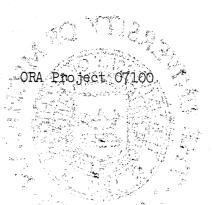
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EXISTENCE THEOREMS FOR WEAK AND USUAL OPTIMAL SOLUTIONS IN LAGRANGE PROBLEMS WITH UNILATERAL CONSTRAINTS

I. Closure Theorems

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EXISTENCE THEOREMS FOR WEAK AND USUAL OPTIMAL SOLUTIONS IN LAGRANGE PROBLEMS WITH UNILATERAL CONSTRAINTS

I. CLOSURE THEOREMS*

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In the present papers (I, II, and III) we prove existence theorems for weak and usual optimal solutions of nonparametric Lagrange problems with (or without) unilateral constraints.

We shall consider arbitrary pairs x(t),u(t) of vector functions, u(t) measurable with values in E_m , x(t) absolutely continuous with values in E_n , and we discuss the existence of the absolute minimum of a functional

$$I[x,u] = \int_{t_0}^{t_2} f_0(t,x(t),u(t))dt,$$

with side conditions represented by a differential system

$$dx/dt = f(t,x(t),u(t)), t_1 < t < t_2,$$

constraints

$$(t,x(t))\in A$$
, $u(t)\in U(t,x(t))$, $t_1 \leq t \leq t_2$,

and boundary conditions

$$(t_1,x(t_1),t_2,x(t_2))\epsilon B$$
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where A is a given closed subset of the tx-space E_1 x E_n , where B is a given closed subset of the $t_1x_1t_2x_2$ -space E_{2n+2} , and where U(t,x) denotes a given closed variable subset of the u-space E_m , depending on time t and space x. Here A may coincide with the whole space E_1xE_m , and U may be fixed and coincide with the whole space E_m .

In the particular situation, where the space U is compact for every (t,x) these problems reduce to Pontryagin problems; in the particular situation where the space U is fixed and coincides with the whole space E_m , then these problems have essentially the same generality of usual Lagrange problems. Throughout these papers we shall assume U(t,x) to be any closed subset of E_m .

In paper I we prove closure theorems for usual solutions. In II we shall prove existence theorems. These will contain as particular cases the Filippov existence theorem for problems of optimal control (U(t,x) compact), existence theorems for usual Lagrange problems $(U = E_m)$, and the Nagumo-Tonelli existence theorem for free problems (m = n, f = u). In III we shall prove existence theorems for weak (or generalized) solutions introduced as measurable probability distributions of usual solutions (Gamkrelidze chattering states).

In successive papers we shall extend the present results to multidimensional Lagrange problems involving partial differential equations in Sobolev's spaces with unilateral constraints.

We begin with an analysis of the concept of upper semicontinuity of variable subsets in E_m . The usual concept of upper semicontinuity is replaced by two others (properties (U) and (Q), §3), which are essentially more general than the uppersemicontinuity, in the sense that closed sets U(t,x), for which uppersemicontinuity property hold, certainly satisfy property (U), and closed and convex sets Q(t,x), for which upper semicontinuity property hold, certainly satisfy property (Q). We then extend (\$4) the closure theorem of A. F. Filippov in various ways, so as to include, among other things, the use of pointwise and not necessarily uniform convergence of some components of a sequence of trajectories. In part II we shall prove existence theorem of optimal smooth solutions (\$7) by a new analysis of a minimizing sequence, and by using the above extension of Filippov's closure theorem as a replacement for Monelli's semicontinuity argument. We shall then deduce (88) existence theorems for the case where f is linear in u, and for free problems of the calculus of variations (m = n, f = u). Finally, we shall prove (§9) existence theorems for weak solutions in the general case above, for the case in which f is linear, and for free problems.

1. THE PROBLEM

We denote by x a variable n-vector $x=(x^1,\ldots,x^n)\in E_n$, by u a variable m-vector $u=(u^1,\ldots,u^m)\in E_m$, and by $t\in E_1$ the independent variable. We denote by A an arbitrary subset of the (t,x)-space, $A\subseteq E_1xE_n$, and, for any $(t,x)\in A$, we denote by U=U(t,x) a variable suspace of the u-space, U(t,x) $\subseteq E_m$. In the terminology of control problems, u is the control variable

and U(t,x) the control space. We denote by $f_1(t,x,u)$, $i=0,1,\ldots,n$, given real functions defined for all $(t,x)\in A$, and all $u\in U(t,x)$, and by f the n-vector function $f=(f_1,\ldots,f_n)$. We denote by B a given subset of the (2n+2)-space (t_1,x_1,t_2,x_2) . We are interested in the determination of a measurable vector function u(t), $t_1 \leq t \leq t_2$, (control function, or steering function, or strategy), and a corresponding absolute continuous vector function x(t), $t_1 < t \leq t_2$, satisfying almost everywhere the differential system

$$dx/dt = f(t,x(t),u(t)), t_1 \le t \le t_2,$$

satisfying the boundary conditions

$$(t_1,x(t_1),t_2,x(t_2))\in B$$
,

satisfying the constraints

$$(t,x(t))\in A$$
, $t_1 \le t \le t_2$,

$$u(t) \in U(t,x(t)),$$
 a.e. in $[t_1,t_2],$

and for which the integral (cost functional)

$$I[x,u] = \int_{t_1}^{t_2} f_0(t,x(t),u(t))dt$$

has its minimum value (see §2 for details). We shall assume that U(t,x) is closed for every $(t,x) \in A$.

2. THE SPACE OF CONTINUOUS VECTOR FUNCTIONS

Let X be the collection of all continuous n-dim. vector functions $\mathbf{x}(t)$ defined on arbitrary finite intervals of the t-axis:

$$x(t) = (x^1, ..., x^n), a \le t \le b, x(t) \in E_n,$$

If x(t), $a \le t \le b$, and y(t), $c \le t \le d$, are any two elements of X, we shall define a distance $\rho(x,y)$. First, let us extend x(t) and y(t) outside their intervals of definition by constancy and continuity in $(-\infty, +\infty)$, and then let

$$\rho(x,y) = |a-c| + |b-d| + \max |x(t)-y(t)|,$$

where max is taken in $(-\infty, +\infty)$. It is known that X is a complete metric space when equipped with the metric ρ . Ascoli's theorem can now be expressed by saying that any sequence of equicontinuous vector functions \mathbf{x}_n of X, whose graphs in the tx-space are equipounded, possesses at least one subsequence which is convergent in the ρ -metric toward an element x of X.

3. ADMISSIBLE PAIRS u(t), x(t)

Let A be a closed subset of the (t,x)-space E_1xE_n . For every (t,x)eA let U(t,x), or control space, be a subset of the u-space E_m . Let M be the set of all (t,x,u) with (t,x)eA,ueU(t,x). Let $f(t,x,u) = (f_1,\ldots,f_n)$ be a continuous vector function defined on M. We shall denote by Q(t,x) the set of all values in E_n taken by f(t,x,u) when u describes U(t,x), or Q(t,x) = f(t,x,U(t,x)). A vector function $u(t) = (u^1,\ldots,u^m)$, $t_1 \le t \le t_2$ (control function) and a vector function $(x,t) = (x^1,\ldots,x^n)$, $t_1 \le t \le t_2$ (trajectory) are said to be an admissible pair provided (a) u(t) is measurable in $[t_1,t_2]$; (b) x(t) is absolutely continuous (AC) in $[t_1,t_2]$, (c) (t,x(t))eA for every $t \in [t_1,t_2]$; (d) u(t)eU(t,x(t)) a.e. in $[t_1,t_2]$; (e) dx/dt = f(t,x(t),u(t)) a.e. in $[t_1,t_2]$. By the expression the vector function x(t), $t_1 \le t \le t_2$, is a trajectory, we shall mean below that there exists a vector function

u(t), $t_1 \le t \le t_2$, such that the pair u(t), x(t) satisfies (abcde). We say also that x(t) is generates by u(t).

4. UPPER SEMICONTINUITY OF VARIABLE SETS

In view of using sets U(t,x),Q(t,x) which are closed but not necessarily compact, we need a concept of upper semicontinuity which is essentially more general than the usual one. We shall introduce two modifications of the usual definition of upper semicontinuity, and we shall denote them as "property (U)" and "property (Q)" since we shall usually use them for the sets U(t,x) and Q(t,x) above, respectively.

We shall discuss properties (U) and (Q) first in relation to arbitrary variable sets V(t,x), Q(t,x) which are functions of (t,x) in A. Then we shall discuss their relations when Q(t,x) is assumed to be the image of V(t,x) as mentioned in no. 2. Properties proved for V(t,x) under conditions (U) or (Q), will be used for V(t,x) when this set satisfies conditions (U) or V(t,x)

(A) The Property (U)

Given any set F in a linear space E we shall denote by cl F, coF, bdF, int F respectively the closure of F, the convex hull of F, the boundary of F, the set of all interior points of F. Thus, cl co F denotes the closure of the convex hull of F. We know that F, cl F, co F, co cl F are all contained in cl co F.

For every $(t,x)\in A$ and $\delta > 0$ let $N_{\delta}(t,x)$ denote the closed δ -neighborhood of (t,x) in A, that is, the set of all $(t',x')\in A$ at a distance $\leq \delta$ from (t,x).

A variable subset U(t,x), $(t,x) \in A$, is said to be an upper semicontinuous function of (t,x) at the point $(\overline{t},\overline{x}) \in A$ provided, given $\varepsilon > 0$, there is a number $\delta = \delta(\overline{t},\overline{x},\varepsilon) > 0$ such that $(t,x) \in \mathbb{N}_{\delta}(\overline{t},\overline{x})$ implies $U(t,x) \subset [U(\overline{t},\overline{x})]_{\varepsilon}$ where $[U]_{\varepsilon}$ denotes the closed ε -neighborhood of U in E_m .

Again let U(t,x), $(t,x)\in A$, $U(t,x)\subseteq E_m$, be a variable subset of E_m , which is a function of (t,x) in A. For every $\delta>0$ let $U(t,x,\delta)=UU(t',x')$, where the union is taken for all $(t',x')\leq \mathbb{N}_{\delta}(t,x)$. We shall say that U(t,x) has the property (U) at $(\overline{t},\overline{x})$ in A, if

$$U(\overline{t}, \overline{x}) = \bigcap_{\delta > 0} cl U(\overline{t}, \overline{x}, \delta).$$

We shall say that U(t,x) has property (U) in A, if U(t,x) has property (U) at every (t,x) of A.

(i) If U(t,x) has property (U) at $(\overline{t,x})$, then $U(\overline{t,x})$ is closed. Indeed,

$$U(\overline{t}, \overline{x}) \subset cl \ U(\overline{t}, \overline{x}) \subset cl \ U(\overline{t}, \overline{x}) = U(\overline{t}, \overline{x}),$$

and hence the ⊂ signs can be replaced by = signs.

(ii) If A is closed, and U(t,x) is any variable set which is a function of (t,x) in A and has property (U) in A, then the set of all $(t,x,u) \in AxE_m$ with $u \in U(t,x)$, $(t,x) \in A$, is closed.

<u>Proof.</u> If $(\overline{t},\overline{x},\overline{u})$ ccl M and $\varepsilon > 0$, then there are ∞ -many points $(t,x,u)\in M$ with $|t-\overline{t}|<\varepsilon$, $|x-\overline{x}|<\varepsilon$, $|u-\overline{u}|<\varepsilon$. Thus, $(\overline{t},\overline{x})\in A$ since A is closed, $(t,x)\in N_{2\mathfrak{C}}(\overline{t},\overline{x})$, $u\in U(t,x)$, $u\in U(\overline{t},\overline{x},2\varepsilon)$, and $u\in I_{\mathfrak{C}}(\overline{t},\overline{x})=U(\overline{t},\overline{x})$, $u\in U(\overline{t},\overline{x})$, since U has property (U) at $(\overline{t},\overline{x})$. This proves that $(\overline{t},\overline{x},\overline{u})\in M$, that is, M is closed.

Note that the sets $U(\overline{t},\overline{x},\delta)$ are not necessarily closed even if A is closed all sets U(t,x) are closed, and we take for $N_{\delta}(\overline{t},\overline{x})$ the closed δ -neighborhood if $(\overline{t},\overline{x})$ in A as stated. This can be seen by the following example. Let $A = [0 \le t \le 1, \ 0 \le x \le 1]$ a subset of E_2 , and $U(t,x) = [z = (z_1,z_2)|z_2 \ge tz_1,-\infty < z_1 < +\infty]$ for $0 < t \le 1$, and $U(0,x) = [z_2 \ge 0, z_1 = 0]$ for t = 0. Then $U(0,x,\delta) = [z = (z_1,z_2)|z_2 \ge \delta z_1$ for $-\infty < z_1 \le 0$, and $z_2 > 0$ for $0 < z_1 < \infty$] for any $\delta > 0$. The sets $U(0,x,\delta)$ are not closed. Here U(t,x) does not satisfy property (U) at the points (0,x). Nevertheless, the statement holds

(iii) If A is closed, and U(t,x) satisfies property (U) in A, then the sets $U(t,x,\delta)$, $(t,x)\in A$, $\delta>0$, are all closed, and hence U(t,x)=0 $U(t,x,\delta)$ for every $(t,x)\in A$.

<u>Proof.</u> Let M_δ denote the set of all points (t,x,u) with $(t,x)\in N_\delta(\overline{t},\overline{x})$, $u\in U(t,x)$. Obviously $N_\delta(\overline{t},\overline{x})\subset A\subset E_{n+1}$; $M_\delta\subset E_{n+1}xE_m$, and $N_\delta(\overline{t},\overline{x})$ is compact and M_δ is closed by force of (ii) above. Let \overline{u} be a point of accumulation of $U(t,x,\delta)$, and for any $\eta>0$ let $V_\eta(\overline{u})$ denote the η -neighborhood of \overline{u} in E_m . Then $M\cap (V_\eta(\overline{u})xE_{n+1})\subset N_\delta(\overline{t},\overline{x})$ $xV_\eta(\overline{u})$, hence $M\cap (V_\eta(\overline{u})xE_{n+1})$ is bounded. Since both M_δ and $V_\eta(\overline{u})xE_{n+1}$ are closed sets, the set $M\cap (V_\eta(\overline{u})xE_{n+1})$ is closed and bounded, and therefore a compact subset of E_{n+1} $x\in M_0$. Now the set $U(\overline{t},\overline{x},\delta)\cap V_\eta(\overline{u})$ is the projection of $M\cap (V_\eta(\overline{u})xE_{n+1})$ on the uspace E_m , and therefore $U(\overline{t},\overline{x},\delta)\cap V_\eta(\overline{u})$ is compact. Thus $\overline{u}\in U(\overline{t},\overline{x},\delta)\cap V_\eta(\overline{u})$, and finally $u\in U(\overline{t},\overline{x},\delta)$. Thus, $U(\overline{t},\overline{x},\delta)$ is closed, or cl $U(\overline{t},\overline{x},\delta)$ = $U(\overline{t},\overline{x},\delta)$, and $U(\overline{t},\overline{x})$ = O_δ cl $U(\overline{t},\overline{x},\delta)$ = $O_\delta U(\overline{t},\overline{x},\delta)$.

(iv) If A is closed and $U_j(t,x)$, $(t,x)\in A$, $j=1,\ldots,\nu$, ν finite, are variable subsets of E_m all satisfying property (U) in A, then their union and their intersections $V(t,x)=U_jU_1(t,x)$, $W(t,x)=\cap_jU_1(t,x)$, $(t,x)\in A$, are subsets of E_m satisfying property (U) in A. The same holds for their product $V(t,x)=U_1$ x...x U_{ν} .

The proof is straightforward.

Under the hypotheses of (ii) the set M is closed but not necessarily compact as the trivial example $U(t,x)=E_m$, $M=AxE_m$, shows. The set M is closed but not necessarily compact even if we assume that A is compact, and that every U(t,x) is compact. This is proved by the following example. Let m=n=1, $A=[(t,x) \in E_2, 0 \le t \le 1, 0 \le x \le 1]$, $U(0,x)=[u \in E_1 | 0 \le u \le 1]$, and, if $t \ne 0$, $U(t,x)=[u \in E_1 | 0 \le u \le 1]$, and $u=t^{-1}$. Then M is the set of all (t,x,u) with $0 \le t \le 1$, $0 \le x \le 1$, and $0 \le u \le 1$, or $u=t^{-1}$ if $t \ne 0$. Obviously, M is closed but not compact. Nevertheless, the statement holds:

(v) If A is compact, if the variable set U(t,x) is compact and convex for every $(t,x)\in A$ and possesses property (U) in A, if for every $(t,x)\in A$ there is some $\delta=\delta(t,x)>0$ such that $U(t,x)\cup U(t',x')\neq \emptyset$ for every $(t',x')\in N_\delta(t,x)$, then M is compact.

<u>Proof.</u> If M is not compact, then there is some sequence of elements $(t_k, x_k, u_k) \in M$, $k = 1, 2, \ldots$, with $(t_k, x_k) \in A$, $|t_k| + |x_k| + |u_k| \to + \infty$. Since A is compact and hence bounded, we have $|u_k| \to + \infty$. On the other hand, there is some subsequence, say still (t_k, x_k) , with $t_k \to \overline{t}$, $x_k \to \overline{x}$, $(\overline{t}, \overline{x}) \in A$. Given $\epsilon > 0$, we have $u_k \in U(\overline{t}, \overline{x}, \epsilon)$ for all k sufficiently large, as well as $U(\overline{t}, \overline{x}) \cap U(t_k, x_k) \neq \emptyset$. Since $U(\overline{t}, \overline{x})$ is compact, there is a solid sphere S containing all of $U(\overline{t}, \overline{x})$ in its interior, say $U(\overline{t}, \overline{x}) \subset A$. On the

other hand, if $\overline{u_k} \in U(\overline{t}, \overline{x}) \cap U(t_k, x_k)$, we have $\overline{u_k} \in \text{int } S$, and $u_k \in E_m$ -S, again for k large. Since both $\overline{u_k}$ and u_k belong to the convex set $U(t_k, x_k)$, the segment $\overline{u_k} u_k$ is contained in $U(t_k, x_k)$. In particular, if u_k' is the point where the segment $\overline{u_k} u_k$ intersects bd S, we have $u_k' \in U(t_k, x_k)$, $u_k' \in U(t_k, x_k)$, and $u_k' \in D$ S. If u' is any point of accumulation of $[u_k']$, then $u' \in D$ S, and $u' \in C$ $U(\overline{t}, \overline{x}, \varepsilon)$ for ever $\varepsilon > 0$. Hence, $u' \in C$ $U(\overline{t}, \overline{x}, \varepsilon) = U(\overline{t}, \overline{x})$, a contradiction, since $U(\overline{t}, \overline{x}) \subset C$ int S. We have proved that M is compact.

(vi) If the set U(t,x) is closed for every $(t,x)\in A$ and is an uppersemicontinuous function of (t,x) in A, then U(t,x) has property (U) in A.

<u>Proof.</u> By hypothesis $U(t,x,\delta) \subset [U(t,x)]_{\epsilon}$, where U_{ϵ} is closed. Hence $cl\ U(t,x,\delta) \subset [U(t,x)]_{\epsilon}$ for $\delta = \delta(t,x,\epsilon)$ and any $\epsilon > 0$. Since U(t,x) is closed, then $[U(t,x)]_{\epsilon} \to U(t,x)$ as $\epsilon \to 0+$. Thus $\bigcap_{\delta} cl\ U(t,x,\delta) \subset U(t,x)$. Since the opposite inclusion is trivial, we have $\bigcap_{\delta} cl\ U(t,x,\delta) = U(t,x)$. Statement (vi) is thereby proved.

The uppersemicontinuity property implies property (U), but the converse is not true, that is, the uppersemicontinuity property for closed sets is more restrictive than the property (U). This is shown by the following example in which all sets are closed. Take n=2 and

$$U(t,x) = [(u^1,u^2) \in E_2 | 0 \le u^1 < + \infty, 0 \le u^2 \le tu^1]$$

for every $(t,x)\in A = [(t,x)\in E_2|0 \le t \le 1, 0 \le x \le 1]$. Then, for $\delta > 0$, we have

$$U(t,x,\delta) = [(u^1,u^2) \in E_2 | 0 \le u^1 < + \infty, \ 0 \le u^2 \le (t+\delta)u^1],$$
 hence $U(t,x) = \bigcap_{\delta} cl \ U(t,x,\delta)$ and $U(t,x)$ has property (U) in A. On the other hand,

 $[U(t,x)]_{\epsilon} = [(u^{1},u^{2})\epsilon E_{2}|0 \le u^{1} < +\infty, -\epsilon \le u^{2} \le tu^{1} + \epsilon(1+t^{2})^{1/2}]UN_{1},$ where $N_{1} = N_{\epsilon}$ (0,0) if t = 0, and, if $t \ne 0$,

$$\mathbb{N}_{1} = \mathbb{N}_{\epsilon}(0,0) \cup [(u^{1},u^{2}) \in \mathbb{E}_{2} | u^{1} \leq 0, u^{2} \geq -t^{-1}u^{1}, -tu^{1} + u^{2} \leq \epsilon (1+t^{2})^{1/2}].$$

Obviously $U(t',x') - [U(t,x)]_{\epsilon} \neq \emptyset$ for t' > t, hence U(t,x) is not an uppersemicontinuous function of (t,x).

(vii) If A is compact, if U(t,x) is compact for every $(t,x)\in A$ and is an upper semicontinuous function of (t,x) in A, then M is compact.

(viii) If A is closed and $U_j(t,x)$, $(t,x)\in A$, $j=1,\ldots,\nu$, ν finite, are variable subsets of E_m all uppersemicontinuous functions of (t,x) in A, then their union V(t,x) and their intersections W(t,x) are semicontinuous functions of (t,x) in A. The same holds for their product $V(t,x)=U_1\times\ldots\times U_{\nu}$, as well as for their convex hull Z(t,x), that is, for the set Z(t,x) of all $u=p_1u_1+\ldots+p_{\nu}u_{\nu}$ with $u_j\in U_j(t,x)$, $p_j\geq 0$, $j=1,\ldots,\nu$, $p_1+\ldots+p_{\nu}=1$.

The proof is straightforward.

(B) The Property (Q)

Let U(t,x), $(t,x) \in A$, $U(t,x) \in E_m$, be any variable subset of E_m , which is a function of (t,x) in A. By using the same notations as in (A), we shall say that U(t,x) has property (Q) at $(\overline{t,x})$ in A, if

$$U(t,x) = \bigcap_{\delta > 0} \text{ cl co } U(\overline{t}, \overline{x}, \delta).$$

We shall say that U(t,x) has property (Q) in A if U(t,x) has property (Q) at every (t,x) of A.

(ix) Property (Q) at some (t,x) implies property (U) at the same (t,x), and

$$U(\overline{t}, \overline{x}) = \bigcap_{\delta} \operatorname{cl} \operatorname{co} U(\overline{t}, \overline{x}, \delta) = \bigcap_{\delta} \operatorname{cl} U(\overline{t}, \overline{x}, \delta) = \bigcap_{\delta} U(\overline{t}, \overline{x}, \delta).$$

Indeed

where first and last sets coincide by property (Q) at $(\overline{t}, \overline{x})$, and hence the inclusion signs \subset can be replaced by = signs.

(xi) If A is closed, and U(t,x) is any variable set which is a function of (t,x) in A and has property (Q) in A, then the set M of all $(t,x,u) \in AxE_m$ with $u \in U(t,x)$, $(t,x) \in A$, is closed.

Under the hypothesis of (i) the set M is closed but not necessarily compact as the trivial example $U(t,x)=E_m$, $M=AxE_m$ shows. Nevertheless, the statement holds:

(xii) If A is compact, if the set U(t,x) is compact for every $(t,x)\in A$ and possesses property (Q) in A, then the set M is compact.

<u>Proof.</u> If M is not compact, then there is some sequence, $(t_k, x_k, u_k) \in M$, $k = 1, 2, \ldots$, with $(t_k, x_k) \in A$, $|t_k| + |x_k| + |u_k| \to + \infty$ as $k \to \infty$. Since A is compact and hence bounded, we have $|u_k| \to + \infty$. On the other hand, there is some subsequence, say still (t_k, x_k) , with $t_k \to \overline{t}$, $\overline{x_k} \to \overline{x}$, $(\overline{t}, \overline{x}) \in A$. Given $\epsilon > 0$, we have then $u_k \in U(\overline{t}, \overline{x}, \epsilon)$ for all k sufficiently large. Since $U(\overline{t}, \overline{x})$ is compact, there is a solid sphere S containing all of $U(\overline{t}, \overline{x})$ in its interior, say $U(\overline{t}, \overline{x}) \subset I$ int $S \subset E_m$. On the other hand, if $u \in U(\overline{t}, \overline{x})$, we have $u \in I$ int S, and $u_k \in E_m - S$, again for k large. Since both u and u_k belong to the

convex set cl co $U(t,x,\epsilon)$, we have $u'_k\epsilon$ cl co $U(t,x,\epsilon)$ where u'_k is the point of intersection of the segment uu_k with the boundary bd S of S. If u' is any point of accumulation of $[u'_k]$, then $u'\epsilon bd$ S, and $u'\epsilon$ cl co $U(\overline{t},\overline{x},\epsilon)$ for every $\epsilon>0$. Hence $u'\epsilon\cap_{\delta}$ cl co $U(\overline{t},\overline{x},\epsilon)=U(\overline{t},\overline{x})$, a contradiction, since $U(\overline{t},\overline{x})$ int S. We have proved that M is compact.

(xiii) If for every $(t,x) \in A$ the set U(t,x) is closed and convex, and U(t,x) is an uppersemicontinuous function of (t,x) in A, then U(t,x) has property (Q) in A.

<u>Proof.</u> By hypothesis $U(t,x,\delta) \subset [U(t,x)]_{\epsilon}$, where U_{ϵ} is closed and convex as the closed ϵ -neighborhood of a closed convex set. Hence, \bigcap_{δ} cl co $U(t,x,\delta) \subset [U(t,x)]_{\epsilon}$ for every $\epsilon > 0$. Since U(t,x) is closed, then $[U(t,x)]_{\epsilon} \to U(t,x)$ as $\epsilon \to 0+$. Thus \bigcap_{δ} cl co $U(t,x,\delta) \subset U(t,x)$. Since the opposite inclusion relation \supset is trivial, we have \bigcap_{δ} cl co $U(t,x,\delta) = U(t,x)$.

(C) Relations Between Properties of U(t,x) and of Q(t,x)

Let us now consider sets $Q(t,x) = f(t,x,U(t,x)), (t,x) \in A, Q(t,x) \subset E_n$, which are the images of sets $U(t,x) \subset E_m$ for every $(t,x) \in A$.

The hypothesis that A is compact, that f is continuous on M, that U(t,x) has property (Q) [or (U)] in A, and that Q(t,x) is convex for every $(t,x)\in A$, does not imply that Q(t,x) has property (Q) [or U] in A. This can be proved by a simple example. Let m=n=1, $A=[-1\le t\le 1,\ 0\le x\le 1]$, let U(t,x) be the fixed interval $U=[u\in E_1|0\le u<+\infty]$, and $f=(u+1)^{-1}$ - t. Then $Q(t,x)=[z\in E_1|-t< z\le 1-t]$, and, if $-1+\delta < t < 1-\delta$, then $close Q(t,x,\delta)=[-t-\delta \le z\le 1-t+\delta]$.

The intersection of all these sets for $\delta > 0$ is the closed set $[z \in E_1]$ -t $\leq z \leq 1$ -t] which is larger than Q(t,x), and thus Q has not property (Q) in A. Actually, Q(t,x) is not closed, and hence Q(t,x) has neither property (Q), nor property (U).

Even the stronger hypothesis that A is compact, that f is continuous on M, that U(t,x) has property (Q) in A, and that Q(t,x) is compact and convex for every $(t,x)\in A$, does not imply that Q(t,x) has property (Q) in A. This can be proved by the following example. Let m=1, n=1, $A=[(t,x)\in E_2, 0 \le t \le 1, 0 \le x \le 1]$, $U=U(t,x)=\lfloor u\in E_1 \mid 0 \le u \le +\infty \rfloor$, and $f(t,x,u)=tu\exp(1-tu)$, $(t,x,u)\in AxU$. For t=0 we have $f\equiv 0$, hence Q(0,x)=[z=0]. For $0 < t \le 1$, we have $Q(t,x)=[0 \le z \le 1]$. All sets Q(t,x) are compact and convex, but Q(t,x) does not satisfy property (Q) nor property (U) in A.

(xiv) If A is closed and f continuous on M, if U(t,x) is an upper semicontinuous function of (t,x), then Q(t,x) possesses the same property,
and also has property (U). If we know that Q(t,x) is convex, then Q(t,x)has also property (Q).

<u>Proof.</u> Each set Q(t,x) is a compact subset of E_n as the continuous image of the compact set U(t,x). Let us prove that M is closed. Let $(\overline{t},\overline{x},\overline{u})$ be a point of accumulation of M. Then there is a sequence (t_k,x_k,u_k) of points of M with $t_k \to \overline{t}$, $x_k \to \overline{x}$, $u_k \to \overline{u}$, and $(t_k,x_k) \in A$, $u_k \in U(t,x)$. Then $(\overline{t},\overline{x}) \in A$ since A is closed, $(t_k,x_k) \in N_{\overline{b}}(\overline{t},\overline{x})$ for all k sufficiently large, and $u_k \in U(t_k,x_k) \subset [U(\overline{t},\overline{x})]_{\varepsilon}$. Thus, $u \in [U(\overline{t},x)]_{\varepsilon}$ for every $\varepsilon > 0$, and hence $\overline{u} \in U(\overline{t},\overline{x})$ since this set is compact. We have proved

that $(\overline{t}, \overline{x}, \overline{u}) \in M$, and that M is closed. Let us prove that Q(t, x) is an uppersemicontinuous function of (t,x). Given $(t,x)\in A$ and $\epsilon > 0$, let $\delta = \delta(t,x,\epsilon) > 0$ be the number relative to the definition of uppersemicontinuity of U(t,x), and let M' be the set of all (t',x',u') with (t',x') $\in \mathbb{N}_{\delta}(t,x)$, $u' \in U(t',x')$, and M'' be the set of all (t',x',u') with $(t',x') \in \mathbb{N}_{\delta}(t,x)$ (t,x), $u' \in [U(t,x)]_{\epsilon}$. Since U(t,x) is compact, also $[U(t,x)]_{\epsilon}$ is compact. Hence $M'' = N_{\delta}(t,x)x[U(t,x)]_{\epsilon}$, and $M' = M\cap M''$. The set M' is compact as the intersection of the closed set M with the compact cylinder M". The function f is continuous on M' and hence bounded and uniformly continuous. Hence, there is some η , $0<\eta\leq \min{[\delta,\varepsilon]}$, such that $(t",x")\varepsilon N_{\eta}(t',x')$, $|u'-u''| \le \eta$, (t',x',u'), $(t'',x'',u'') \in M'$ implies $|f(t',x',u')-f(t'',x'',u'')| \le \varepsilon$. Also, let $\sigma = \min [\eta, \delta(t,x,\eta)]$. Then, for every $(t',x') \in \mathbb{N}_{\sigma}(t,x)$, we have $U(t',x') \in [U(t,x)]_{\eta}$, hence, if $u' \in U(t',x')$, there is some $u'' \in U(t,x)$ with $|u'-u''| < \eta$, and finally $|f(t',x',u')-f(t,x,u'')| \le \epsilon$. Thus, $Q(t',x') \subset$ $[(Q(t,x)]_{\epsilon}$ for every $(t',x')_{\epsilon}N_{\sigma}(t,x)$. This proves that Q(t,x) has the €8-property above. The last part of statement (xiv) is now a consequence of statements (vi) and (xiii).

Remark. The statements and examples above show that properties (U) and (Q) are generalizations of the concept of upper semicontinuity for closed, or closed and convex sets, respectively.

(xv) If A is a closed subset of the tx-space E_1xE_n , if U(t,x), $(t,x)\in A$, $U(t,x)\subset E_m$, is a variable subset of E_m satisfying property (U) in A, if M denotes the set of all (t,x,u) with $(t,x)\in A$, $u\in U(t,x)$, if f_0 is a continuous scalar function from M into the reals, if U(t,x) denotes the variable sub-

set of E_{m+1} defined by $\widetilde{U}(t,x) = [\widetilde{u} = (u^{\circ},u) \in E_{m+1} | u^{\circ} \ge f_{\circ}(t,x,u), u \in U(t,x)],$ then $\widetilde{U}(t,x)$ satisfies property (U).

Proof. First, let us prove that each set $\widetilde{U}(t_0,x_0,\delta)$ is closed. Indeed, if $\widetilde{u}=(u^0,u)$ is a point of accumulation of $\widetilde{U}(t_0,x_0,\delta)$, then there is a sequence $\widetilde{u}_k=(u_k^0,u_k)$ with $u_k^0 \to u^0$, $u_k \to u$, $\widetilde{u}_k \in \widetilde{U}(t_0,x_0,\delta)$. Hence, there is a corresponding sequence of points $(t_k,x_k)\in \mathbb{N}_\delta(t_0,x_0)$ with $u_k^0 \geq f_0(t_k,x_k,u_k)$, $u_k\in U(t_k,x_k)$. Thus $u_k\in U(t_0,x_0,\delta)$. Since $\mathbb{N}_\delta(t_0,x_0)$ is a compact part of the closed set A, there is a subsequence, say still (t_k,x_k) , with $t_k \to \overline{t}$, $x_k \to \overline{x}$, $(\overline{t},\overline{x})\in \mathbb{N}_\delta(t_0,x_0)$. Thus $(t_k,x_k,u_k)\in \mathbb{M}$, $(t_k,x_k,u_k) \to (\overline{t},\overline{x},u)$, and \mathbb{M} is a closed set by force of (ii). By the continuity of f_0 we have then $(\overline{t},\overline{x},u)\in \mathbb{M}$, $u\in U(\overline{t},\overline{x})$, $u^0 \geq f_0(\overline{t},\overline{x},u)$. Thus $\widetilde{u}=(u^0,u)\in \widetilde{U}(\overline{t},\overline{x})$, and $\widetilde{u}\in \widetilde{U}(t_0,x_0,\delta)$.

Now let $\widetilde{u} = (\overset{\circ}{u}, u)$ be a point $\widetilde{u} \in \Omega_{\delta}$ cl $U(t_0, x_0, \delta)$. Thus, there is a sequence of numbers $\delta_k > 0$, $\delta_k \to 0$, with $\widetilde{u} \in \text{cl } \widetilde{U}(t_0, x_0, \delta_k)$, and hence $\widetilde{u} \in \widetilde{U}(t_0, x_0, \delta_k)$ because these last sets are closed. Thus, there is also a sequence of points $(t_k, x_k) \in \mathbb{N}_{\delta_k}(t_0, x_0)$ with $\widetilde{u} \in \widetilde{U}(t_k, x_k)$, or $u^0 \geq f_0(t_k, x_k, u)$, $u \in U(t_k, x_k)$. Hence, for every $\eta > 0$, we have $u \in U(t_0, x_0, \eta)$ for every k sufficiently large (so that $\delta_k \leq \eta$), and, by property (U) of U(t, x) at (t_0, x_0) , also $u \in \mathfrak{q}$ cl $U(t_0, x_0, \eta) = U(t_0, x_0)$. Thus, $u \in U(t_0, x_0)$, $(t_0, x_0, u) \in \mathfrak{q}$, and by $u^0 \geq f_0(t_k, x_k, u)$ and the continuity of f_0 , also $u^0 \geq f_0(t_0, x_0, u)$. We have proved that $u = (u^0, u) \in \widetilde{U}(t_0, x_0)$, hence

$$N_{\delta} \text{ cl } U(t_{0}, x_{0}, \delta) \subseteq U(t_{0}, x_{0}).$$

Since the opposite inclusion relation is trivial, equality sign holds, and $\widetilde{U}(t,x)$ has property (U) at (t_0,x_0) , and, thus, everywhere in A. Statement

(xv) is thereby proved.

The set U(t,x) of statement (xv) has not necessarily property (Q) even if we assume that U(t,x) has property Q and $f_O(t,x,u)$ is convex in u for every $(t,x)\in A$. This can be seen by a simple example. Let $A=[-1\leq t\leq 1,\ 0\leq x\leq 1]$ and let U=U(t,x) be the fixed set $U(t,x)=E_1$, that is, $U=[-\infty< u^1<+\infty]$. Then, each set U(t,x) is closed and convex, and obviously U(t,x) possesses property (Q), and M is the cylinder of all (t,x,u) with $(t,x)\in A$, $u\in E_1$. Finally, let $f_O(t,x,u)=tu^1$, so that f_O is continuous in M and, for every $(t,x)\in A$, $f_O=tu^1$ is linear in u^1 , hence certainly convex in u^1 . Now we have

$$\tilde{U}(t,x) = [(u^{0},u^{1})\in E_{2}|-\infty < u^{1} < +\infty, tu^{1} < u^{2} < +\infty]$$

 $\widetilde{U}(0,x,\delta) = [(u^0,u^1) \in E_2|_{-\infty} < u^1 < +\infty, -\delta|u^1| \le u^2 < +\infty.$ Consequently, co $\widetilde{U}(0,x,\delta) = E_2$, and hence

$$n_{\delta}$$
 cl co $\tilde{U}(0,x,\delta) = E_2,$

while

$$\widetilde{U}(0,x) = [(u^1,u^2) \in \mathbb{E}_2 | -\infty < u^1 < +\infty, u^2 > 0.$$

This shows that U(t,x) does not have property (Q) at the points (0,x) of A.

A scalar function $f_0(t,x,u)$, $(t,x,u) \in M$, is said to be convex in u at $(t_0,x_0) \in A$ if

$$f_0(t_0,x_0,u_0) \leq \sum_{i=1}^{N} \lambda_i f_0(t_0,x_0,u_i),$$

whenever

$$u_0 = \sum_{i=1}^{N} \lambda_i u_i,$$

where $u_i \in U(t_0, x_0)$, $\lambda_i \ge 0$, $i = 1, \ldots$, N, $\lambda_1 + \ldots + \lambda_N = 1$.

A scalar function $f_0(t,x,u)$, (t,x,u) + M, is said to be <u>quasi normally convex</u> in u at $(t_0,x_0,u_0) \in M$ provided, given $\epsilon > 0$, there are a number $\delta = \delta(t_0,x_0,u_0,\epsilon) > 0$, and a linear scalar function $z(u) = z + b \cdot u$, $b = (b_1,\ldots,b_m)$, c, b_1,\ldots,b_m real, such that

- (a) $f_0(t,x,u) \ge z(u)$ for all $(t,x) \in \mathbb{N}_{\delta}(t_0,x_0), u \in U(t,x)$,
- (b) $f_0(t,x,u) \leq z(u) + \epsilon$ for all $(t,x) \in \mathbb{N}_{\delta}(t_0,x_0)$, $u \in U(t,x)$, $|u-u_0| \leq \delta$.

The scalar function $f_0(t,x,u)$ is said to be <u>normally convex</u> in u at (t_0,x_0,u_0) if, given $\epsilon > 0$, there are numbers $\delta = \delta(t_0,x_0,u_0,\epsilon) > 0$, $\nu = \nu(t_0,x_0,u_0,\epsilon) > 0$, and a linear scalar function $z(u) = r + b \cdot u$ as above such that (b) holds and

(a') $f_0(t,x,u) \ge z(u) + \nu |u-u_0|$ for all $(t,x) \in \mathbb{N}_{\delta}(t_0,x_0), u \in \mathbb{U}(t,x)$.

The scalar function $f_0(t,x,u)$ is said to be <u>quasi normally convex in u</u>, or <u>normally convex in u</u>, if it has these properties at every $(t_0,x_0,u_0) \in M$.

For the case where U=U(t,x) is the fixed set $U=E_m$, the following statement gives a useful characterization of the functions f_0 which are normally convex in u.

(xvi) If A is closed, and $f_0(t,x,u)$ is continuous on $M = AxE_m$, then f_0 is normally convex in u if and only if f_0 is convex in u at every $(t_0,x_0) \in A$, and for no points $(t_0,x_0) \in A$, $u_0,u_1 \in E_m$, $u_1 \neq 0$, the relation holds $f_0(t_0,x_0,u_0) = 2^{-1}[f_0(t_0,x_0,u_0+\lambda u_1) + f_0(t_0,x_0,u_0-\lambda u_1)$ for all $\lambda \geq 0$.

This statement was proved in [9a] and [10]. In particular, if for every $(t,x) \in A, \ f_O(t,x,u) \ \text{is convex in } u \ \text{and} \ f_O(t,x,u)/|u| \to +\infty \ \text{as} \ |u| \to +\infty, \ \text{then}$ certainly $f_O(t,x,u) \ \text{is normally convex in } u.$

(xvii) If A is closed subset of the tx-space $E_1 \times E_n$, if U(t,x), $(t,x) \in A$, $U(t,x) \subset E_m$, is a variable subset of E_m satisfying property (Q) in A, if M denotes the set of all (t,x,u) with $(t,x) \in A$, $u \in U(t,x)$, if f_0 is a continuous function from M into the reals, which is convex in u for every $(t,x) \in A$, if either (α) the sets U(t,x) are all contained in a fixed solid sphere S of E_m , or (β) the function $f_0(t,x,u)$ is quasi normally convex in u at every (t_0,x_0,u_0) of M, then the set U(t,x) of statement (xv) has property (Q) in A.

<u>Proof.</u> Let $\widetilde{u}=(u^{\circ},u)$ be a point $\widetilde{u}=\cap_{\delta}$ cl co $\widetilde{U}(t_{o},x_{o},\delta)$. Then there is a sequence $[\delta_{k}]$ of numbers $\delta_{k}>0$, $\delta_{k}\to0$, with $\widetilde{u}\in cl$ co $\widetilde{U}(t_{o},x_{o},\delta_{k})$. Hence, there is a sequence of pairs of points $\widetilde{u}_{k_{1}}$, $\widetilde{u}_{k_{2}}\in E_{m+1}$ and of points \widetilde{v}_{k} of the segment $(\widetilde{u}_{k_{1}}\widetilde{u}_{k_{2}})\in E_{m+1}$, such that

$$v_k \rightarrow v$$
, $v_{k_1}, v_{k_2} \in U(t_0, x_0, \delta_k)$,

$$\tilde{v}_k = \alpha_k \tilde{u}_{k_1} + (1-\alpha_k)\tilde{u}_{k_2}, \quad 0 \le \alpha_k \le 1, \quad k = 1, 2, \dots$$

We shall use the notation $\tilde{v}_k = (v_k^0, v_k)$, $\tilde{u} = (u^0, u)$, $\tilde{u}_{kj} = (u_{kj}^0, u_{kj})$, j = 1,2. Then we have

$$v_k^{\circ} \rightarrow u^{\circ}, v_k \rightarrow u, u_{k_1}, u_{k_2} \in U(t_0, x_0, \delta_k)$$

$$v_k^{\circ} = \alpha_k u_{k_1}^{\circ} + (1 - \alpha_k) u_{k_2}^{\circ}, \quad v_k = \alpha_k u_{k_1} + (1 - \alpha_k) u_{k_2}^{\circ}$$

Consequently, there are points such that

$$(t_{k_1}, x_{k_1}), (t_{k_2}, x_{k_2}) \in N_{\delta k_1}(t_0, x_0) \subset A,$$

$$u_{k_1} \in U(t_{k_1}, x_{k_1}), u_{k_2} \in U(t_{k_2}, x_{k_2}).$$

The sequence $[\alpha_k]$ is bounded, hence there is a convergent subsequence, say still α_k , so that $\alpha_k \to \alpha$ for some $0 \le \alpha \le 1$.

For every $\eta>0$ and k sufficiently large (so that $\delta_k\leq \eta),$ we have $u_{k_1},u_{k_2}\varepsilon U(t_0,x_0,\eta), \text{ hence}$

$$u_{k_1}, u_{k_2} \in cl \ co \ U(t_0, x_0, \eta).$$

As a consequence

$$v_k = \alpha_k u_{k_1} + (1-\alpha_k) u_{k_2} \in cl co U(t_0, x_0, \eta)$$

for all k sufficiently large. As $k \to \infty$, we obtain uecl co $U(t_0,x_0,\eta)$. By the property (U), finally

$$ue \cap_{\eta} cl co U(t_0, x_0, \eta) = U(t_0, x_0). \tag{1}$$

Assume first that condition (α) holds. Then both sequences $[u_{k_1}]$, $[u_{k_2}]$ are bounded, and hence there is a subsequence, say still $[u_{k_1}]$, $[u_{k_2}]$, for which both u_{k_1} and u_{k_2} are convergent in E_m , say $u_{k_1} \rightarrow u_1$, $u_{k_2} \rightarrow u_2$, $u_1, u_2 \in E_m$. For such a subsequence, we have

$$\begin{array}{rcl} v_{k}^{\circ} &=& \alpha_{k}u_{k_{1}}^{\circ} + (1-\alpha_{k})u_{k_{2}}^{\circ} \geq \alpha_{k}f_{o}(t_{k_{1}},x_{k_{1}},u_{k_{1}}) + (1-\alpha_{k})f_{o}(t_{k_{2}},x_{k_{2}},u_{k_{2}}), \\ \\ v_{k} &=& \alpha_{k}u_{k_{1}} + (1-\alpha_{k})u_{k_{2}}, \\ \\ (t_{k_{1}},x_{k_{1}},u_{k_{1}}), \ (t_{k_{2}},x_{k_{2}},u_{k_{2}}) \in M, \end{array}$$

where M is closed. By taking limits as $k \rightarrow \infty$, we have

$$u^{\circ} \geq \alpha f_{\circ}(t_{\circ}, x_{\circ}, u_{1}) + (1-\alpha)f_{\circ}(t_{\circ}, x_{\circ}, u_{2})$$

$$u = \alpha u_{1} + (1-\alpha)u_{2},$$

$$(t_{\circ}, x_{\circ}, u_{1}), (t_{\circ}, x_{\circ}, u_{2}) \in M.$$

By the convexity of f_0 in u at (t_0,x_0) we have now

$$u^{\circ} \ge f_{\circ}(t_{\circ}, x_{\circ}, \alpha u_{1} + (1-\alpha)u_{2}) = f_{\circ}(t_{\circ}, x_{\circ}, u).$$

This proves that $\tilde{u} = (u^{\circ}, u) \in \tilde{U}(t_{\circ}, x_{\circ})$, hence

$$\bigcap_{\delta} cl co U(t_{o}, x_{o}) \subset U(t_{o}, x_{o}).$$
 (2)

Since the opposite inclusion is trivial, = sign holds in this relation, and $\tilde{U}(t,x)$ has property (Q) at (t_0,x_0) . Since $(t_0,x_0)\in A$ is arbitrary, $\tilde{U}(t,x)$ has property (Q) in A.

Assume now that condition (β) holds. As stated by relation (1) above, $u \in U(t_0,x_0)$, hence $(t_0,x_0,u) \in M$. By the quasi normal convexity of f_0 in u at (t_0,x_0,u) we deduce the existence of a number $\delta>0$ and of a linear scalar function z(u)=r +b. v such that (a) $f_0(t,x,v)=z(v)$ for all $(t,x)\in N_\delta(t_0,x_0)$, $v\in U(t,x)$ and (b) $f_0(t,x,w)\leq z(v)+\varepsilon$ for all $(t,x)\in N_\delta(t_0,x_0)$, $v\in U(t,x)$, $|u-v|\leq \delta$. By combining (a) and (b) we have then (c) $z(u)\leq f_0(t_0,x_0,u)=z(u)+\varepsilon$.

Now we have $v_k = \alpha_k u_{k_1} + (1-\alpha_k) u_{k_0}$ for some $0 \le \alpha_k \le 1$, and $v_k \to u$, $(t_{kj}, x_{kj}) \to (t_0, x_0), \ j = 1, 2. \quad \text{Thus, for } k \text{ sufficiently large, } (t_{kj}, x_{kj}) \in \mathbb{N}_\delta$ $(t_0, x_0), \ j = 1, 2, \ \text{and, by property (a),}$

$$\begin{array}{lll} v_{k}^{0} & \geq & \alpha_{k}^{}f_{0}(t_{k_{1}},x_{k_{1}},u_{k_{1}}) + (1-\alpha_{k}^{})f_{0}(t_{k_{2}},x_{k_{2}},u_{k_{2}}) \\ \\ & \geq & \alpha_{k}^{}z(u_{k_{1}}) + (1-\alpha_{k}^{})z(u_{k_{2}}) & = \\ \\ & = & z(\alpha_{k}^{}u_{k_{1}} + (1-\alpha_{k}^{})u_{k_{2}}) & = & z(v_{k}). \end{array}$$

As $k \leftrightarrow +\infty$, we have then $u^O \geq z(u)$, and finally by (c) above, $u^O \geq f_O(t_O, x_O, u)$ $-\varepsilon, \text{ where } \varepsilon > 0 \text{ is arbitrary.} \text{ We conclude that } u^O \geq f_O(t_O, x_O, u), \text{ with } u \varepsilon U(t_O, x_O). \text{ Thus } \widetilde{u} = (u^O, v) \varepsilon U(t_O, x_O), \text{ and again we have proved inclusion}$ (2). The same reasoning above yields that U(t, x) has property (Q) in A.

(xviii) If A is a closed subset of the tx-space $E_1 \times E_n$, if U(t,x), $(t,x) \in A$, is a variable subset of E_m satisfying property (U) in A, if M denotes the set of all (t,x,u) with $(t,x) \in A$, $u \in U(t,x)$, if $f = (f_0,f)$ is a continuous function from M into the \tilde{z} -space E_{n+1} , $z = (z^0,z)$, if $Q(t,x) \subset E_n$, $\tilde{Q}(t,x) \subset E_{n+1}$ are the sets

 $Q(t,x) = f(t,x,U(t,x)) = [z \in E_n | z = f(t,x,u), u \in U(t,x)],$

 $\widetilde{\mathbb{Q}}(t,x) = [\widetilde{z} = (z^{\circ},z) \in \mathbb{E}_{n+1} | z^{\circ} \geq f_{o}(t,x,u), \ z = f(t,x,u), \ u \in \mathbb{U}(t,x)],$ and (a) for every $(t,x) \in \mathbb{A}$, $\mathbb{Q}(t,x)$ is a convex subset of \mathbb{E}_{n} ; (b) $\mathbb{Q}(t,x)$ has propriety (Q) in A; (c) for every $(t,x) \in \mathbb{A}$, z = f(t,x,u) is a 1-1 map from $\mathbb{U}(t,x)$ onto $\mathbb{Q}(t,x)$ with a continuous inverse $u = f^{-1}(t,x,z), \ z \in \mathbb{Q}(t,x)$; (d) the real valued function $\mathbb{F}_{o}(t,x,z) = \mathbb{F}_{o}(t,x,f^{-1}(t,x,z)), \ (t,x) \in \mathbb{A}, \ z \in \mathbb{Q}(t,x),$ is continuous in the set M' of all (t,x,z) with $(t,x) \in \mathbb{A}, \ z \in \mathbb{Q}(t,x),$ and $\mathbb{F}_{o}(t,x,z)$ is convex in z and also quasi normally convex, then the set $\widetilde{\mathbb{Q}}(t,x)$ is convex and has property (Q) in A.

<u>Proof.</u> Indeed, under the specific hypotheses above, the set $\tilde{Q}(t,x)$ can be represented as

$$\overset{\approx}{\mathsf{Q}}(\mathsf{t},\mathsf{x}) = [\overset{\sim}{\mathsf{z}} = (\mathsf{z}^{\mathsf{o}},\mathsf{z}) \boldsymbol{\epsilon} \mathbb{E}_{\mathsf{n}+1} | \mathsf{z}^{\mathsf{o}} \geq \mathbb{F}_{\mathsf{o}}(\mathsf{t},\mathsf{x},\mathsf{z}), \ \mathsf{z} \boldsymbol{\epsilon} \mathbb{Q}(\mathsf{t},\mathsf{x})],$$

and thus \tilde{Q} is generated from Q(t,x) exactly as \tilde{U} is generated from U(t,x). By statement (xvii) above we conclude that $\tilde{Q}(t,x)$ has property (Q) in A.

Remark. The condition that f is a homeomorphism between U and Q is certainly verified in all free problems, where m=n, f=u, that is, $f_1=u^1$, $i=1,2,\ldots,n$ (see no. 9 below). In this situation then we have $F_0(t,x,u)=f_0(t,x,u)$, and the convexity of f_0 in u implies the convexity of

 F_{o} in u. We shall need this remark, and the more general statement (xviii) in part II.

5. CLOSURE THEOREMS

We shall use here the notations of no. 2 and 3. In particular, a trajectory x(t) is defined as in no. 2.

Closure Theorem I. (A first generalization of Filippov's theorem). Let A be a closed subset of E_1 x E_n , let U(t,x) be a closed subset of E_m for every $(t,x)\in A$, let $f(t,x,u)=(f_1,\ldots,f_n)$ be a continuous vector function on M into E_n , and let Q(t,x)=f(t,x,U(t,x)) be a closed convex subset of E_n for every $(t,x)\in A$. Assume that U(t,x) has property (U) in A, and that Q(t,x) has property (Q) in A. Let $x_k(t)$, $t_{1k} \leq t \leq t_{2k}$, $k=1,2,\ldots$, be a sequence of trajectories, which is convergent in the metrix ρ toward an absolutely continuous function x(t), $t_1 \leq t \leq t_2$. Then x(t) is a trajectory.

Remark. If we assume that U(t,x) is compact for every (t,x) $\in A$, and that U(t,x) is an uppersemicontinuous function of (t,x) in A, then by statement (x), the set Q(t,x) has the same property, U(t,x) has property (U), Q(t,x) has property (Q), and closure theorem I reduces to one of A. F. Filippov [2] (not explicitly stated in [2] but contained in the proof of his existence theorem for the Pontryagin problem with U(t,x) always compact).

Proof of Closure Theorem I. The vector functions

$$\phi(t) = x'(t), \quad t_1 \le t \le t_2,$$

$$\phi_k(t) = x_k'(t) = f(t, x_k(t), u_k(t)), \quad t_{1k} \le t \le t_{2k}, \quad k = 1, 2, ...,$$

are defined almost everywhere and are L-integrable. We have to prove that

 $(t,x(t))\in A$ for every $t_1\leq t\leq t_2$, and that there is an admissible control function u(t), $t_1\leq t\leq t_2$, such that

$$\phi(t) = x'(t) = f(t,x(t),u'(t)), u(t)\in U(t,x(t)),$$
 (2)

for almost all $te[t_1t_2]$.

First, $\rho(x_k,x) \to 0$ as $k \to 0$; hence, $t_{1k} \to t_1$, $t_{2k} \to t_2$. If $t \in (t_1,t_2)$, or $t_1 < t < t_2$, then $t_{1k} < t < t_{2k}$ for all k sufficiently large and $(t,x_k(t)) \in A$. Since $x_k(t) \to x(t)$ as $k \to \infty$ and A is closed, we conclude that $(t,x(t)) \in A$ for every $t_1 < t < t_2$. Since x(t) is continuous, and hence continuous at t_1 and t_2 , we conclude that $(t,x(t)) \in A$ for every $t_1 \le t \le t_2$.

For almost all $t \in [t_1, t_2]$ the derivative x'(t) exists and is finite. Let t_0 be such a point with $t_1 < t_0 < t_2$. Then there is a $\sigma > 0$ with $t_1 < t_0 - \sigma < t_0 + \sigma < t_2$, and, for some k_0 and all $k \ge k_0$, also $t_1 k < t_0 - \sigma < t_0 + \sigma < t_2 k$. Let $x_0 = x(t_0)$.

We have $x_k(t) \to x(t)$ uniformly in $[t_0 - \sigma, t_0 + \sigma]$ and all functions x(t), $x_k(t)$ are continuous in the same interval. Thus, they are equicontinuous in $[t_0 - \sigma, t_0 + \sigma]$. Given $\epsilon > 0$, there is a $\delta > 0$ such that $t,t'\epsilon[t_0 - \sigma, t_0 + \sigma]$, $|t-t'| \le \delta$, $k \ge k_0$, implies

$$|x(t) - x(t^{\dagger})| \le \epsilon/2$$
 $|x_k(t) - x_k(t^{\dagger})| \le \epsilon/2$.

We can assume $0 < \delta < \sigma$, $\delta \le \varepsilon$. For any h, $0 < h \le \delta$, let us consider the averages

$$m_{h} = h^{-1} \int_{0}^{h} \varphi(t_{0}+s)ds = h^{-1}[x(t_{0}+h)-x(t_{0})],$$

$$m_{hk} = h^{-1} \int_{0}^{h} \varphi_{k}(t_{0}+s)ds = h^{-1}[x_{k}(t_{0}+h)-x_{k}(t_{0})].$$
(3)

Given $\eta > 0$ arbitrary, we can fix h, $0 < h \leq \delta < \sigma,$ so small that

$$|m_h - \varphi(t_O)| \le \eta. \tag{4}$$

Having so fixed h, let us take $k_1 \ge k_0$ so large that

$$|\mathbf{m}_{hk} - \mathbf{m}_{h}| \le \eta, \quad |\mathbf{x}_{k}(\mathbf{t}_{O}) - \mathbf{x}(\mathbf{t}_{O})| \le \epsilon/2$$
 (5)

for all $k \ge k_1$. This is possible since $x_k(t) \to x(t)$ as $k \to \infty$ both at $t = t_0$ and $t = t_0 + h$. Finally, for $0 \le s \le h$,

$$\begin{split} |x_{k}(t_{0}+s)-x(t_{0})| &\leq |x_{k}(t_{0}+s)-x_{k}(t_{0})|+|x_{k}(t_{0})-x(t_{0})| \\ &\leq \varepsilon/2 + \varepsilon/2 = \varepsilon, \\ |(t_{0}+s)-t_{0}| &\leq h \leq \delta \leq \varepsilon \\ f(t_{0}+s,x_{k}(t_{0}+s),u_{k}(t_{0}+s))\varepsilon Q(t_{0}+s,x_{k}(t_{0}+s)). \end{split}$$

Hence, by the definition of $Q(t_0,x_0,2\varepsilon)$, also

$$\varphi_{\mathbf{k}}(\mathsf{t}_{\mathsf{O}}+\mathsf{s}) = f(\mathsf{t}_{\mathsf{O}}+\mathsf{s},\mathsf{x}_{\mathbf{k}}(\mathsf{t}_{\mathsf{O}}+\mathsf{s}), \mathsf{u}_{\mathbf{k}}(\mathsf{t}_{\mathsf{O}}+\mathsf{s})) \in Q(\mathsf{t}_{\mathsf{O}},\mathsf{x}_{\mathsf{O}},2\epsilon).$$

The second integral relation (3) shows that we have also

$$m_{hk} \in cl co Q(t_0, x_0, 2\epsilon),$$

since the latter is a closed convex set. Finally, by relations (4) and (5), we deduce

$$|\varphi(t_0) - m_{hk}| \le |\varphi(t_0) - m_h| + |m_h - m_{hk}| \le 2\eta$$

and hence

$$\phi(t_0)\epsilon$$
 [cl co $Q(t_0,x_0,2\epsilon)$]_{2 η} .

Here $\eta > 0$ is an arbitrary number, and the set in brackets is closed. Hence,

$$\varphi(t_0)\epsilon$$
 cl co $Q(t_0,x_0,2\epsilon)$,

and this relation holds for every $\epsilon > 0$. By property (Q) we have

$$\varphi(t_0) \in \cap_{\epsilon} cl co Q(t_0, x_0, 2\epsilon) = Q(t_0, x_0),$$

where $x_0 = x(t_0)$, and $Q(t_0, x_0) = f(t_0, x_0, U(t_0, x_0))$. This relation implies that there are points $\overline{u} = \overline{u}(t_0) \in U(t_0, x_0)$ such that

$$\varphi(t_0) = f(t_0, x(t_0), \overline{u}(t_0)). \tag{6}$$

This holds for almost all $t_0 \in [t_1, t_2]$, that is, for all t of a measurable set $I \subset [t_1, t_2]$ with meas $I = t_2 - t_1$. If we take $I_0 = [t_1, t_2] - I$, then means $I_0 = 0$. Hence, there is at least one function $\overline{u}(t)$, defined almost everywhere in $[t_1, t_2]$, for which relation (6) holds a.e. in $[t_1, t_2]$. We have to prove that there is at least one such function which is measurable. For every $t \in I$, let P(t) denote the set

 $P(t) = [u|u \in U(t,x(t)), \phi(t) = f(t,x(t),u] \subseteq U(t,x(t)) \subseteq E_m.$ We have proved that P(t) is not empty.

For every integer $\lambda=1,2,\ldots$, there is a closed subset C_{λ} of I, $C_{\lambda} \subset I \subset [t_1,t_2]$, with meas $C_{\lambda} > \max [0,t_2-t_1-1/\lambda]$, such that $\phi(t)$ is continuous on λ . Let W_{λ} be the set

$$W_{\lambda} = [(t,u)|teC_{\lambda}, ueP(t)] \subset E_1 \times E_m.$$

Let us prove that the set W_{λ} is closed. Indeed, if $(\overline{t},\overline{u})$ is a point of accumulation of W_{λ} , then there is a sequence (t_s,u_s) , $s=1,2,\ldots$, with $(t_s,u_s)\in W_{\lambda}$, $t_s\to E$, $u_s\to \overline{u}$. Then $t_s\in C_{\lambda}$ and $\overline{t}\in C_{\lambda}$ since C_{λ} is closed. Also $x(t_s)\to x(\overline{t})$, $\phi(t_s)\to \phi(\overline{t})$, and since $(t_s,x(t_s))\in A$, $\phi(t_s)=f(t_s,x(t_s),u(t_s))$, $(t_s,x(t_s),u(t_s))\in M$, we have also $(\overline{t},x(\overline{t}))\in A$, $(t,x(\overline{t}),\overline{u})\in M$, because

A and M are closed, and $\phi(\overline{t})=f(\overline{t},x(\overline{t}),\overline{u})$ because f is continuous. Thus, $\overline{u} \in P(\overline{t})$, and $(\overline{t},\overline{x}) \in W_{\lambda}$.

For every integer ℓ let $W_{\lambda\ell}$, $P_{\ell}(t)$, be the sets

$$\begin{split} \mathbf{W}_{\lambda} \ell &= [(\mathtt{t},\mathtt{u}) | (\mathtt{t},\mathtt{u}) \in \mathbf{W}_{\lambda}, |\mathtt{u}| \leq \ell] \subset \mathbf{W}_{\lambda} \subset \mathbf{E}_{1} \times \mathbf{E}_{m}, \\ \mathbf{P}_{\ell}(\mathtt{t}) &= [\mathtt{u} | \mathtt{u} \in \mathbf{P}(\mathtt{t}), |\mathtt{u}| \leq \ell] \subset \mathbf{P}(\mathtt{t}) \subset \mathbf{U}(\mathtt{t},\mathtt{x}(\mathtt{t})) \subset \mathbf{E}_{m}, \\ \mathbf{C}_{\lambda} \ell &= [\mathtt{t} | (\mathtt{t},\mathtt{u}) \in \mathbf{W}_{\lambda} \ell \text{ for some } \mathtt{u}] \subset \mathbf{C}_{\lambda} \subset \mathbf{I} \subset [\mathtt{t}_{1},\mathtt{t}_{2}]. \end{split}$$

Obviously, $W_{\lambda,\ell}$ is compact, and so is $C_{\lambda,\ell}$ as its projection on the t-axis. Also, $U_{\ell}C_{\lambda,\ell} = C_{\lambda}$, and $W_{\lambda,\ell}$ is the set of all (t,u) with $t \in C_{\lambda,\ell}$, $u \in P_{\ell}(t)$. Thus, for $t \in C_{\lambda,\ell}$, P(t) is a compact subset of U(t,x(t)).

For $\mathrm{tcC}_{\lambda\ell}$, the set $\mathrm{P}_{\ell}(\mathrm{t})$ is the nonempty compact subset of all $\mathrm{u}=(\mathrm{u}^1,\ldots,\mathrm{u}^m)\mathrm{cU}(\mathrm{t},\mathrm{x}(\mathrm{t}))$ with $\mathrm{f}(\mathrm{t},\mathrm{x}(\mathrm{t}),\mathrm{u})=\varphi(\mathrm{t})$. As in Filippov's argument let P, be the subset of P with u^1 minimum, let P_2 be the subset of P₁ with u^2 minimum,..., let P_m be the subset of P_{m-1} with u^m minimum. Then P_m is a single point $\mathrm{u}=\mathrm{u}(\mathrm{t})\mathrm{cU}(\mathrm{t},\mathrm{x}(\mathrm{t}))$ with $\mathrm{u}(\mathrm{t})=(\mathrm{u}^1,\ldots,\mathrm{u}^m)$, $\mathrm{tcC}_{\lambda\ell}$, $|\mathrm{u}(\mathrm{t})|\leq \ell$, and $\mathrm{f}(\mathrm{t},\mathrm{x}(\mathrm{t}),\mathrm{u}(\mathrm{t}))=\varphi(\mathrm{t})$. Let us prove that $\mathrm{u}(\mathrm{t})$, $\mathrm{tcC}_{\lambda\ell}$ is measurable. We shall prove this by induction on the coordinates. Let us assume that $\mathrm{u}^1(\mathrm{t}),\ldots,\mathrm{u}^{S-1}(\mathrm{t})$ have been proved to be measurable on $\mathrm{C}_{\lambda\ell}$ and let us prove that $\mathrm{u}^1(\mathrm{t}),\ldots,\mathrm{u}^{S-1}(\mathrm{t})$ have been proved to be measurable on $\mathrm{C}_{\lambda\ell}$ and the argument below proves that $\mathrm{u}^1(\mathrm{t})$ is measurable. For s = 1 nothing is assumed, and the argument below proves that $\mathrm{u}^1(\mathrm{t})$ is measurable. For every integer j there are closed subsets $\mathrm{C}_{\lambda\ell j}$ of $\mathrm{C}_{\lambda\ell}$ with $\mathrm{C}_{\lambda\ell j}\subset\mathrm{C}_{\lambda\ell}$, $\mathrm{C}_{\lambda\ell j}\subset\mathrm{C}_{\lambda\ell}$, $\mathrm{C}_{\lambda\ell j}$, meas $\mathrm{C}_{\lambda\ell j}>0$. [O, meas $\mathrm{C}_{\lambda\ell}$], such that $\mathrm{u}^1(\mathrm{t}),\ldots,\mathrm{u}^{S-1}(\mathrm{t})$ are continuous on $\mathrm{C}_{\lambda\ell j}$. The function $\mathrm{\phi}(\mathrm{t})$ is already continuous on C_{λ} and hence $\mathrm{\phi}(\mathrm{t})$ is continuous on every set $\mathrm{C}_{\lambda\ell}$ and $\mathrm{C}_{\lambda\ell j}$. Let us prove that $\mathrm{u}^S(\mathrm{t})$ is measurable on $\mathrm{C}_{\lambda\ell j}$.

We have only to prove that, for every real a, the set of all $t \in C_{\lambda \ell j}$ with $\phi^S(t) \leq a$ is closed. Suppose that this is not the case. Then there is a sequence of points $t_k \in C_{\lambda \ell j}$ with $u^S(t_k) \leq a$, $t_k \to \overline{t} \in C_{\lambda \ell j}$, $u^S(\overline{t}) > a$. Then $\phi(t_k) \to \phi(\overline{t})$, $u^{\alpha}(t_k) \to u^{\alpha}(\overline{t})$ as $k \to \infty$, $\alpha = 1, \ldots, s-1$. Since $|u^{\beta}(t_k)| \leq \ell$ for all k and $\beta = s, s+1, \ldots, m$, we can select a subsequence, say still $[t_k]$ such that $u^{\beta}(t_k) \to \overline{u}^{\beta}$ as $k \to \infty$, $\beta = s, s+1, \ldots, m$, for some real numbers \overline{u}^{β} . Then $t_k \to \overline{t}$, $x(t_k) \to x(\overline{t})$, $u(t_k) \to \overline{u}$, where

$$\widetilde{\mathbf{u}} = (\mathbf{u}^{1}(\overline{\mathbf{t}}), \dots, \mathbf{u}^{s-1}(\overline{\mathbf{t}}), \widetilde{\mathbf{u}}^{s}, \dots, \widetilde{\mathbf{u}}^{m})$$

Then, given any number $\eta > 0$, we have

$$u(t_k) \in U(t_k, x(t_k)) \subset cl \ U(\overline{t}, x(t), \eta)$$

for all k sufficiently large, and, as $k \rightarrow \infty$, also

$$\tilde{u} \in cl \ U(\overline{t}, x(\overline{t}), \eta).$$

By the property (U) we have

$$\widetilde{u} \in \cap_{\eta} \text{ cl } U(\overline{t}, x(\overline{t}), \eta) = U(\overline{t}, x(\overline{t}))$$

On the other hand $\phi(t_k) = f(t_k, x(t_k), u(t_k)), u(t_k) \le a$, yield as $k \to \infty$,

$$\varphi(\overline{t}) = f(\overline{t}, x(\overline{t}), \widetilde{u}), \quad \widetilde{u}^{S} < a, \tag{6}$$

while $\overline{t} \in C_{\lambda \ell}$ implies

$$\varphi(\overline{t}) = f(\overline{t}, x(\overline{t}), u(\overline{t})), \quad u^{s}(\overline{t}) > a.$$
 (7)

Relations (6) and (7) are contradictory because of the property of minimum with which $u^S(\overline{t})$ has been chosen. Thus $u^S(t)$ is measurable on $C_{\lambda\ell j}$ for every j, and then $u^S(t)$ is also measurable on $C_{\lambda\ell}$. By induction argument, all components $u^1(t), \ldots, u^m(t)$ of u(t) are measurable on $C_{\lambda\ell}$,

hence u(t) is measurable on $C_{\lambda,\ell}$. Since $U_{\ell}C_{\lambda,\ell}=C_{\lambda}$, meas $C_{\lambda}>$ meas $I-1/\lambda$, we conclude that u(t) is measurable on every set C_{λ} and hence on I, with meass $I=t_2-t_1$. Thus, u(t) is defined a.e. on (t_1,t_2) , $u(t)\in U(t,x(t))$ and $f(t,x(t),u(t))=\phi(t)$ a.e. on $[t_1,t_2]$. Closure Theorem I is thereby proved.

Let us denote by $y = (x^1, ..., x^S)$ the s-vector made up of certain components, say $x^1, ..., x^S$, $0 \le s \le n$, of $x = (x^1, ..., x^n)$, and by z the complementary (n-s)-vector $z = (x^{s+1}, ..., x^n)$ of x, so that x = (y,z). Let us assume that f(t,y,u) depends only on the coordinates $x^1, ..., x^S$ of x. If x(t), $t_1 \le t \le t_2$, is any vector function, we shall denote by x(t) = [y(t), z(t)] the corresponding decomposition of x(t) in its coordinates $y(t) = (x^1, ..., x^S)$ and $z(t) = (x^{S+1}, ..., x^N)$.

We shall denote by A_O a closed subset of points $(t,x^1,...,x^S)$, that is, a closed subset of the ty-space E_1xE_S , and let $A=A_O$ x E_{n-S} . Thus, A is a closed subset of the tx-space E_1xE_N .

Closure Theorem II. (A further generalization of Filippov's Theorem). Let A_0 be a closed subset of the ty-space E_1xE_5 , and then $A=A_0$ x E_{n-s} is a closed subset of the tx-space E_1xE_n . Let U(t,y) denote a closed subset of E_m for every $(t,y)\in A_0$, let M_0 be the set of all $(t,y,u)\in E_1+_{g+m}$ with $(t,y)\in A_0$, $u\in U(t,y)$, and let $f(t,y,u)=(f_1,\ldots,f_n)$ be continuous vector function from M into E_n . Let Q(t,y)=f(t,y,U(t,y)) be a closed convex subset of E_n for every $(t,y)\in A_0$. Assume that U(t,y) has property (U) in A_0 and that Q(t,y) has property (Q) in A_0 .

Let $x_k(t)$, $t_{1k} \leq t \leq t_{2k}$, $k = 1, 2, \ldots$, be a sequence of trajectories, $x_k(t) = (y_k(t), z_k(t))$, for which we assume that the s-vector $y_k(t)$ converges in the p-metric toward an AC vector function y(t), $t_1 \leq t \leq t_2$, and that the (n-k)-vector $z_k(t)$ converges (pointwise) for almost all $t_1 < t < t_2$, toward a vector z(t) which admits of a decomposition z(t) = Z(t) + S(t) where Z(t) is an AC vector function in $[t_1,t_2]$, and S'(t) = 0 a.e. in $[t_1,t_2]$ (that is, S(t) is a singular function). Then, the AC vector X(t) = [y(t),Z(t)], $t_1 \leq t \leq t_2$, is a trajectory.

Remark. For s = n, this theorem reduces to closure theorem I.

Proof of Closure Theorem II. The vector functions

$$\varphi(t) = X'(t) = (y'(t),Z'(t)), t_1 \le t \le t_2,$$

$$\phi(t) = x'_{k}(t) = (y'_{k}(t), z'_{k}(t)) = f(t, y_{k}(t), u_{k}(t)), \quad t_{1k} \le t \le t_{2k}$$

$$(8)$$

$$k = 1, 2, ...,$$

are defined almost everywhere and are L-integrable. We have to prove that $[t,y(t),Z(t)]\in A$ for every $t_1\leq t\leq t_2$, and that there is an admissible control function u(t), $t_1\leq t\leq t_2$, such that

$$\phi(t) = X'(t) = (y'(t),Z'(t)) = f(t,y(t),u(t)),$$

$$u(t) \in U(t,y(t)),$$

for almost all $t \in [t_1, t_2]$.

First, $\rho(y_k,y) \to 0$ as $k \to 0$; hence $t_{1k} \to t_1, t_{2k} \to t_2$. If $te(t_1,t_2)$, or $t_1 < t < t_2$, then $t_{1k} < t < t_{2k}$ for all k sufficiently large, and $(t,y_k(t) \in A_0$. Since $y_k(t) \to y(t)$ as $k \to \infty$ and A_0 is closed, we conclude that $(t,y(t)) \in A_0$ for every $t_1 < t < t_2$, and finally $(t,y(t),Z(t)) \in A_0$ x E_{n-s} ,

or $(t,x(t))\in A$, $t_1 \leq t \leq t_2$.

For almost all $tc[t_1,t_2]$ the derivative X'(t)=[y'(t),Z'(t)] exists and is finite, S'(t) exists and S'(t)=0, and $z_k(t) \rightarrow z(t)$. Let t_0 be such a point with $t_1 < t_0 < t_2$. Then there is a $\sigma > 0$ with $t_1 < t_0 - \sigma < t_0 + \sigma < t_2$, and, for some k_0 and all $k > k_0$, also $t_{1k} < t_0 - \sigma < t_0 + \sigma < t_{2k}$. Let $x_0 = x(t_0) = (y_0, Z_0)$, or $y_0 = y(t_0)$, $Z_0 = Z(t_0)$. Let $z_0 = z(t_0)$, $S_0 = S(t_0)$. We have $S'(t_0) = 0$, hence $z'(t_0)$ exists and $z'(t_0) = Z'(t_0)$. Also, we have $Z_k(t_0) \rightarrow z(t_0)$.

We have $y_k(t) \rightarrow y(t)$ uniformly in $[t_0 - \sigma, t_0 + \sigma]$, and all functions y(t), $y_k(t)$ are continuous in the same interval. Thus, they are equicontinuous in $[t_0 - \sigma, t_0 + \sigma]$. Given $\epsilon > 0$, there is a $\delta > 0$ such that $t,t' \in [t_0 - \sigma, t_0 + \sigma]$, $|t - t'| \leq \delta$, $k \geq k_0$, implies

$$|y(t) - y(t')| \le \epsilon/2$$
, $|y_k(t) - y_k(t')| \le \epsilon/2$.

We can assume $0 < \delta < \sigma$, $\delta \le \varepsilon$. For any h,0 < h $\le \delta$, let us consider the averages

$$m_{h} = h^{-1} \int_{0}^{h} \varphi(t_{0} + s) ds = h^{-1} [X(t_{0} + h) - X(t))],$$

$$m_{hk} = h^{-1} \int_{0}^{h} \varphi_{k}(t_{0} + s) ds = h^{-1} [x_{k}(t_{0} + h) - x_{k})],$$
(10)

where X = (y,Z), $x_k = (y_k,z_k)$.

Given $\eta > 0$ arbitrary, we can fix h, $0 < h \leq \delta < \sigma,$ so small that

$$|m_h - \varphi(t_0)| \leq \eta$$

$$|S(t_0 + h) - S(t_0)| < \eta h/4,$$

This is possible since $h^{-1}\int_{0}^{h} \phi(t_{0}+s)ds \rightarrow \phi(t_{0})$ and $[S(t_{0}+h)-S(t_{0})]h^{-1}$ \rightarrow 0 as $h\rightarrow 0+$. Also, we can choose h, in such a way that $z_{k}(t_{0}+h)$ \rightarrow $z(t_{0})$ as $k\rightarrow +\infty$. This is possible since $z_{k}(t)\rightarrow z(t)$ for almost all $t_{1}< t< t_{2}$.

Having so fixed h, let us take $k_1 \ge k_0$ so large that

$$|y_k(t_0) - y(t_0)|$$
, $|y_k(t_0 + h) - y(t_0 + h)| \le \min [\eta h/4, \epsilon/2]$, $|z_k(t_0) - z(t_0)|$, $|z_k(t_0 + h) - z(t_0 + h)| < \eta h/8$.

This is possible since $y_k(t) \to y(t), z_k(t) \to z(t)$ both at $t=t_0$ and $t=t_0+h$. Then we have

$$\begin{split} |h^{-1}[y_k(t_0 + h) - y_k(t_0)] - h^{-1}[y(t_0 + h) - y(t_0)]| \\ &\leq |h^{-1}[y_k(t_0 + h) - y(t_0 + h)]| + |h^{-1}[y_k(t_0) - y(t_0)]| \\ &\leq h^{-1}(\eta h/4) + h^{-1}(\eta h/8) < \eta/2. \end{split}$$

Analogously, since z = Z + S, we have

$$|h^{-1}[z_{k}(t_{o} + h) - z_{k}(t_{o})] - h^{-1}[Z(t_{o} + h) - Z(t_{o})]|$$

$$= |h^{-1}[z_{k}(t_{o} + h) - z_{k}(t_{o})] - h^{-1}[z(t_{o} + h) - z(t_{o})] + h^{-1}[S(t_{o} + h) - S(t_{o})]|$$

$$\leq |h^{-1}[z_k(t_0 + h) - z(t_0 + h)]| + |h^{-1}[z_k(t_0) - z(t_0)]| + |h^{-1}[S(t_0 + h) - S(t_0)]|$$

$$\leq h^{-1}(\eta h/8) + h^{-1}(\eta h/8) + h^{-1}(\eta h/4) = \eta/2.$$

Finally, we have

$$|\mathbf{m}_{hk} - \mathbf{m}_{h}| = |\mathbf{h}^{-1}[\mathbf{x}_{k}(t_{o} + h) - \mathbf{x}_{k}(t_{o})] - \mathbf{h}^{-1}[\mathbf{X}(t_{o} + h) - \mathbf{X}(t_{o})]|$$

$$= |\mathbf{h}^{-1}[\mathbf{y}_{k}(t_{o} + h) - \mathbf{y}_{k}(t_{o})] - \mathbf{h}^{-1}[\mathbf{y}(t_{o} + h) - \mathbf{y}(t_{o})]| +$$

+
$$|h^{-1}[z_k(t_0 + h) - z_k(t_0)] - h^{-1}[z(t_0 + h) - z(t_0)]|$$

 $\leq \eta/2 + \eta/2 = \eta.$

We conclude that for the chosen value of h, $0 < h \le \delta < \sigma$, and every $k \ge k_1$ we have

$$|m_h - \phi(t_0)| \le \eta$$
, $|m_{hk} - m_h| \le \eta$, $|y_k(t_0) - y(t_0)| \le \varepsilon/2$. (11)

For $0 \le s \le h$ we have now

$$\begin{aligned} |y_k(t_0 + s) - y(t_0)| &\leq |y_k(t_0 + s) - y_k(t_0)| + |y_k(t_0) - y(t_0)| \leq \varepsilon/2 + \varepsilon/2 = \varepsilon, \\ |(t_0 + s) - t_0| &\leq h \leq \delta \leq \varepsilon, \end{aligned}$$

$$f(t_0 + s, y_k(t_0 + s), u_k(t_0 + s)) \in Q(t_0 + a, y_k(t_0 + s)).$$

Hence, by definition of $Q(t_0, y_0, 2\varepsilon)$, also

$$\varphi_k(t_o + s) = f(t_o + s, y_k(t_o + s), u_k(t_o + s)) \in Q(t_o, y_o, 2\epsilon).$$

The second integral relation (10) shows that we have also

$$m_{hk} \in cl co Q(t_0, y_0, 2\epsilon)$$

since the latter is a closed convex set. Finally, by relations (11), we deduce

$$|\varphi(t_0) - m_{hk}| \le |\varphi(t_0) - m_h| + |m_h - m_{hk}| \le 2\eta$$

and hence

$$\phi(t_0) \in [cl co Q(t_0, y_0, 2\epsilon)]_{2n}$$

Here $\eta > 0$ is an arbitrary number, and the set in brackets is closed. Hence

$$\phi(t_0)\epsilon$$
 cl co $Q(t_0,y_0,2\epsilon)$,

and this relation holds for every $\epsilon > 0$. By property (Q) we have

$$\phi(t_0) \in \cap_{\epsilon} \text{ cl co } Q(t_0, y_0, 2\epsilon) = Q(t_0, y_0),$$

where $y_0 = y(t_0)$, and $Q(t_0, y_0) = f(t_0, y_0, U(t_0, y_0))$. This relation implies that there are points $\overline{u} = \overline{u}(t_0) \in U(t_0, y_0)$ such that

$$\varphi(t_O) = f(t_O, y(t_O), \overline{u}(t_O)).$$

This holds for almost all t_0 $\varepsilon[t_1,t_2]$. Hence, there is at least one function $\overline{u}(t)$, defined a.e. in $[t_1,t_2]$ for which relation (9) holds a.e. in $[t_1,t_2]$. We have to prove that there is at least one such function which is measurable. The proof is exactly as the one for closure theorem I, where we write y,y_k instead of x,x_k , and will not be repeated here. Closure theorem II is thereby proved.

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