

MULTI-FREQUENCY, MULTI-POLARIZATION EXTERNAL CALIBRATION OF SIR-C/XSAR

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MULTI-FREQUENCY, MULTI-POLARIZATION EXTERNAL CALIBRATION OF SIR-C/XSAR

Abstract

In this final report a summary of our activities with regard to external calibration of the Shuttle Imaging Radar-C/XSAR (SIR-C/XSAR) is provided. The University of Michigan was involved in the development of calibration procedures and precision calibration devices to quantify the complex radar images with an accuracy of 0.5 dB in magnitude and 5 degrees in phase. Our research activities in the area of calibration of polarimetric SARs can be categorized into five areas: (1) development of calibration techniques for point targets, (2) development of polarimetric calibration techniques for distributed targets, (3) design of novel precision calibration targets, (4) development of polarimetric calibration techniques for SAR systems based on point and distributed targets, and (5) application of calibrated images for remote sensing of vegetation and soil moisture.

On April 9, and September 30, 1994 the SIR-C/XSAR instruments were launched twice, each time on an 11-day mission, aboard the NASA space shuttle Endeavor. During both missions several supersites received frequent overflights including the Raco supersite in the upper peninsula of Michigan. The Raco supersite, centered on 46.392 N. Latitude and 84.885 W. Longitude, is located in Chippewa County in the eastern part of Michigan's Upper Peninsula. The area under study and imaged in the SIR-C/X-SAR crossover region is approximately 20 km E-W and 20 km N-S. This site was imaged twelve times between April 9 and April 19 and twelve time between September 30 and October 10. A team consisting of scientists and graduate students were involved in deployment of targets and collection of ancillary data.

1 Introduction

In radar remote sensing, calibration of polarimetric radar systems is of great importance because the success of any inversion algorithm or any radar classifier depends directly on the accuracy of the measured data. To provide a quantitative value for the measured backscatter and remove the distortion from different channels of the radar caused by the active components and the antenna, an external calibration must be performed. The external calibration of a radar system involves a comparison of the measured response of the unknown target with the measured response of one or more calibration targets of the known radar cross section. For this purpose appropriate calibration targets and convenient calibration algorithms are required. A metallic sphere is a desirable calibration target because it is one of the few geometries for which an analytical RCS exist and its backscatter cross section is independent of orientation angle. However, the drawback of a metallic sphere is its

relatively small RCS. In calibration of images acquired from SAR using point calibration targets, the RCS of the calibration targets must be much larger than those of the surrounding pixels in the image. This requirement ensures that the radar return from the background is negligible relative to the return from the calibration target. In practice the RCS of calibration targets for imaging radars can be measured using the metallic sphere.

The following characteristics are desirable for calibration targets of imaging radars: (1) large RCS, (2) wide RCS pattern (being insensitive to orientation angle), (3) easily deployable (having small physical size), (4) stable RCS, and (5) insensitive RCS to its background (no interaction with its surrounding). Accurate measurement of scattering matrices of calibration targets for SARs requires accurate calibration techniques for point targets. Once the calibration targets are designed and fully characterized, a calibration algorithm for the SAR image based on the point calibration targets is required. The accuracy of the overall calibration procedure must then be checked by comparing the calibrated image to the measurement of an independent calibrated instrument such as a truck-mounted scatterometer system. Therefore a calibration procedure for distributed targets for nonimaging radars is also needed.

In any backscatter measurement of distributed targets the quantities of interest are the backscatter coefficients, which are the second moments of the scattered field per unit area. Calibration algorithms based on point targets for synthetic aperture radars must infer the calibration constant for backscattering coefficients from the RCS of the point targets. This process requires accurate knowledge of the SAR impulse function which is very difficult to characterize. To circumvent this problem calibration algorithms based on known distributed targets can be used. Such a calibration algorithm, however, provides the calibrated differential Mueller matrix of a region of the image as opposed to calibrated pixels. In what follows we briefly describe the calibration experiments and then we summarize the techniques and devices developed during the course of this investigation.

2 Calibration Experiment

In this section a brief description of our field activities during both SIR-C missions is given. Figure 1 shows the location of the Raco supersite where all of our calibration activities took place. The overall goal throughout the duration of the SIR-C/X-SAR project has been the development of image calibration algorithms by determining extracting the effects of system distortion parameters from the SIR-C polarimetric radar images. The objectives and methods used for assuring accurate calibration for both SIR-C missions were as follows:

1. Design and development of appropriate point calibration targets.

2. Characterization of RCS of point targets.
3. Deploy and monitor the point targets in the calibration site.
4. Development and assessment of polarimetric calibration algorithms using point point calibration targets.
5. Development of a procedure that would allow calibration of the imaging radars using distributed targets.
6. Deployment and measurement of backscatter for area extended targets with calibrated polarimetric scatterometer system.
7. Absolute calibration of SIR-C/X-SAR imagery acquired at L,C, and X bands
8. Accurate calibration over the geographical extent of the imaged scenes

During the SIR-C flights point calibration targets were distributed in open areas within the area imaged by the sensors. Both passive and active targets were deployed. For the April mission six 1.07 m trihedrals and one C-band PARC were located at the Rifle Range near the Raco Airfield. Two 2.4 m trihedrals were located at the Raco Airfield. Four 2.4 m trihedrals, one L-band single antenna polarimetric active radar calibrator (SAPARC), one C-band SAPARC, and one C-band PARC were located at Cryderman Field. See Figure 2 for the location of these fields.

Details regarding target positioning, including gps derived coordinates, target type, and measured elevation angles and azimuths, can be found in Table 1. The three target locations are depicted on the map SIR-C/X-SAR Test Stands and Calibration Sites. Targets were repositioned and/or monitored for accurate positioning before each overflight using electronic levels and Brunton compasses. Scatterometer measurements were made at L, C, and X-bands in conjunction with each SIR-C/X-SAR overpass. These measurements were made at Cryderman field.

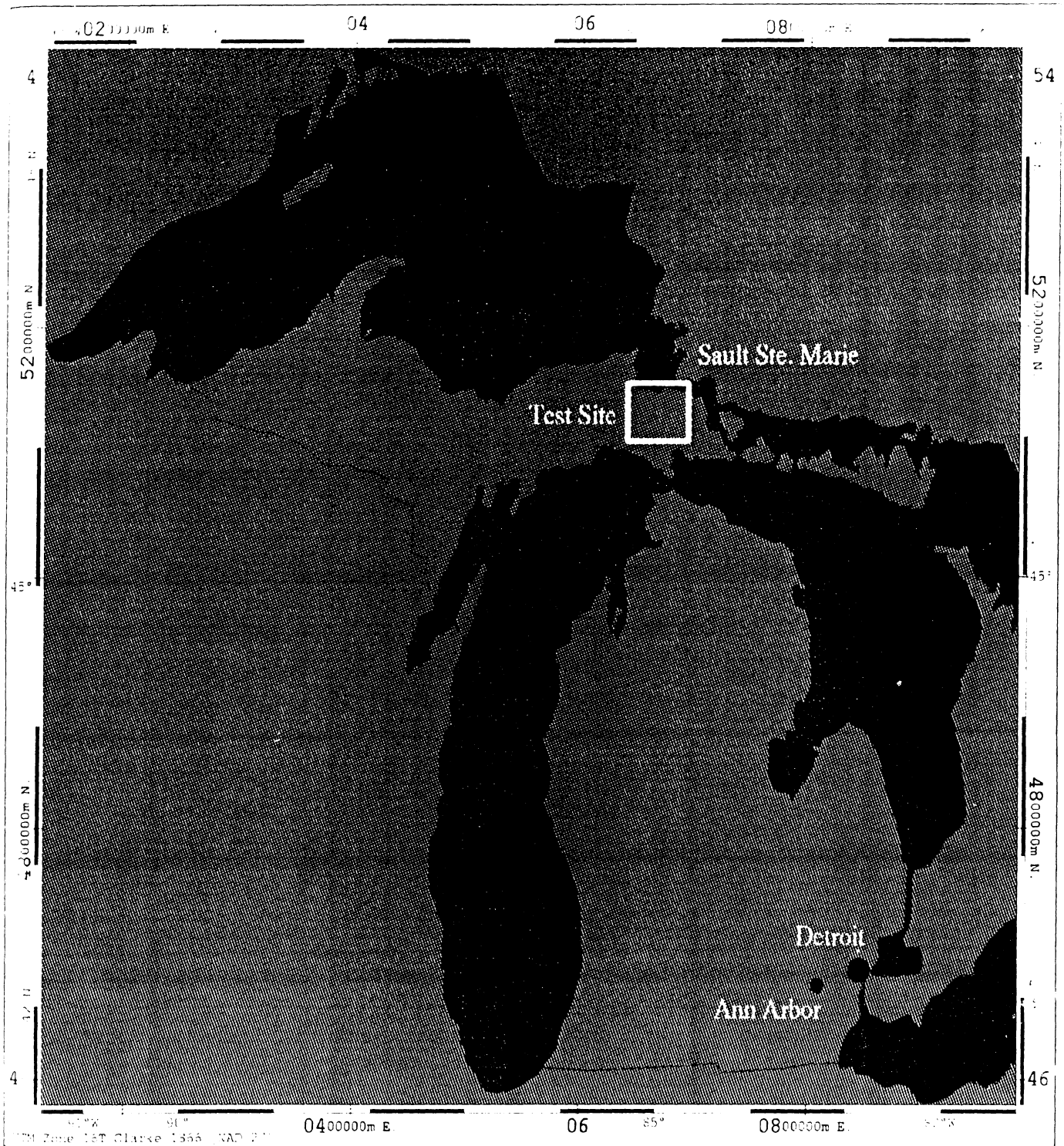
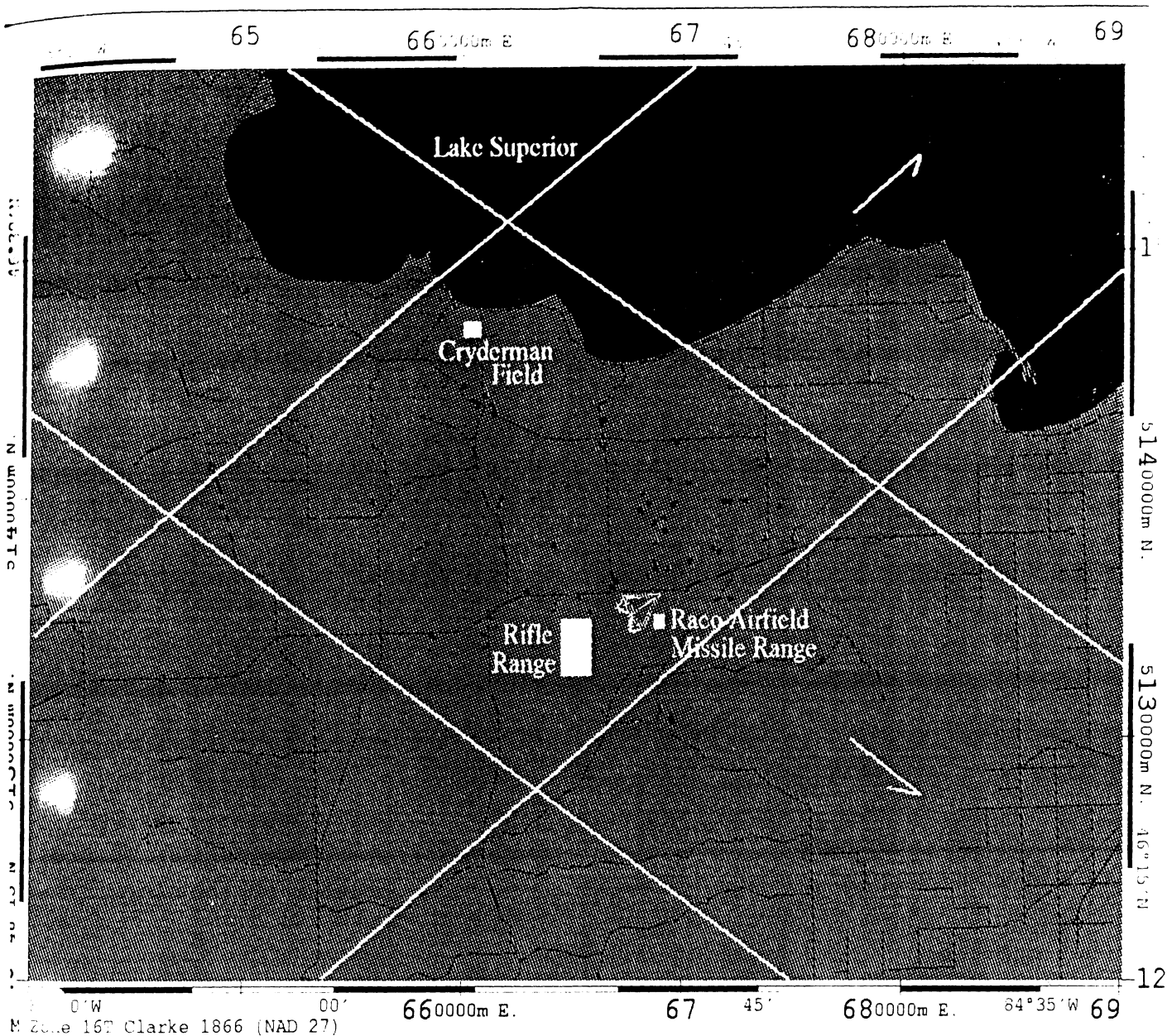


Figure 1: Raco SIR-C/XSAR supersite.



SIR-C Test Stands and Calibration Sites

Racó, Michigan Supersite

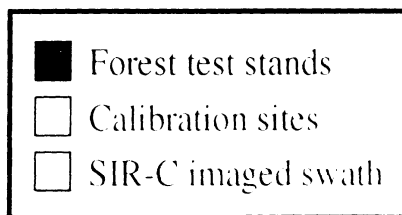
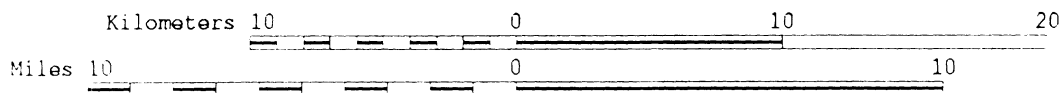


Figure 2: Location of test fields in Racó SIR-C/XSAR supersite.

Table 1: Calibration Targets

Calibration Target Plan at Raco Supersite April 1994 Mission		MET (dd/hh:mm:ss)		00/07:50:29		01/07:32:17							
Site	Target Name	Descendin g	Location		Target Type	Size (cm)	Max RCS (dBm ²)	Elevation Angles (From horizontal)	Azimuth (from True north)	Level (degrees)	Elevation Angles (From horizontal)	Azimuth (from True north)	Level (degrees)
			Latitude	Longitude									
		Local magnetic declination is 6.138° W											
All PARCs		1	1.0000										
		-1	-1.0000										
				Orbit No.									
				Data-Take No.									
				Ascending/Descending									
				North/South Looking (from Shuttle)									
				Look Angle (relative to SIR-C)									
				Local Incidence Angle									
				SIR-C Azimuth Heading (True North)									
				Target Azimuth (True North)									
				Target Looking (N/S)									
				Target Azimuth (Mag. North)									
RIFLERANGE	T2-1	A/D	46.3337	-84.8593	Trihedral	107		30.5	128.9	1.7	30.7	127.9	0.8
	T2-2	A/D	46.3360	-84.8575	Trihedral	107		29.2	128.9	1.1	15.6	155.9	16.6
	T2-3	A/D	46.3453	-84.8497	Trihedral	107		29.6	127.9	5.8	7.5	152.9	15.7
	T2-4	A/D	46.3452	-84.8512	Trihedral	107		27.2	124.9	1.4	29.6	129.9	0.4
	T2-5	A/D	46.3481	-84.8487	Trihedral	107		30.0	128.9	1.3	30.5	128.9	1.0
	T2-6	A/D	46.3506	-84.8500	Trihedral	107		31.2	127.9	-0.5	28.7	129.9	0.1
	P4	A/D	46.3362	-84.8592	C-PARC #2		42.4	31.4	127.4	0.1	30.1	128.9	0.8
RACO AIRFIELD	T1-5	A/D	46.3468	-84.8058	Trihedral	240		30.3	128.9	0.6	29.8	128.9	0.2
	T1-6	A/D			Trihedral	240							
CRYDEFMAN FIELD	T1-1	A/D	46.4591	-84.9070	Trihedral	240		31.0	126.9	0.0	30.4	127.9	0.0
	T1-2	A/D	46.4562	-84.9093	Trihedral	240		31.5	128.9	1.1	30.2	127.9	1.4
	T1-3	A/D	46.4561	-84.9130	Trihedral	240		31.3	125.9	0.5	31.6	127.9	0.3
	T1-4	A/D	46.4571	-84.9152	Trihedral	240		31.0	126.9	0.8	31.4	126.9	0.7
	P1	A/D	46.4578	-84.9104	L-SAPARC			32.1	125.9	1.0	19.9	127.9	0.4
	P2	A/D	46.4597	-84.9102	C-SAPARC			?	?	?	20.2	128.9	yes
	P3	A/D	46.4583	-84.9126	C-PARC #1		44.5	?	?	?	19.4	128.9	0.3
		Date		Saturday		Saturday		Saturday		Sunday		Sunday	
		Day		9-Apr		9-Apr		9-Apr		10-Apr		10-Apr	
		Time		14:55:29		14:55:29		14:55:29		14:32:17		14:32:17	

Site	Target Name	06/05:55:33			06/23:25:12			07/05:34:57			08/05:13:57		
		Elevation Angles (From horizontal)	Azimuth (from True north)	Level (degrees)	Elevation Angles (From horizontal)	Azimuth (from True north)	Level (degrees)	Elevation Angles (From horizontal)	Azimuth (from True north)	Level (degrees)	Elevation Angles (From horizontal)	Azimuth (from True north)	Level (degrees)
RIFLE RANGE	T2-1	29.6	312.9	0.5	11.0	232.9	0.0	-	-	-	-	-	
	T2-2	29.9	313.4	0.5	10.6	231.9	0.0	-	-	-	-	-	
	T2-3	29.8	311.4	0.4	10.8	232.9	0.2	-	-	-	-	-	
	T2-4	-	-	-	10.9	233.9	0.2	9.7	311.9	0.4	10.4	309.9	
	T2-5	30.0	311.9	0.3	10.3	232.9	0.2	9.9	311.9	0.1	9.7	312.9	
	T2-6	-	-	-	10.6	231.9	0.4	9.7	310.9	0.4	9.6	310.9	
P4	31.7	311.9	0.0	41.8	232.9	0.0	37.3	311.9	0.0	41.0	313.9		
RACO AIRFIELD	T1-5	29.3	313.4	0.4	9.3	234.7	0.3	-	-	-	-	-	
	T1-6	30.4	311.9	0.1	10.6	232.7	0.3	10.7	313.9	1.0	18.7	317.9	
CRYDERMAN FIELD	T1-1	-	-	-	12.2	223.9	2.9	11.0	311.9	0.4	10.5	311.9	
	T1-2	-	-	-	-	-	-	9.4	314.9	2.3	10.8	318.9	
	T1-3	29.5	312.9	0.0	15.1	230.9	1.6	-	-	-	-	-	
	T1-4	30.0	313.9	0.4	9.9	232.9	1.0	-	-	-	-	-	
	P1	31.0	310.9	<2.0	41.7	232.9	2.0	?	?	?	42.0	312.9	
P2	31.4	310.9	ok	40.9	227.9	ok	37.0	312.9	ok	42.1	312.9		
P3	32.4	313.9	0.4	41.2	232.9	0.3	37.6	311.9	0.5	41.4	313.9		

Friday
15-Apr
13:00:33

Saturday
16-Apr
6:30:12

Saturday
16-Apr
12:39:57

Sunday
17-Apr
12:16:57

Site	Target Name	Elevation Angles (From horizontal)	Azimuth (from True north)	Level (degrees)	Elevation Angles (From horizontal)	Azimuth (from True north)	Level (degrees)
RIFLE RANGE	T2-1						
	T2-2						
	T2-3						
	T2-4	10.1	311.9	-0.3	10.6	52.9	0.1
	T2-5	9.6	312.4	-0.1	10.4	52.9	0.0
	T2-6	9.6	311.9	-0.6	10.6	52.9	0.1
	P4	43.8	311.9	0.5			
RACO AIRFIELD	T1-5	10.0	59-6.14	0.0	10.0	52.9	0.0
	T1-6	10.0	311.9	0.0			
CRYDEFMAN FIELD	T1-1	10.4	310.9	0.4			
	T1-2	10.4	318.9	1.5			
	T1-3	11.4	51.9	0.4			
	T1-4	10.8	51.9	1.2			
	P1	44.9	312.9	0.3			
	P2 P3	44.2 43.8	313.9 312.9	7 0.6			

09/04:52:22

09/22:20:59

150
150.2
D
N
42.55
44.308
132.785
311.86
S
318

162
162.3
A
S
47.325
49.67
54.17
232.86
N
239

Monday
18-Apr
11:57:22

Tuesday
19-Apr
5:25:59

In the October mission 21 calibration targets were positioned. Six 1.07 m trihedrals, one L-band SAPARC, one C-band SAPARC, and four 2.4 m trihedrals were located at the Rifle Range near the Raco Airfield. Two C-band PARCS were located at the Raco Airfield. Four 2.4 m trihedrals were located at Cryderman Field. In addition, three distributed targets areas were established at the Rifle Range. Details regarding point target positioning, including GPS derived coordinates, target type, and measured elevation angles and azimuths, can be found in Table 2 (October SIR-C/X-SAR Calibration Point Targets). Point targets were repositioned and/or monitored for accurate positioning before each overflight using electronic levels and Brunton compasses. During the 11-day mission, polarimetric scatterometers were used to collect data at L, C, and X-bands in conjunction with each SIR-C/X-SAR overpass. This data is used to define the average Mueller matrix of distributed targets. Three distributed targets, or surfaces, were defined and located at the rifle range. These were approximately 100 m X 100 m. Each plot (S1 to S3) had a distinctive surface roughness with RMS roughness ranging from 2 to 6 cm. (Tables 8 and 9). The locations of the distributed targets are documented on the map SIR-C/X-SAR October 1994 Rifle Range Distributed and Point Target Locations.

The details of experimentations and results are reported in [1] and [2] which are also given in Appendix A.

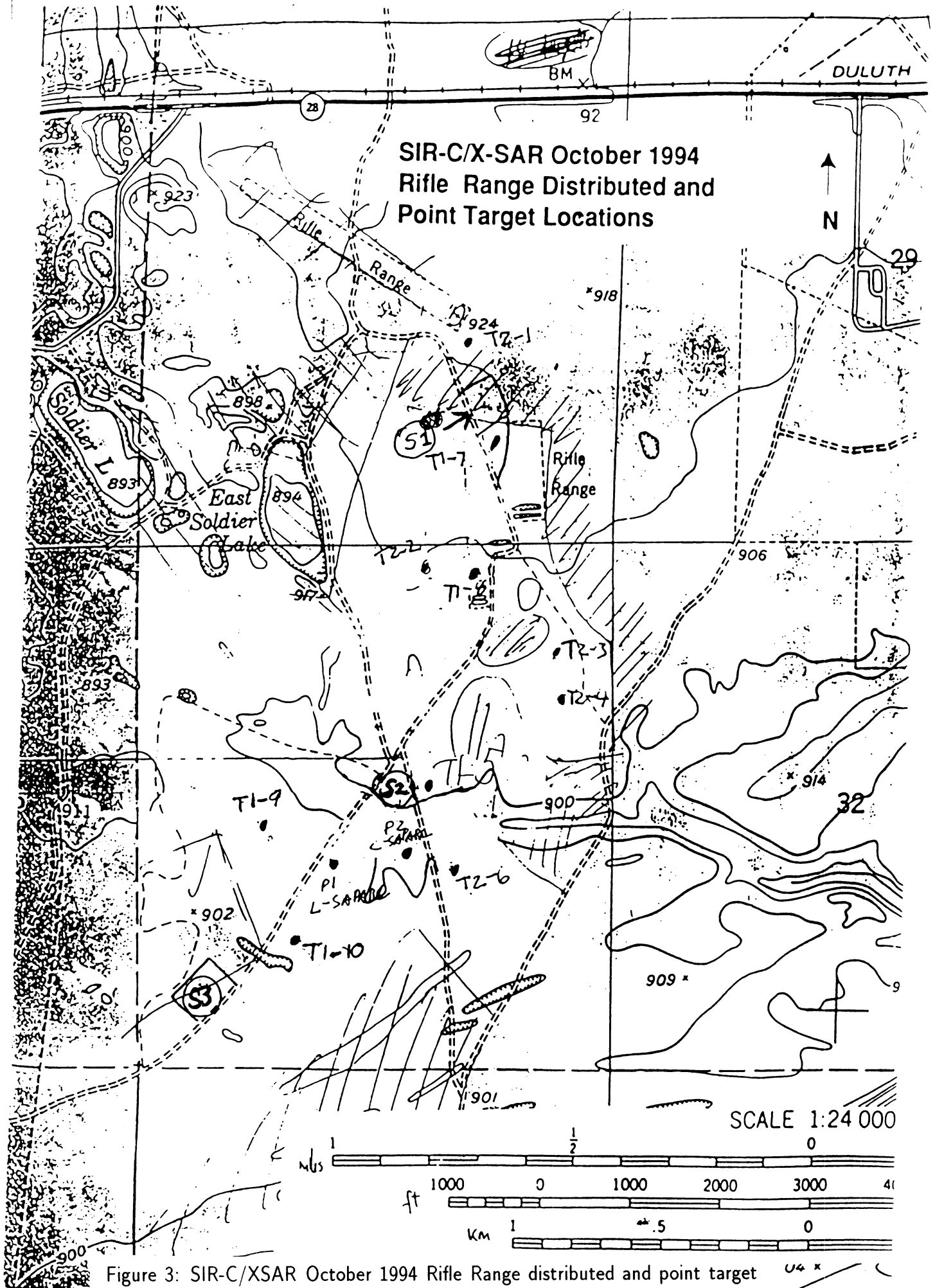


Figure 3: SIR-C/XSAR October 1994 Rifle Range distributed and point target locations.

1 cable 2

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Table 6: October SIR-C/X-SAR Calibration Point Targets

Site	Target Name	Ascending/ Descending	Latitude	Longitude	Target Type	Size (cm)	Max RCS (dBm ²)	Elevation Angles (From horizontal)	Azimuth (from true north)	Level (degrees)	Temp (°C) or Atten. (dB)	Elevation Angles (From horizontal)	Azimuth (from true north)
				Location									
Rifle Range	P1	A/D	46.3481	-84.8487	L-SAPARC			30.0	134.0	0.0	16°	21.1	134.0
	P2	A/D	46.3369	-84.8519	C-SAPARC			30.0	134.0	0.0	16°	21.2	134.0
	T1-7	A/D	46.3360	-84.8575	Trihedral	240		29.9	134.0	0.2		29.8	134.0
	T1-8	A/D	46.3453	-84.8497	Trihedral	240		30.2	135.0	0.1		29.9	134.0
	T1-9	A/D	46.3368	-84.8595	Trihedral	240		29.6	134.0	0.2		30.0	135.0
	T1-10	A/D	46.3506	-84.8500	Trihedral	240		30.3	135.0	0.3		30.1	135.0
	T2-1	A/D	46.3337	-84.8593	Trihedral	107		29.9	135.0	0.3		29.8	134.0
	T2-2	A/D	46.3452	-84.8512	Trihedral	107		29.8	134.0	0.0		29.9	134.0
	T2-3	A/D	46.3422	-84.8461	Trihedral	107		30.0	135.0	0.1		30.0	135.0
	T2-4	A/D	46.3406	-84.8457	Trihedral	107		29.7	135.0	0.2		29.8	135.0
	T2-5	A/D	46.3393	-84.8519	Trihedral	107		29.8	134.0	0.0		30.0	134.0
	T2-6	A/D	46.3365	-84.8503	Trihedral	107		29.9	134.0	0.2		29.9	134.0
Racco Airfield	P3	A/D	46.3568	-84.8048	C-PARC #1		44.5	31.8	134.0	0.4		21.1	134.0
	P4	A/D	46.3508	-84.8196	C-PARC #2		42.4	31.8	134.0	0.5		21.2	134.0
Cryderman	T1-1	A/D	46.4591	-84.9070	Trihedral	240		30.0	136.0	0.6		30.7	136.07
	T1-2	A/D	46.4562	-84.9093	Trihedral	240		30.5	133.5	0.4		30.57	133.57
	T1-3	A/D	46.4561	-84.9130	Trihedral	240		29.9	134.0	0.4		29.97	134.07
	T1-4	A/D	46.4571	-84.9152	Trihedral	240		30.2	134.5	0.1		30.27	134.57
			Local Day						Friday				Saturday
			Local Date						30-Sep				1-Oct
			Local Time						15:06:29				14:47:51

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Level (degrees)	Temp (°C) or Atten. (dB)	Site	Target Name	Ascending/Descending	Latitude	Longitude	Target Type	Size (cm)	Max. RCS (dBm ²)	Elevation Angles (From horizontal)	Azimuth (from true north)	Level (degrees)	Temp (°C) or Atten. (dB)
0.0		Rifle Range	P1	A/D	46.3481	-84.8487	L-SAPARC			22.2	59.5	0.1	5°
0.0	3 dB pad		P2	A/D	46.3369	-84.8519	C-SAPARC			21.9	59.0	yes	5°
0.2			T1-7	A/D	46.3360	-84.8575	Trihedral	240		-	180° off	-	
0.1			T1-8	A/D	46.3453	-84.8497	Trihedral	240		-	180° off	-	
0.1			T1-9	A/D	46.3368	-84.8595	Trihedral	240		-	180° off	-	
0.3			T1-10	A/D	46.3506	-84.8500	Trihedral	240		-	180° off	-	
0.1			T2-1	A/D	46.3337	-84.8593	Trihedral	107		-	180° off	-	
0.1			T2-2	A/D	46.3452	-84.8512	Trihedral	107		-	180° off	-	
0.1			T2-3	A/D	46.3422	-84.8461	Trihedral	107		-	180° off	-	
0.0			T2-4	A/D	46.3406	-84.8457	Trihedral	107		-	180° off	-	
0.2			T2-5	A/D	46.3393	-84.8519	Trihedral	107		-	180° off	-	
0.2			T2-6	A/D	46.3365	-84.8503	Trihedral	107		-	180° off	-	
0.2		Raco Airfield	P3	A/D	46.3568	-84.8048	C-PARC #1		44.5	22.0	239.0	0.8	
0.6			P4	A/D	46.3508	-84.8196	C-PARC #2		42.4	22.0	240.0	0.5	
0.67		Cryderman	T1-1	A/D	46.4591	-84.9070	Trihedral	240		-	180° off	-	drizzle
0.47			T1-2	A/D	46.4562	-84.9093	Trihedral	240		-	180° off	-	
0.47			T1-3	A/D	46.4561	-84.9130	Trihedral	240		-	180° off	-	
0.17			T1-4	A/D	46.4571	-84.9152	Trihedral	240		-	180° off	-	
											Tuesday 4-Oct 7:41:32		

Level (degrees)	Temp (°C) or Atten. (dB)	Elevation Angles (From horizontal)	Azimuth (from true north)	Level (degrees)	Temp (°C) or Atten. (dB)	Site	Target Name	Ascending/Descending	Latitude	Longitude	Target Type	Size (cm)	Max RCS (dBm ²)
0.1	12°	38.1	59.0	0.1		Rifle Range	P1	A/D	46.3481	-84.8487	L-SAPARC		
Yes	14°, 3 dB pad	38.1	59.0	Yes			P2	A/D	46.3369	-84.8519	C-SAPARC	240	
-	-	-	-	-			T1-7	A/D	46.3360	-84.8575	Trihedral	240	
-	-	-	-	-			T1-8	A/D	46.3453	-84.8497	Trihedral	240	
-	-	-	-	-			T1-9	A/D	46.3368	-84.8595	Trihedral	240	
-	-	10.0	59.0	0.3			T1-10	A/D	46.3506	-84.8500	Trihedral	240	
-	-	10.1	58.5	0.1			T2-1	A/D	46.3337	-84.8593	Trihedral	107	
-	-	9.8	59.0	0.3			T2-2	A/D	46.3452	-84.8512	Trihedral	107	
-	-	-	-	-			T2-3	A/D	46.3422	-84.8461	Trihedral	107	
-	-	9.2	59.0	0.4			T2-4	A/D	46.3406	-84.8457	Trihedral	107	
-	-	-	-	-			T2-5	A/D	46.3393	-84.8519	Trihedral	107	
-	-	-	-	-			T2-6	A/D	46.3365	-84.8503	Trihedral	107	
0.5	-	38.0	239.0	0.7		Raco Airfield	P3	A/D	46.3588	-84.8048	C-PARC #1		44.5
0.4	-	38.1	239.0	0.6			P4	A/D	46.3508	-84.8196	C-PARC #2		42.4
0.1	-	9.9	59.0	0.1		Cryderman	T1-1	A/D	46.4591	-84.9070	Trihedral	240	
0.1	-	10.67	59.0	0.1			T1-2	A/D	46.4562	-84.9093	Trihedral	240	
0.1	-	29.57	318.0	0.1			T1-3	A/D	46.4561	-84.9130	Trihedral	240	
0.1	-	33.37	322.07	1.47			T1-4	A/D	46.4571	-84.9152	Trihedral	240	
			Thursday						Local Day				
			6-Oct						Local Date				
			7:01:44						Local Time				

table6 formatted

Elevation Angles (From horizontal)		Azimuth (from true north)		Level (degrees)		Temp (°C) or Atten. (dB)		Elevation Angles (From horizontal)		Azimuth (from true north)		Level (degrees)		Site		Target Name		Ascending/Descending		Latitude		Longitude		Target Type	
		6								7														MET (dd)	
		5:55:31								23:25:02														Orbit No.	
		102								114														Data Take No.	
		102:41								114.1														Ascending/Desce	
		D								A														North/South Loo	
		N								S														Look Angle (relat	
		32.5								41.976														Local Incidence A	
		33.818								43.656														SIR-C Azimuth H	
		131.876								53.667														Target Azimuth C	
		311.862								232.862														Target Looking C	
		S								N														Target Azimuth C	
		318								239														Location	
Elevation Angles (From horizontal)		Azimuth (from true north)		Level (degrees)		Temp (°C) or Atten. (dB)		Elevation Angles (From horizontal)		Azimuth (from true north)		Level (degrees)		Site		Target Name		Ascending/Descending		Latitude		Longitude		Target Type	
33.3		318.0		0.0	15°	43.7		43.7		59.0		0.1	11°	Rifle Range	P1		A/D		46.3481		-84.8487		L-SAPARC		
32.2		310.0		Yes	20°	43.7		43.7		59.0		Yes	13°		P2		A/D		46.3369		-84.8519		C-SAPARC		
29.9		318.0		0.3								0.1			T1-7		A/D		46.3360		-84.8575		Trihedral		
29.9		317.0		0.1		10.0		10.0		59.0		-			T1-8		A/D		46.3453		-84.8497		Trihedral		
-		-		-		-		-		-		-			T1-9		A/D		46.3368		-84.8595		Trihedral		
-		-		-		10.3		10.3		58.5		0.1			T1-10		A/D		46.3508		-84.8500		Trihedral		
-		-		-		10.0		10.0		58.5		0.1			T2-1		A/D		46.3337		-84.8593		Trihedral		
-		-		-		9.7		9.7		59.0		0.0			T2-2		A/D		46.3452		-84.8512		Trihedral		
29.6		318.0		0.1		-		-		-		-			T2-3		A/D		46.3422		-84.8461		Trihedral		
30.0		318.0		0.4		-		-		59.0		0.2			T2-4		A/D		46.3406		-84.8457		Trihedral		
30.1		318.0		0.2		-		-		-		-			T2-5		A/D		46.3393		-84.8519		Trihedral		
33.8		318.0		0.4		43.7		43.7		239.0		-		Raco Airfield	P3		A/D		46.3365		-84.8503		Trihedral		
9.9		59.0		0.1		43.8		43.8		239.0		0.2			P4		A/D		46.3568		-84.8048		C-PARC #1		
10.67		59.0		0.1		9.9		9.9		59.0		0.1		Cryderman	T1-1		A/D		46.4591		-84.9070		Trihedral		
29.57		318.0		0.1		10.6		10.6		59.0		0.1			T1-2		A/D		46.4562		-84.9093		Trihedral		
33.37		322.07		1.47		29.57		29.57		318.0		0.1			T1-3		A/D		46.4561		-84.9130		Trihedral		
		Thursday				33.37		33.37		322.0		1.47			T1-4		A/D		46.4571		-84.9152		Trihedral		
		6-Oct								Friday															
		13:11:31								7-Oct															
										6:41:02															

table6.formatted

Longitude	Target Type	Size (cm)	Max RCS (dBm ²)	Elevation Angles (From horizontal)	Azimuth (from true north)	Level (degrees)	Temp (°C) or Atten. (dB)	Elevation Angles (From horizontal)	Azimuth (from true north)	Level (degrees)	Temp (°C) or Atten. (dB)
-84.8487	L-SAPARC			41.2	318.0	0.0	4.5°	41.2	318.0	0.0	5°, 3 dB pad XMIT
-84.8519	C-SAPARC										
-84.8575	Trihedral	240		41.2	318.0	0.1	5°	41.2	318.0	0.0	5°, 3 dB pad RCV
-84.8497	Trihedral	240		12.4	321.5	0.3		10.3	318.0	0.1	
-84.8595	Trihedral	240		9.9	317.5	0.0		9.9	318.0	0.0	
-84.8500	Trihedral	240		9.9	317.5	0.1		10.1	317.5	0.0	
-84.8593	Trihedral	240		10.2	316.0	0.1		10.6	318.0	0.2	
-84.8512	Trihedral	107		10.0	318.0	0.1		10.0	318.5	0.1	
-84.8461	Trihedral	107		10.0	317.5	0.1		9.9	317.5	0.1	
-84.8457	Trihedral	107		10.0	318.0	0.0		10.0	318.0	0.1	
-84.8519	Trihedral	107		9.9	318.0	0.2		10.0	318.0	0.0	
-84.8503	Trihedral	107		9.8	318.0	0.1		9.9	318.0	0.0	
-84.8048	C-PARC #1		44.5	41.2	318.0	0.4		41.2	318.0	0.5	
-84.8196	C-PARC #2		42.4	41.2	318.0	0.9		41.2	318.0	0.3	
-84.9070	Trihedral	240		10.0	318.0	0.2		10.1	318.0	0.1	
-84.9093	Trihedral	240		10.1	318.0	0.1		10.2	318.0	0.1	
-84.9130	Trihedral	240		10.0	318.0	0.1		9.9	318.0	0.1	
-84.9152	Trihedral	240		10.0	318.0	0.1		10.1	318.0	0.0	
					Sunday				Monday		
					9-Oct				10-Oct		
					12:07:57				11:46:20		
					AIR-SAR Data						

3 SUMMARY OF ACCOMPLISHMENTS

As mentioned, accurate calibration of polarimetric imaging radars involves many steps. Towards this goal, we have focused our activities in four areas: (1) development of calibration algorithms for the purpose of characterizing the scattering matrices of the SAR calibration targets, (2) design and characterization of precision calibration targets, (3) development of a calibration technique for measurement of differential Mueller matrices of distributed targets which is required for cross calibration and calibration methods based on known distributed targets, and (4) development of calibration algorithms for imaging radars. A summary of the work accomplished in each area is given next.

3.1 Calibration Algorithms For Point Targets

Three distinct algorithms have been developed for the measurement of scattering matrices of point targets. Our objective in the development of these algorithms was to characterize the scattering matrices of SAR calibration targets with a high degree of accuracy by comparing them against a precision metallic sphere. The choice of the calibration algorithm depends on the particular system and the accuracy-versus-complexity criterion. For example, in the calibration technique which will be referred to as IACT (isolated antenna calibration technique) only a metallic sphere and any other target with relatively high cross-polarized component are required to determine the radar distortion parameters [4]. The scattering matrix of the depolarizing target need not be known. This technique is very convenient, however it is only applicable to radar systems with low cross-talk. Refer to Appendix B for a detailed explanation of the procedure.

Another calibration technique that is not based on any *a priori* knowledge of the system was also developed [4]. In this technique the transmit and receive distortion matrices of the radar system are characterized using three independent targets with known scattering matrices. Although this method is very general, its drawback is the errors caused by orienting the calibration targets with respect to the antenna system coordinate frame (see Appendix B). Using the property of reciprocal passive antennas, a convenient calibration technique was later developed that determines the distortion parameters of a radar system using only a metallic sphere [5]. This technique will be referred to as STCT (single target calibration technique). Using this calibration technique the scattering matrix elements of a target can be measured with an accuracy of 0.5 dB in magnitude and ± 5 degrees in phase. The calibration procedure is described in Appendix B.

3.2 Measurement and Calibration of Differential Mueller Matrices

The overall accuracy of a calibration procedure for imaging radars can be assessed if an independent accurate measurement of an area within the image were available. With this purpose in mind, we developed an algorithm for backscatter measurement of uniform distributed targets using a scatterometer system. A major difficulty in the Mueller matrix measurement of distributed targets is the lack of known distributed targets, and therefore the calibration coefficient must be inferred from point calibration targets. This process is rather complex, particularly when the radar distortions vary over the illuminated area. This is the case when a scatterometer is used for the measurement. Amplitude and phase variation of the radiation pattern of the scatterometer antenna causes variation in the distortion parameters of the radar over its illuminating area. In this case the distortion parameters must be determined over the entire main beam of the radar system using point calibration targets in order to find the calibration coefficient for distributed targets [6].

Using this procedure, the differential Mueller matrix of an area can be determined, which in turn can be used to calibrate a polarimetric SAR. In such a calibration technique, it can be shown that the impulse response of the SAR (ambiguity function) need not be determined. The detailed procedure and experimental results of the Mueller matrix measurement is given in Appendix C.

3.3 Characterization and Design of Precision Active Calibration Targets

There are significant differences between point calibration targets used for conventional radars and imaging radars. These differences are the direct result of the target deployment configuration. For imaging radars, the calibration targets are placed on the ground (in the presence of the distributed target), whereas in the case of conventional radars the calibration targets are placed in free space. The success of an external calibration procedure relies on the knowledge of the scattering matrix of the calibration targets. In order to reduce the effect of background (direct contribution) on the RCS of a calibration target for imaging radars, it is required that the RCS of the target be much larger than that of the surrounding background.

Calibration targets, in general, can be categorized into two major groups: (1) passive calibrators and (2) active calibrators [7]. Passive calibrators are more stable and reliable than their active counterparts, however, their large physical dimensions is their major drawback. Trihedral corner reflectors are the most widely used targets for imaging radars because of their high RCS and wide RCS pattern. In recent years, polarimetric active radar calibra-

tors (PARC's) have been used extensively and are planned to be employed for external calibration of the SIR-C/XSAR mission. In addition to high RCS and wide RCS pattern, PARC's are desirable for their relatively small physical size. In June 1990, the scattering matrices of JPL L- and C-band PARC's were measured and the results were reported [8]. The measurements were conducted over a wide range of incidence angles in azimuth, elevation, 45° , and 135° planes. It was found that the RCS patterns of the L-band PARC's whose antennas were in close proximity, were unsymmetric and the phase patterns exhibited rapid fluctuations. These undesirable characteristics prompted design of a novel single antenna PARC' (see Appendix D). The new PARC' can provide a very high RCS while having a relatively small physical size. We are currently in the process of manufacturing two L-band and two C-band single antenna PARC's (SAPARC'). The features and performance characteristics of a C-band SAPARC' was reported [9].

3.4 Analysis, Design, and Construction of an Optimum Corner Reflector

PARC's are excellent calibration targets in regard to large RCS and wide RCS pattern requirements. However, the scattering matrix of a PARC is singular and can only provide three equations for the unknown distortion parameters of a radar instead of four [10]. Besides, in order to check the validity of a calibration algorithm, independent known targets are required. Trihedral corner reflectors are suitable for this purpose. Large ordinary trihedrals are not very reliable for calibration. The frame of these trihedrals are not sturdy enough and causes geometrical deformations. Obviously construction of a sturdy trihedral with such large dimensions renders them practically undeployable. The other problem is the coherent interaction of the trihedral with the ground. The reflected wave from the surface in front of the trihedral scatters off of the lower panel edge and returns to the radar. Also rays from the scatterers on the ground may enter the trihedral cavity and reflect back towards the radar. Basically, the image of these scatterers in the trihedral are visible. This interaction occurs with the upper portion of the side panels. The significance of this interaction depends on the tilt angle of the lower panel, since the lower panel can shadow some of the scatterers in front of the trihedral. RCS analysis of trihedral corner reflectors shows that only a portion of the trihedral is contributing to the RCS. A new class of corner reflectors that does not suffer from the aforementioned problems were designed and constructed. These corner reflectors are suitable for calibration of imaging radar systems [11] (also see Appendix E).

3.5 Calibration Algorithms for Polarimetric SAR Systems

We have developed two approaches for calibration of polarimetric synthetic aperture radars. The first approach is based on point calibration targets [12]. In this method the polarimetric ambiguity function of the SAR is estimated from a trihedral in the image and using a model similar to the one used in STCT, the calibration constant and distortion parameters of the SAR can be obtained. Accuracy of this calibration directly depends on the knowledge of the scattering matrix of the trihedral calibration target. The detailed procedure and actual implementation of this technique is given in Appendix F. In the second approach a uniform distributed target is used as a calibration target [13]. The differential Mueller matrix of this target can be characterized using the scatterometer systems, and the radar distortion parameters and the calibration constant can be obtained directly from this algorithm. The outcome of this calibration algorithm is the calibrated differential Mueller matrices of the uniform regions in the image. The advantages offered here are as follows: (1) point targets are not needed and the calibration is not influenced by the interaction of the targets with their backgrounds, (2) estimation of polarimetric ambiguity function is not required, (3) since the differential Mueller matrix is calculated from many independent measurements the effect of noise and measurement errors are minimized. In Appendix F this procedure is explained in detail.

3.6 Cross Calibration Experiment

In June 1991 a cross calibration experiment using JPL AirSAR and the University of Michigan scatterometer system was conducted to assess the accuracy of SAR calibration using point targets. The results of this experiment is reported in Appendix G. Four different uniform distributed targets, three rough surfaces with different roughness and a hay field, were measured with both the scatterometers and the JPL SAR at three different incidence angles. After processing the data, significant discrepancies between the two measurements were observed. Two factors are believed to be responsible for these discrepancies, both related to the trihedrals used in the experiment. One is the effect of coherent and incoherent interaction of the ground with the trihedrals. These factors affect the scattering matrix of the trihedrals used in the calibration. The second factor is the possible geometrical deformation of the trihedrals.

3.7 Applications

In the past two years we have examined the applications of calibrated polarimetric SARs in radar remote sensing of vegetation. First high fidelity scattering models for short vegetation was developed [13,14] and then inver-

sion algorithms were developed and physical parameters of vegetation were retrieved from calibrated polarimetric SARs [14,15]. Appendix H includes copies of these papers.

4 Students Supported

Throughout the course of this investigation the effort of the following Ph.D. and M.S. students were supported fully or partially by this project.

Ph.D. Students

1. Michael Whitt
2. Yisok Oh
3. Tsenchieh Chiu
4. Jim Stiles
5. Roger DeRoo

M.S. Students

1. M. Ali Tassoudji
2. James Ahne
3. A. Zambetti

5 Publications

Journal Publications:

1. Sarabandi, K., F.T. Ulaby, and M.A. Tassoudji, "Calibration of polarimetric radar systems with good polarization isolation", *IEEE Trans. Geosci. Remote Sensing*, vol. 28, no. 1, Jan. 1990.
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14. Svendsen, M.T., K. Sarabandi, and H. Skriver, "Retrieval of vegetation parameters from SAR data using a coherent scattering model for grassland," *IEEE Trans. Geosci. Remote Sensing.*, submitted for publication (April 99).

Conference Papers:

1. M.T. Svendsen, and K. Sarabandi, "Retrieval of vegetation parameters from SAR data using a coherent scattering model for grassland." *Proc. 2nd Int. Workshop on Retrieval of Bio- and Geo-physical Parameters from SAR data for Land Appl.*, Noordwijk, Netherlands, 21-23 Oct., 1998. (invited)
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APPENDIX A

RESULTS OF SIR-C/XSAR EXPERIMENTS