ELECTROMAGNETISM IN MOVING, CONDUCTING MEDIA

By Rudolph M. Kalafus

7322-3-T = RL-2153

Distribution of this report is provided in the interest of information exchange. Responsibility for the contents resides in the author or organization that prepared it.

Issued by Originator as Report No. 7322-3-T

Prepared under Grant No. NGR-23-005-107 by
THE UNIVERSITY OF MICHIGAN
Ann Arbor, Mich.

for Langley Research Center

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION

For sale by the Clearinghouse for Federal Scientific and Technical Information
Springfield, Virginia 22151 – CFSTI price $3.00
FOREWORD

The material contained in this report was also used as a Dissertation for the partial fulfillment of the requirements for the degree of Doctor of Philosophy in the Department of Electrical Engineering, The University of Michigan.
ACKNOWLEDGMENT

The author wishes to express his appreciation to Prof. C. T. Tai, who suggested the problem and has generously provided his continuing guidance and encouragement, and to the other members of the committee for their helpful suggestions. He also wishes to acknowledge the cooperation of Professor Ralph E. Hiatt and Claire White in the preparation of the manuscript, and to Katherine McWilliams who carefully typed it.
TABLE OF CONTENTS

ACKNOWLEDGMENTS

LIST OF FIGURES

I  PRELIMINARY DISCUSSION
   1.1  Introduction
   1.2  Maxwell's Equations for Moving Media

II  OHM'S LAW
   2.1  The Forms of Ohm's Law
   2.2  Formulation of Joule Heat
   2.3  The Atomistic Model

III SOURCE AND RESPONSE CHARGES AND CURRENTS
   3.1  Decomposition of Charges and Currents
      3.1.1  Case A: Charge Sources
      3.1.2  Case B: Current Sources
   3.2  Relationship of Response Charge Density to Source Charge
       and Current Densities
      3.2.1  Stationary Charge Sources
      3.2.2  Case B: Current Sources

IV  VECTOR AND SCALAR POTENTIALS; DEVELOPMENT OF THE
    GREEN'S FUNCTIONS
   4.1  Static Charge Source Distributions
      4.1.1  Differential Equations for the Potentials
      4.1.2  Green's Function Solution
      4.1.3  Summary
   4.2  Harmonic Current Source Distributions
      4.2.1  Differential Equations for the Potentials
      4.2.2  Green's Function Solution
      4.2.3  Summary

V  SUMMARY AND CONCLUSIONS

REFERENCES

APPENDIX A
# LIST OF FIGURES

<table>
<thead>
<tr>
<th>Figure</th>
<th>Description</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>3-1</td>
<td>Contours in the $h$-Plane for Evaluating $g_2(z)$</td>
<td>24</td>
</tr>
<tr>
<td>3-2</td>
<td>Response Charge Density Along the $z$-Axis for a Point Source Charge at the Origin</td>
<td>26</td>
</tr>
<tr>
<td>3-3</td>
<td>Charges and Currents for a Thin-Wire Antenna.</td>
<td>28</td>
</tr>
<tr>
<td>4-1</td>
<td>Contours in the $h$-Plane for Evaluating $H {G}$.</td>
<td>49</td>
</tr>
<tr>
<td>4-2</td>
<td>Contours in the $\lambda$-Plane for Evaluating $F {G}$.</td>
<td>53</td>
</tr>
<tr>
<td>4-3</td>
<td>Contours in the $h$-Plane for Evaluating $G (\bar{R}</td>
<td>0)$</td>
</tr>
<tr>
<td>4-4</td>
<td>Cerenkov Cone Geometry for High Velocities.</td>
<td>60</td>
</tr>
</tbody>
</table>
ELECTROMAGNETISM IN MOVING; CONDUCTING MEDIA

By
Rudolph M. Kalafus

ABSTRACT

Based on Minkowski's theory of the electrodynamics of moving bodies, the present work is concerned with the systematic solution of problems involving sources placed in a uniformly moving, conducting medium. In order to accomplish this it is first necessary to examine the two differing forms of Ohm's law for moving media that are found in the literature. It is concluded here that the two forms are equivalent and interchangeable, and that their apparent difference arises out of different definitions of conduction and convection currents.

Another difficulty which is encountered when dealing with conducting media is related to the relaxation phenomenon. The total charge and current densities cannot be independently specified, but must be consistent with the relaxation phenomenon; for non-conducting media only the equation of continuity must be met. A scheme is developed here which involves a separation of currents and charges into source and response terms. The source terms can be specified independently, but the total charge must be consistent with Maxwell's equations.

Vector and scalar potentials are developed from the field quantities, and partial differential equations for the potentials are derived for two classes of problems: static charge sources, and harmonic current sources. For unbounded regions potential solutions are found by the method of Green's functions, which satisfy the same differential equations. The differential equations are solved by transform methods, and the Green's functions are found in closed form.

The medium is assumed to have constant scalar parameters of permittivity, permeability, and conductivity. The results are valid for all values of conductivity and frequency, and for relativistic velocities.
I

PRELIMINARY DISCUSSION

1.1 Introduction

There have been several papers written in recent years on the subject of moving media, most of which deal with lossless media. Nag and Sayled (1956) applied Minkowski's theory of the electrodynamics of moving bodies to the phenomenon of Cerenkov radiation, by considering the problem of a static charge in a moving medium. Sayled (1958) later extended this to the two-medium problem of a charge imbedded in a channel of moving dielectric. Wave-motion in moving media has been discussed by Collier and Tai (1964 and 1965). The more involved problem of harmonic current source has received appreciable attention, notably from Compton and Tai (1964 and 1965), Lee and Papas (1964 and 1965), Tai (1965a and 1965b), and Daly, Lee, and Papas (1965). Unlike the present work, the concern there was with lossless media.

The formulation of field problems involving charge and current distributions as sources in a moving, conducting medium is delicate, and raises certain questions which have not been clearly settled up to now; Pyatii (1966) notes this in his thesis. One of the questions raised regards the formulation of Ohm's law for moving media, for which two different forms exist in the literature. Another concerns the relaxation phenomenon and its expression in moving media. In order to discuss the fields set up by charge distributions moving in a medium it becomes necessary to either set up an initial-value ballisitic problem, where at a given instant of time the charges have a given velocity, mass, and location, or to postulate impressed currents and charges which maintain their velocity by some unspecified energy source. In order to adequately treat the first problem one should consider the reaction forces and collisions and find the resulting velocity as a function of time. This is an ex-
tremely difficult approach to use. The second approach is used in altered form in antenna problems and, in fact, most problems involving the calculation of fields due to a particular source configuration. The second method will be employed here, treating the sources as stationary, and imbedded in a uniformly moving medium. The medium is assumed to have constant permeability, permittivity and conductivity.

In the first chapter Maxwell's equations for moving media are reviewed, and cast in dyadic form. The second chapter is devoted to the formulation of Ohm's law, with a discussion on the two apparently different forms which exist in the literature. Chapter III treats the decomposition of charges and currents into source and response terms, thus making it possible to rigorously approach problems in which sources are present. The relationship of the response charges to the sources is derived. Finally, Chapter IV is devoted to the development of the vector and scalar potentials and their differential equations. Green's functions are found in closed form, allowing the complete solution of field problems in moving, conducting media. Throughout the work, attention is focussed on two classes of problems: the first involves stationary charge distributions, and the second treats harmonic, stationary current distributions. At no time is any low-velocity approximation used; that is, the results are valid for relativistic velocities. Furthermore, it is not necessary to limit the values of conductivity to either low or high values.

1.2 Maxwell's Equations for Moving Media

For the sake of completeness we shall now develop the constitutive relations for an isotropic, linear medium in motion and introduce the dyadic symbolism convenient to discussion of the theory. Minkowski's powerful theory will be used throughout this work, as it provides an elegant framework for the discussion of electrodynamics.

As is well known, Minkowski postulated as his starting point that Maxwell's equations in their indefinite form are to be treated as physical laws, and as such have the same form in any coordinate system in uniform motion relative to the medium, in accord with the postulates of special relativity. The terminology "indefinite" and "definite" forms of Maxwell's equations was explained
by Tai (1964). Maxwell's equations in their indefinite form are:

\[ \nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \quad (I), \quad \nabla \cdot \vec{D} = \rho \quad (II), \]

\[ \nabla \times \vec{H} = \frac{\partial \vec{D}}{\partial t} + \vec{J} \quad (III), \quad \nabla \cdot \vec{B} = 0 \quad (IV). \]

These along with the constitutive relations comprise the definite form. Denoting the coordinate system of the medium by primes (i.e., that coordinate system with respect to which the medium is stationary), we remark again that the above equations hold for primed quantities; in addition, for linear, isotropic media the following constitutive relations hold:

\[ \vec{B}' = \mu' \vec{H}', \quad \vec{D}' = \epsilon' \vec{E}'. \tag{1.1} \]

The corresponding constitutive relations in any other system of reference which is moving with respect to the medium are not as simple. To find them, it is first necessary to know the relations between the field quantities of the two reference frames.

In particular, let us choose for the unprimed system one which moves in the negative \( z \)-direction with a constant velocity \( v \). This we may do with no loss of generality. The medium then moves with velocity \( v \) in the positive \( z \)-direction relative to the unprimed, or "stationary", system. The transformation of electric field, for example, is given by

\[ \vec{E}'_z = \vec{E}_z = (\vec{E} + \nabla \times \vec{B})_z, \quad \vec{E}'_{x, y} = \gamma (\vec{E} + \nabla \times \vec{B})_{x, y}, \tag{1.2a} \]

where \( \gamma = (1 - v^2/c^2)^{-1/2} \), and \( c \) is the speed of light in vacuo. The development of the transformation of the field quantities is discussed by Sommerfeld (1952), Section 34; the results will be used here. The above transformation relation may be written in dyadic symbolism as

\[ \vec{E}' = \gamma \cdot (\vec{E} + \nabla \times \vec{B}), \tag{1.2b} \]
where the elements of the dyadic $\bar{\gamma}$ are given by the array

\[
\begin{bmatrix}
\gamma & 0 & 0 \\
0 & \gamma & 0 \\
0 & 0 & 1
\end{bmatrix}.
\]

The other field quantities transform in a similar manner:

\[
\bar{D}' = \bar{\gamma} \cdot \left( \bar{D} + \frac{1}{c^2} \bar{v} \times \bar{H} \right),
\]

\[
\bar{B}' = \bar{\gamma} \cdot \left( \bar{B} + \frac{1}{c^2} \bar{v} \times \bar{E} \right),
\]

and

\[
\bar{H}' = \bar{\gamma} \cdot \left( \bar{H} - \bar{v} \times \bar{D} \right). \tag{1.3}
\]

Substituting these relations into the constitutive relations above, we get

\[
\bar{D} + \frac{1}{c^2} \bar{v} \times \bar{H} = \epsilon' (\bar{E} + \bar{v} \times \bar{B})
\]

and

\[
\bar{B} - \frac{1}{c^2} \bar{v} \times \bar{E} = \mu' (\bar{H} - \bar{v} \times \bar{D}) \tag{1.4}
\]

Combining these eliminates one field quantity. Thus eliminating $\bar{D}$ allows $\bar{B}$ to be expressed in terms of $\bar{E}$ and $\bar{H}$, and eliminating $\bar{B}$ gives $\bar{D}$ in terms of $\bar{E}$ and $\bar{H}$ (Tai, 1965b):

\[
\bar{D} = \epsilon' \bar{\alpha} \cdot \bar{E} + \bar{\Omega} \times \bar{H},
\]

and

\[
\bar{B} = \mu' \bar{\alpha} \cdot \bar{H} - \bar{\Omega} \times \bar{E}, \tag{1.5}
\]
where

\[ \bar{\Omega} = \frac{(n^2 - 1)}{1 - n^2 \beta^2} \frac{\bar{v}}{c^2}, \]

\[ \beta = \frac{v}{c} \]

\[ n^2 = c^2 \mu' \epsilon' = \mu' \epsilon'/\mu_o \epsilon_o, \]

and the elements of the dyadic \( \bar{\alpha} \) are given by

\[
\begin{bmatrix}
  a & 0 & 0 \\
  0 & a & 0 \\
  0 & 0 & 1 \\
\end{bmatrix},
\]

where

\[ a = \frac{1 - \beta^2}{1 - n^2 \beta^2}. \]

In the stationary system, then, \( \bar{D} \) and \( \bar{E}, \bar{B} \) and \( \bar{H} \) no longer are related uniquely as in the case of stationary media. If, in addition, \( \bar{J} \) is a known independent function or is related to the field quantities in a known manner, the indefinite form of Maxwell's equations along with the constitutive relations comprise the definite form of Maxwell's equations.
2.1 The Forms of Ohm's Law

Ohm's Law for moving media appears in two different forms in the literature: one is isotropic, given by Weyl (1922), p. 195:

\[ \frac{\mathbf{j}^{(1)}}{c} = \gamma \sigma' \mathbf{E}^* \quad , \]  

(2.1)

where the superscript "(1)" indicates the first form of \( \frac{\mathbf{j}}{c} \), the conduction current density, \( \sigma' \) denotes the rest-frame conductivity,

and

\[ \mathbf{E}^* = \mathbf{E} + \nabla \times \mathbf{B} \quad . \]

The other form is anisotropic and is the one most widely used in the literature (see especially Sommerfeld (1952) p. 283, and Cullwick (1959) p. 92):

\[ \frac{\mathbf{j}^{(2)}}{c} = \frac{\sigma'}{\gamma} \frac{\mathbf{E}}{\gamma} \cdot \frac{\mathbf{E}}{\gamma} \cdot \mathbf{E}^* \quad . \]  

(2.2)

The difference between them,

\[ \frac{\mathbf{j}^{(1)}}{c} - \frac{\mathbf{j}^{(2)}}{c} = \sigma' \gamma (1 - \gamma^{-2}) \mathbf{E}_z = \beta^2 \sigma' \gamma \mathbf{E}_z \quad , \]  

(2.3)

is of the order of \( \beta^2 \), and is negligible for velocities significantly less than the speed of light \( c \). It is important to know which, if either, is correct. Before we treat this question, it will be instructive to note how each form arises.
We first note the transformation relations between the current and charge densities, which arise from the Lorentz transformation of special relativity, and relate quantities in two systems in uniform relative motion (see Appendix A, Eq. (A.9)):

\[
\begin{align*}
\begin{cases}
\tilde{J}' = \gamma \bar{\gamma}^{-1} \cdot (\tilde{J} - \rho \bar{v}) \\
\rho' = \gamma (\rho - \frac{\bar{v} \cdot \tilde{J}}{c^2})
\end{cases}
\end{align*}
\quad \text{or} \quad
\begin{align*}
\begin{cases}
\tilde{J} = \gamma \bar{\gamma}^{-1} \cdot (\tilde{J}' + \rho' \bar{v}) \\
\rho = \gamma (\rho' + \frac{\bar{v} \cdot \tilde{J}'}{c^2})
\end{cases}
\end{align*}
\quad \text{(2.4)}
\]

where the elements of the dyadic \( \bar{\gamma}^{-1} \) are given by

\[
\begin{bmatrix}
\gamma^{-1} & 0 & 0 \\
0 & \gamma^{-1} & 0 \\
0 & 0 & 1
\end{bmatrix}.
\]

The crux of the difference concerns the decomposition of current density into convection and conduction terms. Convection current is associated with free charge in motion, while conduction is associated with electric fields in conducting media. Both formulations of Ohm's law proceed from the assumption that in the rest frame system of the medium (indicated by primed quantities) the current is all conduction:

\[
\tilde{J}' = \sigma' \bar{E}' = \tilde{J}'_c.
\quad \text{(2.5)}
\]

Weyl, on the one hand, uses the relation \( \tilde{J} = \gamma \bar{\gamma}^{-1} \cdot (\tilde{J}' + \rho' \bar{v}) \) to show that

\[
\tilde{J} = \gamma \bar{\gamma}^{-1} \cdot \sigma' \bar{E}' + \gamma \rho' \bar{v} = \sigma' \gamma \bar{E}' + \gamma \rho' \bar{v} ,
\quad \text{(2.6)}
\]

since the transformation of electric field is given by (see Eq. (1.2))
\[ \mathbf{E}' = \mathbf{\nabla} \cdot \mathbf{E}^* \quad (2.7) \]

Weyl then calls that part which depends explicitly on the conductivity "conduction current density", denoted by the subscript \(c\), and the remaining part "convection current density", denoted by the subscript \(v\):

\[ \mathbf{J}^{(1)}_c = \sigma' \gamma \mathbf{E}^* \quad , \quad \mathbf{J}^{(1)}_v = \gamma \rho' \mathbf{\nabla} \quad (2.8) \]

Sommerfeld, on the other hand, uses the transformation relation \( \mathbf{J}' = \gamma \mathbf{\nabla}^{-1} \cdot (\mathbf{J} - \rho \mathbf{\nabla}) \) to show that

\[ \mathbf{J} = \rho \mathbf{\nabla} + \mathbf{\nabla} \cdot \mathbf{J}' = \rho \mathbf{\nabla} + \frac{\sigma'}{\gamma} \mathbf{\nabla} \cdot \mathbf{E}^* \quad , \quad (2.9) \]

and calls the second term "conduction current density":

\[ \mathbf{J}^{(2)}_c = \frac{\sigma'}{\gamma} \mathbf{\nabla} \cdot \mathbf{E}^* \quad , \quad \mathbf{J}^{(2)}_v = \rho \mathbf{\nabla} \quad (2.10) \]

The difference between the two charge densities which appear in \( \mathbf{J}^{(1)}_v \) and \( \mathbf{J}^{(2)}_v \),

\[ \rho - \gamma \rho' = \gamma \rho' - \gamma \rho' + \frac{\mathbf{v} \cdot \mathbf{E}'}{c^2} = \sigma' \frac{\mathbf{v} \cdot \mathbf{E}'}{c^2} \quad , \quad (2.11) \]

is called the "apparent charge density" and arises from the relativistic transformations. In pre-relativistic electrodynamics a moving charge resulted in a current, but a moving current did not give rise to a charge. In relativistic electrodynamics this is not the case, but intuition is of little help in attaching a physical significance to the apparent charge density. Depending on whether it is assigned to the convection term or the conduction term, one or the other of the decompositions above is derived.

We shall show by elementary thermodynamical considerations that the heat loss expression can be derived independently of the form of Ohm's law.
used, and thus that either form is adequate. Further, the fields arising from charge distributions can also be equally well formulated in either form. While Schlomka (1950) uses an electron-theoretic model to conclude that \( J_c^{(2)} \) is "correct", and Cullwick accepts his reasoning, we shall disagree with his argument and conclude that the two forms are interchangeable, and differ only in definitions of "convection" and "conduction" terms.

2.2 Formulation of Joule Heat

The rate at which heat is developed per unit volume is given in the rest frame of the medium by

\[
\frac{dQ'}{dV'} = \frac{j_c}{c} \cdot E' = \sigma' \left| E' \right|^2,
\]  

(2.12)

which can be expressed in the stationary (unprimed) system as

\[
\frac{dQ'}{dV} = \sigma' \left| \frac{\gamma}{E} \cdot E' \right|^2
\]  

(2.13)

by use of Eq. (1.2).

We must, of course, consider the same volume in each system, so that relative to the unprimed system the volume is moving, and in accordance with the results of special relativity, appears shortened, i.e.

\[
dV' = \gamma dV
\]  

(2.14)

Borrowing on the results of relativistic thermo-dynamics (Møller (1952), p. 107), the heat developed per unit time transforms as follows:

\[
dQ' = \gamma^2 dQ
\]  

(2.15)

so that the rate of heat per unit volume seen from the stationary system is given by

\[
\frac{dQ}{dV} = \frac{1}{\gamma} \frac{dQ'}{dV'} = \frac{\sigma'}{\gamma} \left| \frac{\gamma}{E} \cdot E' \right|^2
\]  

(2.16)
or
\[ \frac{dQ}{dV} = J_c^{(1)} \cdot \frac{\vec{E}}{\gamma} \cdot \frac{\vec{E}^*}{\gamma^2} = J_c^{(2)} \cdot \vec{E}^* . \] (2.17)

Thus the Joule heat loss per unit volume per unit time can be readily expressed by either formulation of Ohm's law.

2.3 The Atomistic Model

Schlomka (1950) uses an atomistic, or electron-theoretic model, much like one described by Pauli (1958), p. 106, as a basis for claiming that \( J_c^{(2)} \) is the correct formulation of Ohm's law in moving media. His argument is briefly the following: conduction current is composed of a flow of electrons which travel on the average with some velocity \( \vec{u}' \) relative to the medium, i.e.,
\[ \vec{J}_c' = \rho_e' \vec{u}' , \] (2.18)

where \( \rho_e' \) is the charge density of the electrons (\( \rho_e' < 0 \)). By conservation of charge
\[ dq = \rho_e' dV' = \rho_e dV = \rho_e^0 dV^0 , \] (2.19)

where the superscript zero indicates that frame of reference with respect to which the charge is at rest, i.e. which has a velocity \( \vec{u}' \) relative to the medium. Thus, using (2.14) and noting that here the relative velocities are \( u \) and \( u' \) rather than \( v \),
\[ \frac{dq}{dV^0} = \rho_e' \sqrt{1 - \left( \frac{u'}{c} \right)^2} = \rho_e \sqrt{1 - \left( \frac{u}{c} \right)^2} . \] (2.20)

The transformation of velocities is given by Möller (1952), p. 53. In the dyadic notation, they can be condensed to one vector equation:
\[ \vec{u} = \frac{\bar{x}^{-1} \cdot (\vec{u}' + \vec{v})}{1 + \frac{\vec{u}' \cdot \vec{v}}{c^2}} . \]  

(2.21)

Now the conduction current in the unprimed system is given by the product of the charge density \( \rho_e \) and the relative velocity of the electrons and the medium \( \vec{u} - \vec{v} \) as seen from the unprimed coordinate system, or

\[ \vec{J}_c = \rho_e (\vec{u} - \vec{v}) , \]

(2.22)

which by using the relations above, gives

\[ \vec{J}_c = \frac{\bar{\gamma} \cdot \vec{J}'_c}{\gamma} = \frac{\sigma' \cdot \bar{\gamma} \cdot \bar{E} + \bar{E}^*}{\gamma} = \vec{J}^{(2)}_c , \]

(2.23)

which is the expression used by Sommerfeld.

There are two considerations which cast some doubt on the generality and validity of the reasoning. The first regards the concept of the relative velocity of two bodies as seen by a third (moving) observer. This is an intuitive carry-over from the Newtonian concept of addition of velocities. This being so, it is doubtful whether such an argument can be used in a situation where special relativity holds, to distinguish a second-order effect.

The second objection involves the phenomenological quality of Maxwell's and Minkowski's equations. The model of a cloud of electrons each traveling with a velocity \( u \) is an artificial one, especially since the possibility of fast conduction electrons is ignored, i.e. notions of Newtonian mechanics are again assumed. In view of these objections and the fact that the Joule heat has a unique and consistent expression in either formulation, the question is reduced to one of definition. Schomarka asserts that new formulas would have to be derived in the first formulation, a statement that is not born out by this work. In fact, it will prove more convenient for our purposes to use the first form when discussing problems where sources are present. This will be made clear in the next chapter.
III

SOURCE AND RESPONSE CHARGES AND CURRENTS

3.1 Decomposition of Charges and Currents

It is desirable to be able to treat problems that involve charge particles which obtain their velocities through a medium by other than electrical means. An example is the problem of a charged particle moving through a dielectric; Nag and Sayied (1956) treat this by considering a stationary charge in a moving dielectric. The charge is the source of the fields, and acts as a forcing function in Maxwell's equations. In treating conducting media a peculiar problem arises, that of the relaxation phenomenon; any charge placed in a conducting medium tends to disappear. If the charge is moving, the situation is more complicated. Suppose there is a convection current $\vec{J}'_V$ caused by charges moving through the medium in addition to the conduction current:

$$\vec{J}' = \vec{J}'_V + \sigma' \vec{E}' , \quad (3.1)$$

Taking the divergence of (3.1) and using the relations $\nabla' \cdot \vec{D}' = \rho'$ and $\vec{D}' = \varepsilon' \vec{E}'$ along with the equation of continuity, $\nabla' \cdot \vec{J}' + \partial \rho'/\partial t' = 0$, we get

$$\frac{\partial \rho'}{\partial t'} + \frac{\sigma'}{\varepsilon'} \rho' = - \nabla' \cdot \vec{J}'_V . \quad (3.2)$$

If we consider a constant charge moving along the $z'$-axis with constant velocity $u'$, and attempt to identify this charge with the total charge, i.e.

$$\vec{J}'_V = \rho' \vec{u}'$$

where

$$\rho' = \rho' (z' - u' t') = \text{constant} ,$$

substitution into (3.2) requires that $\rho' = 0$. Thus, we conclude that one cannot
arbitrarily assume a given convection current that is compatible with the relaxation condition. This leads us to separate the total charge density $\rho'$ into a source term $\rho'_s$ and a response term $\rho'_r$, and identify the source term with the moving charge:

$$\rho' = \rho'_s + \rho'_r \quad \text{and} \quad \vec{J}'_v = \rho'_s \vec{u}'$$

then $\rho'_r$ can be found by requiring that it be consistent with (3.2). Thus (3.2) becomes

$$\frac{\partial \rho'_r}{\partial t'} + \frac{\sigma'_r}{\varepsilon'} \rho'_r = - \nabla' \cdot \left[ \rho'_s (z' - u't') \vec{u}' \right] - \frac{\partial \rho'_s}{\partial t'} - \frac{\sigma'_r}{\varepsilon'} \rho'_s$$

$$= - \frac{\sigma'_r}{\varepsilon'} \rho'_s \quad , \quad (3.3)$$

since

$$\nabla' \cdot (\rho'_s \vec{u}') = \vec{u}' \cdot \nabla' \rho'_s = - \frac{\partial \rho'_s}{\partial t'} (z' - u't') \quad .$$

Similarly if a current source such as an antenna is placed in a moving medium and considered as an independent forcing function, the total current in the primed system is comprised of conduction current and the source current as seen from the rest frame of the medium:

$$\vec{J}' = \vec{J}'_s + \sigma' \vec{E}' \quad (3.4)$$

The problem that presents itself is the expression of charge and current densities in the unprimed system.

In this work we shall usually define the stationary or unprimed system as that coordinate system which transforms the source to rest. At this point it is not necessary to restrict consideration only to harmonic current sources, although later discussions will have that limitation. There are two classes of problems that will be dealt with in this work: "static" charge sources and
harmonic current sources in conducting, moving media. We shall now discuss the decomposition of currents and charges in the stationary system.

3.1.1 Case A: Charge Sources

First we will suspend the restriction that the stationary system be that with respect to which the charges are at rest, in order to show the generality of the formulation. Consider a set of charges moving through a conducting medium with constant velocity \( \bar{u}' \) relative to the medium, the motion being maintained by an unspecified mechanical force. Suppose the medium moves with velocity \( \bar{v} = v \bar{z} \) relative to the stationary coordinate frame. An observer in the stationary frame sees the charge moving with velocity \( \bar{u} \), where \( \bar{u} \) and \( \bar{u}' \) are uniquely related. This relation involves the relativistic addition of velocities, given by Eq. (2.32):

\[
\bar{u}' = \frac{\bar{u} - \bar{v}}{1 - \frac{\bar{u} \cdot \bar{v}}{c^2}}, \quad \text{or} \quad \bar{u} = \frac{\bar{u}' + \bar{v}}{1 + \frac{\bar{u}' \cdot \bar{v}}{c^2}}.
\]

(3.5)

The source charge densities are related by

\[
\rho_s \sqrt{1 - \left(\frac{\bar{u}}{c}\right)^2} = \rho_s' \sqrt{1 - \left(\frac{\bar{u}'}{c}\right)^2} = \rho_s'' ,
\]

(3.6)

where the double prime indicates that coordinate system which transforms the charge to rest. This relation follows from the principle of the invariance of charge:

\[
dq_s = \rho_s \, dV = \rho_s' \, dV' = \rho_s'' \, dV''
\]

(3.7)

and

\[
\sqrt{1 - \left(\frac{\bar{u}}{c}\right)^2} = \sqrt{1 - \left(\frac{\bar{u}'}{c}\right)^2} = dV'' ,
\]

(3.8)
(see Møller (1952), p. 45), which combine to give the above relation of charge densities.

As stated above, in the rest frame of the medium the total current consists only of conduction current \( \vec{J}_c = \sigma' \vec{E}' \) and convection current \( \vec{J}_v = \rho'_s \vec{U}' \) due to the motion of the source charge:

\[
\vec{J}' = \rho'_s \vec{U}' + \sigma' \vec{E}' \quad \text{,} \quad \rho' = \rho'_s + \rho'_r .
\] (3.9)

In the stationary system, we add \( \rho'_s \vec{U} \) to the current density expression of the Ohm's law discussion which consists of conduction current and convection current due to the motion of the medium:

\[
\vec{J} = \rho'_s \vec{U} + \vec{J}_c + \vec{J}_v \quad \text{,} \quad \rho = \rho'_s + \rho'_r .
\] (3.10)

It will now be shown that the quantity \( \vec{J}_c + \vec{J}_v \) does not explicitly depend on \( \rho'_s \), and the decomposition into conduction and convection is similar to that previously discussed in Section 2.1.

The transformation law for current density is given by Eq. (A.9) of Appendix A:

\[
\vec{J} = \gamma \frac{\vec{\pi}}{\gamma}^{-1} \cdot (\vec{J}' + \rho' \vec{V}) ,
\] (3.11)

so that

\[
\vec{J}_c + \vec{J}_v = \vec{J} - \rho'_s \vec{U} = \gamma \frac{\vec{\pi}}{\gamma}^{-1} \cdot \vec{J}' + \gamma \rho' \vec{V} - \rho'_s \vec{U}
\]

\[
= \rho'_s \gamma \frac{\vec{\pi}}{\gamma}^{-1} \cdot \vec{U}' + \gamma \sigma' \frac{\vec{\pi}}{\gamma}^{-1} \cdot \vec{E}' + \gamma \rho'_s \vec{V} + \gamma \rho'_r \vec{V} - \rho'_s \vec{U} .
\] (3.12)

Since \( \vec{E}' = \frac{\vec{\pi}}{\gamma} \cdot \vec{E}'^* \), and using Eq. (3.5),
\[
\begin{align*}
\bar{J}_c + \bar{J}_v &= \rho'_s \gamma \bar{\gamma}^{-1} \cdot (\bar{u} + \bar{v}) - \rho_s \bar{u} + \gamma \sigma' \bar{E}^* + \gamma \rho'_r \bar{v} \\
&= \rho_s \left[ \frac{\sqrt{1 - \left(\frac{u}{c}\right)^2}}{\sqrt{1 - \left(\frac{v}{c}\right)^2}} \right] \gamma \bar{\gamma}^{-1} \cdot (\bar{v} + \bar{v}) - \bar{u} + \gamma \sigma' \bar{E}^* + \gamma \rho'_r \bar{v} .
\end{align*}
\]

(3.13)

From Eq. (3.5), it is a matter of simple vector algebra to show that the following identity holds:

\[
\gamma \left(1 - \frac{\bar{v} \cdot \bar{u}}{c^2} \right) = \sqrt{\frac{1 - \left(\frac{u}{c}\right)^2}{1 - \left(\frac{v}{c}\right)^2}} .
\]

(3.14)

Using this relation along with Eq. (3.5), and substituting them into Eq. (3.13), the bracketed term vanishes, leaving

\[
\bar{J}_c + \bar{J}_v = \sigma' \gamma \bar{E}^* + \gamma \rho'_r \bar{v} .
\]

(3.15)

Here as in the sourceless case, we are free to decompose the convection and conduction terms in two ways:

\[
\begin{align*}
\bar{J}^{(1)}_c &= \sigma' \gamma \bar{E}^* , & \bar{J}^{(1)}_v &= \gamma \rho'_r \bar{v} ,
\end{align*}
\]

or

\[
\begin{align*}
\bar{J}^{(2)}_c &= \sigma' \frac{\bar{F} \cdot \bar{F}}{\gamma} \cdot \bar{E}^* , & \bar{J}^{(2)}_v &= \rho'_r \bar{v} .
\end{align*}
\]

(3.16)

We will generally use the first form,

\[
\bar{J} = \rho_s \bar{u} + \sigma' \gamma \bar{E}^* + \gamma \rho'_r \bar{v} .
\]

(3.17)
In the case where the charge is at rest in the stationary system, \( \bar{u} = 0 \), leaving
\[
\bar{J} = \sigma' \gamma \overline{E}^* + \gamma \rho_r' \overline{v} .
\] (3.18)

Similarly the response charge density \( \rho_r \) is related to \( \rho'_r \) in a manner similar to Eq. (2.11):
\[
\rho_r = \rho - \rho_s = \gamma (\rho' + \frac{\overline{v} \cdot \overline{J}'_r}{c}) - \rho_s = \gamma \rho'_s + \gamma \rho'_r + \gamma \rho'_ s \frac{\overline{v} \cdot \overline{u}}{c^2} + \sigma' \gamma \frac{\overline{v} \cdot \overline{E}'}{c^2} - \rho_s
\]
\[
= \rho'_s \left[ \gamma (1 + \frac{\overline{u} \cdot \overline{v}}{c^2}) - \frac{\rho_s}{\rho'_s} \right] + \sigma' \gamma \frac{\overline{v} \cdot \overline{E}}{c^2} + \gamma \rho'_s .
\] (3.19)

Substituting Eqs. (3.6) and (3.14) into (3.19) the bracketed term vanishes. Thus we can write the charge density in the stationary frame as
\[
\rho = \rho_s + \rho_r = \rho_s + \gamma \rho'_r + \sigma' \gamma \frac{\overline{v} \cdot \overline{E}}{c^2} .
\] (3.20)

Equations (3.18) and (3.20) constitute the desired current-charge expressions in the stationary system. Later on in Section 3.2.1, the relationship between the source and response terms will be derived. There it will be shown that \( \gamma \rho'_r \) satisfies a first-order partial differential equation, with \( \rho_s \) as the forcing function.

3.1.2 Case B: Current Sources

Instead of a convection current \( \rho_s \overline{u} \) there is here an impressed current density \( \overline{J}'_s \) in this class of problems, having an associated charge \( \rho'_s \).

In the primed system the impressed current density moves, so that a convection term appears in the transformation (Eq. (3.11)):
\[
\overline{J}'_s = \gamma \overline{r}^{-1} \cdot (\overline{J}_s - \rho_s \overline{v}) ;
\] (3.21)
also, from the transformation law (Eq. (2.4)),

\[ \rho'_s = \gamma \left( \rho_s - \frac{\mathbf{V} \cdot \mathbf{J}}{c^2} \right). \]  

(3.22)

These quantities, being independent source quantities, do not depend on the parameters of the medium. Equation (3.9) becomes

\[ \mathbf{J}' = \gamma \frac{\rho'_s}{\mathbf{V}} \cdot \left( \mathbf{V} - \rho_s \mathbf{V} \right) + \sigma' \mathbf{E}' . \]  

(3.23)

Using the transformation relations, we have also

\[ \mathbf{J}' = \gamma \frac{\rho'_s}{\mathbf{V}} \cdot \left( \mathbf{V} - \rho_s \mathbf{V} \right) = \gamma \frac{\rho'_s}{\mathbf{V}} \cdot \mathbf{V} - \gamma \rho_s \mathbf{V} - \gamma \rho \mathbf{V} . \]  

(3.24)

Equating these two expressions yields the decomposition of the second form

\[ \mathbf{J} = \mathbf{J} + \rho \mathbf{V} + \sigma' \frac{\mathbf{V} \cdot \mathbf{V}}{\gamma} \cdot \mathbf{E}^* \]

\[ = \mathbf{J} + J^{(2)} + J^{(2)} , \]

(which is the equation given by Sommerfeld (1952) p. 283), or, equivalently, in the first form

\[ \mathbf{J} = \mathbf{J} + J^{(1)} + J^{(1)} = \mathbf{J} + \gamma \rho'_s \mathbf{V} + \gamma \sigma' \mathbf{E}^* . \]  

(3.25)

As before, the charge density decompositions are given by

\[ \rho = \rho_s + \rho_r = \rho_s + \gamma \rho'_r + \gamma \sigma' \frac{\mathbf{V} \cdot \mathbf{E}}{c^2} . \]  

(3.26)

The relationship of \( \gamma \rho'_r \) to \( \rho_s \) is discussed in Section 3.2.2.
3.2 Relationship of Response Charge Density to Source Charge and Current Densities

In this section we shall develop the differential equation for the response charge density $\gamma \rho'_R$ in terms of the source terms in the unprimed system. Thus the first form of the decomposition in (3.16) of charge and current densities will be used, even though it would be more satisfying to express everything in terms of the unprimed system. The reason for this is that while the final expression for $\gamma \rho'_R$ involves only charge and current terms, this does not seem to be the case for $\rho'_R$, since a term involving the electric field appears.

We shall develop the desired differential equation in its most general form first, and then discuss the effects of assuming time-independent stationary charges and time-harmonic current sources. The final results of the paper are limited to these two classes of problems.

In order to develop the differential equation for $\gamma \rho'_R$, Eqs. (II) and (III) of Maxwell's equations, the constitutive relation for $D$, and the expressions for charge and current densities are needed:

\[ \nabla \cdot \vec{D} = \rho \, \text{(II)}, \quad \nabla \times \vec{H} = \frac{\partial \vec{D}}{\partial t} + \vec{J} \, \text{(III)}, \]
\[ \vec{D} = \varepsilon ' \vec{\sigma} \cdot \vec{E} + \vec{\Omega} \times \vec{H} \]  \hspace{1cm} (3.27)
\[ \vec{J} = \sigma \vec{E}^* + \gamma \rho'_R \vec{v} + \vec{J}_s \]  \hspace{1cm} (3.28)
\[ \rho = \rho_s + \gamma \rho'_R + \sigma \frac{\nabla \cdot \vec{E}}{c^2} \]  \hspace{1cm} (3.29)
\[ \sigma = \sigma' \gamma \]  \hspace{1cm} (3.30)

and
\[ \vec{E}^* = \vec{E} + \vec{v} \times \vec{B} = \vec{\sigma} \cdot \vec{E} + \mu' a \vec{v} \times \vec{H} \]  \hspace{1cm} (3.31)

Substituting (3.27) and (3.29) into (II) gives
\[ \nabla \cdot \mathbf{D} = \epsilon' \nabla \cdot \mathbf{\bar{\sigma}} \cdot \mathbf{E} - \mathbf{\bar{\Omega}} \cdot \nabla \times \mathbf{\bar{H}} \]

\[ = \rho \]

\[ = \rho_s + \gamma \rho'_r + \sigma \frac{\mathbf{\bar{V}} \cdot \mathbf{E}}{c^2}. \quad (3.32) \]

First note that using (III),

\[ \mathbf{\bar{\Omega}} \cdot \left( \frac{\partial \mathbf{\bar{D}}}{\partial t} + \mathbf{J} \right) = \epsilon' \mathbf{\bar{\Omega}} \cdot \frac{\partial \mathbf{E}}{\partial t} + \sigma \mathbf{\bar{\Omega}} \cdot \mathbf{E} + \mathbf{\Omega} \mathbf{v} \gamma \rho'_r + \mathbf{\bar{\Omega}} \cdot \mathbf{\bar{J}}_s, \quad (3.33) \]

\[ 1 + \mathbf{\Omega} \mathbf{v} = \mathbf{a}, \quad (3.34) \]

and

\[ \frac{\mathbf{\bar{\Omega}} + \frac{\mathbf{\bar{V}}}{c^2}}{\sigma} = \frac{\mathbf{\bar{V}}}{c^2} \mathbf{n}^a \mathbf{a}. \quad (3.35) \]

Multiplying by \( \sigma / \epsilon' \) and rearranging terms gives

\[ \sigma \nabla \cdot \mathbf{\bar{\sigma}} \cdot \mathbf{E} - \sigma \mathbf{\bar{\Omega}} \cdot \frac{\partial \mathbf{E}}{\partial t} - \sigma \mu' \mathbf{a} \mathbf{v} \cdot \mathbf{E} \]

\[ = \frac{\sigma}{\epsilon'} \left( \rho_s + \mathbf{\bar{\Omega}} \cdot \mathbf{\bar{J}}_s + \mathbf{a} \gamma \rho'_r \right). \quad (3.36) \]

Similarly, taking the divergence of (III) and combining this with (II) yields the continuity equation

\[ \nabla \cdot \mathbf{J} = -\frac{\partial \rho}{\partial t}, \quad (3.37) \]

which upon using (3.28), (3.29), and (3.31) becomes

\[
\sigma \nabla \cdot \mathbf{\bar{\sigma}} \cdot \mathbf{E} + \nabla \cdot (\gamma \rho'_r \mathbf{\bar{V}}) + \nabla \cdot \mathbf{\bar{J}}_s - \sigma \mu' \mathbf{a} \mathbf{v} \cdot \nabla \times \mathbf{\bar{H}}
\]

\[ = -\frac{\partial \rho_s}{\partial t} - \frac{\partial (\gamma \rho'_r)}{\partial t} - \frac{\sigma \mathbf{\bar{V}}}{c^2} \cdot \frac{\partial \mathbf{E}}{\partial t}. \quad (3.38) \]
Note that
\[ \bar{\nabla} \cdot \left( \frac{\partial \bar{D}}{\partial t} + \bar{J} \right) = \epsilon' \bar{\nabla} \cdot \frac{\partial \bar{E}}{\partial t} + \sigma \bar{\nabla} \cdot \bar{E} + v^2 \gamma \rho'_r + \bar{v} \cdot \bar{J}_s \quad , \quad (3.39) \]
\[ \nabla \cdot (\gamma \rho'_r \bar{v}) = \bar{v} \cdot \nabla \gamma \rho'_r \quad , \quad (3.40) \]
\[ \frac{\bar{v}}{c^2} (\alpha n^2 - 1) = \bar{\Omega} \quad , \quad (3.41) \]
\[ \mu' \epsilon' v^2 = n^2 \beta^2 \quad , \quad (3.42) \]
and
\[ \nabla \cdot \bar{J}_s = - \frac{\partial \rho_s}{\partial t} \quad . \quad (3.43) \]

Combining (3.38) through (3.43), and arranging terms, we get
\[ \sigma \nabla \cdot \bar{\sigma} \cdot \bar{E} - \sigma \bar{\Omega} \cdot \frac{\partial \bar{E}}{\partial t} - \sigma^2 \mu' a \bar{v} \cdot \bar{E} \]
\[ = - \left( \bar{v} \cdot \nabla + \frac{\partial}{\partial t} - \frac{\sigma a \beta^2}{\epsilon' \gamma} \right) \gamma \rho'_r + \sigma \mu' a \bar{v} \cdot \bar{J}_s \quad . \quad (3.44) \]

Subtracting (3.36) from (3.44) eliminates the field quantities, leaving the desired differential equation
\[ \left( \frac{\partial}{\partial t} + \bar{v} \cdot \nabla + \frac{\sigma}{\epsilon' \gamma^2} \right) \gamma \rho'_r = - \frac{\sigma}{\epsilon' \gamma} \left( \rho_s - \frac{\bar{v} \cdot \bar{J}_s}{c^2} \right) \quad , \quad (3.45) \]

where it is noted that
\[ 1 - \beta^2 = 1 / \gamma \quad , \quad (3.46) \]
and
\[ \frac{\bar{\Omega}}{\epsilon'} - \mu' a \bar{v} = - \frac{1}{\epsilon' \frac{\bar{v}}{c^2}} \quad . \quad (3.47) \]

from the definitions.
The primary interest of this work is stationary charge sources and
time-harmonic current sources. In the former case the unprimed coordinate
system is that of the charge, so that in (3.17), \( \mathbf{u} = 0 \), and thus \( \mathbf{J}_S = 0 \). The
steady-state solution obtained by setting \( \partial/\partial t = 0 \) is not trivially zero, which
is the case for stationary media. While it would be desirable to know the
transient behavior, the problem is not simple because of the continuity
Eq. (3.43) the source current density would have a singular behavior in
time if one postulated a source charge which suddenly appeared. The steady-state
solution is physically interpretable, and will be discussed.

For time-harmonic current sources such as radiators, the steady-state
solution is found by setting \( \partial/\partial t = -i\omega \).

3.2.1 Stationary Charge Sources

In this case \( \mathbf{J}_S = 0 \), \( \partial/\partial t = 0 \), and Eq. (3.45) reduces to

\[
\left( \frac{\partial}{\partial z} + \frac{\sigma}{\varepsilon' \gamma^2 \nu} \right) \gamma \rho'_{\mathbf{r}} = - \frac{\sigma}{\varepsilon' \nu} \rho_S ,
\]

which has the form

\[
\left( \frac{\partial}{\partial z} + b \right) u(z) = U_o(z) ,
\]

where

\[
b = \frac{\sigma}{\varepsilon' \gamma^2 \nu}
\]

\[
U_o(z) = \rho_S ,
\]

and

\[
u(z) = \gamma \rho'_{\mathbf{r}} .
\]

As a boundary condition we shall assume that \( u(\infty) \) vanishes. The solution is
well-known, but we shall include the solution by Fourier transforms. There will
be need to made use of the techniques later on in more complicated situations.
Let the Fourier transform in $z$ of a function $f(z)$ be defined by

$$F\{f\} = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{izx} f(z) \, dz \quad (3.50)$$

where it is assumed that $\int_{-\infty}^{\infty} |f(z)|^2 \, dz$ is bounded, that is, $f(z)$ is $L^2$ integrable in $(-\infty, \infty)$. Then we know that the integral $\int_{-\infty}^{\infty} F\{f\} \, dh$ converges to $f(z)$ wherever $f(z)$ is continuous (Morse and Feshbach 1953, p. 458). We first note that

$$\frac{1}{2\pi} \int_{-\infty}^{\infty} e^{izx} \frac{\partial f}{\partial z} \, dz = \frac{1}{2\pi} e^{izx} f \bigg|_{-\infty}^{\infty} - \frac{i}{2\pi} \int_{-\infty}^{\infty} e^{izx} f(z) \, dz$$

$$= -i\hbar F\{f\}, \quad (3.51)$$

since $f(\pm z)$ must vanish as $z$ approaches infinity for $f(z)$ in the class $L^2$. Multiplying Eq. (3.38) by $e^{izx}/2\pi$ and integrating from $-\infty$ to $+\infty$ gives

$$(-i\hbar + b) F\{u\} = -F\{U_0\},$$

or

$$F\{u\} = \frac{-i F\{U_0\}}{\hbar + ib}. \quad (3.52)$$

Taking the inverse transform by multiplying by $e^{-izx}$ and integrating over $h$ from $-\infty$ to $\infty$ gives, at points where $u(z)$ is continuous,
\begin{equation}
    u(z) = -i \int_{-\infty}^{\infty} \frac{e^{-ihz} F\{U_o\}}{h + ib} \, dh .
\end{equation}

(3.53)

We now make use of a theorem related to the convolution integral, and described in Morse and Feshbach (1953), p. 465, which states, for \( g_1(z) \) and \( g_2(z) \) \( L^2 \) integrable in \((-\infty, \infty)\):

\begin{equation}
    \frac{1}{2\pi} \int_{-\infty}^{\infty} g_1(\xi) g_2(z - \xi) d\xi = \int_{-\infty}^{\infty} F\{g_1\} F\{g_2\} e^{ihz} \, dh .
\end{equation}

(3.54)

Letting \( g_1(z) = U_o(z) \) and \( g_2(z) = -i \int_{-\infty}^{\infty} \frac{e^{-ihz}}{h + ib} \, dh \), we note that

\[ F\{g_2\} = \frac{-i}{h + ib} , \quad \text{and that} \]

\begin{equation}
    u(z) = \int_{-\infty}^{\infty} e^{-ihz} F\{U_o\} F\{g_2\} \, dh = \frac{1}{2\pi} \int_{-\infty}^{\infty} g_2(z - \xi) U_o(\xi) d\xi .
\end{equation}

(3.55)

In order to evaluate \( g_2(z) \) we use the technique of contour integration.

Referring to Fig. 3-1, it is noted that for \( z < 0 \), the exponential \( e^{-ihz} \)

![Contour Diagram](image)

FIG. 3-1: CONTOURS IN THE h-PLANE FOR EVALUATING \( g_2(z) \).
approaches zero uniformly in the upper half plane on the semi-circle as the radius approaches infinity. Thus the contribution along the semi-circle contour to the integral is negligible, and from the theory of residues,

\[ g_2(z) = -i \int_{-\infty}^{\infty} \frac{e^{-ihz}}{h+ib} \, dh = -i \int_{\text{Semi-Circle}} + 2\pi i \sum \text{Residue} = 0, \ z < 0, \]

(3.56)

since \( e^{-ihz} \) has no finite poles, and \((h+ib)^{-1}\) has only one pole, not enclosed by the contour. For \( z > 0 \), the contour can be closed in the lower half-plane. Then the contribution to the integral along the infinite semi-circle is again zero, and the residue at \( h = -ib \) is merely \( ie^{-bz} \), giving

\[ g_2(z) = -2\pi e^{-bz}, \quad z > 0. \]

(3.57)

Thus, combining (3.46) and (3.47),

\[ g_2(z) = \begin{cases} 
0, & z < 0 \\
-2\pi e^{-bz}, & z > 0 
\end{cases}, \]

(3.58)

so that from Eq. (3.45)

\[ u(z) = -\int_{-\infty}^{z} e^{-b(z-\xi)} U_0(\xi) d\xi, \]

(3.59)

or

\[ u(z) = -\int_{0}^{\infty} e^{-b\xi} U_0(z-\xi) d\xi. \]

(3.60)

Written in the original terminology we can now state that the differential Eq. (3.37) has the solution
\[
\gamma \rho^I_r(z) = -\frac{\sigma}{\varepsilon' v} \int_0^\infty e^{-\varepsilon' \gamma \frac{2}{v}} \rho_s(z - \xi) \, d\xi. 
\] (3.61)

In the important case where \( \rho_s \) is a point charge at the origin,

\[
\rho_s = q \delta(x) \delta(y) \delta(z), 
\] (3.62)

where \( \delta(x) \) has the properties that \( \delta(x) = 0 \) for \( x \neq 0 \),

\[
\int_a^b \delta(x) \, dx = 1 \quad \text{for} \quad a < 0 < b, \quad \text{and} \quad \int_a^b f(x) \delta(x) \, dx = f(0) \quad \text{for} \quad a < 0 < b. 
\] (3.63)

Then here

\[
\gamma \rho^I_r(z) = \begin{cases} 
0, & z < 0 \\
-\frac{\sigma z}{\varepsilon' v} - \frac{q e^{-\varepsilon' \gamma \frac{2}{v}}}{\varepsilon' v} \delta(x) \delta(y), & z > 0
\end{cases} 
\] (3.64)

This is shown graphically in Fig. 3-2.

![Diagram](image)

FIG. 3-2: RESPONSE CHARGE DENSITY ALONG THE \( z \)-AXIS FOR A POINT SOURCE CHARGE AT THE ORIGIN.
Thus along the $z$-axis, trailing the source charge, is a wake of response charge. The sign of the charge is opposite that of the source. The minimum value of the response charge is proportional to the conductivity and inversely proportional to the velocity, so that for small velocities the effect is significant. In effect the response charge tends to cancel out the effects of the source. The more closely the response charge is concentrated at the source, the more significant this screening effect is.

3.2.2 Case B: Current Sources

In the case of current sources, it is assumed that $J_s$ is given, and that $\partial/\partial t = -i\omega$. Then (3.45) becomes

$$
\left[ \frac{\partial}{\partial z} + \frac{1}{v} \left( \frac{\sigma}{\epsilon\gamma^2} - i\omega \right) \right] \gamma \rho'_r = -\frac{\sigma}{\epsilon\gamma} \left( \rho_s - \frac{\vec{v} \cdot \vec{J}_s}{c^2} \right),
$$

where the source charge density is determined by the continuity relation,

$$
\rho_s = \frac{\nabla \cdot \vec{J}_s}{i\omega}.
$$

This also has the form of (3.49). The only difference is that the resulting pole of Fig. 3-1 is shifted horizontally; this has no effect on the integration so that the results of Section 3.2.1 follow directly. From (3.59) we can write the solution as the superposition integral

$$
\gamma \rho'_r(z) = -\frac{\sigma}{\epsilon\gamma v} \int_{-\infty}^{z} e^{\frac{(i\omega - \sigma)}{\epsilon\gamma^2} \left( \frac{z - \xi}{v} \right)^2} \left[ \rho_s(\xi) - \frac{\vec{v} \cdot \vec{J}_s(\xi)}{c^2} \right] d\xi.
$$

As an example, consider a thin wire antenna of length $2l$ oriented in the $x$-direction, and having a triangular current distribution:

$$
\vec{J}_s = \hat{x} \frac{l}{\ell} \frac{I_0(t - |x|)}{\ell} \delta(y) \delta(z), \quad |x| \leq \ell.
$$

(3.68)
Then by the equation of continuity (3.43),

$$\rho_s = \frac{1}{1\omega} \nabla \cdot \overline{J_s}$$

$$= \frac{I_o}{1\omega I} \delta(y) \delta(z) \frac{\partial (\ell - |x|)}{\partial x}, \quad |x| < \ell,$$

or

$$\rho_s = \frac{I_o}{1\omega I} \delta(y) \delta(z) \cdot \begin{cases} 1, & -\ell \leq x < 0 \\
-1, & 0 < x \leq \ell \end{cases}.$$  \hspace{1cm} (3.69)

Then since $\nabla \cdot \overline{J_s} = 0$, the response charge density can be written, from (3.67),

$$\gamma\rho'_r = -\frac{\sigma}{\epsilon' \nu} \int_{-\infty}^{\infty} e^{i\omega - \sigma/\epsilon' \gamma^2} \left( \frac{z - \xi}{\nu} \right) \rho_s(\xi) \, d\xi,$$

$$\gamma\rho'_r = -\frac{\sigma I_o}{\epsilon' \nu \omega I} \delta(y) e^{i\omega - \sigma/\epsilon' \gamma^2} \frac{z}{\nu} S_0(z) \cdot \begin{cases} 1, & -\ell \leq x < 0 \\
-1, & 0 < x \leq \ell \end{cases}.$$ \hspace{1cm} (3.70)

This example is indicated schematically in Fig. 3-3:

![Diagram of antenna setup with charge and current density distributions](image)

FIG. 3-3: CHARGES AND CURRENTS FOR A THIN-WIRE ANTENNA.
It can now be demonstrated why it was necessary to decompose charges as well as currents into source and response terms. For if, instead, we had begun with the sourceless formulation of Sommerfeld,

$$\overline{J} = \rho \overline{V} + \sigma' \frac{\overline{F} \cdot \overline{F} \cdot \overline{E}^*}{\gamma},$$  \hspace{1cm} (3.71)$$

and added an impressed current source $\overline{J}_s$, and written

$$\overline{J} = \overline{J}_s + \rho \overline{V} + \sigma' \frac{\overline{F} \cdot \overline{F} \cdot \overline{E}^*}{\gamma},$$  \hspace{1cm} (3.72)$$

the convection term $\rho \overline{V}$ would become meaningless, if $\rho$ is taken as the total charge density. For as the conductivity $\sigma'$ vanishes, we would then get

$$\overline{J} = \overline{J}_s + \rho \overline{V}.$$  \hspace{1cm} (3.73)$$

But we know that a lossless medium, in motion or not, with a stationary charge and current distribution, gives rise to no convection term, that is,

$$\overline{J} = \overline{J}_s,$$  \hspace{1cm} (3.74)$$

and since in general, $\rho \neq 0$, this contradicts (3.72).

On the other hand, in the formulation of the present work, we have

$$\overline{J} = \overline{J}_s + \gamma \rho'_{\overline{F}} \overline{V} + \sigma' \gamma \overline{E}^*.$$  \hspace{1cm} (3.75)$$

Now as the conductivity vanishes, $\gamma \rho'_{\overline{F}}$ vanishes by (3.67), and we are left with

$$\overline{J} = \overline{J}_s,$$

as is required.
IV

VECTOR AND SCALAR POTENTIALS; DEVELOPMENT OF THE GREEN'S FUNCTIONS

In this chapter we shall derive the vector and scalar potentials and the differential equations they satisfy, for the two classes of problems of interest to us. The Green's function approach will be used to find solutions to the linear, inhomogeneous, partial differential equations. In this approach the forcing function is replaced by a point function, or \( \delta \)-function, in space, and the solution to the resulting differential equation is called a Green's function. The solutions to the differential equations for the vector or scalar potentials are then given by a superposition of Green's functions. The field quantities then follow from the potentials.

The class of problems involving charge sources gives rise to a complicated differential equation in the general time-dependent case, one not readily solved. If steady-state behavior is assumed, that is, \( \partial / \partial t = 0 \), the equation is greatly simplified, and is amenable to solution. We shall derive the differential equations and present them in their entirety, and find the Green's function solution in closed form for the steady-state case.

The harmonic current source class of problems is treated in a modified way, i.e., the potentials are defined differently than usual. The modified approach gives rise to simpler differential equations. Steady-state behavior is again assumed, and Green's function solutions are found in closed form.

The discussion is limited to consideration of unbounded media. Thus we are primarily interested in the particular solutions to the differential equations. There is thus a unique correspondence between the solutions and their transforms; we will use the method of Hankel transforms in the cylindrical coordinate \( r = (x^2 + y^2)^{1/2} \), and Fourier transforms in the longitudinal coordinate \( z \). The solutions are valid for all values of conductivity \( \sigma \), and all velocities \( v \).
4.1 Static Charge Source Distributions

4.1.1 Differential Equations for the Potentials

For a linear, uniformly moving, conducting medium, Maxwell's equations are given by

\[ \nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \quad (I), \quad \nabla \cdot \vec{D} = \rho \quad (II), \]

\[ \nabla \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t} \quad (III), \quad \nabla \cdot \vec{B} = 0 \quad (IV), \]

where the constitutive relations are, using the definitions of Eq. (1.5)

\[ \vec{B} = \mu^' \vec{\sigma} \cdot \vec{H} - \vec{\Omega} \times \vec{E}, \]

\[ \vec{D} = \varepsilon^' \vec{\sigma} \cdot \vec{E} + \vec{\Omega} \times \vec{H}, \quad (4.1) \]

and charge and current densities are decomposed as follows:

\[ \vec{J} = \sigma(\vec{E} + \nabla \times \vec{B}) + \gamma \rho^' \vec{\nabla} = \sigma(\vec{\sigma} \cdot \vec{E} + \mu^' a \nabla \times \vec{H}) + \gamma \rho^' \vec{\nabla}, \]

\[ \rho = \rho^s + \gamma \rho^r + \frac{\nabla \cdot \vec{E}}{c^2}. \quad (4.2) \]

Here we have used Eqs. (3.29) and (3.31). The quantity \( \gamma \rho^r \) is determined by the source density \( \rho^s \); this was discussed in Section 3.2.1. In finding this relationship of response to source, it should be noted that only (II) and (III) of Maxwell's equations were used. In deriving the expressions for the potentials, it is necessary to use (I) and (IV) as well.

For source charge problems, the vector potential \( \vec{A} \) is defined in the usual manner, using (IV):

\[ \vec{B} = \nabla \times \vec{A}. \quad (4.3) \]
Note that this is only a partial definition, since $\vec{A}$ is not unique. Any other vector potential $\vec{A}$, which differs from $\vec{A}$ by the gradient of some scalar, would also satisfy this relation. From (1),

$$\nabla \times \overline{E} = -\frac{\partial}{\partial t} \nabla \times \overline{A} = -\nabla \times \frac{\partial \vec{A}}{\partial t},$$

or

$$\overline{E} = -\frac{\partial \vec{A}}{\partial t} - \nabla \phi, \quad \text{(4.4)}$$

where $\phi$ is some scalar potential.

We are free to choose $\vec{A}$ to be in the $z$-direction without losing generality. Thus cross-products of $\vec{A}$ with $\nabla$ or $\vec{\Omega}$ will vanish in the following development. The equation $\nabla \cdot \vec{D} = \rho$ has already been expanded in Eq. (3.36)

$$\nabla \cdot \overline{\vec{E}} = -\vec{\Omega} \cdot \frac{\partial \vec{E}}{\partial t} - \sigma \mu' a \nabla \cdot \vec{E} = \frac{\rho_s + a \gamma \rho_i'}{\epsilon}. \quad \text{(4.5)}$$

This becomes, using (4.4),

$$\nabla \cdot \vec{a} \cdot \left(\frac{\partial \vec{A}}{\partial t} + \nabla \phi\right) - \vec{\Omega} \cdot \left(\frac{\partial^2 \vec{A}}{\partial t^2} + \nabla \frac{\partial \phi}{\partial t}\right) - \sigma \mu' a \nabla \cdot \left(\frac{\partial \vec{A}}{\partial t} + \nabla \phi\right) = \frac{\left(\rho_s + a \gamma \rho_i'\right)}{\epsilon}. \quad \text{(4.6)}$$

From (4.1)

$$\mu' \overline{H} = \overline{\vec{a}}^{-1} \cdot \vec{B} + \frac{1}{a} \vec{\Omega} \times \overline{E}$$

$$= \overline{\vec{a}}^{-1} \cdot (\nabla \times \overline{A}) - \frac{1}{a} \vec{\Omega} \times \left(\frac{\partial \vec{A}}{\partial t} + \nabla \phi\right)$$

$$= \frac{1}{a} \nabla \times (\vec{A} + \vec{\Omega} \phi), \quad \text{(4.7)}$$

where the elements of $\overline{\vec{a}}^{-1}$ are given simply by
\[
\begin{bmatrix}
1/a & 0 & 0 \\
0 & 1/a & 0 \\
0 & 0 & 1
\end{bmatrix}.
\]

Also, from (4.1),

\[
\bar{D} = \epsilon' \bar{\sigma} \cdot \bar{E} + \Omega x \bar{H}
\]

\[
= -\epsilon' \frac{\partial \bar{A}}{\partial t} - \epsilon' \bar{\sigma} \cdot \nabla \phi + \frac{1}{a \mu'} \Omega x \left[ \nabla x (\bar{A} + \bar{\Omega} \phi) \right]. \quad (4.8)
\]

From Eq. (4.2),

\[
\bar{J} = \sigma (\bar{E} + \nabla x \bar{B}) + \gamma \rho' \bar{\nu}. \quad (4.9)
\]

Thus (III) becomes

\[
\nabla x \bar{H} = \frac{1}{\mu' a} \nabla x \nabla x (\bar{A} + \bar{\Omega} \phi) = \bar{J} + \frac{\partial \bar{D}}{\partial t}
\]

\[
= -\sigma \left[ \frac{\partial \bar{A}}{\partial t} + \nabla \phi - \bar{\nu} x (\nabla x \bar{A}) \right] - \epsilon' \frac{\partial^2 \bar{A}}{\partial t^2} - \epsilon' \bar{\sigma} \cdot \nabla \frac{\partial \phi}{\partial t} + \frac{1}{\mu' a} \Omega x \left[ \nabla x \frac{\partial}{\partial t} (\bar{A} + \bar{\Omega} \phi) \right]
\]

\[
+ \gamma \rho' \bar{\nu}. \quad (4.10)
\]

By choosing a gauge condition which is consistent with the well-known gauge condition for stationary, conducting media, separate partial differential equations may be obtained for \( \bar{A} \) and \( \phi \). The development of the gauge condition is given in Appendix A. It can be written:

\[
\nabla \cdot \bar{A} - \sigma \mu' a \bar{\nu} \cdot \bar{A} - \Omega \cdot \frac{\partial \bar{A}}{\partial t} = -\bar{\nu} \cdot \nabla \phi - \sigma \mu' a \phi - \frac{1}{c^2} \left( \frac{n^2 - \beta^2}{1 - n^2 \beta^2} \right) \frac{\partial \phi}{\partial t}. \quad (4.11)
\]
Substituting this into (4.6) yields the differential equation for \( \phi \):

\[
(\nabla \cdot \bar{\sigma} \cdot \nabla) \phi - \sigma \mu' a \nabla \cdot \nabla \phi - 2 \frac{\nabla}{\partial t} \cdot \nabla \frac{\partial \phi}{\partial t} - \frac{1}{c^2} \left( \frac{n^2 - \beta^2}{1 - n^2 \beta^2} \right) \frac{\partial^2 \phi}{\partial t^2} = - \frac{1}{c^4} (\rho_a + a \gamma \rho_t') .
\]

To show this, we first note the following relation, which follows from (4.11):

\[
\nabla \cdot \bar{\sigma} \cdot \left( \frac{\partial \bar{A}}{\partial t} + \nabla \phi \right) = \frac{\partial \bar{A}}{\partial t} \cdot \nabla \phi + (\nabla \cdot \bar{\sigma} \cdot \nabla) \phi
\]

\[
= (\nabla \cdot \bar{\sigma} \cdot \nabla) \phi + \sigma \mu' a \bar{v} \cdot \nabla \frac{\partial \bar{A}}{\partial t} + \frac{\partial^2 \bar{A}}{\partial t^2} - \frac{\nabla \cdot \nabla \phi}{\partial t} - \sigma \mu' a \frac{\partial \phi}{\partial t} - \frac{1}{c^2} \left( \frac{n^2 - \beta^2}{1 - n^2 \beta^2} \right) \frac{\partial^2 \phi}{\partial t^2}
\]

Using this relation in (4.6), it can be seen that the terms involving the vector potential \( \bar{A} \) drop out, leaving (4.12).

Turning our attention now to (4.10), we first draw upon a vector identity noted by Tai (1965a):

\[
\nabla \times (\bar{\sigma}^{-1} \cdot (\nabla \times (\bar{\sigma}^{-1} \cdot \bar{F}))) = \frac{1}{a} \left[ (\bar{\sigma} \cdot \nabla) (\nabla \cdot \bar{F}) - (\nabla \cdot \bar{\sigma} \cdot \nabla) \bar{F} \right].
\]

(4.14)

When \( \bar{F} \) is the vector potential \( \bar{A} \), and it is noted that \( \bar{A} \) is in the z-direction only, the left hand side becomes

\[
\nabla \times (\bar{\sigma}^{-1} \cdot (\nabla \times (\bar{\sigma}^{-1} \cdot \bar{A}))) = \nabla \times (\bar{\sigma}^{-1} \cdot (\nabla \times \bar{A})) = \frac{1}{a} \nabla \times \nabla \times \bar{A}
\]

and thus

\[
\nabla \times \nabla \times \bar{A} = \frac{1}{a} \left[ (\bar{\sigma} \cdot \nabla) (\nabla \cdot \bar{A}) - (\nabla \cdot \bar{\sigma} \cdot \nabla) \bar{A} \right].
\]

(4.15)
When this is substituted into Eq. (4.10), and the terms are regrouped, we get

\[
(\nabla \cdot \vec{\sigma} \cdot \nabla) \vec{A} - (\vec{\sigma} \cdot \nabla) (\nabla \cdot \vec{A}) - \mu'\varepsilon' a^2 \frac{\partial^2 \vec{A}}{\partial t^2} - \sigma \mu' a^2 \frac{\partial \vec{A}}{\partial t} + a \nabla \times (\nabla \times \Omega \vec{\phi}) + \sigma \mu' a^2 \nabla \vec{\phi} + \mu'\varepsilon' a^2 \nabla \cdot \vec{\sigma} \cdot \nabla \frac{\partial \vec{\phi}}{\partial t} - a \nabla \times (\nabla \times (\Omega \frac{\partial \vec{\phi}}{\partial t})) - \mu' a^2 \gamma \rho \vec{v}.
\]

\[
(4.16)
\]

The fifth term on the left can be written as follows:

\[
a \nabla \times (\nabla \times (\Omega \frac{\partial \vec{A}}{\partial t})) = a \nabla (\nabla \cdot \vec{A}) - a (\Omega \cdot \nabla) \vec{A},
\]

\[
(4.17)
\]

where use is made of the vector identity

\[
\nabla (\vec{F} \cdot \vec{G}) = \vec{F} \times (\nabla \times \vec{G}) + \vec{G} \times (\nabla \times \vec{F}) + (\vec{F} \cdot \nabla) \vec{G} + (\vec{G} \cdot \nabla) \vec{F}.
\]

\[
(4.18)
\]

and it is noted that derivatives of \( \Omega \) are zero since \( \Omega \) is assumed constant.

Similarly, the sixth term on the left becomes

\[
\sigma \mu' a^2 \nabla \times (\nabla \times \vec{A}) = \sigma \mu' a^2 \nabla (\nabla \cdot \vec{A}) - \sigma \mu' a^2 (\nabla \cdot \nabla) \vec{A},
\]

\[
(4.19)
\]

and the third and fourth terms on the right combine to give

\[
\mu'\varepsilon' a^2 \nabla \cdot \vec{\sigma} \cdot \nabla \frac{\partial \vec{\phi}}{\partial t} - a \nabla \times (\nabla \times (\Omega \frac{\partial \vec{\phi}}{\partial t})) = \frac{n^2}{c^2} a^2 \nabla \cdot \vec{\sigma} \cdot \nabla \frac{\partial \vec{\phi}}{\partial t} - a \nabla (\Omega^2 \frac{\partial \vec{\phi}}{\partial t}) + a (\Omega \cdot \nabla) (\Omega \frac{\partial \vec{\phi}}{\partial t}).
\]

35
\[ \frac{n^2}{c^2} \alpha^2 \frac{\partial \phi}{\partial t} - a \Omega^2 \nabla \frac{\partial \phi}{\partial t} + a \frac{\Omega (\bar{\Omega} \cdot \nabla)}{c} \frac{\partial \phi}{\partial t}. \] 

(4.20)

The transverse component, denoted by the subscript \( T \), can be written

\[
a \left( \frac{n^2}{c^2} - \frac{\Omega^2}{c^2} \right) \nabla_T \frac{\partial \phi}{\partial t} = \frac{a}{c^2} \left( \frac{n^2 - \beta^2}{1 - n^2 \beta^2} \right) \nabla_T \frac{\partial \phi}{\partial t} \] 

(4.21a)

which follows from the definitions of \( \Omega \) and \( a \). Similarly the z-component is merely that of the first term of (4.20), or

\[
\frac{n^2}{c^2} \frac{\partial^2 \phi}{\partial z \partial t}. \]

(4.21b)

Also, the first term on the right of (4.16) can be re-written:

\[
a \nabla \times \nabla \times (\bar{\Omega} \phi) = a \nabla \nabla \cdot (\bar{\Omega} \phi) - a \nabla^2 (\bar{\Omega} \phi)
\]

\[= a \bar{\nabla} (\bar{\Omega} \cdot \nabla \phi) - a \bar{\Omega} \nabla^2 \phi \]

\[= a \bar{\Omega} \times (\nabla \times \nabla \phi) + a (\bar{\Omega} \cdot \nabla) \nabla \phi - a \bar{\Omega} \nabla^2 \phi \]

\[= a (\bar{\Omega} \cdot \nabla) \nabla \phi - a \bar{\Omega} \nabla^2 \phi, \] 

(4.22)

where use is made of the following vector identities, in addition to (4.18):

\[\nabla \times \nabla \times \bar{F} = \nabla \nabla \cdot \bar{F} - \nabla^2 \bar{F}, \]

(4.23a)

\[\nabla \cdot (\bar{F} \psi) = \bar{F} \cdot \nabla \psi + \psi \nabla \cdot \bar{F}, \]

(4.23b)

\[\nabla^2 (\bar{F} \psi) = \bar{F} \nabla^2 \psi \text{ for } \bar{F} \text{ a constant vector}, \]

(4.23c)

\[\nabla \times (\nabla \psi) = 0, \]

(4.23d)
and it is noted that derivatives of $\bar{\Omega}$ vanish, since $\bar{\Omega}$ is a constant vector.

The second term on the left of (4.16) can be rewritten, using the gauge condition of Eq. (4.11). This gives, for the transverse components,

$$
\begin{align*}
\left[ - (\vec{\sigma} \cdot \nabla) \left( \nabla \cdot \vec{A} \right) \right]_T &= - \sigma \mu' a^2 v T \nabla \cdot \vec{A} - a \Omega \nabla \frac{\partial A}{\partial t} + a \Omega \nabla \frac{\partial \phi}{\partial z} \\
&\quad + \sigma \mu' a^2 v T \phi + \frac{a}{c^2} \left( \frac{n^2 - \beta^2}{1 - n^2 \beta^2} \right) \nabla \frac{\partial \phi}{\partial t} . \quad (4.24a)
\end{align*}
$$

For the $z$-component,

$$
\begin{align*}
\left[ - \left( \vec{\sigma} \cdot \nabla \right) \left( \nabla \cdot \vec{A} \right) \right]_z &= - \sigma \mu' a v \frac{\partial A}{\partial z} - \Omega \frac{\partial^2 A}{\partial z \partial t} + \Omega \frac{\partial^2 \phi}{\partial z^2} \\
&\quad + \sigma \mu' a \frac{\partial \phi}{\partial z} + \frac{1}{c^2} \left( \frac{n^2 - \beta^2}{1 - n^2 \beta^2} \right) \frac{\partial^2 \phi}{\partial z \partial t} . \quad (4.24b)
\end{align*}
$$

Using (4.17), (4.19), and (4.24), the transverse part of the left hand side of (4.16) reduces to

$$
a \Omega \nabla T \frac{\partial \phi}{\partial z} + \sigma \mu' a^2 v T \phi + \frac{a}{c} \left( \frac{n^2 - \beta^2}{1 - n^2 \beta^2} \right) \nabla T \frac{\partial \phi}{\partial t} . \quad (4.25a)
$$

Similarly the transverse part of the right side of (4.16) after using (4.21) and (4.22) becomes

$$
a \Omega \nabla T \frac{\partial \phi}{\partial z} + \sigma \mu' a^2 v T \phi + \frac{a}{c} \left( \frac{n^2 - \beta^2}{1 - n^2 \beta^2} \right) \nabla T \frac{\partial \phi}{\partial t} , \quad (4.25b)
$$

which is the same as (4.25a). Thus the transverse components cancel, and we are left with only longitudinal components. This means that the vector
differential equation reduces to a single scalar differential equation, an important result.

Summing up the longitudinal components on each side, we get

\[
(\nabla \cdot \mathbf{E} \cdot \nabla) \mathbf{A} - \sigma \mu' a^2 v \frac{\partial \mathbf{A}}{\partial z} - \frac{2}{c^2} \omega^2 \frac{\partial \mathbf{A}}{\partial t} + \frac{4}{c^2} \sigma \mu' a^2 \frac{\partial \phi}{\partial z} + \frac{2}{c^2} \mathbf{E}^2 \frac{\partial \phi}{\partial t} \\
- \frac{n a}{c} \frac{\partial \mathbf{A}}{\partial t} - \sigma \mu' a^2 \frac{\partial \mathbf{A}}{\partial t}
\]

\[
= a^2 (\overline{\Omega} \cdot \nabla) \frac{\partial \phi}{\partial z} - a \overline{\Omega} \nabla^2 \phi + \frac{4}{c^2} \sigma \mu' a^2 \frac{\partial \phi}{\partial z} + \frac{2}{c^2} \mathbf{E}^2 \frac{\partial \phi}{\partial t}
\]

\[
- \mu' a^2 \gamma \rho' \overline{v} . \quad (4.26)
\]

Examining those terms involving \( \frac{\partial^2 \phi}{\partial z^2} \) and \( \nabla^2 \phi \), we note that

\[
\hat{a} a (\overline{\Omega} \cdot \nabla) \frac{\partial \phi}{\partial z} - a \overline{\Omega} \nabla^2 \phi - \overline{\Omega} \frac{\partial^2 \phi}{\partial z^2} = - a \overline{\Omega} \nabla^2 \phi - \overline{\Omega} \frac{\partial^2 \phi}{\partial z^2}
\]

\[
= - \overline{\Omega} (\nabla \cdot \mathbf{E} \cdot \nabla) \phi . \quad (4.27)
\]

Since the quantities are parallel vectors, we can drop the vector notation. After multiplication by \( \overline{\Omega} \), Eq. (4.6) becomes

\[
- \Omega (\nabla \cdot \mathbf{E} \cdot \nabla) \phi = \frac{\partial^2 A}{\partial z \partial t} - \Omega^2 \frac{\partial^2 \mathbf{A}}{\partial t^2} - \sigma \mu' a v \Omega \frac{\partial \mathbf{A}}{\partial t}
\]

\[
- \Omega^2 \frac{\partial^2 \phi}{\partial z \partial t} - \sigma \mu' a v \Omega \frac{\partial \phi}{\partial z} + \Omega \frac{\rho_s}{\epsilon'} + a \frac{\Omega}{\epsilon'} \gamma \rho' . \quad (4.28)
\]

38
Using (4.27) and (4.28), Eq. (4.26) becomes

\[
(\nabla \cdot \tilde{\sigma} \cdot \nabla) A - \sigma \mu' av \frac{\partial A}{\partial z} - 2 \Omega \frac{\partial^2 A}{\partial z \partial t} - \sigma \mu' a (a - v \Omega) \frac{\partial A}{\partial t} - \left( \frac{n \frac{a}{c}}{2} - \Omega^2 \right) \frac{\partial^2 A}{\partial t^2}
\]

\[
= - \sigma \mu' a (1 - a + v \Omega) \frac{\partial \phi}{\partial z} \left[ \frac{1}{2} \left( \frac{n}{2} - \beta^2 \right) - \frac{n a}{c^2} + \Omega^2 \right] \frac{\partial^2 \phi}{\partial z \partial t} + \Omega \frac{\rho_s}{\epsilon^r} - (\mu' a v - \Omega) a \gamma \rho' r.
\]

(4.29)

It can be seen from the definitions of \( a \) and \( \Omega \) that the following relations hold:

\[
a - v \Omega = 1,
\]

\[
\frac{n \frac{a}{c}}{2} - \Omega^2 = \frac{\frac{n}{2}}{c} - \frac{\frac{2 \beta^2}{c}}{1 - n \beta^2},
\]

and

\[
\mu' a v - \frac{\Omega}{\epsilon^r} = \frac{1}{\epsilon^r} \cdot \frac{a v}{c^2},
\]

(4.30)

so that (4.29) becomes, finally,

\[
(\nabla \cdot \tilde{\sigma} \cdot \nabla) A - \sigma \mu' a v \frac{\partial A}{\partial z} - 2 \Omega \frac{\partial^2 A}{\partial z \partial t} - \sigma \mu' a \frac{\partial A}{\partial t} - \frac{1}{2} \left( \frac{n \frac{a}{c}}{2} - \Omega^2 \right) \frac{\partial^2 A}{\partial t^2}
\]

\[
= \frac{1}{\epsilon^r} \left( \Omega \rho_s - \frac{a v}{c^2} \gamma \rho' r \right).
\]

(4.31)

Written in scalar form, the corresponding expression (4.12) for the scalar potential \( \phi \) becomes

39
\[ (\nabla \cdot \vec{F} \cdot \nabla) \phi - \sigma \mu^\prime a v \frac{\partial \phi}{\partial z} - 2 \Omega \frac{\partial^2 \phi}{\partial z \partial t} - \sigma \mu^\prime a \frac{\partial \phi}{\partial t} - \frac{1}{c^2} \left( \frac{n^2 - \beta^2}{1 - n^2 \beta^2} \right) \frac{\partial^2 \phi}{\partial t^2} = - \frac{1}{\epsilon^'} \left( \rho_s + \alpha \gamma \rho^\prime_r \right) . \] (4.32)

Comparison of (4.31) and (4.32) reveals that the two differential equations are identical, except for the source terms.

Let \( \phi_s \) be the solution to the differential equation when only the first term appears on the right of (4.32), and \( \phi_r \) the solution when only the second term appears. Then

\[ \phi = \phi_s + \phi_r . \] (4.33)

If \( \vec{A}_s \) and \( \vec{A}_r \) are similarly defined from Eq. (4.31), the particular solutions are related by constant quantities:

\[ \vec{A}_s = -\vec{\Omega} \phi_s \]

and

\[ \vec{A}_r = \frac{\vec{v}}{c^2} \phi_r . \] (4.34)

From the transformation relations for \( A' \) and \( \phi' \) in the rest system of the medium (see Appendix A, Eq. (A.8)),

\[ A' = \gamma (A - \frac{\vec{v} \phi}{c^2}) = \gamma ( - \Omega \phi_s + \frac{\vec{v}}{c^2} \phi_r - \frac{\vec{v}}{c^2} \phi_s ) , \]

or

\[ A' = -\gamma \mu^\prime \epsilon^a v \phi_s , \] (4.35)
and thus \( \Lambda' \) depends only on the source term \( \rho_s \) and not on the response charge density \( \rho_r'. \) On the other hand,

\[
\Phi' = \gamma (\Phi - vA) = \gamma (\Phi_s + \Phi_r + v \Omega \Phi_s - \frac{\gamma^2}{2} \Phi_r),
\]

or

\[
\Phi' = \gamma a \Phi_s + \frac{1}{\gamma} \Phi_r. \tag{4.36}
\]

It is also of interest to express the fields in terms of the scalar potentials; from (4.3), (4.4), (4.7), and (4.8) we get

\[
\overline{B} = \nabla \times \overline{A} = (\nabla \Phi \times \frac{\hat{z}}{c}) = \nabla \times \Phi_s - \frac{\nabla}{c} \times \nabla \Phi_r,
\]

\[
\overline{E} = -\frac{\partial \overline{A}}{\partial t} - \nabla \Phi
\]

\[
= \overline{\Omega} \frac{\partial \Phi_s}{\partial t} - \nabla \Phi_s - \frac{\nabla}{c} \frac{\partial \Phi_r}{\partial t} - \nabla \Phi_r,
\]

\[
\overline{H} = \frac{1}{\mu' a} \nabla \times (\overline{A} + \overline{\Omega} \Phi)
\]

\[
= \frac{2}{\mu' a c^2} (\nabla \Phi_r \times \nabla)
\]

\[
= -\epsilon' \frac{\nabla}{c} \times \nabla \Phi_r,
\]

and

\[
\overline{D} = -\epsilon' \frac{\partial \overline{A}}{\partial t} + \epsilon' \overline{\phi} \cdot \nabla \phi + \frac{1}{\mu' a} \overline{\Omega} \times \left[ \nabla \times (\overline{A} + \overline{\Omega} \Phi) \right].
\]
\[
\begin{align*}
\frac{\partial \phi}{\partial t} + \epsilon' \Omega = - \epsilon' \vec{\sigma} \cdot \nabla \phi - \frac{\epsilon' \nu}{c} \frac{\partial \phi}{\partial t} - \epsilon' \vec{\sigma} \cdot \nabla \phi = 0 \\
- \epsilon' \vec{\Omega} \times (\nabla \times \nabla \phi) 
\end{align*}
\]  
(4.37)

For this case it can be seen that for zero conductivity, \( \gamma \rho_r' \) vanishes, and so does \( \phi_r \) and \( \vec{H} \). Thus for lossless moving media when \( A \) and \( \phi \) have the same boundary conditions, \( \vec{H} = 0 \). In this case we have a static configuration in space, so the result that \( \vec{E} \times \vec{H} = 0 \) is to be expected, since there is no radiation at all.

4.1.2 Green's Function Solution

The system of equations for the potentials given in equations (4.31) and (4.32) is quite complicated, involving, as it does, three variables. It was seen in Section 3.2.1 that there is a steady-state behavior for the currents and charges for large \( t \) which is found either by letting \( t \) approach infinity or setting \( \partial / \partial t = 0 \) from the start. If the assumption is made that \( \partial / \partial t = 0 \), the differential equations simplify to

\[
(\nabla \cdot \vec{\sigma} \cdot \nabla) A - \sigma \mu' a v \frac{\partial A}{\partial z} = \frac{1}{\epsilon'} (\Omega \rho_s - a \frac{v}{c^2} \gamma \rho_r') 
\]

and

\[
(\nabla \cdot \vec{\sigma} \cdot \nabla) \phi - \sigma \mu' a v \frac{\partial \phi}{\partial z} = - \frac{1}{\epsilon'} (\rho_s + a \gamma \rho_r') 
\]  
(4.38)

The Green's function method utilizes a function \( G(\vec{R} \mid \vec{R}_o) \) which is the solution to a given differential equation when the source term is a point source in space at \( \vec{R}_o \); that is, \( G(\vec{R} \mid \vec{R}_o) \) satisfies the equation

\[
\left[ (\nabla \cdot \vec{\sigma} \cdot \nabla) - \sigma \mu' a v \frac{\partial}{\partial z} \right] G(\vec{R} \mid \vec{R}_o) = - \delta(\vec{R} \mid \vec{R}_o) 
\]  
(4.39)
where $\vec{R}$ is the vector from the origin to the field point, $\vec{R}_o$ is the vector from the origin to the source point, and the derivatives operate on the field coordinates. The symbol $\delta(\vec{R}|\vec{R}_o)$ denotes a quantity which vanishes for $\vec{R} \neq \vec{R}_o$, and has the property that

$$\int_V f(\vec{R}) \delta(\vec{R}|\vec{R}_o) \, dV = f(\vec{R}_o)$$

where the volume $V$ encloses the point $\vec{R}_o$. In all of the problems in this work we shall be dealing with unbounded media, so that for all fields, potentials, and Green's functions, the boundary conditions will be the radiation condition, namely that only functions which do not increase away from the source are allowed; also, that for unbounded media, the homogeneous solutions vanish. This means that no sources exist for the fields other than the given sources, which are assumed to occupy a finite region.

It will now be shown that the vector and scalar potentials are related to the Green's function in the following way:

$$\vec{\Lambda}(\vec{R}) = -\frac{1}{\varepsilon}, \quad \iint_{V_o} G(\vec{R}|\vec{R}_o) \left[ \vec{\nabla} \rho_s(\vec{R}_o) - \frac{\alpha V}{c^2} \gamma \vec{P}_r'(\vec{R}_o) \right] \, dV_o,$$

and

$$\phi(\vec{R}) = \frac{1}{\varepsilon}, \quad \iint_{V_o} G(\vec{R}|\vec{R}_o) \left[ \rho_s(\vec{R}_o) + a \gamma \rho_r'(\vec{R}_o) \right] \, dV_o, \quad (4.40)$$

where $V_o$ indicates a volume enclosing the sources. To show this, we shall define three-dimensional Fourier transforms and use the relation (3.54), extended to three-dimensions. Let the Fourier transform $\mathcal{F}$ of a function $F(\vec{R})$ be defined as follows:
\[
\mathcal{F}(\mathbf{h}) = (2\pi)^{-3} \iiint_{-\infty}^{\infty} e^{i \mathbf{h} \cdot \mathbf{R}_0} \mathcal{F}(\mathbf{R}_0) \, d^3\mathbf{R}_0 \ ,
\]

(4.41)

where \( d^3\mathbf{R}_0 = dx_0 \, dy_0 \, dz_0 \). Then if \( \mathcal{F}(\mathbf{R}_0) \) is class \( L^2 \) in each variable \( x_0', y_0', \) and \( z_0 \) for all real values of \( x_0', y_0', \) and \( z_0 \), the inverse transform is given by

\[
\mathcal{F}(\mathbf{R}) = \iiint_{-\infty}^{\infty} e^{-i \mathbf{h} \cdot \mathbf{R}} \mathcal{F}(\mathbf{h}) \, d^3\mathbf{h} \ ,
\]

(4.42)

where \( d^3\mathbf{h} = dh_x \, dh_y \, dh_z \). Taking the transform of both sides of (4.38a) and (4.39) gives:

\[
(-\mathbf{\bar{h}} \cdot \mathbf{a} \cdot \mathbf{h} + 1 \sigma \mu' \mathbf{a} \cdot \mathbf{h}) \mathbf{\bar{A}} = \mathbf{\bar{J}} \ ,
\]

and

\[
\begin{align*}
(-\mathbf{\bar{h}} \cdot \mathbf{a} \cdot \mathbf{h} + 1 \sigma \mu' \mathbf{a} \cdot \mathbf{h}) \mathcal{G}(\mathbf{h} | \mathbf{R}_0) &= (2\pi)^{-3} \iiint_{-\infty}^{\infty} \int_{\delta(R | \mathbf{R}_0)} \delta \, d^3\mathbf{R} \\
&= (2\pi)^{-3} e^{i \mathbf{h} \cdot \mathbf{R}_0} \ ,
\end{align*}
\]

(4.43)

where \( J \) represents the term on the right of (4.38a). From these relations,

\[
\mathbf{\bar{A}}(\mathbf{h}) = (2\pi)^3 e^{-i \mathbf{h} \cdot \mathbf{R}_0} \mathcal{F}(\mathbf{h}) \mathcal{G}(\mathbf{h} | \mathbf{R}_0) \ .
\]

(4.44)

The three-dimensional version of (3.54) follows from Parseval's theorem:

\[
\begin{align*}
\iiint_{-\infty}^{\infty} \mathcal{F}(\mathbf{h})^* \, d^3\mathbf{h} &= (2\pi)^{-3} \iiint_{-\infty}^{\infty} \mathcal{F}(\mathbf{R}_0)^* \, d^3\mathbf{R}_0 \ ,
\end{align*}
\]

(4.45)
where the asterisk (*) indicates the complex conjugate; this is subject to the conditions stated above. Let $\mathcal{F}(\vec{R}_0) = J(\vec{R}_0)$ so that $\mathcal{F}(\vec{h}) = \mathcal{F}(\vec{h})$.

Similarly, let

$$
\hat{H}^* (\vec{h}) = e^{-i\vec{h} \cdot (\vec{R} + \vec{R}_0)} \mathcal{G}(\vec{h} | \vec{R}_0).
$$

(4.46a)

Then

$$
\hat{H}(\vec{h}) = e^{i\vec{h} \cdot (\vec{R} + \vec{R}_0)} \mathcal{G}^*(\vec{h} | \vec{R}_0)
$$

and

$$
H(\vec{R}_1) = \int \int \int_{-\infty}^{\infty} e^{-i\vec{h} \cdot (\vec{R} - \vec{R}_0)} \mathcal{G}^*(\vec{h} | \vec{R}_0) \, d^3h,
$$

or

$$
H^*(\vec{R}_1) = \int \int \int_{-\infty}^{\infty} e^{-i\vec{h} \cdot (\vec{R} + \vec{R}_0 - \vec{R}_1)} \mathcal{G}(\vec{h} | \vec{R}_0) \, d^3h
$$

$$
= G(\vec{R} + \vec{R}_0 - \vec{R}_1 | \vec{R}_0).
$$

(4.46b)

Noting that $H^*(\vec{R}_0) = G(\vec{R} | \vec{R}_0)$ and using (4.42), (4.44), (4.45), and (4.46) to find $A(\vec{R})$,

$$
A(\vec{R}) = \int \int \int_{-\infty}^{\infty} e^{-i\vec{h} \cdot \vec{R}} \mathcal{A}(\vec{h}) \, d^3h = (2\pi) \int \int \int_{-\infty}^{\infty} e^{-i\vec{h} \cdot (\vec{R} + \vec{R}_0)} \mathcal{F}(\vec{h}) \mathcal{G}(\vec{h} | \vec{R}_0) \, d^3h
$$

$$
= \int \int \int_{-\infty}^{\infty} J(\vec{R}_0) \mathcal{G}(\vec{R} | \vec{R}_0) \, d^3R_0,
$$

(4.47)
which was to be proved. Substitution of the appropriate term for \( J \) yields Eq. (4.40). Similar results hold for \( \varphi(\vec{R}) \). It should also be noted that this discussion holds independently of the operator form; this will be useful later on.

We turn our attention now to finding the Green's function that satisfies Eq. (4.39), which in cylindrical components can be written:

\[
\frac{a}{r} \frac{\partial}{\partial r} r \frac{\partial G}{\partial r} + \frac{\sigma^2 G}{\partial z^2} - \sigma \mu' a v \frac{\partial G}{\partial z} = - \delta(\vec{R}) \frac{\delta(\vec{R})}{2\pi r} - \delta(\vec{R}_o) \frac{\delta(\vec{R}_o)}{2\pi r}.
\]

(4.48)

The parameter "a" can be either positive or negative, depending on the value of \( n\beta \); for low velocities \( n\beta < 1 \), and \( a > 0 \). For velocities which are very high, \( n\beta > 1 \), and \( a < 0 \); in this case the velocity \( v = \beta c \) of the medium is greater than the speed of light in the medium, \( c/n \), and the Cerenkov radiation condition is met. We shall treat both conditions in this work.

The method of solving the differential equations is straightforward: by taking appropriate transforms, the differential equation can be transformed into an algebraic expression like (4.43). The transformed unknown can then be expressed as a ratio of polynomials. Upon taking the inverse transforms, the solution can be expressed as a multiple integral. If we are fortunate, the integrals may be reduced to a closed form. This will prove to be the case in the present work.

Case A. Low Velocities: \( v < c/n \), and \( a > 0 \). Here we let \( \alpha^2 = a \), and \( b = \sigma \mu' \alpha^2 v/2 \), and without loss of generality, we may choose \( \vec{R}_o = 0 \) temporarily. Then (4.48) becomes

\[
\frac{1}{r} \frac{\partial}{\partial r} r \frac{\partial G}{\partial r} + \frac{1}{\alpha^2} \frac{\partial^2 G}{\partial z^2} - \frac{2b}{\alpha^2} \frac{\partial G}{\partial z} = - \frac{\delta(r)\delta(z)}{2\pi r \alpha^2}.
\]

(4.49)

The Hankel transform technique is well suited to this problem. Given a
function $f(r)$, the Hankel transform $H\{f\}$ is defined by

$$H\{f(r)\} = \int_0^\infty J_0(\lambda r) f(r) r \, dr,$$

(4.50)

for all functions $f(r)$ of class $L^1$, i.e. such that $\int_0^\infty |f(r)| \, dr$ is bounded. From the well-known theory of Hankel transforms, the function $f(r)$ is related to its transform by

$$f(r) = \int_0^\infty J_0(\lambda r) H\{f\} \lambda \, d\lambda.$$

(4.51)

It follows from the definition (4.50) that

$$H\left\{\frac{1}{r} \frac{\partial}{\partial r} r \frac{\partial f}{\partial r}\right\} = -\lambda^2 H\{f\}.$$

(4.52)

This can be shown as follows:

$$H\left\{\frac{1}{r} \frac{\partial}{\partial r} r \frac{\partial f}{\partial r}\right\} = \int_0^\infty J_0(\lambda r) \frac{\partial}{\partial r} \left(r \frac{\partial f}{\partial r}\right) \, dr$$

$$= J_0(\lambda r) r \frac{\partial f}{\partial r} \bigg|_0^\infty - \int_0^\infty r \frac{\partial f}{\partial r} \frac{\partial}{\partial r} J_0(\lambda r) \, dr$$

$$= 0 - f(r) \frac{J_0(\lambda r)}{\partial r} \bigg|_0^\infty + \int_0^\infty f(r) \left(\frac{1}{r} \frac{\partial}{\partial r} r \frac{\partial}{\partial r} J_0(\lambda r)\right) \, dr$$

$$= -\lambda^2 H\{f\},$$

(4.53)

where it is noted that from the definition of the Bessel function that
\[
\frac{1}{r} \frac{\partial}{\partial r} r \frac{\partial J_0(\lambda r)}{\partial r} + \lambda^2 J_0(\lambda r) = 0 ,
\]

and it is assumed that \( f(r) \) has a behavior such that:

\[
\lim_{r \to 0} f(r) r J_0(\lambda r) = \lim_{r \to 0} r \frac{\partial f}{\partial r} = 0 ,
\]

\[
\lim_{r \to 0} r f(r) (-\lambda^2 r) = -\lambda^2 \lim_{r \to 0} r^2 f(r) = 0 ,
\]

\[
\lim_{r \to \infty} r J_0(\lambda r) = \lim_{r \to \infty} \sqrt{\frac{2}{\pi}} \frac{\partial f}{\partial r} = 0 ,
\]

and

\[
\lim_{r \to \infty} r f(r) \frac{\partial J_0(\lambda r)}{\partial r} = \lim_{r \to \infty} \frac{\sqrt{2}}{\pi} \mathcal{F} \frac{\partial f}{\partial r} = 0 .
\]

Taking the Hankel transform of Eq. (4.49) gives

\[
\left( \lambda^2 - \frac{1}{\alpha^2} \frac{\partial^2}{\partial z^2} + \frac{2b}{\alpha^2} \right) H\{G\} = \frac{\delta(z)}{2\pi \alpha} .
\]

Further, taking the Fourier transform in \( z \) gives

\[
\left( \lambda^2 + \frac{h^2 - 2ibh}{\alpha^2} \right) F\left\{ H\{G\} \right\} = \frac{1}{4\pi \alpha} ,
\]

or

\[
F\left\{ H\{G\} \right\} = \frac{1/4 \pi^2}{(h - ib)^2 + \alpha^2 \lambda^2 + b^2} .
\]

48
The roots of the denominator are at

\[ h_{1,2} = i b \pm i \sqrt{\frac{\alpha^2 \lambda^2 + b^2}{\alpha \lambda + b}} \]  

\hspace{2cm} (4.58)

one is in the upper half-plane, one in the lower for all \( \lambda \). The inverse Fourier transform of (4.57) in \( h \) is given by

\[ H \{ G \} = \frac{1}{4\pi^2} \int_{-\infty}^{\infty} \frac{e^{-ihz} \, dh}{(h-h_1)(h-h_2)} \]  

\hspace{2cm} (4.59)

From the exponential it is evident that for \( z < 0 \) the contour can be closed in the upper half plane, and for \( z > 0 \) closed in the lower half plane, and the theory of residues applied. For \( z < 0 \), the residue is
\[
\frac{e^{bz} e^{-z\sqrt{\frac{\alpha^2 \lambda^2}{\alpha^2 \lambda^2 + b^2}}}}{2iz\sqrt{\frac{\alpha^2 \lambda^2}{\alpha^2 \lambda^2 + b^2}}},
\]
and for \( z > 0 \), it is
\[
\frac{e^{bz} e^{-z\sqrt{\frac{\alpha^2 \lambda^2}{\alpha^2 \lambda^2 + b^2}}}}{-2iz\sqrt{\frac{\alpha^2 \lambda^2}{\alpha^2 \lambda^2 + b^2}}}
\]
Noting that the contour in the lower half-plane is counterclockwise, (4.59) becomes
\[
H\{G\} = \frac{1}{4\pi} \frac{e^{bz} e^{-z\sqrt{\frac{\alpha^2 \lambda^2}{\alpha^2 \lambda^2 + b^2}}}}{2iz\sqrt{\frac{\alpha^2 \lambda^2}{\alpha^2 \lambda^2 + b^2}}}
\]
\[
= \frac{1}{4\pi} e^{bz} \frac{e^{-z\sqrt{\frac{\alpha^2 \lambda^2}{\alpha^2 \lambda^2 + b^2}}}}{\sqrt{\frac{\alpha^2 \lambda^2}{\alpha^2 \lambda^2 + b^2}}}
\]
(4.60)
The inverse Hankel transform, from Eq. (4.51), gives the integral
\[
G = \frac{e^{bz}}{4\pi \alpha} \int_{0}^{\infty} J_{\alpha}(\lambda r) \frac{e^{-\alpha|z|\sqrt{\frac{\lambda^2}{\lambda^2 + b^2/\alpha^2}}}}{\sqrt{\frac{\lambda^2}{\lambda^2 + b^2/\alpha^2}}} \lambda d\lambda 
\]
(4.61)
This can be solved by a change of variables: let \( \xi^2 = \lambda^2 + b^2/\alpha^2 \); then
\( \xi \, d\xi = \lambda \, d\lambda \), and the positive real axis in \( \lambda \) maps into the straight line contour \( b/\alpha < \xi < \infty \) in \( \xi \). Then Eq. (4.61) can be written
\[
G = \frac{e^{bz}}{4\pi \alpha} \int_{b/\alpha}^{\infty} e^{-\alpha|z|\xi} J_{\alpha}\left(\xi \sqrt{\frac{\xi^2 - b^2/\alpha^2}{\lambda^2}}\right) d\xi
\]
(4.62)
This is a tabulated Laplace transform given, for example, in Magnus and Oberhettinger (1954), p. 132. Finally, the Green's function can be written as

\[ G(\overline{R} | 0) = \frac{e^b z}{4\pi \alpha} \frac{e^{-b \sqrt{\frac{r^2 + 2}{\alpha}}}}{\sqrt{\frac{r^2 + 2}{\alpha} z^2}}. \]  

(4.63)

Replacing \( \overline{R} \) by \( \overline{R} - \overline{R}_o \) and substituting for \( \alpha \) and \( b \) gives

\[ G(\overline{R} | \overline{R}_o) = e^{\frac{\sigma \mu' a v}{2} (z - z_o)} e^{-\frac{\sigma \mu' a v}{2} R_1} \frac{e^{\frac{1}{2} \alpha R_1}}{4\pi a^{1/2} R_1}. \]  

(4.64)

where \( R_1 = \sqrt{(r - r_o)^2 + a(z - z_o)^2} \). This is the form desired. Note that as \( \sigma \to 0 \), this becomes simply

\[ G(\overline{R} | \overline{R}_o) = \frac{1}{4\pi a^{1/2} R_1}. \]  

(4.65)

Case B. High Velocities: \( v > c/a \), and \( a < 0 \). Here we let \( \alpha^2 = -a \) and define \( b \) as before, i.e. \( b = \sigma \mu' \alpha^2 v/2 \). Again letting \( \overline{R}_o = 0 \) Eq. (4.48) now becomes

\[ \frac{1}{r} \frac{\partial}{\partial r} r \frac{\partial G}{\partial r} - \frac{1}{2} \frac{\partial^2 G}{\partial z^2} - \frac{2b}{\alpha} \frac{\partial G}{\partial z} = \frac{\delta(r) \delta(z)}{2\pi r \alpha}. \]  

(4.66)

Taking the Fourier transform first this time gives

\[ \left( \frac{1}{r} \frac{\partial}{\partial r} r \frac{\partial}{\partial r} + \frac{h^2 + 2ibh}{\alpha^2} \right) F\{G\} \left( \frac{\delta(r)}{4\pi r \alpha^2} \right). \]  

(4.67)
Taking the Hankel transform and using (4.52) yields the algebraic expression

$$\left[ \lambda^2 - \frac{h^2 + 2i\hbar}{\alpha^2} \right] \ H \left\{ F \{G\} \right\} = -\frac{1}{4\pi^2} \frac{z^2}{\alpha}, \quad (4.68)$$

or

$$H \left\{ F \{G\} \right\} = \frac{-1/4\pi^2}{\lambda^2 - \left( \frac{h^2 + 2i\hbar}{\alpha^2} \right)} \frac{2}{\alpha}. \quad (4.69)$$

The inverse Hankel transform of (4.69), using Eq. (4.51) is then

$$F \{G\} = \frac{1}{4\pi^2} \int_0^\infty \frac{J_0(\lambda r) \lambda \, d\lambda}{\lambda^2 - \left( \frac{h^2 + 2i\hbar}{\alpha^2} \right)} \quad (4.70)$$

Now \( J_0(\lambda r) = \frac{1}{2} H_0^{(1)}(\lambda r) + \frac{1}{2} H_0^{(2)}(\lambda r) \). If \( R(\lambda^2) \) denotes a rational function in \( \lambda^2 \), then

$$\int_0^\infty H_0^{(2)}(\lambda r) R(\lambda^2) \lambda \, d\lambda = \int_{-\infty}^{-\infty} H_0^{(2)}(e^{i\pi} \lambda r) R(\lambda^2) (-\lambda) (-d\lambda)$$

$$= \int_{-\infty}^0 H_0^{(2)}(e^{i\pi} \lambda r) R(\lambda^2) \lambda \, d\lambda$$

$$= \int_{-\infty}^0 H_0^{(1)}(\lambda r) R(\lambda^2) \lambda \, d\lambda \quad (4.71)$$

since

$$H_0^{(2)}(e^{i\pi} z) = -H_0^{(1)}(z),$$

52
from the circuit relations for the Hankel functions. (See, for example, Sommerfeld (1949), p. 315, (11)). Thus (4.70) can be written

\[
F\{G\} = -\frac{1}{8\pi^2 \alpha^2} \int_C \frac{H_0^{(1)}(\lambda r) \lambda d\lambda}{\lambda^2 - \left(\frac{n^2 + 21\lambda b}{\alpha^2}\right)}, \quad (4.72)
\]

where the contour \( C \) is given in Fig. 4-2, and the branch cut must not be taken in the upper half-plane. (Otherwise, the circuit relation above could not hold).

**FIG. 4-2: CONTOURS IN THE \( \lambda \)-PLANE FOR EVALUATING \( F \{G\} \).**

It is well known that the asymptotic behavior of the Hankel function is given by

\[
H_0^{(1)}(\lambda r) \sim \sqrt{\frac{2}{\pi \lambda r}} e^{i\lambda r} e^{-\lambda /4}
\]

for large amplitudes of \( \lambda \), and since \( r > 0 \), the contour can be closed in the
upper half-plane, enclosing only the pole at \( \lambda_1 = \frac{1}{\alpha} \sqrt{h^2 + 21h b} \). By the theory of residues, (4.72) becomes
\[
F\{G\} = -\frac{1}{8\pi^2} \cdot \frac{2\pi i}{\alpha^2} \cdot \frac{H^{(1)}_0 \left[ \frac{r}{\alpha} \sqrt{h^2 + 21h b} \right]}{2\lambda_1} \lambda_1
\]
\[
= -\frac{i}{8\pi^2} H^{(1)}_0 \left[ \frac{r}{\alpha} \sqrt{h^2 + 21h b} \right].
\] (4.73)

The inverse Fourier transform in \( h \) gives
\[
G(\tilde{R}|0) = \frac{1}{8\pi^2} \int_{-\infty}^{\infty} e^{-iz} H^{(1)}_0 \left[ \frac{r}{\alpha} \sqrt{h^2 + 21h b} \right] dh. \] (4.74)

The argument of the Hankel function vanishes at \( h = 0 \) and \( h = -21b \), the Hankel function itself behaves logarithmically at these points, so that these points are branch points, and the branch cuts must extend to infinity. Thus it is appropriate to choose the branch cut so that it lies along the negative imaginary axis, as in Fig. 4-3.

![Fig. 4-3: Contours in the h-plane for evaluating G(\tilde{R}|0).](image)

FIG. 4-3: CONTOURS IN THE h-PLANE FOR EVALUATING G(\tilde{R}|0).
For large amplitudes of \( h \), the integrand behaves as

\[
\exp \left[ -i h \left( z - \frac{r}{\alpha} \right) \right].
\]

Thus for \( z < r/\alpha \), the contour can be closed in the upper-half plane, and for \( z > r/\alpha \) it can be closed in the lower half-plane.

For \( z < r/\alpha \) the contour in the upper-half plane encloses no poles and encounters no branch cuts; furthermore, since the Hankel function behaves logarithmically near the branch points, the integral around the branch points vanishes, leaving

\[
G(\bar{R}10) = 0 \text{ for } z < r/\alpha .
\]

(4.75)

For \( z > r/\alpha \), the presence of the branch cut dictates that the imaginary axis cannot be crossed, and since no poles are enclosed,

\[
\int_C = \int_{C_1} ,
\]

(4.76)

where the contours are indicated in Fig. 4-7.

It is necessary to examine the argument of the Hankel function with some care. Assuming the radical is taken as positive, the arguments of the radical can be obtained for the contour \( C_1 \) in the following manner: for \( \arg h = -\pi/2 \), or \( h = -iA \), where \( A = |h| \),

\[
\arg \sqrt{h^2 + 2ihb} = \begin{cases} 
\arg \left( -i \right) & A < 2b \\
\arg \left( -iA^2 - 2Ab \right) & A > 2b 
\end{cases}
\]

\[
= \begin{cases} 
0, & A < 2b \\
-\pi/2, & A > 2b
\end{cases} .
\]

(4.77)
Similarly for \( \arg h = 3\pi/2 \), or \( h = \imath^3 A \),

\[
\arg \sqrt[6]{h^2 + 2\imath h} = \arg \sqrt[4]{1^2 A^2 + 2^1 A^2}
\]

\[
= \arg \sqrt[2]{2 A^2 + 1^2 A^2}
\]

\[
= \begin{cases} 
\arg \left( \imath^2 \sqrt[2]{2 A^2 - A^2} \right), & A < 2b \\
\arg \left( \imath^3 \sqrt[2]{A^2 - 2 A b} \right), & A > 2b 
\end{cases}
\]

\[
= \begin{cases} 
\pi, & A < 2b \\
3\pi/2, & A > 2b 
\end{cases}.
\]

Comparing (4.77) with (4.78), it can be seen that for \( A < 2b \), the argument of the radical along the left side of the contour \( C_1 \) differs from that along the right by \( \pi \), and for \( A > 2b \), this difference is \( 2\pi \).

Thus for \( z > r/\alpha \), (4.74) can be written

\[
G(\overline{z})_0 = \frac{1}{8\pi^2} \left\{ \int_0^{-i2b} - \int_0^{i2b} - \int_{-i2b}^{-i\infty} - \int_{i2b}^{i\infty} \right\}
\]

\[
= \frac{1}{8\pi^2} \left\{ \int_0^{-i2b} e^{-ihz} \left[ H(1) \left( \frac{r}{b} \sqrt{h^2 + 2ibh} \right) - H(1) \left( \frac{r}{b} e^{i\pi \sqrt{h^2 + 2ibh}} \right) \right] dh \\
+ \int_{-i2b}^{-i\infty} e^{-ihz} \left[ H(1) \left( \frac{r}{b} \sqrt{h^2 + 2ibh} \right) - H(1) \left( \frac{r}{b} e^{i2\pi \sqrt{h^2 + 2ibh}} \right) \right] dh \right\}.
\]

\[
\text{(4.79)}
\]
Substituting \( u = i(h + i b) \) in the first integral and \( v = i(h + i b) \) in the second, this becomes

\[
G(\mathcal{R}|0) = -\frac{e^{-bz}}{8\pi a^2} \left\{ \int_{-b}^{b} e^{-u z} \left[ H_{0}^{(1)} \left( \frac{r}{a} \sqrt{b^2 - u^2} \right) - H_{0}^{(1)} \left( \frac{r}{a} e^{i\pi} \sqrt{b^2 - u^2} \right) \right] du \right. \\
+ \int_{b}^{\infty} e^{-v z} \left[ H_{0}^{(1)} \left( \frac{ir}{a} \sqrt{v^2 - b^2} \right) - H_{0}^{(1)} \left( \frac{ir}{a} e^{i2\pi} \sqrt{v^2 - b^2} \right) \right] dv \left. \right\}.
\]

\[\text{(4.80)}\]

From the circuit relations given, for example, in Sommerfeld, \(1949\) p. 314, we have

\[
H_{0}^{(1)}(e^{i\pi} z) = -H_{0}^{(2)}(z)
\]

and

\[
H_{0}^{(1)}(e^{i2\pi} z) = -2H_{0}^{(2)}(z) - H_{0}^{(1)}(z),
\]

\[\text{(4.81)}\]

which when substituted into \(4.80\) gives

\[
G(\mathcal{R}|0) = -\frac{e^{-bz}}{8\pi a^2} \left\{ 2 \int_{-b}^{b} e^{-u z} J_{0} \left( \frac{r}{a} \sqrt{b^2 - u^2} \right) du + 4 \int_{b}^{\infty} e^{-v z} J_{0} \left( \frac{ir}{a} \sqrt{v^2 - b^2} \right) dv \right\}.
\]

\[\text{(4.82)}\]

Since \( J_{0}(-1z) = J_{0}(1z) = I_{0}(z) \), where \( I_{0} \) is the modified Bessel function, this can be written

\[
G(\mathcal{R}|0) = -\frac{e^{-bz}}{2\pi a^2} \left\{ \frac{1}{2} \int_{-b}^{b} e^{-u z} J_{0} \left( \frac{r}{a} \sqrt{b^2 - u^2} \right) du + \int_{b}^{\infty} e^{-v z} I_{0} \left( \frac{r}{a} \sqrt{v^2 - b^2} \right) dv \right\}.
\]

\[\text{(4.83)}\]

The right-hand integral is a tabulated Laplace transform given, for example, in Magnus and Oberhettinger \(1954\), p. 134:
\[
\int_{b}^{\infty} e^{-vz} I_{0} \left( \frac{r}{\alpha} \sqrt{v^2 - b^2} \right) dv = e^{-b} \sqrt{\frac{2}{z^2 - r^2/\alpha^2}}. \tag{4.84}
\]

The finite integral of (4.83) is more involved. First of all, we note that \( J_{0} \) is an even function in \( u \), so that

\[
\frac{1}{2} \int_{-b}^{b} e^{-uz} J_{0} \left( \frac{r}{\alpha} \sqrt{b^2 - u^2} \right) du = \frac{1}{2} \int_{-b}^{b} \cosh(uz) J_{0} \left( \frac{r}{\alpha} \sqrt{b^2 - u^2} \right) du
\]

\[
= \int_{0}^{b} \cosh uz J_{0} \left( \frac{r}{\alpha} \sqrt{b^2 - u^2} \right) du = \int_{0}^{b} \cos(1uz) J_{0} \left( \frac{r}{\alpha} \sqrt{b^2 - u^2} \right) du
\]

\[
= \frac{\pi iz}{2} \int_{0}^{b} J_{-1/2}(1uz) J_{0} \left( \frac{r}{\alpha} \sqrt{b^2 - u^2} \right) u^2 du,
\]

since \( J_{-1/2}(z) = \sqrt{\frac{2}{\pi z}} \cos z \). Let \( u = b \sin \theta \); then \( \sqrt{b^2 - u^2} = b \cos \theta \), and this becomes

\[
\sqrt{\frac{\pi iz}{2}} b^2 \int_{0}^{\pi/2} J_{-1/2} (b \sin \theta) J_{0} \left( \frac{rb}{\alpha} \cos \theta \right) \sin^{1/2} \theta \cos \theta d \theta.
\tag{4.85}
\]

Now Sonine's second finite integral can be written (see Watson (1922), p. 376)

\[
\int_{0}^{\pi/2} J_{\mu} (z_1 \sin \theta) J_{\nu} (Z \cos \theta) \sin^{\mu + 1} \theta \cos^{\nu + 1} \theta d \theta
\]

\[
= \frac{Z^\nu}{\nu + 1} J_{\mu + \nu + 1} \left( \frac{\sqrt{Z^2 + Z_1^2}}{(Z^2 + Z_1^2)^{1/2}} \right). \tag{4.86}
\]

58
Thus by letting $\mu = -1/2$, $\nu = 0$, $z_1 = ibz$, $Z = rb/\alpha$, (4.85) becomes

$$
\sqrt{\pi}ib^3 \cdot (ibz)^{-1/2} \frac{J_{1/2}\left(\frac{r}{\alpha}\sqrt{\frac{2}{z}} - \frac{2z}{r^2} \right)}{b^{1/2} \sqrt{\frac{r^2}{z^2} - \frac{2z}{r^2} \frac{1}{\alpha^2}}} = \sinh\left(\frac{b}{z} \sqrt{\frac{2}{z} - \frac{r^2}{\alpha^2}}\right)
$$

(4.87)

Thus, using (4.83), (4.84), and (4.87), we find that

$$
G(\mathbf{R}|0) = -\frac{e^{-bz}}{2\pi \alpha} \left[ \frac{\sinh\left(\frac{b}{z} \sqrt{\frac{2}{z} - \frac{r^2}{\alpha^2}}\right) + e^{-b\sqrt{\frac{2}{z} - \frac{r^2}{\alpha^2}}}}{\sqrt{\frac{2}{z} - \frac{r^2}{\alpha^2}}} \right]
$$

$$
= -\frac{e^{-bz}}{2\pi \alpha} \frac{\cosh\left(\frac{b}{\alpha} \sqrt{\frac{2}{z} \alpha^2 - r^2}\right)}{\sqrt{\frac{2}{z} \alpha^2 - r^2}}.
$$

(4.88)

Letting $R$ be replaced by $R_0$ and noting the definitions of $\alpha$ and $b$, we have the desired solution for the Green's function:

$$
G(\mathbf{R}|\mathbf{R}_0) = \begin{cases} 0, & |a|(z-z_o) < (r-r_o) \\ -\frac{\sigma |a| \sqrt{z-z_o}}{2} \cosh\left[\frac{1}{2} \sigma \frac{1/2 |a|}{\alpha} \sqrt{R_0^2}, |a|(z-z_o) > (r-r_o) \right] \\ -\frac{\sigma |a| \sqrt{z-z_o}}{2} \cosh\left[\frac{1}{2} \sigma \frac{1/2 |a|}{\alpha} \sqrt{R_0^2}, |a|(z-z_o) > (r-r_o) \right] \\ -\frac{\sigma |a| \sqrt{z-z_o}}{2} \cosh\left[\frac{1}{2} \sigma \frac{1/2 |a|}{\alpha} \sqrt{R_0^2}, |a|(z-z_o) > (r-r_o) \right] \\ -\frac{\sigma |a| \sqrt{z-z_o}}{2} \cosh\left[\frac{1}{2} \sigma \frac{1/2 |a|}{\alpha} \sqrt{R_0^2}, |a|(z-z_o) > (r-r_o) \right] \\ -\frac{\sigma |a| \sqrt{z-z_o}}{2} \cosh\left[\frac{1}{2} \sigma \frac{1/2 |a|}{\alpha} \sqrt{R_0^2}, |a|(z-z_o) > (r-r_o) \right] \end{cases}
$$

(4.89)

where $R_0 = \sqrt{(z-z_o)^2 + |a| - (r_r_o)^2}$. The Cerenkov cone is defined by
\[ |a|^{1/2} (z - z_o) = r - r_o , \]

or

\[ (z - z_o) = \gamma \sqrt{n^2 \beta^2 - (r - r_o)} . \]  \hspace{1cm} (4.90)

**FIG. 4-4: CERENKOV CONE GEOMETRY FOR HIGH VELOCITIES.**

In Fig. 4-4,

\[ \theta = \cot^{-1} \left( \gamma \sqrt{n^2 \beta^2 - 1} \right) = \cos^{-1} \left( \frac{\sqrt{n^2 \beta^2 - 1}}{\sqrt{n^2 \beta^2 - \beta^2}} \right) , \]  \hspace{1cm} (4.91)

which for \( \beta \) small, while \( n \beta > 1 \), approaches the familiar shock wave formula

\[ \theta \approx \sin^{-1} (1/n\beta) . \]  \hspace{1cm} (4.92)

From the solution (4.89) it can be seen that as \( z - z_o \) increases, the solution decays exponentially, since the exponential dominates over the hyperbolic
costne function of large values of \( z - z_0 \). For lossless media, this approaches the well-known result

\[
G(\bar{R} | \bar{R}_o) = \begin{cases} 
0, & z < r/|a|^{1/2} \\
-\frac{1}{2\pi|a|^{1/2}R_2}, & z > r/|a|^{1/2} 
\end{cases}
\]  \quad (4.93)

4.1.3 Summary

Let us now summarize the results for static charge distributions, where \( \partial / \partial t = 0 \): given a static source charge distribution \( \rho_s(\bar{R}_o) \) in a moving conducting medium, the fields are related to the vector and scalar potentials by

\[
\bar{B} = \nabla \times \bar{A}, \quad \bar{E} = -\nabla \phi,
\]

\[
\bar{H} = \frac{1}{\mu'\alpha} \nabla \times (\bar{A} + \bar{\Omega} \phi),
\]

\[
\bar{D} = \varepsilon' \bar{\varepsilon} \cdot \nabla \phi + \frac{1}{\mu'\alpha} \bar{\Omega} \times \left[ \nabla \times (\bar{A} + \bar{\Omega} \phi) \right], \quad (4.94)
\]

and the potentials are related to the sources by

\[
\bar{A}(\bar{R}) = -\frac{1}{\varepsilon'} \iiint_{V_o} G(\bar{R} | \bar{R}_o) \left[ \bar{\Omega} \rho_s(\bar{R}_o) - \frac{a\bar{v}}{c^2} \gamma \rho'_r(\bar{R}_o) \right] dV_o,
\]

\[
\phi(\bar{R}) = \frac{1}{c^2} \iiint_{V_o} G(\bar{R} | \bar{R}_o) \left[ \rho_s(\bar{R}_o) + a \gamma \rho'_r(\bar{R}_o) \right] dV_o, \quad (4.95)
\]

where the volume \( V_o \) encloses the sources; the response charge is related to the source charge density by

61
\[ \gamma \rho_s^r \left( \mathbf{R}^r_0 \right) = -\frac{\alpha}{\epsilon' \nu} \int_{-\infty}^{z_0} \exp \left[ -\frac{\alpha}{\epsilon' \gamma \nu} (z_0 - \xi) \right] \rho_s(\mathbf{R}^r_0, \xi) \, d\xi, \quad (4.96) \]

and the Green's function is given by

\[ G(\mathbf{R}|\mathbf{R}^r_0) = \frac{e^{-\frac{\mu' a v}{2} (z-z_0)}}{4 \pi a^{1/2} R_1} \quad n \beta < 1 \]

or

\[ G(\mathbf{R}|\mathbf{R}^r_0) = \begin{cases} 
0, & |a|(z-z_0) < (r-r_0) \\
-\frac{\alpha \mu' a v}{2} (z-z_0) e^{-\frac{\mu' a v}{2} R_1} \cos h \left( \frac{\mu' a^{1/2} v}{2} \frac{R_2}{2} \right), & |a|(z-z_0) > (r-r_0) 
\end{cases} \quad n \beta > 1 \]

where

\[ R_1^2 = (r-r_0)^2 + a(z-z_0)^2 \]

and

\[ R_2^2 = |a|(z-z_0)^2 - (r-r_0)^2. \quad (4.97) \]

4.2 Harmonic Current Source Distributions

4.2.1 Differential Equations for the Potentials

One way to approach the problem of harmonic current source distributions would be to develop a differential equation of the form (4.31) for current sources, and make the substitution \( \partial/\partial t = -i\omega \). It turns out that there is another approach which develops a Green's function equation that is considerably simpler. This
development follows that of Tai (1965b) for lossless media, and involves the introduction of a set of potentials differing from $\bar{A}$ and $\phi$.

For harmonically oscillating fields, Maxwell's equations can be written, where all quantities have the time dependence $e^{-i\omega t}$,

\[ \nabla \times \bar{E} = i \omega \bar{B} \quad \text{(Ih)}, \quad \nabla \cdot \bar{D} = \rho \quad \text{(IIh)}, \quad \nabla \times \bar{H} = \bar{J} - i \omega \bar{D} \quad \text{(IIIh)}, \quad \nabla \cdot \bar{B} = 0 \quad \text{(IVh)}. \]

The constitutive relations are given by

\[ \bar{B} = \mu' \bar{\sigma} \cdot \bar{H} - \bar{\Omega} \times \bar{E}, \]

\[ \bar{D} = \epsilon' \bar{\sigma} \cdot \bar{E} + \bar{\Omega} \times \bar{H}, \]

and

\[ \bar{J} = \bar{J}_s + \gamma \rho_{r} \bar{v} + \sigma (\bar{\sigma} \cdot \bar{E} + \mu' a \bar{v} \times \bar{H}), \]

where

\[ \rho = \rho_s + \gamma \rho_{r} + \sigma \frac{\bar{v} \cdot \bar{E}}{c} \quad \text{.} \quad (4.98) \]

Substituting the constitutive relations into Maxwell's equations (I) - (IV) and eliminating $\bar{B}$ and $\bar{D}$, we get for (Ih) and (IIIh),

\[ (\nabla + i \omega \bar{\Omega}) \times \bar{E} = i \omega \mu' \bar{\sigma} \cdot \bar{H}, \]

and

\[ (\nabla + i \omega \bar{\Omega} - \sigma \mu' a \bar{v}) \times \bar{H} = -i \omega \epsilon' \bar{\sigma} \cdot \bar{E} + \bar{J}_s + \gamma \rho_{r} \bar{v}. \quad (4.99) \]

Let

\[ \bar{p} = \sigma \mu' a \bar{v}. \]

Equation (4.99) can be simplified by introducing two auxiliary field vectors $\bar{E}_1$ and $\bar{H}_1$ defined as follows:
$$\vec{E}_1 = e^{i\omega \Omega z} \vec{E} ,$$

and

$$\vec{H}_1 = e^{(i\omega \Omega - p)z} \vec{H} .$$  (4.100)

Then

$$\nabla \times \vec{E} = \nabla \times (e^{-i\omega \Omega z} \vec{E}_1) = e^{-i\omega \Omega z} \nabla \times \vec{E}_1 + \nabla (e^{-i\omega \Omega z}) \times \vec{E}_1 ,$$

$$= e^{-i\omega \Omega z} \left[ \nabla \times \vec{E}_1 - i\omega \vec{\Omega} \times \vec{E}_1 \right] .$$  (4.101)

Similarly

$$\nabla \times \vec{H} = e^{(-i\omega \Omega + p)z} \left[ \nabla \times \vec{H}_1 - i\omega \vec{\Omega} \times \vec{H}_1 + \vec{p} \times \vec{H}_1 \right] .$$  (4.102)

Substituting these relations into (4.99) gives

$$\nabla \times \vec{E}_1 = i\omega \mu' \ e^{\rho z} \frac{\vec{\sigma}}{\sigma} \cdot \vec{H}_1 ,$$  (4.103a)

and

$$\nabla \times \vec{H}_1 = (-i\omega \epsilon' + \sigma) \ e^{-\rho z} \frac{\vec{\sigma}}{\sigma} \cdot \vec{E}_1 + (\vec{j}_s + \gamma \rho' \nabla) e^{(i\omega \Omega - p)z} .$$  (4.103b)

By taking the divergence of the first relation (4.103a),

$$\nabla \cdot \nabla \times \vec{E}_1 = 0 = i\omega \mu' \ \nabla \cdot \left( e^{\rho z} \frac{\vec{\sigma}}{\sigma} \cdot \vec{H}_1 \right) ,$$  (4.104)

so that we can partially define a vector potential $\vec{A}_1$ by

$$\mu' e^{\rho z} \frac{\vec{\sigma}}{\sigma} \cdot \vec{H}_1 = \nabla \times \left( \frac{\vec{\sigma}^{-1}}{\sigma} \cdot \vec{A}_1 \right) ,$$

or

$$\mu' \vec{H}_1 = e^{-\rho z} \frac{\sigma^{-1}}{\sigma} \left[ \nabla \times \left( \frac{\sigma^{-1}}{\sigma} \cdot \vec{A}_1 \right) \right] .$$  (4.105)

From Eq. (4.103), $\vec{E}_1$ is then related by
\[ E_1 = i\omega \cdot \tau - 1 \cdot A_1 - \nabla \phi_1, \quad (4.106) \]

where \( \phi_1 \) is a scalar potential.

Substituting the potentials into the second relation (4.103b), we get

\[
\nabla \times \left[ e^{-p \cdot z} \frac{1}{\alpha} \cdot \left( \nabla \times \left( \frac{1}{\alpha} \cdot A_1 \right) \right) \right] = \mu' (-i\omega \epsilon_1 + \sigma) e^{-p \cdot z} \left( i\omega A_1 - \sigma \cdot \nabla \phi_1 \right)
+ \mu' \left( \tau_s + \gamma \rho_r \nabla \right) e^{(i\omega \Omega - p) \cdot z}. \quad (4.107)
\]

Using the vector identity

\[
\nabla \times (\psi \tau) = \psi \nabla \times \tau + \nabla \psi \times \tau,
\]

Eq. (4.107) can be written, after regrouping terms, as

\[
\nabla \times \left[ e^{-\frac{p \cdot z}{\alpha}} \cdot \left( \nabla \times \left( \frac{1}{\alpha} \cdot A_1 \right) \right) \right] - \frac{\mathbf{p}}{a} \times \left[ \nabla \times \left( \frac{1}{\alpha} \cdot A_1 \right) \right] - k^2 A_1
= (i\omega \mu' \epsilon_1 - \sigma \mu') \cdot \nabla \phi_1 + \mu' \left( \tau_s + \gamma \rho_r \nabla \right) e^{i\omega \Omega \cdot z}, \quad (4.108)
\]

where \( k^2 = \omega^2 \mu' \epsilon_1 + i\omega \sigma \mu'. \)

Similarly, using (IIh), another equation can be found:

\[
\nabla \cdot D = \epsilon_1 \nabla \cdot \sigma \cdot E + \nabla \cdot (\Omega \times H) = \epsilon_1 \nabla \cdot \sigma \cdot E - \Omega \cdot \nabla \times H
= e^{i\omega \Omega \cdot z} \left( \nabla \cdot \sigma \cdot E_1 - i\omega \Omega \cdot E \right)
= e^{-i\omega \Omega \cdot z} \left( \nabla \cdot \sigma \cdot E_1 - i\omega \Omega \cdot E \right)
- e^{-(i\omega \Omega - p) \cdot z} \Omega \cdot \left[ \nabla \times H_1 - (i\omega \Omega - p) \times H_1 \right]
= e^{-i\omega \Omega \cdot z} \left( \nabla \cdot \sigma \cdot E_1 - i\omega \Omega \cdot E \right)
- e^{-(i\omega \Omega - p) \cdot z} \Omega \cdot \left[ e^{-p \cdot z} (i\omega \epsilon_1 + \sigma) \sigma \cdot E_1 + e^{(i\omega \Omega - p) \cdot z} \left( \tau_s + \gamma \rho_r \nabla \right) \right]
\]

65
\[ = e^{-i\omega \Omega z} \left[ \varepsilon' \nabla \cdot \vec{\alpha'} \cdot \vec{E}_1 - \sigma \vec{\Omega} \cdot \vec{E}_1 \right] - \vec{\Omega} \cdot \vec{J}_s - \gamma \rho_r' v \Omega \]

\[ = \rho_s + \gamma \rho_r' + \sigma \frac{\vec{\nabla} \cdot \vec{E}_1}{c^2} \]

\[ = \rho_s + \gamma \rho_r' + \sigma \frac{\vec{\nabla} \cdot \vec{E}_1}{c^2} e^{-i\omega \Omega z} \quad (4.109) \]

Substituting the potentials through the relation (4.106), and grouping terms, we obtain

\[ \nabla \cdot \vec{\Omega} - \frac{\sigma}{\epsilon' c^2} \left( \frac{\vec{\nabla} \cdot \vec{E}_1}{c^2} + \vec{\Omega} \right) \cdot \nabla \phi_1 = i \omega \nabla \cdot \vec{A}_1 - \frac{i \omega \sigma}{\epsilon' c^2} \left( \frac{\vec{\nabla} \cdot \vec{E}_1}{c^2} + \vec{\Omega} \right) \cdot \vec{A}_1 \]

\[ - \frac{1}{\epsilon'} \left[ \vec{\Omega} \cdot \vec{J}_s + (1 + \nu \Omega) \gamma \rho_r' + \rho_s \right] e^{i\omega \Omega z} \quad (4.110) \]

Since \(1 + \nu \Omega = a_\nu\), and \(\frac{\vec{\nabla} \cdot \vec{E}_1}{c^2} + \Omega = \mu' \epsilon' a_\nu\), thus can be written as

\[ \nabla \cdot \vec{\Omega} - \frac{\sigma}{\epsilon' c^2} \nabla \phi_1 = i \omega \nabla \cdot \vec{A}_1 - i \omega \vec{p} \cdot \vec{A}_1 - \frac{1}{\epsilon'} \left[ \vec{\Omega} \cdot \vec{J}_s + \rho_s + a \gamma \rho_r' \right] e^{i\omega \Omega z} \quad (4.111) \]

Equations (4.109) and (4.111) are two coupled equations for \(\vec{A}_1\) and \(\phi_1\). We are free to further define the potentials by a gauge condition, which we choose to be

\[ \nabla \cdot \vec{A}_1 - \vec{p} \cdot \vec{A}_1 = (i \omega \epsilon' - \sigma) \mu' a_\nu^2 \phi_1 \quad (4.112) \]

We have immediately then, from (4.111),

\[ \nabla \cdot \vec{\Omega} - \vec{p} \cdot \nabla \phi_1 + \frac{2 a_\nu^2}{c^2} \phi_1 = -\frac{1}{\epsilon'} \left[ \vec{\Omega} \cdot \vec{J}_s + \rho_s + a \gamma \rho_r' \right] e^{i\omega \Omega z} \quad (4.113) \]

Turning our attention to Eq. (4.108), it can be seen that (4.14) can be applied directly to the first term. Noting the vector identity...
\[ \nabla (\mathbf{\bar{c}} \cdot \mathbf{F}) = \mathbf{\bar{c}} \times (\nabla \times \mathbf{F}) + (\mathbf{\bar{c}} \cdot \nabla) \mathbf{F} \]

for constant \( \mathbf{\bar{c}} \), the second term of (4.108) becomes

\[
\frac{1}{a} \mathbf{\bar{p}} \times \left[ \nabla \times (\mathbf{\bar{c}}^{-1} \cdot \mathbf{A}_1) \right] = \frac{1}{a} \nabla(\mathbf{\bar{p}} \cdot \mathbf{A}_1) - \frac{1}{a} (\mathbf{\bar{p}} \cdot \nabla) \mathbf{\bar{c}}^{-1} \cdot \mathbf{A}_1. \tag{4.114} \]

Using (4.14) and (4.114), Eq. (4.108) becomes

\[
(\nabla \cdot \mathbf{\bar{c}} \cdot \nabla) \mathbf{\bar{A}}_1 - (\mathbf{\bar{c}} \cdot \nabla)(\nabla \cdot \mathbf{\bar{A}}_1) + a \nabla(\mathbf{\bar{p}} \cdot \mathbf{A}_1) - a (\mathbf{\bar{p}} \cdot \nabla) \mathbf{\bar{c}}^{-1} \cdot \mathbf{A}_1 + k^2 a^2 \mathbf{\bar{A}}_1
\]

\[
= - (i \omega \epsilon' - \sigma) \mu' a^2 \mathbf{\bar{c}} \cdot \nabla \Phi_1 - \mu' a^2 (\mathbf{\mathbf{j}}_s + \gamma \rho' \nabla) e^{i \omega \Omega z}. \tag{4.115} \]

By breaking the terms up into components it can be shown that

\[
\nabla(\mathbf{\bar{p}} \cdot \mathbf{A}_1) - a (\mathbf{\bar{p}} \cdot \nabla) (\mathbf{\bar{c}}^{-1} \cdot \mathbf{A}_1) = - (\mathbf{\bar{p}} \cdot \nabla) \mathbf{\bar{A}}_1 + (\mathbf{\bar{c}} \cdot \nabla) (\mathbf{\bar{p}} \cdot \mathbf{A}_1). \tag{4.116} \]

By substituting (4.116) and the gauge condition (4.112) into (4.115), we have, finally,

\[
(\nabla \cdot \mathbf{\bar{c}} \cdot \nabla) \mathbf{\bar{A}}_1 - (\mathbf{\bar{c}} \cdot \nabla) \mathbf{\bar{A}}_1 + k^2 a^2 \mathbf{\bar{A}}_1 = - \mu' a^2 (\mathbf{\mathbf{j}}_s + \gamma \rho' \nabla) e^{i \omega \Omega z}, \tag{4.117} \]

which involves no terms in \( \Phi_1 \). Comparison with Eq. (4.113) shows that the vector and scalar potentials satisfy the same differential equation, except for the source terms, and thus can be found from the same Green's function, ignoring the homogeneous solutions. Furthermore, by comparing this expression with (4.31), it is evident that this formulation is considerably simpler.

4.2.2 Green's Function Solution

From an inspection of Eqs. (4.113) and (4.117), it is evident that the appropriate Green's function for the problem satisfies the following differential equation:

\[
(\nabla \cdot \mathbf{\bar{c}} \cdot \nabla) G - (\mathbf{\bar{p}} \cdot \nabla G + k^2 a^2 G = - \delta (\mathbf{\bar{R}} | \mathbf{\bar{R}}_o) \tag{4.118} \]
It was remarked before that the discussion of Section 4.1.2 does not depend on the form of the operator, so that the results of that section may be applied directly to this case. Thus

\[ \mathcal{A}(\mathcal{R}) = \mu' a^2 \iint V_o \iiint G(\mathcal{R} | \mathcal{R}_o) \left[ \mathcal{J}_s(\mathcal{R}_o) + \mathcal{J}_s(\mathcal{R}) e^{i\omega \Omega z_o} \right] dV_o \]

and

\[ \varnothing(\mathcal{R}) = \frac{1}{c^2} \iint V_o \iiint G(\mathcal{R} | \mathcal{R}_o) \left[ \mathcal{J}_s(\mathcal{R}_o) + \rho_s(\mathcal{R}_o) + a \gamma'_r(\mathcal{R}_o) \right] e^{i\omega \Omega z_o} dV_o, \]

(4.119)

where \( V_o \) encloses the sources, and \( dV_o = d^3R_o = dx_o dy_o dz_o \).

In cylindrical components, Eq. (4.118)

\[ \left( \frac{a}{r} \frac{\partial}{\partial r} \frac{r}{\partial r} + \frac{\partial^2}{\partial z^2} - \frac{\partial}{\partial z} + k^2 a^2 \right) G(\mathcal{R} | \mathcal{R}_o) = -\delta(\mathcal{R} - \mathcal{R}_o). \]  

(4.120)

As with the static charge distribution, there are two conditions which give rise to different solutions: for low velocities such that \( v > c/n \), and \( a > 0 \), and for high velocities such that \( v > c/n \), or \( a > 0 \).

**Case A. Low Velocities:** \( v < c/n \). Let \( \alpha^2 = a \), and \( b = p/2 \). Again without loss of generality we may take \( \mathcal{R}_o = 0 \) for the time being. Then Eq. (4.120) can be written as

\[ \left( \frac{\alpha^2}{r} \frac{\partial}{\partial r} \frac{r}{\partial r} + \frac{\partial^2}{\partial z^2} - 2b \frac{\partial}{\partial z} + k^2 a^4 \right) G(0) = -\frac{\delta(r) \delta(z)}{2\pi r}. \]

(4.121)

Taking the Hankel transform in \( r \) and the Fourier transform in \( z \) yields the algebraic equation

\[ (\lambda^2 \alpha^2 + h^2 - 2i\hbar - k^2 a^4) F \{ G \} = 1/4\pi^2, \]

(4.122)
or

\[
F \left\{ \mathcal{H} \{ G \} \right\} = \frac{1}{4\pi^2} \frac{1}{h^2 - 2ihb + \lambda^2 \alpha^2 - k^2 \alpha^2} \quad (4.123)
\]

Taking the inverse Fourier transform in \( h \), we obtain the integral

\[
\mathcal{H} \{ G \} = \frac{1}{4\pi^2} \int_{-\infty}^{\infty} \frac{e^{-ihz}}{h^2 - 2ihb + \lambda^2 \alpha^2 - k^2 \alpha^2} \, dh \quad . \quad (4.124)
\]

It is necessary to carefully examine the location of the roots of the denominator of the integrand. Expanded, the denominator is

\[
(h - ib)^2 + \lambda^2 \alpha^2 - \frac{\omega_n^2 \alpha^4}{c^2} + b^2 - i \frac{\sigma \omega_n \alpha^4}{\epsilon' c^2} \quad . \quad (4.125)
\]

By inspection, the roots are given by

\[
h_{1,2} = ib - ib \sqrt{1 + \frac{\lambda^2 \alpha^2 - \frac{\omega_n^2 \alpha^4}{b^2}}{\frac{\sigma \omega_n \alpha^4}{b \epsilon' c^2}}} \quad . \quad (4.126)
\]

If the real part of the radical is greater than one, then there will be one root in the upper-half plane, and one in the lower. We are thus interested in the range of \( \omega \) for which this is true for all real \( \lambda \). The worst case is obviously for \( \lambda = 0 \); thus we let \( \lambda \) vanish and consider the radical

\[
u + iv = \sqrt{1 - \frac{\omega_n^2 \alpha^2}{b \epsilon' c^2}} - i \frac{\sigma \omega_n \alpha^4}{\epsilon' c^2} \quad , \quad (4.127)
\]

where \( u \) and \( v \) are real. Substituting \( x = \omega \epsilon' / \sigma \), this simplifies to

\[
u + iv = \frac{1}{n} \sqrt{(1 - 2ix)^2 - (1 - n^2 \beta^2 \alpha^2)} \quad . \quad (4.128)
\]

We first note that at \( x = 0 \), \( u = 1 \), and at large values of \( |x| \),
\[ u + iv \sim \frac{(1 - 2ix)}{n\beta} \]

or

\[ u \sim \frac{1}{n\beta} > 1 \]  \hspace{1cm} (4.129)

This suggests that \( u \) has a minimum value for some value or values of \( x \).

Thus let us set \( \frac{du}{dx} = 0 \) and take the derivative of (4.128) with respect to \( x \). Then we obtain

\[ i \frac{dv}{dx} = \frac{1}{n\beta} \cdot \frac{(1-2ix)(-2i)}{\sqrt{(1-2ix)^2 - (1-n^2\beta^2)}} \cdot \frac{\sqrt{(1+2ix)^2 - (1-n^2\beta^2)}}{\sqrt{(1+2ix)^2 - (1-n^2\beta^2)}} \]  \hspace{1cm} (4.130)

or

\[ \frac{dv}{dx} = -\frac{2}{n\beta} \frac{\sqrt{(1-2ix)^2 \left[(1+2ix)^2 - (1-n^2\beta^2)\right]}}{\sqrt{(1-2ix)^2 - (1-n^2\beta^2)}} \cdot \sqrt{(1+2ix)^2 - (1-n^2\beta^2)} \]  \hspace{1cm} (4.131)

The denominator is real and non-negative, since it involves the product of a quantity and its conjugate. In order for \( \frac{dv}{dx} \) to be real, it is necessary that the imaginary part of the numerator be zero; i.e., that

\[ \text{Re} \left\{ (1-2ix)^2 \left[(1+2ix)^2 - (1-n^2\beta^2)\right] \right\} > 0 \]

and

\[ \text{Im} \left\{ (1-2ix)^2 \left[(1+2ix)^2 - (1-n^2\beta^2)\right] \right\} = 0 \]  \hspace{1cm} (4.132)

The second condition holds only if \( x = 0 \), and this also satisfies the first condition. Thus the minimum value of \( u \) is 1, and occurs at \( x = 0 \), or \( \omega = 0 \), and the roots of expression (4.125) lie one in the upper half plane, and one in the lower, for all \( \omega > 0 \).
Thus (4.124) can be evaluated by closing the contour in the upper half-plane for \( z < 0 \), and in the lower half-plane for \( z > 0 \), and applying the theory of residues; then (4.124) becomes

\[
H \{ G \} = \frac{2\pi i}{4\pi^2} \begin{cases} 
-\frac{ih_1 z}{e^{(h_1 - h_2)}} & , \quad z < 0 \\
-\frac{ih_2 z}{e^{(h_2 - h_1)}} & , \quad z > 0
\end{cases}
\]

or

\[
H \{ G \} = \frac{e^{bz}}{4\pi\alpha} \sqrt[4]{\frac{2 - k^2}{\lambda^2 - k^2 + \frac{b^2}{\alpha^2}}}.
\] (4.133)

Taking the inverse Hankel transform of (4.133) results in the integral

\[
G (\mathbb{R}) = \frac{e^{bz}}{4\pi\alpha} \int_0^\infty \frac{J_0 (\lambda r) e^{-\alpha |\lambda|}}{\sqrt[4]{\lambda^2 - k^2 + \frac{b^2}{\alpha^2}}} \lambda d\lambda.
\] (4.134)

This can be written in closed form by making use of Sommerfeld's formula, given, for example, by Magnus and Oberhettinger, (1954), p. 34. It is first necessary to examine the argument of the radical. First of all the quantity

\[
k^2 \frac{2}{\alpha^2} - \frac{b^2}{\alpha^2} = \frac{\omega_n^2}{\alpha^2} + i \frac{\omega \sigma_n}{\epsilon' c^2} - \frac{b^2}{\alpha^2}
\]

lies in the first or second quadrant, for \( \omega > 0 \), and thus
\[ 0 \leq \arg \sqrt{k^2 \alpha^2 - \frac{b^2}{\alpha^2}} \leq \pi/2. \] 

(4.135)

Also, the quantity

\[ \lambda^2 - k^2 \alpha^2 + \frac{b^2}{\alpha^2} = \lambda^2 - \frac{2 \omega n}{c^2} \alpha^2 - \frac{i \omega \sigma n}{\epsilon' c^2} \alpha^2 + \frac{b^2}{\alpha^2} \]

lies in the third or fourth quadrant, so that

\[ -\pi/2 < \arg \sqrt{\lambda^2 - k^2 \alpha^2 + \frac{b^2}{\alpha^2}} \leq 0. \] 

(4.136)

Thus Sommerfeld's formula applies, and we get the expression

\[ G(\mathbf{R}|0) = \frac{e^{bz}}{4\pi \alpha} \frac{1}{\sqrt{\sqrt{2 \alpha z + r^2}}} \cdot \] 

(4.137)

Replacing \( \mathbf{R} \) by \( \mathbf{R} - \mathbf{R}_o \), and using the definitions of \( b \) and \( \alpha \), the final solution is obtained:

\[ G(\mathbf{R}|\mathbf{R}_o) = \frac{e^{\frac{\sigma \mu'}{2} (z - z_o) \sqrt{a} \frac{1}{2} R_1}}{4\pi a^{1/2} R_1} \cdot \] 

(4.138)

where

\[ R_1 = \sqrt{a(z - z_o)^2 + (r - r_0)^2} \]

and

\[ k_1 = \sqrt{\frac{2}{k - b/a^2} = \frac{\omega n}{c} \sqrt{1 + \left(\frac{\sigma}{2\omega \epsilon'}\right)^2 + \left(\frac{\sigma}{2\omega \epsilon' a}\right)^2}.} \]
For frequencies in the range $\omega < \sigma/2\epsilon'$, it is more appropriate to write this in ascending form in $\omega$; noting (4.135), Eq. (4.138) can be written

$$G(R|R_0) = \frac{e^{-\mu' a v (z-z_0)/\sigma} e^{-\sigma_1 a^{1/2} R_1}}{4\pi a^{1/2} R_1},$$

(4.139)

where

$$\sigma_1 = \sqrt{\frac{b^2}{a^2} - k^2} = \frac{\sigma n}{2\epsilon' c} \sqrt{(1 - i \frac{2\omega\epsilon'}{\sigma})^2 - \frac{1}{a^2 \gamma^2}}.$$ 

The Green's function does not increase indefinitely for large positive values of $z$ in spite of the presence of the term $e^{b z}$ in (4.137). Consider the numerator of the expression for large positive values of $z$; we have, approximately, noting (4.135),

$$\exp \left[ \left( b - \sqrt{\frac{b^2}{\sigma} - k^2 a^2} \right) z \right] = \exp \left[ b \left( 1 - \sqrt{1 - k^2 a^2 / b^2} \right) z \right].$$

(4.140)

The radical is exactly (4.127), whose real part has a minimum value of unity at $\omega = 0$. Thus the exponential has an argument which is not positive, and does not increase indefinitely for large $z$.

Note that as the conductivity $\sigma$ vanishes, the Green's function becomes that for the lossless case, reported by Tai (1965a):

$$G(R|R_0) = \frac{e^{-ika^{1/2} R_1}}{4\pi a^{1/2} R_1},$$

(4.141)

where here $k = \omega n/c$. 

73
Note also that if we let \( \omega = 0 \) in (4.138), we get the static charge source Green's function of (4.64):

\[
G (\mathbf{R}|\mathbf{R}_0) = \frac{e^{\frac{\sigma \frac{\mu^1 a v}{2} (z - z_0)}{R_1}} - e^{\frac{\sigma \frac{\mu^1 a^{1/2} v}{2}}{R_1}}}{4 \pi a^{1/2}}. \tag{4.142}
\]

(4.138) is probably the most useful Green's function obtained in this work, since it can be readily applied to the problem of an antenna in a moving, conducting medium.

Case B. High Velocities: \( v > c/n, \ a < 0 \). Let \( \alpha^2 = -a \) and \( b = -p/2 \). As before, we may take \( \mathbf{R}_0 = 0 \) temporarily without loss of generality. Then Eq. (4.120) becomes

\[
\left( \frac{\alpha^2}{r} \frac{\partial}{\partial r} r \frac{\partial}{\partial r} - \frac{\partial^2}{\partial z^2} - 2 b \frac{\partial}{\partial z} - k^2 \alpha^2 \frac{4}{} \right) G(\mathbf{R}|0) = \frac{\delta(r) \delta(z)}{2 \pi r}. \tag{4.143}
\]

Taking the Hankel transform in \( r \), followed by the Fourier transform in \( z \), yields the algebraic expression:

\[
\left( \lambda^2 \alpha^2 - h^2 - 2ibh + k^2 \alpha^2 \right) F \left\{ \{H \{G\}\} \right\} = -\frac{1}{4\pi^2}, \tag{4.144}
\]

or

\[
F \left\{ \{H \{G\}\} \right\} = \frac{1}{4\pi^2} \frac{1}{h^2 + 2ibh - \lambda^2 \alpha^2 - k^2 \alpha^2}. \tag{4.145}
\]

Taking the inverse Fourier transform in \( h \) gives the integral

\[
H \{G\} = \frac{1}{4\pi^2} \int_{-\infty}^{\infty} \frac{e^{-ihz} dh}{(h^2 + 2ibh - \lambda^2 \alpha^2 - k^2 \alpha^2)}. \tag{4.146}
\]
The roots of the denominator are given by

\[ h_{1,2} = -ib \pm \sqrt{\frac{\lambda^2 \alpha^2}{c^2} + \frac{\omega n \alpha}{c^2} (1 + i \frac{\sigma}{\omega \epsilon}) - b^2} \]

\[ = -ib \pm \sqrt{1 - \frac{\lambda^2 \alpha^2}{b^2} - \frac{\omega n \alpha}{b^2 c^2} (1 + i \frac{\sigma}{\omega \epsilon})} . \]  

(4.147)

Since we anticipate a shock wave behavior as with static charge sources, we ask the question, for what range of \( \omega \) are both poles in the lower half plane, or equivalently, for what range of \( \omega \) is the real value of the radical less than unity? It is evident that the worst case is for \( \lambda = 0 \). Thus we want to examine the expression

\[ \sqrt{1 - \frac{\omega^2 n^2 \alpha^2}{b^2 c^2} (1 + i \frac{\sigma}{\omega \epsilon})} , \]  

(4.148)

which is identical to (4.127). The discussion that followed (4.127) applies here as well, with one modification: since now \( n \beta > 1 \), relations (4.29) now become

\[ u + iv \sim \frac{(1-2ix)}{n\beta} , \]

or

\[ u \sim \frac{1}{n\beta} < 1 . \]  

(4.149)

and as before \( u = 1 \) at \( x = 0 \). Thus \( u \) is maximized rather than minimized, at some finite value of \( x \); as in (4.132), this turns out to be at \( x = 0 , \) or \( \omega = 0 \).

Thus for positive \( \omega \), the roots of \( h \) are both in the lower half-plane, rather than one in each half-plane as in Fig. 4-5.

For \( z < 0 \), the contour in (4.146) can be closed in the upper half-plane, and since it encloses no poles of the integrand of (4.146),

\[ H \{G\} = 0 , \ z < 0 . \]  

(4.150)
For \( z > 0 \), the contour can be closed in the lower half-plane, and encloses both poles of the integrand. Thus by the theory of residues,

\[
H \{ G \} = -\frac{2\pi i}{4\pi} \left[ \frac{-i h_1 z}{e} \left( \frac{1}{h_1 - h_2} \right) + \frac{-i h_2 z}{e} \left( \frac{1}{h_2 - h_1} \right) \right]
\]

\[
= -\frac{e^{-bz}}{2\pi \alpha} \frac{\sin \left( \sqrt{\lambda + \frac{22}{c^2}} \left( \frac{1 + \frac{\omega_n \alpha}{c^2}}{\omega \epsilon'} - \frac{b^2}{\alpha^2} \right) \right)}{\sqrt{\lambda + k \alpha^2 - \frac{b^2}{\alpha^2}}} \sin \left( \frac{2}{\alpha^2} \right)
\]

(4.151)

Taking the inverse Hankel transform in \( \lambda \) gives the integral

\[
G (R|0) = -\frac{e^{-bz}}{2\pi \alpha} \int_0^\infty \frac{J_0 (\lambda r) \sin \left( \sqrt{\lambda + \frac{22}{c^2}} \left( \frac{1 + \frac{\omega_n \alpha}{c^2}}{\omega \epsilon'} - \frac{b^2}{\alpha^2} \right) \right)}{\sqrt{\lambda + k \alpha^2 - \frac{b^2}{\alpha^2}}} \lambda d\lambda
\]

(4.152)

This can be reduced into closed form by means of the Sonine-Gegenbauer formula (see Watson (1922), p. 414), which states:

\[
\int_0^\infty J_\mu (\lambda r) J_\nu \left( \frac{2}{\alpha^2} \sqrt{\lambda + \frac{22}{c^2}} \right) (\lambda^2 + k_1 \alpha^2)^{\nu/2} \lambda^\mu + 1 d\lambda
\]

\[
= \begin{cases} 
0, & \alpha z < r \\
\frac{\mu}{\nu} \left[ \frac{2}{\alpha^2} \left( \frac{1}{\alpha^2} - \frac{r^2}{2} \right) \right]^{\nu - \mu - 1} J_\nu - \mu - 1 (k_1 \frac{2}{\alpha^2} \left( \frac{1}{\alpha^2} - \frac{r^2}{2} \right) \right), & \alpha z > r
\end{cases}
\]

(4.153)

for \( \text{Re} \nu > \text{Re} \mu > -1; \alpha, z, r \) real and non-negative. If we substitute \( \mu = 0, \nu = 1/2 \),

\[
k_1^2 \alpha^2 = k^2 \alpha^2 - b^2 / \alpha^2, \quad \text{and use the well-known relations}
\]

76
\[ J_{1/2}(Z) = \sqrt{\frac{2}{\pi Z}} \sin Z, \]

and

\[ J_{-1/2}(Z) = \sqrt{\frac{2}{\pi Z}} \cos Z, \]

then the Sonine - Gegenbauer formula becomes

\[ \frac{1}{\alpha z} \int_0^\infty J_0(\alpha r) \sin \left( \alpha z \sqrt{r^2 + k^2 - b^2 / \alpha^2} \right) \lambda \, d\lambda \]

\[ = \begin{cases} 0, & \alpha z < r \\ \frac{1}{\alpha z} \cos \left( \frac{k_1 \alpha \sqrt{r^2 - \alpha^2 - a^2}}{2} \right), & \alpha z > r \end{cases} \]

Thus the Green's function solution can be written, for \( z > 0 \),

\[ G(\vec{R}|0) = -\frac{1}{2\pi \alpha} e^{-bz} \begin{cases} 0, & \alpha z < r \\ \frac{1}{\alpha z} \cos \left( \frac{k_1 \alpha \sqrt{(\alpha z - r)^2}}{2} \right), & \alpha z > r \end{cases} \]

Using (4.150), replacing \( \vec{R} \) by \( \vec{R} - \vec{R}_0 \), and using the definitions of \( b \) and \( \alpha \), we have, finally,
\[ G(\mathbf{R}|\mathbf{R}_o) = \begin{cases} 0, & |a|^{1/2}(z-z_o)<(r-r_o) \\ -\sigma \frac{\mu'|a|v}{2} \frac{(z-z_o)}{\cos \left( k_1 |a|^{1/2} R_2 \right)} e^{-\frac{\sigma |a|^{1/2} |(z-z_o)-(r-r_o)|}{2\pi |a|^{1/2} R_2}}, & |a|^{1/2}(z-z_o)>(r-r_o) \end{cases} \]  

where

\[ R_2 = \sqrt{a^2 |(z-z_o)^2-(r-r_o)^2|} \]

and

\[ k_1 = \sqrt{k^2 - b^2/a^2} = \frac{\omega n}{c} \sqrt{\left( 1 + \frac{2\sigma}{\omega \epsilon' a} \right)^2 + \left( \frac{\sigma}{2\omega \epsilon' a} \right)^2} \]

For large conductivity \( \sigma \) or low frequencies such that \( \sigma > 2\omega \epsilon' \), it is more appropriate to write this in terms of an attenuation factor \( \alpha_1 \):

\[ G(\mathbf{R}|\mathbf{R}_o) = \begin{cases} 0, & |a|(z-z_o)<(r-r_o) \\ -\sigma \frac{\mu'|a|v}{2} \frac{(z-z_o)}{\cosh \left( \alpha_1 |a|^{1/2} R_2 \right)} e^{-\frac{\sigma |a|^{1/2} |(z-z_o)-(r-r_o)|}{2\pi |a|^{1/2} R_2}}, & |a|(z-z_o)>(r-r_o) \end{cases} \]  

where

\[ \alpha_1 = \frac{1}{a} \sqrt{b^2 - k^2 a^2} = \frac{\sigma n}{2\epsilon' c} \sqrt{\left( 1 - \frac{2i\omega \epsilon' c}{\sigma} \right) - \frac{1}{a^2 \gamma^2}}. \]

For lossless media \( \sigma = 0 \), and the Green's function reduces to:

\[ G(\mathbf{R}|\mathbf{R}_o) = \begin{cases} 0, & |a|^{1/2}(z-z_o)<(r-r_o) \\ -\frac{\cos(k|a|^{1/2} R_2)}{2\pi |a|^{1/2} R_2}, & |a|^{1/2}(z-z_o)>(r-r_o) \end{cases} \]  

78
where here \( k = \omega n/c \). This agrees with the result obtained by Tai (1965a).

Furthermore, if \( \omega \) is allowed to vanish, the Green's function becomes that for static charge sources, Eq. (4.89):

\[
G(\mathbf{R}|\mathbf{R}_0) = \begin{cases} 
0, \\
\frac{-\sigma \mu'|a|v}{e \frac{z - z_0}{2}} \cosh \left[ \frac{1}{2} \sigma \mu'|a|^{1/2} \nu R_2 \right] \\
2\pi |a|^{1/2} R_2
\end{cases}
\]

(4.160)

While the hyperbolic cosine term in (4.158) involves a rising exponential, the decaying exponential term dominates. This can be seen by considering the numerator of (4.158) for large values of positive \((z - z_0)\):

\[
\exp \left[ b \left( 1 - \sqrt{1 - k^2 a^2/b^2} \right) (z - z_0) \right]
\]

The radical is exactly (4.148). In the discussion of this quantity it was shown that its real part is less than unity for all positive \( \omega \). Thus for large values of positive \((z - z_0)\), the solution decreases with increasing \((z - z_0)\).

4.2.3 Summary

Summarizing the results of Section 4.2, we can say that for harmonically varying current sources, the fields are related to the potentials \( \overline{A}_1 \) and \( \phi_1 \) by

\[
\overline{E} = e^{-i\omega} \Omega z (i \omega \overline{\sigma}^{-1} \cdot \overline{A}_1 - \nabla \phi_1),
\]

\[
\overline{H} = \frac{1}{\mu'} e^{-i\omega} \Omega z \overline{\sigma}^{-1} \left[ \nabla \times (\overline{\sigma}^{-1} \cdot \overline{A}_1) \right],
\]

\[
\overline{B} = e^{-i\omega} \Omega z \left[ (\nabla - i\omega \overline{\Omega}) \times (\overline{\sigma}^{-1} \cdot \overline{A}_1) + \overline{\Omega} \times \nabla \phi_1 \right],
\]

79
and
\[
\bar{D} = e^{-i\omega \Omega z} \left[ \epsilon' (i\omega \bar{A}_1 - \bar{\sigma} \cdot \nabla \phi_1) + \frac{\Omega}{a\mu'} x (\nabla x (\bar{\sigma}^{-1} \cdot \bar{A}_1)) \right],
\]
(4.161)

where the time dependence of all field and charge-current quantities is understood to be \( e^{-i\omega t} \). The potentials are given by
\[
\bar{A}_1(\bar{R}) = \mu' a^2 \int \int \int_{V_o} G(\bar{R} | \bar{R}_o) \left[ \bar{J}_s (\bar{R}_o) + \bar{\Gamma} \gamma \rho'_r (\bar{R}_o) \right] e^{i\omega \Omega z} \, dV_o
\]
and
\[
\phi_1(\bar{R}) = \frac{1}{\epsilon'} \int \int \int_{V_o} G(\bar{R} | \bar{R}_o) \left[ \bar{\Omega} \cdot \bar{J}_s (\bar{R}_o) + \rho_s (\bar{R}_o) + a \gamma \rho'_r (\bar{R}_o) \right] e^{i\omega \Omega z} \, dV_o,
\]
(4.162)

where the volume \( V_o \) encloses the sources. The response charge density \( \gamma \rho'_r (\bar{R}_o) \) is related to the source currents and charges by
\[
\gamma \rho'_r (\bar{R}_o) = -\frac{\sigma}{\epsilon' \gamma v} \int_{-\infty}^{z_o} e^{-(\alpha - \gamma)} \left[ \rho_s (\bar{R}_o', \zeta) - \frac{\bar{v}}{c^2} \cdot \bar{J}_s (\bar{R}_o', \zeta) \right] d\zeta,
\]
(4.163)

and it is noted that \( i\omega \rho_s = \nabla \cdot \bar{J}_s \), and \( \bar{R}_o = \bar{R}_o - \bar{z}_o \).

The Green's function necessary to find the potentials in (4.162) is, for \( v < c/a \), or \( a > 0 \):
\[
G (\bar{R} | \bar{R}_o) = \frac{e^{\frac{\mu' a v}{2} (z - z'_o) i k_1 a^{1/2} R_1}}{4 \pi a^{1/2} R_1},
\]
(4.164)

where
\[
R_1 = \sqrt{a (z - z'_o)^2 + (r - r'_o)^2}
\]
and
\[
k_1 = \sqrt{k^2 - b^2 / a^2}
\]

80
or for $v > c/a$, or $a < 0$:

$$G(R|R_o) = \begin{cases} 0, & |a|^{1/2}(z-z_o) < (r-r_o) \\ -e^{\mu t|a|v (z-z_o)} & \frac{\cos (k_1 |a|^{1/2}R_2)}{2\pi |a|^{1/2}R_2}, |a|^{1/2}(z-z_o) > (r-r_o) \end{cases}$$

(4.165)

where

$$R_2 = \sqrt{|a|(z-z_o)^2 - (r-r_o)^2}.$$
V
SUMMARY AND CONCLUSIONS

Two classes of problems have been solved in the area of moving, conducting media: static and radiation fields of static charges, and radiation fields of harmonic current sources. No limitation is put either on the range of conductivities and frequencies, or on the velocities. For the limiting case of vanishing conductivity, the solutions here reduce to already published solutions.

The results of the first class of problems find application to the fields of particle beams permeating matter, including the Cerenkov radiation effect. The second class can be applied to antenna problems involving radiating elements in a moving, conducting fluid.

There are several areas and problems to which it would be interesting and useful to extend the methods developed here. The two-dimensional counterpart of both classes of problems can be readily solved, from the differential equations of the Green's functions. The fields of stationary currents as well as stationary charges could be developed. Boundary value problems are also of interest, for example, the fields in a filled circular waveguide excited by charges of high velocities. The application of the methods to the problem of a short dipole in a moving, conducting medium is an important application on which the author is presently working.
REFERENCES


83
REFERENCES
(Continued)


APPENDIX A

TRANSFORMATION RELATIONS FOR THE POTENTIALS
AND THE GAUGE CONDITION

Minkowski's theory of the electrodynamics of moving bodies is based on the covariant formulation of electromagnetism with respect to coordinate systems in uniform relative motion. This in turn is based on the Lorentz transformation of coordinates, where in addition to the space coordinates $x$, $y$, and $z$, time is considered as a fourth coordinate $ct$, where $c$ is the velocity of light in vacuo. This and the following discussion are taken from Sommerfeld, "Electrodynamics", (1952) Section 27. If the primed system coordinates moves with a velocity $v$ in the positive $z$-direction with respect to the unprimed system, they are related under the Lorentz transformation by

$$x' = x, \quad y' = y, \quad z' = \gamma (z - vt),$$
$$t' = \gamma (t - \frac{vz}{c^2}) \quad (A.1)$$

In the dyadic symbolism, using the definition

$$\mathbf{R} = x\mathbf{\hat{x}} + y\mathbf{\hat{y}} + z\mathbf{\hat{z}},$$

for primed and unprimed systems, (A.1) can be written as

$$\mathbf{R}' = \gamma \frac{\mathbf{R}}{\gamma} \cdot (\mathbf{R} - \mathbf{v}t)$$

and

$$t' = \gamma (t - \frac{\mathbf{v} \cdot \mathbf{R}}{c}) \quad (A.2)$$

These can be inverted straightforwardly to give

$$\mathbf{R} = \gamma \frac{\mathbf{R}}{\gamma} \cdot (\mathbf{R}' + \mathbf{v}t')$$

85
and

$$t = \gamma (t' + \frac{\mathbf{v} \cdot \mathbf{R}}{c^2}) .$$

(A.3)

The "del" operator $\nabla'$ with the time derivative $\partial / \partial t'$ can be shown to follow a similar set of relations:

$$\nabla' = \mathbf{x} \frac{\partial}{\partial x'} + \mathbf{y} \frac{\partial}{\partial y'} + \mathbf{z} \frac{\partial}{\partial z'}$$

$$= \mathbf{x} \frac{\partial}{\partial x} \frac{\partial}{\partial x'} + \mathbf{y} \frac{\partial}{\partial y} \frac{\partial}{\partial y'} + \mathbf{z} \left( \frac{\partial}{\partial z} \frac{\partial}{\partial z'} + \frac{\partial}{\partial z} \frac{\partial}{\partial z'} \right),$$

by using (A.3), giving

$$\nabla' = \mathbf{x} \frac{\partial}{\partial x} + \mathbf{y} \frac{\partial}{\partial y} + \mathbf{z} \gamma \left( \frac{\partial}{\partial z} + \frac{\mathbf{v}}{c^2} \frac{\partial}{\partial t'} \right)$$

$$= \gamma \gamma^{-1} \cdot (\nabla + \frac{\mathbf{v}}{c^2} \frac{\partial}{\partial t}).$$

(A.4)

Similarly,

$$\frac{\partial}{\partial t'} = \frac{\partial t}{\partial t'} \frac{\partial}{\partial t} + \frac{\partial z}{\partial t'} \frac{\partial}{\partial z}$$

$$= \gamma \left( \frac{\partial}{\partial t} + \mathbf{v} \cdot \nabla \right).$$

(A.5)

Sometimes it is convenient to use what is sometimes called the total time derivative, given by

$$\frac{D}{Dt} = \frac{\partial}{\partial t} + \mathbf{v} \cdot \nabla.$$

(A.6)

Then (A.4) and (A.5) become

$$\nabla' = \frac{\mathbf{v}}{\gamma} \cdot (\nabla + \frac{\mathbf{v}}{c^2} \frac{D}{Dt}).$$
\[ \frac{\partial}{\partial t'} = \gamma \frac{D}{Dt} . \]  

(A.7)

Four-vectors are quantities having four components which obey the Lorentz transformation, and are thus said to transform like the coordinates. In the covariant formulation of electromagnetism, there are two important four-vectors: the four-potential \( (\vec{A}, \ i \phi/\kappa) \), and the four-current density \( (\vec{J}, \ i \kappa \rho) \), where the notation used here means that the vector corresponds to the space coordinate \( \vec{R} \) and the scalar corresponds to the time coordinate, \( \kappa t \). Thus since the components of these four-vectors transform as the coordinates, from (A.2) we have

\[
\begin{align*}
\vec{A}' &= \gamma \gamma^{-1} \cdot (\vec{A} - \frac{\vec{v}}{c^2} \phi) \\
\phi' &= \gamma (\phi - \vec{v} \cdot \vec{A})
\end{align*}
\]  

(A.8)

and

\[
\begin{align*}
\vec{J}' &= \gamma \gamma^{-1} \cdot (\vec{J} - \vec{v} \cdot \rho) \\
\rho' &= \gamma (\rho - \frac{\vec{v} \cdot \vec{J}}{c^2})
\end{align*}
\]  

(A.9)

In this theory, then, a moving current produces a charge, although for small velocities it is negligible.

Turning our attention now to the gauge condition, we note that if the primed system is that coordinate system which transforms the medium to rest, then the vector and scalar potentials in that system are related by the familiar gauge condition

\[ \nabla' \cdot \vec{A}' + \mu' \epsilon' \frac{\partial \phi'}{\partial t'} + \sigma' \mu' \phi' = 0 . \]  

(A.10)
Noting that $\sigma = \gamma \sigma'$, using (A.4), (A.5), and (A.8), we obtain

$$\nabla' \cdot \mathbf{A}' = \gamma^2 (\mathbf{\mathbf{\Sigma}}^{-1} \cdot \nabla + \frac{\nabla}{c^2} \frac{\partial}{\partial t}) \cdot (\mathbf{\mathbf{\Sigma}}^{-1} \nabla \mathbf{\mathbf{\Sigma}}^{-1} \cdot \mathbf{A}' - \frac{\nabla}{c^2} \frac{\partial}{\partial t})$$

$$= \gamma^2 \left[ \nabla \cdot \mathbf{\mathbf{\Sigma}}^{-1} \nabla \mathbf{\mathbf{\Sigma}^{-1}} \cdot \mathbf{A}' + \frac{\nabla}{c^2} \frac{\partial}{\partial t} (\mathbf{\mathbf{\Sigma}}^{-1} \cdot \nabla \mathbf{\mathbf{\Sigma}}^{-1}) - \frac{\partial}{\partial t} (\mathbf{\mathbf{\Sigma}}^{-1} \cdot \nabla \mathbf{\mathbf{\Sigma}}^{-1}) \right]$$

$$\mu' c^2 \frac{\partial}{\partial t} = \frac{\gamma^2}{c^2} \left( \frac{\partial}{\partial t} + \nabla \cdot \nabla \right) (\phi - \nabla \cdot \mathbf{A})$$

$$= \gamma^2 \frac{n^2}{c^2} \left[ -\nabla \cdot \frac{\partial}{\partial t} (\nabla \cdot \nabla) (\nabla \cdot \mathbf{A}) + \frac{\partial}{\partial t} (\nabla \cdot \nabla) \right]$$

and

$$\sigma' \mu' \phi' = \sigma \mu' (\phi - \nabla \cdot \mathbf{A})$$.

Noting that $\nabla \cdot (\nabla \phi) = \nabla \cdot \nabla$, and collecting terms, we get

$$\nabla \cdot \mathbf{\mathbf{\Sigma}}^{-1} \nabla \mathbf{\mathbf{\Sigma}^{-1}} \cdot \mathbf{A}' - (n^2 - 1) \frac{\nabla}{c^2} \frac{\partial}{\partial t} - \frac{\partial}{\partial t} \left( \frac{\partial}{\partial t} (\nabla \cdot \nabla) \right)$$

$$= - (n^2 - 1) \frac{\nabla}{c^2} \cdot \nabla \phi - \frac{1}{c^2} (n^2 - \beta^2) \frac{\partial}{\partial t} - \frac{\partial}{\partial t} \phi' \frac{\mu' \phi'}{\gamma^2}$$,

After dividing through by $(1 - n^2 \beta^2)$ and noting that $a = \left[ \gamma^2 (1 - n^2 \beta^2) \right]^{-1}$ and $\Omega = \nabla (n^2 - 1) / (c^2 (1 - n^2 \beta^2))$, this can be written as

$$\nabla \cdot \mathbf{\mathbf{\Sigma}}^{-1} \nabla \mathbf{\mathbf{\Sigma}^{-1}} \cdot \mathbf{A}' - \Omega \cdot \frac{\partial}{\partial t} - \sigma \mu' a \nabla \cdot \mathbf{A}'$$

$$= - \Omega \cdot \nabla \phi - \sigma \mu' a \phi - \frac{1}{c^2} (n^2 - \beta^2) \frac{\partial}{\partial t}$$.

For $\mathbf{A}'$ in the z-direction, the first term becomes $\nabla \cdot \mathbf{A}'$, and (A.11) is exactly Eq. (4.11) of the text.