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Technical Note

ASYMMETRIC PRIME ENDS

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SUMMARY

Each simply connected domain in the plane has at most countably many prime ends whose right and left wings do not coincide. On the other hand, to each countable set E on the unit circle C there corresponds a function which is holomorphic and univalent in the unit disk D and which has the property that it carries each point of E and no point of C E onto a prime end with unequal wings.

1. CLUSTER SETS

Let f denote a function which maps the unit disk D: |z| < 1 onto the Riemann sphere R, and let $e^{i\theta}$ be a fixed point on the unit circle C: |z| = 1. A point w on R belongs to the <u>cluster set</u> $C(f, e^{i\theta})$ of f at $e^{i\theta}$ provided there exists a sequence $\{z_n\} = \{r_n e^{i\theta} n\}$ such that $r_n \nearrow 1$, $\theta_n \to \theta$, $f(z_n) \to w$. It belongs to the <u>radial cluster set</u> $C_\rho(f, e^{i\theta})$ provided the sequence $\{z_n\}$ can be chosen with $\theta_n = \theta$ for all n. It belongs to the <u>right cluster set</u> $C_R(f, e^{i\theta})$ (or to the <u>left cluster set</u> $C_L(f, e^{i\theta})$) provided the sequence $\{z_n\}$ can be chosen with $\theta_n \nearrow \theta$ (or with $\theta_n \nearrow \theta$).

If f is continuous in D, then the set of points $e^{i\theta}$ where $C_{\rho}(f, e^{i\theta})$ does not contain $C(f, e^{i\theta})$ is a set of first category [1]; but even if f is required to be holomorphic and univalent in D, the point set in question may have measure 2π , as can be seen, for example, from the construction described in [4, Section 2]. In other words, the set where the radial cluster set is a proper subset of the complete cluster set is thin topologically but may be large geometrically. The following theorem implies that the point set where the right and left cluster sets do not coincide is subject to much more severe restrictions, even if no conditions whatever are imposed on the function f.

THEOREM 1. If f maps the unit disk into the Riemann sphere, then

$$C_R(f, e^{i\theta}) = C(f, e^{i\theta}) = C_L(f, e^{i\theta})$$

for all except at most countably many points $e^{i\theta}$.

Since the right (left) cluster set of a function contains the set which has been called the right (left) boundary cluster set, Theorem 1 is a corollary of Collingwood's recent theorem [2] to the effect that the right and left boundary cluster sets at $e^{i\theta}$ coincide with $C(f, e^{i\theta})$, except possibly at countably many points $e^{i\theta}$. However, for the sake of completeness and simplicity, we give here a proof which is independent of the concept of boundary cluster sets.

We cover the Riemann sphere R with a succession of nets N_K (k = 1,2,...), each with finitely many (closed) triangular meshes $m_{Kn}(n = 1, 2, ..., n_K)$ of diameter less than 1/k. By means of any convenient ordering, we arrange all the meshes m_{Kn} into a sequence $\{m_j\}$. For each index j, we consider the set S_j of those points $e^{i\theta}$ for which the mesh m_j contains a point of $C(f, e^{i\theta})$ but does not meet the set $C_R(f, e^{i\theta})$. Clearly, the set S_R of points $e^{i\theta}$ for which $C(f, e^{i\theta}) \sim C_R(f, e^{i\theta})$ is not empty is the union of the sets S_j .

If $e^{i\theta} \in S_j$, then $e^{i\theta}$ is the endpoint of an arc $I(\theta) = (e^{i\phi}, e^{i\theta})(\phi < \theta)$ such that $C(f, e^{i\psi})$ does not meet the mesh m_j if $e^{i\psi}$ lies on $I(\theta)$; for otherwise m_j would meet the set $C_R(f, e^{i\theta})$, contrary to the hypothesis that $e^{i\theta} \in S_j$. Since the arc $I(\theta)$ cannot contain points of S_j , the set S_j , is at most countable, and therefore S_R is at most countable. Likewise, the corresponding set S_L is at most countable, and the theorem is proved.

2. ASYMMETRIC PRIME ENDS

Let the function f be holomorphic and univalent in the unit disk D, and let B denote the image of D under f. If P is the prime end of B that corresponds to the point $e^{i\theta}$, the two cluster sets $C_R(f, e^{i\theta})$ and $C_L(f, e^{i\theta})$ coincide with

what Ursell and Young [6, p. 14] have called the <u>right</u> and <u>left</u> <u>wings</u> of P. We shall say that the prime end P is <u>asymmetric</u> if its two wings are not identical. The following theorem is an immediate consequence of Theorem 1.

THEOREM 2. Each simply connected plane domain has at most countably many asymmetric prime ends.

In order to formulate our next theorem, we partition the set of asymmetric prime ends of a fixed simply connected domain into three classes U_R , U_L , and U_{RL} , as follows: a prime end belongs to U_R if its left wing is a proper subset of its right wing, to U_L if its right wing is a proper subset of its left wing, and to U_{RL} if neither of its wings is a subset of the other.

THEOREM 3. Let E_R, E_L, and E_{RL} be three disjoint sets on the unit circle

C, each at most countable. Then there exists a function f which maps the unit

disk conformally onto a domain B in such a way that each point in E_R, E_L, or

E_{RL} corresponds to a prime end in U_R, U_L, or U_{RL}, respectively, while all other

points of C correspond to symmetric prime ends of B.

To prove Theorem 3, we order the points of $E_RUE_LUE_{RL}$ into a sequence $\{z_j\}$ (j = 1, 2,...). With each point z_j we associate a sequence of points z_{jp} lying on C and converging to z_j . We construct a function of the form

$$f(z) = z + \sum_{j,p} A_{jp} \{1 - (1 - z/\rho_{jp}z_{jp})^{k_{jp}}\},$$

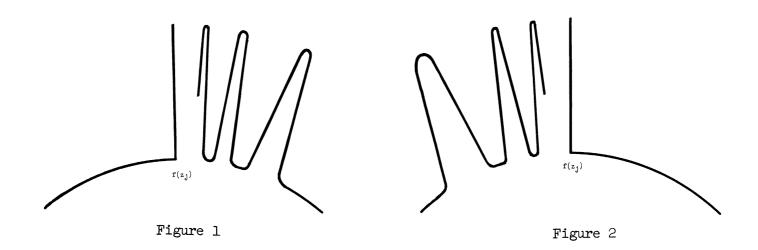
where the A_{jp} are appropriate complex constants, $k_{jp} \searrow 0$ and $\rho_{jp} \searrow 1$ as $p \rightarrow \infty$, and where the symbol in braces represents that branch of the corresponding function which takes the value 0 at z=0.

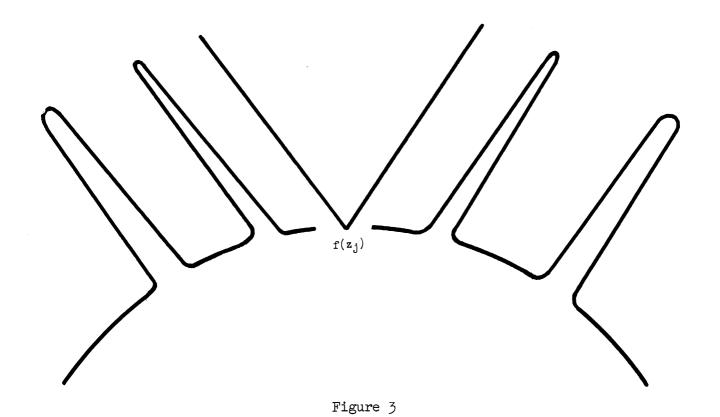
The constants that determine the function f can be chosen in such a way that f is holomorphic and univalent in D, such that the radial limit $f(e^{i\theta})$ of f exists, for each value θ , and such that the boundary of the image of D, in the neighborhood of a point $f(z_j)$, appears roughly as in Figure 1, 2, or 3, according as z_j belongs to E_R , E_L , or E_{RL} . We say "roughly" because each of the tooth-like extensions of the domain B may carry further extensions (indeed, the deformations may be everywhere dense on the boundary; difficulties that might arise from unwanted condensations of singularities can be avoided by subjecting the constants A_{jp} to the restriction $|A_{jp}| \leq 1/j!$, in other words, by requiring that the teeth associated with the point z_j have length at most 1/j!. The details of the proof are similar to the details in [3, Sections 3 and 4], and we omit them.

Theorem 3 makes no mention of Carathéodory's four kinds of prime ends.

Our construction leads to a domain whose asymmetric prime ends are of the second whose symmetric prime ends are of the first kind. No matter what construction is used, the asymmetric prime ends must be of the second or fourth kind, since the prime ends of the first and third kinds have no subsidary points. The following theorem shows that no other topological restriction on the distribution of the asymmetric prime ends exists.

THEOREM 4. Let $C = E_1 \cup E_2 \cup E_3 \cup E_4$ be a decomposition of the unit circle such that some homeomorphic mapping of the unit disk onto a simply connected domain B induces a homeomorphism ϕ of the sets E_1 , E_2 , E_3 , E_4 onto the sets of prime ends of the first, second, third, and fourth kind, respectively, of B. Let S_R , S_L , and S_{RL} be disjoint countable subsets of $E_2 \cup E_4$. Then the domain



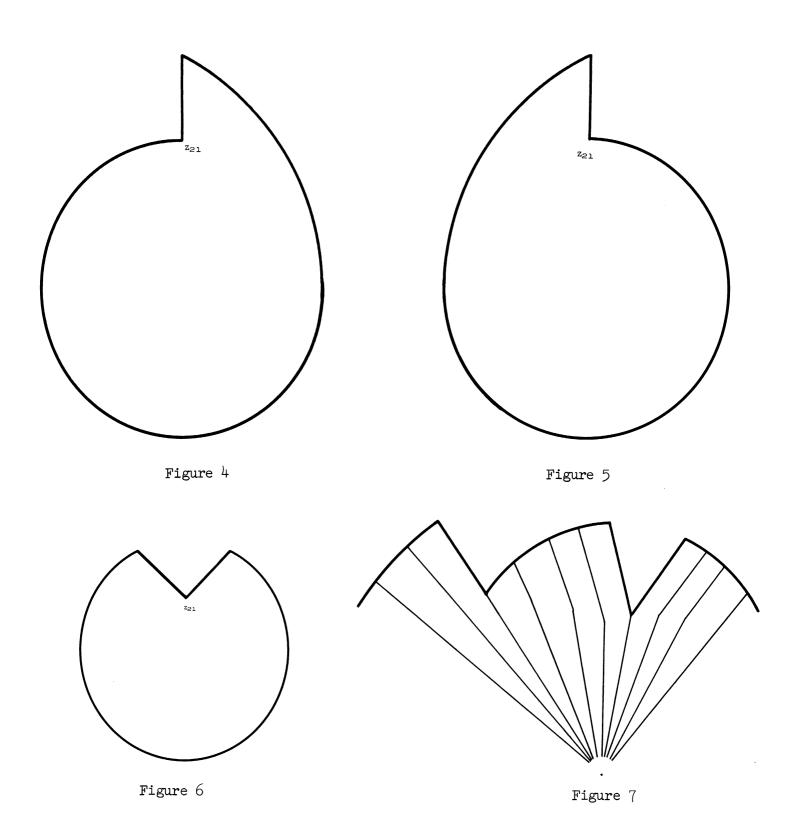


B can be chosen in such a way that S_R , S_L , and S_{RL} correspond to the sets U_R , U_L , and U_{RL} , respectively, under the homeomorphism ϕ .

A detailed proof of Theorem 4 would be tedious, and we give only a brief sketch to show how the construction in Sections 3 to 8 of [5] can be modified so as to yield the desired result.

In [5], the set E_{234} of points corresponding to prime ends of the second, third, or fourth kind is represented as the union of a sequence of disjoint sets $E_{234.i}$ (i = 1, 2, ...). The set $E_{234.1}$ is open, and each of the sets $E_{234.i}$ (i = 2, 3, ...) is closed and nowhere dense. The unit disk is subjected to certain deformations determined by the set $E_{234.2}$; the process is repeated (on a successively smaller scale) with reference to $E_{234.i}$ (i = 3, 4, ...). Thereafter, a special program of further deformations is launched with reference to $E_{234.1}$.

For our present purpose, we denote by $S_{R.i}$, $S_{L.i}$, and $S_{RL.i}$ the intersections of S_R , S_L , and S_{RL} with $E_{234.i}$. First we order the set $S_{R.2} \cup S_{L.2} \cup S_{RL.2}$ into a finite or infinite sequence $\{z_{2j}\}$. In the neighborhood of z_{21} , we deform the boundary of the unit disk in the manner indicated by Figures 4, 5, or 6, according as z_{21} belongs to S_R , S_L , or S_{RL} , and we map the set $C \setminus z_{21}$ onto the curved portion of the deformed boundary. We proceed similarly (but on smaller scales) with regard to z_{22} , z_{23} , The unit disk is then mapped onto the star-domain which has been obtained, in such a way that the radii of D are deformed as is indicated in Figure 7. Clearly, the transformation can be constructed in such a way that it is continuous throughout the disk |z| < 3/4 and on every radius of D that does not terminate at one of the points z_{2j} . The



transformed unit disk is then further deformed according to the program in Sections 5 and 6 of [5].

The analogous deformations which have to be carried out with reference to the sets $\mathbb{E}_{234.i}$ (i = 3, 4, ...) are obvious (see Section 7 of [5]).

The deformations of the disk D that are used in [5] for the sake of the set $E_{234.1}$ are somewhat more complicated, because $E_{234.1}$ consists of interior points. However, the intersection of $E_2 \cup E_4$ with $E_{234.1}$ is partitioned into sets that are nowhere dense, and each of these is treated separately. Therefore we can proceed as above, provided we exercise one precaution: In the third and fourth paragraphs of Section 8 of [5], a certain denumerable set and a certain near-perfect set are extracted from $E_2 \cap E_{234.1}$ and used for special purposes. These special purposes would interfere with our technique of creating asymmetric prime ends at the points of the extracted sets, and therefore the extracted sets must be selected in such a way that they contain no points of S_R , S_L , or S_{RL} . Since E_2 is locally uncountable in $E_{234.1}$, the latter requirement presents no special difficulty.

This sketch must suffice, because any exposition which covered all details would have to include the laborious description in [5]; and it is easier for the reader to acquaint himself first with the description in [5], and to supply thereafter the modifications which we have now sketched, than it would be to struggle through a detailed description in which the various operations are presented simultaneously.

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