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Disturbance type and species life history predict mammal responses to humans

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67 Running head: Mammal traits predict responses to humans

68 **Abstract**

69 Human activity and land use change impact every landscape on Earth, driving declines in many
70 animal species while benefiting others. Species ecological and life history traits may predict
71 success in human-dominated landscapes such that only species with “winning” combinations of
72 traits will persist in disturbed environments. However, this link between species traits and
73 successful coexistence with humans remains obscured by the complexity of anthropogenic
74 disturbances and variability among study systems. We compiled detection data for 24 mammal
75 species from 61 populations across North America to quantify the effects of (1) the direct
76 presence of people and (2) the human footprint (landscape modification) on mammal occurrence
77 and activity levels. Thirty-three percent of mammal species exhibited a net negative response
78 (i.e., reduced occurrence or activity) to increasing human presence and/or footprint across
79 populations, while 58% of species were positively associated with increasing disturbance.
80 However, apparent benefits of human presence and footprint tended to decrease or disappear at
81 higher disturbance levels, indicative of thresholds in mammal species’ capacity to tolerate
82 disturbance or exploit human-dominated landscapes. Species ecological and life history traits
83 were strong predictors of their responses to human footprint, with increasing footprint favoring
84 smaller, less carnivorous, faster-reproducing species. The positive and negative effects of human
85 presence were distributed more randomly with respect to species trait values, with apparent
86 winners and losers across a range of body sizes and dietary guilds. Differential responses by
87 some species to human presence and human footprint highlight the importance of considering
88 these two forms of human disturbance separately when estimating anthropogenic impacts on
89 wildlife. Our approach provides insights into the complex mechanisms through which human
90 activities shape mammal communities globally, revealing the drivers of the loss of larger
91 predators in human-modified landscapes.

92

93 **Keywords**

94 anthropogenic disturbance, carnivore, conservation, environmental filter, human footprint index,
95 human-wildlife coexistence, traits, ungulate, occupancy, wildlife

96

97 **Introduction**

98 As the spatial extent and intensity of human activity expands worldwide (Larson et al., 2016;
99 Venter et al., 2016), it is increasingly critical to understand how animal communities respond to
100 anthropogenic disturbance (Gallo et al., 2017; Magle et al., 2016; Parsons et al., 2018).
101 Disturbance effects on animal distribution and activity are typically assumed to be negative
102 (Belote et al., 2020; Dirzo et al., 2014), yet for some species, human activities confer benefits as
103 well as costs. These trade-offs are particularly common for mammals, as greater resource
104 availability and reduced competition or predation in human-dominated landscapes (Bateman &
105 Fleming, 2012; Moll et al., 2018) may offset the impacts of habitat loss and exposure to
106 anthropogenic mortality (Hill et al., 2020; Sévêque et al., 2020). At the community level, the
107 differential responses of species to human disturbance may have a filtering effect (Aronson et al.,
108 2016; Santini et al., 2019), such that only species with “winning” combinations of ecological and
109 life history traits (i.e., those suited to coexistence with humans) will persist in disturbed
110 environments (Pineda-Munoz et al., 2021). Human disturbance may therefore reshape mammal
111 communities in ways that are predictable from suites of species traits, with implications for both
112 single-species conservation efforts and broader patterns of ecosystem functioning (Estes et al.,
113 2011; Schmitz et al., 2018).

114

115 Anthropogenic activity involves multiple distinct stressors, which may interact with species traits
116 to determine the net effect of human influence on mammal behavior and habitat use. Recent
117 work (Doherty et al., 2021; Nickel et al., 2020) demonstrates that two broad types of human
118 disturbance – direct human presence (e.g., recreation, hunting; (Kays et al., 2017; Naidoo &
119 Burton, 2020)) and human footprint on the landscape (e.g., habitat fragmentation, development;
120 (Smith et al., 2019; Suraci et al., 2020; Venter et al., 2016)) – have different and often opposing
121 effects on mammals, likely because these two disturbance types represent distinct sets of filters
122 that interact differently with species traits. For instance, mammal body size and trophic position

123 may determine whether the immediate presence of humans induces fear responses that result in
124 reduced habitat use and suppressed activity (Clinchy et al., 2016; Ordiz et al., 2019; Suraci,
125 Clinchy, et al., 2019) or whether human presence leads to indirect benefits through relaxed
126 predation/competition (Berger, 2007; Muhly et al., 2011). Species traits may similarly determine
127 mammal responses to human footprint. Species with large space requirements may be more
128 negatively impacted by habitat loss and fragmentation (Crooks et al., 2017; Ripple et al., 2014),
129 while those with higher dietary flexibility may benefit from increased resource availability in
130 modified landscapes (Bateman & Fleming, 2012; Newsome & Van Eeden, 2017). Across
131 disturbance types, suites of traits may be strongly related to both the likelihood that a species will
132 occur in areas of high human influence (Aronson et al., 2016; Evans et al., 2011; Santini et al.,
133 2019), as well as the intensity with which a species uses such areas when present (e.g., the
134 number of individuals present and/or the frequency with which a site is visited; (Lewis et al.,
135 2015; Moll et al., 2018; Suraci, Clinchy, et al., 2019)), potentially allowing ecologists to predict
136 shifts in mammal community structure and species interactions with increasing disturbance
137 intensity.

138
139 However, variation among populations may obscure the link between species-level traits and
140 measured responses to human disturbance. Within a given mammal species, populations
141 frequently vary in the intensity or directionality of their response to a given disturbance type
142 depending on local conditions, including habitat productivity and exposure to anthropogenic
143 mortality (Belote et al., 2020; Kays et al., 2017; Moreno-Rueda & Pizarro, 2009; Sévêque et al.,
144 2020). Indeed, studies of recreation impacts in protected areas commonly report contrasting
145 responses to human presence by different populations of the same species (Bateman & Fleming,
146 2017; Patten & Burger, 2018; Reed & Merenlender, 2008; Reilly et al., 2017), and use of
147 developed areas may also vary among populations based on trade-offs between anthropogenic
148 threat and resource availability (Bateman & Fleming, 2012; Carlos et al., 2009). Therefore,
149 elucidating general patterns in mammal responses to human disturbance requires explicitly
150 accounting for variation among populations as well as across species.

151
152 Here we examine the link between mammal species traits and responses to human disturbance at
153 the continental scale, hypothesizing that species with particular combinations of trait values are

154 more negatively impacted by human influence. Specifically, we hypothesized that larger, more
155 carnivorous species and those with slower life history strategies (i.e., longer maturation periods,
156 slower reproductive rates) are more negatively affected by both human presence and human
157 footprint, given that these species are typically more likely to come into conflict with humans
158 (Oriol-Cotterill et al., 2015; Ripple et al., 2014) and may experience higher rates of
159 anthropogenic mortality (Darimont et al., 2015; Hill et al., 2020). To test our hypotheses, we
160 compiled camera trap data for 24 medium-to-large ungulate and carnivore species from 61 study
161 areas across North America (Fig. 1A), which collectively represent a substantial proportion of
162 the North American range for all mammal species in our analysis. Each camera trapping project
163 deployed cameras across gradients of both human presence (Fig. 1B) and human footprint (Fig.
164 1C), covering a broad range of both disturbance types, from undeveloped, remote landscapes to
165 well used parks and urban centers. Our analysis addresses two objectives. We first quantify
166 mammal species responses to human disturbance across North America, incorporating variation
167 among populations of the same species to determine the net effect of human presence and human
168 footprint on habitat use and activity levels for each species. We then model mammal responses to
169 anthropogenic disturbance as a function of species ecological and life history traits to discern the
170 mechanistic drivers of human influence on mammal communities.

171

172 **Materials and methods**

173 *Camera trapping projects and species*

174 We compiled data from 61 camera trapping studies (here after, “projects”) from across the
175 continental United States, Canada, and Mexico, representing 3,212 unique camera locations
176 sampled for a total of 454,252 trap days. Details of each camera trapping project are presented in
177 Table S1. Projects were conducted between 2007 and 2019, ranged in spatial extent between 0.4
178 and 61,506 km² ($\bar{x} \pm SD = 3,473.1 \pm 9834.9$), deployed camera traps at three to 487 unique
179 camera sites ($\bar{x} \pm SD = 52.6 \pm 87.6$) and operated for between 63 and 106,480 trap days ($\bar{x} \pm SD$
180 $= 7,446.7 \pm 17,488.5$). While the specific locations across North America sampled in this study
181 were driven by the availability of existing camera trap data sets, we endeavored to cover a large
182 and representative proportion of the continent and to focus on areas with overlapping mammal
183 species composition. We focused our analyses on 24 medium-to-large mammal species in the
184 orders *Artiodactyla* and *Carnivora* that were reliably identifiable from camera trap images and

185 which represented three trophic guilds: herbivores, omnivores, and carnivores (Table S2). We
186 only included those species that were detected by at least three camera trapping projects and with
187 a total of at least 100 independent detections to ensure convergence of occupancy models (see
188 below). Due to data limitations, we treated eastern and western spotted skunks (*Spilogale*
189 *putorius* and *S. gracilis*) as a single species. We considered different camera trapping projects to
190 approximate separate populations of each focal species, while acknowledging that there may be
191 some overlap among adjacent projects.

192
193 We used the geographic location of each camera site to standardize the spacing between sites by
194 (i) treating groups of camera sites within 10 m of each other as a single site and (ii) subsampling
195 camera sites such that each site was at least 500 m from its nearest neighbor. For the latter step,
196 when two or more camera sites were within 500 m of each other, we retained the site with the
197 longest sampling duration. Because data on camera activity and camera failures were
198 inconsistently recorded across projects, we used detection (i.e., photograph) time stamps to
199 algorithmically identify breaks in camera activity of greater than four weeks (28 days). We
200 considered these to be likely camera failures and the durations of these activity breaks were
201 therefore subtracted from the total trap nights for the corresponding camera site. Averaged across
202 all camera sites, these breaks in activity accounted for 4.6% (\pm 12.3% SD) of the total time a
203 camera was deployed across the study.

204 205 *Estimating human presence and human footprint*

206 We estimated human presence as the detection rate (i.e., detections per trap day) of humans at
207 each camera site. Human detections included all people on foot, bicycles, and motorized
208 vehicles, but did not include detections of domestic animals unless a person was also present in
209 the photograph. Because the number of individuals in each photograph was inconsistently
210 reported between projects, each detection event could include one or multiple humans and thus
211 detection rates should be interpreted as groups of humans detected per trap day (Nickel et al.,
212 2020). Detections of people on camera provide a fine-scale estimate of hotspots of human
213 presence across a landscape (e.g., where recreational activity is highest).

214

215 Human footprint at each camera site was estimated from the Human Footprint Index (HFI) which
216 ranges between 0 and 50 and integrates multiple anthropogenic pressures on the landscape
217 including development, agriculture, and transportation infrastructure (Venter et al., 2016). We
218 used the most recent (i.e., 2009) HFI map and extracted the average HFI value within a 1-km
219 buffer around each camera site. This buffer size matches the resolution of the HFI layer itself and
220 is comparable to the buffer size used in previous studies examining the effects of landscape
221 context on occupancy model parameters across multiple study areas and for species with a range
222 of movement capacities (e.g., Nickel et al., 2020; Rich et al., 2017). We note that the spatial
223 resolution of the HFI (i.e., 1 km) may not match the optimal scale of effect of human footprint
224 for all species considered here (Moll et al., 2020). However, this layer is among the few available
225 at the necessary geographic extent (i.e., all of North America) and has been found to correlate
226 strongly with wildlife behavioral responses in previous large-scale studies considering a range of
227 mammal species (e.g., Tucker et al., 2018).

228
229 Across all projects human presence ranged from zero people/groups per day in remote areas to
230 more than 10 per day (max = 12.5) in heavily used protected areas and suburban neighborhoods
231 (Fig. S1a). The human footprint ranged from an HFI of zero, representing undeveloped
232 landscapes in or near protected areas, to more than 40 (max = 46.1) in urban centers such as
233 Detroit, Michigan and Albany, New York (Fig. S1b). Areas of high human footprint often also
234 have many people present (though this is not always the case, e.g., in heavily modified
235 agricultural landscapes). However, given that camera trap detections represent a fine-scale
236 estimate of human presence (i.e., in the immediate vicinity of the camera), and because cameras
237 in suburban and urban landscapes were often set in locations frequented by wildlife but not by
238 people (e.g., riparian corridors, woodlots, or private property), our measures of human presence
239 and footprint are uncorrelated at the level of individual cameras (Pearson's $r = 0.003$, $p = 0.77$)
240 and only weakly correlated at the project level (project-level means; $r = 0.22$, $p = 0.09$).

241 *Quantifying mammal responses to human disturbance via occupancy models*

242 We fit a series of single-species occupancy models to detection data for each of the 24 focal
243 species. Occupancy models estimate two linked parameters, occupancy probability, ψ , the
244 probability that at least one individual of a focal species “occupies” a given site, and intensity of
245

246 use, p , the probability of detecting the species at that site, given that the site is occupied (Burton
247 et al., 2015; MacKenzie et al., 2002). When studying wide-ranging wildlife species, individuals
248 may use multiple camera sites and may be absent from any given camera site for periods longer
249 than the survey interval (Burton et al., 2015; Efford & Dawson, 2012; Neilson et al., 2018). We
250 therefore interpret ψ as ‘site use’ rather than occupancy *per se* (Kays et al., 2020). We refer to p
251 as “intensity of use” (rather than simply “detection probability” (sensu MacKenzie et al., 2002))
252 to reflect the fact that the likelihood of detecting a species at a used site depends strongly on the
253 local abundance of the species at that site (Royle, 2004; Royle & Nichols, 2003) and likely also
254 varies with changes in individual behavior (e.g., increased crypsis or reduced activity levels
255 where perceived mortality risk is high (Suraci, Clinchy, et al., 2019)). We therefore use
256 covariates on p to investigate how anthropogenic disturbance affects the frequency or intensity
257 with which an occupied site is used (Lewis et al., 2015).

258

259 In addition to human presence and footprint, we estimated several covariates for each camera site
260 with the potential to affect occupancy and/or intensity of use (Table S1). We calculated percent
261 forest cover around each camera site using the 2010 Global Tree Cover database (30-m
262 resolution) (Hansen et al., 2013) and estimated net primary productivity (NPP) around each site
263 using NASA’s MODIS system annual NPP layer (500-m resolution) (Running & Zhao, 2019) for
264 2016, the median year of all detection events in this study. Forest cover and NPP were estimated
265 within a 1-km buffer around each camera site, matching the spatial scale at which the human
266 footprint was estimated and capturing the landscape context experienced by animals using that
267 camera site (Nickel et al., 2020; Rich et al., 2017). We also estimated forest cover in the
268 immediate vicinity of each site (i.e., 100-m buffer) to capture the effects of local vegetation
269 cover on species detection probability. Given the large number of ecoregions represented by our
270 continental-scale data set, we elected to use forest cover and NPP as continuous proxies for
271 habitat and ecosystem type rather than expending model degrees of freedom on several discrete
272 habitat categories. Principal investigators for each camera trapping project provided data on
273 whether their project baited camera sites (with either scent lures or food rewards) as well as the
274 prevalence of legal hunting within the project area for both carnivores and ungulates. Typically,
275 hunting data were not available for each individual camera site within a project. We therefore
276 assigned each camera site to one of two hunting prevalence categories depending on hunting

277 activity across the project area: 0 = no or only limited hunting (of carnivores and/or ungulates)
278 within the project area, where limited hunting implies that only a subset of camera sites was
279 located within areas where hunting was permitted/occurring; 1 = hunting occurred across the
280 project area (i.e., at most or all camera sites, as reported by data contributors). Finally, we
281 included the geographic location of each camera site (latitude and longitude) in our occupancy
282 models to account for potential similarities between sites in occupancy and intensity of use
283 stemming from geographic proximity (Rota et al., 2016). Several other aspects of camera
284 deployment (e.g., camera height, whether cameras were set on trails) may affect the probability
285 of detecting mammal species, but data on these variables were only available for a subset of
286 camera trapping projects. We therefore included a random effect for each project in the
287 occupancy models described below to accommodate variation between projects not explicitly
288 modeled by detection covariates.

289

290 Several camera trapping projects spanned multiple seasons and years (Table S1). To satisfy the
291 occupancy model assumption of closure to changes in site-level occupancy status during a given
292 sampling period (Burton et al., 2015), data for each camera site were divided into seasonal
293 sampling periods of at most six months: summer (March to August) and winter (September to
294 February). We determined the total duration that each camera was active within each sampling
295 period using the timestamp of the first and last detection event within that period. We treated
296 each week of a given sampling period as a separate survey and modeled the number of weeks in
297 which the focal species was detected during sampling period i at camera site j in project k as

298

$$299 \quad y_{ijk} \sim \text{BetaBinom}(p_{ijk} * z_{ijk}, S_{ijk}, \rho)$$

$$300 \quad z_{ijk} \sim \text{Bernoulli}(\Psi_{ijk})$$

301 where S_{ijk} is the total number of weeks that camera site j (nested in project k) was active during
302 sampling period i and thus available for sampling, and ρ is the overdispersion parameter of the
303 beta-binomial distribution. We modeled y as beta-binomially distributed because preliminary
304 analyses indicated that variation between projects led to overdispersion in detection data relative
305 to the variability accommodated by the more standard binomial distribution, a situation that is
306 well handled by a beta-binomial model (Gelman & Hill, 2007). The mean of the beta-binomial

307 distribution for camera site j during sampling period i is given by the intensity of use, p ,
308 multiplied by z , the latent occupancy state of the focal species at that camera site (Royle &
309 Dorazio, 2008). z_{ijk} is in turn drawn from a Bernoulli distribution with probability ψ , i.e., the
310 probability that the focal species occupies camera site j during sampling period i .

311
312 Occupancy probability and intensity of use were modeled as

$$\begin{aligned} 313 \quad \text{logit}(\Psi_{ijk}) = & \alpha_{0jk} + \alpha_{1k} \text{Presence}_{ij} + \alpha_{2k} \text{Footprint}_j + \alpha_{3k} \text{Presence}_{ij}^2 + \alpha_{4k} \text{Footprint}_j^2 \\ 314 \quad & + \alpha_5 \text{Hunt}_j + \alpha_6 \text{Forest}_{1km}_j + \alpha_7 \text{NPP}_j + \alpha_8 \text{Season}_i + \alpha_9 \text{Latitude}_j + \alpha_{10} \\ 315 \quad & \text{Longitude}_j \end{aligned}$$

$$\begin{aligned} 316 \quad \text{logit}(p_{ijk}) = & \beta_{0jk} + \beta_{1k} \text{Presence}_{ij} + \beta_{2k} \text{Footprint}_j + \beta_{3k} \text{Presence}_{ij}^2 + \beta_{4k} \text{Footprint}_j^2 \\ 317 \quad & + \beta_5 \text{Hunt}_j + \beta_6 \text{Forest}_{100m}_j + \beta_7 \text{Bait}_j + \beta_8 \text{Season}_i \end{aligned}$$

319
320 We modeled occupancy as a function of percent forest cover in a 1-km radius around the camera
321 site to estimate the effect of local habitat type on the probability of site use, while detection
322 probability was modeled as a function of forest cover in the immediate vicinity of the camera
323 (100-m radius), as sight lines and thus the ability to detect species that are present may be
324 reduced in more heavily forested habitats relative to open areas. For both human presence and
325 human footprint, we fit linear and quadratic terms to test for potential non-linear effects of
326 increasing human disturbance on species responsiveness. Because all covariates were mean
327 centered for direct comparison (see below for details), linear terms are interpretable
328 independently of quadratic terms (Schielzeth, 2010). Different populations of a given mammal
329 species may not necessarily exhibit consistent responses to human disturbance. For both ψ and p ,
330 we therefore allowed the intercept (α_0, β_0) and the coefficient estimates for human presence ($\alpha_1,$
331 β_1) and human footprint (α_2, β_2), as well as their quadratic terms ($\alpha_3, \alpha_4, \beta_3, \beta_4$), to vary by
332 camera trapping project k . All project-level covariates were modeled as being drawn from a
333 common distribution, with hyperparameters μ and σ^2 describing the mean and variance across all
334 projects in the data set. For instance, α_{0k} was modeled as

$$335 \quad \alpha_{0k} \sim N(\mu_{\alpha_0}, \sigma_{\alpha_0}^2).$$

336 To account for the fact that many camera sites were sampled repeatedly across multiple sampling
337 periods, the intercepts were further modeled as camera site-level random effects, with camera
338 site j nested in project k , i.e.,

$$339 \alpha_{0jk} \sim N(\alpha_{0k}, \sigma_{\alpha_k}^2)$$

$$340 \beta_{0jk} \sim N(\beta_{0k}, \sigma_{\beta_k}^2)$$

341 where $\sigma_{\alpha_k}^2$ is an error term describing the variance between camera sites for a given project (and
342 likewise for $\sigma_{\beta_k}^2$).

343
344 Because a primary objective of this study was to model mammal responses to human disturbance
345 (estimated from occupancy model coefficients) as a function of species traits, it was essential
346 that model coefficients were comparable across species. We therefore fit identical occupancy
347 models to each species' data (using all model terms just described) rather than attempting to
348 identify the best model for each individual species through model comparison. All model
349 covariates were mean-centered, and continuous covariates were scaled by two standard
350 deviations. We centered and scaled disturbance covariates prior to subsetting the data for each
351 single-species model such that a given value of human presence/footprint received the same
352 standardized value in all models to ensure comparability across species. Pearson correlation
353 coefficients (r) between all pairs of model covariates were < 0.6 , with the exception of latitude
354 and longitude ($r = -0.62$). For each focal species, occupancy models only included data from
355 projects that detected the species at least once.

356
357 To determine whether each human disturbance type had a net positive or negative effect on site
358 occupancy and intensity of use for a given species, we calculated the probability that each human
359 disturbance linear effect (i.e., α_1 , α_2 , β_1 , and β_2 above) was more extreme (greater or less) than
360 zero using the Bayesian posterior distribution of the coefficient estimate (referred to as the
361 "posterior probability" of the disturbance effect). We quantified the number of species
362 exhibiting an effect of each disturbance type by counting the species for which the posterior
363 probability of a positive or negative effect was > 0.9 . This value corresponds to 80% Bayesian
364 credible intervals around the disturbance coefficient that do not include zero and was chosen to

365 capture species with limited sample sizes and/or high variability between populations that
366 nonetheless exhibited a strong trend towards a positive or negative association with
367 anthropogenic influence.

368

369 *Modeling mammal responses to disturbance as a function of species traits*

370 A primary objective of this study was to examine how a species' traits affect its responsiveness
371 to human disturbance while explicitly accounting for variation between populations of the same
372 species. We therefore extracted project-level estimates for the (linear) effect of human presence
373 and human footprint on both occupancy and detection probability (i.e., α_{1k} , α_{2k} , β_{1k} , and β_{2k}
374 above) from each single-species occupancy model and modeled these values as a function of
375 species traits. We modeled each of the four disturbance-response combinations (i.e., presence
376 and footprint effects on ψ and p) separately.

377

378 For each focal species, we used the PanTHERIA database (Jones et al., 2009) to extract a suite of
379 species traits that may affect responsiveness to human disturbance. This included several traits
380 related to size and space use requirements, namely adult body mass, home range size, and
381 longevity (i.e., maximum lifespan). We also extracted traits related to species reproductive
382 strategy, including litter size, weaning age (i.e., the average age at which young become
383 independent of their mother for nutritional needs), and age at sexual maturity (Jones et al., 2009).
384 We used the EltonTraits database (Wilman et al., 2014) to extract data on the proportion of each
385 of 10 diet categories in the diet of each species and used these data to calculate two dietary
386 indices. Following Santini et al. (2019), we used the Shannon Index to estimate dietary diversity
387 for each species based on all 10 diet categories. We also calculated the proportion of the diet
388 consisting of vertebrate prey as an estimate of each species' degree of carnivory (EltonTraits diet
389 categories "vertebrate-endoderm", "vertebrate-ectoderm", "vertebrate-fish", and "vertebrate-
390 unknown"). The proportion of vertebrate prey and scavenging in the diet was used to classify
391 each species into three trophic guilds: herbivore (0%), omnivore (1-50%), and carnivore (>50%
392 vertebrate prey and scavenging). All species trait values are presented in Table S2. We
393 conducted a principal components analysis (PCA) on all trait and dietary data and extracted the
394 first two principal components (PC1 and PC2), which collectively accounted for 72.3% of the

395 variation in trait values between species. We then used PC1 and PC2 as covariates in modeling
396 species responses to human disturbance.

397

398 Our response variables in these models, i.e., the effects of presence or footprint on species
399 occupancy or detection, are themselves model estimates and are thus not perfectly observed. We
400 therefore determined the posterior variance around each project-level disturbance effect size, as
401 estimated by single-species occupancy models, and propagated this error through the multi-
402 species trait models. We treated the “true” disturbance effect on occupancy or detection, w_{is} , as
403 an unobserved latent variable for which we have an observed value, v_{is} , with an associated
404 “observation” error value, $\sigma_{o,is}^2$

$$405 v_{is} \sim N(w_{is}, \sigma_{o,is}^2)$$

406 where i is a project-level disturbance effect size observation for species s . We then modeled the
407 true, unobserved disturbance effect, w_{is} , as a function of PC1, PC2 and their interaction using a
408 Gaussian linear model. We also included the geographic location of each project (project-level
409 mean latitude and longitude, Table S1) in all models to account for potential similarities between
410 projects in mammal responses stemming from geographic proximity. The linear models included
411 a random intercept for species to account for the fact that each species’ response to disturbance
412 was estimated for several camera trapping projects. The species-level random effect was nested
413 within family to account for the influence of taxonomic relatedness in driving similar responses
414 between species. Other taxonomic levels were not included because there were either too few
415 categories (only two orders, *Artiodactyla* and *Carnivora*, were represented) or too few
416 observations per category (most genera were only represented by a single species) to estimate the
417 random effects, inhibiting model convergence.

418

419 *Model fitting and checking*

420 We analyzed all occupancy models (24, one for each focal species) and species trait models (4)
421 in a Bayesian framework using the Stan programming language called through the Rstan
422 package in R (Stan Development Team, 2020). For each model we ran three Hamiltonian Monte
423 Carlo (HMC) chains of either 2000 or 4000 iterations each (depending on ease of model
424 convergence) and retained 1,000 samples from the posterior distribution of each chain for
425 inference. Following Gelman et al. (2008) and Gabry et al. (2019), we chose vague or weakly

426 informative priors for all random variables and random starting values for each HMC chain. We
427 confirmed convergence of HMC chains by visual inspection of trace plots and via the Gelman-
428 Rubin statistic (“R-hat” values < 1.1 for all parameters) (Gelman, 2006), and verified the
429 reliability of model inference following the procedure outlined by Gabry et al. (2019). We tested
430 model fit using Bayesian p-values, which compare test statistics calculated from observed and
431 expected (i.e., model-generated) data (Hobbs & Hooten, 2015). P-values were calculated using
432 test statistics appropriate for the model distributions – for occupancy models we calculated
433 Freeman-Tukey (Conn et al., 2018) and chi-squared statistics (Royle & Dorazio, 2008), and for
434 the trait models we used the mean and coefficient of variation (Hobbs & Hooten, 2015). We
435 detected satisfactory to excellent fit between model and data for all occupancy models ($0.41 \leq p$
436 ≤ 0.92 ; all p-values shown in Table S5) and trait models ($0.35 \leq p \leq 0.81$; all p-values shown in
437 Table S4). All code for performing the analyses described here can be found at
438 <https://github.com/jsuraci/Suraci-et-al-MammalLifeHistory>.

439

440 **Results**

441 Standardized occupancy model coefficients, summarizing the average response to disturbance
442 across all populations of a given species, revealed that 17% of the 24 mammal species in our
443 study (three herbivores and one carnivore) were negatively affected by human presence (i.e., the
444 posterior probability of a negative effect of human presence on occupancy and/or intensity of use
445 was > 0.9, see Methods). Elk (*Cervus elaphus*) exhibited reduced site occupancy with increasing
446 human presence, while moose (*Alces alces*), mountain goats (*Oreamnos americanus*) and
447 wolverines (*Gulo gulo*) exhibited reduced intensity of use (Fig. 2A and B). Thirty-three percent
448 of species were positively associated with human presence (two herbivores, two omnivores, four
449 carnivores). Bighorn sheep (*Ovis canadensis*), black bears (*Ursus americanus*), and wolverines
450 exhibited increased site occupancy with increasing human presence, while mule deer
451 (*Odocoileus hemionus*), bobcats (*Lynx rufus*), grey foxes (*Urocyon cinereoargenteus*), pumas
452 (*Puma concolor*), and wolves (*Canis lupus*) tended to increase intensity of use in areas of higher
453 human activity (Fig. 2A and B).

454

455 Human footprint had a negative effect on site occupancy and/or intensity of use for 25% of
456 mammal species (one herbivore, one omnivore, and four carnivores), and a positive effect for

457 38% of species (three herbivores, two omnivores, and four carnivores). Species negatively
458 associated with human footprint included grizzly bears (*Ursus arctos*), lynx (*Lynx canadensis*),
459 wolves, and wolverines, all of which were less likely to occupy sites with increasing footprint
460 and exhibited decreased intensity of use when present, while moose and martens (*Martes*
461 *americanus*) exhibited decreased intensity of use only. Raccoons (*Procyon lotor*) and white-
462 tailed deer (*O. virginianus*) were positively associated with human footprint in terms of both
463 occupancy and intensity of use, while elk, mule deer, striped skunks (*Mephitis mephitis*), red
464 foxes (*Vulpes vulpes*), bobcats, coyotes (*Canis latrans*), and pumas all tended to use occupied
465 sites more intensively at higher levels of human footprint (Fig. 2A and B).

466
467 For several species exhibiting positive responses to disturbance, intensity of use peaked at low to
468 intermediate values of human presence (six species, Fig. 3A) or footprint (eight species, Fig.
469 3B), indicative of thresholds in these species' capacity to tolerate disturbance or exploit human-
470 dominated landscapes. Red foxes were the single exception, being the only species to exhibit an
471 increasingly positive association with human presence at medium to high disturbance levels (Fig.
472 3A). Full results for all occupancy models are presented in Figure S2

473
474 The first two components of the PCA performed on species trait values (accounting for 72.3% of
475 trait variation) describe axes of increasing body size with decreasing life history speed (i.e.,
476 smaller litters, slower maturation; PC1), and increasing space use with greater carnivory (PC2;
477 Fig. 4A and Table S3). Bayesian regression models revealed that the effects of human footprint
478 on both site occupancy (Fig. 4B; $\beta = -0.22$ [95% CI = -0.48,0.01]) and intensity of use (Fig. 4C;
479 $\beta = -0.23$ [-0.57,0.04]) were increasingly negative at higher values of PC1 (posterior probability
480 of a negative slope = 0.97 and 0.95, respectively; Table S4), indicating that larger, longer-lived
481 mammal species and those with slower maturation and reproductive rates are less likely to occur
482 in modified landscapes and are less active when present. Human footprint also had an
483 increasingly negative effect on occupancy (but not intensity of use; Table S4) for species with
484 higher PC2 values (Fig. 4D; $\beta = -0.40$ [-0.76, -0.04]; probability of a negative slope = 0.99),
485 indicating that species with more carnivorous diets and larger home ranges are less likely to use a
486 given site as landscape modification increases. We did not detect a relationship between human
487 presence and species traits in their effects on site occupancy or intensity of use (Bayesian

488 regression; posterior probability of a negative slope ranged between 0.33 and 0.85 for all
489 relationships; Table S4).

490

491 **Discussion**

492 By bringing together data on activity and habitat use from mammal populations across North
493 America, our study provides a comprehensive understanding of mammal responses to human
494 disturbance. We found that species' ecological and life history traits were strong predictors of
495 their responses to human footprint on the landscape, confirming our hypothesis that larger, more
496 carnivorous, and slower reproducing species are more negatively affected by human landscape
497 modification. Contrary to our expectations, however, species traits were not strongly related to
498 their responses to human presence, highlighting the importance of considering these two forms
499 of human disturbance separately when estimating anthropogenic impacts on wildlife (Nickel et
500 al., 2020; Sévêque et al., 2020).

501

502 Our occupancy model estimates revealed relatively few overall “winners” and “losers”, i.e.,
503 species that tended to respond positively or negatively across disturbance types. Instead, most
504 species exhibited differing, and frequently opposing, responses to human presence and footprint
505 (Fig. 2A and B). This pattern was previously reported for mammals in a single study area (Nickel
506 et al., 2020), and our results suggest this is a common feature of human-mammal interactions
507 across North America. Negative effects of human presence likely stem from fear of humans
508 causing mammals to suppress their activity levels (Suraci, Clinchy, et al., 2019) or avoid areas of
509 high human influence entirely (Oriol-Cotterill et al., 2015), while positive associations may
510 reflect the shield that human presence provides for some species against predators or competitors
511 (Berger, 2007; Hebblewhite et al., 2005; Muhly et al., 2011). Positive responses to human
512 presence by larger bodied species with substantial space requirements (e.g., pumas, wolves,
513 wolverines; Fig. 2B) may also reflect the growing intensity of recreation and ecotourism in
514 otherwise relatively undisturbed areas of wildlife habitat (Anton et al., 2020; Nickel et al., 2020),
515 leaving such species with little choice but to share space with people.

516

517 Despite the loss of natural habitat associated with increasing human footprint, agricultural lands
518 and developed areas nonetheless present opportunities for some species through resource

519 subsidies or relaxed predation/competition (Prugh & Sivy, 2020; Sévêque et al., 2020). Increased
520 human footprint is also associated with decreased movement and smaller home ranges for many
521 mammal species (Doherty et al., 2021; Tucker et al., 2018), including large predators such as
522 pumas (Nickel et al., 2021). Thus, higher intensity of use in more heavily modified habitats by
523 species that otherwise tend to avoid human footprint (e.g., pumas and bobcats, (Serieys et al.,
524 2021; Suraci et al., 2020)) may reflect restricted movement options and thus intensified use of
525 remaining habitat fragments in moderately developed areas.

526

527 Importantly, for several mammal species that exhibited positive associations with human
528 presence or footprint, the apparent benefits of human activity were diminished or reversed at
529 higher disturbance levels (Fig. 3). For instance, black bears, elk, and wolves were most active at
530 sites visited by approximately one person/group every 8-12 days (Fig. 3A), and several species
531 exhibited peak intensity of use in partially cleared habitats with low density development (i.e.,
532 intermediate HFI values, Fig. 3B). These results indicate that several mammal species exhibit
533 thresholds in their tolerance for human disturbance beyond which habitat may no longer be
534 viable. We suggest that such thresholds are critical to consider when attempting to promote
535 “landscapes of coexistence” (i.e., ecological conditions that allow the long-term persistence of
536 sensitive mammal species in human-dominated landscapes; (Gehr et al., 2017; Oriol-Cotterill et
537 al., 2015)) and functional connectivity between populations, particularly as several large
538 mammal species continue to recolonizing modified landscapes in North American and globally
539 (Gantchoff & Belant, 2017; Gilbert et al., 2016; Hemmingmoore et al., 2020; Rio-Maior et al.,
540 2019).

541

542 Larger mammal species and those with slower life histories were both less likely to occur in
543 areas of high human footprint and exhibited a lower intensity of use when present. The human
544 footprint is associated with a multitude of threats including vehicle strikes (Grilo et al., 2020),
545 sensory pollution (Dominoni et al., 2020), and invasive species (Shochat et al., 2010). Our results
546 suggest that smaller mammals and those with faster life histories are better able to avoid these
547 threats (Hill et al., 2020) or can offset heightened anthropogenic mortality through high
548 reproductive rates (Santini et al., 2019). Additionally, species with more carnivorous diets and
549 larger space requirements were less likely to occur in modified landscapes. Wide ranging

550 carnivores frequently come into conflict with humans over perceived threats to human life and
551 livelihood (Carter & Linnell, 2016; Chapron & López-Bao, 2016; Treves & Karanth, 2003), and
552 their large home range sizes may make them more susceptible to the impacts of habitat
553 fragmentation in modified landscapes (Crooks, 2002; Ripple et al., 2014). While our analyses
554 were focused on North American mammal communities, we suggest that the patterns observed
555 here are likely applicable to medium-to-large mammal species globally. Recent work focused on
556 urban environments has similarly shown that both high reproductive output (large litter size) and
557 high dietary diversity are frequently associated with mammal use of urban areas worldwide
558 (Santini et al., 2019), highlighting the importance of these traits in allowing mammals to
559 successfully exploit modified landscapes. Additionally, the exclusion of larger predatory
560 mammals from areas of high human footprint is a common phenomenon in systems around the
561 world (Ordiz et al., 2013; Oriol-Cotterill et al., 2015).

562

563 Our study provides a framework for predicting the filtering effect of human land use change on
564 mammal communities, helping to clarify the often ambiguous relationship between human
565 footprint and mammal community composition (Belote et al., 2020; Hill et al., 2020). Our results
566 indicate that as human footprint increases, mammal community composition will shift towards
567 smaller herbivorous and omnivorous species with faster reproductive strategies and smaller
568 space requirements. The speed and extent of shifts in community composition following land
569 conversion to agriculture or development will likely depend on local legal protections (e.g.,
570 hunting regulations; (Chapron & Treves, 2016)) and environmental conditions (e.g., ecosystem
571 productivity; (Belote et al., 2020)). Our analysis accounted for population-level variation in these
572 and additional factors, showing that, while the effects of hunting and environmental covariates
573 varied substantially between species (Fig. S2), trends towards reduced occurrence and activity of
574 large-bodied, slow-reproducing mammals in more developed areas were robust to variation in
575 local conditions.

576

577 Our estimates of human footprint (i.e., contemporary landscape modification) represent only a
578 snapshot in time and do not explicitly incorporate legacies of human land use (e.g., historical
579 management regimes; Jonason et al., 2014; Moreira & Russo, 2007) or other forms of ecological
580 disturbance such as fire (Geary et al., 2020; Pastro et al., 2014), both of which are known to play

581 important roles in shaping observed community structure by affecting vegetation composition
582 and species interactions. Our objective in the present study was to detect general patterns in
583 human disturbance impacts on mammals across a range of ecological conditions. However, we
584 note that understanding the interaction between current human land use and other drivers of
585 landscape pattern, both historical and contemporary, will be critical in accurately predicting
586 mammal community responses to future landscape modification in any particular location.

587
588 While species traits predicted responses to human footprint, they were not predictive of
589 responses to human presence, suggesting that the benefits and costs of using habitats frequently
590 visited by humans (e.g., recreationists in protected areas or urban green spaces) are distributed
591 somewhat randomly across body sizes, trophic guilds, and reproductive strategies. This finding
592 likely reflects the fact that many species are able to mitigate the impacts of human presence on
593 space use through increased nocturnality (Gaynor et al., 2018). Whereas landscape modification
594 is relatively constant in space and time, human presence is largely diurnal, meaning that even
595 species that are relatively sensitive to the immediate presence of people (e.g., many carnivores,
596 (Suraci, Clinchy, et al., 2019)) may be able to use human-dominated areas at night when people
597 are less active (Anton et al., 2020; Suraci, Frank, et al., 2019). Importantly, however, shifting
598 temporal activity to avoid humans may be costly by constraining temporal niche space and
599 forcing increased overlap with predators or competitors (Sévêque et al., 2020; Smith et al.,
600 2018).

601
602 The structure and diversity of mammal communities are key determinants of ecosystem
603 processes, with larger-bodied mammals affecting primary production and nutrient cycling
604 through herbivory and trophic interactions (Estes et al., 2011; Schmitz et al., 2018). Here we
605 show that the capacity of mammal species to coexist with humans in modified landscapes is
606 predictable from suites of species traits, highlighting the types of mammal communities that are
607 likely to persist with increased landscape conversion. Such communities will be composed of
608 smaller, faster breeding species with limited space requirements, which may play a more muted
609 role in driving ecosystem processes relative to larger, more mobile, and more carnivorous
610 species (Estes et al., 2011; Ripple et al., 2014; Tucker et al., 2018). Human presence has less
611 predictable spatial impacts on mammal communities but may nonetheless alter wildlife behavior

612 in ways that dampen trophic interactions and the links between ecosystems (Suraci, Clinchy, et
613 al., 2019; Tucker et al., 2018). Continued landscape modification and increased human use of
614 remaining natural areas portend greater reliance of mammal species on human-dominated
615 landscapes. Predicting which species are likely to thrive or perish under multiple sources of
616 anthropogenic pressure is critical to conserving mammal communities and the ecosystem
617 services they provide.

618
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625 analysis from CCW, MLA, and KMG, and with valuable input on writing from all authors.

626 **Data and code availability:** The data that support the findings of this study are openly available
627 on figshare at <https://doi.org/10.6084/m9.figshare.14444600.v1>. All code necessary to replicate
628 the analyses is available on GitHub at [https://github.com/jsuraci/Suraci-et-al-](https://github.com/jsuraci/Suraci-et-al-MammalLifeHistory)
629 [MammalLifeHistory](https://github.com/jsuraci/Suraci-et-al-MammalLifeHistory).

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933 **Figure legends:**

934 **Figure 1.** Continental-scale assessment of mammal responses to human disturbance.

935 (a) Locations of 61 camera trap projects across North America are shown. Projects ranged from
936 undeveloped but heavily used protected areas (i.) through mosaics of developed and undeveloped
937 land (ii.) to urban centers (iii.). Within each project, camera sites spanned a gradient of both (b)
938 human presence and (c) human footprint. The color of each camera site (point) in b and c
939 represents human detections per day and the Human Footprint Index value, respectively, at that
940 location (both color gradients on the log scale). Mean \pm SD disturbance levels are shown for the
941 three example projects.

942

943 **Figure 2.** Human presence and footprint have contrasting impacts within and among mammal
944 species. Occupancy model coefficient estimates for the effects of human presence (square) and
945 human footprint (diamond) on (a) site occupancy and (b) intensity of site use. Error bars are 95%
946 (thin) and 80% (thick) Bayesian credible intervals. Coefficient estimates are grouped by trophic
947 guild (based on percent of vertebrate prey and scavenging in the diet, see Table S2).

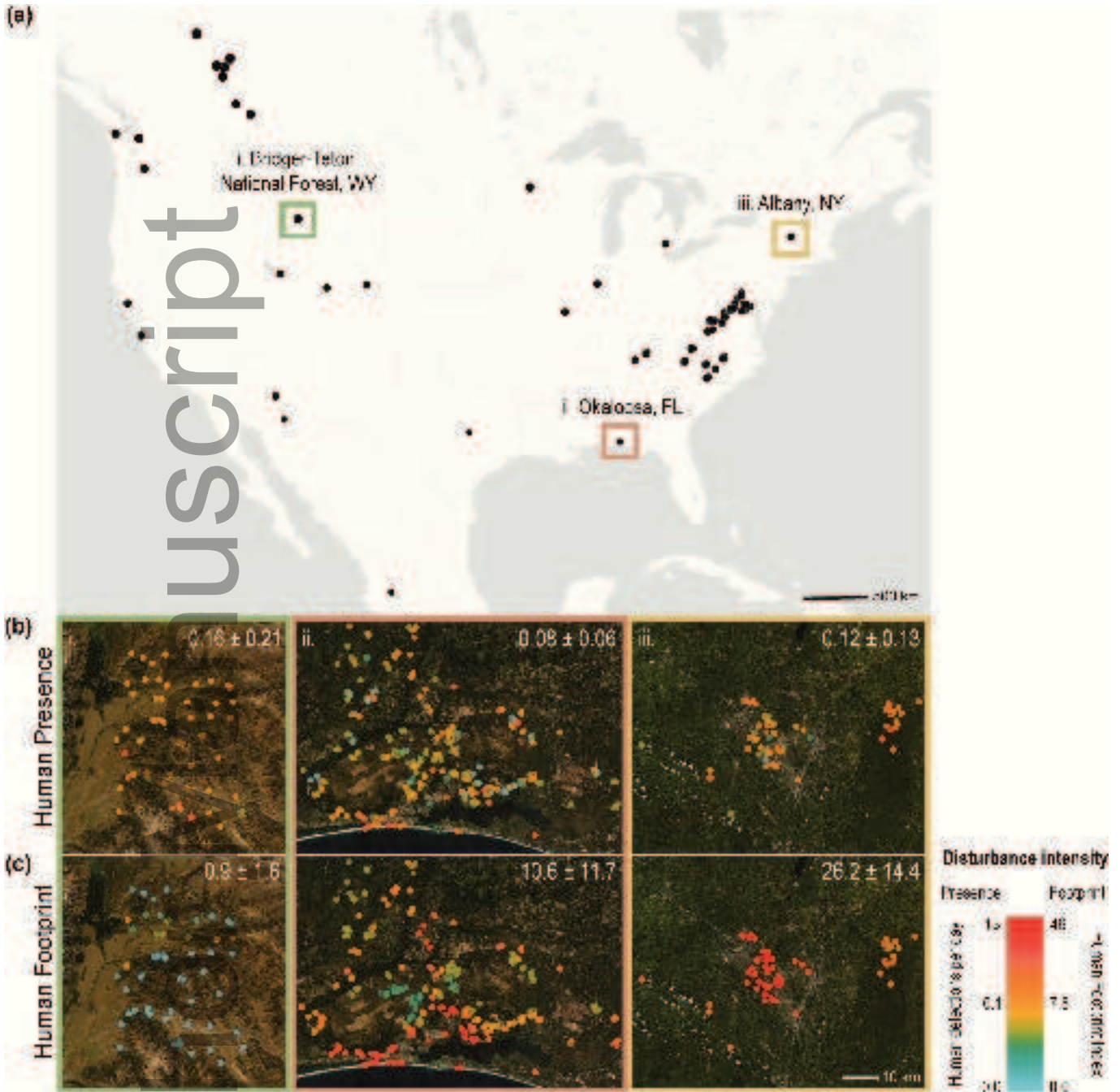
948

949 **Figure 3.** Non-linear effects of human disturbance. Occupancy model predictions for the change
950 in intensity of site use with increasing **(a)** human presence and **(b)** human footprint. Results are
951 shown for species for which models estimated a > 0.9 probability of a quadratic effect. Lines are
952 color coded by trophic guild, as defined in Figure 2.

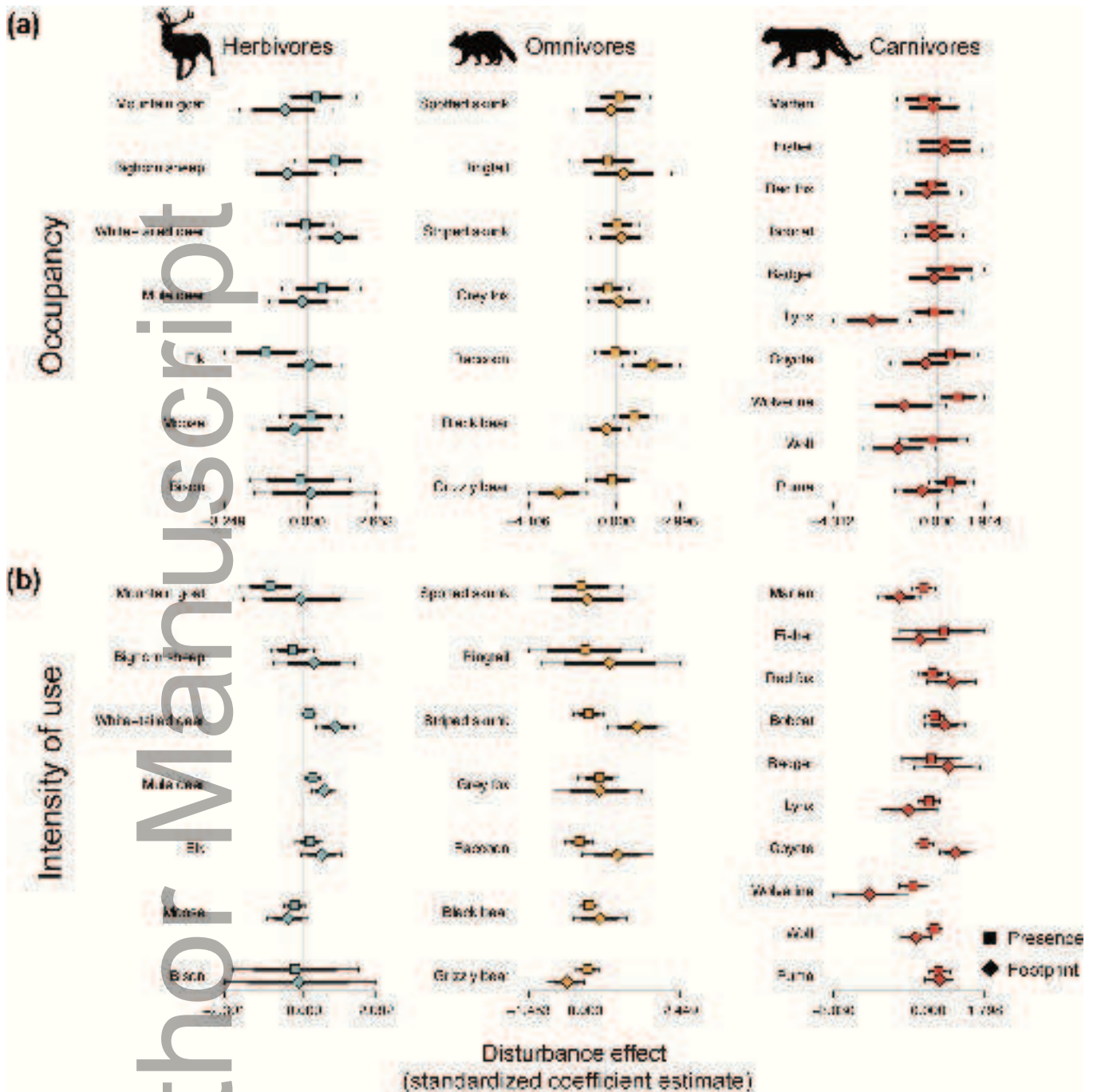
953

954 **Figure 4.** Species traits predict responses to human footprint. **(a)** Biplot of the principal
955 components analysis performed on species trait data, with each mammal species plotted based on
956 its values of the first two principal components (PC1 – larger body size and slower life history
957 and PC2 – greater space use and more carnivorous). Factor loadings for each trait are shown in
958 grey (see also Table S3). Mammal responses to human footprint were increasingly negative with
959 increasing values of PC1 for both **(b)** site occupancy and **(c)** intensity of use. Occupancy
960 responses to footprint **(d)** were also negatively associated with PC2. Data points in **b-d** are
961 population-level estimates of each species' response to human footprint, where values above
962 zero (dashed line) indicate a positive response (i.e., increased occupancy or intensity of use with
963 increasing footprint) and those below zero a negative response. Solid lines and shaded areas are
964 the estimated slope and 95% Credible Intervals from hierarchical linear models (see also Table
965 S4). Data in all plots are color-coded by trophic guild, as defined in Figure 2.

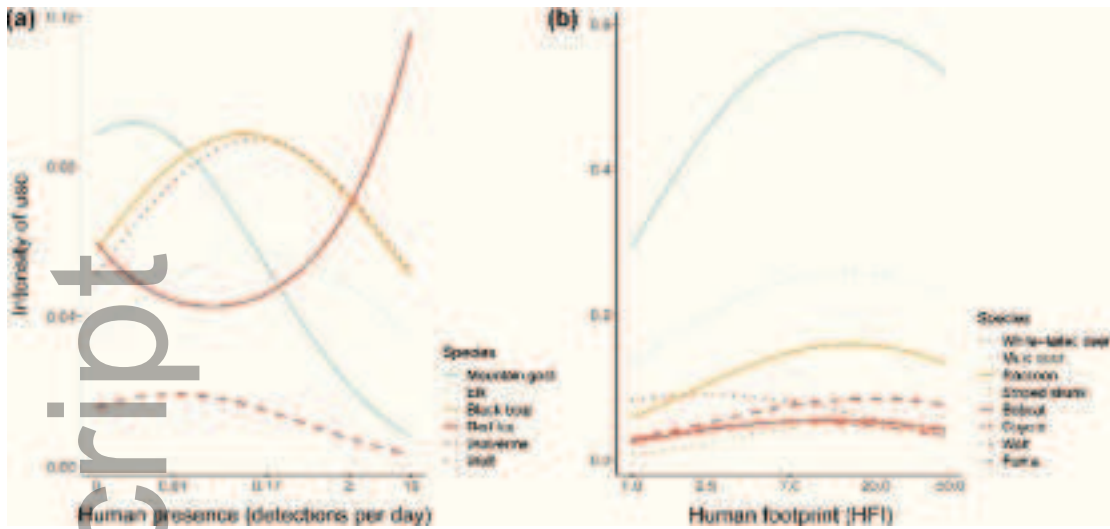
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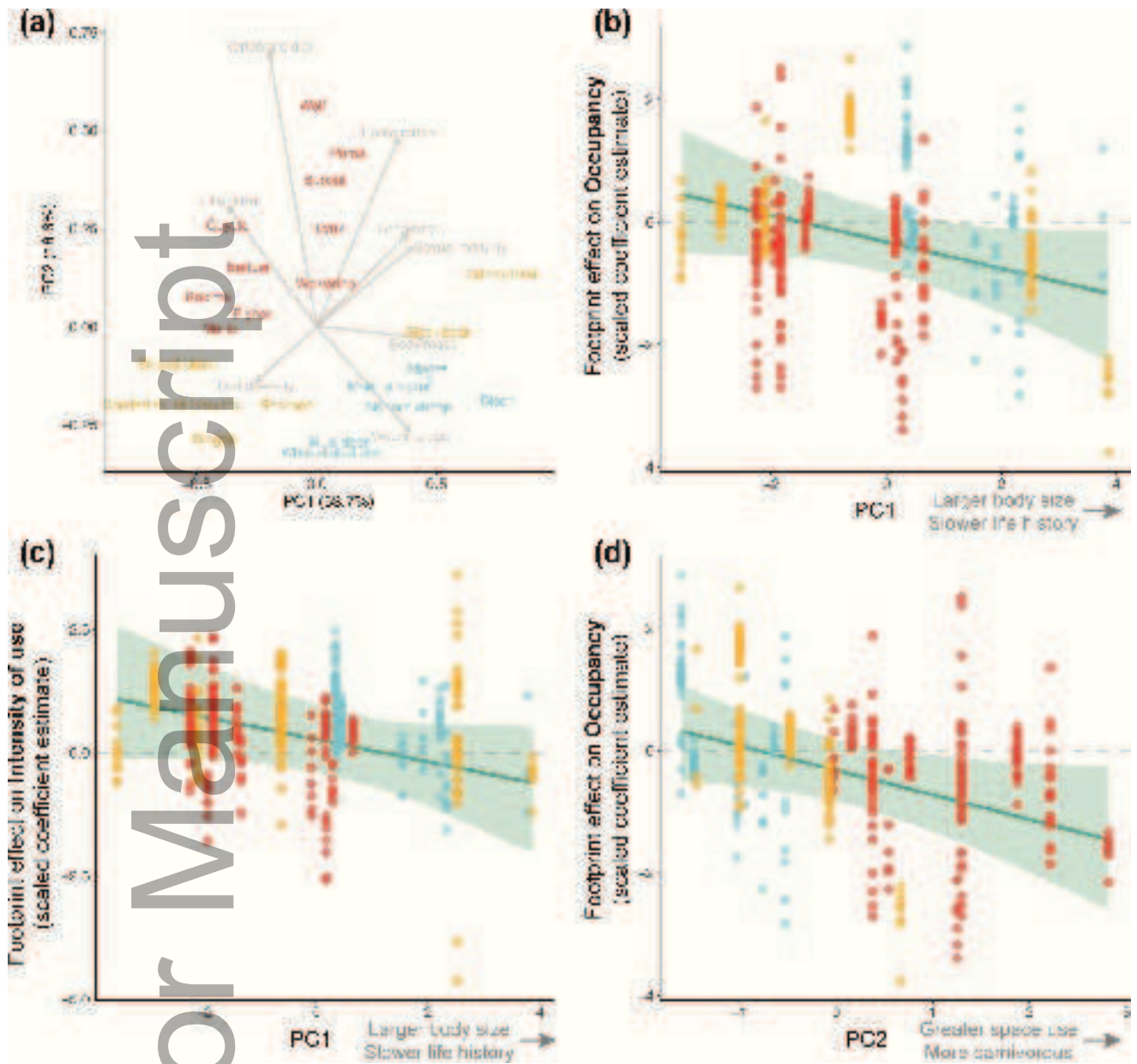


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