
361 to issues with model fitting and convergence of the imputation algorithm. In order to
362 better understand possible identifiability-related convergence issues, we performed a set of
363 simulations evaluating convergence of the imputation algorithm under a variety of modeling
364 scenarios.

365 We simulated data under a linear mixed model, cure model, and mixture of normals
366 respectively as described in the Supplementary Materials. We imposed $\sim 50\%$ covariate or
367 outcome missingness (but not both) using MAR or LMAR mechanisms. For each simulated
368 dataset, we performed imputation using a correct working missingness model structure. For
369 each outcome model parameter, we evaluated parameter convergence using the Gelman-
370 Rubin convergence statistic (Gelman & Rubin 1992).

371 Simulations demonstrated good convergence properties under LMAR/MAR covariate
372 and MAR outcome missingness. Under LMAR outcome missingness, the outcome model
373 parameters appeared to converge, but missingness model parameter (in particular, for the
374 latent variable) showed some evidence of convergence problems. The drawn values of the
375 outcome model parameters appeared reasonable (with small or no bias) even when the
376 missingness model parameters do not converge, but this may not be true in general. When
377 we fixed the value of the parameter related to the latent variable in the missingness model,
378 we saw a large improvement in the convergence properties of the imputation algorithm.

379 **6. Application to head and neck cancer data**

380 We consider data from a cohort study of $N=1226$ patients treated for head and neck
381 squamous cell carcinoma (HNSCC). This study was conducted by the University of Michigan
382 Head and Neck Specialized Program of Research Excellence (SPORE) and followed patients
383 who were treated at the University of Michigan Cancer Center for HNSCC between Nov.
384 2003 and July 2013. Details about this study can be found in Duffy et al. (2008) and

385 Peterson et al. (2016). After treatment, patients were followed for recurrence. Covariate
 386 information was also collected at baseline. We are interested in studying the association
 387 between covariates and the time to HNSCC recurrence after treatment. For head and neck
 388 cancer, it has been established that some patients can be cured by treatment, and these patients
 389 will never experience a recurrence (Taylor 1995). We model the time to HNSCC recurrence
 390 using a Cox proportional hazards cure model.

391 HPV status was unavailable for 55.8% of the subjects, and small amounts of missingness
 392 was present in other study variables. Beesley et al. (2016) explores imputation-based
 393 approaches for dealing with the missing covariate data for this study. The analysis in Beesley
 394 et al. (2016), however, assumes that covariate missingness is MAR and does not depend on
 395 underlying cure status. An induced LMAR association between missingness in HPV status
 396 and cure status (denoted G) could occur if HPV missingness is related to an unmeasured
 397 variable that is also related to the cure probability. In this study, the HPV missingness rate is
 398 related to calendar time (in a nonlinear way), and calendar time may be associated with the
 399 cure rate. Additionally, a more experienced doctor may be more likely to recommend HPV
 400 testing and to have cured patients. We cannot control for this effect due to a lack of detailed
 401 information about treating doctors for each patient. Given the large rate of missingness in
 402 HPV status, we are interested to explore the robustness of model inference to our assumptions
 403 about the missingness mechanism.

404 We are interested in comparing model inference assuming MAR to inference obtained
 405 when missingness in HPV is assumed to be LMAR. We assume missingness in all other
 406 variables is MAR. We consider three working assumptions for HPV status missingness: (A)
 407 MAR, (B) missingness dependent only on cure status, and (C) missingness dependent on cure
 408 status, age at diagnosis, cancer site, and (grouped) enrollment year. Assumptions (B) and (C)
 409 are modeled using logistic regression.

410 We apply our proposed SMC imputation method to impute the missing data. In this
 411 setting, G is the partially latent cure status, Y is the censored event time data (time and
 412 indicator), and \mathbf{X} is the set of covariates. Here, the model $Y|G = 1, \mathbf{X}$ is a Cox regression
 413 and the model for $G|\mathbf{X}$ is a logistic regression. We impute cure status G using (2). As
 414 suggested in Beesley et al. (2016), we impute missing values of each p th covariate $X^{(p)}$
 415 using a standard regression model with $\mathbf{X}^{(-p)}$, G , $G \times \hat{H}_0(T)$, and $G \times \hat{H}_0(T) \times \mathbf{X}^{(-p)}$
 416 as predictors. Here, $\hat{H}_0(T)$ is an estimate of the cumulative baseline hazard of having an event
 417 in the non-cured group. As in Beesley et al. (2016), we will draw values for the regression
 418 model's parameter without conditioning on the imputed $X^{(p)}$ (as is done in usual chained
 419 equations). Variables included in $X^{(p)}$ for the imputation include log-transformed number
 420 of sexual partners, PNI, comorbidities, smoking habits, alcohol use, age, cancer site, cancer
 421 stage, gender, and enrollment period (2003-2008, 2009-2011, 2012-2013).

422 Table 2 presents the cure model fit under different assumptions about the missingness
423 mechanism. We see that the fits are nearly identical. The largest difference between the fits
424 is in the estimate for the HPV effect on the time to recurrence in the non-cured group. We
425 estimate a slightly stronger effect of HPV status under LMAR assumptions than under MAR
426 assumptions, and the strongest effect is estimated when missingness is assumed to be LMAR
427 dependent on G and other covariates. However, the HPV effect is not significant in any of the
428 fits. We cannot make conclusions about the correct missingness mechanism, but regardless
429 of the true missingness model, the CPH cure model inference appears to be very robust to
430 different specifications of the working missingness model.

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Table 2. Cure model fits to head and neck data under different missing model assumptions.

Missingness model:	MAR*	LMAR1*	LMAR2*
	Logistic regression, odds ratio (95% CI)		
Age/10	1.14 (1.00, 1.31) [†]	1.14 (0.99, 1.32)	1.14 (1.00, 1.30) [†]
Cancer Stage			
I/Cis (ref)			
II	1.25 (0.57, 2.74)	1.25 (0.54, 2.89)	1.25 (0.57, 2.74)
III	2.36 (1.18, 4.72) [†]	2.32 (1.16, 4.61) [†]	2.33 (1.18, 4.63) [†]
IV	3.32 (1.74, 6.33) [†]	3.30 (1.74, 6.26) [†]	3.30 (1.80, 6.03) [†]
Cigarette Use			
Never (ref)			
Current	1.46 (0.97, 2.18)	1.47 (0.96, 2.24)	1.46 (0.98, 2.16)
Former	1.27 (0.85, 1.90)	1.28 (0.85, 1.93)	1.28 (0.84, 1.95)
HPV Status			
Negative (ref)			
Positive	0.34 (0.19, 0.58) [†]	0.35 (0.19, 0.64) [†]	0.34 (0.20, 0.56) [†]
Comorbidities			
None (ref)			
Mild	1.14 (0.77, 1.69)	1.15 (0.79, 1.68)	1.15 (0.79, 1.68)
Moderate	1.66 (1.08, 2.56) [†]	1.66 (1.07, 2.58) [†]	1.66 (1.07, 2.55) [†]
Severe	1.94 (1.10, 3.43) [†]	1.94 (1.08, 3.48) [†]	1.97 (1.08, 3.57) [†]
Cancer Site			
Larynx (ref)			
Hypopharynx	1.93 (0.88, 4.22)	1.93 (0.86, 4.30)	1.99 (0.91, 4.33)
Oral Cavity	1.24 (0.81, 1.90)	1.24 (0.81, 1.89)	1.24 (0.81, 1.90)
Oropharynx	1.68 (0.94, 3.02)	1.64 (0.90, 2.97)	1.68 (0.95, 2.96)
	Cox proportional hazards, hazard ratio (95% CI)		
Age/10	1.08 (0.98, 1.19)	1.08 (0.98, 1.18)	1.08 (0.98, 1.19)
Cancer Stage			
I/Cis (ref)			
II	1.67 (0.70, 3.95)	1.62 (0.69, 3.82)	1.61 (0.66, 3.88)
III	2.42 (1.22, 4.79) [†]	2.40 (1.24, 4.66) [†]	2.42 (1.21, 4.84) [†]
IV	2.76 (1.48, 5.16) [†]	2.76 (1.47, 5.18) [†]	2.77 (1.45, 5.29) [†]
Cigarette Use			
Never (ref)			
Current	0.98 (0.70, 1.38)	0.97 (0.70, 1.35)	0.97 (0.70, 1.33)
Former	0.94 (0.66, 1.33)	0.94 (0.67, 1.32)	0.94 (0.67, 1.32)
HPV Status			
Negative (ref)			
Positive	0.91 (0.55, 1.48)	0.85 (0.51, 1.40)	0.81 (0.52, 1.28)
Comorbidities			
None (ref)			
Mild	0.89 (0.65, 1.23)	0.89 (0.65, 1.22)	0.89 (0.65, 1.22)
Moderate	1.10 (0.75, 1.61)	1.09 (0.73, 1.61)	1.09 (0.75, 1.58)
Severe	1.07 (0.63, 1.80)	1.06 (0.64, 1.74)	1.06 (0.63, 1.80)
Cancer Site			
Larynx (ref)			
Hypopharynx	1.43 (0.77, 2.67)	1.42 (0.78, 2.60)	1.42 (0.78, 2.58)
Oral Cavity	1.33 (0.90, 1.97)	1.32 (0.92, 1.90)	1.32 (0.92, 1.89)
Oropharynx	1.02 (0.62, 1.68)	1.06 (0.66, 1.70)	1.09 (0.69, 1.72)

*Corresponds to working model for Prob(HPV missing). LMAR1 includes G only. LMAR2 includes G and covariates includes main effects for cancer site, age, and enrollment year group.

[†] Significant at $p = 0.05$

431

7. Discussion

432 We present a novel sequential imputation algorithm that can handle both missing at
433 random (MAR) and latent missing at random (LMAR) covariate and outcome missingness
434 for models with latent or partially latent variables. Unlike existing methods, the proposed
435 approach does not require specification of the full joint distribution of the complete data. The
436 proposed algorithm imputes the latent variable as part of the missing data, allowing the latent
437 variable to be directly used to help impute the other variables.

438 We first consider the more restrictive setting where the joint model is fully specified. We
439 use results under a joint model to *inform the structure* of the imputation distributions and the
440 method for drawing parameters in the proposed algorithm *without requiring specification of*
441 *the joint model*. The proposed approach is very flexible and can accommodate either a chained
442 equations-type approach to imputation or a substantive model compatible (SMC) imputation
443 approach that is more strongly informed by the outcome model.

444 Several authors have previously proposed approaches for handling latent ignorable
445 missingness in specific joint modeling settings (Jung 2007; Yang, Lu & Shoptaw 2008;
446 Lu, Zhang & Lubke 2011), and Harel (2003) proposes a non-iterative imputation approach
447 for dealing with general latent-dependent missingness under a joint model. These methods,
448 however, all rely on the prior specification of a joint model for the complete data. In practice,
449 however, such a joint model may be difficult or too restrictive. Therefore, there is a need
450 to consider methods for imputing variables under latent ignorability that incorporate less
451 restrictive assumptions about the joint model.

452 Therefore, we consider two departures for joint model-based imputation: SMC
453 imputation and chained equations imputation. It is worth noting the distinction between the
454 SMC imputation method and joint modeling. The primary distinction in our setting is in the
455 specification (or lack thereof) of the joint distribution for \mathbf{X} . The imputation distributions
456 for L and \mathbf{Y} are similar to the distributions obtained under a joint model. However, the
457 ability to avoid specifying the joint distribution of the covariates provides a large advantage
458 in terms of modeling—the covariate distribution is the hard one to specify. We often have
459 many covariates of different types and with different restrictions, and specification of a valid
460 joint distribution can be very challenging. Therefore, replacing the need to specify the joint
461 distribution of \mathbf{X} with specification of the conditional distribution for only the variables
462 with missingness does present a clear advantage over joint modeling in many settings, and
463 the statistical properties of the resulting algorithm can be quite different. This motivates a
464 separate treatment of SMC imputation from joint modeling. The proposed chained equations
465 imputation method, where only the latest variable is imputed using assumptions about the
466 outcome model, takes an additional step away from joint modeling; the other variables are

467 imputed using regression models specified separately for each variable with missingness. It
468 is worth noting that, while the proposed methods can be applied under MAR or under LMAR
469 missingness assumptions, the primary novelty lies in handling imputation under LMAR. We
470 are not aware of any literature developing SMC imputation or chained equations imputation
471 methods to handle latent ignorable missingness for a *general class* of latent variable models.

472 Simulations demonstrate that the proposed methods can result in good performance (in
473 terms of bias, coverage, etc) under a variety of modeling scenarios as long as the working
474 missingness model contains the true model. In practice, we will not know the true missingness
475 model. Preliminary simulations in the LMAR setting suggest that this may not always be a
476 problem as long as we posit a working missingness is somewhat *close* to the true model.
477 Suppose missingness is truly LMAR. We demonstrate that imputation incorrectly assuming
478 MAR can result in biased outcome model parameter estimates, and the proposed approach
479 using LMAR assumptions can correct or reduce this bias. Suppose instead that missingness is
480 truly MAR. Simulations demonstrate that imputation under LMAR can produce good results
481 as long as the working model contains the true MAR mechanism. Since associations between
482 missingness and fully observed variables can be directly explored using the observed data,
483 we can often identify observed factors related to sampling to construct a good working model
484 structure for LMAR-based imputation.

485 Additional simulations explore the numerical convergence properties of the proposed
486 SMC imputation algorithm. We do not see evidence of convergence issues under MAR
487 outcome missingness or MAR/LMAR covariate missingness except in the case where the
488 working missingness model contains many highly correlated predictors. In some scenarios,
489 we see convergence issues when we have LMAR outcome missingness, and parameters of the
490 missingness model were particularly susceptible. Convergence problems can be substantially
491 reduced by fixing parameters related to the latent variable in the missingness model.

492 We apply the imputation approach to a motivating study of head and neck cancer
493 recurrence. We impute missing values under MAR and LMAR assumptions, and the
494 resulting model fits are very similar. In this application, the model inference is robust to
495 the assumptions about missingness. We also see this phenomenon in the simulations based
496 on the cure model, suggesting that the cure model in particular may be fairly robust to
497 MAR assumptions under cure status-dependent missingness. This issue is discussed in more
498 detail in the Supplementary Materials (Simulation 6). We may be generally less concerned
499 about accounting for latent-dependent missingness in the cure model setting, where the latent
500 variable is always partially observed.

501 One criticism of methods that do not assume a fully-specified joint distribution is
502 that the algorithm is not guaranteed to converge to draws from a valid joint posterior
503 predictive distribution for the missing values (Van Buuren et al. 2006). Our proposed

504 imputation approach is similarly not guaranteed to converge to a valid joint distribution in
505 general, and convergence can be impacted by identifiability issues. In this paper, we do
506 not prove convergence properties for the proposed algorithm beyond existing properties in
507 the SMC imputation and chained equations literature (Bartlett et al. 2014, e.g.). Instead,
508 we use simulation to identify settings that may be particularly susceptible to concerns
509 about convergence. We demonstrate that the convergence of the proposed algorithm can
510 be impacted by parameter identifiability. Care should be taken to monitor algorithm
511 convergence, particularly in the setting of LMAR outcome missingness or with working
512 missingness models containing many predictors. We similarly do not prove identifiability
513 properties for general LMAR mechanisms. In some settings (e.g. Wu & Carroll 1988;
514 Miao, Ding & Geng 2016), identifiability has been demonstrated analytically, but exploring
515 identifiability can be difficult in general. We view proofs of identifiability for general LMAR
516 mechanisms to be outside the scope of this work. Instead, we provide some guidance for
517 applying the proposed methods in the presence of possible identifiability issues.

518 The proposed methods can be applied under MAR and LMAR outcome/covariate
519 missingness. Unlike usual MAR-based imputation, the proposed imputation approach
520 requires us to model the data missingness mechanism when missingness is *assumed to be*
521 LMAR. However, this direct dependence on the missingness model provides a convenient
522 framework for studying the sensitivity of outcome model inference to different assumptions
523 about the missingness mechanism (Little 1995; Molenberghs, Beunckens & Sotito 2008).
524 Additionally, we propose an imputation procedure when missingness is *assumed to be* MAR,
525 but this approach is similar to other methods existing in the literature that do not require a
526 joint model. Simulations suggest that the proposed LMAR-based imputation approach can
527 be applied even in MAR settings as long as the working missingness model contains or is
528 close to the true model and the LMAR-based model is well-identified. Since associations
529 between missingness and observed variables can be readily evaluated using observed data,
530 we may often be able to construct a reasonable working missingness model allowing for
531 additional dependence on the latent variable. The proposed method allows us to incorporate
532 the outcome model directly into the imputation of the latent variable (and possibly missing
533 covariate/outcome values), potentially resulting in improved imputations and reduced bias
534 in the downstream analysis compared to usual chained equations. Our proposed method,
535 therefore, provides a flexible and novel generalization of the usual MAR-based imputation
536 that allows us to study a wider class of missingness models, of which MAR is a special case.

537

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