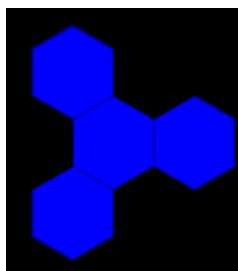


Spatial Synthesis: Volume I, Centrality and Hierarchy. Book 1.

Sandra Lach Arlinghaus and William C. Arlinghaus
University of Michigan and Lawrence Technological University

[Institute of Mathematical Geography](#), Ann Arbor, 2005

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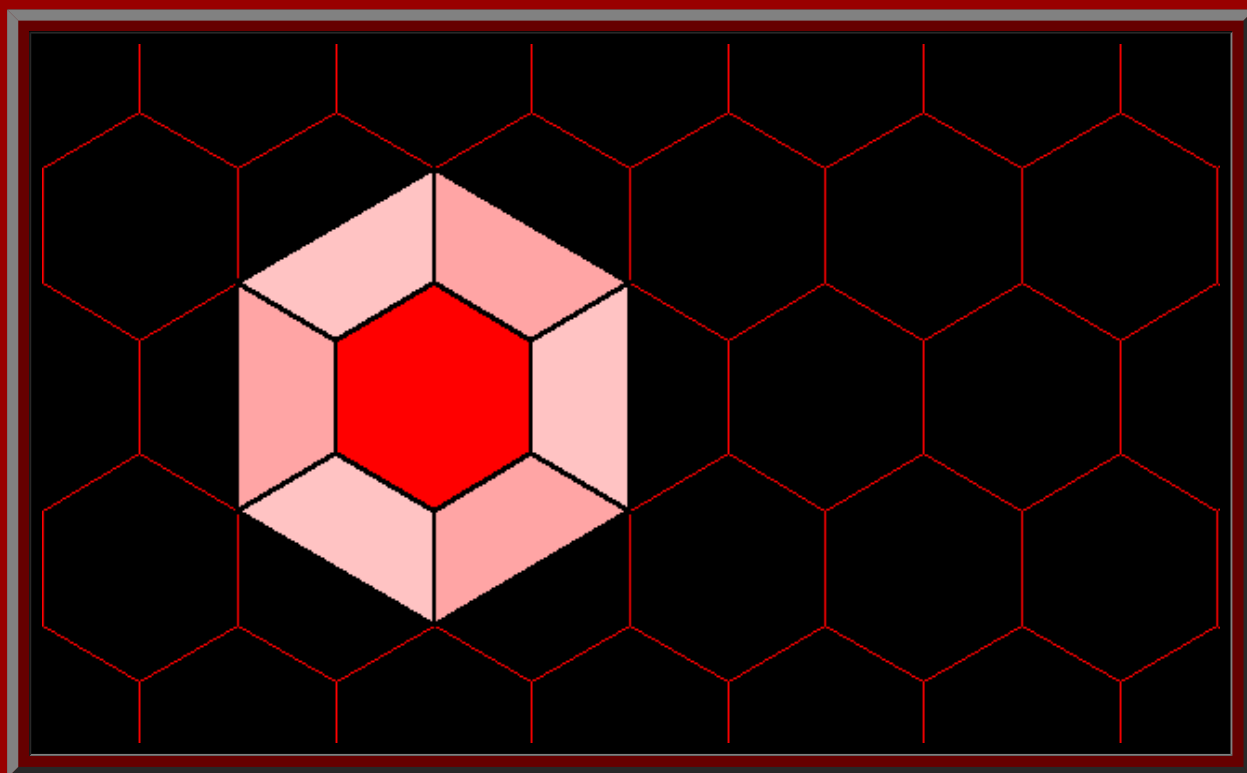
Spatial Synthesis: An eBook Series

[Sandra Lach Arlinghaus](#) and [William Charles Arlinghaus](#)

Volume I: Centrality and Hierarchy

Book 1: Regular Lattices, Geometry, and Number Theory.

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[Download Cosmo Player \(free\) Browser Plug-in for interactive virtual reality.](#)
[Link](#) showing more detail on how to use Cosmo Player.

Possible Future Volumes

Proposed topics for future volumes of Spatial Synthesis, as invited in

Solstice: An Electronic Journal of Geography and Mathematics,

Volume XIII, Number 2, Winter 2002

(<http://www.InstituteOfMathematicalGeography.org>).

Volume I; Centrality and Hierarchy (Books 2, 3, )

Volume II: Distance and Geodesic

Volume III: Adjacency and Connection

Volume IV: Minimax, Absolute/relative, and Density

Volume V: Scale, Orientation, and Dimension
Volume VI: Partition, Separation, and Diffusion
Volume VII: Transformation and Symmetry

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Spatial Synthesis: Centrality and Hierarchy, Volume I, Book 1.
Sandra Lach Arlinghaus and William Charles Arlinghaus

ABOUT THE AUTHORS

(See their linked websites for more information.)

Sandra Lach Arlinghaus

- Ph.D. Theoretical Geography
- Pirelli INTERNETional Award Semi-Finalist (top 80) for submission in 2004, based on part of this book (appearing in *Solstice*).
- Pirelli INTERNETional Award Finalist (top 20 in the world of over 1200 invited entries), 2002 competition, for previous e-book, *Graph Theory and Geography: An Interactive View eBook*, John Wiley and Sons, 2002.
- Pirelli INTERNETional Award SemiFinalist (top 80 in the world of over 1000 invited entries), 2001 competition, for *Solstice: An Electronic Journal of Geography and Mathematics*, Institute of Mathematical Geography, <http://www.InstituteOfMathematicalGeography.org> .
- Numerous publications, both classical and electronic, in a variety of disciplines (some are included in the attached e-Library).
- Biography appears in numerous Marquis publications, including *Who's Who in America* and *Who's Who in the World*.

William C. Arlinghaus

- Ph.D. Mathematics, Algebraic Graph Theory (book based on dissertation appears in the *Memoirs* Series of the American Mathematical Society)
- Pirelli INTERNETional Award Semi-Finalist (top 80) for submission in 2004, based on part of this book (appearing in *Solstice*).
- Pirelli INTERNETional Award Finalist (top 20) for previous e-book, *Graph Theory and Geography: An Interactive View eBook*, John Wiley and Sons, 2002.
- A variety of publications, mostly in graph theory.
- Biography appears in various biographical publications, including the ACBL *Encyclopedia of Bridge* and Marquis's *Who's Who in the Midwest*.

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Spatial Synthesis: Centrality and Hierarchy, Volume I, Book 1.
Sandra Lach Arlinghaus and William Charles Arlinghaus

Acknowledgments

We live in exciting times and one of the reasons they are exciting is the great electronic resource called the Internet. It opens up remarkable possibilities involving "publication" in the broadest sense of the word: dissemination of information in creative, interesting, and even interactive ways. We have been exploring a few of the dimensions it has to offer in previous works and continue in this one, emphasizing the role of virtual reality in mathematical models. The Institute of Mathematical Geography (IMaGe) has been a leader in these efforts since 1985. Over the past 20 years, there have been more changes than we might ever have foreseen. The IMaGe website archives those efforts. Here, we note simply one previous work in a similar vein: a work by these two authors co-authored with the late Frank Harary. That work was entitled *Graph Theory and Geography: An Interactive View eBook*, published by John Wiley and Sons (Wiley-Interscience Series in Optimization and Discrete Mathematics) in April of 2003 as their first eBook publication. Professor Emeritus, Mitchell J. Rycus, Taubman College of Architecture and Urban Planning, The University of Michigan (Ann Arbor) notes of that one in a request for review sent by Wiley,

"I've had a chance to look at the Arlinghaus et al. book and I think it's just great! It is what an eBook is supposed to be--interactive, animated, easy to read and easily accessible, and of course, the context has to be as well written and as authoritative as any printed text. *Graph Theory [and Geography]* does indeed have all these elements, and more since it is both a math and geography text in one document. What a treat to have the opportunity to review it and (I hope) to keep it for reference for my work."

The current work draws partially from the success of the Wiley eBook as well as from the continuing experience with IMaGe and its electronic journal, *Solstice: An Electronic Journal of Geography and Mathematics* (founded, 1990). Articles appeared in *Solstice* as a means of testing book content. The comments below relate to these tests.

- Rycus:
"Wow! That was a good run--top 20 of *Pirelli* is certainly an honored position. I took a peek at your new work and it should have a better chance with the virtual machine and all. You guys are great!"
- Waldo Tobler, Professor Emeritus, Department of Geography, University of California, Santa Barbara, June 20, 2004.
"Sandra, This is a very impressive issue. I look forward to your and Bill's forthcoming book."
- Steve Quigley, Executive Editor, John Wiley and Sons, November 5, 2004.
"Sandra, ... you are the most forward thinking person about electronic delivery that I personally know. ... "

We hope that all readers of this document, and of those derivative ones to come, will also enjoy them and learn from them. This document would not have been possible without the kind help and wise counsel of numerous individuals. Klaus-Peter Beier, Adjunct Associate Professor of Engineering and Director of the 3D Laboratory of the Duderstadt Center, The University of Michigan, offered a marvelous course in Virtual Reality (Engineering 477) in which the first author had the privilege to participate in the Fall of 2003 and 2004. She was thus able, through Professor Beier's patience and fine lectures, to add virtual reality scenes to this book. The Graduate Student Instructors in the course offered clear instruction to help her to work through the laboratory exercises: Thana Chirapiwat (who had earlier been a student of hers in a GIS course), Bonnie Congxi Bao, and Jamie Cope. The staff of the 3D Laboratory of the Duderstadt Center was also of great help: Lars Schumann, Steffen Heise, Brett Lyons, Eric Maslowski, and Scott Hamm.

They also thank Merle Johnson of the City of Ann Arbor ITS Department and Chandra Hurd Gochanour of

the City of Ann Arbor Planning Department: the former for his generosity in sharing aerials and maps from City of Ann Arbor files and the latter for sharing her expertise in analyzing city data and in checking selected files related to material on this site. Donald T. Uchman, Coordinator of Space Graphics, Space Information and Planning, Plant Extension--AEC, The University of Michigan, kindly shared official University map files on locations and sizes of buildings.

This work has been in progress for over 15 years and is an ongoing venture. Numerous colleagues have been helpful, often in ways that might be considered indirect, but generally which feed into an important infrastructure in understanding on which we build our work. At the risk of missing some, we thank particularly, Frank Harary (1921-2005), John D. Nystuen, Kenneth H. Rosen, Matthew Naud, Steve Quigley, Susanne Steitz, Penelope Kaiserlian, Sylvia Hecimovich, Douglas Kelbaugh, Fred Beal, Susan Pollay, Karen Hart, Paul Mohai, Mitchell J. Rycus, Waldo R. Tobler, Michael Batty, Michael J. Woldenberg, John F. Kolars, Marvin Mikesell, Chauncy D. Harris (1914-2003), and Marco Farinelli.

The authors wish to thank members of their respective university communities who were supportive, in various ways, of this project. S. Arlinghaus thanks the Dean of the School of Natural Resources and Environment of The University of Michigan, Rosina Bierbaum, for her consistent appointment of this author to her annual post. This author hopes that a strong win-win situation is created when scholars publish materials in association with such appointments. W. Arlinghaus wrote the chapters on elementary number theory and on binary quadratic forms while on a semester sabbatical from the Mathematics Department at Lawrence Technological University. He thanks those who made that sabbatical possible, particularly his Department Chair, David Bindschadler. Also, both authors wish to thank Donald F. Lach (1917-2000), Bernadotte E. Schmitt Professor of History, University of Chicago, and the staff of the Joseph Regenstein Library of the University of Chicago who helped procure German maps and texts from 1941.

Errors that remain are, of course, ours alone.

Sandra Lach Arlinghaus
William Charles Arlinghaus

Ann Arbor, Michigan
June 21, 2005.

Software used in the course of making this book was made by the following firms:

- Environmental Systems Research Institute, ArcView and ArcGIS software
- MacroMedia, Dreamweaver, MX.
- Adobe, Photoshop and ImageReady, 7.0.
- Sun Microsystems
- Microsoft
- Alta 4 (Germany), ImageMapper
- Discreet, 3D Studio Max
- Animal Movement (Alaska Biological Station)

Hardware used centered on the equipment in the "Usability Lab" of the Duderstadt Center (with two flat screen monitors working together for a wide view) and on a Hewlett-Packard Pavilion f1903, with an Intel Pentium 4 Processor, 512 MB PC3200 DDR SDRAM memory, Intel Graphics Media Accelerator, 200GB hard drive and a 19 inch flat screen monitor set to highest resolution.

Acknowledgment

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Spatial Synthesis: Centrality and Hierarchy, Volume I, Book 1.
Sandra Lach Arlinghaus and William Charles Arlinghaus

Dedication

To our Parents

Alma S. Lach
and to the memory of
Donald F. Lach

To the memories of:
Francis A. Arlinghaus
Blanche S. Arlinghaus

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Spatial Synthesis: Centrality and Hierarchy, Volume I, Book 1.
Sandra Lach Arlinghaus and William Charles Arlinghaus

Kioskland: A Strategy for Linking Hierarchical Levels of Virtual Reality Maps*

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Adjunct Professor of Mathematical Geography and Population-Environment Dynamics
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The University of Michigan

with input from**:
Klaus-Peter Beier, Matthew Naud, John D. Nystuen
Taejung Kwon, Adrien Lazzaro, Paul Oppenheim, Aaron Rosenbaum (Fall 2003)
Nikolai Nolan, Rasika Ramesh, Itzhak Shani (Fall 2004)

Technical note:

The images linked to this article require the reader to install Cosmo Player or Cortona or another browser plug-in designed for viewing Virtual Reality files on the internet.

Use a recent version of Internet Explorer as the browser (or an early version of Netscape, series 4.7x) or other browser that supports virtual reality.

These images are also best viewed on a current computer with at least 512 MB of RAM (more is better!) with the screen resolution set as high as possible.

The electronic pages of this journal have, for the past few years, contained numerous examples of virtual reality maps: from planning for extra residential units in downtown [Ann Arbor](#) to tracking rugged voyages of [Lewis and Clark](#). Many maps cover large areas of terrain; they are global in scale. Virtual reality, however, often is best executed in the small, at a local scale (Beier (lectures in [Engineering 477](#), The University of Michigan), [Crispen](#)). The virtual maps tend to become large in file size quickly, causing the maps not to load properly. One problem is that software that easily creates virtual maps may not also optimize file size. That persistent problem of the virtual modeler can be partially addressed by importing Virtual Reality Modeling Language (vrmf) files exported from Geographic Information System software (GIS software) into a software package that executes polygon reduction of the vrmf code. Beyond such reduction, however, there remains the geographer's dilemma of scale transformation and a need to map both globally and locally. A [classical](#) way to execute such transformation is to arrange the spatial information in layers of a nested hierarchy and use a well-defined transformation to move from one level of that hierarchy to another. In the case of virtual reality maps (VR-maps), one puts individual maps in separate layers, separating maps before they become too heavy to run smoothly, or adequately, on current computing equipment (the creator, of course, needs to decide the target audience and the computing environment in which its members are likely to function).

Earlier work on creating a 3D Atlas of Ann Arbor has produced thousands of separate virtual maps of the downtown ([inventory](#) of previous work; click on the "Archive" button). Some are maps that show the current stock of buildings. Others are maps that suggest future buildout scenarios based on concepts provided by leading architectural and construction experts. The images below show screen capture of separate virtual reality models. The image on this offers a simple solution to link the different hyperlinked images, using kiosks that transform the user, via the internet, from one hierarchical level to another.

File Navigation Notes

- Click [here](#) to download a copy of Cosmo Player to use as a plug-in for your browser in order to view virtual reality files.
- The screen captures of virtual reality models in this article are taken from browsers with Cosmo Player installed.
- View the virtual reality models in your browser:
 - To use pre-defined viewpoints, and have controlled navigation of the model, pull down the "[viewpoints](#)" menu in the lower lefthand corner.
 - When using the driving controls to navigate the model freely, adjust driving speed using the "[preferences](#)" menu in the lower righthand corner.
- Other plug-ins for viewing virtual reality files in browsers are available for free download. Cortona is one such option. Go to Google, Yahoo, or other to search for them if the links on the page for Cosmo Player, above, fail to work.

This [linked](#) image shows a screen capture of an associated [virtual reality](#) model of downtown Ann Arbor with buildings represented as simple boxes extruded from digitized building footprints. Over several years, such images, of both actual and projected cityscape, served as one set of basic materials for planning efforts for city officials involved in various aspects of municipal planning. Visualizing alternative outcomes associated with different zoning types and land use patterns was helpful in understanding how decisions might be reached. Maps and decisions often go hand in hand.

These maps and box-models were useful in a general way: for looking at patterns of vacant land, possible infill sites, general skyline resulting from proposed infill, relation of topography to the built environment, and as a general inventory of the existing downtown scene by building height, zoning type, and special designation (such as historic district or floodplain designation or State-owned property, as are University of Michigan buildings). Many buildings, however, are not boxes, and all buildings have texture. In the municipal arena of

professional planning, supplementary architectural drawings and models are therefore critical (until the day arrives that virtual models are easy and inexpensive to make at all levels of detail). Thus, one wishes for virtual maps that show more detail: not only for planning purposes but for others as well. An important other use centers on **emergency response**: of **firefighters** (using virtual training of firefighters in their downtime in the firehouse, for example), of **police officers**, of **environmental management personnel**, and of a whole host of **first responders** ([link](#) to the 3D Laboratory, Duderstadt Center, The University of Michigan).

The introduction of photographic textures on files causes rapid enlargement of file size. The map in this [linked](#) image shows a screen capture of one view of a **virtual reality** file in which textures have been applied to a number of buildings in the downtown area. The file is about at the limit of what a typical desktop modern machine running 512 MB of RAM can run in a reasonable (not optimal) time (anywhere from 1 to 5 minutes to load the model depending on various local conditions such as amount of free hard drive space, fragmentation of the hard drive, internet connection speed, age of machine, and so forth). In this file, there are textures only on selected buildings. There are no street or sidewalk textures and there is no street "furniture" nor are there any other related accessories such as traffic lights, lane markers, or cars.

The extra detail that comes at high cost in terms of file size is quite attractive for many applications. Another way to introduce extra detail is to put links on the virtual buildings. Thus, in the last [linked](#) virtual reality model, one can click on selected buildings to look inside: not at an image of the interior but to internet links to the interior via a firm's own webpage and so forth. Try **219 S. Main Street**: look at the bottom of Cosmo Player to see building addresses as the mouse is moved across virtual buildings with active links to html pages. The corresponding html page that comes up when the building is clicked on in the virtual reality model is [linked](#) here. The background color of the html page is significant. All buildings in the same physical, four-sided, block have the same color background. Buildings in adjacent blocks (with adjacency defined as being "across the street from") have a different color.*** When environmental managers choose to insert, in the html pages, detail about environmental hazards known to be in particular buildings (for private municipal use only), then this model provides even more information valued by these managers, and other first responders, in times of disaster. One advantage to this approach using html files linked to virtual buildings is the small file size of the linked web page; another is that no special knowledge, beyond simple html, is required to maintain the model.

Finally, one may wish to introduce even more detail with street textures, benches, trees, and so forth. All of this detail quickly increases file size. Over the course of two years, student groups worked for three months to produce more detailed files. In the Fall of 2003, in Professor Klaus-Peter Beier's Engineering 477 course (The University of Michigan), with Faculty Advisors Arlinghaus, Naud, and Nystuen, students Kwon, Lazzaro, Oppenheim, and Rosenblum produced a detailed model of the intersection of Main and Liberty Streets that Beier edited substantially (look both at the [screen capture](#) and at the [virtual reality](#) model). In the Fall of 2004, again in Engineering 477, students Nolan, Ramesh, and Shani, produced a detailed model of Main and Huron Streets that Beier edited substantially (look both at the [screen capture](#) and at the [virtual reality](#) model). Both of these models were edited by the author in terms of cleaning of photographic images (removing the foreground where it remained), adjusting building shape and height to be correct and to be compatible with materials from the City of Ann Arbor and The University of Michigan, and adjusting building location so that the detailed models would fit correctly and seamlessly with the City of Ann Arbor files and with The University of Michigan files. These adjustments involved the use of ArcView GIS software from ESRI, Adobe PhotoShop, Windows notepad as a vrmf editor, and 3D Studio Max from Discreet. The adjustments were executed in the Usability Lab of the Duderstadt Center of The University of Michigan using computing equipment configured with a double flat-screen monitor for wide-angle viewing, and also on a home desktop with a large single flat screen monitor.

While each model has its own uses, an obvious desire is to be able to move from one to another without returning to a page and links: to move directly from one level of the hierarchy to another and stay within the virtual world. One way to execute such movement is to insert markers, "kiosks," in files to link from one level to another. Each virtual kiosk has an internet link on it: the virtual kiosk serves as a center of information based on the virtual matter of the internet much as its real-world kiosk counterpart serves as a center of information based on printed matter. Thus, the virtual kiosks, when loaded with correct information regarding Uniform Resource Locators (URLs), serve as well-defined transformations from one hierarchical level of virtual map to another. The table below shows how to use this single file. The rows represent layers in a hierarchy: moving across the rows is a lateral move within the same hierarchy or virtual image. The columns represent movement from one virtual image to another; in this case, using kiosks loaded with appropriate URLs to execute that movement.

Enter the Virtual World [here](#)

The links to images below show the path through that World

Entry to file.
The viewpoints menu suggests the lateral move (blue highlight).

[Image](#)

The direct link to this world is given in the table heading, above.

Lateral move to kiosk, at Main and Liberty, to next level. Click on the kiosk, in the virtual reality file, to go to next image, below.

[Image](#)

	<p>More detailed view of scene at Main and Liberty. Note the kiosk in the street. Click on it, in the virtual reality file, to go to the next image below, showing even more detail of a region more local than that shown here.</p> <p>Image Panorama Direct link to this world</p>	<p>The viewpoints menu suggests the lateral move (blue highlight).</p> <p>Image</p> <p>In the various views at this hierarchical level, the streets outlined in white lie within the Downtown Development Authority (DDA); those outlined in yellow do not.</p>	<p>More detailed view of scene at Main and Huron. Note the kiosk in the street. Click on it, in the virtual reality file, to go to the next image below, showing even more detail of a region more local than that shown here.</p> <p>Image Panorama</p>
	<p>Most detailed view of Main and Liberty; note the variety of viewpoints available. Try them. Click on the "artifacts" switch to see trees and other detail.</p> <p>Image Panorama: entry Image Panorama: intersection Direct link to this world</p>		<p>Most detailed view of Main and Huron; note the variety of viewpoints available. Try them.</p> <p>Image Panorama Direct link to this world</p>

Follow the path suggested in the table above to become familiar with navigation through the various layers of the model. Use viewpoints or drive freely within layers. One entry point to the virtual world offers access to a wide range of virtual files. An important aspect of such transformation is thus that one can have many files together in a single file no heavier to view than the single heaviest layer of the hierarchy. It would not have been possible, using merging techniques or some such equivalent strategy, to create the entire set as a single file. When kiosks (or some conceptually equivalent mechanism for jumping between hierarchical levels) are employed, it is easy to imagine emergency managers training first responders to fly through a small file of the entire city with chunky buildings in order to learn the general city layout. When each street corner or other strategic location in this general model is marked with a kiosk then with one click of the kiosk a detailed model pops up, while additional clicks on individual buildings in this detailed view reveal the interiors of buildings as html files. This sort of arrangement has been created for the City of Ann Arbor (and given to them). Creation of the model has taken several years and involved the use of a wide variety of resources, both human and digital. Maintenance, however, can be achieved using a simple text editor to alter the underlying code in either the html files or in the vrm files (part of the code for one building is [attached](#)). Thus, highly computer-literate City employees, armed with digital cameras and good computing resources can maintain the model and insert changes and additions to suit a variety of needs and interests: the process is in place. The arrangement of spatial information in a hierarchy is an efficient arrangement not only in the classical worlds of pen and paper but also in the contemporary world of digital models as well as in the practical implementation of such hierarchical arrangements in the real world.

*

The author thanks Merle Johnson of the City of Ann Arbor ITS Department and Chandra Hurd of the City of Ann Arbor Planning Department: the former for his generosity in sharing aeriels and maps from City of Ann Arbor files and the latter for sharing her expertise in analyzing city data and in checking selected files related to material on this site. She also thanks Donald T. Uchman, Coordinator of Space Graphics, Space Information and Planning, Plant Extension--AEC, The University of Michigan, for his willingness to share official University map files on locations and sizes of buildings.

Prof. Klaus-Peter Beier, Ph.D., Director of the 3D Laboratory of the Duderstadt Center of The University of Michigan has offered extraordinary insight and support on various phases of this project. The author is indebted to his graciousness in sharing computing as well as intellectual resources. She is also extremely appreciative of the assistance and wise advice from staff members in the 3D Laboratory of the Duderstadt Center, Scott Hamm, Steffan Heise, Brett Lyons, Eric Maslowski, and Lars Schumann, and also to Graduate Student Instructors in Engineering 477, Thana Chirapiwat, Jamie Cope, and Bonnie Congxi Bao.

The name "Kioskland" derives from a paper by that name by the author (1976, Department of Geography, The University of Michigan, unpublished).

** Matthew Naud, M. S. and M. P. P., is Environmental Coordinator for the City of Ann Arbor and a principal member of the Emergency Management team. John D. Nystuen, Ph.D. is Professor Emeritus of Geography and Urban Planning, The University of Michigan.

In the Fall of 2003, Taejung Kwon was a Ph.D. Candidate in the Taubman College of Architecture and Urban Planning, The University of Michigan, Adrien Lazzaro was a Master's degree Candidate in the School of Information, The University of Michigan, and Paul Oppenheim and Aaron Rosenbaum were undergraduates (Seniors) majoring

in computer science.

In the Fall of 2004, Nikolai Nolan was an undergraduate majoring in General Studies, Rasika Ramesh was a beginning graduate student in the School of Information, and Itzhak Shani was an undergraduate (Senior) majoring in Engineering.

***[The Four Color Theorem](#) is used in color assignment; thus, in a grid street pattern, two colors are both necessary and sufficient to distinguish all blocks (animated Four Color map [link](#)). No more than four colors are ever required (viewing the block geometry as part of a plane or a sphere). Thus, background color of the linked html page also gives subtle information as to location.

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Volume XVI, Number 1.

<http://www.InstituteOfMathematicalGeography.org/>

Introduction

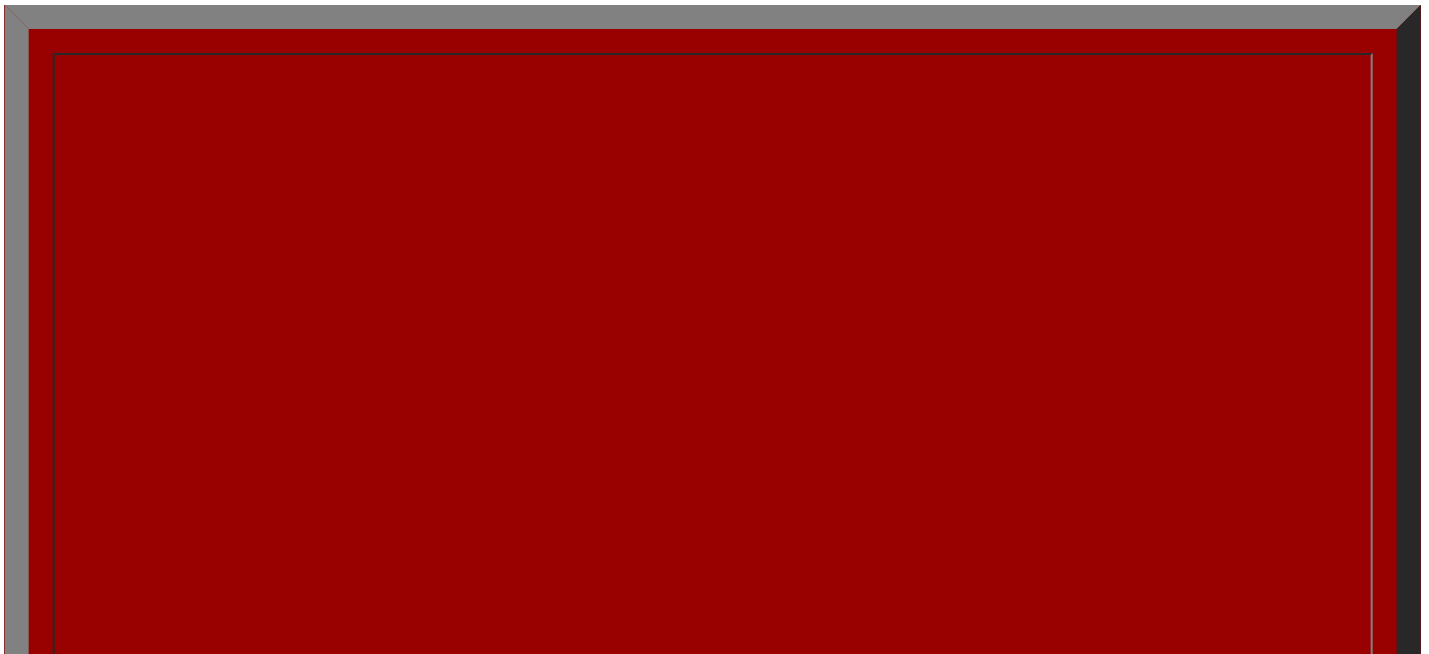
The brain is wider than the sky,

*For put them side by side;
The one the other will include,
With ease, and You beside.*

Emily Dickinson

Synthesis begins with a global view and dissects that view to consider individual components, as they contribute to that whole: the whole is often more than the sum of the individual parts considered. In contrast, analysis often begins with a sequence of local views and assembles a global view from these, as a sum of parts: the assembled view may or may not fit "reality." These two different approaches to scholarship yield different results and employ different tools. In this work, we take a synthetic approach to looking at real world issues that have mathematics as a critical, but often unseen, component. This approach permits one, also, to learn the associated mathematics as it naturally unfolds in real world settings, often in a relatively "painless" manner. The reader learns mathematics required to consider the broad problem at hand, rather than learning mathematics according to the determination of a (perhaps) artificial curriculum. The underlying philosophy is different, as is the format. The eBook is required, however, given the interactive and animated features that enliven the book and motivate the reader to explore diverse realms in the worlds of geography and mathematics and in their interface.

Figure 0.1 offers an abstract view of the idea of "spatial synthesis." Each large hexagon represents a single scholarly discipline: mathematics on the left and geography on the right (as an example). A single field (geometry, for example) is identified (deep red trapezoid) from one the broad discipline of mathematics, and is aligned with a counterpart (deep red trapezoid) field (cartography) from the other broad discipline of geography. Despite the alignment of appropriate entities, a gap remains. In institutional settings reliant on predetermined disciplinary boundaries, interdisciplinary research often founders in this gap for lack of support of various kinds. What is required, therefore, is to seal the gap and to unify aligned, related structure (represented as a single deep red hexagon formed from two trapezoids in Figure 0.1).



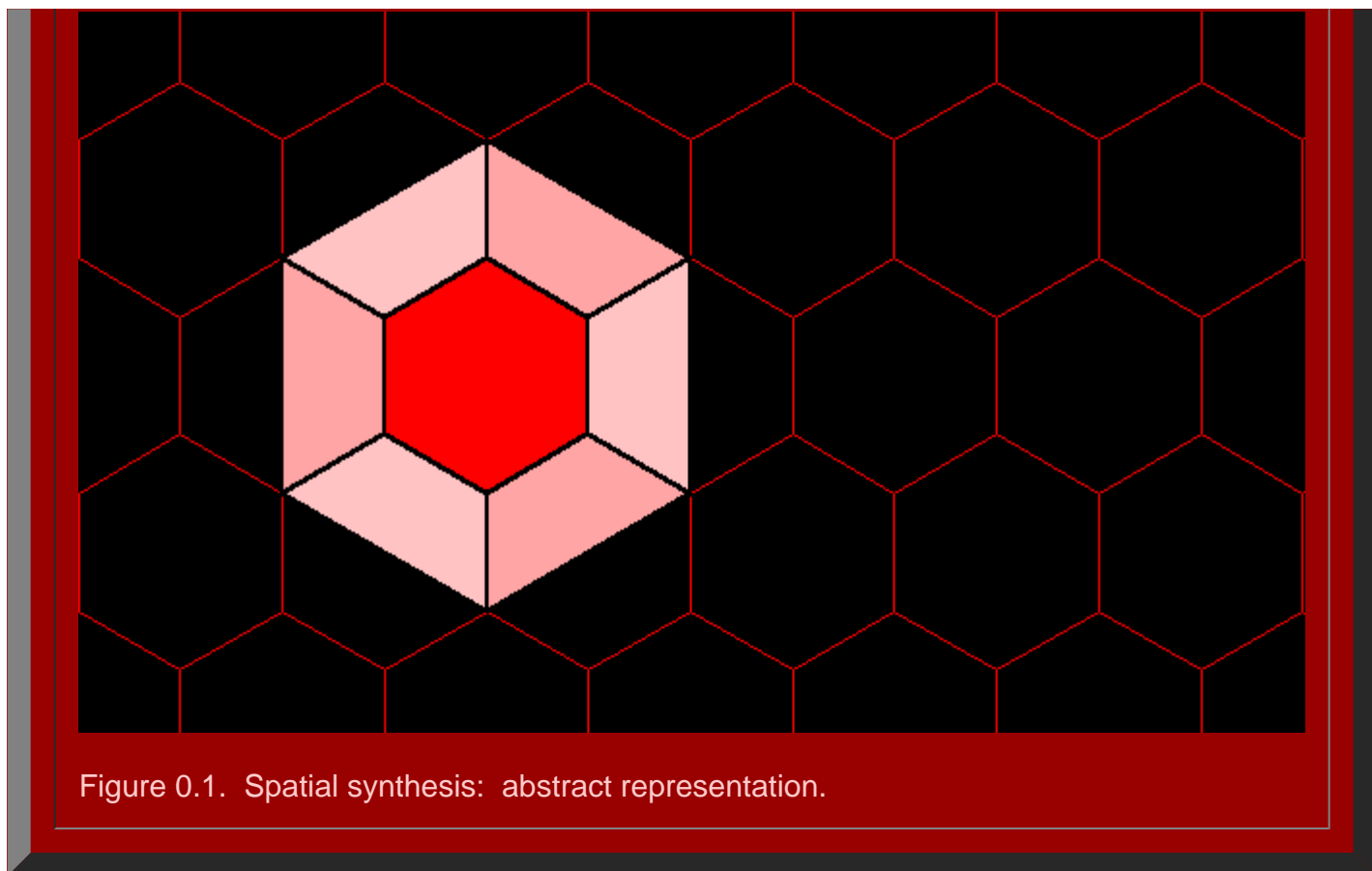


Figure 0.1. Spatial synthesis: abstract representation.

One well known classical approach to this style of scholarship appears in the work of Eratosthenes of Alexandria (c. 276-194 B.C.). Eratosthenes made critical discoveries in both mathematics and geography that might seem unrelated. His [prime number sieve](#) (see Chapter 3 of this work for more detail) permitted the complete characterization of all whole numbers and offered, therefore, an understanding of the whole number system. The idea of understanding a whole, that one could never see, also applies to [his measurement](#) of the circumference of the Earth. In his role as Librarian of the great library of Alexandria, he had access to works of his many outstanding predecessors. He worked with spherical geometry, [latitude and longitude](#), [earth-sun relations](#), and a variety of geometric and [trigonometric](#) ideas. Eratosthenes sealed the gap between number theory and the real world with the idea of using abstract tools to understand more than what one could see, be that an infinity of whole numbers or an Earth larger than a hometown; his brain was wider than his sky.

The astonishing scholarship of Eratosthenes serves as a model, in a variety of ways, for this effort. The body of the text draws from disciplines in pure mathematics and aligns them with real world material. The underlying mathematics is critical to the effort. Beyond the synthesis of apparently disparate disciplines, however, is the model of Eratosthenes the librarian. In our present world, each of us is an amateur librarian in the great virtual library of the Internet. Direct access to materials from all over the world is available on our desktops. Thus, where possible, we assemble a subset of this library in this electronic book. The eBook, itself, serves therefore not only as an interactive forum employing state-of-the-art techniques for communicating scientific information, but also as a library on the topic it covers. Thus, we dedicate this effort to the spirit of Eratosthenes of Alexandria: may his research strategy endure for many more millennia!

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Spatial Synthesis: Centrality and Hierarchy, Volume I, Book 1.
Sandra Lach Arlinghaus and William Charles Arlinghaus

Chapter 1

Classical Central Place Hierarchies: A Real World View

[Link to original file, with interactive mapplets:](#)

CAUTION: This particular link to a file with Java applets may cause a browser crash depending on various configurations of hardware and software. No other link is known to have that possibility.

eHighlights of this Chapter

[Animated central place hierarchies: global view and sequence of local views](#)
[Virtual reality representation of sample point hierarchies \(requires Cosmo Player or Cortona\)](#)
[The evidence of historical maps cast in the current technological setting](#)

Circular regions surrounding lattice points

A scatter of points, spread evenly across the plane, may take on a variety of configurations. If one wishes to consider circular buffers around each point, then these buffers may overlap or be widely spaced. The space between buffers, in the background behind them, is interstitial space separating buffers. A natural issue to consider is to minimize interstitial space and provide some sort of maximal coverage of the plane by the buffers: to provide a "close packing" of the plane by circles.

Two close packings of the plane with circles of identical radius are shown in Figure 1.1: one with circles centered on a square lattice and the other with circles centered on a triangular lattice.

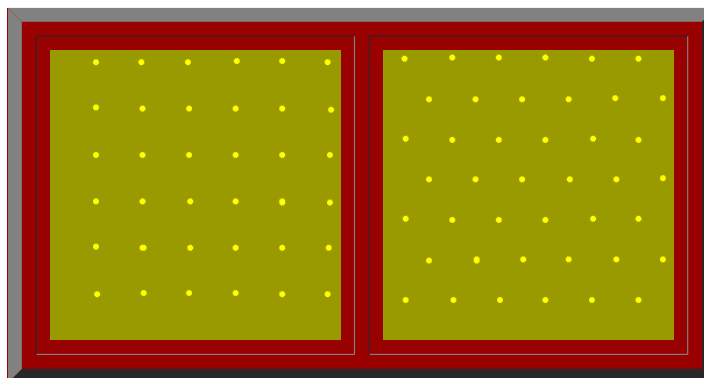
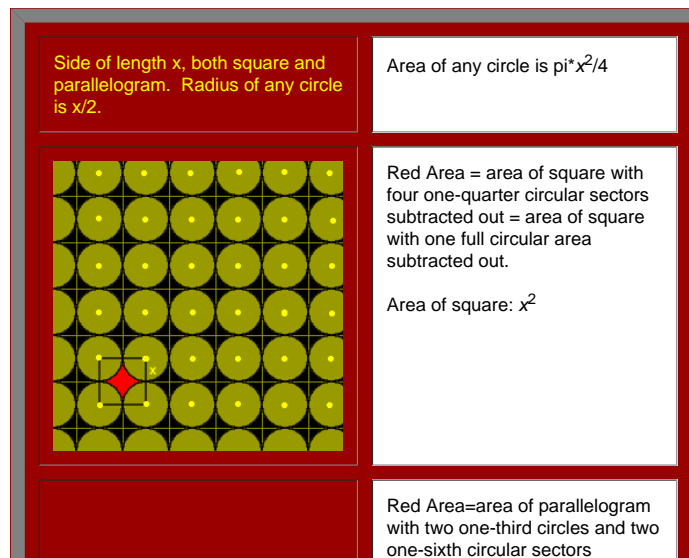


Figure 1.1 left, right. Animation shows square and triangular lattices in the plane and associated close packings with circles of identical radius. (Source of base image, no longer present at the cited url:http://www.psc.edu/~burkardt/src/graph_paper/graph_paper.html graph paper showing grid, triangular and hexagonal regions, John Burkardt, Pittsburgh Supercomputing Center, Carnegie Mellon University, University of Pittsburgh.).

It is a straightforward matter to calculate the interstitial space between circles associated with a square of side x in the square lattice and a corresponding parallelogram of side x in the triangular lattice. The radius of the circles in each figure is therefore $x/2$ and the area of the circles $\pi x^2/4$. Figure 1.2 shows a calculation of interstitial space: there is less interstitial area, between circles, within the parallelogram than there is within the square. Extrapolating this idea across the plane, one imagines naturally that the close packing of circles on the triangular lattice is denser than is the close packing of circles on the square lattice.



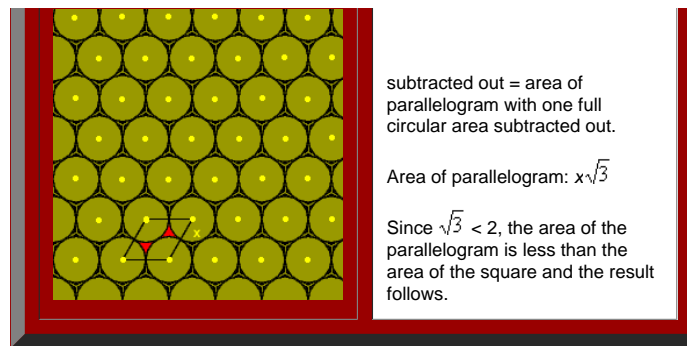


Figure 1.2. There is less interstitial area between circles within the parallelogram than there is between circles within the square. (Source of base image, no longer present at the cited url:http://www.psc.edu/~burkardt/src/graph_paper/graph_paper.html graph paper showing grid, triangular and hexagonal regions, John Burkardt, Pittsburgh Supercomputing Center, Carnegie Mellon University, University of Pittsburgh.).

This chain of reasoning indicates that the close packing of the plane by circles of identical radius is denser for a triangular lattice than it is for a square lattice. [Gauss](#) (1831) proved that, in fact, the densest lattice packing of the plane is the one based on the triangular lattice. In 1940, [Fejes-Toth](#) proved that that same packing is not only the densest lattice packing of the plane but is also the densest of all possible plane packings.

If one thinks, then, of the circles as if they were bubble-foam, the circles centered on a square grid pattern expand and collide to form a grid of squares (suggested in the top figure in Figure 1.2). The circles centered on a triangular grid pattern expand and collide to form a mesh of regular hexagons (suggested in the bottom figure in Figure 1.2). Because the close packing of circles centered on points spaced in a triangular grid is the densest possible close packing of the plane, the space-filling pattern of hexagonal cells associated with that packing also possesses unique character. If one were to enter a square or triangular grid into Geographic Information System software, and ask the software to calculate [Thiessen](#) polygons the grid of square cells would emerge from the square lattice and the grid of hexagonal cells would emerge from the triangular lattice. Thus, these cells can arise in a number of technical ways.

The theoretical issues surrounding tiling in the plane are complex; even deeper are those issues involving packings in three dimensional space. We confine our interest in that matter to simply illustrating Gauss's methods and stating Fejes-Toth's extension of it. The reader interested in probing this topic further is referred to the [references](#). Interpretation of the simple triangular grid has range sufficient to fill this volume and more.

Basic assumptions

One classical interpretation of what dots on a lattice might represent is found in the geometry of "central place theory." Readers interested in the development of this theory, over time and with regard to a clear understanding of who did what and when it was done, are referred to the references. We simply present some of the ideas in order to focus on the geometry. Geometric central place models take the complex human process of urbanization and look at it in an abstract theoretical form in order to uncover principles which might endure despite changes over time, situation, cultural tradition, and all the various human elements that are truly the hallmarks of urbanization. Simplicity helps to reveal form: models are not representations of reality. They do, however, offer a way to look at some structural elements of complexity. Thus, consider dots on a triangular lattice as populated places (often, villages). Circles, expanding into hexagons, are areas that are tributary to the populated places. In the traditional formulation (described after [Kolars and Nystuen](#)) one considers four basic postulates (no one of which is "real" but each of which is simple):

- The backdrop of land supports uniform population density
- There is a maximum distance that residents can easily penetrate into the tributary area (often called "maximum range").
- There is slow, steady population growth
- Village residents who move, as a result of growth (or for other reasons), attempt to remain in close contact with their previous location (to maintain social or other networks).

Suppose, in a triangular lattice of villages, that one village adds to its retailing activities. After some time, growth occurs elsewhere. How might other villages compete to serve tributary areas: how will the larger, new villages share the tributary area? The answers lead to a surprising number of possible scenarios. Figure 1.3 shows the first in an infinite number of possibilities. Animated locations, for competing larger villages, are shown in Figure 1.3. The smallest villages are represented as small red dots; next nearest neighbors competing for intervening red dots are represented in blue; and, next nearest neighbors competing for intervening blue dots are represented in green. Of course, one is usually only willing to travel so far to go to a place only slightly larger, so the fact that the animated pattern could be extended to an infinite number of levels, beyond green, may not mirror the second postulate. Over time, however, one might suppose further growth and an entire hierarchy of populated places.





Figure 1.3. A triangular lattice of dots with animated locations for competing locations entering and vanishing from the picture.

Such a view of growth leads to another set of assumptions (after [Christaller](#)).

- The underlying market is spread evenly across an abstract geographic plane
- The underlying, discrete population is evenly spread
- There is a set of central place activities which reflects willingness to travel.

Within these added constraints, there are some embedded assumptions, as well. In particular, central place activities are viewed as themselves occupying no space: an important point in terms of retaining simplicity of form in order to look at structure. The problems of industrial location or of site plans for commercial activity are complex and important issues in themselves; however, they serve to obfuscate what is under consideration here. Hence, these complex activities are assumed to occupy mere points. Further, there is embedded the idea of a natural hierarchy of central place activities: that one might be willing to travel to get to a strip mall 5 miles away for routine shopping but for greater activities and service would be willing to travel 30 miles to a regional mall that offers all the goods and services of the smaller mall plus additional ones. These ideas are further elaborated in the following four points.

- The population of each location is a function of the number of goods and services it offers.
- The central place system is a closed system
- Each central place offers all goods and services offered by lower order places plus added ones: the number of central places in the system is therefore, in some sense, optimal
- Communication within the central place system is perfect.

With these postulates and added constraints in mind, we examine the geometric configurations that are classically identified as central place hierarchies. These are Walter Christaller's view in looking for pattern from the broad to the particular; in interpreting these ideas, however, we present the characterization of August [Lösch](#), in working from the small to the large, as a synthesis of conceptual material.

Marketing principle: $K=3$

Consider a central place point, A , in a triangular lattice (Figure 1.4). Unit hexagons (fundamental cells) surround each of the points in the lattice and represent the small tributary area of each village (red hexagons in Figure 1.5a). Growth at A has distinguished it from other villages in the system. It will now serve a tributary area larger than will the unit hexagon. There are six villages directly adjacent to A . The unit hexagons represent a partition of area based on even sharing of area between A and these six villages. When A expands its central place activities, others may also desire to do so as well. Figure 1.4 shows the locations for the next nearest competitors, such as A' in blue, to enter the system. Given that they, too, will share area evenly, a set of larger hexagons emerges (blue hexagons in Figure 1.5a). The competitors that enter are spaced at a distance, in terms of lattice points spaced one unit apart, of $\sqrt{3}$ units (Figure 1.4). The position of the competitors that enter the system in this scenario are as close as possible to A ; expansion of goods and services at any of the six closest neighbors would constitute no change in basic pattern. One might imagine, therefore, that emphasis on distance minimization optimizes marketing capability--distance to market is at a minimum. Figure 1.5a shows the unit hexagons and the larger hexagons based on expansion of goods and services. To get a view of a large scatter of dots, arranged according to this idea, consider the [linked](#) virtual reality model. Use the Viewpoints to see an overview and a closeup; drive through it on your own.



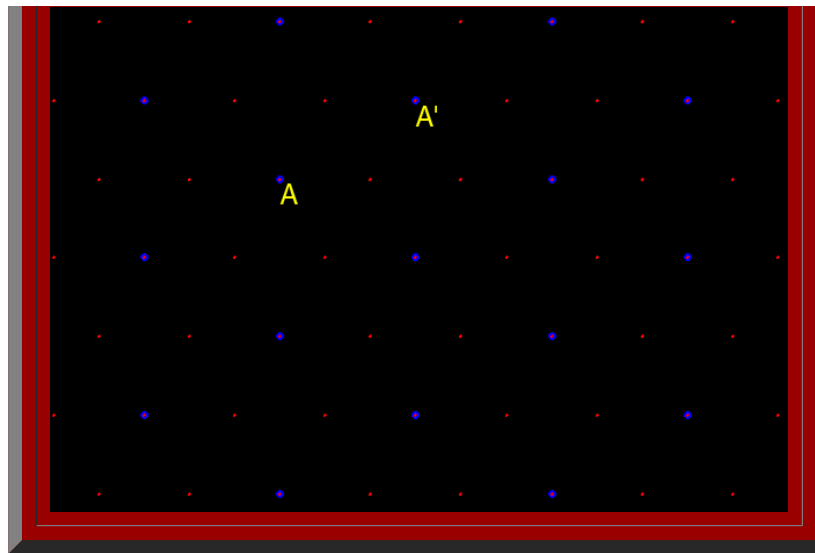


Figure 1.4. $K=3$: Marketing. Distance measurement between adjacent competing new centers, A and A' : in this case, competing centers, blue dots, are spaced $\sqrt{3}$ units apart, assuming a distance of one unit between adjacent red dots.

Thus, when competitors are chosen in this manner, the pattern of one layer of hexagons, in relation to another, has become known as a hierarchy arranged according to a "marketing principle" (Figure 1.5a). Notationally, it is captured by the square of the distance between competing centers: as a " $K=3$ " hierarchy (Figure 1.4). Each large hexagon contains the equivalent of three smaller hexagons. One large hexagon = 1 small hexagon + six copies of $1/3$ of a small hexagon = 3 small hexagons (Figure 1.5b, c, and d). Thus, the value $K=3$ is not only related to distance between competing centers but also to size of tributary areas generated by competition: as a constant of the hierarchy.



Figure 1.5a. $K=3$ hierarchy showing three layers of a nested hierarchy of hexagons of various sizes oriented with respect to one another according to the distance principle illustrated in Figure 1.4.

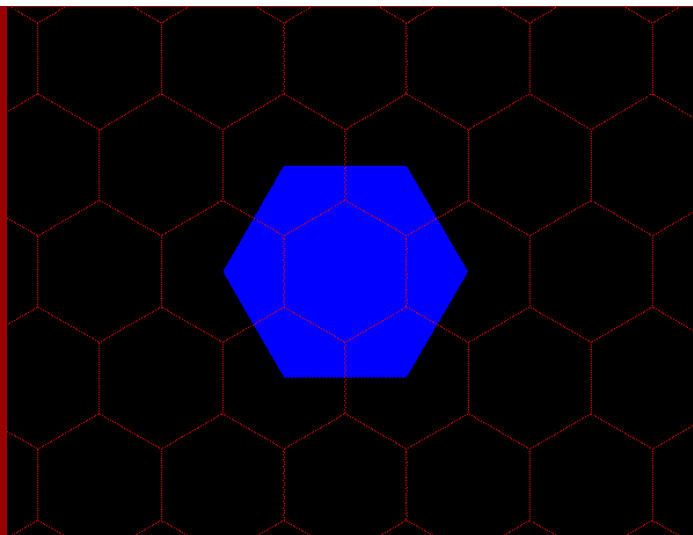


Figure 1.5b. Each blue hexagon contains the equivalent of three red hexagons: one entire red hexagon surrounded by six copies of $1/3$ of a red hexagon.

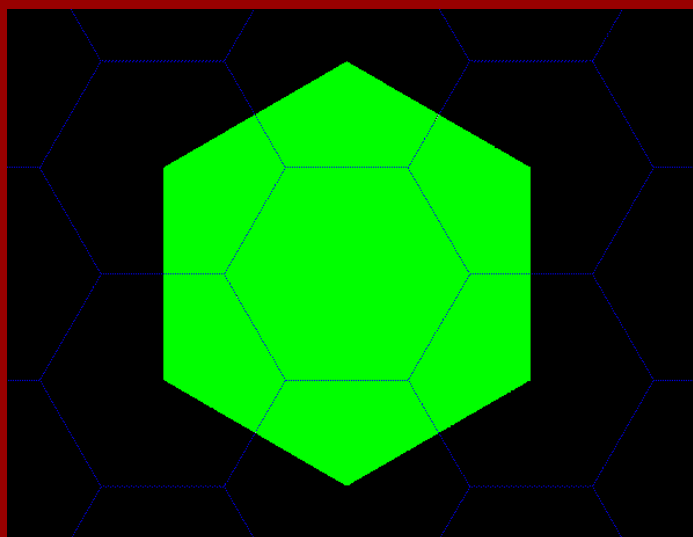


Figure 1.5c. Each green hexagon contains the equivalent of three blue hexagons: one entire blue hexagon surrounded by six copies of $1/3$ of a blue hexagon.

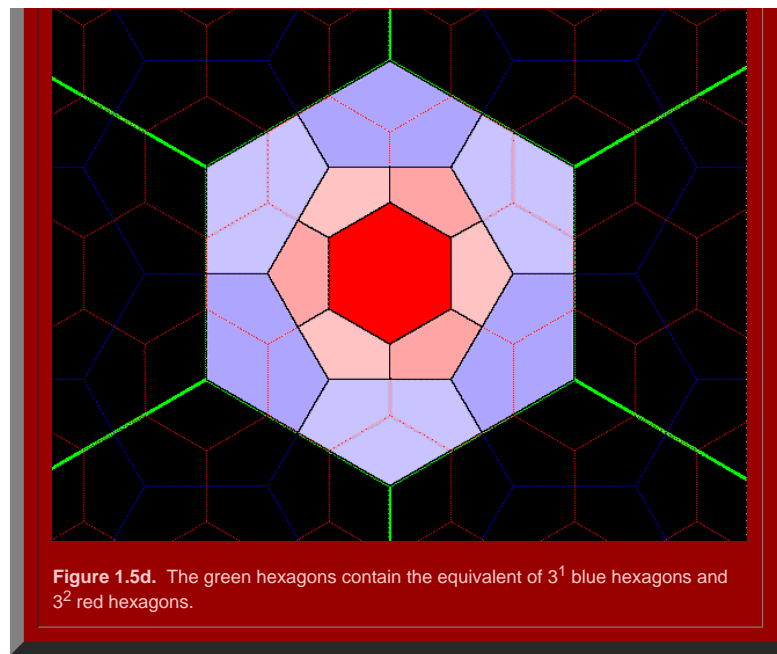


Figure 1.5.

[Back](#) to Chapter 2 $K=3$ reference.

Transportation principle: $K=4$

Figure 1.6 shows the locations for the next nearest competitors, next beyond those from $K=3$, to enter the system. Given that they, too, will share area evenly, a set of even larger hexagons emerges. Figure 1.7a shows the unit hexagons and the larger hexagons based on expansion of goods and services. The competitors that enter are spaced at a distance, in terms of lattice points spaced one unit apart, of 2 units (Figure 1.6). The position of the competitors that enter the system in this scenario lie along radials that fan outward from A and pass along existing boundaries to tributary areas. One might imagine, therefore, that emphasis on market penetration, or transportation, is the focus here. To get a view of a large scatter of dots, arranged according to this idea, consider the [linked](#) virtual reality model. Use the Viewpoints to see an overview and a closeup; drive through it on your own.

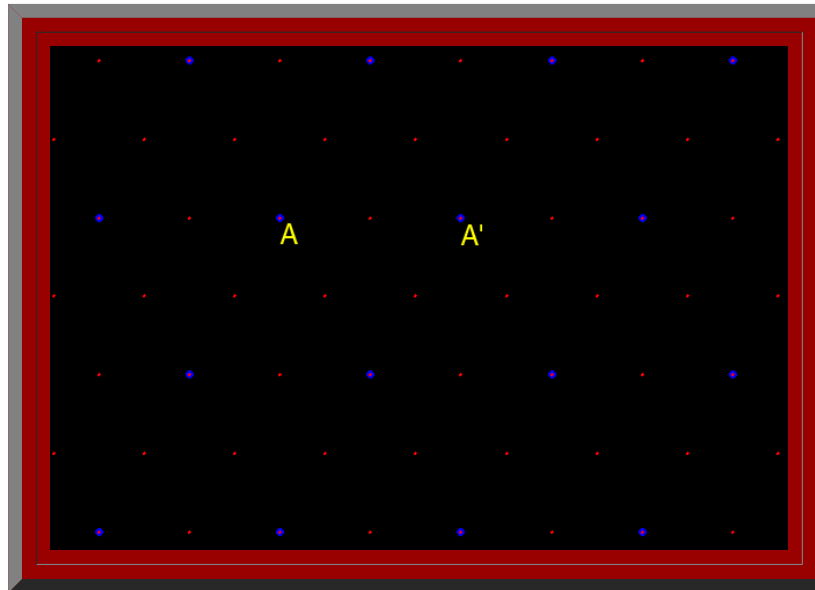


Figure 1.6. $K=4$: Marketing. Distance measurement between adjacent competing new centers, A and A' is 2 units, in this case (assuming a distance of 1 unit between adjacent red dots).

Thus, when competitors are chosen in this manner, the pattern of one layer of hexagons, in relation to another, has become known as a "transportation principle" (Figure 1.7a). Notationally, it is captured by the square of the distance between competing centers: as a " $K=4$ " hierarchy (Figure 1.6). Each large hexagon contains the equivalent of four smaller hexagons. One large hexagon = 1 small hexagon + six copies of $1/2$ of a small hexagon = 4 small hexagons (Figure 1.7b, c, d). Thus, the value $K=4$ is not only related to distance between competing centers but also to size of tributary areas generated by competition--as a constant of the hierarchy.



Figure 1.7a. $K=4$ hierarchy showing three layers of a nested hierarchy of hexagons of various sizes oriented with respect to one another according to the distance principle illustrated in Figure 1.6.

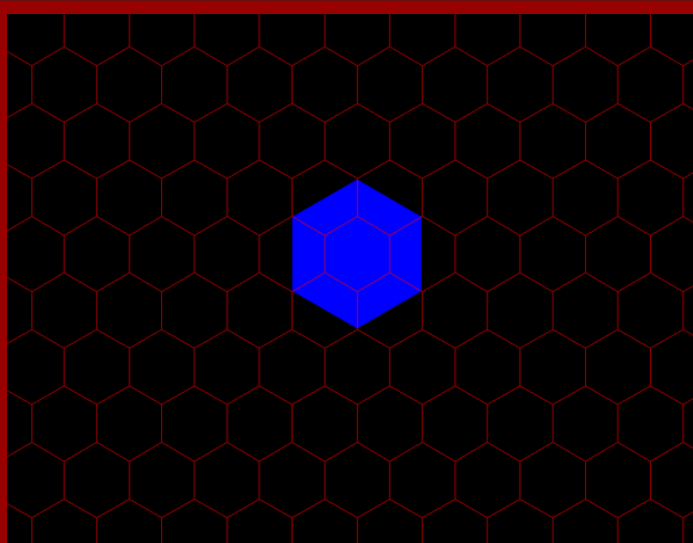


Figure 1.7b. Each blue hexagon contains the equivalent of four red hexagons: one entire red hexagon surrounded by six copies of $1/2$ of a red hexagon.

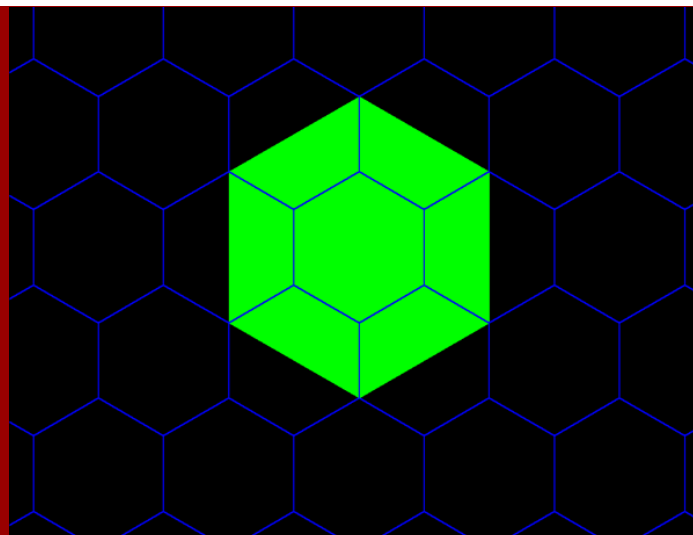


Figure 1.7c. Each green hexagon contains the equivalent of four blue hexagons: one entire blue hexagon surrounded by six copies of 1/2 of a blue hexagon.

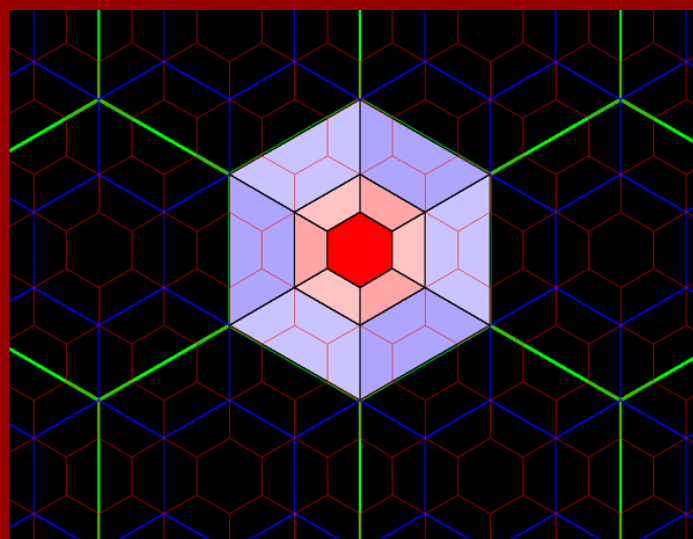


Figure 1.7d. The green hexagons contain the equivalent of 4^1 blue hexagons and 4^2 red hexagons.

Figure 1.7.

[Back](#) to Chapter 2 $K=4$ reference.

Administrative principle: $K=7$

Figure 1.8 shows the locations for the next nearest competitors, next beyond those from $K=4$, to enter the system. Given that they, too, will share area evenly, a set of even larger hexagons emerges. Figure 1.9a shows the unit hexagons and the larger hexagons based on expansion of goods and services. The competitors that enter are spaced at a distance, in terms of lattice points spaced one unit apart, of $\sqrt{7}$ units (Figure 1.8). The position of the competitors that enter the system in this scenario create larger hexagons whose boundaries pass through very few other populated places: hence, top-down control, or rule from the center is emphasized. One might imagine, therefore, an emphasis on administrative control here. To get a view of a large scatter of dots, arranged according to this idea, consider the [linked](#) virtual reality model. Use the Viewpoints to see an overview and a closeup; drive through it on your own.

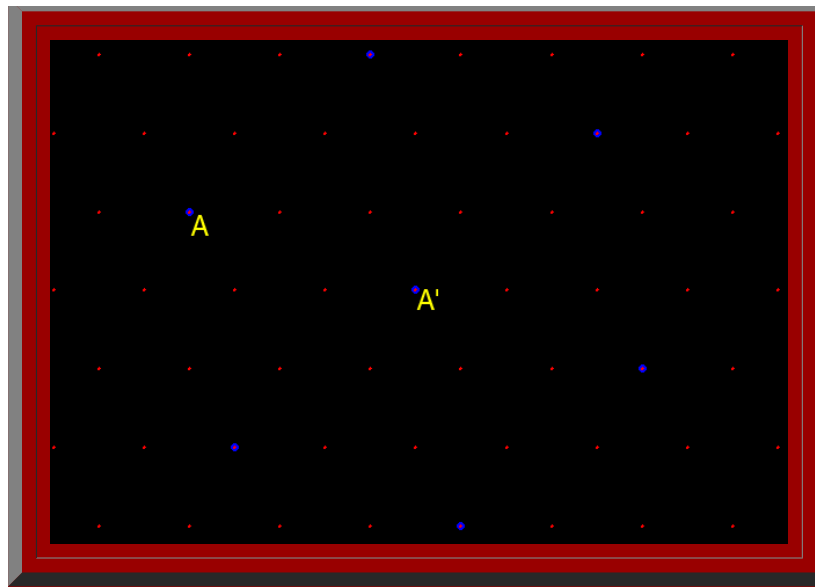


Figure 1.8. $K=7$: Marketing. Distance measurement between adjacent competing new centers, A and A' is $\sqrt{7}$ (assuming a distance of 1 unit between adjacent red dots).

Thus, when competitors are chosen in this manner, the pattern of one layer of hexagons, in relation to another, has become known as a hierarchy arranged according to an "administration principle" (Figure 1.9a). Notationally, it is captured by the square of the distance between competing centers: as a " $K=7$ " hierarchy (Figure 1.8). Each large hexagon contains the equivalent of seven smaller hexagons. One large hexagon = 1 small hexagon + six copies of a small hexagon (underfit and overfit regions balance) = 7 small hexagons (Figure 1.9b, c, d). Thus, the value $K=7$ is not only related to distance between competing centers but also to size of tributary areas generated by competition--as a constant of the hierarchy.



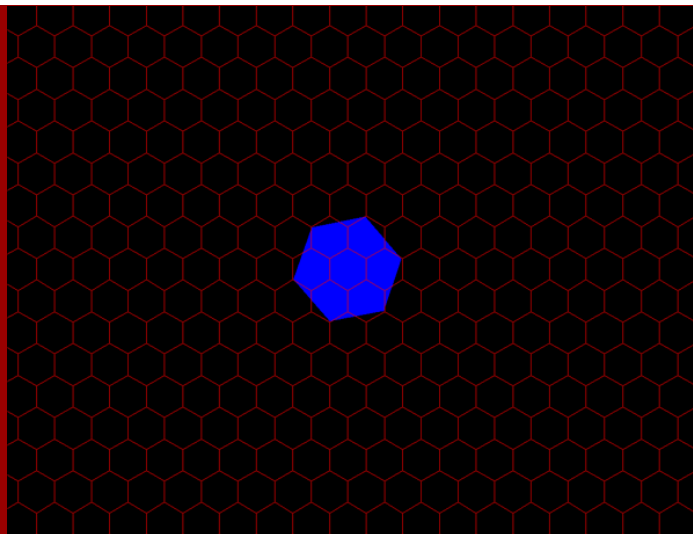


Figure 1.9b. Each blue hexagon contains the equivalent of seven red hexagons: one entire red hexagon surrounded by six copies equivalent to a single red hexagon. Each of the perimeter red hexagons is composed of $11/12$ of a single red hexagonal cell plus $1/12$ of an adjacent red cell: in an underfit/overfit pattern.

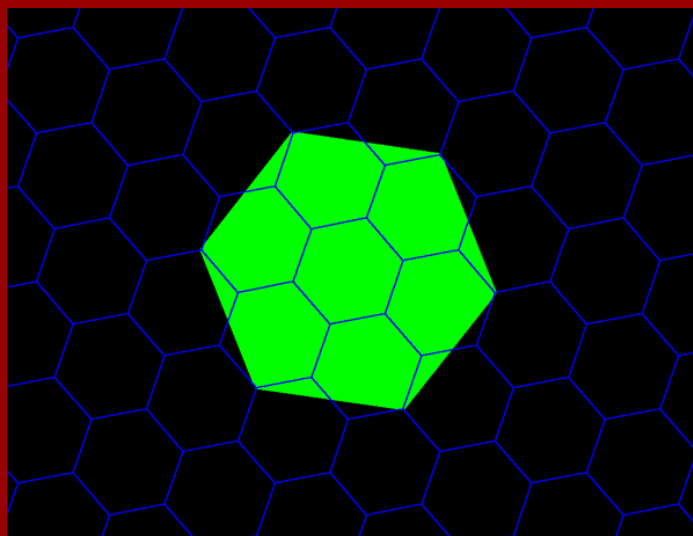


Figure 1.9c. Each green hexagon contains the equivalent of seven blue hexagons: one entire blue hexagon surrounded by six copies equivalent to a single blue hexagon. Each of the perimeter blue hexagons is composed of $11/12$ of a single blue hexagonal cell plus $1/12$ of an adjacent blue cell: in an underfit/overfit pattern.

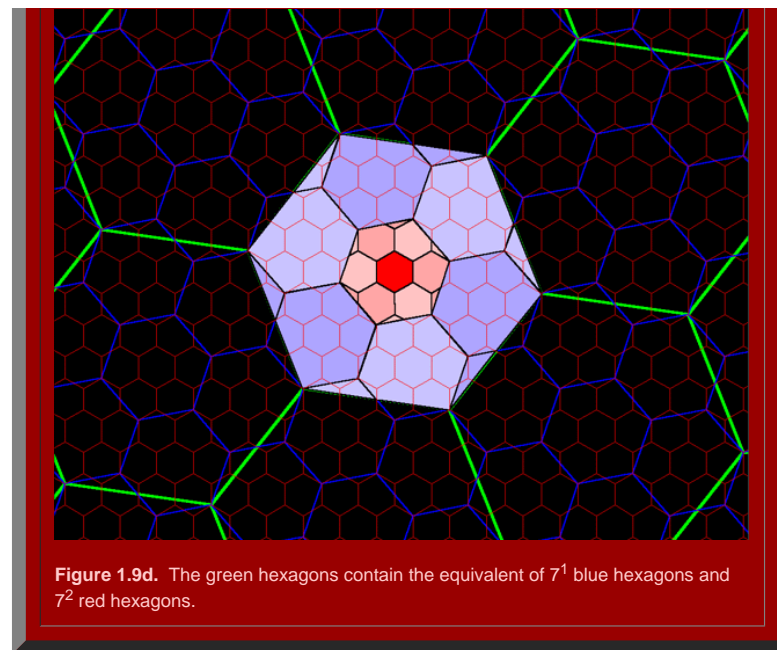


Figure 1.9.

[Back](#) to Chapter 2 $K=7$ reference.

A tiled view of each hierarchy: mechanics of construction

The process of creating larger hexagons, as larger tributary areas representing expanded central place activities, can be carried out indefinitely. The set of figures above (1.5, 1.7, and 1.9) shows the general patterns that emerge and underscores, particularly, the importance of the constant of the hierarchy. Large hexagons in one layer contain the equivalent of K^1 hexagons of the next smallest size within them; they contain the equivalent of K^2 hexagons from the level two layers down in the hierarchy, and so forth. The K value is an invariant of each geometric hierarchy that uniquely characterizes it. The mathematical search for invariants as bench marks against which to view abstract structure is equivalent to the geographical search for bench marks in the field (physical or human) against which to view mapped, spatial structure.

Virtual reality central place skylines

The initial conditions from the real world may suggest building a hierarchy from small hamlets to large cities, in the style of Christaller, or they may suggest the reverse, in the style of Lösch (or any of an infinite number of possibilities in between--we confine ourselves to the extremes). Independent of such choice, however, the resulting geometry is identical: a pattern of hexagons of various sizes, dependent on spacing between competing centers at a given hierarchical level, is the result. To see the different initial patterns of dots, and to move them around on the screen, it is useful to capture the dot patterns above as virtual reality scenes. Animation of successive virtual reality scenes, as a sequence of screen captures of the scene from various vantage points, offers the reader a chance to examine closely the three different styles of initial dot scatter used to create the geometries of hexagons associated with $K=3$, $K=4$, and $K=7$.

The linked figures, Figures [1.11](#) (derived from Figure 1.5), [1.12](#) (derived from Figure 1.7), and [1.13](#) (derived from Figure 1.9), offer a view of central place $K=3$, $K=4$, and $K=7$ landscapes as central place skylines in virtual reality. Links to each of these were given above, as they developed. Here, we simply accumulate the set in one set of links near each other for ease in making comparisons. Load CosmoPlayer and click on the links to drive through these landscapes and experience them as if the higher order central places represent taller urban structures, such as cell towers or other dominant skyline features. Figure 1.10 shows each of these virtual reality models, from the vantage point of "entry," as animated screen capture so that one might readily compare the three hierarchies. Figures 1.11 and 1.12 show similar animations, for purposes of comparison of pattern among $K=3$, $K=4$, and $K=7$, from the vantage point of "Overview" and "Close Up" respectively. Movies of these animations permit the reader to control the animation frame rate: [Movie of 1.10](#), [movie of 1.11](#), and [movie of 1.12](#). (If the horizontal scroll bar does not show at the bottom of the linked image, expand your browser to show the full screen: in Microsoft Internet Explorer, for example, hit the F11 key.) In the next chapter, we use virtual reality to take a closer look at the geometry of these hierarchies; thus, it is worth the effort now to load the plug-in and to practice virtual navigation in a simple landscape.



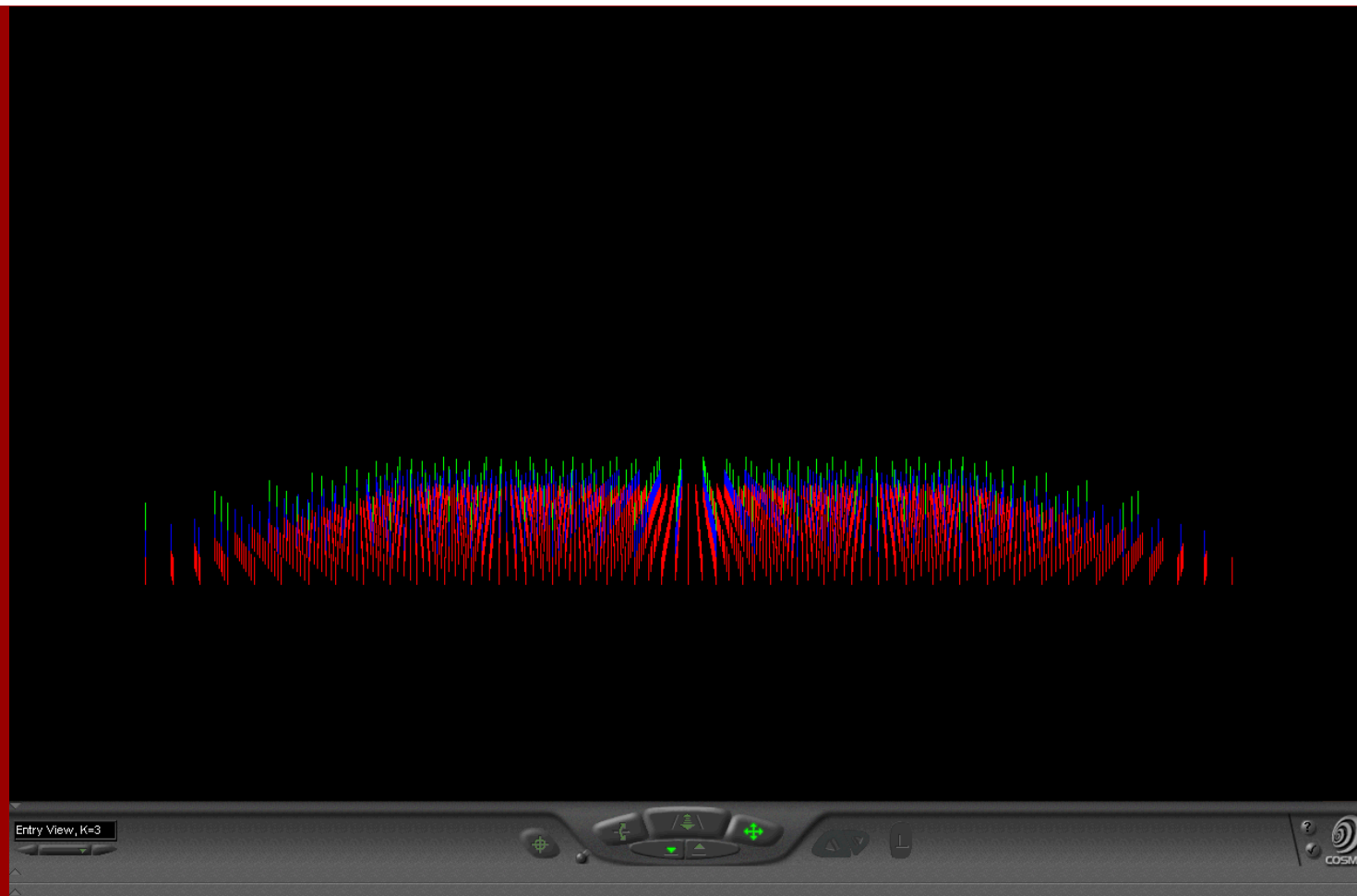


Figure 1.10. $K=3$, $K=4$, and $K=7$ hierarchies animated as viewed from the "entry" viewpoint of associated virtual reality models.

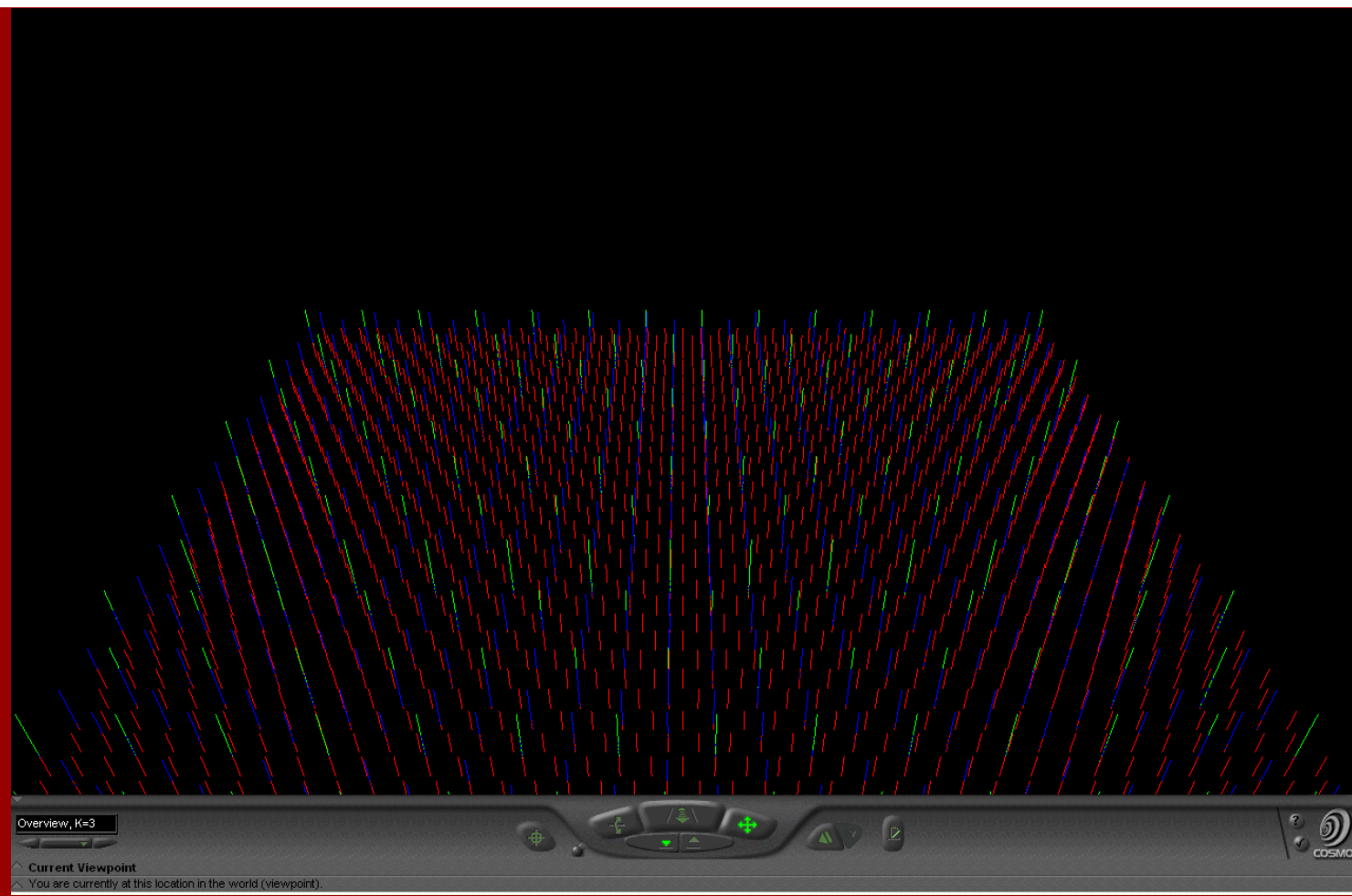


Figure 1.11. $K=3$, $K=4$, and $K=7$ hierarchies animated as viewed from the "overview" viewpoint of associated virtual reality models.

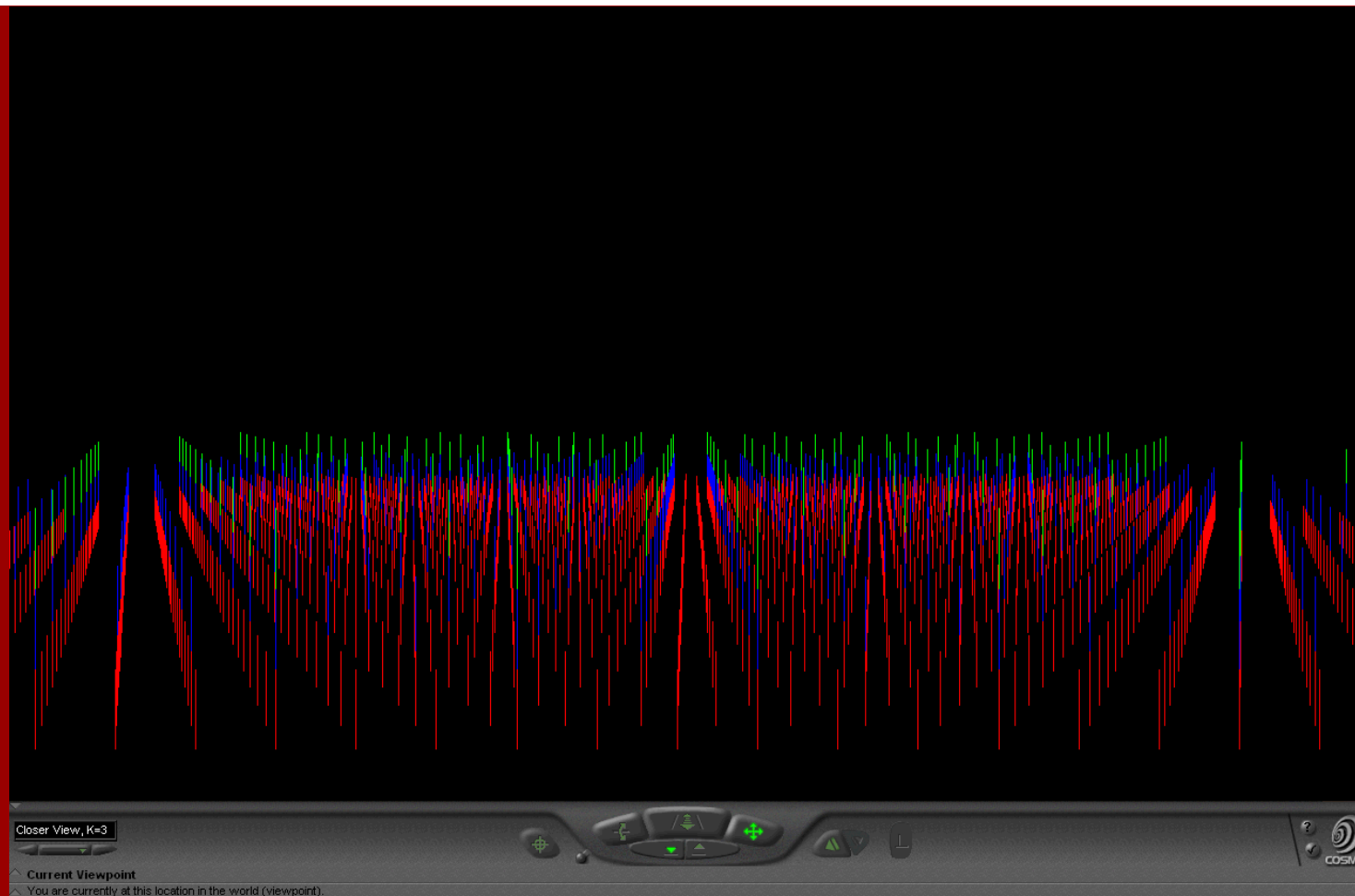


Figure 1.12. $K=3$, $K=4$, and $K=7$ hierarchies animated as viewed from the "close up" viewpoint of associated virtual reality models.

Mapplets

Another method, that is available only in current technology, for looking simultaneously at connection patterns between multiple layers of central place networks involves capturing them as Java (TM) Applets: as "Mapplets." This process also suggests some sort of stability of the geometric structure: the mapplet reflects stability in structural form. Shake the mapplet; it settles down to the expected hierarchy. Pull the mapplet; still it settles down to the underlying hierarchical form. One might speculate about real-world forces that pull on mathematical form: the form endures.

Figure 1.13. $K=3$ Mapplet

Figure 1.14. $K=4$ Mapplet

Figure 1.15. $K=7$ Mapplet

Mapplets focus on connection patterns between successive hierarchical layers and, when K values are loaded as distances between hierarchies, they also suggest some elusive form of structural stability of geometric form. Animated maps of the central place geometry of the plane, coupled with mapplets showing animated hierarchical pattern alone, suggest another sort of three dimensional view of central place geometry.

Central place hierarchies as Thiessen polygons

One difficulty with considering central place landscapes rests in their visualization. Slight errors in placement of points get magnified in overlay alignments. To create a meshed hierarchy in which overlays are aligned is a drafting task of substantial proportions, when done by hand. Geographic Information System software, however, offers an easy and accurate method of constructing central place landscapes at almost any level of complexity (up to the limits of hardware and software capability). Figures 1.4-1.9 were created using ArcView GIS (v. 3.2, ESRI). The method for creating GIS-generated central place landscapes employed the following steps:

- obtain as a base map a triangular lattice shape file; such a file may be created in ArcView using EdTools extension to precisely translate a point.

- ensure that each record in the underlying database has a unique code entered in "number" format (using the "add record number" feature of Animal Movement extension, if need be).
- if desired, create in a separate layer, a bounded region to serve as limits within which to calculate the landscape--a rectangle, for example. One way to create such a region is to calculate the minimum convex polygon (convex hull) of the distribution of red dots using Home Range extension.
- load Spatial Analyst extension (ESRI) to ArcView and calculate [Thiessen polygons](#) using the Analysis|Assign Proximity command; choose the rectangle layer as the region within which to calculate the [Thiessen](#) polygons. Alternately, employ the same strategy using Home Range extension and calculate Dirichlet regions.
- The result will appear as a set of small hexagons surrounding the dots, as in the red layers in Figures 1.4-1.9.
- Repeat the procedure on other triangular lattices, with broader spacing of lattice points as in the blue and green points above, derived from the base lattice. The result will produce landscapes such as those in Figures 1.4-1.9 depending on how the broader spacing pattern is selected.

This strategy is simple to execute and straightforward to discover. Its importance, however, lies in its ease of use and its accuracy. Large environments can be created almost as easily as small ones and historical central place studies can be captured electronically. Indeed, central place studies done by hand can be checked and planning documents from the past can be recast as central place geometries.

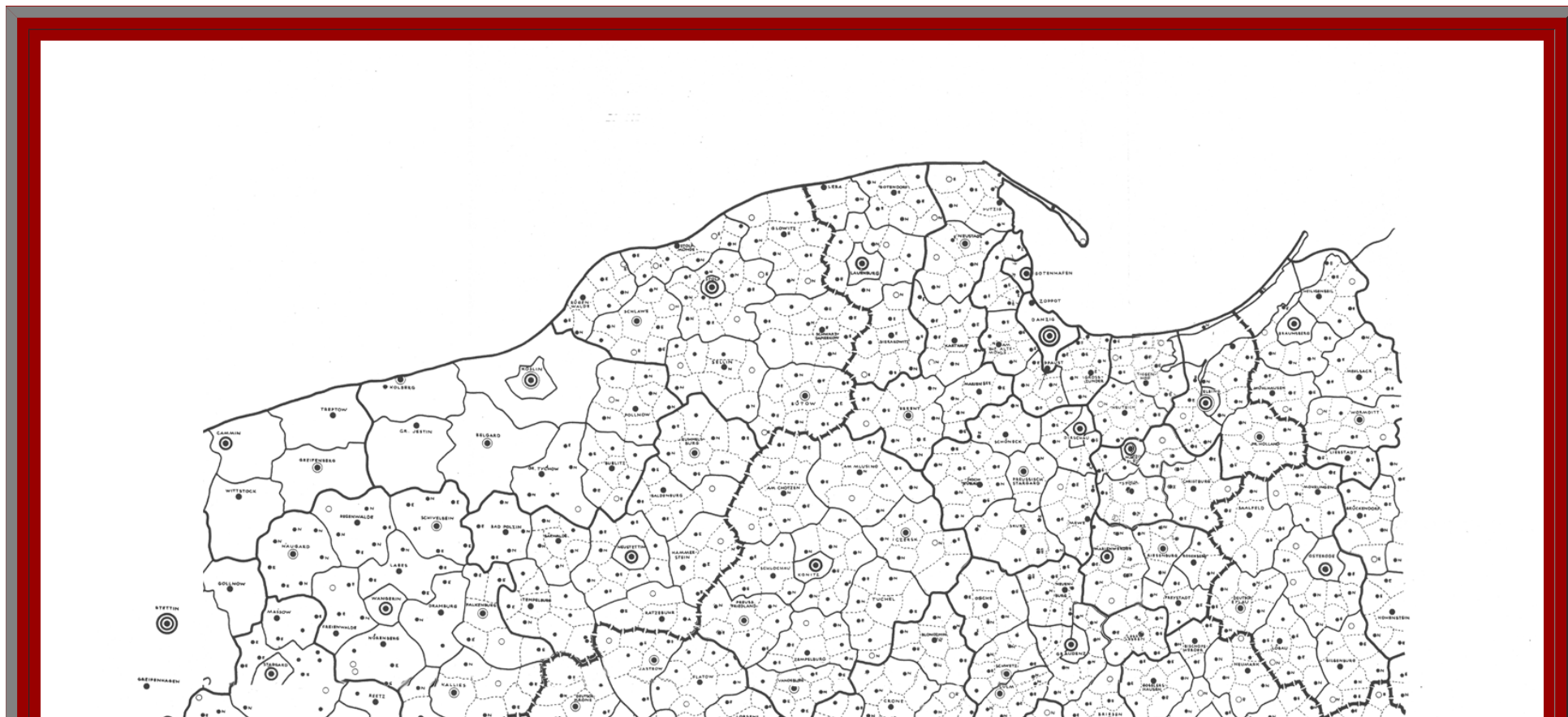
Christaller and settlements in Central Europe

The map in Figure 1.16 shows Walter Christaller's sense of regional settlement planning in Eastern Europe. [Harris and Berry](#), note in "Walter Christaller: An Appreciation," that central place theory served as the basis for settlement planning in Eastern Europe:

"...Christaller's involvement in the tumultuous social movements that affected Germany profoundly influenced his life. Like many young Germans, he became aligned with left-wing causes during the 1920s, and later his work was used as the basis of Nazi settlement planning in Eastern Europe. As a result this gentle and kindly man was shunned politically by both East and West after World War II, even as he was being accorded belated recognition for his pioneering contributions to theoretical geography."

The first author contacted Harris directly, in writing and on the telephone, to find out more about the source of that statement. The [linked](#) letter shows one part of his fascinating answer. He also offers citations to appropriate documents to read. The map in Figure 1.16 is based directly on material from [one](#) of these sources.

In it, larger cities are spaced farther apart than are smaller ones. Towns and villages fill interstitial space. Surely it must have taken [Christaller](#) much time and effort to construct this map. We have scanned it from a map in the 1941 reference and pieced together the scanned images. The scanning strategy was a multistep process because the map was quite large. First, 8.5 by 14 inch photocopies were made of the map in the book. It took 8 of those to capture the map, with overlap. Then, each piece was scanned at 600dpi on a flatbed scanner. The goal was to reassemble the scanned pieces on a canvas in Adobe Photoshop. File size of the 8 pieces prohibited such strategy and caused file oversize errors. Thus, each piece was reduced in size from 6900 pixels wide to 2000 pixels wide (preserving the aspect ratio). Then, each of these smaller images (smaller in physical size but not in resolution) was saved as a transparent .gif. The images with transparent backgrounds were then brought into Adobe Photoshop and assembled as a set of layers; use of transparency was important because it was only then that we could see how to fit the pieces together. To see an even larger version of this map (on which place names can be read easily), click [here](#); the attached file is over 5 MB in size: scroll both horizontally and vertically to see the linked map.



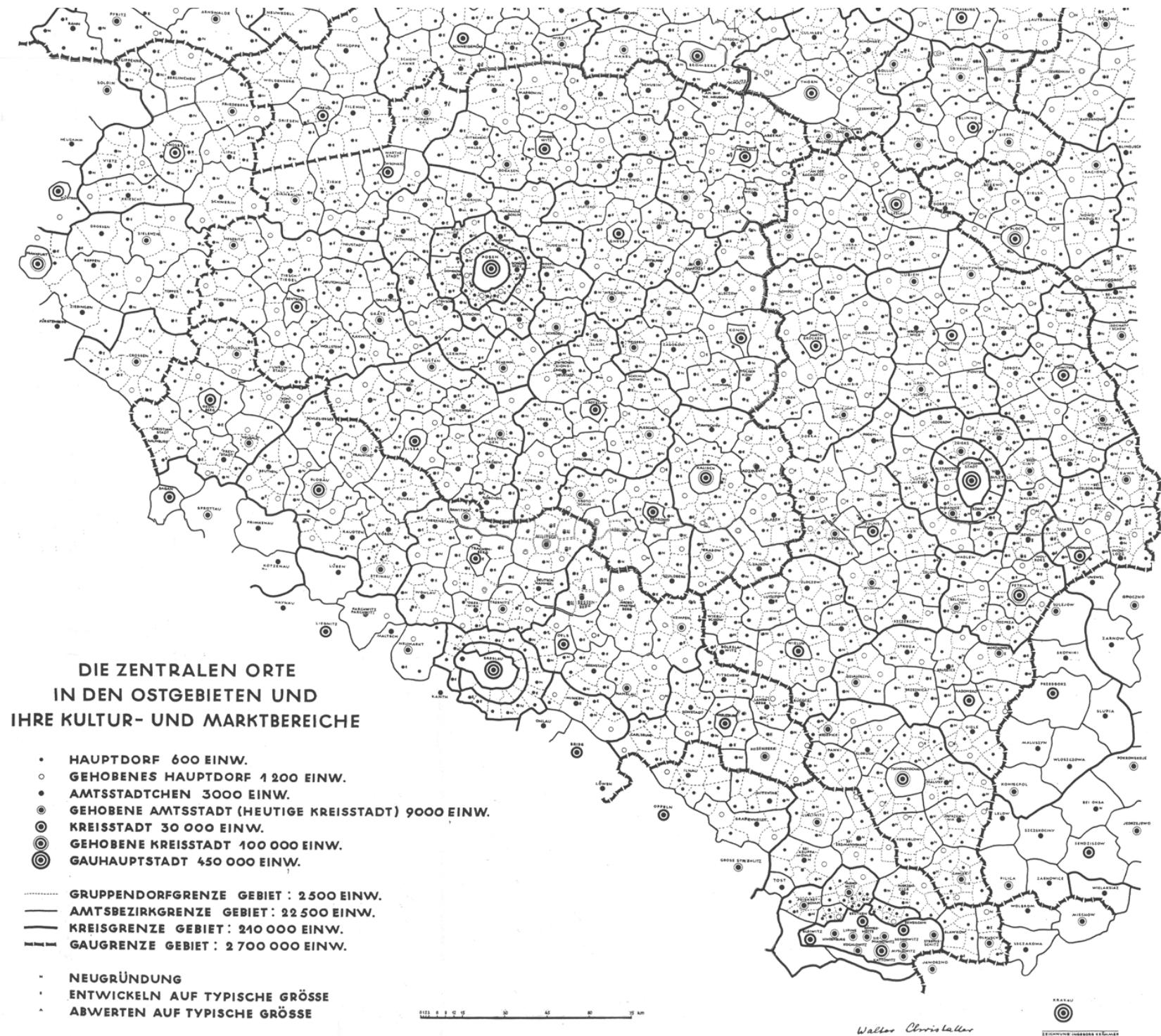


Figure 1.16. Walter Christaller's view of central places in Eastern Germany, 1941. Click on the map above to see a larger image.

(Source: *Struktur und Gestaltung der Zentralen Orte des Deutschen Ostens*, Gemeinschaftswerk im Auftrage der Reichsarbeitsgemeinschaft für Raumforschung, Teil 1, Dr. Walter Christaller, Die Zentralen Orte in den Ostgebieten und ihre Kultur- und Marktgebiete, K. F. Koehler Verlag, Leipzig, 1941).

Digitize the original map.

One question that arises is, does the map drawn by Christaller, showing a plan for settlement in Eastern Europe, actually conform to a central place theory pattern as might be generated today? [Preston \(1992\)](#) notes that Christaller used an administrative hierarchy, as well as a [mixed hierarchy](#), in creating plans for the east, mixing marketing, transportation, and administration/separation principles. A map of the sort above is complex. Current technology permits creation of geometric consideration of historical evidence. It is a straightforward manner to digitize the dots set down by Christaller in different layers in a GIS according to assigned hierarchical level. Use of Thiessen polygons to create pattern is also simple to execute. Thus, when the image of Figure 1.16 was brought into Geographic Information System software, we separated the layers of dots as Christaller had suggested in the legend. The sizes of the colored dots in Figure 1.17 show an animated view of the seven levels of urban areas entering the system: from largest to smallest.

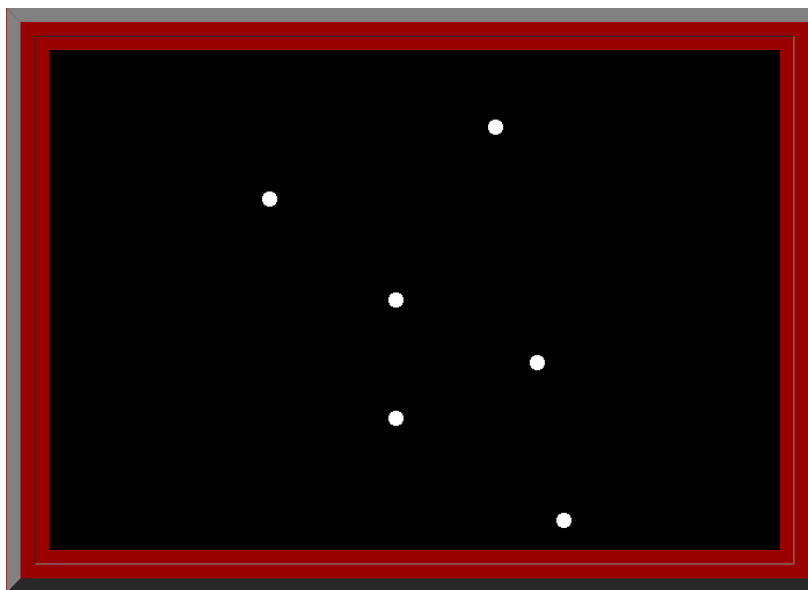


Figure 1.17. The central places of Figure 1.16 entered into a Geographic Information System.

Both the legend of Figure 1.16 and the animated map of Figure 1.17 suggest that all layers in this hierarchy are similar in nature. A closer look, however, at Figure 1.16 might see the first five layers as those with central place activities and see layers six and seven (the most rural) as working together to form a single, final layer that fills in between central places. No sixth or seventh layer places have links to subordinate places. Figure 1.18 shows those two most rural layers represented as a single layer as a scatter of yellow dots. These yellow dots are then analyzed using [Thiessen](#) polygons to create a cellular mesh that appears quite local in nature.



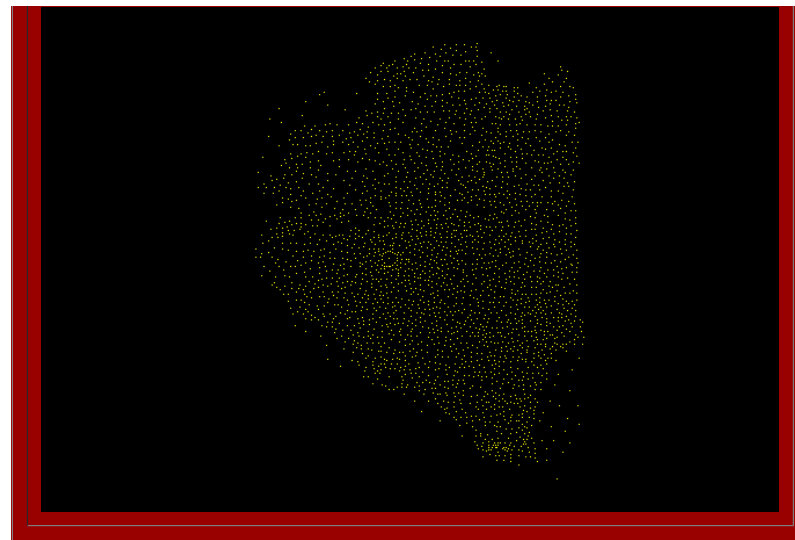


Figure 1.18. Thiessen polygons form a cellular mesh based on the two most rural layers of the hierarchy from map 1.16.

Figure 1.19 shows a sample overlay of the local cellular mesh on the original Christaller map.

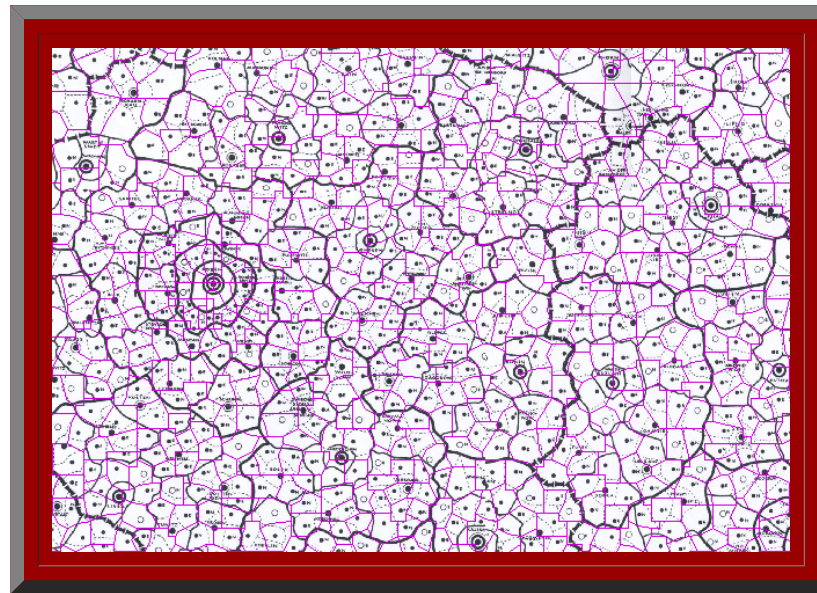


Figure 1.19. Overlay showing cellular mesh superimposed on Christaller map. Posen is the large city located near the middle/left.

Next, we constructed, using the GIS, Thiessen central place networks for each of the first five layers of the hierarchy identified by Christaller. Figure 1.20 shows these animated layers embedded in the convex hull of the map in Figure 1.16.



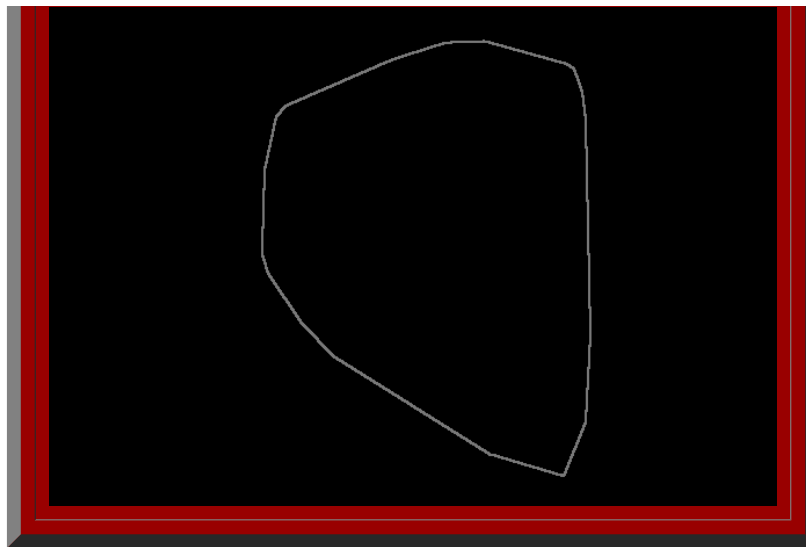
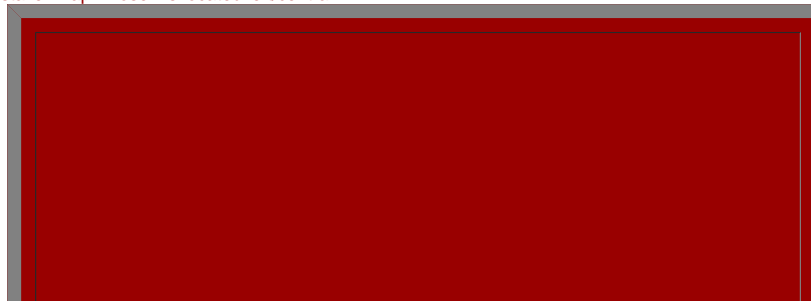


Figure 1.20. Thiessen-generated mesh for each of the five layers of largest urban places in the legend of the Christaller map.

Figure 1.21 shows a closeup comparing each of these layers to the actual map. Note the underfit/overfit pattern at the most global level (as with fractal generators for $K=7$).



Figure 1.21. Each of the layers of Figure 1.20 overlain on the Christaller map. Posen is located left/central.



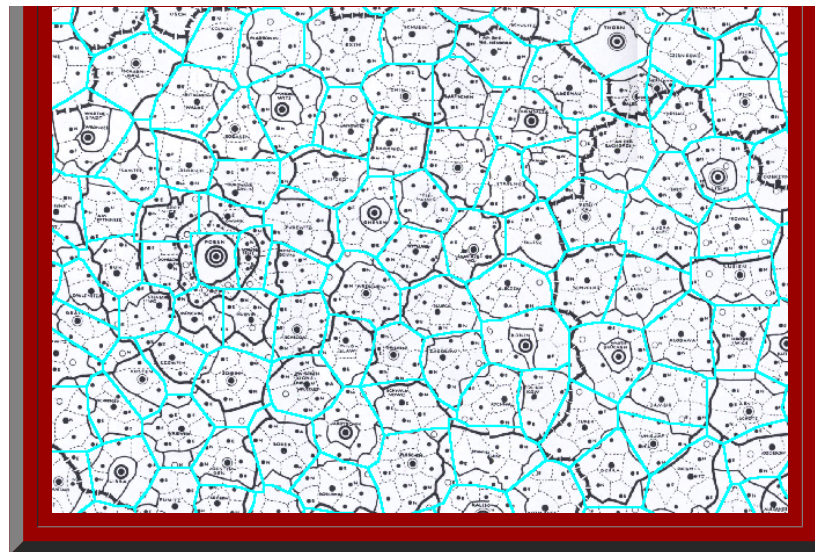


Figure 1.22. Isolated frame from the animation in Figure 1.21, showing the correspondence between the cyan Thiessen-generated polygons and the underlying Christaller map. When the place names are linked, via the hierarchy shown in Christaller's map, as a Mapplet (Figure 1.23), the hierarchical pattern becomes clear in yet another visual manner.

Figure 1.23.

Clearly one can recreate maps from the past using techniques of the present. The strategy of aligning existing work with new technique will be carried forward into the next chapter. Establishing such alignment is interesting; projecting theorems and concepts on which it is based, into future research, is the real reason for making such alignments: to see that new procedures provide adequate results on known cases so that they serve as a procedural benchmark to extend into new theoretical and practical realms.

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Spatial Synthesis: Centrality and Hierarchy, Volume I, Book 1.
Sandra Lach Arlinghaus and William Charles Arlinghaus

Chapter 2

Fractal Generation of the Classical Hexagonal Hierarchies

Concepts from fractal geometry embrace the entire geometry of classical central place theory. One type of fractal iteration sequence alone, a self-similarity transformation, produces all possible central place nets. This alignment presents more than mere technique for a verification of a geometry of central places (although it does do that, too); the geometry of the central place model is well-known and has been clearly, and comprehensively, discussed in Michael Dacey's 1965 article ([Dacey 1965](#)). The conceptual material here reveals an exact procedure for the merging of two separate theories: one from pure mathematics and one from economics and geography. In so doing, it suggests, in general, the power of one to enrich the other through the lodging of one discipline in the house of the other, and in particular, a theory in its own right derived from associating mathematically-specialized central place concepts with mathematically-broader fractal concepts.

In this chapter, we show in detail the alignment of fractal geometry with classical central place theory. In subsequent work, we illustrate how this geometry extends into far-flung realms to solve existing unsolved problems of classical central place theory and probe directions for further theoretical discovery and empirical application. The alignment of the existing classical material with fractal geometry is of interest in its own right; far more important, however, is the benchmark that this alignment creates--classical central place geometry serves as a field check for the fractal maps prior to the use of these maps as guides in the realm of theoretical geography.

"Fractals Take a Central Place"

In the material below, we illustrate, using a hexagon as an initiator, different selections of generators applied to the initial hexagon, to produce the different hexagonal hierarchies of classical central place theory (based on original concept and work of S. Arlinghaus (1985); see [link](#)). In the previous chapter we formed central place landscapes by moving from small hexagons to large ones; here, we reverse the process and dissect, using the self-similarity transformation, a large hexagon to create the smaller ones. In both processes, the results correspond exactly. The art is in generator selection, and it is simply that art that is presented in this chapter. Later work will delve into the mathematical foundations of that art.

The $K=3$ Hierarchy

When an hexagonal initiator is chosen and a two-sided generator, with included angle of 120 degrees, is used to make successive replacement of the sides of the hexagon (as in the animated Figure 2.1 a), the outline of the next layer of the $K=3$ central place hierarchy is generated (the black lines in Figure 2.1a suggest interior connections). The replacement sequence applies the generator in an alternating pattern to the outside and then to the inside of the initiator. When the original generator is scaled down, with shape preserved, and applied in the outside/inside sequence to the newly formed blue polygon, the next lower level central place $K=3$ hierarchy is formed (as in the animated Figure 2.1b). The second, blue polygon contains three scaled-down hexagons, self-similar to the first hexagon (Figure 2.1a); the red polygon in the animation sequence contains three shapes self-similar to the blue polygon (Figure 2.1b), and 27 (or 3 cubed) hexagons self-similar to the original hexagon (Figure 2.1b). The invariant of 3, in the $K=3$ hierarchy, is replicated in this particular fractal iteration sequence.

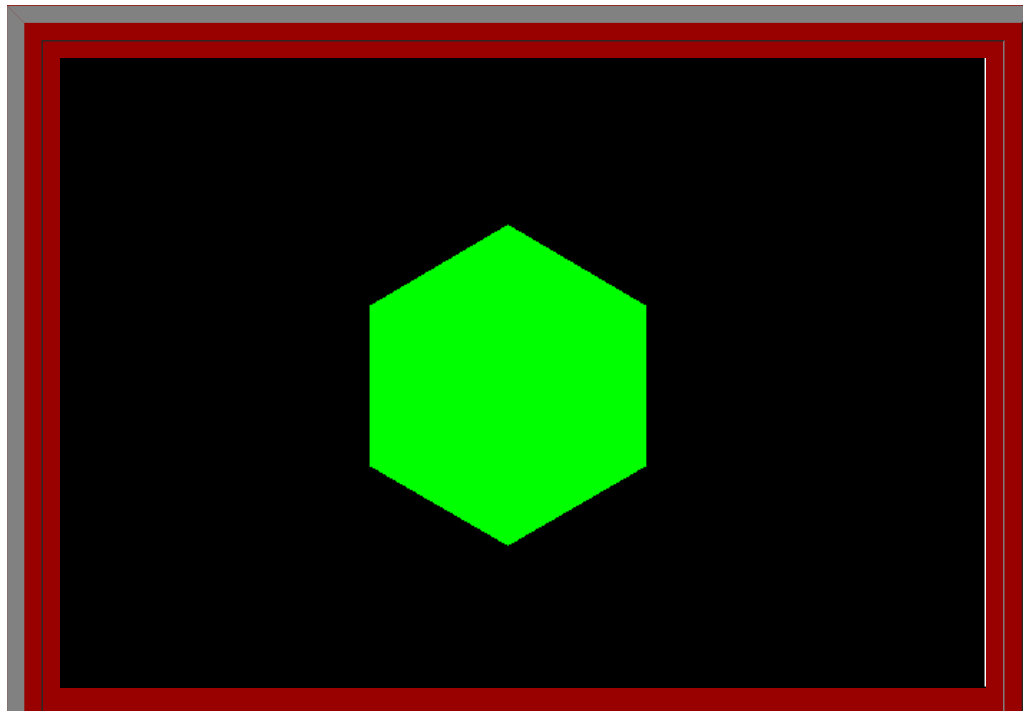


Figure 2.1a. Animated $K=3$ fractal iteration sequence: first transformation using a two-sided fractal generator applied successively to sides of the hexagonal initiator.

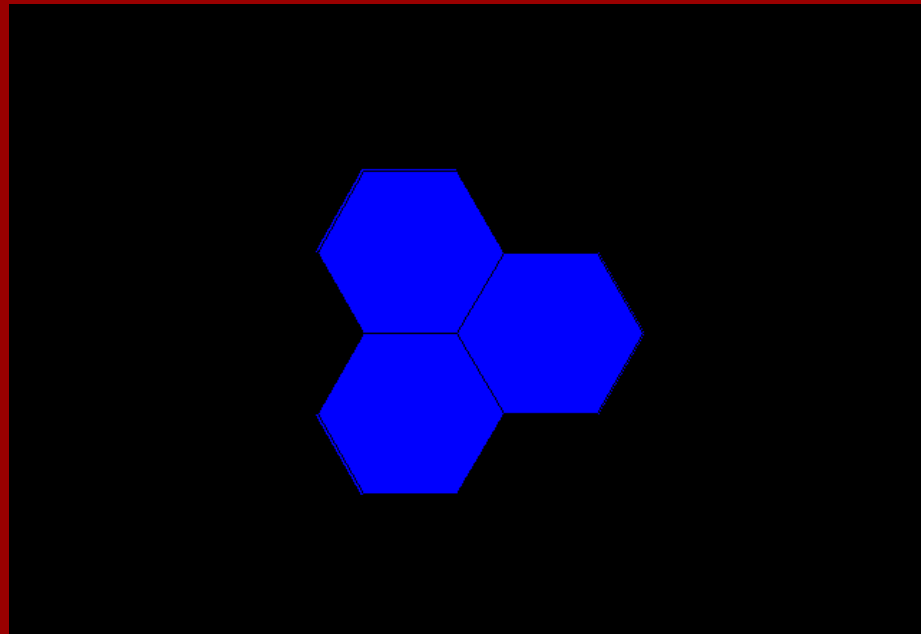
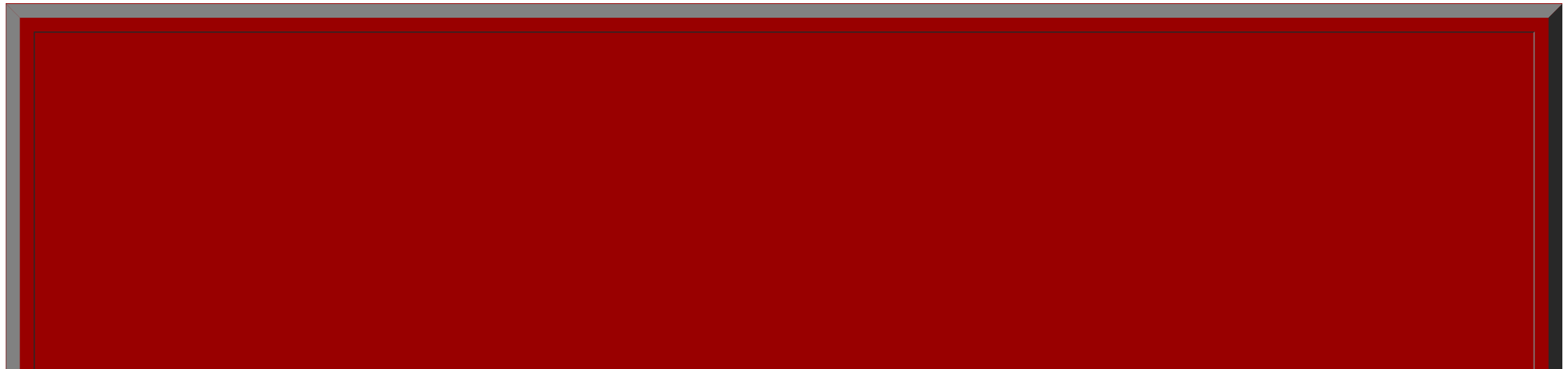
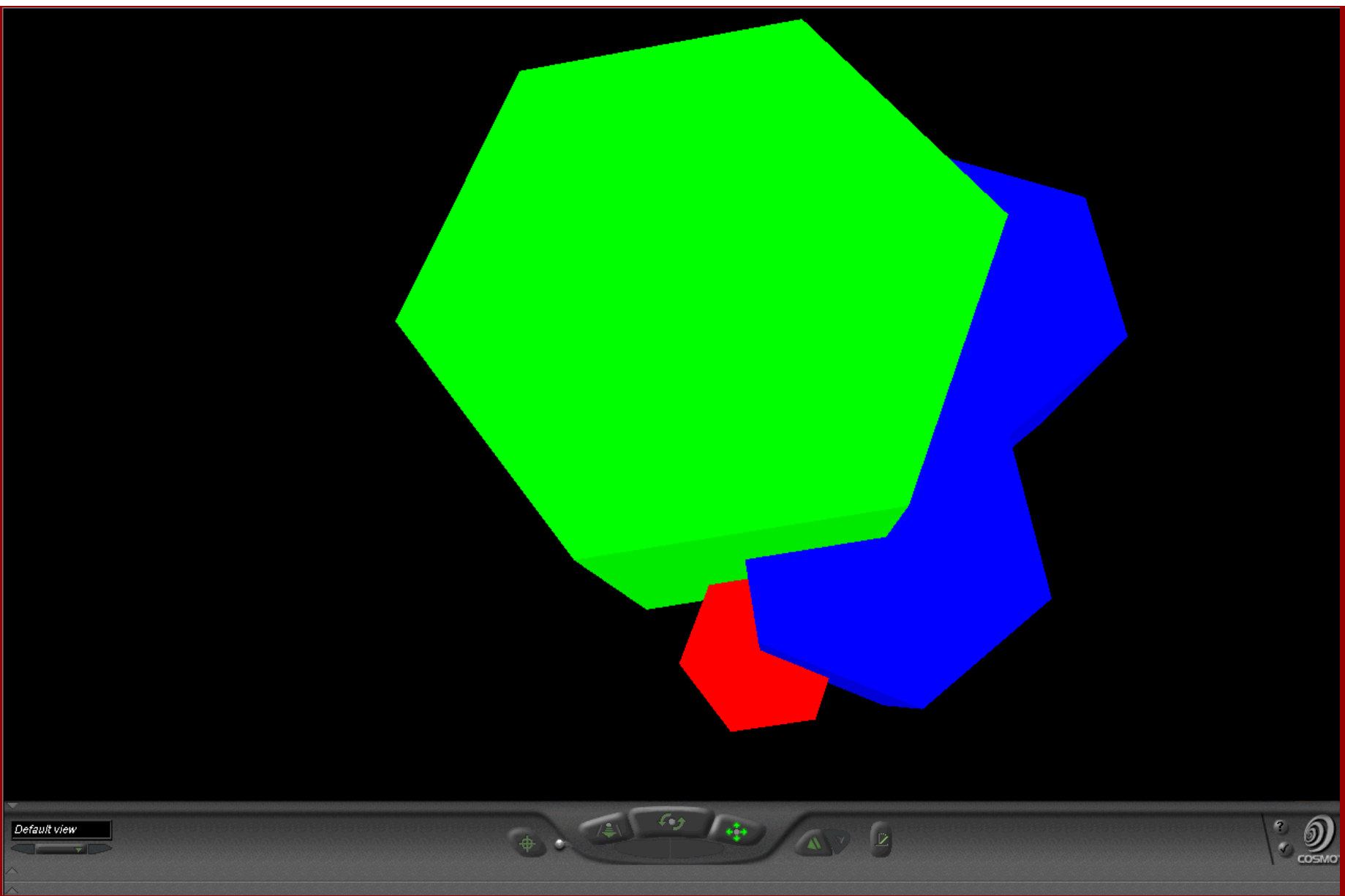


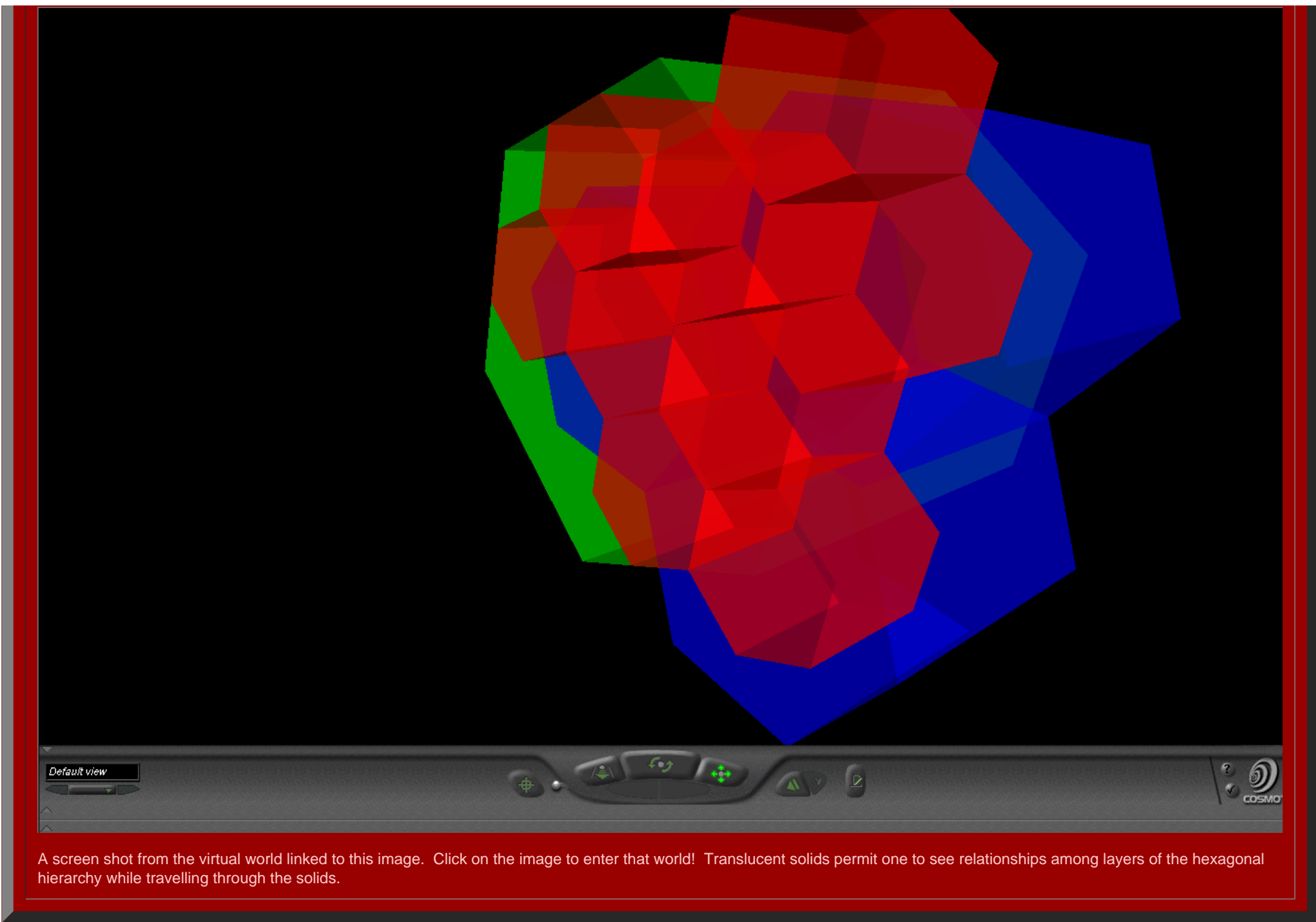
Figure 2.1b. Animated $K=3$ fractal iteration sequence: second transformation using a scaled-down two-sided fractal generator applied successively to sides of the blue polygon generated in Figure 2.1a.

It remains to determine if the polygons generated in Figure 2.1 will in fact fit together to form the broad central place landscape of arbitrary size suggested in Figure 1.5. To that end, we stack the layers generated above using the fractal iteration sequence to form a tile of layers centered on the single polygonal initiator (Figure 2.2). Click [here](#) to see a virtual solid model of the tile with which the reader can interact. Click [here](#) to see a virtual translucent model of the tile with which the reader can interact. Consider the screen captures below from those virtual reality models.



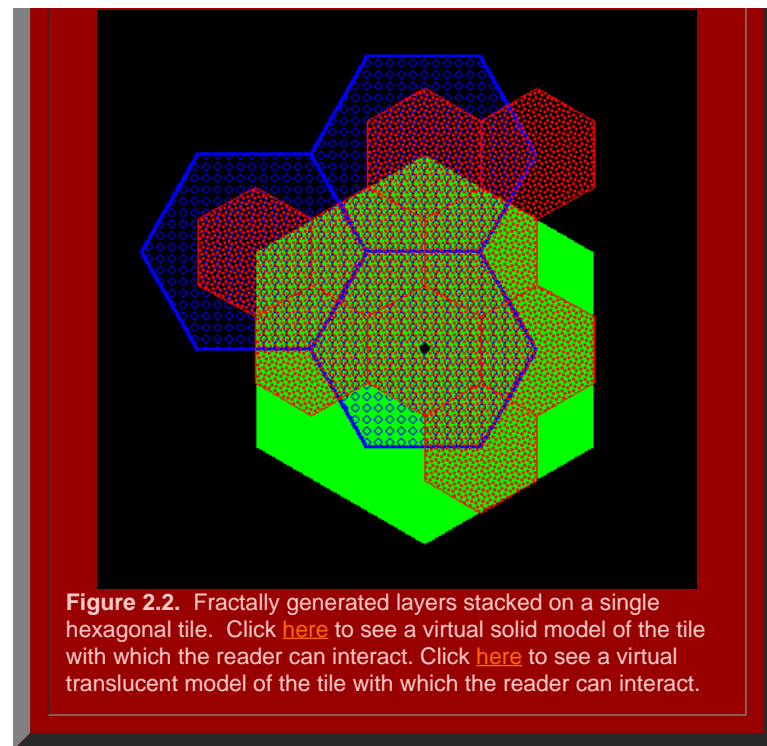


A screen shot from the virtual world linked to this image. Click on the image to enter that world!



A screen shot from the virtual world linked to this image. Click on the image to enter that world! Translucent solids permit one to see relationships among layers of the hexagonal hierarchy while travelling through the solids.





Finally, we tile the plane using the hexagonal initiators, from Figure 2.2 with the attached stack of smaller hexagons, to discover if the superimposed structure also fits together perfectly (Figure 2.3). Hexagonal tiles are used to cover the plane without gaps, as is the case with the sample of green hexagons in Figure 2.3a. The hexagons mesh perfectly to cover the plane (Theorem of [Gauss](#)). In Figure 2.3b, the green outline of the hexagons remains. Each of the solid green hexagons has had the fractal generator above applied and the consequent superimposed blue tiles come into view sequentially in this animation. Again, the fit is exact, as we had hoped it might be. Finally, in Figure 2.3c, the blue outline only is retained from Figure 2.3b (along with the green outline from Figure 2.3a). The final fractally generated layer derived from the blue polygons of Figure 2.3b comes into view in shades of red (or yellow/gold for contrast). The final layer of hexagonal base of unit hexagons appears last. The fit is perfect: each green hexagon contains the equivalent of four blue hexagons and each blue hexagon contains the equivalent of four red hexagons. The fractal generation procedure created exactly the classical central place landscape of [Figure 1.5](#) (return here using the Back button on your browser). As the animation proceeds in Figure 2.3, further layers of the fractally generated hierarchy, attached to the tile in Figure 2.2, come into view illustrating an exact meshing of tiles at all levels to form a $K=3$ hierarchy.



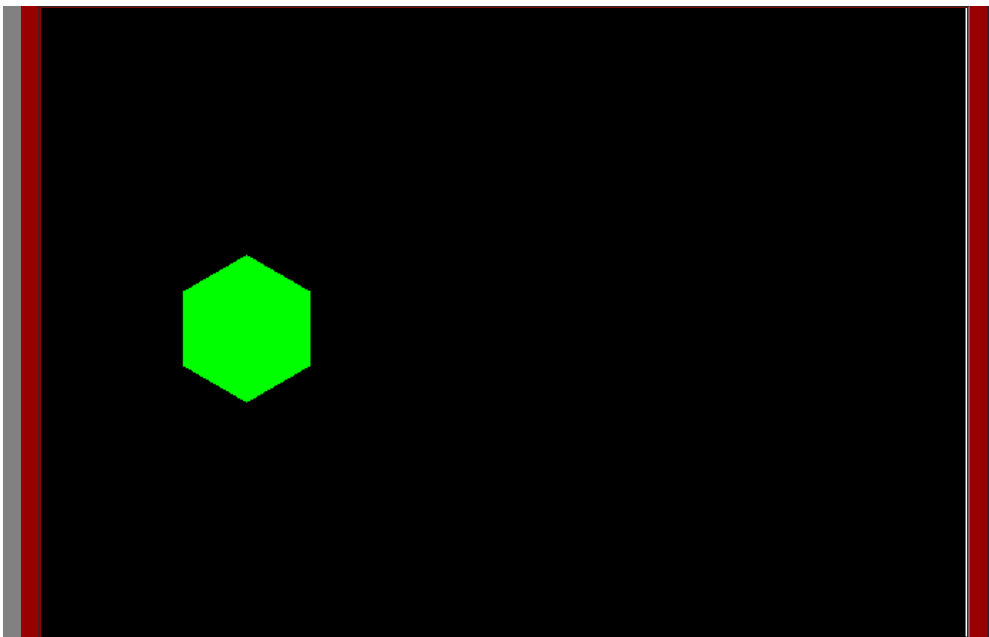


Figure 2.3a. Green layer on tile from Figure 2.2 fits exactly to tile the plane (Theorem of Gauss).

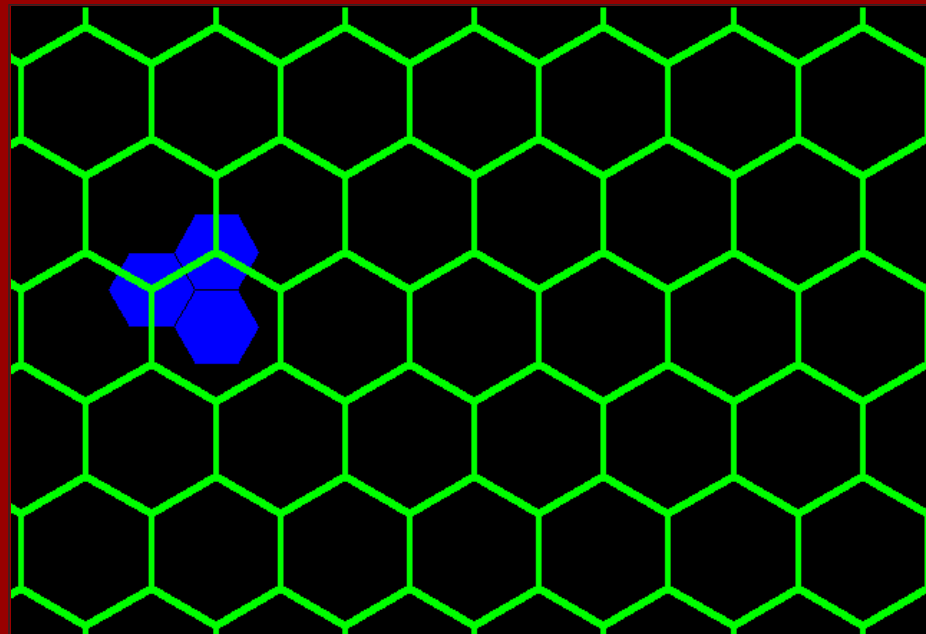
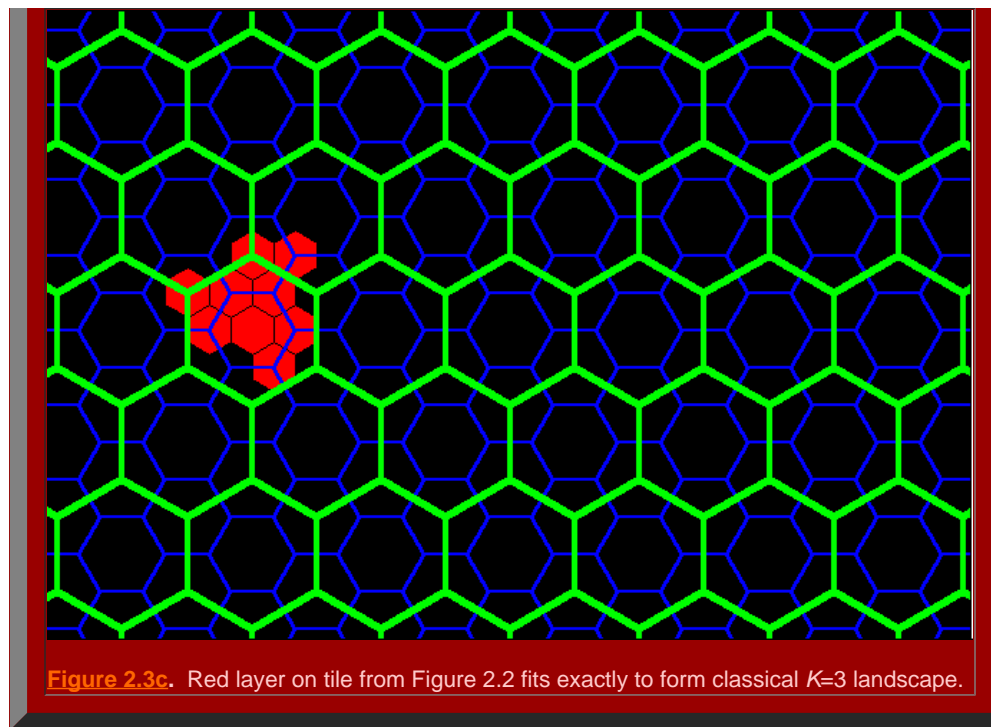


Figure 2.3b. Blue layer on tile from Figure 2.2 fits exactly to form classical $K=3$ landscape.



The $K=4$ Hierarchy

When an hexagonal initiator is chosen and a three-sided generator, with included angles of 120 degrees and shaped in the form of an isosceles trapezoid, is used to make successive replacement of the sides of the hexagon (as in the animated Figure 2.4a), the outline of the next layer of the $K=4$ central place hierarchy is generated (the black lines in Figure 2.4a suggest interior connections). The replacement sequence applies the generator in an alternating pattern to the outside and then to the inside of the initiator. When the original generator is scaled down, with shape preserved, and applied in the outside/inside sequence to the newly formed blue polygon, the next lower level central place $K=4$ hierarchy is formed (as in the animated Figure 2.4b). The second, blue polygon contains four scaled-down hexagons, self-similar to the first hexagon (Figure 2.4a); the red polygon in the animation sequence contains four shapes self-similar to the blue polygon (Figure 2.4b), and 64 (or 4 cubed) hexagons self-similar to the original hexagon (Figure 2.4b). The invariant of 4, in the $K=4$ hierarchy, is replicated in this particular fractal iteration sequence.



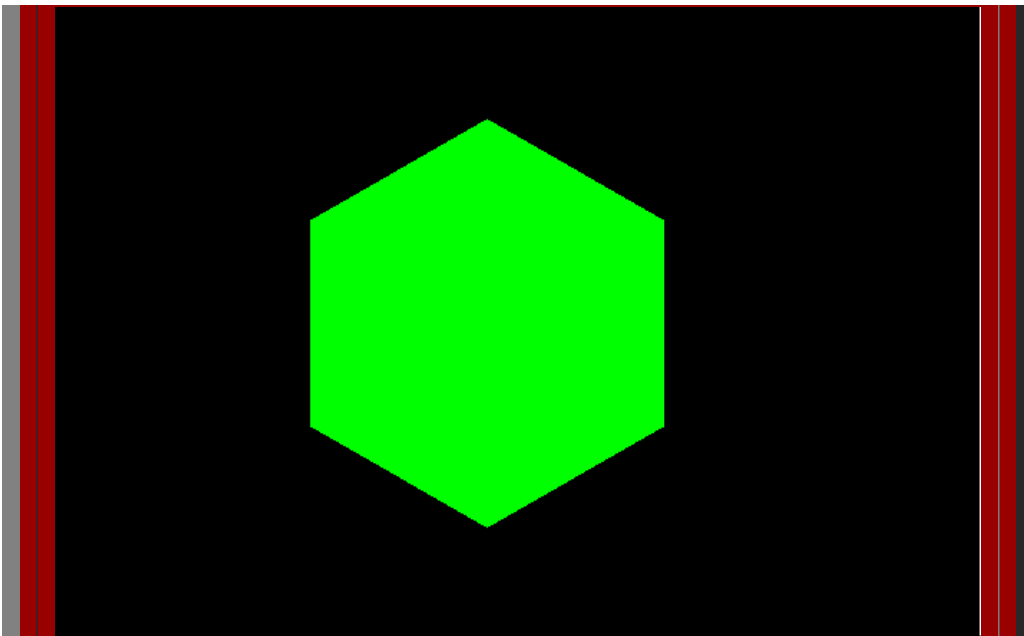


Figure 2.4a. Animated $K=4$ fractal iteration sequence: first transformation using a three-sided fractal generator applied successively to sides of the hexagonal initiator.

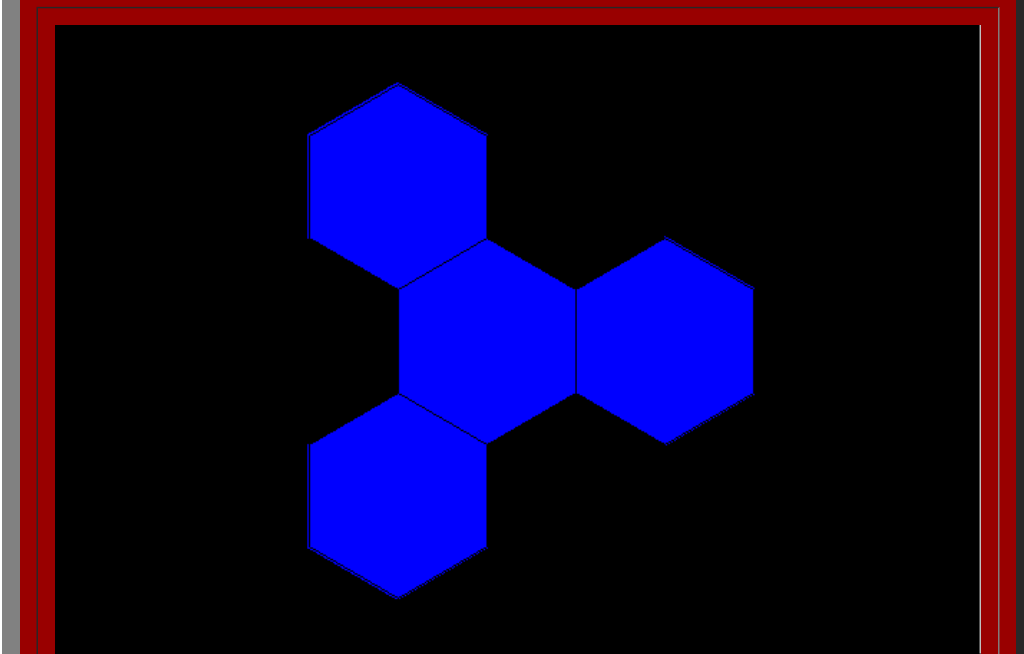
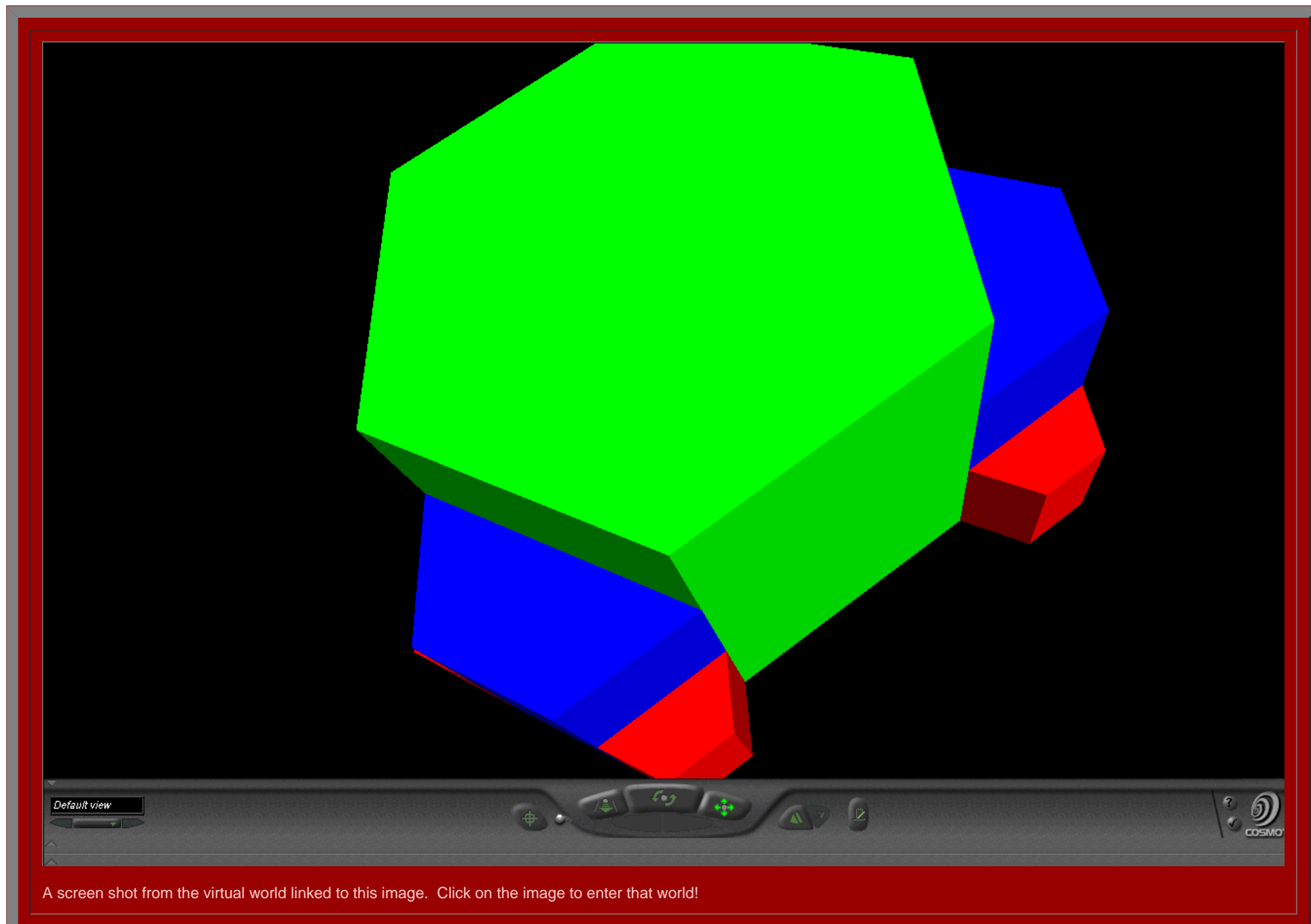
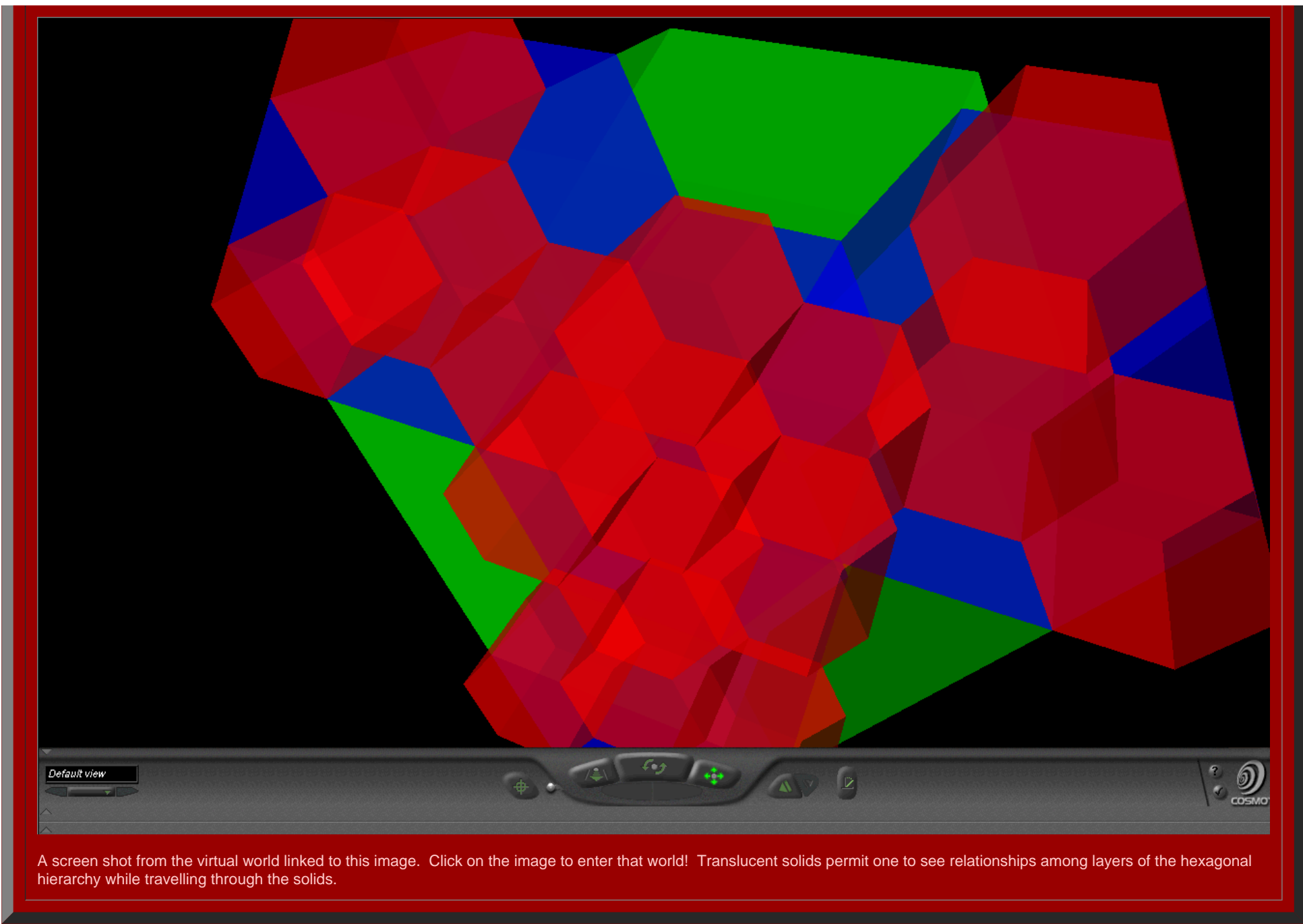


Figure 2.4b. Animated $K=4$ fractal iteration sequence: second transformation using a scaled-down three-sided fractal generator applied successively to sides of the blue polygon generated in Figure 2.4a.

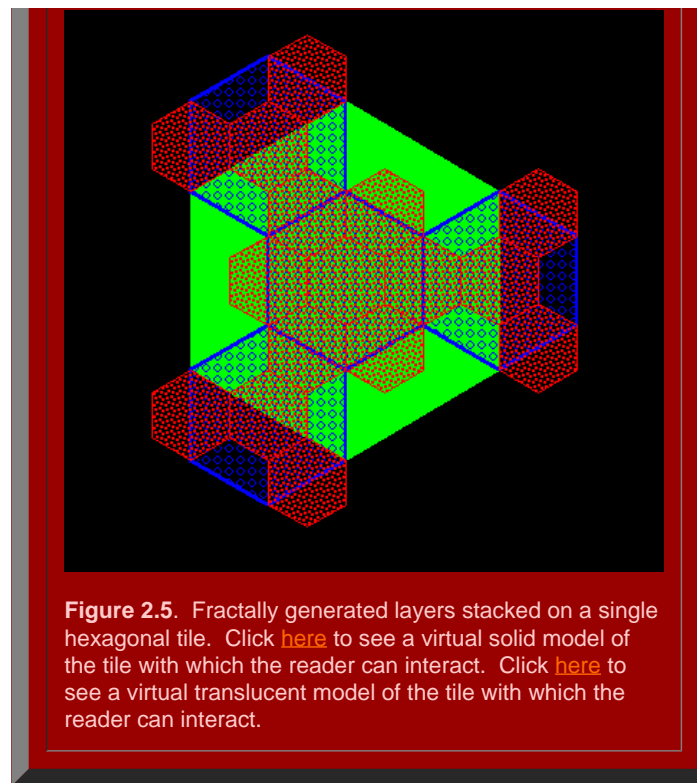
It remains to determine if the polygons generated in Figure 2.4 will in fact fit together to form the broad central place landscape of arbitrary size suggested in [Figure 1.7](#). To that end, we stack the layers generated above using the fractal iteration sequence to form a tile of layers centered on the single polygonal initiator (Figure 2.5). Click [here](#) to see a virtual solid model of the tile with which the reader can interact. Click [here](#) to see a virtual translucent model of the tile with which the reader can interact. Consider the screen captures below from those virtual reality models.



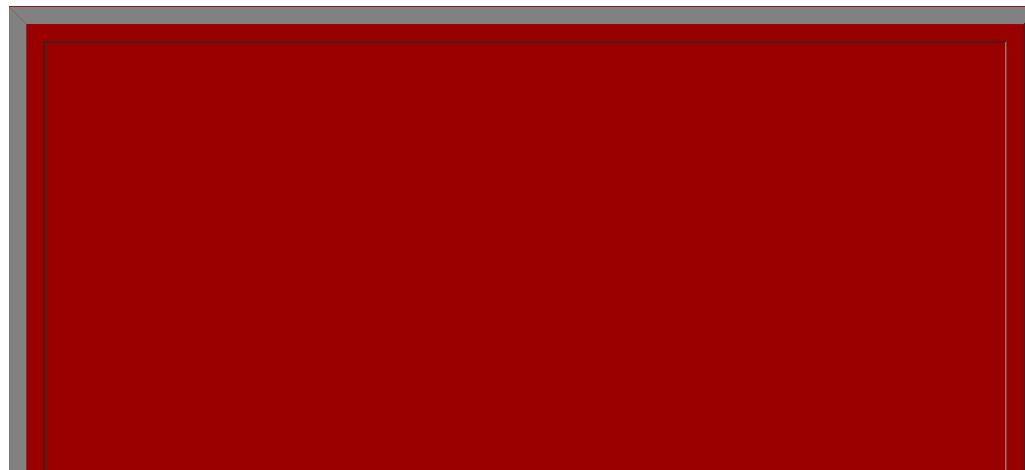


A screen shot from the virtual world linked to this image. Click on the image to enter that world! Translucent solids permit one to see relationships among layers of the hexagonal hierarchy while travelling through the solids.





Finally, we tile the plane using the hexagonal initiators, from Figure 2.5 with the attached stack of smaller hexagons, to discover if the superimposed structure also fits together perfectly (Figure 2.6). Hexagonal tiles are used to cover the plane without gaps, as is the case with the sample of green hexagons in Figure 2.6a. The hexagons mesh perfectly to cover the plane (Theorem of [Gauss](#)). In Figure 2.6b, the green outline of the hexagons remains. Each of the solid green hexagons has had the fractal generator above applied and the consequent superimposed blue tiles come into view sequentially in this animation. Again, the fit is exact, as we had hoped it might be. Finally, in Figure 2.6c, the blue outline only is retained from Figure 2.6b (along with the green outline from Figure 2.6a). The final fractally generated layer derived from the blue polygons of Figure 2.6b comes into view in shades of red (or yellow/gold for contrast). The final layer of hexagonal base of unit hexagons appears last. The fit is perfect: each green hexagon contains the equivalent of four blue hexagons and each blue hexagon contains the equivalent of four red hexagons. The fractal generation procedure created exactly the classical central place landscape of [Figure 1.7](#) (return here using the Back button on your browser). As the animation proceeds in Figure 2.6, further layers of the fractally generated hierarchy, attached to the tile in Figure 2.5, come into view illustrating an exact meshing of tiles at all levels to form a $K=4$ hierarchy.



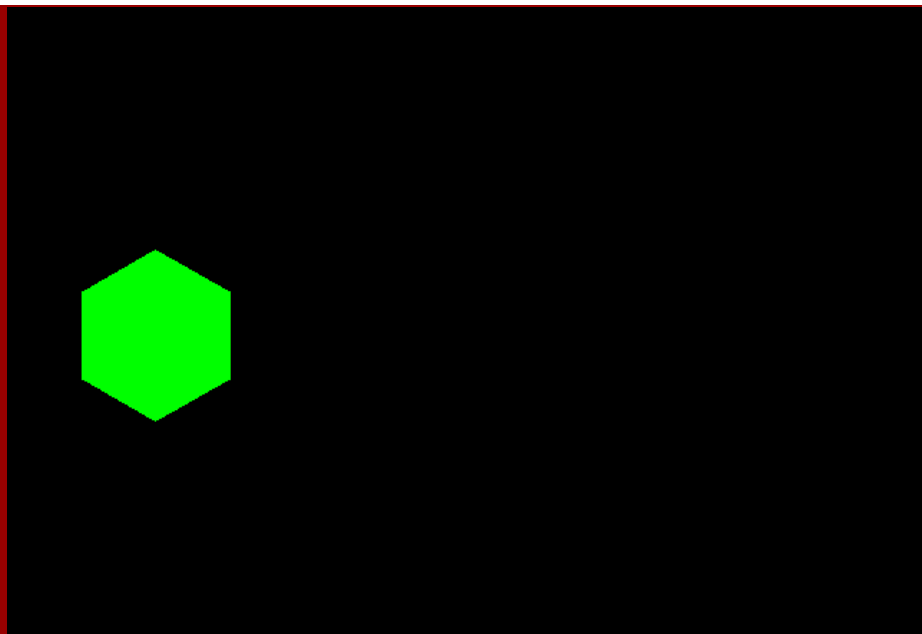


Figure 2.6a. Green layer on tile from Figure 2.5 fits exactly to tile the plane (Theorem of Gauss).

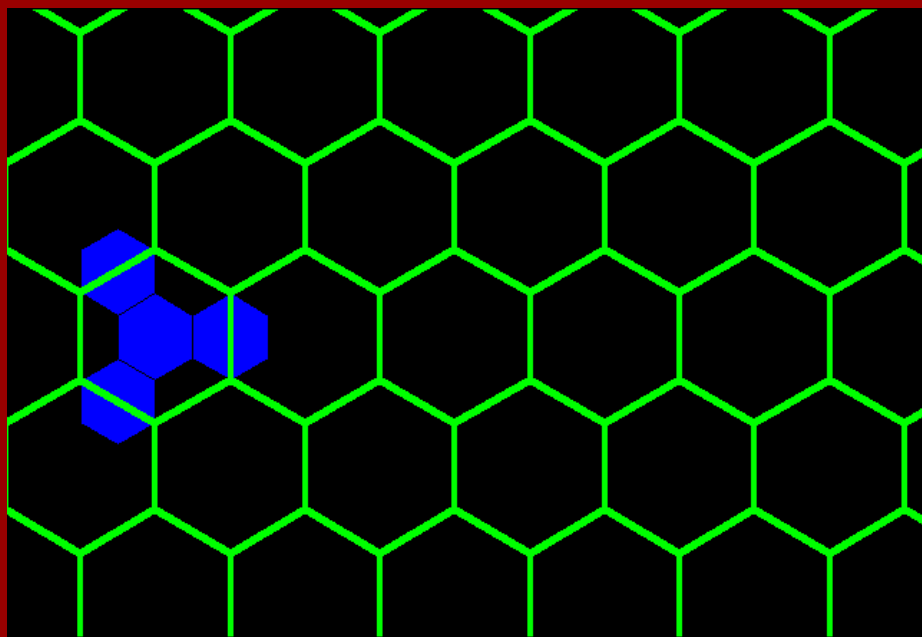
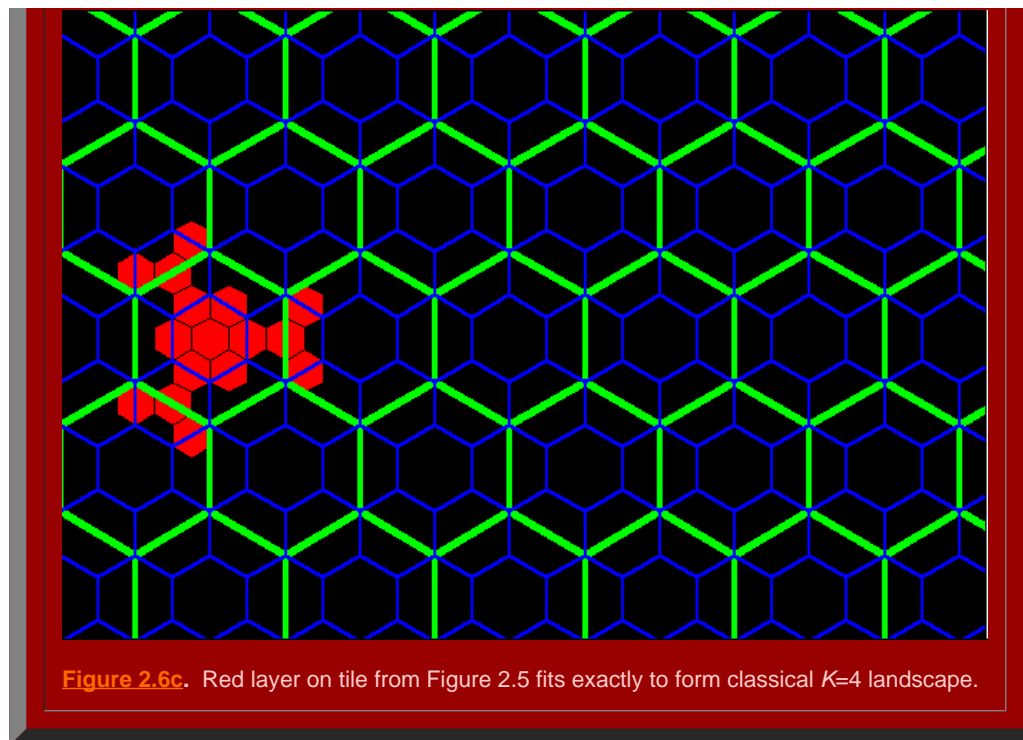


Figure 2.6b. Blue layer on tile from Figure 2.5 fits exactly to form classical $K=4$ landscape.



The $K=7$ Hierarchy

When an hexagonal initiator is chosen and a three-sided generator, with included angles of 120 degrees and shaped in a zig-zag form, is used to make successive replacement of the sides of the hexagon (as in the animated Figure 2.7a), the outline of the next layer of the $K=7$ central place hierarchy is generated (the black lines in Figure 2.7a suggest interior connections). The replacement sequence applies the generator in an alternating pattern to the outside and then to the inside of the initiator. When the original generator is scaled down, with shape preserved, and applied in the outside/inside sequence to the newly formed blue polygon, the next lower level central place $K=7$ hierarchy is formed (as in the animated Figure 2.7b). The second, blue polygon contains seven scaled-down hexagons, self-similar to the first hexagon (Figure 2.7a); the red polygon in the animation sequence contains seven shapes self-similar to the blue polygon (Figure 2.7b), and 343 (or 7 cubed) hexagons self-similar to the original hexagon (Figure 2.7b). The invariant of 7, in the $K=7$ hierarchy, is replicated in this particular fractal iteration sequence.



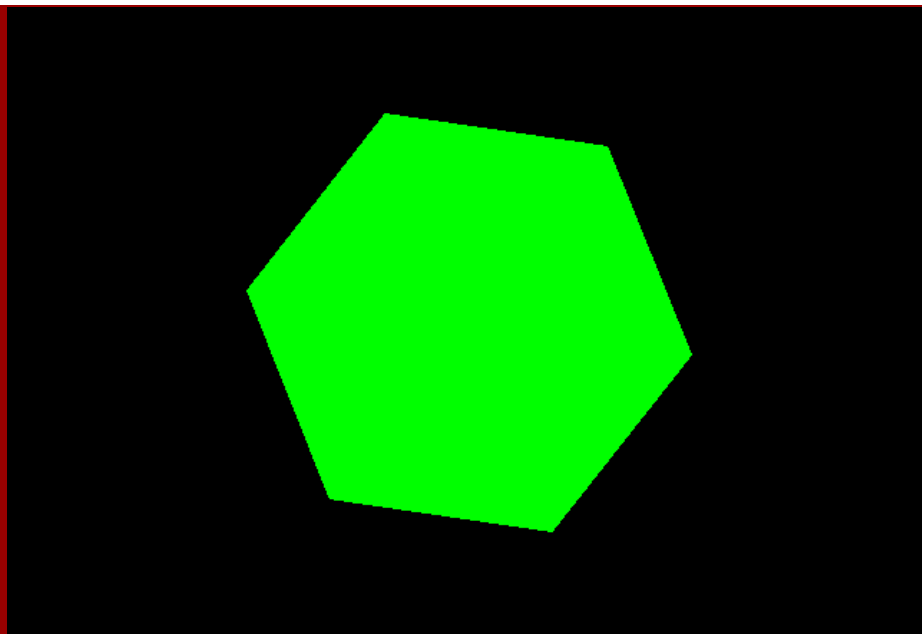


Figure 2.7a. Animated $K=7$ fractal iteration sequence: first transformation using a three-sided fractal generator applied successively to sides of the hexagonal initiator.

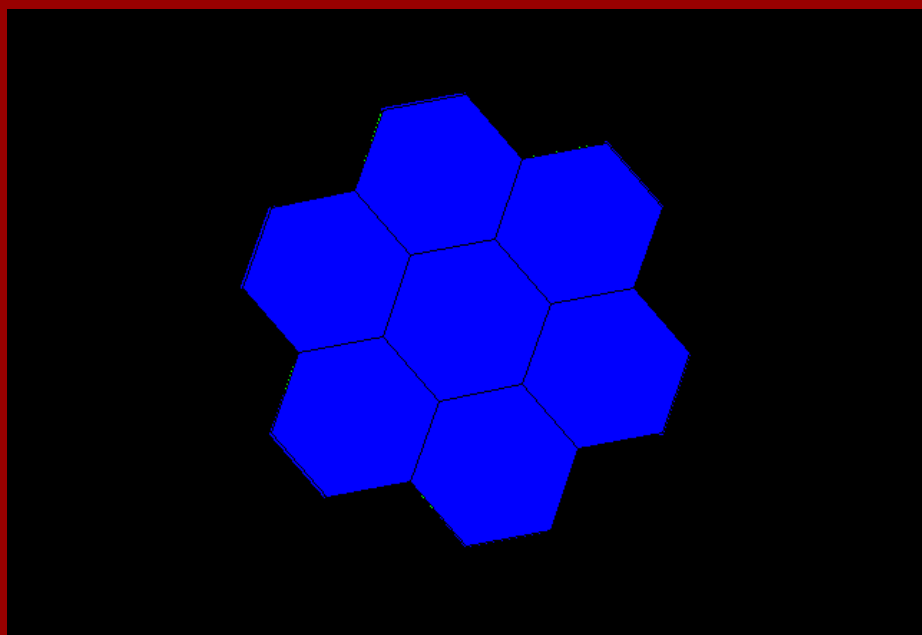
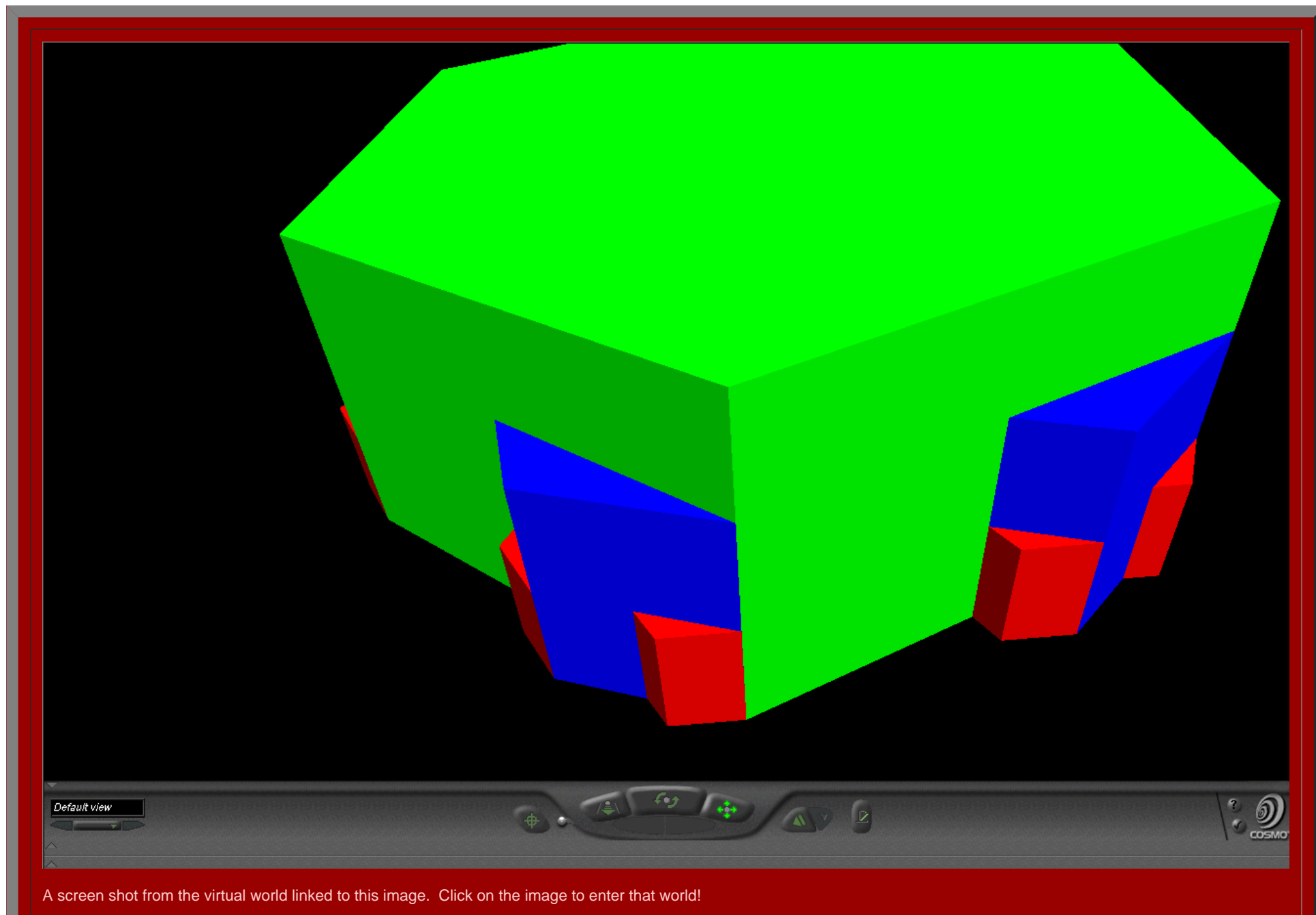
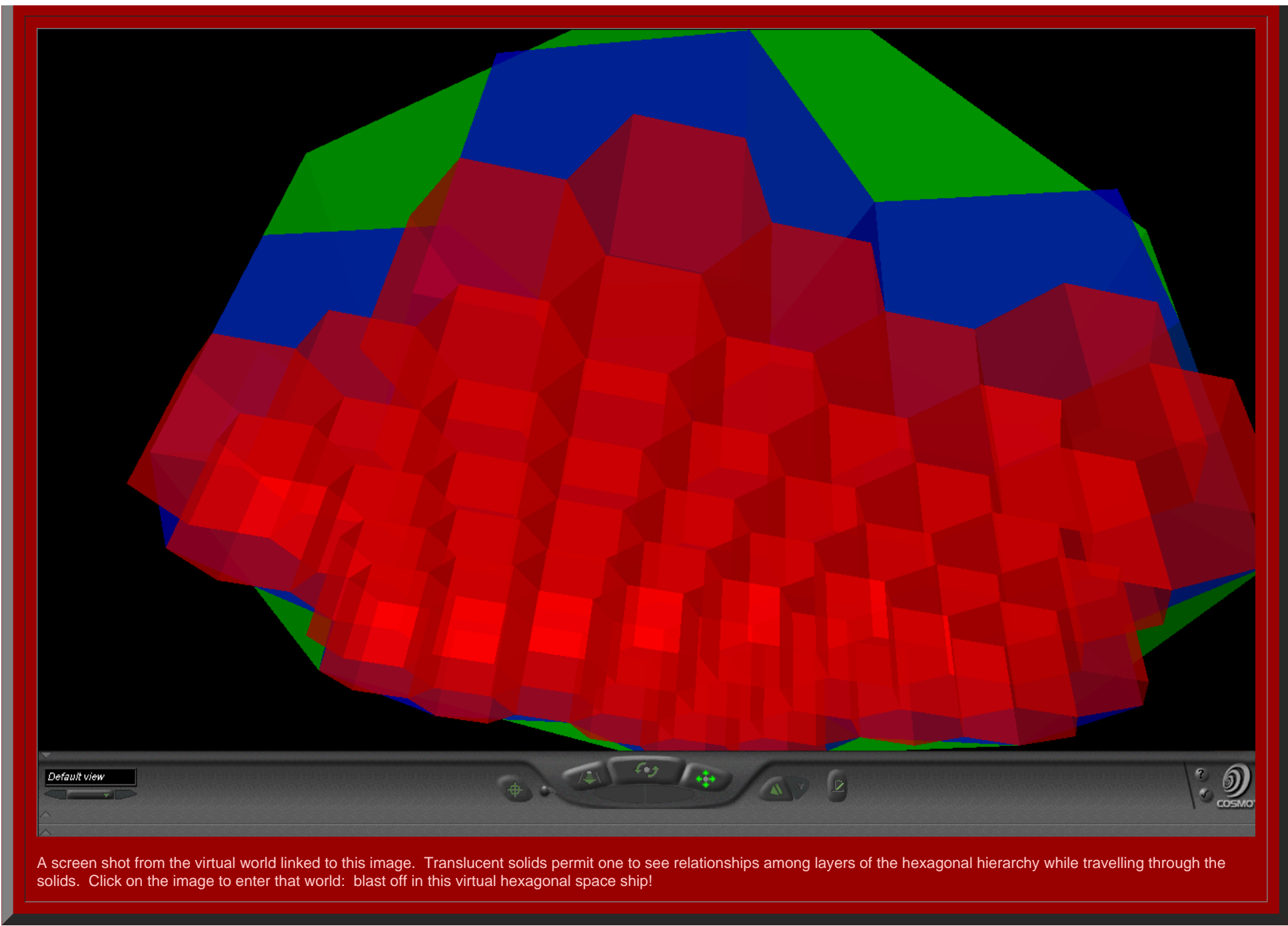


Figure 2.7b. Animated $K=7$ fractal iteration sequence: second transformation using a scaled-down three-sided fractal generator applied successively to sides of the blue polygon generated in Figure 2.7a.

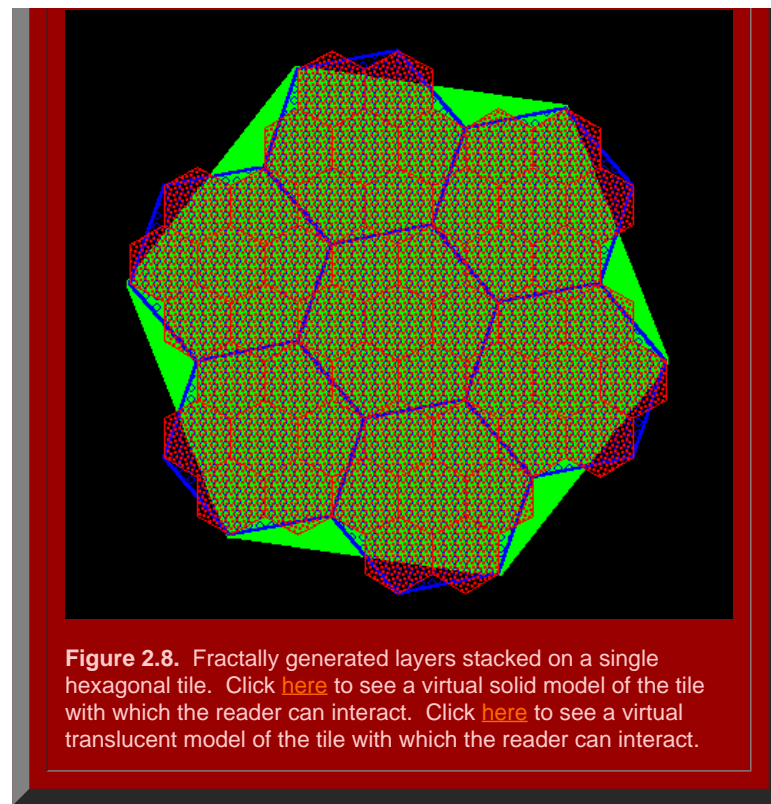
It remains to determine if the polygons generated in Figure 2.7 will in fact fit together to form the broad central place landscape of arbitrary size suggested in [Figure 1.9](#). To that end, we stack the layers generated above using the fractal iteration sequence to form a tile of layers centered on the single polygonal initiator (Figure 2.8). Click [here](#) to see a virtual solid model of the tile with which the reader can interact. Click [here](#) to see a virtual translucent model of the tile with which the reader can interact. Consider the screen captures below from those virtual reality models.





A screen shot from the virtual world linked to this image. Translucent solids permit one to see relationships among layers of the hexagonal hierarchy while travelling through the solids. Click on the image to enter that world: blast off in this virtual hexagonal space ship!





Finally, we tile the plane using the hexagonal initiators, from Figure 2.8 with the attached stack of smaller hexagons, to discover if the superimposed structure also fits together perfectly (Figure 2.9). Hexagonal tiles are used to cover the plane without gaps, as is the case with the sample of green hexagons in Figure 2.9a. The hexagons mesh perfectly to cover the plane (Theorem of [Gauss](#)). In Figure 2.9b, the green outline of the hexagons remains. Each of the solid green hexagons has had the fractal generator above applied and the consequent superimposed blue tiles come into view sequentially in this animation. Again, the fit is exact, as we had hoped it might be. Finally, in Figure 2.9c, the blue outline only is retained from Figure 2.9b (along with the green outline from Figure 2.9a). The final fractally generated layer derived from the blue polygons of Figure 2.9b comes into view in shades of red (or yellow/gold for contrast). The final layer of hexagonal base of unit hexagons appears last. The fit is perfect: each green hexagon contains the equivalent of four blue hexagons and each blue hexagon contains the equivalent of four red hexagons. The fractal generation procedure created exactly the classical central place landscape of [Figure 1.9](#) (return here using the Back button on your browser). As the animation proceeds in Figure 2.9, further layers of the fractally generated hierarchy, attached to the tile in Figure 2.8, come into view illustrating an exact meshing of tiles at all levels to form a $K=3$ hierarchy.



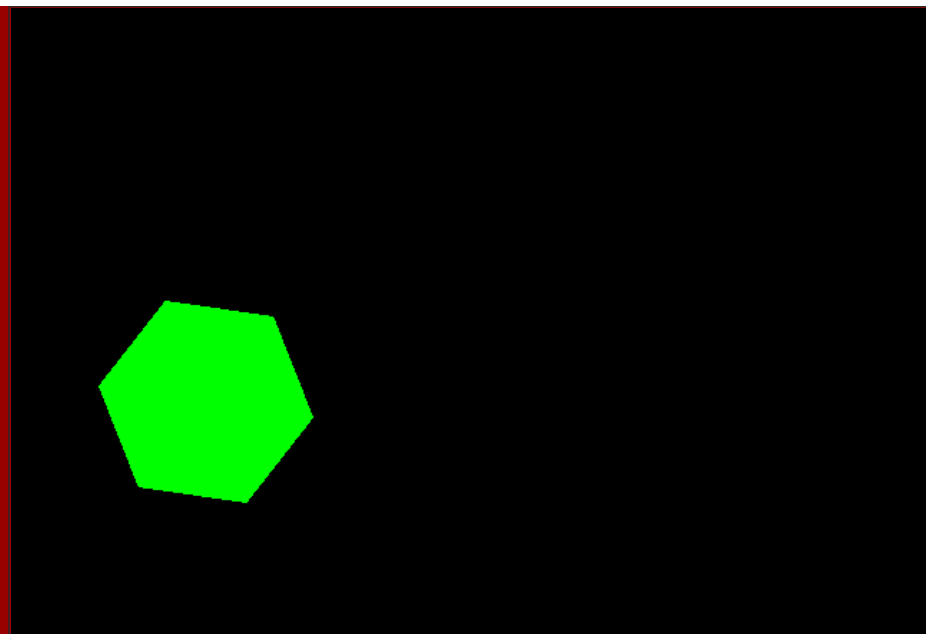


Figure 2.9a. Green layer on tile from Figure 2.8 fits exactly to tile the plane (Theorem of Gauss).

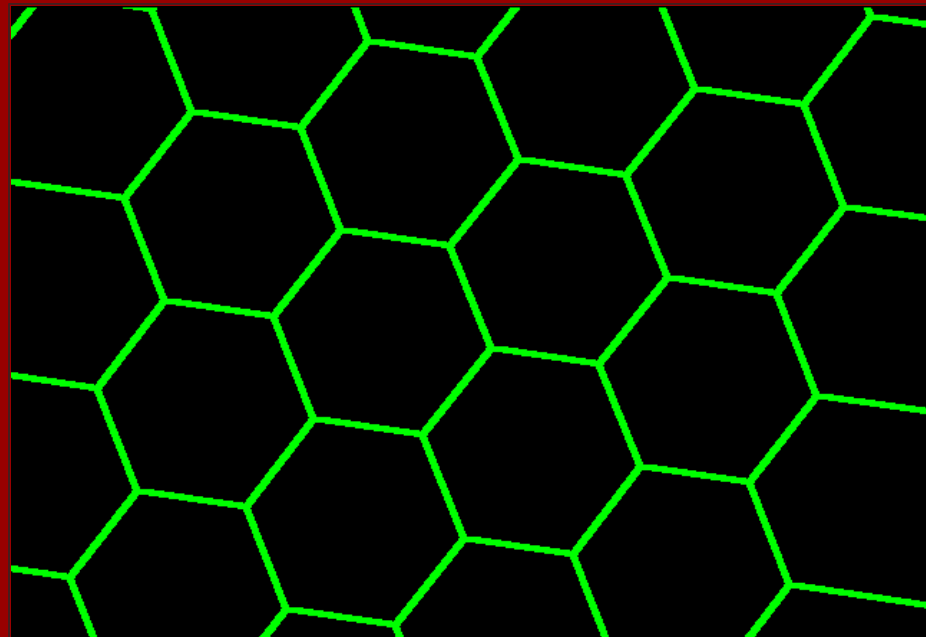


Figure 2.9b. Blue layer on tile from Figure 2.8 fits exactly to form classical $K=7$ landscape.

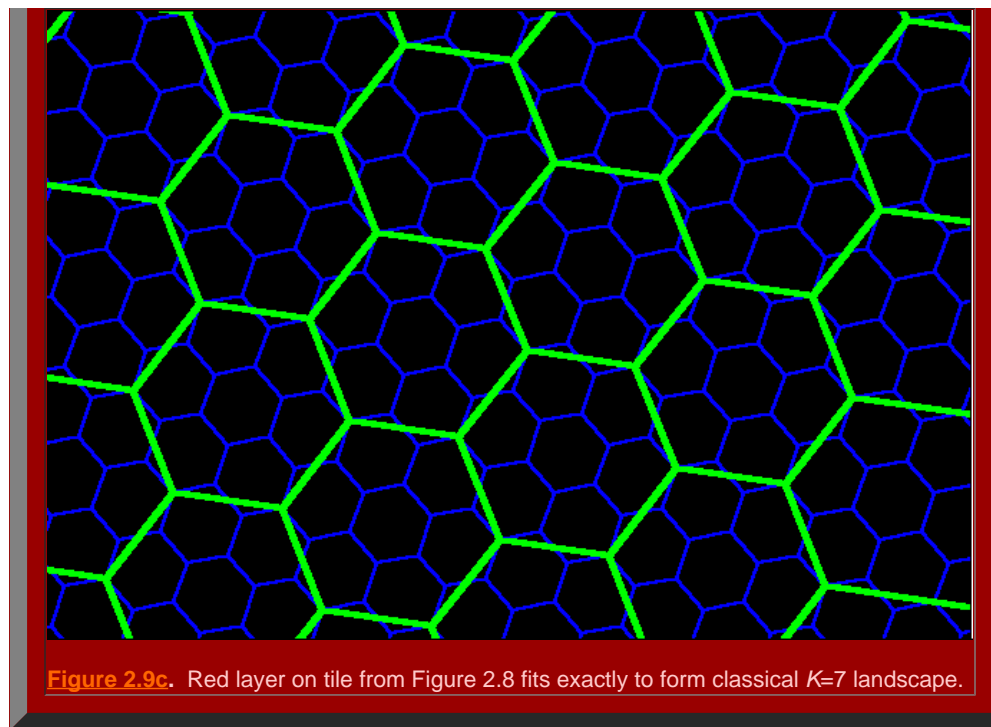


Figure 2.9c. Red layer on tile from Figure 2.8 fits exactly to form classical $K=7$ landscape.

Thus, the complex mechanics of classical central place theory come alive as a single dynamic system when viewed using fractal geometry. The fit is exact.

The added role of the fractional dimension

A fractal iteration sequence, such as those above but carried out infinitely, might be thought to increase the extent to which a line "fills" space. [Mandelbrot](#) captures this notion of space-filling with the concept of fractional dimension (hence "fractal"). He uses Hausdorff-Besicovitch dimension to measure the enduring mathematical concept of space-filling (see bibliography). We employ Mandelbrot's formulation for fractional dimension D as, $D = \log(\text{number of generator sides}) / \log(\text{square root of } K)$. Thus, the following values for fractally-generated central place hierarchies emerge:

- $K=3$, $D = \log 2 / \log \sqrt{3} = 1.2618595$
- $K=4$, $D = \log 3 / \log 2 = 1.5849625$
- $K=7$, $D = \log 3 / \log \sqrt{7} = 1.1291501$

The idea with the space-filling is to pick an arbitrary point in the bounded space containing the curve. Place a circle of arbitrarily small radius around that point. Does that circle contain a point on the curve as the fractal iteration sequence goes to infinity? If that is the case for any point, then the curve is said to fill space and have dimension 2. If not, then there are holes or gaps (perhaps of infinitesimal size) in the space and the curve fails to fill space completely and has fractional dimension between 1 and 2 (as a sort of Swiss cheese with holes). Thus, the $K=4$ fractal iteration sequence, if permitted to repeat infinitely, has the highest fractional dimension of these three: this curve gets "closer" to arbitrary points in space than do the lines of the other hierarchies, as one might hope a hierarchy interpreted as a "transportation" hierarchy would. The fractional dimension of the fractal iteration sequence corresponds to the intuitive notion of scholars over time as to interpretation: another benchmark or field test of theory. The $K=7$ fractal iteration sequence, if permitted to repeat infinitely, has the lowest fractional dimension of these three, keeping control from the center optimized and hence supporting the "administrative" or "separation" interpretation often given to the classical $K=7$ hierarchy. Finally, the $K=3$ falls between: marketing needs greater spatial penetration than does administration but less than does transportation. Here, the fit between classical interpretation and fractal calculation is reasonable (one could never say "exact" because the terms "marketing," "transportation," and "administrative" are inexact terms themselves).

What is difficult with fractals is to visualize the infinite process. Graphic color display, including three dimensional display, offers exciting strategies for visualization. Very quickly, however, it becomes difficult to draw the fine lines required by repeating the process at more and more local scales: physical lines have width. Electronic lines can be controlled and made finer than can pen lines, but eventually the line-width limits the capability to produce graphic images. Eventually, the mind's eye must take over and extrapolate the visual infinite process.

Another possibility might be to draw on the other human senses to aid in that extrapolation. Thus, Figure 2.10 shows figures generated by [Fractal Music 1.9](#); click on the images and hear the associated music. The left figure shows the cellular automata base generated by default--it is bilaterally symmetric about a central vertical line and was generated using a symmetrically

arranged initiator string of 64 digits ranging in value from 0 to 7 (one for each tone). The next figure, $K=3$, shows the cellular automata diagram (another sort of "bubble foam" in appearance) generated using the value for the fractional dimension of the $K=3$ hexagonal hierarchy carried out to 64 decimal places as the initiator string for the music. The next figure, $K=4$, shows the cellular automata diagram generated using the value for the fractional dimension of the $K=4$ hexagonal hierarchy carried out to 64 decimal places as the initiator string for the music. The final figure, $K=7$, shows the cellular automata diagram generated using the value for the fractional dimension of the $K=7$ hexagonal hierarchy carried out to 64 decimal places as the initiator string for the music. Click on each figure to hear the music. Each musical sequence, of over 1000 steps, was created from the default base, changing only the initiator string, so that the fractional dimension is what operates on a "seed" value of basic notes. The listener should hear the basic pattern in all characterizations: great symmetry in the base value; abrupt changes of state in the $K=3$ value; a smoother filling of musical space in the $K=4$ music; and, gaps in the $K=7$ musical characterization derived from the $K=7$ fractional dimension. The bilaterally symmetric bubble-foam figure associated with the base has been skewed by each of the K -values, as has the corresponding music. Thus, we extend visualization from two dimensional graphical images to three dimensional graphical images to the mind's eye, and finally, to the mind's ear: capturing hierarchical pattern through 1000 steps or more is easy in the musical clips. Such characterization offers added capability to those of us with all of our senses that are functional: for those with limited visual sensory function, it offers a way to an auditory "visualization" of the beauty of geometry.

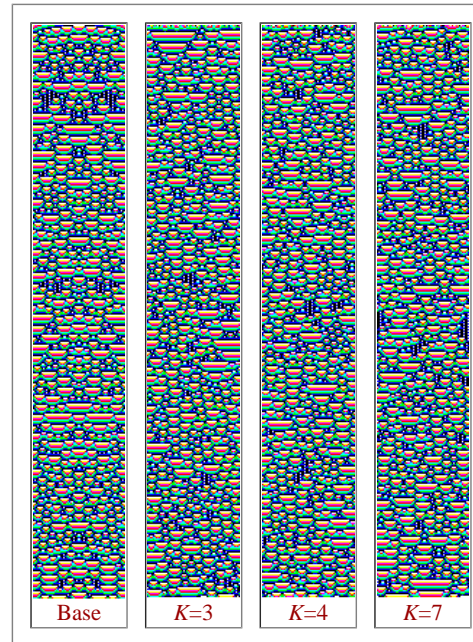


Figure 2.10. Fractal music connection. Click on the images generated by the fractional dimensions of the hexagonal hierarchies; compare these to the default base created by the software.

In subsequent chapters, we offer mathematical proof of these ideas and extensions of these ideas into new realms. The classical is used for alignment of new with the old: a strategy useful in a wide range of theoretical and applied research.

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Spatial Synthesis: Centrality and Hierarchy, Volume I, Book 1.
Sandra Lach Arlinghaus and William Charles Arlinghaus

Chapter 3

Number Theory Background

Primes and Divisibility

Even in ancient times, people were fascinated by the idea of divisibility. This book is interested primarily in positive integers, just as Euclid was.

Definition 3.1. A positive integer a is said to be a divisor of another positive integer b if $b=ac$ for some positive integer c . (If a is a divisor of b , we write $a|b$ and say "a divides b," or "b is a multiple of a").

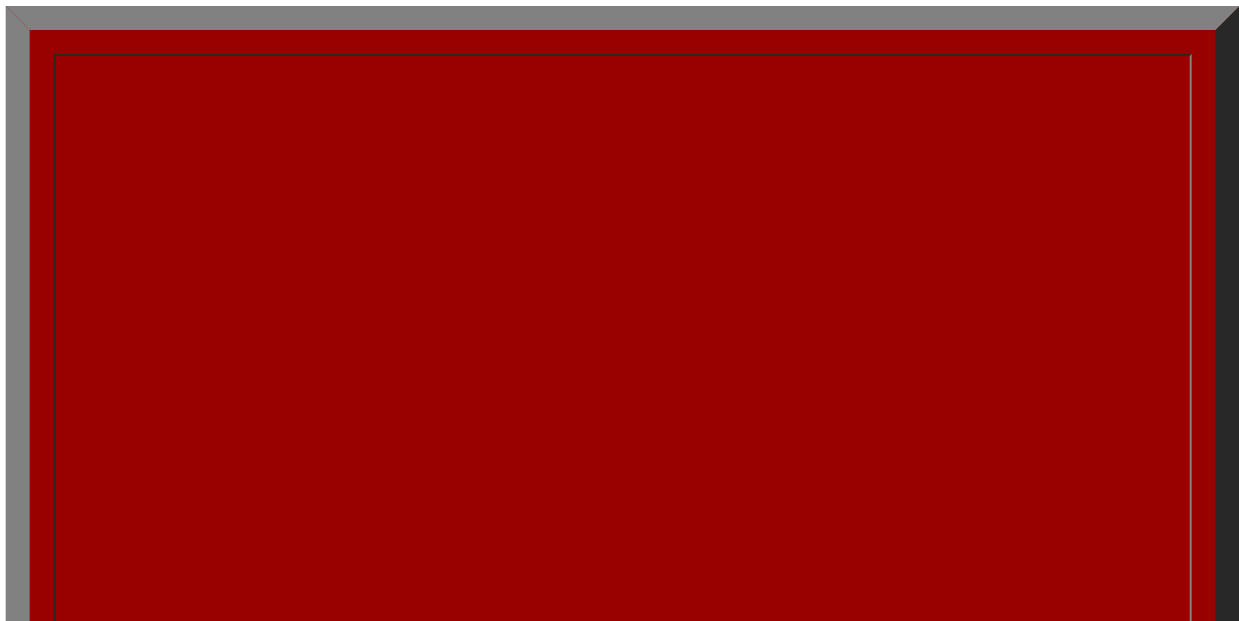
Definition 3.2. If an integer $p>1$ has only 1 and p as divisors, it is called prime (for example 2, 3, 4, 7, and 11 are primes).

Two elementary facts help illuminate the place of primes among the integers. First, if p_1, p_2, \dots, p_n are primes, then $N=1+p_1p_2\dots p_n$ is not divisible by any of p_1, p_2, \dots, p_n (the remainder when N is divided by any p_i is 1). Thus either N is prime or N has a prime divisor other than the p_i . Thus,

Theorem 3.3. (Euclid). There are infinitely many primes.

Also, if $n>1$ is not prime (such an integer is called composite), n must have a prime divisor $\leq \sqrt{n}$, since it must have a divisor $\leq \sqrt{n}$ ($n = ab$ implies $a \leq \sqrt{n}$ or $b \leq \sqrt{n}$), and that divisor is either prime or has a prime divisor $\leq \sqrt{n}$. Thus, one can determine if a number $\leq \sqrt{n}$ is prime by eliminating all multiples of the primes $\leq \sqrt{n}$. This method is known as the [Sieve of Eratosthenes](#) (Figure 3.1).

For example, all primes $< 169=13^2$ can be determined by crossing out the multiples of 2, 3, 4, 7, and 11. Indeed, given that every even integer > 2 is composite (since divisible by 2) and every integer >5 is composite (since divisible by 5), one need only consider integers with last digit 1, 3, 7, or 9 and cross out the multiples of 3, 7, and 11. That process is illustrated in the animated Figure 3.1.



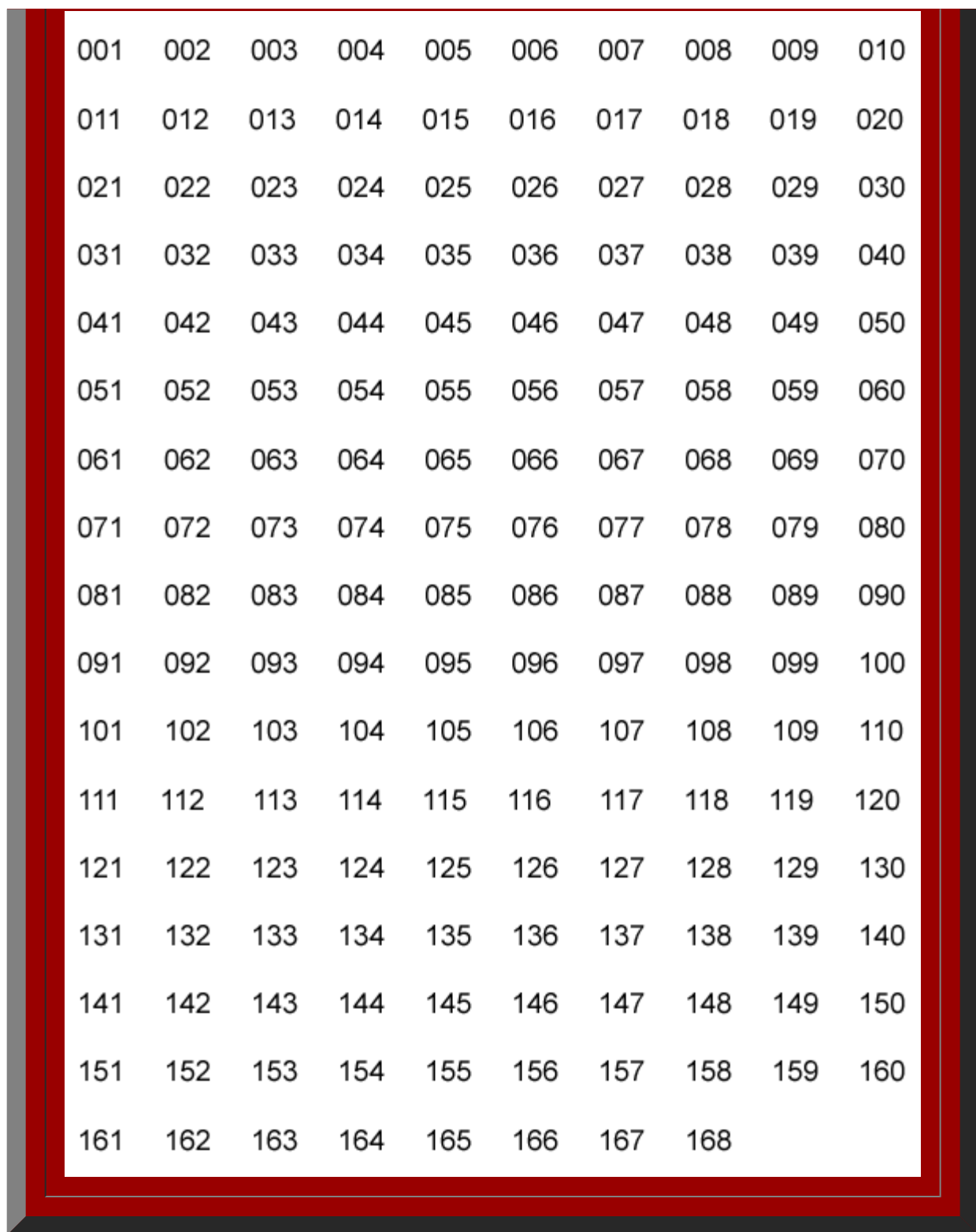


Figure 3.1. Animated Sieve of Eratosthenes. Primes are sifted out that are less than $169 = 13^2$. Thus, only multiples of 2, 3, 5, 7, and 11 need be eliminated. The animation shows the successive elimination of these multiples to reveal the set of all primes less than 169. Click [here](#) to see a movie in which the reader can control the animation rate in order to study pattern.

The primes are the building blocks of the integers, since every positive integer can be written uniquely as a product of primes ([Fundamental Theorem of Arithmetic](#)). This uniqueness extends only to the primes involved and how many times they are involved; for example, the fact that $12 = 2 \cdot 2 \cdot 3 = 2 \cdot 3 \cdot 2 = 3 \cdot 2 \cdot 2$ does not violate uniqueness. By convention, we say that 1 is a product of no primes. It is the desire for unique

factorization that led to the avoidance of 1 as a prime; obviously, 1 can be included in a factorization of a number as often as desired.

Take a [side trip](#) to an application that employs a strategy that is abstractly similar to the method of Eratosthenes. It does so, however, in the urban setting of downtown Ann Arbor, Michigan.

The Euclidean Algorithm

Almost as important as knowing what divisors an integer has is knowing what divisors it shares with other integers. For this allows the consideration of equations relating one integer to another.

Definition 3.4. Let a, b be two positive integers. The greatest common divisor (a, b) of these two integers is the largest positive integer d such that $d|a$ and $d|b$.

For example $(12, 16) = 4$ since $4|12$ $4|16$, and no greater divisor of 12 (6, 12 are possibilities) is a divisor of 16.

The greatest common divisor is useful in reducing fractions to lowest terms, since if a/b is a fraction $[a/(a,b)]/[b/(a,b)]$ is in lowest terms.

For example, $12/16 = [12/4]/[16/4] = 3/4$.

Definition 3.5. The above definition can be extended to any integer as follows

1. if a and b are integers, neither of which is equal to 0, then $(a, b) = (|a|, |b|)$
2. if $a \neq 0$, then $(a, 0) = |a|$ ($(0,0)$ is not defined).

If the prime factorizations of a and b are readily available, it is easy to find (a, b) .

For example, if $a = 360 = 2^3 \cdot 3^2 \cdot 5$ and $b = 756 = 2^2 \cdot 3^3 \cdot 7$, then $(a,b) = 2^2 \cdot 3^2 = 36$, since the highest power of 2 which is a factor of (a, b) is the lowest power of 2 in the factorizations of a and b (i.e. the 2^2 in b).

Unfortunately, it is not always obvious what the prime factorizations of a and b are when the problem of finding (a, b) occurs. A method that is relatively quick and always successful is called the [Euclidean Algorithm](#). It depends on some easy properties of divisibility, familiar from grade school arithmetic and high school algebra.

Suppose a and b are positive integers, $a > b$. Then there are integers q (quotient) and r (remainder) such that $a = bq + r$ and $0 \leq r < b$ (these were first encountered when learning long division in the fourth grade).

For example, $756 = 360(2) + 36$; in fourth grade terms, if we want to compute $756/360$, the quotient is 2, the remainder 36.

This division algorithm is closely related to the idea of greatest common divisor, as the following mini-theorem demonstrates.

Mini-Theorem 3.6. Suppose a, b, r are positive integers with $a = bq + r$, $0 < r < b < a$. Then $(a,b) = (b, r)$.

Proof: It is only necessary to show that a, b, r share exactly the same divisors, since then they certainly have the same GREATEST common divisor.

1. First, suppose $n|a$ and $n|b$, say $a = nx$ and $b = ny$. Then $r = a - bq = nx - nyq = n(x - yq)$, so $n|r$.
2. Suppose $n|b$ and $n|r$, say $b = ny$ and $r = nz$. Then $a = bq + r = nyq + nz = n(yq + z)$, so $n|a$.

Mini-Fact 3.7. If $a = bq$, then $(a, b) = b$.

These two small facts are all we need to prove the famous

Euclidean Algorithm 3.8. Suppose a, b are positive integers with $a > b$. Suppose further that

$$\begin{array}{ll} a = bq_0 + r_1 & 0 < r_1 < b \\ b = r_1q_1 + r_2 & 0 < r_2 < r_1 \\ r_1 = r_2q_2 + r_3 & 0 < r_3 < r_2 \\ \dots & \\ r_{n-1} = r_nq_n + r_{n+1} & 0 < r_{n+1} < r_n \\ r_n = r_{n+1}q_{n+1} & \end{array}$$

Then $(a, b) = r_{n+1}$, the last non-zero remainder in the process.

Proof: First note that the process defined above is a finite one, since each remainder is smaller than the previous one, with the result that eventually, the integer remainder must become 0. ([Computer scientists](#) might be interested in [Lamé's Theorem](#), which proves that this process can take at most $5n$ steps, where n is the number of decimal digits in b .)

By the mini-fact, $(r_n, r_{n+1}) = r_{n+1}$. But, by the mini-theorem, $(a, b) = (b, r_1) = (r_1, r_2) = \dots = (r_{n-1}, r_n) = (r_n, r_{n+1})$. Therefore, $(a, b) = r_{n+1}$.

For example,

$$\begin{array}{l} 756 = 360(2) + 36 \\ 360 = 36(10) \end{array}$$

so that $(756, 360) = 36$

It is always possible to express (a, b) as $ma + nb$ for some integers m and n . That this is true can be seen from the Euclidean Algorithm as follows:

$$(a, b) = r_{n+1} = r_{n-1} - r_nq_n = r_{n-1} - (r_{n-2} - r_{n-1}q_{n-1})q_n = \dots$$

That is, one can work backwards through the equations until (a, b) is expressed in terms of a and b . But the computations appear quite difficult, and it appears that all the quotients and remainders are needed. But the computation can be done more easily if each remainder is expressed in terms of a and b as the Euclidean Algorithm is carried out. Note that

$$\begin{array}{l} a = 1(a) + 0(b) \\ b = 0(a) + 1(b) \end{array}$$

Then since

$$\begin{array}{l} r_1 = a - bq_0, \\ a = 1(a) + 0(b) \\ -q_0b = -q_0(a) - q_0(1)(b) \end{array}$$

Subtracting

$$r_1 = a - q_0b = 1a - q_0b$$

This process can be continued for each remainder.

In fact, the a and b can be left understood and only their coefficients kept track of. A detailed example follows.

Example. Find $d = (6888, 792)$, and find m, n such that $6888m + 792n = d$.

First computation $6888 = 792(8) + 552$.

Notice

$$6888 = 1(6888) + 0(792)$$

$$792 = 0(6888) + 1(792)$$

$$552 = 6888 - 8(792) = [1 - 8(0)]6888 + [0 - 8(1)]$$

$$(792) = 1(6888) - 8(792)$$

so we retain the following information

$$\begin{array}{r} 6888 \quad 1 \quad 0 \\ 792 \quad 0 \quad 1 \\ 6888 = 792(8) + 552 \quad 552 \quad 1 \quad -8 \end{array}$$

noting that $1 - 8(0) = 1$ and $0 - 8(1) = -8$ so row 3 above is obtained by subtracting 8(row 2) from row 1.

Second computation $792 = 552(1) + 240$.

Notice

$$240 = 792 - 2(552)$$

$$= [0 - 1(1)]6888 + [1 - 1(-8)](792) = -1(6888) + 9(792)$$

so we retain the following information

$$\begin{array}{r} 6888 \quad 1 \quad 0 \\ 792 \quad 0 \quad 1 \\ 6888 = 792(8) + 552 \quad 552 \quad 1 \quad -8 \\ 792 = 552(1) + 240 \quad 240 \quad -1 \quad 9 \end{array}$$

noting row 4 = row 2 - 1(row 3) since 1 is the quotient in the second computation.

Full computation

$$\begin{array}{r} 6888 \quad 1 \quad 0 \\ 792 \quad 0 \quad 1 \\ 6888 = 792(8) + 552 \quad 552 \quad 1 \quad -8 \\ 792 = 552(1) + 240 \quad 240 \quad -1 \quad 9 \\ 552 = 240(2) + 72 \quad 72 \quad 3 \quad -26 \\ 240 = 72(3) + 24 \quad 24 \quad -10 \quad 87 \\ 72 = 24(3) \end{array}$$

In each case, an **arbitrary row** is obtained by subtracting the **quotient times the row above** from **the row two rows above**.

The result: $(6888, 792) = 24$, $24 = -10(6888) + 87(792)$.

This example is illustrated in the animation in Figure 3.2.

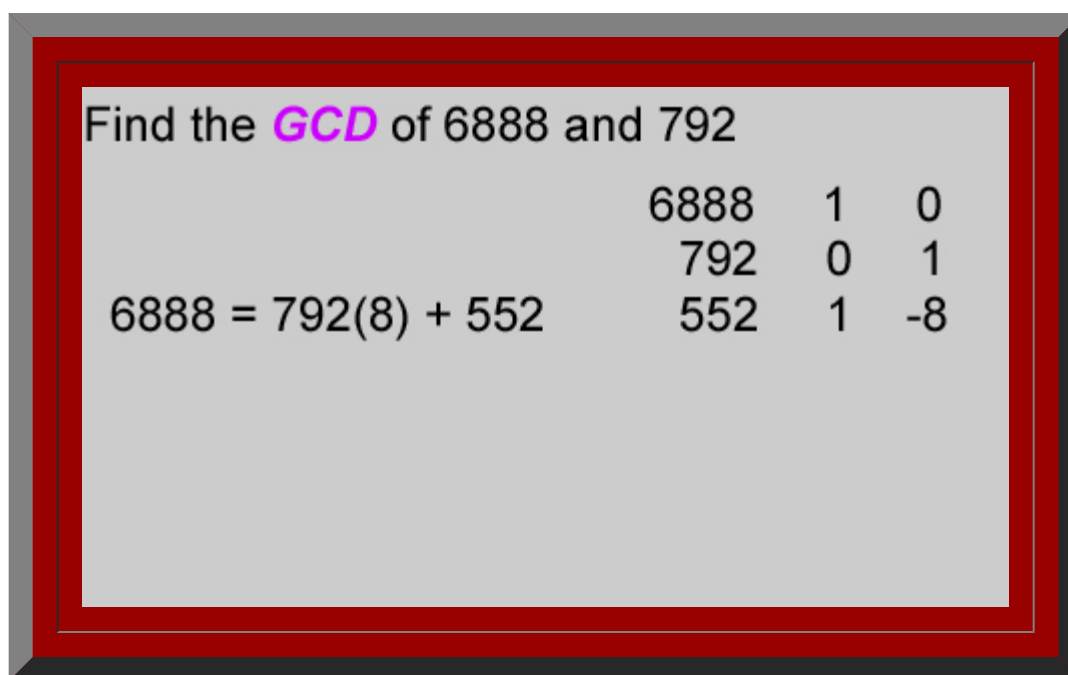


Figure 3.2. Animation of Euclidean Algorithm application. Click [here](#) to see a movie in which the reader can control the animation rate in order to study pattern.

The procedure of this section will be of great significance in solving congruences in the next section.

Number-theoretic congruence

One of the most powerful tools of number theory is the notion of congruence, which partitions the integers into finite sets of related integers.

Definition 3.9. Two integers x and y are said to be congruent modulo m (a positive integer) if m is a divisor of $x - y$. This is written $x \equiv y \pmod{m}$.

The most common place the everyday world uses congruence, albeit not consciously, is in telling time. Any time y a multiple of 12 hours after a time x is called by the same time as x .

For example, 60 hours after 3 o'clock, it is once more 3 o'clock, since $60 + 3 \equiv 3 \pmod{12}$.

Indeed, it is quite common to use a set of small representatives of all the possibilities modulo m . In telling time, 1, 2, ..., 12 are used for all possibilities. Military time uses 0, 1, ..., 23 for the hours in a day modulo 24. Mathematicians usually use 0, 1, ..., $m-1$ when they want representatives for the classes of numbers which are congruent modulo m , for the following reason.

Theorem 3.10. If $a = mb + r$, $0 \leq r < m$, then $a \equiv r \pmod{m}$.

Proof: $a - r = mb$, so m is a divisor of $a - r$. Thus the natural representative of a number modulo m is its remainder when divided by m .

In fact, any set of m integers, none of which is congruent to any of the others modulo m , is called a complete residue system modulo m . No doubt this name comes from thinking of remainders as residues (what's left over) after division by m . It is easy to create an addition and multiplication for these residues.

Theorem 3.11. Suppose $x \equiv y \pmod{m}$ and $s \equiv t \pmod{m}$. Then $x + s \equiv y + t \pmod{m}$ and $xs \equiv yt \pmod{m}$.

Proof: Suppose $x - y = am$ and $s - t = bm$. Then $(x + s) - (y + t) = (x - y) + (s - t) = am + bm = (a + b)m$. So $x + s \equiv y + t \pmod{m}$. Also $xs - yt = (xs - xt) + (xt - yt) = x(s - t) + (x - y)t = xbm + amt = m(xb + at)$. So $xs \equiv yt \pmod{m}$.

Telling time is an obvious example of the addition part of this theorem. For instance, 5 hours after 9 o'clock comes 2 o'clock, since $9 + 5 \equiv 2 \pmod{12}$.

Linear congruences

The first type of equation to investigate is the linear congruence $ax \equiv b \pmod{m}$. One needed fact is an easy consequence of the Euclidean Algorithm.

Lemma 3.12. If $a \mid bc$ and $(a, b) = 1$, then $a \mid c$.

Proof: Suppose $bc = ax$. Because $(a, b) = 1$, there are integers m, n such that $1 = ma + nb$. Then $c = cma + cnb = cma + nax = a(cm + nx)$. Thus $a \mid c$.

This allows proof of a limited cancellation theorem. In ordinary algebra, if $ax = ay$, then $x = y$. Such a general theorem is impossible for congruences.

For example, $6(4) \equiv 6(2) \pmod{12}$, but 4 is not congruent to 2 mod 12.

However, if $(a, m) = 1$, cancellation is still possible.

Theorem 3.13. If $ax \equiv ay \pmod{m}$ and $(a, m) = 1$, then $x \equiv y \pmod{m}$.

Proof: Since $ax \equiv ay \pmod{m}$, $a(x - y) \equiv 0 \pmod{m}$. Thus $m \mid a(x - y)$. But, since $(a, m) = 1$, Lemma 3.12 assures $m \mid (x - y)$. Therefore, $x \equiv y \pmod{m}$.

This enables a complete analysis of $ax \equiv b \pmod{m}$ if $(a, m) = 1$.

Theorem 3.14. Suppose $(a, m) = 1$. Then

- $ax \equiv 1 \pmod{m}$ has a unique solution $x \equiv t \pmod{m}$
- $ax \equiv b \pmod{m}$ has a unique solution $x \equiv tb \pmod{m}$.

Proof:

- Since $(a, m) = 1$, there are integers s, t such that $ms + at = 1$, so $at - 1 = ms$. Therefore $at \equiv 1 \pmod{m}$. This is the only solution, since by **Theorem 3.13** $at \equiv ay \pmod{m}$ implies $x \equiv y \pmod{m}$.
- To solve $ax \equiv b \pmod{m}$, multiply through by this number t . Therefore $t(ax) \equiv tb \pmod{m}$. Since $ta \equiv 1 \pmod{m}$, this gives $x \equiv tb \pmod{m}$. As before, this solution is unique.

The solution of $ax \equiv 1 \pmod{m}$ is sometimes called the inverse a^{-1} of a modulo m , analogous to the fact that $a^{-1} = 1/a$ is the multiplicative inverse of a in ordinary arithmetic. Of course, a natural question arises: what happens if $(a, m) \neq 1$. There are two cases: $(a, m) \mid b$ and $(a, m) \nmid b$.

Theorem 3.15. Suppose $d = (a, m) \nmid b$. Then $ax \equiv b \pmod{m}$ has no solution.

Proof: If $ax \equiv b \pmod{m}$, then $ax - b = my$ for some integer y . Thus $b = ax - my$. But since $d \mid a$ and $d \mid m$, this means $d \mid b$, contrary to the theorem's hypothesis. (Note: $a = ds, m = dt$ means $b = dsx - dty = d(sx - ty)$.)

Theorem 3.16. Suppose $d = (a, m) \mid b$. Then $ax \equiv b \pmod{m}$ has a unique solution modulo $m \mid d$ and d solutions modulo m .

Proof: Let $b = dr, a = ds, m = dt$. Then $ax \equiv b \pmod{m}$ is and only if $ax - b = my$ for some integer y . Substituting for a, b, c $dsx - ds = dty$. Canceling $xs - r = ty$ or $sx \equiv r \pmod{t}$. By [Theorem 3.14](#), this has a unique solution modulo $t = m/d$. Call this solution A (so $sA \equiv r \pmod{t}$). Then, $A, A + t, \dots, A + (d-1)t$ are the d solutions (modulo m). Note that these are all congruent modulo t but incongruent modulo m , and notice that since $sA - r = tB$ for some B

$$\begin{aligned} s(A+kt) - r &= t(B+sk), k=0, 1, \dots, d-1 \\ ds(A+kt) - dr &= dt(B+sk), k=0, 1, \dots, d-1 \\ a(A+kt) - b &= m(B+sk), k=0, 1, \dots, d-1 \\ a(A+kt) &\equiv b \pmod{m}, k=0, 1, \dots, d-1 \end{aligned}$$

Fermat's Little Theorem and Euler's Theorem

The ability to solve congruences leads to some interesting results.

Theorem 3.17 (Fermat's Little Theorem) Suppose p is a prime, $(a, p) = 1$. Then $a^{p-1} \equiv 1 \pmod{p}$.

Proof: Consider the integers $a, 2a, 3a, \dots, (p-1)a$. These $p-1$ integers are all incongruent mod p , since by [Theorem 3.13](#) $sa \equiv ta \pmod{p}$ implies $s \equiv t \pmod{p}$. Since none of them is divisible by p (by Lemma 3.12, if $p \mid ka$, then $p \mid k$, which is false). Thus these $p-1$ integers are congruent to the integers $1, 2, \dots, p-1$ in some order. Therefore, $a(2a)\dots(p-1)a \equiv 1(2)\dots(p-1) \pmod{p}$. By [Theorem 3.13](#), cancellation of $2(3)\dots(p-1)$ gives $a^{p-1} \equiv 1 \pmod{p}$.

Fermat's Little Theorem can be used to perform some amazing computations. For example, it can be used to compute the remainder when 3^{2460} is divided by 113, certainly a computation unlikely by direct computation. But [Theorem 3.17](#) assures $3^{112} \equiv 1 \pmod{113}$. Simple division gives $2460 = 112(13) + 4$. Therefore $3^{2460} = 3^{112(13)+4} = (3^{112})^{13} 3^4 \equiv 3^4 \equiv 81 \pmod{113}$. So the remainder when 3^{2460} is divided by 113 is 81.

The situation of [Theorem 3.17](#) can be generalized.

Definition 3.18. Let m be a positive integer. A complete reduced residue system modulo m is the set of numbers obtained from a complete residue system by removing all the integers which have a factor in common with m .

For example, the integers $1, 2, \dots, p-1$ are a reduced residue system modulo a prime p . Also, the integers $1, 3, 7, 11, 13, 17, 19$ for a reduced residue system modulo 20.

Definition 3.19. The Euler ϕ -function (phi-function) $\phi(m)$ (or, $\phi(m)$ in subscripts or superscripts) is the number of integers in a complete reduced residue system modulo m .

For example $\phi(p) = p-1, \phi(20) = 8$.

The Euler ϕ -function has been studied extensively. The interested reader should consult any of the

numerous number theory texts listed in the references. [Fermat's Little Theorem](#) can be generalized as follows:

Theorem 3.20.(Euler's Theorem) Suppose $(a, m) = 1$. Then $a^{\phi(m)} \equiv 1 \pmod{m}$.

Proof: Let $1, x_2, x_3, \dots, x_{\phi(m)}$ be a reduced residue system modulo m . As in [Theorem 3.17](#), $a, ax_2, \dots, ax_{\phi(m)}$ are all incongruent modulo m ; also, since each has no factor in common with m , they form a complete reduced residue system and are congruent to $1, x_2, \dots, x_{\phi(m)}$ in some order. Therefore $a(ax_2) \dots (ax_{\phi(m)}) \equiv x_2 x_3 \dots x_{\phi(m)} \pmod{m}$, so by cancellation $a^{\phi(m)} \equiv 1 \pmod{m}$.

Again, by way of example, it is easy to compute the remainder when 13^{8059} is divided by 20. By Euler's Theorem, $13^{\phi(20)} = 13^8 \equiv 13^3 \pmod{20}$. But $13^2 = 169 \equiv 9 \pmod{20}$. Therefore $13^3 = 13^2(13) \equiv 9(13) \equiv 117 \equiv 17 \pmod{20}$. Thus the remainder is 17.

Wilson's Theorem and Quadratic Residues

Definition 3.21. Let m be a positive integer, $(a, m) = 1$; a is said to be a quadratic residue modulo m if the congruence $x^2 \equiv a \pmod{m}$ has a solution.

A great deal of discussion about quadratic residues centers on prime moduli. The case $p = 2$ is not very interesting, since a is a quadratic residue if and only if $a \equiv 1 \pmod{2}$. So odd primes are of the most interest.

Theorem 3.22. Let p be an odd prime. Then the congruence $x^2 \equiv a \pmod{p}$ has either 0 or 2 solutions modulo p .

Proof: If $s^2 \equiv a \pmod{p}$, then $(-s)^2 \equiv a \pmod{p}$, and since p is odd, s and $-s$ are incongruent \pmod{p} . ($s \equiv -s \pmod{p}$ implies $2s \equiv 0 \pmod{p}$.) Thus, if there is one solution, there are two solutions. If t is another solution, then $t^2 \equiv a \equiv s^2 \pmod{p}$. Then $t^2 - s^2 \equiv 0 \pmod{p}$, so $(t - s)(t + s) \equiv 0 \pmod{p}$. Thus p is a divisor of either $t - s$ or $t + s$, so either $t \equiv s \pmod{p}$ or $t \equiv -s \pmod{p}$. So there are no other solutions.

A surprising consequence of this simple fact is

Theorem 3.23 (Wilson's Theorem) If p is a prime, then $(p - 1)! \equiv -1 \pmod{p}$.

Proof: If $p = 2$, this just says $1 \equiv -1 \pmod{2}$, which is true. If p is an odd prime, the congruence $x^2 \equiv 1 \pmod{p}$ has the two solutions $x \equiv 1 \pmod{p}$ and $x \equiv -1 \equiv p - 1 \pmod{p}$. If a is an integer between 2 and $p - 2$, then the congruence $ax \equiv 1 \pmod{p}$ has a unique solution by [Theorem 3.14](#), and that solution is not congruent to a modulo p , or a would satisfy $a^2 \equiv 1 \pmod{p}$, not possible by [Theorem 3.22](#). Thus the integers $2, \dots, (p - 2)$ can be grouped into $(p-3)/2$ pairs (a_i, a_i^{-1}) , $1 \leq i \leq (p-3)/2$ such that for each i , $(a_i, a_i^{-1}) \equiv 1 \pmod{p}$. Thus the product $(p-1)! \equiv 1(p-1)(a_1, a_1^{-1}) \dots (a_k, a_k^{-1}) \equiv p - 1 \equiv -1 \pmod{p}$, where $k = (p-3)/2$.

Quadratic Residues and Euler's Criterion

Suppose p is an odd prime. Clearly $1^2, 2^2, \dots, ((p-1)/2)^2$ are all quadratic residues. Further, if $1 \leq x, y \leq (p-1)/2$, then x^2 and y^2 are incongruent modulo p , since $x^2 \equiv y^2 \pmod{p}$ implies $(x-y)(x+y) \equiv 0 \pmod{p}$; but then either $p|(x-y)$ and $x = y$ or $p|(x+y)$, which is impossible since $2 \leq x+y \leq p-1$. So there are $(p-1)/2$ quadratic residues accounted for. But

$(-1)^2, (-2)^2, \dots, (-(p-1)/2)^2$ give the same numbers as $1^2, 2^2, \dots, ((p-1)/2)^2$; so since $-(p-1)/2, \dots, -1, 1, \dots, (p-1)/2$ is a complete reduced residue system modulo p , there are exactly $(p-1)/2$ quadratic residues mod p

and hence there are $(p-1)/2$ quadratic non-residues modulo p .

Definition 3.24 Legendre symbol. The symbol (a/p) , called the Legendre symbol, is defined by $(a/p) =$

- 1 if a is a quadratic residue mod p
- (-1) if a is not a quadratic residue mod p .

Some number theorists write $(0/p)=0$. Clearly $0^2 \equiv 0 \pmod{p}$, but quadratic residues are defined to be relatively prime to the modulus.

Now suppose a is a quadratic residue. Then there is an x with $x^2 = a$. But by [Fermat's Little Theorem](#) $x^{p-1} \equiv 1 \pmod{p}$, so $a^{(p-1)/2} = x^2 \equiv 1 \pmod{p}$. On the other hand, suppose a is not a quadratic residue. Then, if $(r, p)=1$, the equation $rx \equiv a \pmod{p}$ has a unique solution $s \pmod{p}$ by [Theorem 3.14](#), and s is not congruent to $r \pmod{p}$ (otherwise a would be a quadratic residue). Thus the elements of the set $1, 2, \dots, p-1$ can be grouped into $(p-1)/2$ pairs, where the product of each pair is $\equiv a \pmod{p}$. Thus $a^{(p-1)/2} \equiv 1(2)\dots(p-1) \equiv -1$ by [Wilson's Theorem](#). Thus we have proved

Theorem 3.25 Euler's Criterion $(a/p) \equiv a^{(p-1)/2} \pmod{p}$

This enables one to prove some interesting facts about quadratic residues

Theorem 3.26

- a) $(a^2/p) = 1$
- b) $(a/p) = (b/p)$ if $a \equiv b \pmod{p}$
- c) $((ab)/p) = (a/p)(b/p)$
- d) $(-1/p) = (-1)^{(p-1)/2}$

Proof:

a) and b) are obvious, d) is a restatement of [Euler's Criterion](#) for $a = 1$, and c) follows since $(ab)^{(p-1)/2} = a^{(p-1)/2} b^{(p-1)/2}$

So -1 is a quadratic residue of primes $p \equiv 1 \pmod{4}$, since then $(p-1)/2$ is even but not of primes $p \equiv 3 \pmod{4}$, since then $(p-1)/2$ is odd. The product of quadratic residues is a quadratic residue, but so is the product of quadratic non-residues. The product of a residue and a non-residue is a non-residue.

For example, if $p = 7$, the quadratic residues are congruent to $1^2, 2^2, 3^2 \pmod{7}$; that is congruent to $1, 2, 4$. Note that -1 is not a residue. Since 2 and 4 are residues, so is $2(4) \equiv 1 \pmod{7}$. Since 3 and 6 are non-residues, $3(6) \equiv 4 \pmod{7}$ is a residue. But $4(6) \equiv 5 \pmod{7}$, the product of a residue and a non-residue, is a non-residue.

Similarly, for $p = 13$ the residues are $1, 3, 4, 9, 10, 12$ and the non-residues are $2, 5, 6, 7, 8, 11$; $-1 \equiv 12 \pmod{13}$ is a residue, $4(9) \equiv 10 \pmod{13}$ is a residue, $5(6) \equiv 4 \pmod{13}$ is a residue, and $4(7) \equiv 2 \pmod{13}$ is a non-residue.

For $p=11$, the residues are $1, 3, 4, 5, 9$; the non-residues $2, 6, 7, 8, 10$.

Quadratic Reciprocity

The most famous theorem relating quadratic residues, the [Law of Quadratic Reciprocity](#), was first proved by [Gauss](#).

Theorem 3.27. Gauss's Law of Quadratic Reciprocity.

If p, q are odd primes $(p/q)(q/p) = (-1)^{((p-1)/2)((q-1)/2)} = (-1)^{((p-1)(q-1))/4}$

This theorem has been proved many times in many ways. An example illustrates its power. There are many proofs available on the Internet. Take a look at the [linked](#) paper to see one contemporary strategy. Compare the proof of Wilson's Theorem in the linked material to the proof of Wilson's Theorem above in order to gain insight into the strategy in the linked paper. Then, consider the example below and then the proof of the Quadratic Reciprocity law that appears in that link. (Click [here](#), if the link at the beginning of this paragraph fails).

$$(p/3)(3/p) = (-1)^{(p-1)(3-1)/4} = (-1)^{(p-1)/2} = (-1/p)$$

$$\text{Therefore, } (p/3)(3/p)(3/p) = (-1/p)(3/p) = (-3/p)$$

$$\text{Therefore } (p/3) = (-3/p)$$

But $(p/3) = (1/p) = 1$ if $p \equiv 1 \pmod{3}$ and $(p/3) = (2/3) = -1$. Thus -3 is a quadratic residue of the primes $p \equiv 1 \pmod{3}$ but not of the primes $p \equiv 2 \pmod{3}$.

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Spatial Synthesis: Centrality and Hierarchy, Volume I, Book 1.
Sandra Lach Arlinghaus and William Charles Arlinghaus

Chapter 4

Geometric Representations for Arbitrary Hierarchies

In the last chapter, we saw the complex mechanics of classical central place theory come alive as a single dynamic system when viewed through the lens of fractal geometry. The fit of the classical and fractal geometric hierarchies is exact. Thus, as one might use a carefully surveyed topographic map, with field-checked spot elevations, as a guide into dense jungle or other unsurveyed landscapes, so too we use our carefully field checked alignment of the classical and the fractal as a guide into unseen or unproven areas of theoretical geography. The difference is that the "field" tests in one case occur in "terrestrial space" while in the other the "field" tests occur in "geometry, number theory, and pure mathematics."

We saw hexagonal hierarchies, of different orientation, cell size, and stacking characteristics, arise from the same base of unit hexagons. These were associated with three integers: 3, 4, and 7. The thoughtful reader might naturally ask a number of questions, such as:

- are there other numbers that would serve as K values or are 3, 4, and 7 the only such values?
 - are 5 or 6 possible K values?
 - are there K values larger than 7?
 - how many K values are there?
- Dacey considered these issues.
- How does one determine the number of sides in a fractal generator that will generate a correct hierarchy for arbitrary K values?
 - How does one determine fractal generator shape that will generate a correct hierarchy for arbitrary K values?

In this chapter we offer geometric representations for higher numerical K values. Subsequent chapters will develop the number theory required to execute these constructions.

Coordinatization of the triangular lattice

Previous chapters employed a lattice of points to represent central places as a synthetic (coordinate-free) system. It is straightforward to assign a coordinate system, as well. If a point is given the usual Euclidean coordinate (x,y) , based on perpendicular axes, its distance from the origin is easily calculated to be $(x^2 + y^2)^{1/2}$. Thus, there is a natural association of the quadratic expression $x^2 + y^2$ with the point (x,y) . Such an expression is sometimes called a quadratic form. Quadratic forms have been studied extensively and material about them will appear in Chapter 5.

When the plane is occupied by a set of hamlets, each equidistant from its nearest neighbors, it seems more reasonable to pick a coordinate system which gives coordinates $(0,0)$, $(1,0)$, and $(0,1)$ to three hamlets which are vertices of an equilateral triangle. Thus it is natural to have a horizontal x -axis and a y -axis at angle 60° to the x -axis, as illustrated in Figure 4.1. Now, however, the calculation of distance between a point with coordinates (x,y) and the origin $(0,0)$ is more complicated. Figure 4.1 illustrates the situation when x and y are both positive. The right triangle whose hypotenuse has length this distance now has vertical side of length $\sqrt{3}y/2$ and horizontal side of length $y/2+x$. Thus the distance, d , is

$$\sqrt{(\sqrt{3}y/2)^2 + (y/2+x)^2} = \sqrt{3y^2/4 + y^2/4 + yx + x^2} = \sqrt{x^2 + xy + y^2}$$

The quadratic form $x^2 + xy + y^2$ is thus associated with the vertex (x,y) as both Dacey and Loeb had suggested earlier.



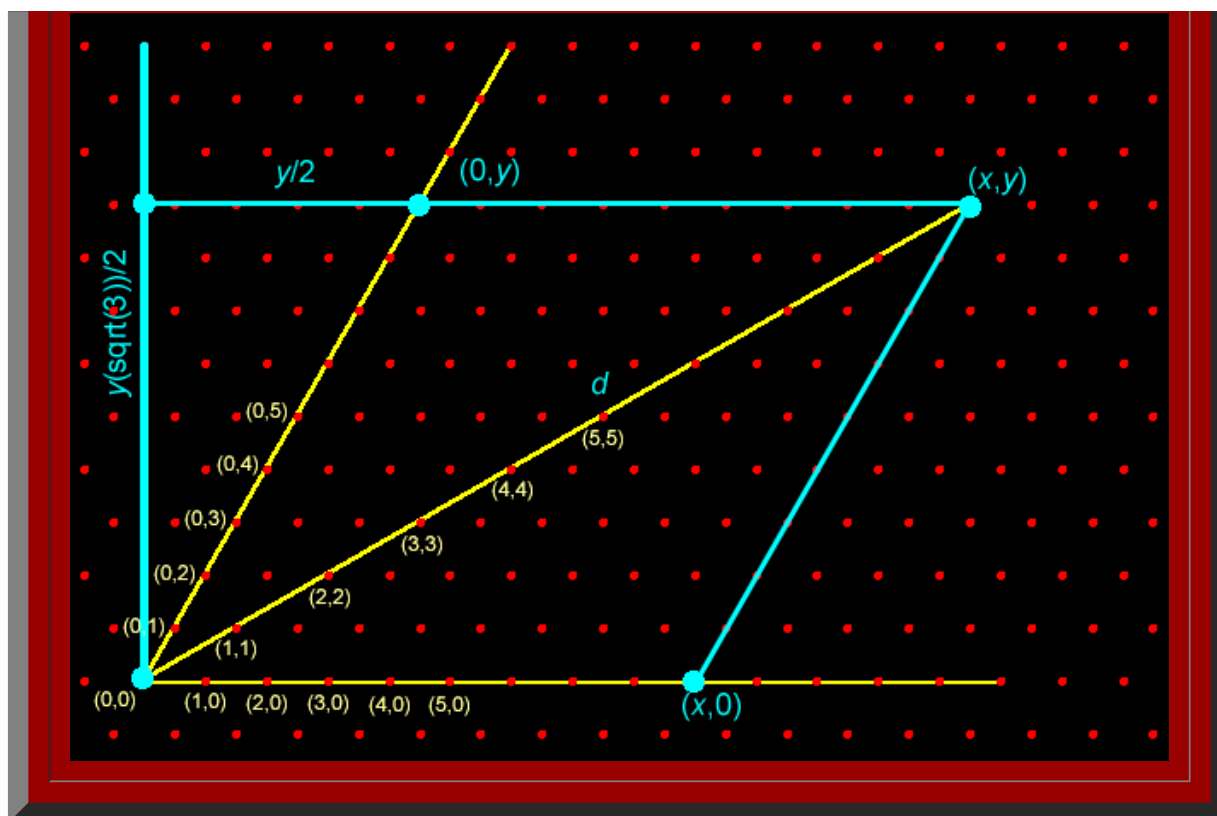


Figure 4.1. The standard y -axis of Cartesian coordinates is shown in cyan (turquoise). The yellow lines show the oblique axes. The value d represents the distance between the origin and an arbitrary point, (x,y) , drawn in this case on the line $y = x$ of the oblique axes.

The illustration in Figure 4.1 shows both values as positive. Thus, it must be established that this distance is the same even when x and y are not both positive. When x and y are both negative, $|x|$ must be substituted for x , and $|y|$ must be substituted for y , but the calculation remains the same.

When exactly one of x or y becomes negative, the geometry is different. Now the vertical side of the relevant right triangle has side of length

$$\sqrt{3}|y|/2$$

but the horizontal side is now of length $x - |y|/2$.

Thus the appropriate distance is

$$\sqrt{(-\sqrt{3}y/2)^2 + (x - (-y)/2)^2} = \sqrt{x^2 + xy + y^2}$$

When x is negative and y is positive, a similar calculation results.

Thus the form $x^2 + xy + y^2$ is indeed associated with the vertex (x,y) in this coordinate system. Any positive integer that is equal to $x^2 + xy + y^2$ for some integers x and y is called

Löschian, after August Lösch. One mathematical question that then occurs is: what integers are Löschian? The next chapter (Chapter 5) develops the number theory necessary to answer that question. Other issues involve values of K greater than 7 as well as questions involving number of generator sides and generator shape mentioned above. The rest of this chapter deals with these items.

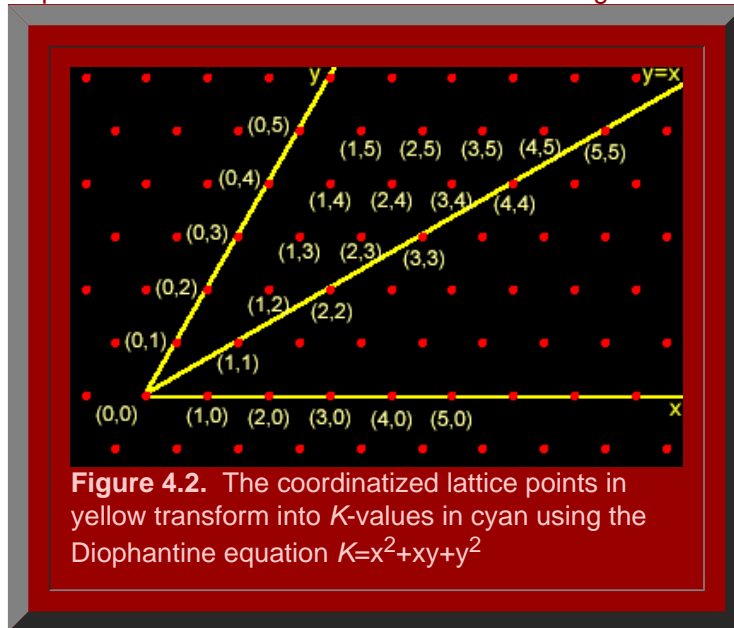
Higher K -values: An Infinite Number

Earlier research, by August Lösch, Michael Dacey, and others shows illustrations of K -values greater than 7. Indeed, research by Arthur Loeb, in crystallography, and Dacey, in geography, led to independent discovery that the Diophantine equation, $x^2 + xy + y^2 = K$ would generate all K values when pairs of positive integers were substituted for x and for y . Thus, when $(x,y)=(1,1)$ the equation $x^2 + xy + y^2 = K$ yields a value of $K=3$; when $(x,y)=(0,2)$, it follows that $K=4$; and, when $(x,y)=(1,2)$, it follows that $K=7$. Pairs such as $(0,0)$ and $(1,0)$ yield only trivial results so that the values of 3, 4, and 7 are the three smallest K -values. There are no other K values less than 7.

The result of Loeb/Dacey is important because it shows

- that there is an infinite number of possible K values
- that this infinity of values is in one-to-one correspondence with the integral lattice points in the plane
- that one can give a numerical generating function to create K values

Thus, a graph of lattice points in the plane offers a convenient method of visualizing K -values larger than 7 (Figure 4.2).

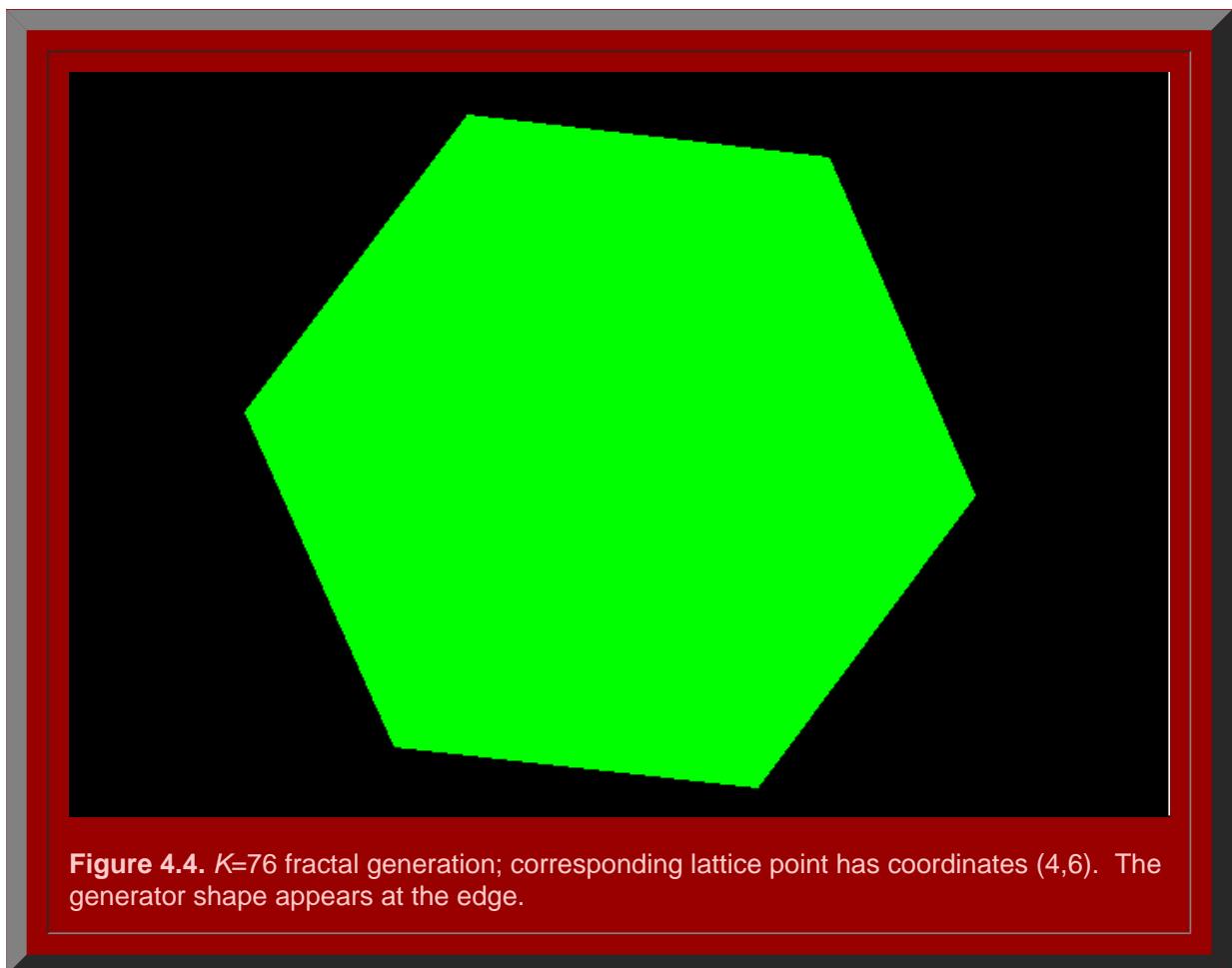
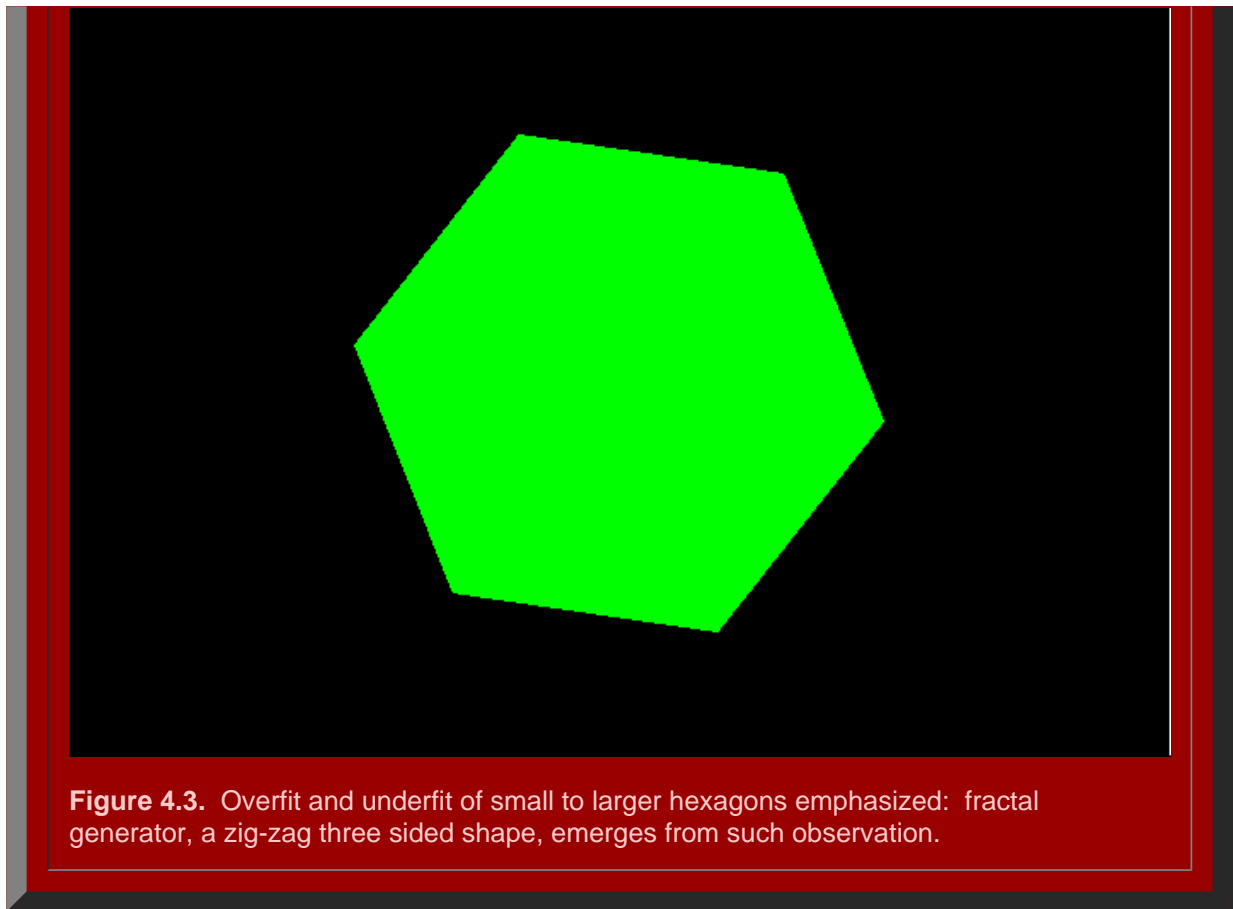


The Diophantine equation, $x^2+xy+y^2 = K$, is symmetric: the points (1,2) and (2,1) represent different locations in the plane. They both generate the same K value. Thus, it suffices to consider only a portion of the available lattice points: those in the first quadrant on one side of the line $y=x$. Because the pattern of points associated with central place hierarchies is based on a triangular lattice, the graph of lattice points displayed in Figure 4.2 is based on an oblique, rather than on a rectangular, coordinate system with angles at the origin of 60 and 120 degrees. Combining considerations of symmetry and oblique coordinates led to Figure 4.2. In that figure, both coordinate pairs, and corresponding K -value generated by the Diophantine equation, are shown.

With an infinite number of K -values available, it is a daunting consideration to try to figure out how to create a nested hierarchy of hexagonal trade areas suited to each value of K . Simple drawing skills do not suffice. One needs a formal strategy that can be replicated at will. Fractal geometry will offer that capability.

In the previous chapter, fractal generators appear simply to be plucked out of thin air: there is art in generator selection. Actually, the generator for the $K=7$ hierarchy suggested itself naturally with observations of overfit/underfit of the six small hexagons in relation to the boundary of the next larger one (Figure 4.3). From there, it was simply a matter of educated guessing and trial and error to find generators for $K=3$ and $K=4$ hierarchies. Someone with considerable experience working with this approach might, for example, figure out a fractal generator for a $K=76$ hierarchy, associated with the lattice point (4,6) (Figure 4.4). For replication by arbitrary individuals to be successful, however, one needs to capture the art in the formalized theory and language of mathematics: to transform art into science.





Fractal Generation of Arbitrary K-Values: Geometric Evidence

Once one generator shape is known, can it be used to determine other generator shapes? The answer is yes. The table in Table 4.1 illustrates that the $K=3$ generator, with a half a "hexstep" added, leads to the $K=7$ generator.


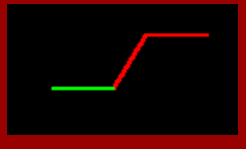
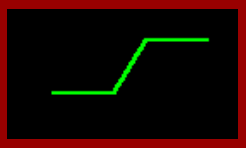
$K=3$ generator.	
$K=3$ generator (red) with one half hexstep added (green).	
$K=7$ generator	


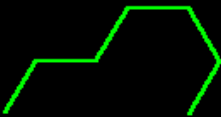
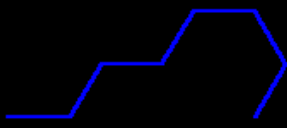
Table 4.1. The $K=3$ generator leads to the $K=7$ generator.

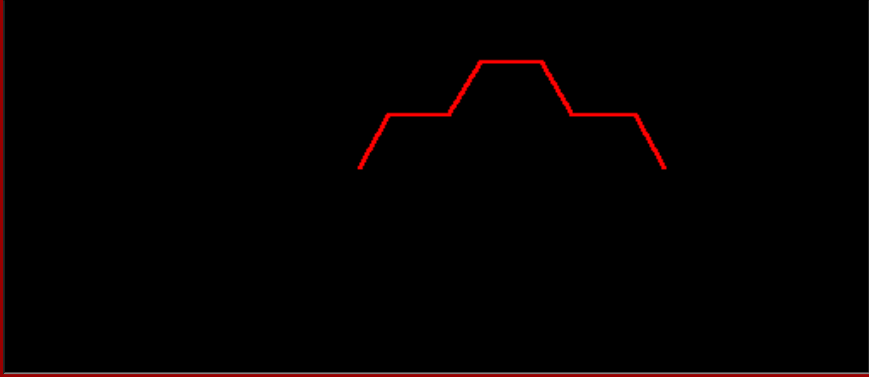
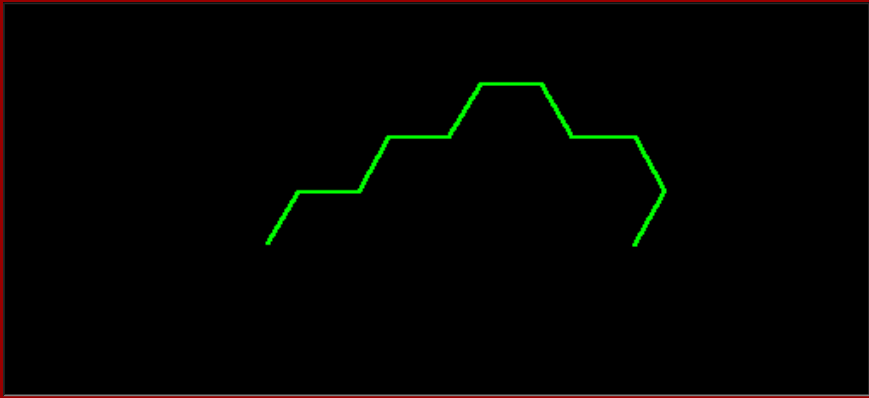
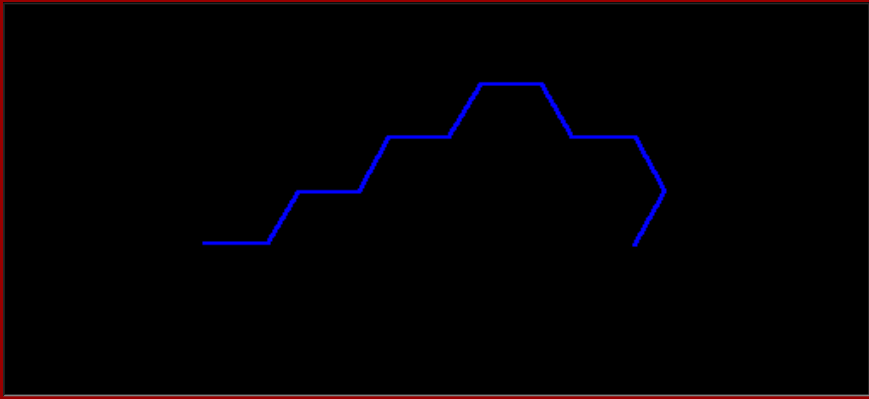
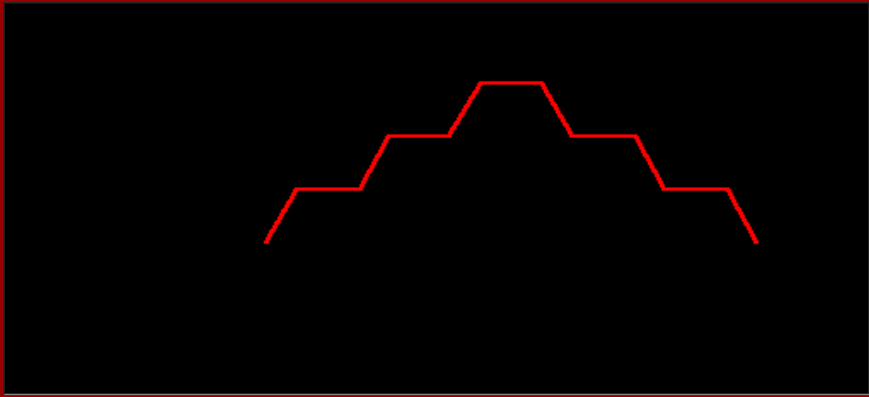

To try to uncover pattern useful in creating fractal generators for arbitrary K values, we begin by looking at a subset of K values: those along the y -axis, only. In that case, because $x^2+xy+y^2 = 0 + 0 + y^2 = K$, it follows that the square root of K is an integer and that the lattice points $(0,y)$ on the y -axis may be rewritten as $(0, \sqrt{K})$. Trial and error with finding fractal generators for selected values along the y -axis produced the table of generators shown in Figure 4.5. The trivial value of $K=1$, associated with the point $(0,1)$ is not shown in this figure. Within that "trial and error" process a pattern emerged, demonstrated in the animated Figure 4.5.

- Begin with the $K=4$ generator (lowest value on the y -axis): generator in red.
 - To the previous generator, add a full hexstep to the left of it and a half hexstep, curled under, to the right: generator in green. This new generator produces the $K=9$ hierarchy.
 - To the previous generator, add a half hexstep to the left (flat portion of the step): generator in blue. This new generator produces the $K=16$ hierarchy.
- Add two full hexsteps, one on each side, to the $K=4$ generator, creating a symmetric generator that produces the $K=25$ hierarchy.
 - To the previous generator, add a full hexstep to the left of it and a half hexstep, curled under, to the right: generator in green. This new generator produces the $K=36$ hierarchy.
 - To the previous generator, add a half hexstep to the left (flat portion of the step): generator in blue. This new generator produces the $K=49$ hierarchy.
- Add two full hexsteps, one on each side, to the $K=25$ generator, creating a symmetric generator that produces the $K=64$ hierarchy.
 - To the previous generator, add a full hexstep to the left of it and a half hexstep, curled under, to the right: generator in green. This new generator produces the $K=81$ hierarchy.
 - To the previous generator, add a half hexstep to the left (flat portion of the step): generator in blue. This new generator produces the $K=100$ hierarchy.





Lattice Coordinate	K-value (y-axis values)	Generator Shape	Hierarchy Type
(0,2)	$K=4$		4
(0,3)	$K=9$		3
(0,4)	$K=16$		7

$(0,5)$	$K=25$		4
$(0,6)$	$K=36$		3
$(0,7)$	$K=49$		7
$(0,8)$	$K=64$		4
$(0,9)$	$K=81$		3

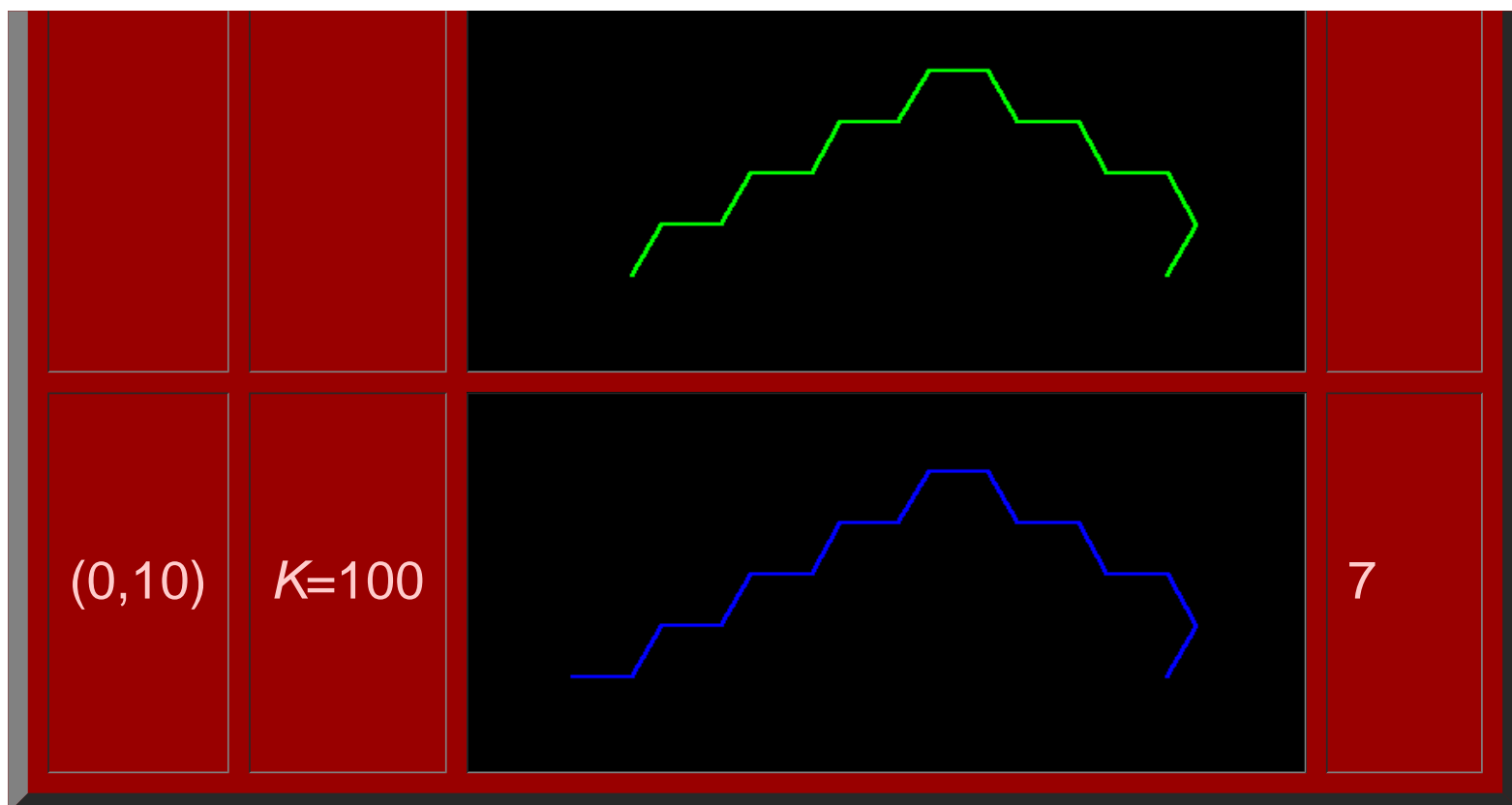


Figure 4.5. Fractal generators for selected values on the y -axis of lattice points generated by $x^2+xy+y^2 = K$. Animation and static versions.

Broadly speaking, we observe the following pattern (refer for this discussion to the static portion of Figure 4.5; the colors match).

- **(0,2), K=4.** Begin with the isosceles trapezoidal shape of the $K=4$ hierarchy.
 - Note its bilateral symmetry about a vertical line.
 - Note that it takes two sides to climb the right side to the top of the generator
- **(0,3), K=9.** For $K=9$, begin with the $K=4$ generator and
 - add one full hex-step to the left
 - add one half hex-step to the right, tucked under at 120 degrees
 - note that it takes three sides to climb the right side to the top of the generator, one more than it did for the "begin" value
- **(0,4), K=16.** For $K=16$, begin with the $K=9$ generator and
 - add one half level part of a hex-step to the left
 - note that it takes the same number of sides to climb the right side to the top of the generator as it did in the previous case.
- **(0,5), K=25.** For $K=25$, begin with the $K=4$ generator and
 - add a full hex-step to the left
 - add a full hex-step to the right
 - note that it takes four sides to climb the right side to the top of the generator
 - note the bilateral symmetry about a vertical line
- **(0,6), K=36.** For $K=36$, begin with the $K=25$ generator and
 - add one full hex-step to the left
 - add one half hex-step to the right, tucked under at 120 degrees
 - note that it takes one more side to climb the right side to the top of the generator than it did for the "begin" value
- **(0,7), K=49.** For $K=49$, begin with the $K=36$ generator and
 - add one half level part of a hex-step to the left
 - note that it takes the same number of sides to climb the right side to the top of the generator as it did in the previous case.
- **(0,8), K=64.** For $K=64$, begin with the $K=25$ generator and
 - add a full hex-step to the left
 - add a full hex-step to the right
 - note that it takes six sides to climb the right side to the top of the generator

note the bilateral symmetry about a vertical line

- **(0,9), K=81.** For $K=81$, begin with the $K=64$ generator and
 - add one full hex-step to the left
 - add one half hex-step to the right, tucked under at 120 degrees
 - note that it takes one more side to climb the right side to the top of the generator than it did for the "begin" value
- **(0,10), K=100.** For $K=100$, begin with the $K=81$ generator and
 - add one half level part of a hex-step to the left
 - note that it takes the same number of sides to climb the right side to the top of the generator as it did in the previous case.

.....continue, using the pattern without Figure 4.5.....

- **(0,11), K=121.** For $K=121$, begin with the $K=64$ generator and
 - add a full hex-step to the left
 - add a full hex-step to the right
 - note that it takes eight sides to climb the right side to the top of the generator
 - note the bilateral symmetry about a vertical line
- **(0,12), K=144.** For $K=144$, begin with the $K=121$ generator and
 - add one full hex-step to the left
 - add one half hex-step to the right, tucked under at 120 degrees
 - note that it takes one more side to climb the right side to the top of the generator than it did for the "begin" value

.....

After a number of cases, there appears to be a clear pattern, color-coded as red-green-blue. If that pattern is correct, then the reader could, through successive (but perhaps tedious) application of this pattern, produce a fractal generator for an arbitrary value on the y -axis. We will show a more systematic procedure later in this Chapter for finding generator size and shape; it will, however, be based on the observations above, so it is important that the reader have a clear understanding of them.

To produce generators for K -values not on the y -axis is also a simple matter of examining pattern. Figure 4.6 shows how to form generators for all other K -values (not on the y -axis) simply by adding hex-steps to the y -axis K -value generators as one moves to the right across lines of lattice points parallel to the line $y=x$ (cyan lines in Figure 4.7). Thus, the reader could then form a fractal generator for an arbitrary K -value.

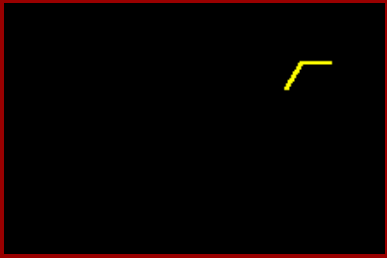

<p>Y-axis value and line position</p>	<p>Fractal generators off the y-axis as determined by y-axis generator shape.</p>
<p>(0,0): the first generator appears for $K=3$ (not on the y-axis; $K=0$, on the y-axis, is disregarded) and subsequent generators appear for K-values of 12, 27, and 48 as one moves to the right across the line $y=x$.</p>	
<p>(0,1): the first generator appears for $K=7$ (not on the y-axis; $K=1$, on the y-axis, is disregarded) and subsequent generators appear for K-values of 19, 37, and 61 as one moves to the right across the line displaced by 1 from, and parallel to, the</p>	



Figure 4.6. Fractal generators are produced for arbitrary K -values from y -axis K -values. See the cyan lines in Figure 4.7.

Fractal Generation of Arbitrary K -Values: the Cross-cut Equation as a Systematic Characterization of Generator Size and Shape

In Figure 4.5, the "red" category corresponds to a generator type similar to the $K=4$ generator: an isosceles trapezoid with some number of hex-steps on either side, producing a bilaterally symmetric form. The "blue" category corresponds to a generator type similar to the $K=7$ category, identical to the previous case but with one half level hex-step added to the left. If one looks at the trivial cases of $K=0$ and $K=1$ in Figure 4.6, this style of pattern is evident in moving from $K=3$ to $K=7$. Thus, it appears that there are really only three basic, or primitive, styles of generator type: $K=3$ (green), $K=4$ (red), and $K=7$ (blue). Because generator shape on the y -axis determines generator shape off the axis along rays parallel to the line $y=x$ (cyan lines in Figure 4.7), we next consider partitioning the set of all K values according to these three categories using a set of parallel rays (cyan lines in Figure 4.7) to create that partition. Thus, we seek another equation to represent that partition with the intent of using it to cut across the Diophantine equation and provide straightforward solution to finding the number of sides and the shape of fractal generators for arbitrary K -values.

The pattern of numerical K values along rays parallel to $y=x$, shown as cyan lines, is captured in Figure 4.7. Thus,

- along $y=x$, we have $K=3x^2$: the K values along that ray, only, are generated exactly by substituting 0, 1, 2, 3, 4,... into that equation yielding K values of 0, 3, 12, 27, 48, ...
- along the ray displaced 1 unit from the line $y=x$, we have $K=3x^2+3x+1$: the K values along that ray, only, are generated exactly by substituting 0, 1, 2, 3, 4,... into that equation yielding K values of 1, 7, 19, 37, 61,...
- along the ray displaced 2 units from the line $y=x$, we have $K=3x^2+6x+4$: the K values along that ray, only, are generated exactly by substituting 1, 2, 3, 4,... into that equation yielding K values of 4, 13, 28, 49, 76,...
- along the ray displaced 3 unit from the line $y=x$, we have $K=3x^2+9x+9$: the K values along that ray, only, are generated exactly by substituting 0, 1, 2, 3, 4,... into that equation yielding K values of 9, 21, 39, 63, 93,...



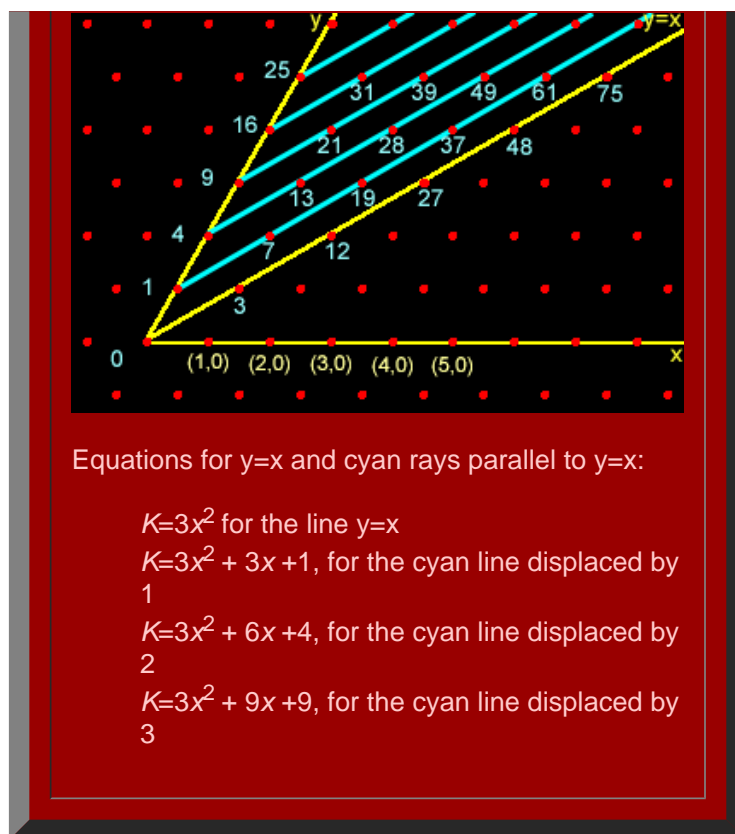


Figure 4.7. Pattern suggesting cross-cut equation. The equation for the cyan rays, parallel to $y=x$, generate exactly the K -values associated with lattice points along that ray (when integers are substituted into those equations..

Generalizing from the observed pattern, it appears that the equation $K=3x^2 + 3bx + b^2$, where b counts the number of units the ray is displaced from $y=x$, will serve to capture all the K -values associated with the lattice points along a single horizontal ray parallel to $y=x$ (cyan, Figure 4.7), and to capture no others elsewhere. This idea is stated in the following theorem; the next chapter will present some of the number theoretic infrastructure behind it.

Fundamental Theorem (S. Arlinghaus, 1985, and S. Arlinghaus in S. and W. Arlinghaus, 1989).

In a triangular central place lattice, the central place K -values, lying along any single one of the rays parallel to the line $y=x$, are generated by substituting non-negative integral values into a quadratic equation $K=3x^2 + 3bx + b^2=3x^2+3(\sqrt{K})x+(\sqrt{K})^2$, where $b=0, 1, \dots, n, \dots$ counts the number of units the ray is translated from $y=x$.

Thus, any single K value has two quadratic equations that represent it. We now proceed to use properties of these quadratic equations to extract information from them sufficient to determine the number of fractal generator sides and number of hex-steps for arbitrary K values from algebraic information, alone. Thus, an informed reader will have the capability to replicate the results, independent of relative position on any image. As an analogy, this process is similar to using latitude and longitude as numerical measures to determine absolute position on the earth-sphere rather than using parallels and meridians as geometric measures to determine relative position on the earth-sphere.

Number of Generator Sides

The patterns observed appear often to involve partitions related to the number 3. Thus, we consider a value based on divisibility by 3 as one index.

Define an integral value j , using K -values along the y -axis, only, as:

- If K is congruent to $0 \pmod{3}$, then $j=(\sqrt{K}) / 3$;
- If K is not congruent to $0 \pmod{3}$, then $j=((\sqrt{K}) - 1) / 3$ or $j=((\sqrt{K}) - 2) / 3$, which ever is an integer (clearly, both cannot be integers-- K leaves either a remainder of 1 or of 2 when divided by 3).

As some examples:

7	116	4617 =67.948
8	111	4572 ^{1/2} =67.616
9	105.333	
10	99	4464 ^{1/2} =66.813
11	92	4401 ^{1/2} =66.340
12	84.333	
13	76	4257 ^{1/2} =65.245
14	67	4176 ^{1/2} =64.621
15	57.333	
16	47	3996 ^{1/2} =63.213
17	36	3897 ^{1/2} =62.425
18	24.333	
19	12	3681 ^{1/2} =60.671

Table 4.2. This table shows candidate values for b for $K=397$ in the left-hand column. It shows values of $(397-b^2)/3$ for each of those candidate values in the center column. The right-hand column shows the square root of the discriminant of the quadratic expression $3x^2 + 3bx + b^2$ for different values of b (from 0 to 19) that produce an integral value in the center column.

Now we have two quadratic equations to solve simultaneously to obtain the ordered pair that gives rise to the Lösschian value of 397.

$$397 = 3x^2 + 3x + 1$$

$$397 = x^2 + xy + y^2$$

Solving the first equation using standard techniques from high school algebra, and choosing the positive value, gives $x = 11$. Use that value of x to find $y = 12$ in the second equation. There are no other lattice points that give rise to this particular Lösschian number because there is no other integral discriminant of the quadratic form $3x^2 + 3bx + b^2$.

The geometric characterization of the central place lattice as a set of integral lattice points lying along a set of lines parallel to $y = x$ resulted, after some work, in a Fundamental Theorem that permits the algebraic determination of a quadratic form, $3x^2 + 3bx + b^2$, to generate a set of lattice points lying along a single line. When this second quadratic form was applied to the Diophantine equation, $K = x^2 + xy + y^2$, easy calculations permit the determination of the lattice coordinates associated with an arbitrary Lösschian number and of whether or not those coordinates are unique.

Uniqueness of Lösschian numbers: solutions to previously unsolved problems.

Solving the K-value Twin Hierarchy Problem

Dacey noticed that some K -values have more than one central place hierarchy associated with them. Using classical methods, however, it is difficult to determine what these hierarchies might look like. Indeed, Dacey noted this issue as an unsolved problem in the classical geometry of central place theory. The fractal approach, when extended to arbitrary K -values, permits solution of this unsolved problem using the Fundamental Theorem and associated constructions.

Suppose it has been determined that the number 49 is a Lösschian number. Express 49 as $3x^2 + 3bx + b^2$, for some b . To do so, consider values of b from 0 to $49^{1/2}$. The greatest integer in this square root is 7. Thus, possibilities for b range from 0 to 7. Because $3x^2 + 3bx = 49 - b^2$, it follows that $49 - b^2$ must be divisible by 3. This fact eliminates from further consideration, as b , any integer between 0 and 7 for which $49 - b^2$ is not a multiple of 3. These values are shown in the central column of Table 4.3. Additionally, the material associated with the Fundamental Theorem states that the discriminant of the quadratic form, $3x^2 + 3bx + b^2$ must be an integer. Thus, in the right-hand column of Table 4.3 we calculate these discriminants for each of the candidate b -values singled out in the central column. The only candidate b values that remains are $b=2$ and $b=7$ and therefore the correct quadratic forms to also associate with 49 are $3x^2 + 6x + 4$ and $3x^2 + 21x + 49$. Geometrically, the ordered pairs that generate 49 are represented as a lattice points that lies along the line $b=2$, displaced two units from the line $y=x$ in the oblique coordinate system, and along the line $b=7$, displaced seven units from the line $y=x$ in the oblique coordinate system.

$b(49-b^2)/3$	Square root of discriminant
---------------	-----------------------------

0	16.333	
1	16	$585^{1/2}=24.186$
2	15	$576^{1/2}=24$
3	13.333	
4	11	$540^{1/2}=23.237$
5	8	$512^{1/2}=22.627$
6	4.333	
7	0	$441^{1/2}=21$

Table 4.3. This table shows candidate values for b for $K=49$ in the left-hand column. It shows values of $(49-b^2)/3$ for each of those candidate values in the center column. The right-hand column shows the square root of the discriminant of the quadratic expression $3x^2 + 3bx + b^2$ for different values of b (from 0 to 7) that produce an integral value in the center column.

Now we have two sets of two quadratic equations each to solve simultaneously to obtain the ordered pairs that gives rise to two different hexagonal hierarchies associated with the Lösschian value of 49.

$$49 = 3x^2 + 6x + 4$$

$$49 = x^2 + xy + y^2$$

$$49 = 3x^2 + 21x + 49$$

$$49 = x^2 + xy + y^2$$

In the first set of equations, $x=3$ and $y=5$. In the second set, $x=0$ and $y=7$. There are no other lattice points that give rise to this particular Lösschian number because there is no other integral discriminant, beyond these two, of the quadratic form $3x^2 + 3bx + b^2$. Thus, $K=49$ is produced either from the lattice point $(0,7)$ on the y -axis or from the lattice point $(5,3)$ not on the y -axis. Figure 4.8 illustrates the two different fractal generators that give rise to the two different hierarchies using the procedure based on the Fundamental Theorem in associating fractal generators with lattice points.

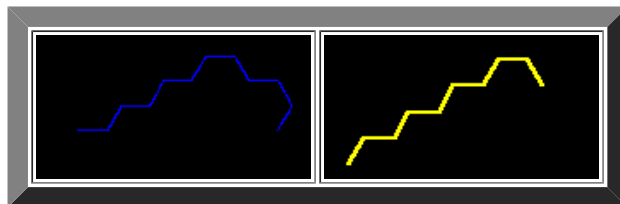


Figure 4.8. Geometric solution of the $K=49$ twin hierarchy puzzle. The left frame shows an 11-sided generator formed from the ordered pair $(0,7)$ on the y -axis, yielding a $K=7$ type of hierarchy. The right frame shows a 9-sided generator formed from the ordered pair $(5,3)$, not on the y -axis, yielding a $K=4$ type of hierarchy.

This example illustrates the fact that the Fundamental Theorem solves, completely, the previously unsolved problem involving uniqueness, and its lack, in calculating hexagonal hierarchies. The geometric characterization of the central place lattice as a set of integral lattice points lying along a set of lines parallel to $y = x$ resulted, after some work, in a Fundamental Theorem that permits the algebraic determination of a quadratic form, $3x^2 + 3bx + b^2$, to generate a set of lattice points lying along a single line. When this second quadratic form was applied to the Diophantine equation, $K = x^2 + xy + y^2$, easy calculations permit the determination of the lattice coordinates associated with an arbitrary Lösschian number and also the determination of whether those coordinates are unique.

Putting the Pieces Together

The material in the previous sections indicates a plausible strategy for producing appropriate fractal generators that will create, through iteration, exact central place hierarchies for arbitrary K -values. It does so using only number theoretic properties of two quadratic forms. Thus, process is replicable and independent of previous cases. In the next chapter we consider some of the number theoretic infrastructure on which these methods rest and in a final chapter we present some real world considerations.

Chapter 5

Binary Quadratic Forms and the L\"oschian Diophantine Equation

One proof of Gauss's Law of Reciprocity, using contemporary techniques was linked to at the end of the previous chapter. There are also numerous classical proofs, some of which rest on the Chinese Remainder Theorem ([link](#) to one of them). Because such proofs often assume that the reader already knows the Chinese Remainder Theorem, and because it has been our experience that readers often do not know this theorem, we present it here in detail.

The Chinese Remainder Theorem

At the time the [greatest common divisor](#) was defined, it would have been possible to define a related number, the least common multiple.

Definition 5.1. Suppose a and b are two positive integers. The least common multiple $[a, b]$ is the smallest positive integer which is a multiple of both a and b . The relationship between them is illustrated in the following lemma.

Lemma 5.2. Let a and b be two positive integers. Then

- a) $(a, b) [a, b] = ab$
- b) If $d \mid a$ and $d \mid b$, then $d \mid (a, b)$
- c) If $a \mid m$ and $b \mid m$, then $ab \mid m$.

Proof:

- a) Consider the prime factorizations of a, b . Let

$$a = p_1^{a_1} p_2^{a_2} \dots p_k^{a_k}$$

$$b = p_1^{b_1} p_2^{b_2} \dots p_k^{b_k}$$

(in this case, some exponents may be 0; a prime is included in the list if it is a divisor of either a or b).

Then

$$(a, b) = p_1^{c_1} \dots p_k^{c_k} \text{ where } c_i = \min \{a_i, b_i\}$$

$$[a, b] = p_1^{d_1} \dots p_k^{d_k} \text{ where } d_i = \max \{a_i, b_i\}$$

Since $a_i + b_i = c_i + d_i$ for each i , $(a, b) [a, b] = ab$.

- b) There are integers s, t such that $(a, b) = as + bt$. If $a = dx$, $b = dy$, $(a, b) = d(xs) + d(yt) = d(xs + yt)$. So $d \mid (a, b)$.

- c) Let $m = [a, b]q + r$, $0 \leq r < [a, b]$. As in b), since $a \mid m$ and $a \mid [a, b]$, $a \mid r$. Similarly $b \mid r$. Since $r < [a, b]$, this contradicts the fact that $[a, b]$ is the LEAST common multiple of a and b . So $r = 0$. If $(a, b) = 1$, $[a, b] = ab$ by part a), so $ab \mid m$.

The least common multiple is used in arithmetic to add fractions, where it is called the least common denominator. For example, since $[15, 21] = 15(21)/(15,21) = 15(21)/3 = 105$

$$4/15 + 5/21 = (4/15)((21/3)/(21/3)) + (5/21)((21/3)/(21/3)) = (4(7) + 5(5))/105 = 53/105.$$

The least common multiple arises when it is desired to solve several congruences (with different moduli) simultaneously. The process below appears to have been known in first century China. Hence it has come to be known as the Chinese Remainder Theorem.

Theorem 5.3. The Chinese Remainder Theorem

Let m_1, m_2, \dots, m_r be positive integers such that $(m_i, m_j) = 1$ if $i \neq j$. Let a_1, \dots, a_r be any integers. Then the system of congruences

$$x \equiv a_1 \pmod{m_1}$$

$$x \equiv a_2 \pmod{m_2}$$

....

$$x \equiv a_r \pmod{m_r}$$

has a common solution of x , and if x, y are two such solutions $x \equiv y \pmod{m=m_1 m_2 \dots m_r}$.

Proof:

For each j , let $k_j = m / m_j$. Thus $(k_j, m_j) = 1$, since m_j has no factors in common with any m_i if $i \neq j$. Thus there is an integer b_j with $k_j b_j \equiv 1 \pmod{m_j}$. Also, if $i \neq j$, $k_j b_j \equiv 0 \pmod{m_i}$. Let $x = \sum k_j b_j a_j$, $1 \leq j \leq r$. Then, for each i , $x \equiv k_i b_i a_i \equiv a_i \pmod{m_i}$. Further, if x and y are two solutions $x \equiv y \pmod{m_i}$. Thus $m_i \mid (x - y)$ for each i . By [Lemma 5.2c](#) $m \mid (x - y)$. So $x \equiv y \pmod{m}$.

Here is a classic example. A man has a basket of eggs. He doesn't know how many eggs there are, but when he counts them by twos, there is one left over. Similarly, when he counts by threes or fives, there is one remaining. When he counts by sevens, there are two left over. What is the least number of eggs he could have in his basket? If x is the number of eggs, the system of congruences is

$$x \equiv 1 \pmod{2}$$

$$x \equiv 1 \pmod{3}$$

$$x \equiv 1 \pmod{5}$$

$$x \equiv 2 \pmod{7}$$

So $m=210$, $k_1=105$, $k_2=70$, $k_3=42$, $k_4=30$. To find b_1, b_2, b_3, b_4 solve

$$105b_1 \equiv 1 \pmod{2} \text{ or } b_1 \equiv 1 \pmod{2}$$

$$70b_2 \equiv 1 \pmod{3} \text{ or } b_2 \equiv 1 \pmod{3}$$

$$42b_3 \equiv 1 \pmod{5} \text{ or } 2b_3 \equiv 1 \pmod{5}$$

$$30b_4 \equiv 1 \pmod{7} \text{ or } 2b_4 \equiv 1 \pmod{7}$$

One set of solution is $b_1=1, b_2=1, b_3=3, b_4=4$. Thus $x=105(1)(1)+70(1)(1)+42(3)(1)+30(4)(1)=541$. The smallest positive integer congruent to $541 \pmod{210}$ is 121. Thus the least number of eggs the man has is 121.

While computations such as those of the above example are fascinating, the theoretical consequences are more important.

Theorem 5.4. Suppose $(m_1, m_2) = 1$. Then the equation $f(x) \equiv 0 \pmod{m=m_1 m_2}$ has a solution if and only if both $f(x) \equiv 0 \pmod{m_1}$, and $f(x) \equiv 0 \pmod{m_2}$ have solutions (here $f(x)$ is a polynomial with integer coefficients).

Remark: In fact if $f(x) \equiv 0 \pmod{m_1}$ has n_1 solutions and $f(x) \equiv 0 \pmod{m_2}$ has n_2 solutions, then $f(x) \equiv 0 \pmod{m}$ has $n_1 n_2$ solutions. See [Niven, Zuckerman, and Montgomery](#), Theorem 2.20, for a proof. In the book, the theorem will be used to see if $x^2 \equiv a$ has solutions for certain composite moduli.

Proof: If $f(x) \equiv 0 \pmod{m}$, then for some integer k , $f(x) = km = km_1m_2$. Thus $f(x) \equiv 0 \pmod{m_1}$ and $f(x) \equiv 0 \pmod{m_2}$. On the other hand, suppose $f(x) \equiv 0 \pmod{m_1}$ and $f(x) \equiv 0 \pmod{m_2}$ both have solutions. Suppose $f(a_1) \equiv 0 \pmod{m_1}$ and $f(a_2) \equiv 0 \pmod{m_2}$. By the [Chinese Remainder Theorem](#), there is an integer $x \pmod{m}$, $x \equiv a_1 \pmod{m_1}$ and $x \equiv a_2 \pmod{m_2}$. Then $f(x) \equiv f(a_1) \equiv 0 \pmod{m_1}$ and $f(x) \equiv f(a_2) \equiv 0 \pmod{m_2}$. Thus $m_1 \mid f(x)$, $m_2 \mid f(x)$. Thus since $(m_1, m_2) = 1$, by Lemma 5.2 $m = m_1m_2 \mid f(x)$, so $f(x) \equiv 0 \pmod{m}$.

The [Chinese Remainder Theorem](#) can also be used to help calculate the value of Euler's ϕ -function.

Theorem 5.5.

- If p is a prime, $\phi(p^n) = p^n - p^{n-1}$
- If $(m_1, m_2) = 1$, $\phi(m_1, m_2) = \phi(m_1)\phi(m_2)$.

Proof:

- Suppose p is a prime. Then, consider the complete residue system $1, 2, \dots, p^n$. The only integers in this list NOT relatively prime to p are $p, 2p, \dots, (p^{n-1})p$. Thus $\phi(p^n) = p^n - p^{n-1}$.
- The goal is to establish a one-to-one correspondence between integers a in the set $\{1, 2, \dots, m\}$ which are relatively prime to m and pairs of integers (a_1, a_2) , where

a_1 is in $\{1, 2, \dots, m_1\}$, relatively prime to m_1

a_2 is in $\{1, 2, \dots, m_2\}$, relatively prime to m_2 .

First, suppose $(a, m) = 1$. Then $(a, m_1) = 1$ and $(a, m_2) = 1$. Let a_i be the remainder when a is divided by m_i , $i = 1, 2$. Second, suppose a_1, a_2 are as above. Then the [Chinese Remainder Theorem](#) assures there is a unique a in $\{1, 2, \dots, m\}$ with $a \equiv a_1 \pmod{m_1}$ and $a \equiv a_2 \pmod{m_2}$. Since $(a, m_1) = 1$ and $(a, m_2) = 1$, it follows that $(a, m_1m_2) = 1$. Thus, since this one-to-one correspondence exists, $f(m) = f(m_1)f(m_2)$.

For example, since $\phi(4) = 4 - 2 = 2$ and $\phi(5) = 4$, $\phi(20) = 8$. Since $\phi(8) = 8 - 4 = 4$ and $\phi(9) = 9 - 3 = 6$, $\phi(72) = 4(6) = 24$. One of the pairings of part b) of the theorem is of $(1, 2)$, where $(1, 8) = 1$ and $(2, 9) = 1$ with 65, a number relatively prime to 72 with $65 \equiv 1 \pmod{8}$ and $65 \equiv 2 \pmod{9}$. This is the solution of the system

$$x \equiv 1 \pmod{8}$$

$$x \equiv 2 \pmod{9}$$

determined by the [Chinese Remainder Theorem](#) ($k_1=9, k_2=8; b_1=1, b_2=8$) since $x \equiv 9(1)(1) + 8(8)(2) = 137 \equiv 65 \pmod{72}$.

Binary Quadratic Forms

In order to find which integers are of the form $x^2 + xy + y^2$ for integers x, y (as desired by [Loeb](#) and [Dacey](#)), it is first necessary to study binary quadratic forms in general.

Definition 5.6.

- A function $f(x, y) = ax^2 + bxy + cy^2$ is called a binary quadratic form. If $n = f(x_0, y_0)$ for some integers x_0, y_0 , then the form f represents n properly if $(x_0, y_0) = 1$, improperly if $(x_0, y_0) \neq 1$.
- The points (x, y) where x, y are integers are called lattice points.
- The discriminant d of a quadratic form is $d = b^2 - 4ac$.
- A form is called

positive definite if it takes on only positive values when $(x, y) \neq (0, 0)$.

negative definite if it takes on only negative values when $(x, y) \neq (0, 0)$.

semidefinite if it takes on only non-negative values or non-positive values.

Theorem 5.7.

- a) $d \equiv 0$ or $1 \pmod{4}$
- b) A form with $d = 0$ is semidefinite but not definite. A form with positive discriminant is indefinite. A form with negative discriminant is definite (positive if $a > 0$, negative if $a < 0$)

Theorem 5.8. Let $M = [m_{11} m_{12}; m_{21}, m_{22}]$. Let $[u; v] = M[x; y]$, that is $u = m_{11}x + m_{12}y$, $v = m_{21}x + m_{22}y$. Then this transformation is a permutation of the lattice points in the plane if and only if $\det M = \pm 1$.

Definition 5.9. Two quadratic forms $f(x, y) = ax^2 + bxy + cy^2$ and $g(x, y) = Ax^2 + Bxy + Cy^2$ are said to be equivalent if there is a matrix M of determinant 1, $M = [m_{11}, m_{12}; m_{21}, m_{22}]$, such that $g(x, y) = f(m_{11}x + m_{12}y, m_{21}x + m_{22}y)$.

Theorem 5.8 suggests that matrices of determinant -1 could have been allowed in **Definition 5.9**. Indeed, some number theory texts allow this. Still others use the term "properly equivalent" if $\det M = 1$, "improperly equivalent" if $\det M = -1$. Niven, Zuckerman, and Montgomery use the approach of **Definition 5.9**.

Theorem 5.9.

- a) Equivalence of forms partitions the set of quadratic forms into sets of forms all of which are equivalent to each other.
- b) Equivalent forms represent the same integers n , and represent the same integers properly.
- c) Equivalent forms have the same discriminant.

Definition 5.10. Let f be a binary quadratic form whose discriminant is not a perfect square; f is called reduced if $-|a| < b \leq |c|$ or if $0 \leq b \leq |a| = |c|$.

Theorem 5.11. If d is not a perfect square, each equivalence class of binary quadratic forms of discriminant d contains at least one reduced form.

Theorem 5.12. Suppose f is a reduced positive definite quadratic form of discriminant d . The $0 < a \leq (-d/3)^{0.5}$.

Corollary 5.13. There is only one reduced form with discriminant -3.

Proof: By Theorem 5.12 $a = 1$; $b = 0$ is impossible since $a \equiv b^2 \pmod{4}$. Therefore, Definition 5.10 assures $b = 1$, $c = 1$.

Theorem 5.14. Let n and d be given integers with $n \neq 0$. There is a binary quadratic form of discriminant d which represents n properly if and only if $x^2 \equiv d \pmod{4|n|}$ has a solution.

Corollary 5.15. Suppose $a \equiv 0$ or $1 \pmod{4}$. If p is an odd prime, there is a binary quadratic form of discriminant which represents p if and only if $(d/p) = 1$.

Application to Lösschian Numbers

Definition 5.16. A positive integer n is called Lösschian if there are integers x and y such that $n = x^2 + xy + y^2$.

Since there is only one reduced form of discriminant -3, namely $x^2 + xy + y^2$, and since if n is representable by a form of discriminant -3 if and only if it is representable by an equivalent reduced form, **Theorem 5.14** assures that n is properly representable by $x^2 + xy + y^2$ if and only if $x^2 \equiv -3 \pmod{4n}$ or $x^2 + 3 \equiv 0 \pmod{4n}$ has a solution.

By **Theorem 5.4**, $x^2 + 3 \equiv 0 \pmod{4n}$ has a solution if and only if $x^2 + 3 \equiv 0 \pmod{p_i^{a_i}}$ has a solution for every i .

- 1) If $p \mid n$ and $p \equiv 1 \pmod{3}$, then by **quadratic reciprocity** $(-3/p) = (p/3) = 1$ and also $(-3/p^n) = (p^n/3) = (p/3)^n$

$= 1$, so $x^2 + 3 \equiv 0 \pmod{p^n}$ has a solution for every n .

2) However suppose $p \equiv 2 \pmod{3}$. Then $(-3/p) = 1$, and so $x^2 + 3 \equiv 0 \pmod{p}$ has no solution. But $x^2 + 3 \equiv 0 \pmod{p^n}$ implies $p^n \mid (x^2 + 3)$ which in turn implies that $p \mid (x^2 + 3)$, which is impossible.

3) Of course $x^2 + 3 \equiv 0 \pmod{3}$ has a solution ($x = 0$) but $x^2 + 3 \equiv 0 \pmod{3^n}$ has no solution for $n > 1$ since $9 \mid (x^2 + 3)$ implies $3 \mid x^2$ implies $3 \mid x$, say $x = 3a$; but then $x^2 + 3 = 3(3a^2 + 1) \equiv 3 \pmod{9}$, a contradiction.

Thus N is properly representable by $x^2 + xy + y^2$ if and only if $N = 3^a p^b$, where every $p \equiv 1 \pmod{3}$ and $a = 0$ or 1 . Of course if $N = x^2 + xy + y^2$, $c^2 N = (cx)^2 + (cx)(cy) + (cy)^2$ so the square of any properly representable integer is improperly representable. Thus an integer N is Lösschian if and only if $N = 3^a p^b q^{2g}$ where every $p \equiv 1 \pmod{3}$, every $q \equiv 2 \pmod{3}$. Of course, sometimes, it is not necessary to find the prime factorization of N to see if it is Lösschian. Since always $x^2 + xy + y^2 \equiv 0$ or $1 \pmod{3}$ [try the nine cases $x \equiv a, y \equiv b \pmod{3}$; if $a = b$, $x^2 + xy + y^2 \equiv 0 \pmod{3}$; otherwise $x^2 + xy + y^2 \equiv 1 \pmod{3}$].

So if $N \equiv 2 \pmod{3}$, N is non-Lösschian.

For example, $N = 32759$ is non-Lösschian (it is not immediately obvious that $N = 17(41)(47)$).

Similarly, suppose $N = p^n M$, where $(M, p) = 1$, $p \equiv 0, 1 \pmod{p}$. If $M \equiv 2 \pmod{3}$, N is non-Lösschian, since the sum of the exponents of the primes $\equiv 2 \pmod{3}$ in the prime factorization of M must be odd.

For example, $N = 8073 = 3^3(299)$, and $299 \equiv 2 \pmod{3}$. So 8073 is non-Lösschian. In fact, $8073 = 3^3(13)(23)$.

In summary,

Theorem 5.17. Let N be a positive integer. Then

- N is properly representable as $x^2 + xy + y^2$ for integers x, y if and only if $N = 3^a M$, where $a = 0, 1$ and every prime factor of M is $\equiv 1 \pmod{3}$.
- N is Lösschian if $N = 3^a M T^2$, where every prime factor of M is $\equiv 1 \pmod{3}$ and every prime factor of T is $\equiv 2 \pmod{3}$.
- N is non-Lösschian if $N \equiv 2 \pmod{3}$
- N is non-Lösschian if $N = p^n M$, $(M, p) = 1$, $M \equiv 2 \pmod{3}$.

Lösschian numbers: examples of Theorem usage

In this chapter, we have proved a theorem that lets anyone determine exactly which numbers are Lösschian and which numbers are not Lösschian. The formal mechanics of proof drew on a variety of earlier theorems and on facts from number theory. The creative effort involved the recasting of Marshall's earlier work in a form that would lead to the desired conclusion of a sufficient condition. Readers wishing to examine the history of this development are referred to articles published by [Marshall](#) (1975), [S. Arlinghaus](#) (1985), and [S. Arlinghaus and W. Arlinghaus](#) (1989). So that one might see how the results of Theorem 5.17 can be implemented, we offer several examples below.

- $K = 175$ is Lösschian, since $K = 5^2 \times 7$.
- $K = 125 = 5^3$ is not Lösschian
- $K = 245 = 5 \times 7^2$ is not Lösschian
- $K = 85$ is not Lösschian, even though 85 is congruent to $1 \pmod{3}$, since $K = 5 \times 17$, and both 5 and 17 are congruent to $2 \pmod{3}$
- $K = 49$ is Lösschian as 49 may be generated using the Diophantine equation on either the ordered pair $(0, 7)$ or on $(3, 5)$: representation is not unique.

Theorem 5.17 offers an easy way to check whether a given number is Lösschian. It does not give the geometric characterization of the associated hierarchy. For that characterization, the reader then needs to return to the material in Chapter 4 and the [Fundamental Theorem](#) offered there.

Chapter 6

Back to the Real World: Eratosthenes in Ann Arbor

eHighlights of this Chapter

[Application of Eratosthenes sieve to parcel map of Ann Arbor](#)

[Virtual reality of downtown Ann Arbor: used in work on a maximum height in the downtown](#)

Back to the Real World

The synthetic approach to central place geometry, in earlier chapters, has found application (by S. Arlinghaus and others as noted) in the usual and the unusual. The articles below have all appeared in *Solstice* and links to those articles are given below (*Solstice*, itself, is a Pirelli INTERNETional Award Semi-Finalist (top 80), 2001).

- 1990, June. "[Beyond the Fractal, pages 17-35](#)" suggests a transformation of the geometry presented in this work aligned with earlier work of Hagerstrand on the diffusion of an innovation. (Link is to scanned images of hardcopy printed from original TeX files sent as e-mail transmissions with instructions to the user to print out the file on a TeX enabled printer. See [link](#) in Bibliography for access to TeX code.)
- 1990, December. "[Fractal Geometry of Infinite Pixel Sequences: "Super-definition" Resoultion? pages 98-103](#)" offers an application of this geometry to the cathode ray tube, followed up on with queries from the business world. (Link is to scanned images of hardcopy printed from original TeX files sent as e-mail transmissions with instructions to the user to print out the file on a TeX enabled printer. See [link](#) in Bibliography for access to TeX code.)
- 1993, June. "[Micro-cell Hex-nets](#)" explores the use of this geometry in association with systems of relay towers on the geographic landscape. (Link is to scanned images of hardcopy printed from original TeX files sent as e-mail transmissions with instructions to the user to print out the file on a TeX enabled printer. See [link](#) in Bibliography for access to TeX code.)
- 1996, December. "[Web Fractals: An Overview](#)"
- 2002, December. "[Spatial Synthesis: Research Program](#)" with W. C. Arlinghaus.
- 2004, June. "[Spatial Synthesis Sampler. Geometric Visualization of Hexagonal Hierarchies: Animation and Virtual Reality](#)" with W. C. Arlinghaus, a Pirelli INTERNETional Award Semi-Finalist (top 80), 2003.
- 2004, December. "[Spatial Synthesis: A 3D Atlas of Ann Arbor](#)"
- 2005, June. "[Spatial Synthesis. The Evidence of Cartographic Example: Centrality and Hierarchy.](#)" Serves as a lead-in to this book.

Communication of these ideas, an important part of real-world use of information, has appeared in a number of other locales, as well. A few links are given below to work by S. Arlinghaus (and others as noted).

- 1985. "Fractals Take A Central Place." *Geografiska Annaler, Series B*.
- 1986. "Steiner Transformations" in *Essays on Mathematical Geography*, [Monograph 3, pages 55-70](#), Institute of Mathematical Geography.
- 1987. "Fractals: Constructions, Speculations, and Concepts" in *Essays on Mathematical Geography--II*, [Monograph 5, pages 54-66](#), Institute of Mathematical Geography.
- 1989. "The Fractal Theory of Central Place Geometry: A Diophantine Analysis of Fractal Generators for Arbitrary Loschian Numbers" with W. C. Arlinghaus. *Geographical Analysis*.
- 1990 (January). "Geometry of boundary exchanges: Compression patterns for boundary dwellers" with John D. Nystuen. *The Geographical Review*, American Geographical Society of New York.
- 1991. "Table for Central Place Fractals" in *Essays on Mathematical Geography--III*, [Monograph 14, pages 6-15](#), Institute of Mathematical Geography.
- 1991. "Tiling According to the Administrative Principle" in *Essays on Mathematical Geography--III*, [Monograph 14, pages 16-25](#), Institute of Mathematical Geography.
- 1993. *Fractals in Geography* edited by Nina Siu-Ngan Lam and Lee De Cola, Chapter 10, "Central Place Fractals: Theoretical Geography in an Urban Setting." Prentice-Hall.
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Eratosthenes in Ann Arbor

Ann Arbor is a small city in southeastern Michigan. It is home to the main campus of The University of Michigan, a state university with over 35,000 students on the Ann Arbor campus. The student population composes about 1/3 of the population of the city. Much of the rest of the population works at the university in some capacity or in research industry, businesses, or institutions that locate near the campus. Most cities in the US have shapes that are topologically equivalent to a circle, in terms of paying taxes to the city: land parcels that lie within the city boundaries pays taxes to the city. There are, of course, cities that contain enclaves within their boundaries that are not part of the city itself: Detroit, for example, contains the small (in area) towns of Hamtramck and Highland Park totally within its borders. However, in the case of Ann Arbor and other small cities that contain large state universities, the city is more of an annulus (doughnut) in shape. A large hole, containing the university is cut out of the city: lands in this hole do NOT pay taxes to the city. Hence, a disproportionately large property tax burden is placed on owners of non-university parcels within the city.

For the city to offer a fine quality of life to all its residents (taxpayers and others) there need to be mechanisms to create continuing economic development within the city. One way to do this is to increase the stock of housing and space for commercial and other establishments in support of that housing. This path is all the more attractive in light of enduring interests in reducing "sprawl" and in preserving open space in the more rural surrounding lands. In a city with few remaining empty buildable lots, this approach seems to offer few alternatives, the most obvious of which is to increase the density of dwelling units within the city. When density increases are proposed in established residential neighborhoods there is often loud and long public objection from residents of those neighborhoods. There may also be serious environmental considerations, as well. Few residents, however, seem to object to increasing density in the downtown: many who already live there moved in with an acceptance of taller buildings and those who do not live there often do not care about the idea of increasing density in the downtown. What

people do seem to care about, however, is what an increase in downtown residential density may mean to the character, appearance, and feeling of the downtown. To some, an 18 story building is a visual blight on the skyline that provokes negative comment everytime it is viewed; yet, others note that they have become accustomed to it and view it as an old, familiar friend. Building height can be a source of substantial dispute.

The problem of where to locate tall buildings, with sensitivity to existing building types on adjacent and nearby lots, is a difficult one. In Ann Arbor, building height is currently limited by "floor area ratio" (FAR). The FAR is calculated as the ratio of floor area in a building divided by parcel area, times 100. If a given parcel has an FAR of 100 assigned to it, then a building footprint built lot line to lot line may have a height of 1 story. If a parcel has an FAR of 200 assigned to it, then a building footprint built lot line to lot line may have a height of 2 stories. Similarly, an FAR of 300, assigned to a parcel, yields a building of height 3 stories covering the entire parcel. Thus, on a parcel with an FAR of 300, one might, instead, build a building on half of the lot area but of height six stories, or on a third of the lot area but of height 9 stories. On the same parcel, a 30 story building could be built only if its footprint covered one-tenth of the land area of the parcel.

The FAR provides a height limit based on the size of foundation needed to support a tall building. It also offers subtle encouragement for preserving some amount of open space and visual variation in the region to which it applies. The drawback is that a tall building may get built with no regard to the broader context of how a new building will fit in with existing buildings on the surrounding parcels. A possible side effect of using FAR (alone) to limit height is that it might encourage parcel amalgamation by large developers, thereby driving out desired local small business owners.

The issue of creating greater height in the downtown is a complex one. In 2003, Mayor John Hieftje and the Ann Arbor City Council established, in conjunction with the Downtown Development Authority, DDA, (Susan Pollay, Executive Director) a Taskforce to study increasing residential land use in the downtown. Some of the materials studied by that group was created by the first author, in collaboration with others (Fred J. Beal, President Beal Construction, and Douglas S. Kelbaugh, Dean Taubman College of Architecture and Urban Planning, The University of Michigan). The material that follows highlights the use of concepts from this book that were used in that context. It, and associated materials were used in public hearings and by City Council in passing the recommendations of that Taskforce. A more [complete story](#) of the policy and 3D modeling aspects is available elsewhere (link to Arlinghaus, Beal, and Kelbaugh).

A Prime Parcel Sieve.

The FAR is assigned by zoning type. In the downtown, there are currently parcels assigned to each of 22 different zoning categories (AG, C1, C1A, C1AR, C2A, C2AR, C2B, C2BR, C3, M1, M1A, M2, O, P, PL, PUD, R1D, R2A, R2B, R4B, R4C, R4D). Roughly speaking, any category beginning with C is a commercial category; M is for manufacturing; R is for residential. The AG category is for agricultural zoning, O is for office, P (except for PUD) is for Public Land (as for the University of Michigan), and PUD is for Planned Unit Development.

Enumeration of parcels via geometric partition

In Figure 6.1, the animated map shows the downtown area of the City of Ann Arbor parcel map colored as a thematic map by zoning category: the broad PL zoning is part of the central campus of the University of Michigan. The curved line near the left side of the map, representing the Ann Arbor Railroad corridor, has most of the manufacturing parcels adjacent to it. Separate categories enter the picture in sequence, arranged according to alphabetical ordering of zoning category. The coloring scheme is exhaustive: every parcel is covered. It is also mutually exclusive: no parcel has more than one color. Thus, the zoning classification serves as a geometric partition of the parcels. It offers a way to enumerate all the parcels: to order them in some logical fashion and to assign some quality to them as well, in much the way that we assign both cardinal and ordinal properties to numbers.

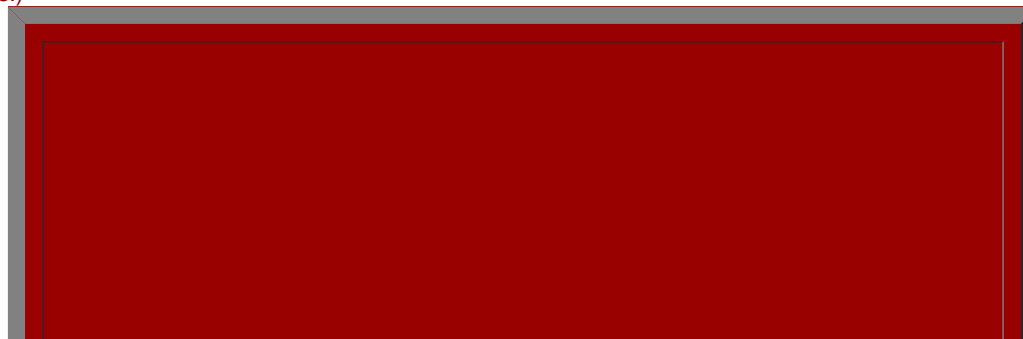


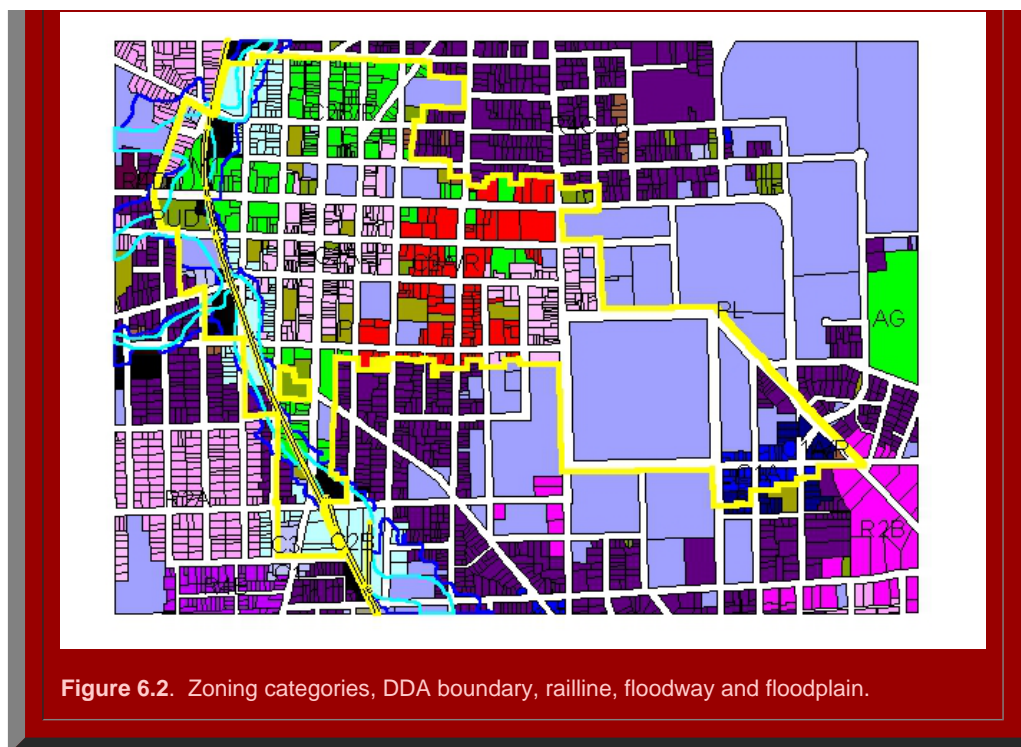


The casting out of parcels

With an enumeration of all parcels in hand, groups of parcels will be removed in accordance with various ideas. The goal is to select targets of opportunity for taller projects. The mechanism for such selection is similar to the mechanism for the selection of prime numbers employed by Eratosthenes ([link](#) back to Eratosthenes's Sieve). In the case of the downtown, parcels meeting certain criteria are cast out from further consideration as prime parcels much as numbers meeting certain criteria (multiples of 2, multiples of 3, multiples of 5, and so forth) were cast out from further consideration as prime numbers. What remains, are "primes": prime numbers or prime parcels. These prime parcels will then be viewed as possible targets of opportunity. Local considerations of various sorts might then be superimposed on them, such as design standards, spacing of tall buildings, or whatever constraints are within the legal [code](#) of the city.

Animated maps are useful for showing change; static maps are useful when one wishes to take a longer look at pattern without regard to change in pattern. Thus, Figure 6.2 shows the final frame of the animated map in Figure 6.1 along with a layer showing the boundary of the Downtown Development Authority (DDA) in yellow, the railline in black/yellow, the floodway (channel) outline of Allen's Creek in blue, and the floodplain outline of Allen's Creek in cyan. We begin the process of casting out parcels according to some replicable logic (not as 'multiples' but according to some logical scheme). (In Ann Arbor, the "downtown" generally refers to the DDA: a state-enabled authority that can capture increases in taxable value to pay for improvements within the defined boundaries.)



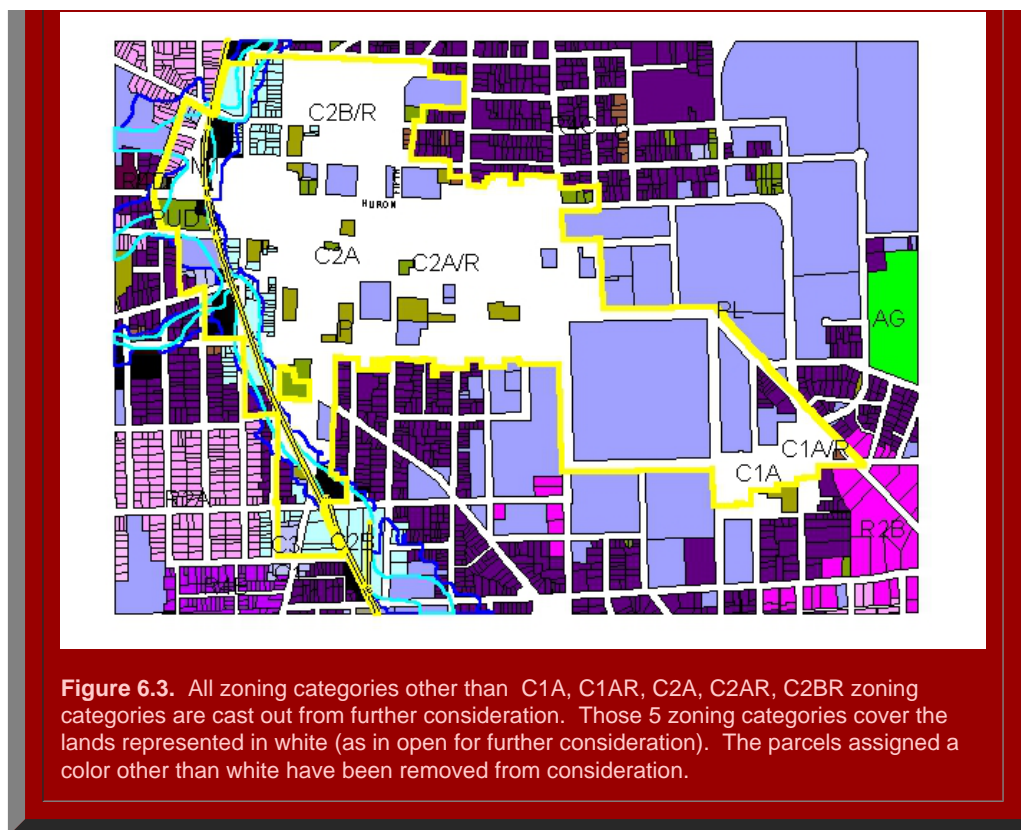


CASTING OUT:

- **All zoning categories that cannot support height in excess of FAR are cast out.**

Consider only zoning categories, as the downtown "core," of C1A, C1AR, C2A, C2AR, C2BR as those categories that might contain parcels that are targets of opportunity for building structures of height greater than that permitted by FAR. Thus, all parcels of zoning type other than those 5 are cast out from further consideration. This process opens up quite a bit of land within the DDA as possibilities for tall buildings (shown in white in Figure 6.3). As in the prime number seive, the first step removes a substantial set, parcels in color, from further consideration. Subsequent steps remove smaller subsets from further consideration.

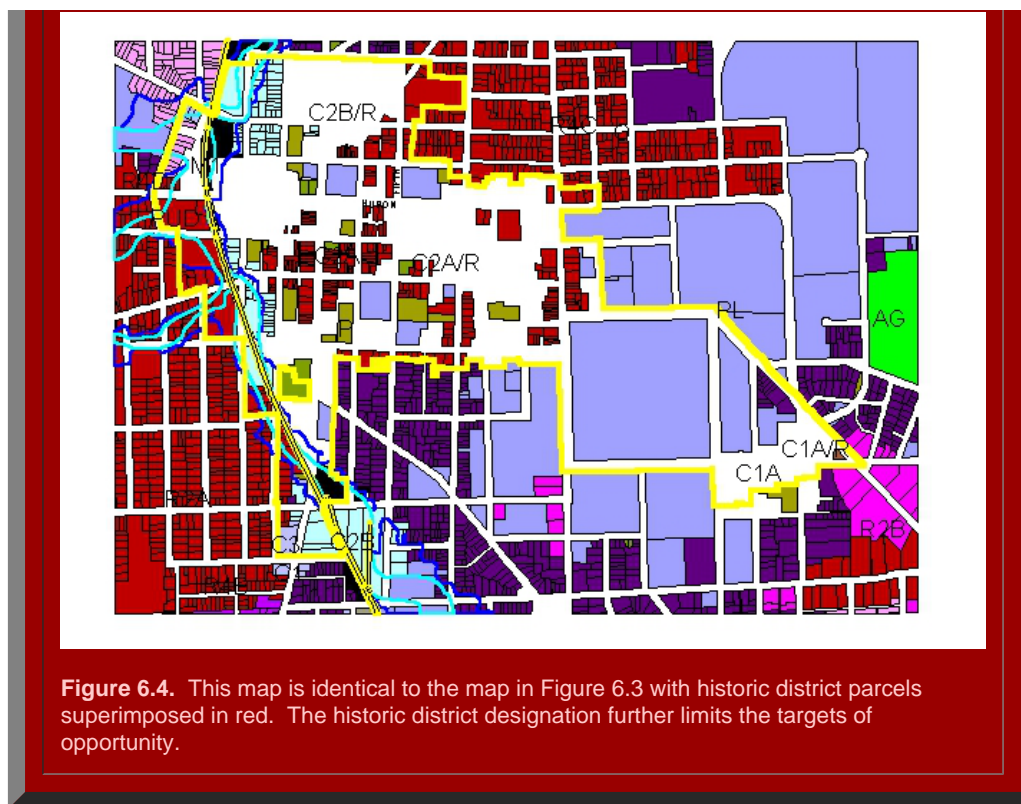




- **All historic district parcels are cast out.**

When parcels containing historic district designation (and often relatively short buildings) are superimposed on the pattern in Figure 6.3, further limitation of targets of opportunity is the result (in Figure 6.4, historic district parcels are red). In this step, all historic district parcels are cast out, further limiting the number of parcels eligible to be considered for "prime" parcel status (Figure 6.4). The white area, targets of opportunity for tall buildings within the DDA, remains large but not as large as in Figure 6.3. Successive casting out of other parcels continues in the steps to follow.





- **Floodplain parcels are cast out.**

All parcels whose centroids lie within the floodplain of Allen Creek are cast out as possible prime parcels. Parcels that intersect the floodplain, but whose centroid does not lie in the floodplain remain. The reason to use the centroid analysis is that public benefit might come from having a building erected on the part of the parcel not in the floodplain and saving the part of the parcel in the floodplain as part of a greenway or other broad environmental amenity.

- **All parcels containing "steep slopes" are cast out.**

Many of these are also floodplain parcels, as above. Elsewhere, the definition of "steep slope" is problematic. Generally, the DDA is fairly flat, away from the creek valley.

- **Church parcels are cast out.**

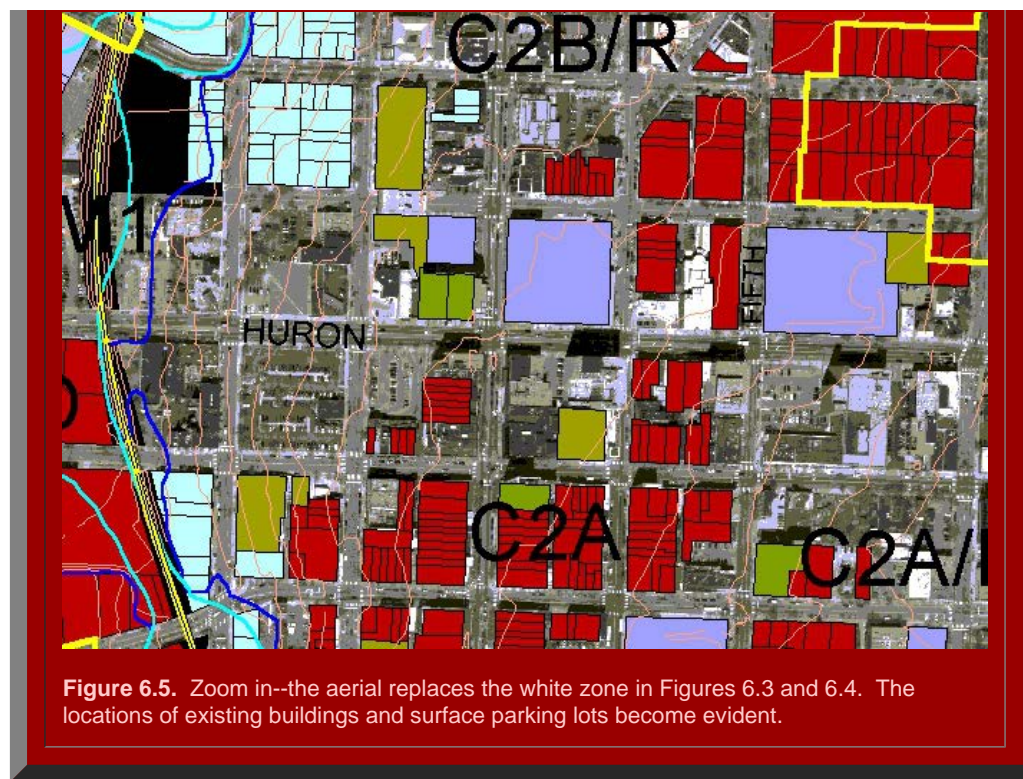
Parcels containing churches, as listed in published official records, are cast out.

All possible prime parcels, as targets for opportunity to support buildings of height in excess of the FAR, are those that pass through this sieve: those that are not cast out based on zoning, environmental, and cultural factors above.

Zooming in

To take a closer look at the area, zoom in on a portion of it. One idea is to use the street hierarchy to select general target areas: wider streets support taller nearby structures. Thus, the zoom-in of Figure 6.5 is on Huron Street, the widest street in the DDA. Insert an aerial photo behind the map: the "white" area of earlier maps has been replaced with aerial so that one can see directly the current content of all potential prime parcels. With the aerial replacing the white zone, one can see what is currently located on each parcel. Thus, identification of immediate targets is easy: note the surface parking lots (with clearly underutilized existing infrastructure). Parcels already containing buildings might, or might not, become targets.





The map in Figure 6.5 shows each parcel from lot line to lot line. Building footprints were digitized from aerials provided by the City. Associated databases gave estimates of building height. [Interactive maps](#) offered a constructive way to link a variety of two dimensional sets of information (as in Maps 6.1, 6.2, and 6.3).

- [I-Map 6.1: Click here](#) for a link to an interactive map showing building footprints and height (on mouse-over) as well as building address and street names (on mouse-over). Parcel boundaries are shown on the underlying aerial and on the green Downtown Development Authority (DDA) area. The Allen Creek floodway (underground) and flood plain are shown, shaded, respectively in blue and turquoise. Click on a building or a street to see associated entries in the underlying database.
- [I-Map 6.2: Click here](#) for a link to an interactive aerial showing parcel boundaries, zoning, building height (on mouse-over), and street name. DDA outline, only, is shown in light yellow so the user may zoom in to get a closer view of the aerial within the DDA (up to 800% enlargement--can see cars clearly). The Allen Creek floodway (underground) and flood plain are shown, outlined, respectively in blue and light blue; again, because the shading is removed, the viewer may look at the content of the floodway/floodplain in greater detail than above. Click on a building or a street to see associated entries in the underlying database.
- [I-Map 6.3: Click here](#) for a link to an interactive aerial showing zoning boundaries in the downtown, zoning type (on mouse-over), building height (in the "zoneht" record of the database), and street name. Click on a building or a street to see associated entries in the underlying database.

Designing the Vertical City: the Use of Virtual Reality Models

Once the parcels that could serve as targets of opportunity for tall buildings were agreed upon by the Taskforce, the prime parcels, a series of several hundred virtual reality models were developed to visualize alternatives for the DDA. The reader interested in the detail of the planning process, local policy matters, and the mechanics involved in model construction are referred to the following materials in the references. The focus here is on the use of a concept identical to Eratosthenes prime number sieve to sift out parcels eligible for further consideration, as above, and the subsequent application of virtual reality to visualize complex geometric situations, as in the case of Christaller nets, in order to facilitate scientific communication and eventual policy decisions by official municipal bodies.

The set of buildings that currently exist within the DDA was used as a base on which to build alternative scenarios of what might be done. Figure 6.6a shows a screen-capture of a virtual reality model built by extruding building footprints according to height records from the City of Ann Arbor Planning Department (Figure 6.6b is the virtual reality model; try driving around in it).

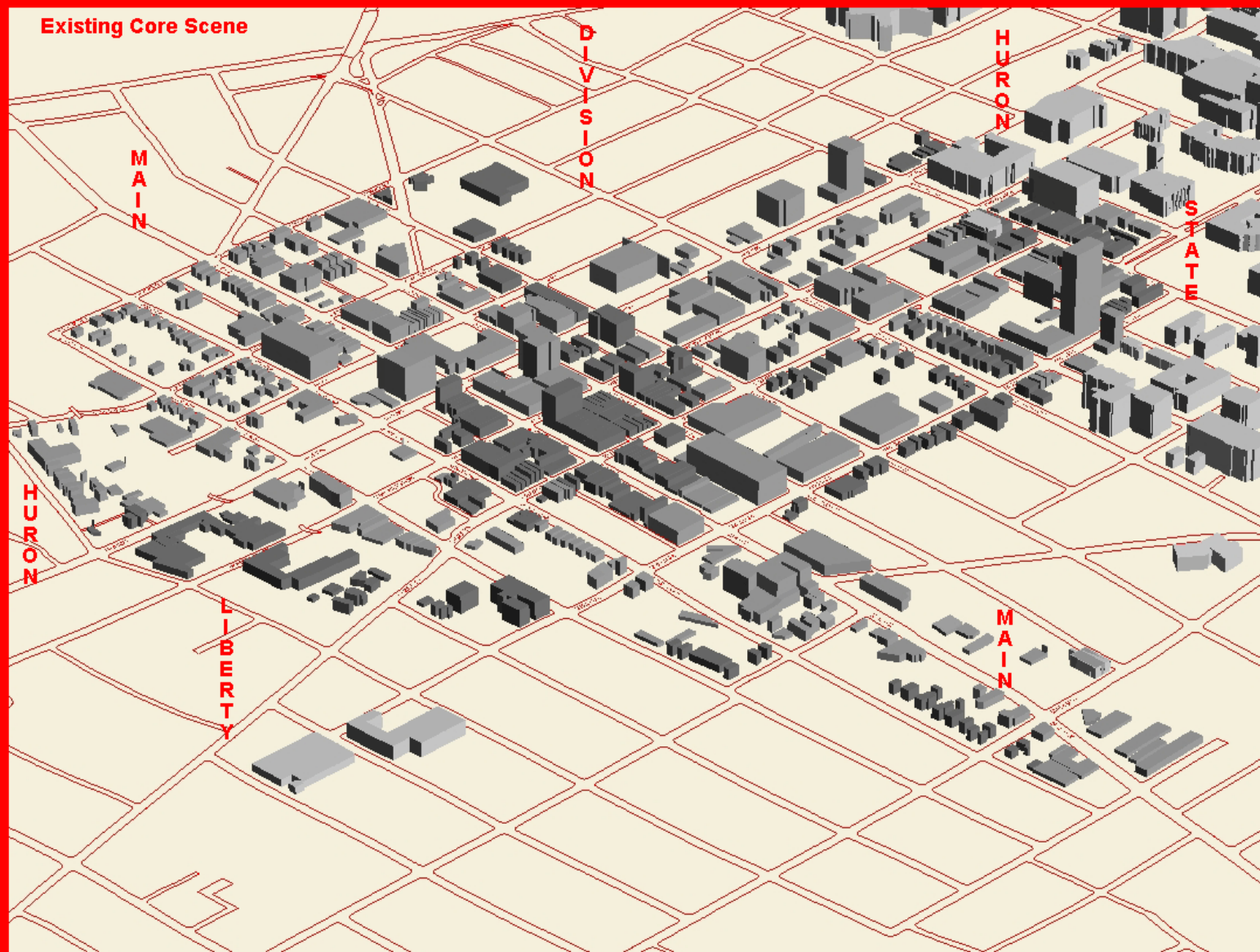


Figure 6.6a. Downtown Ann Arbor buildings extruded from footprints digitized from aerial.
 Figure 6.6b: [link](#) to virtual reality model from which Figure 6.6a was taken.

Figures 6.7a and b, 6.8a and b suggest how that model was used: colored buildings are added, only on prime parcels, according to numbers of residential units to be added and to guidelines suggested by Taskforce members (selected for expertise in construction, urban planning, architecture, and so forth). Different building colors respond to different particular suggestions. This set of four models represents merely one possible scenario; input from numerous sources was important in creating a variety of alternatives for policy makers to consider.

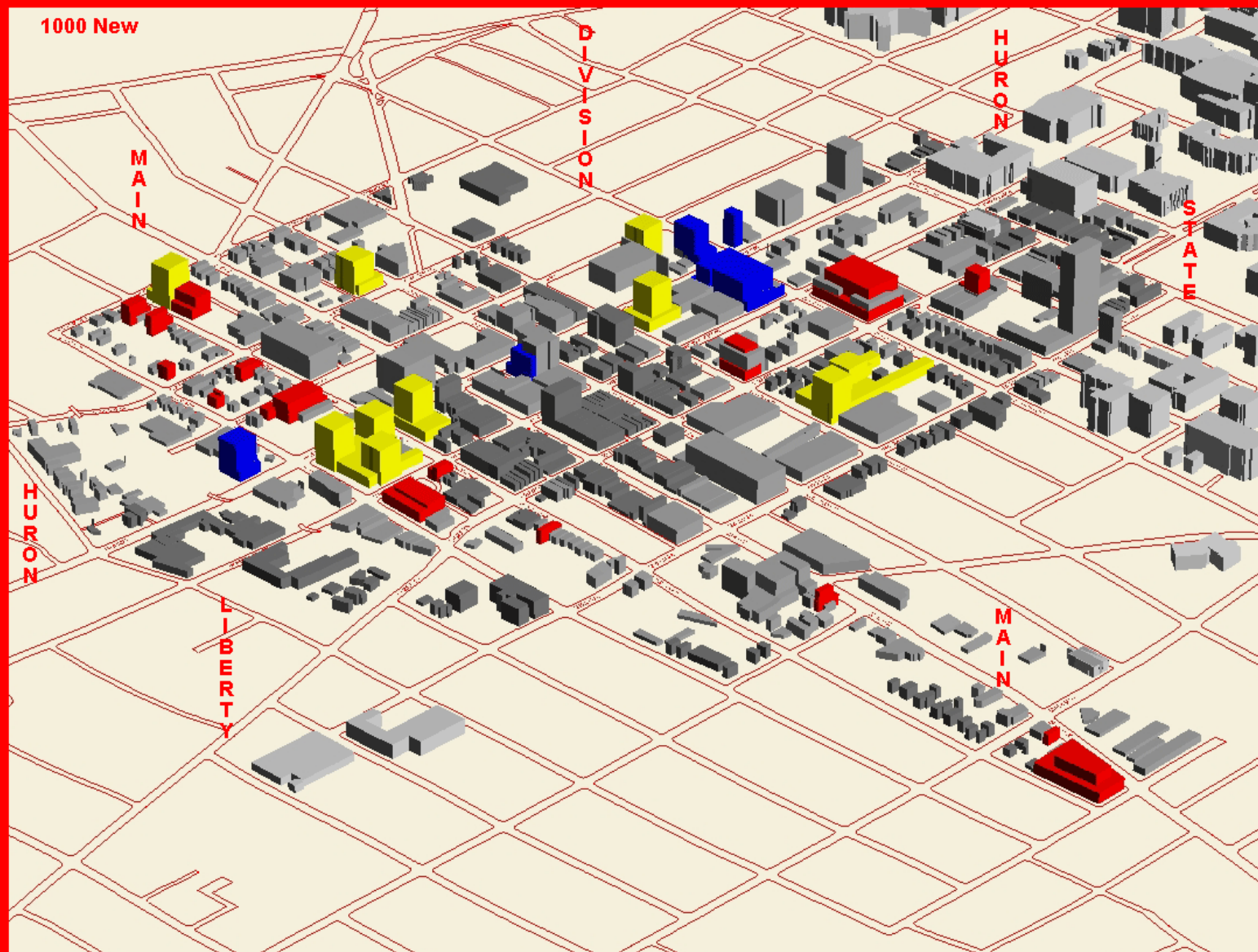


Figure 6.7a. Downtown Ann Arbor buildings extruded from footprints digitized from aerial. Gray buildings are existing buildings. Yellow buildings are built on empty lots or on surface parking lots. Blue buildings are built along Huron Street (possibly as replacements for, or on top of, existing buildings). Red buildings are built with upper story setbacks on a subset of streets identified by the Taskforce. The number of new buildings is sufficient to support 1000 new residential units. All non-gray buildings are built on prime parcels.

Figure 6.7b: [link](#) to virtual reality model from which Figure 6.7a was taken.

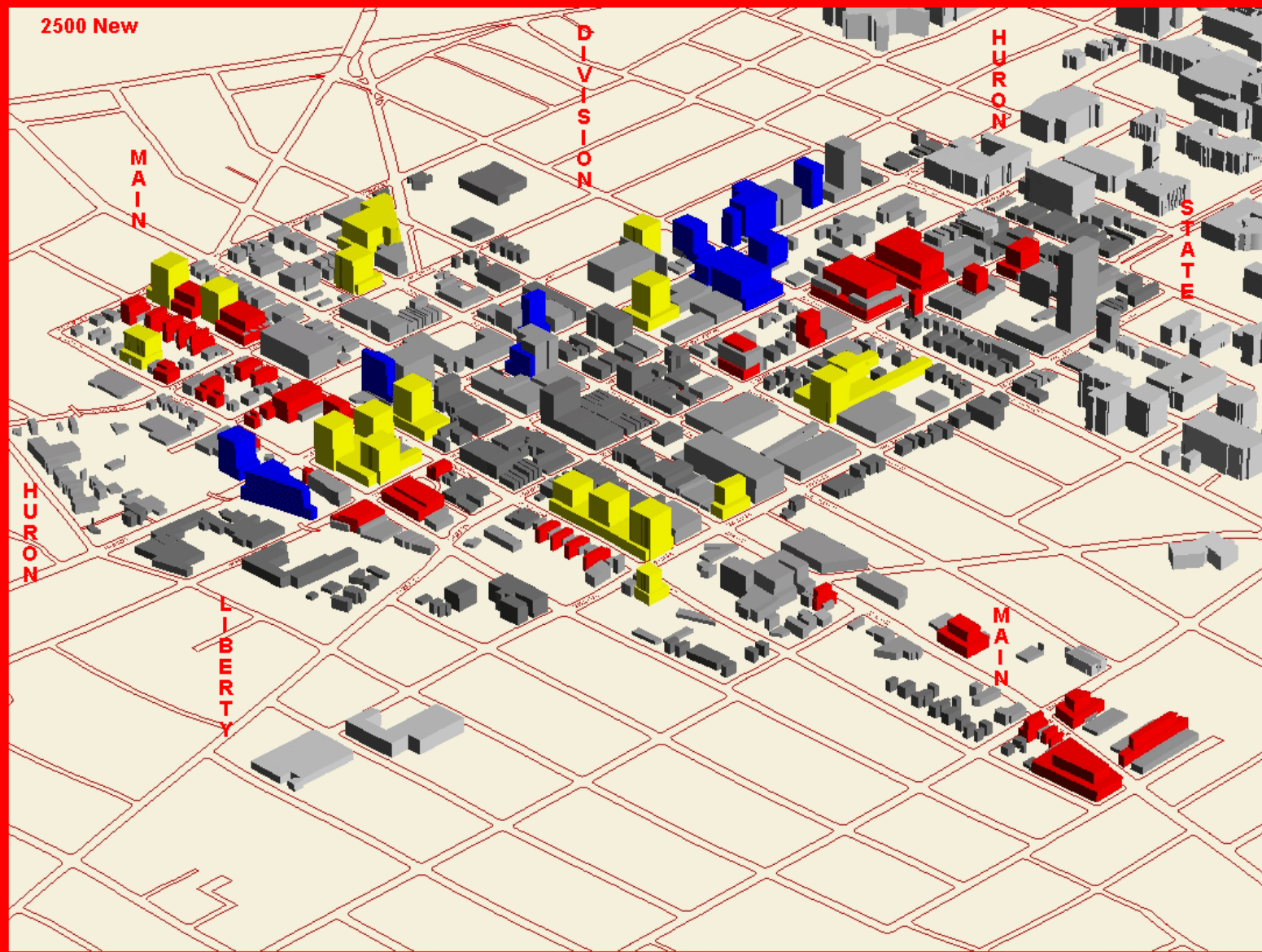


Figure 6.8a. Downtown Ann Arbor buildings extruded from footprints digitized from aerial. Gray buildings are existing buildings. Yellow buildings are built on empty lots or on surface parking lots. Blue buildings are built along Huron Street (possibly as replacements for, or on top of, existing buildings). Red buildings are built with upper story setbacks on a subset of streets identified by the Taskforce. The number of new buildings is sufficient to support 2500 new residential units. All non-gray buildings are built on prime parcels.

Figure 6.8b: [link](#) to virtual reality model from which Figure 6.8a was taken.

Virtual reality models served to pique conversations and help Taskforce members to visualize alternatives. Eventually, they saw a need to compare one virtual reality model to another. For that purpose, "viewpoints" were inserted into the VR models (find the "viewpoints" pull down in Figures 6.6b, 6.7b, 6.8b, so that different models could each be viewed from exactly the same vantage point (guided by the computer). While the insertion of viewpoints was helpful, direct comparison still required retention of a great deal of visual information in one's memory. Animation of the models of the DDA, as in Figure 6.9 offered a way to look at multiple global alternatives.

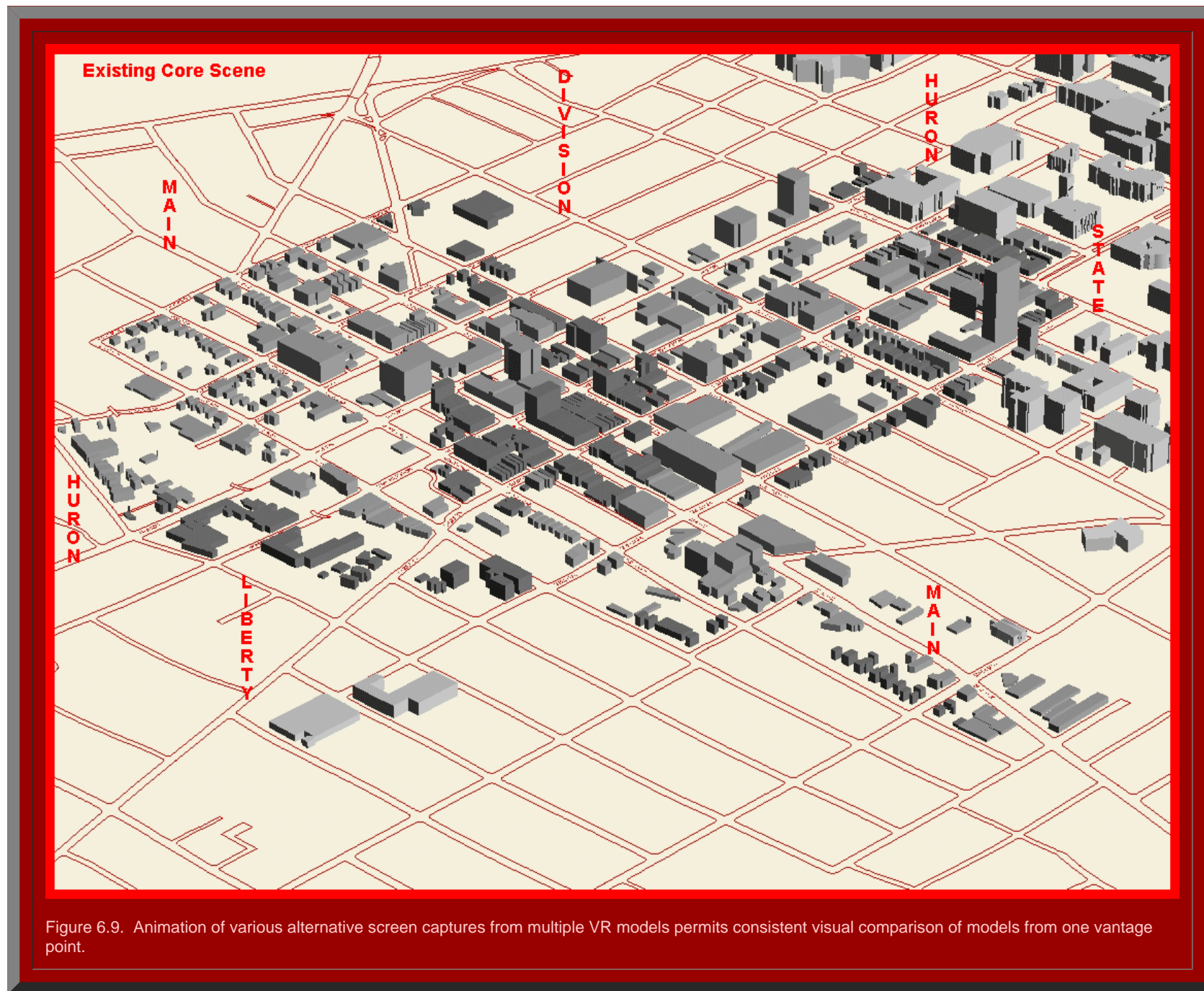


Figure 6.9. Animation of various alternative screen captures from multiple VR models permits consistent visual comparison of models from one vantage point.

Thus, the solution for local views was also to take screen captures from the same viewpoint of different VR models and stack them in an animation. The 3D VR models above were built on May 27, 2004. Earlier models were shown to the public on April 27; public reaction was used to create a responsive model on May 3. The May 3 model was used in conjunction with the April 27 model as a stacked animation built from the taller April 27 model fading into the shorter response model. The results were presented to the Taskforce, May 10, as in Figures 6.10, 6.11, 6.12, and others. These exemplify the idea of using animation to make clear visual comparisons by taking screen captures from VR models from the same viewpoint: the VR models might all be from the same time, as in Figure 6.9, or they might be from different times as well, as in Figures 6.10, 6.11, and 6.12.

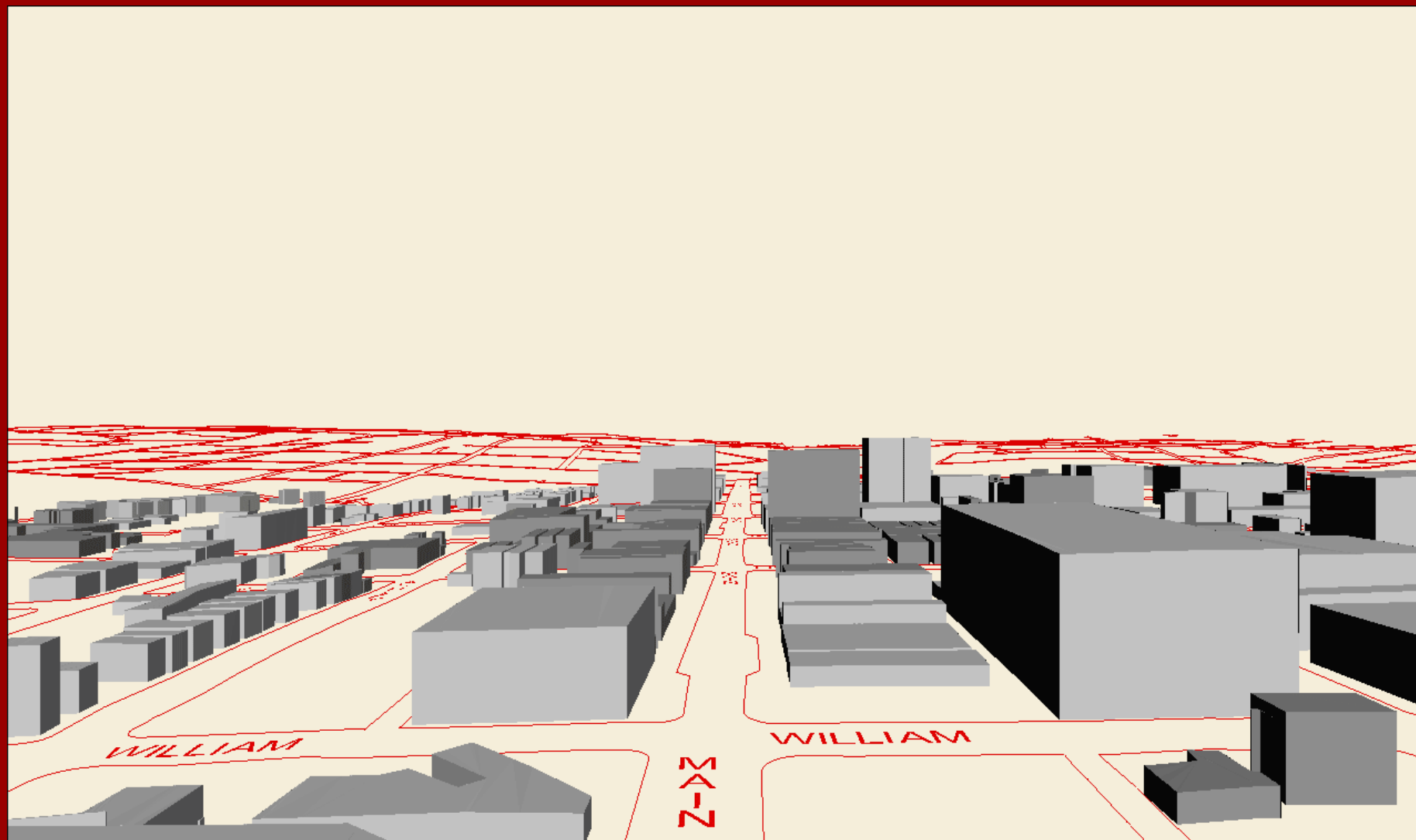


Figure 6.10. Animation of various alternative screen captures from multiple VR models permits consistent visual comparison of models from one vantage point.

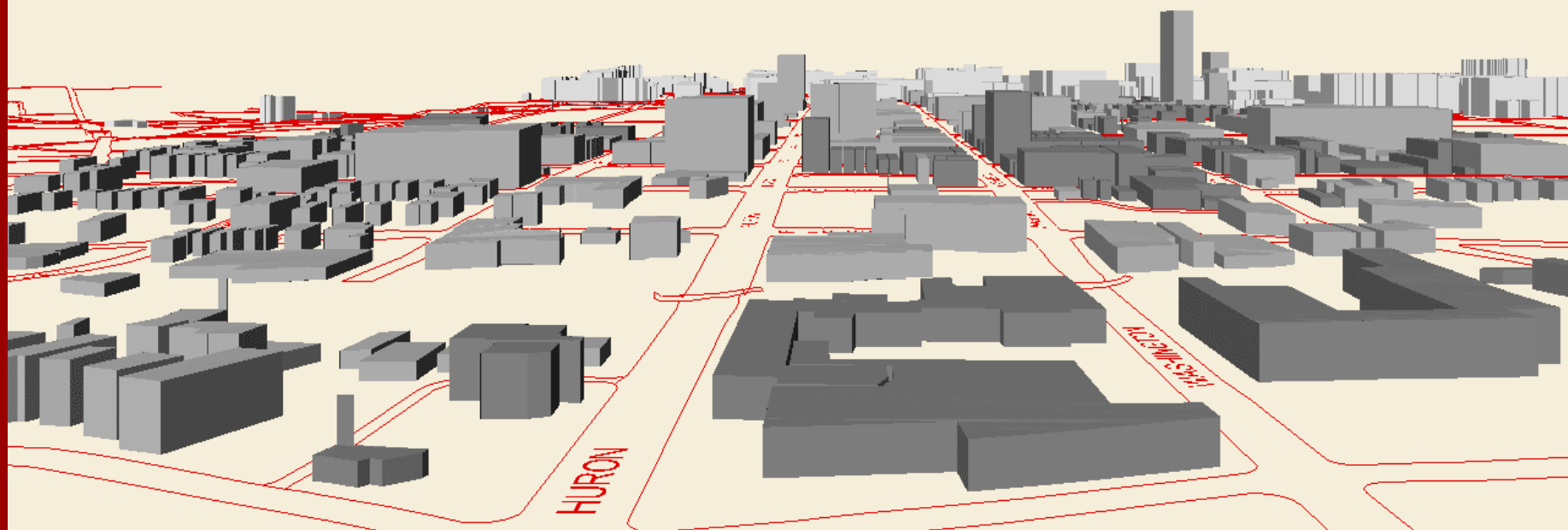


Figure 6.11. Animation of various alternative screen captures from multiple VR models permits consistent visual comparison of models from one vantage point.

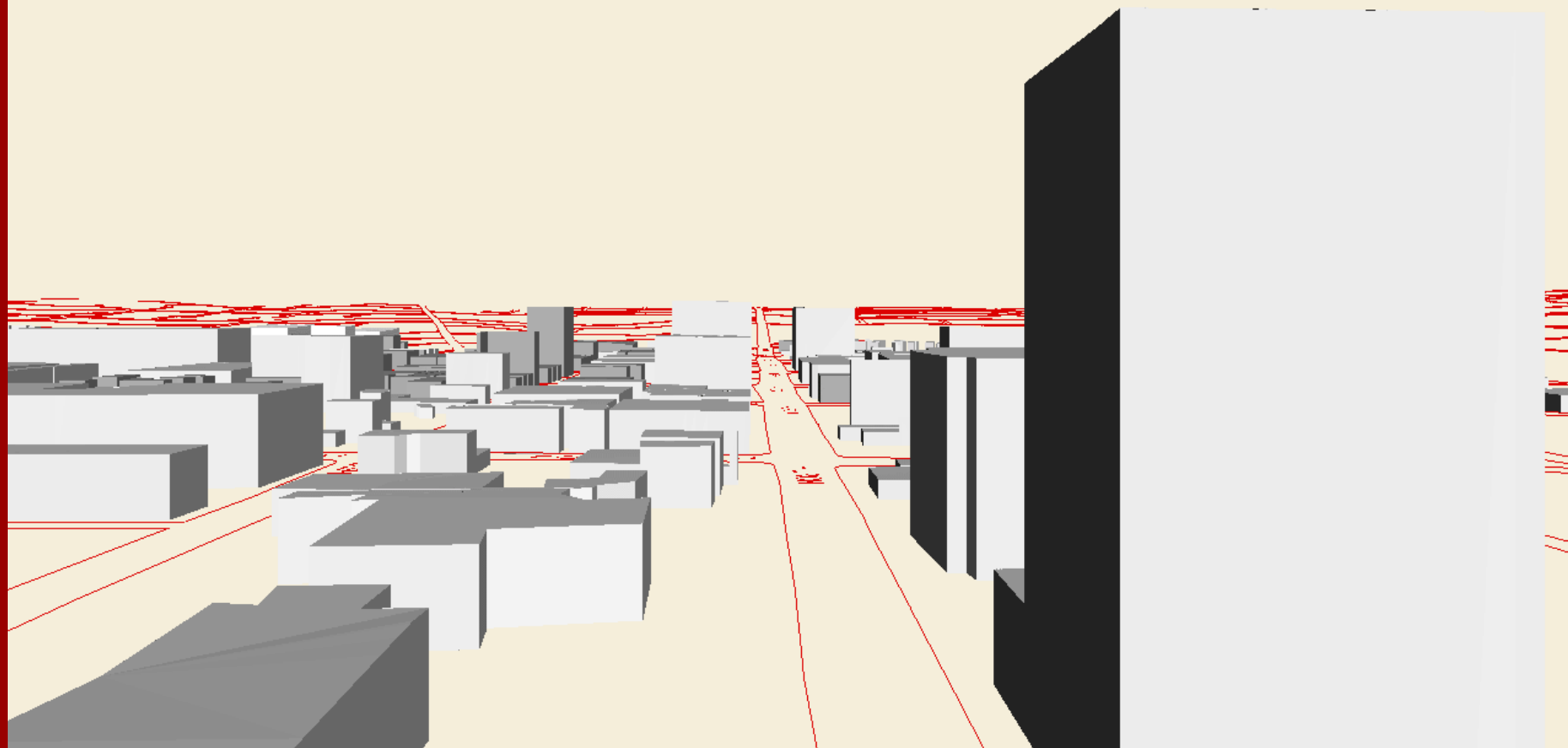


Figure 6.12. Animation of various alternative screen captures from multiple VR models permits consistent visual comparison of models from one vantage point.

These models, and results from hundreds of others, were presented to the Taskforce in 11 different meetings in the spring of 2004. They were presented in a public hearing to the citizens of Ann Arbor on April 27, 2004 as chronicled in a front page story in The Ann Arbor News with a picture of a model on the front page. They were presented to the Mayor and City Council on June 7, 2004. A previous [article](#) in Solstice describes this activity in detail. On July 19, 2004, the resolution derived in part from these models was approved by City Council with a request for a special session in September subsequent to the opportunity for City Council to analyze the mass of materials. From sieve to virtual reality, the strategy employed in one local study condensed time across millennia.

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Spatial Synthesis: Centrality and Hierarchy, Volume 1, Book 1.
Sandra Lach Arlinghaus and William Charles Arlinghaus

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Software used in the course of making this book was made by the following firms:

- Environmental Systems Research Institute, ArcView and ArcGIS software
- Macromedia, Dreamweaver, MX.
- Adobe, Photoshop and ImageReady, 7.0
- Sun Microsystems
- Microsoft
- Alta 4 (Germany), ImageMapper
- Discreet, 3D Studio Max
- Animal Movement (Alaska Biological Station)
- Fractal Music 1.9, <http://www.fractal-vibes.com>; free download.

Hardware used centered on the equipment in the "Usability Lab" of the Duderstadt Center (with two flat screen monitors working together for a wide view) and on a Hewlett-Packard Pavilion f1903, with an Intel Pentium 4 Processor, 512 MB PC3200 DDR SDRAM memory, Intel Graphics Media Accelerator, 200GB hard drive and a 19 inch flat screen monitor set to highest resolution.

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Spatial Synthesis: Centrality and Hierarchy, Volume I, Book 1.

Sandra Lach Arlinghaus and William Charles Arlinghaus

Appendices

- [Eratosthenes's Measurement of the Earth](#)
 - [Latitude and Longitude](#)
 - [Earth-Sun Relations](#)
 - [Trigonometry](#)
 - [Thiessen Polygons](#)
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Spatial Synthesis: Centrality and Hierarchy, Volume I, Book 1.

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ERATOSTHENES'S MEASUREMENT OF THE CIRCUMFERENCE OF THE EARTH

Eratosthenes of Alexandria (appointed Director of the Great Library at Alexandria in 236 B.C.) was an innovator in measurement. Not only did he create a prime number sieve, but also he figured out how to measure the circumference of the Earth. To do so, he used Euclidean Geometry and simple measuring tools. Below, we show the style of measurement that he is said to have made (different accounts give different details).

- Assume the Earth is a sphere.
- The circumference of the sphere is measured along a great circle on the sphere.
- Find the circumference of the Earth by finding the length of intercepted arc of a small central angle.
- Find two places on the surface of the Earth that lie on the same meridian (or close to it): meridians are halves of great circles.
- Eratosthenes chose Alexandria and Syene, near contemporary Aswan (Figure 1).

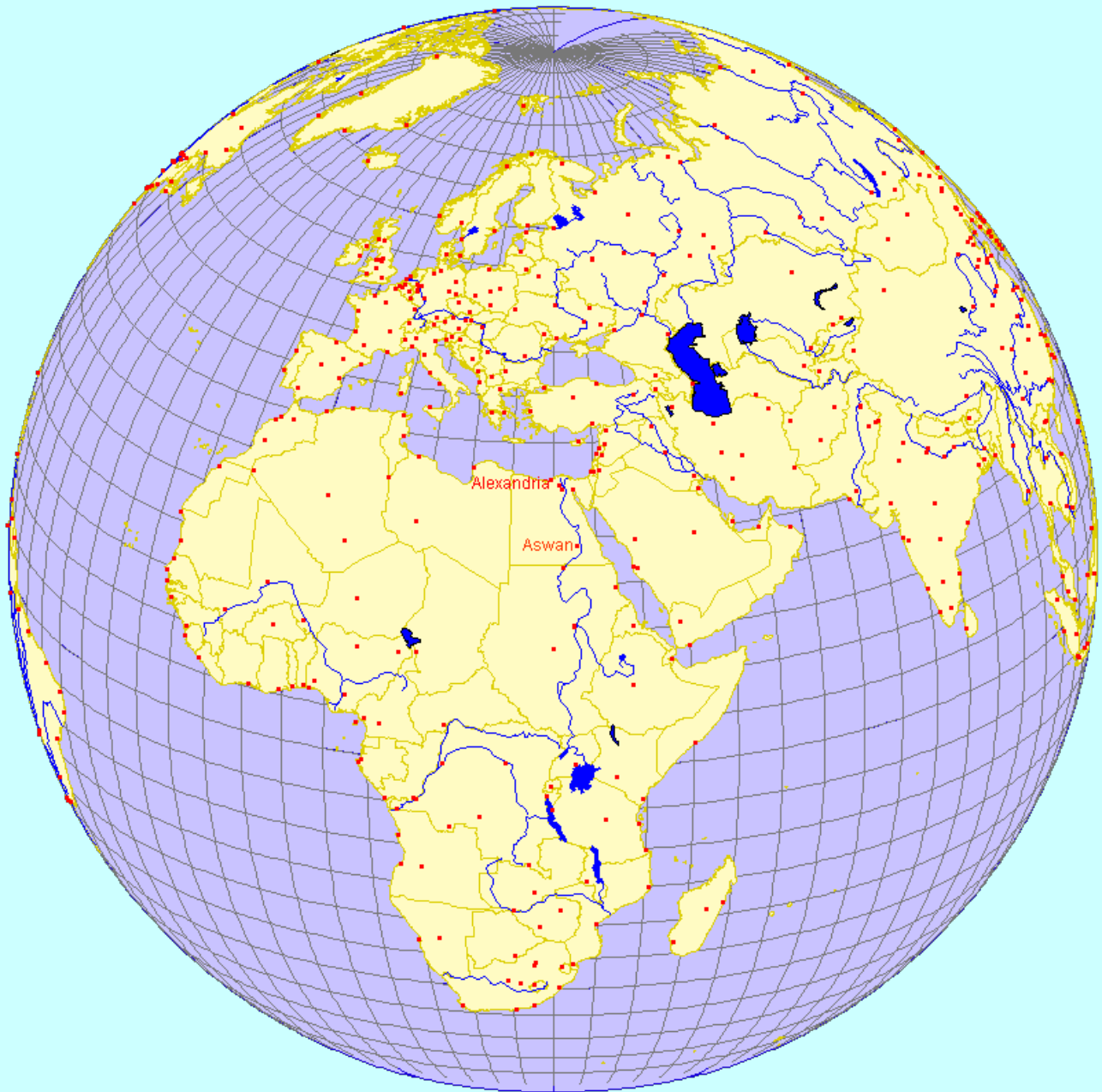


Figure 1. Relative location of Alexandria and Aswan. They are close to lying on the same meridian (half of a great circle).

- Assume that the rays of the Sun are parallel to each other.
- The Sun's rays are directly overhead, on the Summer Solstice (c. June 21), at 23.5 degrees N. Latitude.
- Syene is located at about 23.5 degrees N. Latitude. Hence, on the Summer Solstice, the reflection of the sun will appear in a narrow well (and it will not on other days). Eratosthenes apparently understood this idea.
- Alexandria is north of Syene. Thus, on June 21, objects at Alexandria will cast shadows whereas those at Syene will not.
- Eratosthenes focused on an obelisk or post located in an open area. He measured the shadow that the obelisk cast (A'A''), functioning in the manner of a gnomon on a sundial, and then measured the height of the obelisk (AA') (perhaps using a string anchored to the tip of the obelisk).

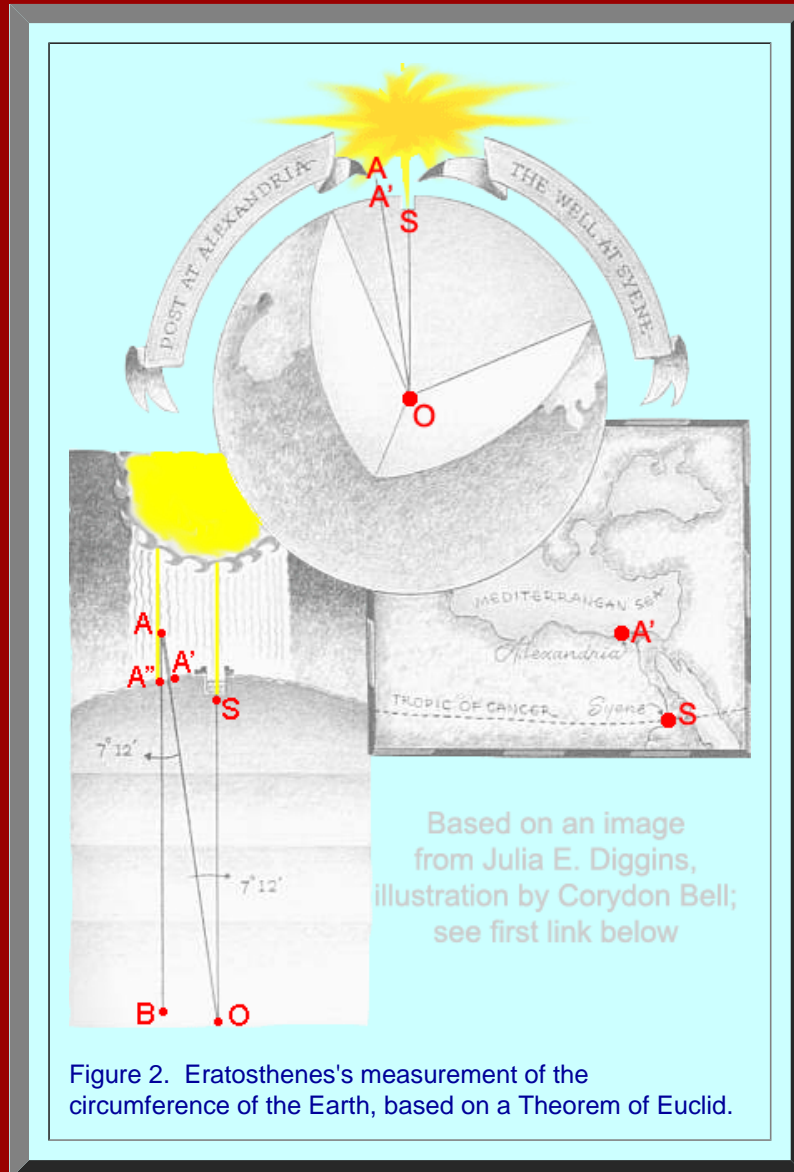


Figure 2. Eratosthenes's measurement of the circumference of the Earth, based on a Theorem of Euclid.

- According to Euclid, two parallel lines cut by a transversal have alternate interior angles that are equal. The Sun's rays are the parallel lines. One ray, at Alexandria, touches the tip of the obelisk and extends earthward toward the tip of the shadow of the obelisk, AA''. It is extended to AB in Figure 2. The other ray, SO, at Syene, goes into the well and extends abstractly to the center of the Earth, O. The obelisk, AA', also extends abstractly to the center of the Earth, O; thus, the line, AO, determined by the tip of the obelisk and the center of the Earth is a transversal cutting the two parallel rays, SO and AB, of the sun.
- Angles (BAO) and (SOA) are thus alternate interior angles in geometric configuration described above; therefore, they are equal.
- Use the length of the obelisk shadow and the height of the obelisk to determine angle BAO; triangle AA'A'' is a right triangle with the right angle at A'. Thus, we would note, $\tan(A'AA'') = (\text{length of shadow})/(\text{height of obelisk})$. Eratosthenes's measurements of these values led him to conclude that the measure of angle (A'AA'') was 7 degrees and 12 minutes.
- The value of 7 degrees and 12 minutes is 1/50th of the degree measure of a circle. Since he assumed that Alexandria and Syene both lay on a meridian (half a great circle), it followed that the distance between these two locations was 1/50th of the circumference of the Earth.
- Eratosthenes calculated the distance between Alexandria and Syene using records involving camel caravans. The distance he

used was 5000 stadia. Thus, the circumference of the Earth is 250,000 stadia, which translates to somewhat less than 25,000 miles (depending on how ancient units convert to modern units). This value is remarkably close to current values used.

Many of the assumptions made by Eratosthenes were not accurate; apparently, however, underfit and overfit of error balanced out to produce a good result. For example, Syene and Alexandria are not on the same meridian; Syene is not at exactly 23.5 degrees N. Latitude, and so forth. See the link to Astronomy Online for more discussion of historical and astronomical matters.

J. E. Diggins, The Whole Round Earth, <http://www.anselm.edu/homepage/dbanach/erat.htm>

Astronomy Online: <http://www.algonet.se/~sirius/eaae/aol/market/collabor/erathost/>

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Latitude and Longitude

Figures and text based on images and text from a GeoSystems webpage which no longer exists.
Permission was granted for an earlier use of selected images when the previous site was contacted.

Consider the Earth to be modeled as a sphere: the Earthsphere. The Earth is not actually a sphere, but a sphere is a good approximation to its shape and the sphere is easy to work with using classical mathematics of Euclid and others.

- Given a sphere and a plane. There are only a few logical possibilities about the relationship between the plane and the sphere.
 - The sphere and the plane do not intersect.
 - The plane touches the sphere at exactly one point: the plane is tangent to the sphere.
 - The plane intersects the sphere.
 - and does not pass through the center of the sphere: in that case, the circle of intersection is called a small circle.
 - and does pass through the center of the sphere: in that case, the circle of intersection is as large as possible and is called a great circle.
- Great circles are the lines along which distance is measured on a sphere: they are the geodesics on the sphere.
 - In the plane, the shortest distance between two points is measured along a line segment and is unique.
 - On the sphere, the shortest distance between two points is measured along an arc of a great circle.
 - If the two points are not at opposite ends of a diameter of the sphere, then the shortest distance is unique.
 - If the two points are at opposite ends of a diameter of the sphere, then the shortest distance is not unique: one may traverse either half of a great circle. Diametrically opposed points are called antipodal points: anti+pedes, opposite+feet, as in drilling through the center of the Earth to come out on the other side.
- To reference measurement on the Earthsphere in a systematic manner, introduce a coordinate system.
 - One set of reference lines is produced using a great circle in a unique position (bisecting the distance between the poles): the Equator. A set of evenly spaced planes, parallel to the equatorial plane, produces a set of evenly spaced small circles, commonly called parallels. They are called that because it is the planes that are parallel to each other.
 - Another set of reference lines is produced using a half of a great circle, joining one pole to another, that has a unique position: the half of a great circle that passes through the Royal Observatory in Greenwich, England (three points determine a circle). Here it is historical consideration that produces the uniqueness in selection. Choose a set of evenly spaced halves of great circles obtained by rotating the diametral plane along the polar axis of the Earth. These lines are called meridians: meri+dies=half day, the situation of the Earth at the equinoxes (see page on [seasons](#)). The unique line is called the Prime Meridian; other halves of great circles are called meridians.

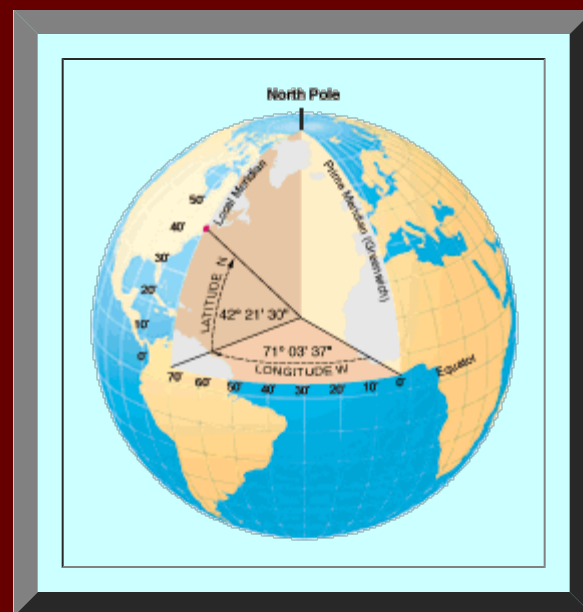
This particular reference system for the Earth is not unique; an infinite number is possible. There is abstract similarity between this particular geometric arrangement and the geometric pattern of Cartesian coordinates in the plane.

- To use this arrangement, one might describe the location of a point, P , on the Earthsphere as being at the 3rd parallel north of the Equator and at the 4th meridian to the west of the Prime Meridian. While this might serve to locate P according to one reference system, someone else might employ a reference system with a finer mesh (halving the distances between success lines) and for that person, a correct description of the location of P would be at the 6th parallel north of

the Equator and at the 8th meridian to the west of the Prime Meridian. Indeed, an infinite number of locally correct designations might be given for a single point: an unsatisfactory situation in terms of being able to replicate results. The problem lies in the use of a relative, rather than an absolute, locational system.

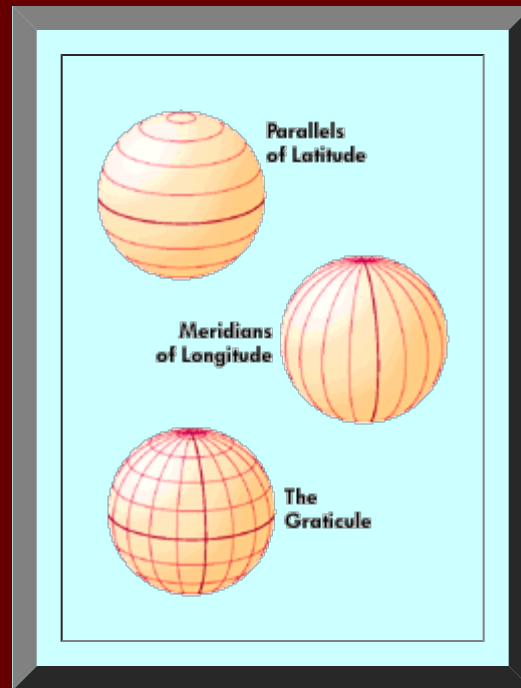
- To convert this system to an absolute system, that is replicable, employ some commonly agreed upon measurement strategy to standardize measurement. One such method is the assumption that there are 360 degrees of angular measure in a circle.
 - Thus, *P* might be described as lying 42 degrees north of the equator, and 71 degrees west of the Prime Meridian. The degrees north are measured along a meridian; the degrees west are measured along the Equator or along a parallel (the one at 42 north is another natural choice). The north/south angular measure is called Latitude; the east/west angular measure is called Longitude.
 - The use of standard circular measure creates a designation that is unique for *P*; at least unique to all whose mathematics rests on having 360 degrees in the circle.

Parts of degrees may be noted as minutes and seconds, or as decimal degrees. A degree (°) of latitude or longitude can be subdivided into 60 parts called minutes ('). Each minute can be further subdivided into 60 seconds ("). Thus, 42 degrees 30 minutes is the same as 42.50 degrees because $30/60 = 50/100$. Current computerized mapping software often employs decimal degrees as a default; older printed maps may employ degrees, minutes, and seconds. Thus, the human mapper needs to take care to analyze the situation and make appropriate conversions prior to making measurements of position. Such conversion is simple to execute using a calculator. For example, 42 degrees 21 minutes 30 seconds converts to $42 + 21/60 + 30/3600$ degrees = 42.358333 degrees; powers of ten replace powers of 60.

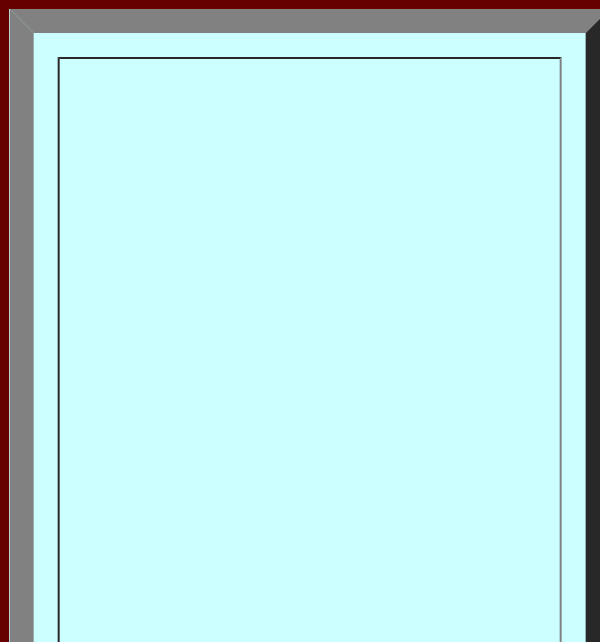


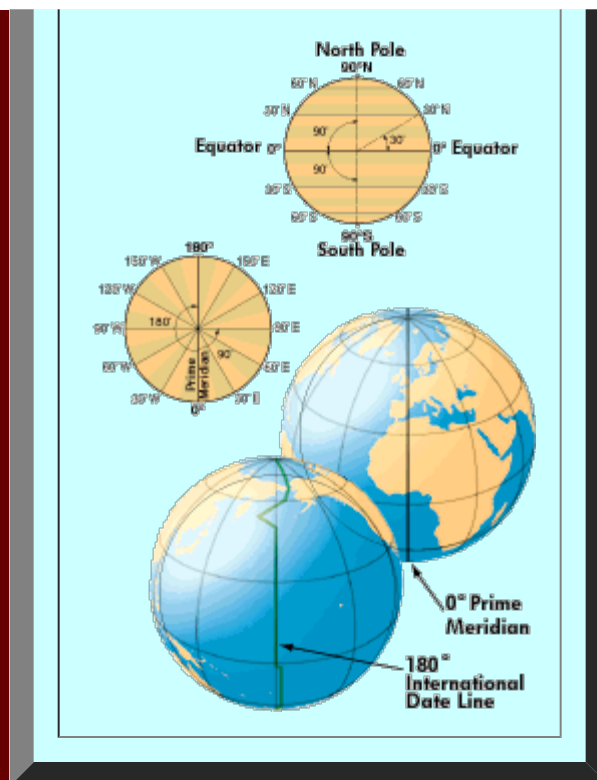
- The figure below shows the reference system described above placed on a sphere. What might be called a Cartesian grid in the plane is called a graticule on the sphere.
 - All parallels have the same latitude; they are the same distance above or below, north of or south of, the Equator.
 - All meridians have the same longitude; they are the same distance east or west of the Prime Meridian.

Spacing between successive parallels or meridians might be at any level of detail; however, when circular measure describes the position of these lines, that description is unique up to agreement to use 360 degrees in a circle. One spacing for the set of meridians that is convenient on maps of the world, is to choose spacing of 15 degrees between successive meridians. The reason for this is that since the meridians converge at the ends of the polar axis, that each meridian then represents the passage of one hour of time. Given that we agree to partition a day into 24 hours, 24 times 15 is 360, meridians may also mark time.

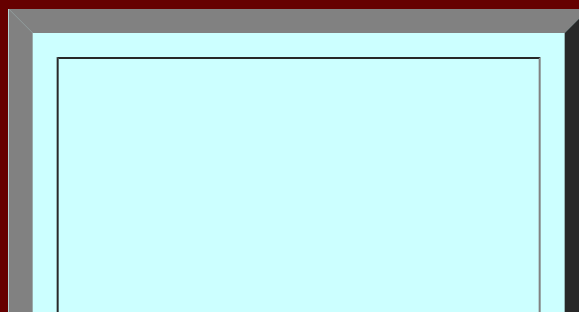


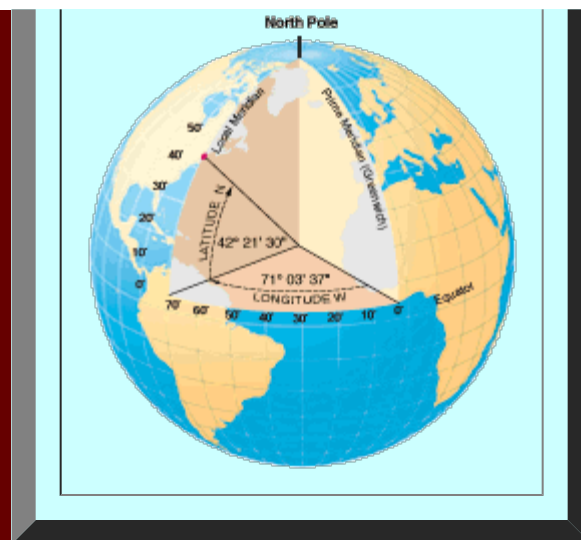
- Bounds of measurement (see the figure below).
 - Latitude runs from 0° at the equator to 90°N or 90°S at the poles.
 - Longitude runs from 0° at the prime meridian to 180° east or west, halfway around the globe. The International Date Line follows the 180° meridian, making a few jogs to avoid cutting through land areas.





- Length of one degree on the Earthsphere.
 - One degree of latitude, measured along a meridian or half of a great circle, equals approximately 69 miles (111 km). One minute is just over a mile, and one second is around 100 feet (a pretty precise location on a globe with a circumference of 25,000 miles). Calculation: $25,000/360 = 69.444$.
 - Because meridians converge at the poles, the length of a degree of longitude varies, from 69 miles at the equator to 0 at the poles (longitude becomes a point at the poles). Calculation: at latitude theta, find the radius, r , of the parallel, small circle, at that latitude. The radius, R , of the Earthsphere is $R = 25,000 / (2 \cdot \pi) = 3978.8769$ miles. Thus, $\cos \theta = r/R$ (using a theorem of Euclid that alternate interior angles of parallel lines cut by a transversal are equal). Therefore, $r = R \cos \theta$. Then, the circumference of the small circle is $2r \cdot \pi$ and the length of one degree at theta degrees of latitude is $2r \cdot \pi / 360$. For another application of this particular theorem of Euclid, see the [linked page](#) concerning Eratosthenes measurement of the Earthsphere.
 - For example, at 42 degrees of latitude, $r = 2956.882$. Thus, the circumference of the parallel at 42 degrees north is approximately 18578.6205 miles. Thus, the length of one degree of longitude, measured along the small circle at 42 degrees of latitude, is: 51.607 miles.
 - This particular calculation scheme is a rich source of elementary problems using geometry and trigonometry. Consider the following question: at what latitude is the length of one degree on longitude exactly half the value of one degree of longitude at the equator?
 - Readers wishing a visual review of trigonometry may find this [link](#) to be of use.

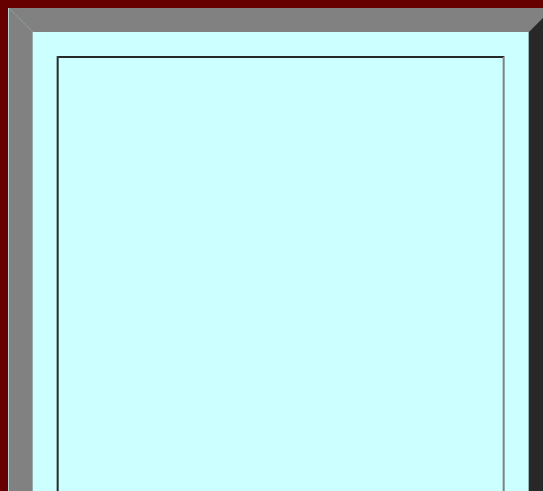


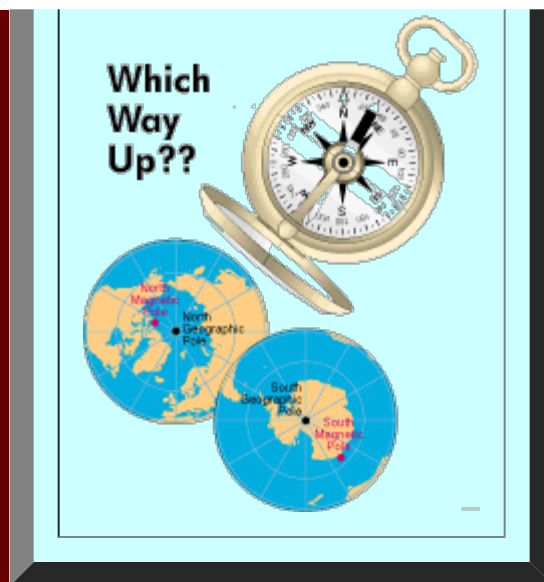


- The position of the sun in the sky. On June 21, the direct ray of the sun is overhead, or perpendicular to a plane tangent to the Earth's surface, at 23.5 degrees north latitude ([link](#) to page about seasons). The angle of the sun in the sky at noon on that day is 90 degrees. What is the angle of the sun in the sky, at noon on June 21, at 42 degrees north latitude? Again, simple geometry and trigonometry solve the problem for this value and for any other. Use the fact that $42 - 23.5 = 18.5$ degrees; that there are 180 degrees in a triangle (look for a right triangle with the right angle at 42 degrees north latitude); and that corresponding angles of parallel lines cut by a transversal are equal. The answer works out to be 71.5 degrees. Thus, on June 21 at local noon, in the northern hemisphere at 42 degrees north latitude the sun will appear in the south at 71.5 degrees above the horizon; in the southern hemisphere at 42 degrees south it will appear in the northern sky at 71.5 degrees above the horizon. Between the tropics, some interesting situations prevail ([link](#) to [Parallels between Parallels, pages 74-86](#)). Use of this technique is important in calculating shadow and related matters in electronic mapping: it was employed in making several virtual reality models of in this book.

Further Directions:

- The north and south poles are the earth's geographic poles, located at each end of its axis of rotation. All meridians meet at these poles. The compass needle points to either of the earth's two magnetic poles. The north magnetic pole is located in the Queen Elizabeth Islands group, in the Canadian Northwest Territories. The south magnetic pole lies near the edge of the continent of Antarctica, off the Adélie Coast. The magnetic poles are constantly moving. What are the implications of this fact for the stability of our graticule?





- All of our geometric analysis is based on Euclidean geometry, assuming Euclid's Parallel Postulate: given a line and a point not on the line--through that point there passes exactly one line that does not intersect the given line. Non-Euclidean geometries violate this Postulate. What does the geometry of the Earthsphere become in the non-Euclidean world?

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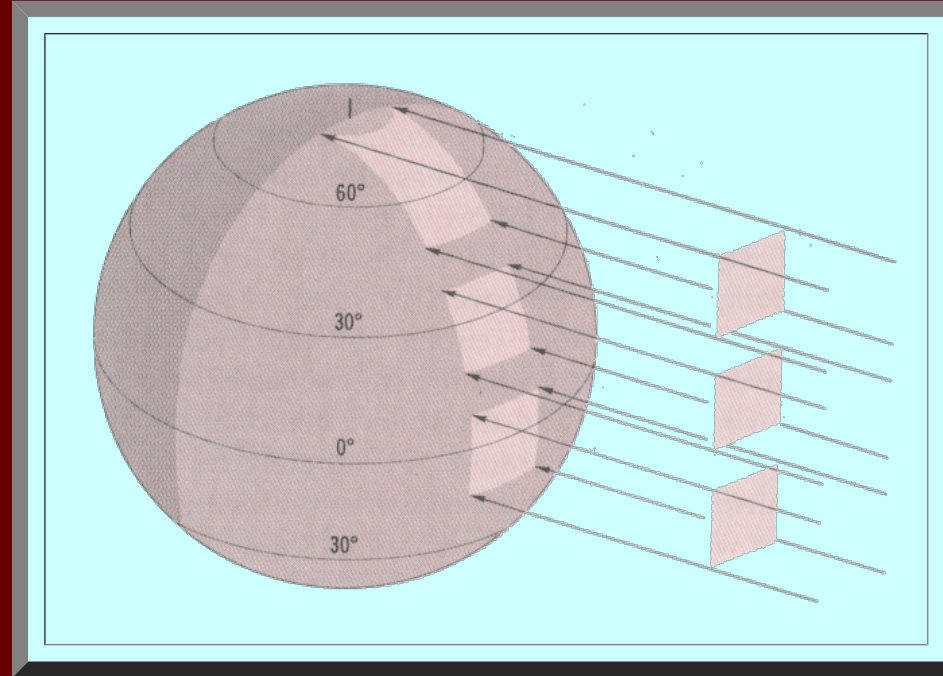
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SEASONS: A VISUAL DISPLAY

Diagrams based on images from pages 64-67,
John F. Kolars and John D. Nystuen, drawings by Derwin Bell,
Physical Geography: Environment and Man, McGraw-Hill, 1975.
Figures produced here with permission.

SUNLIGHT INTENSITY IS A FUNCTION OF LATITUDE

At higher latitudes, sunlight is spread out over a wider area and is thus less intense.
The sun is most intense when the direct ray is overhead or orthogonal to a tangent plane to the Earth.

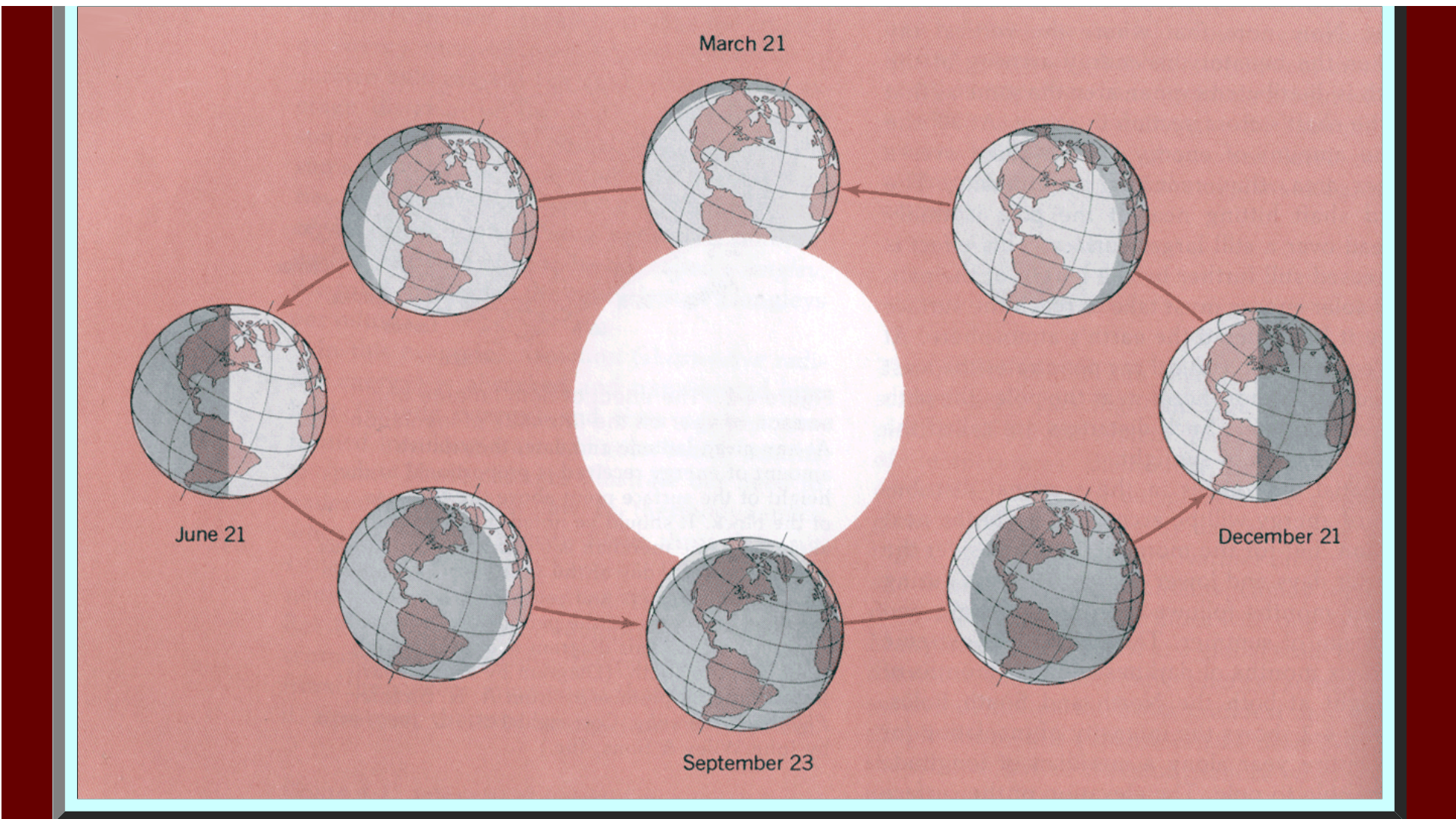


ANNUAL REVOLUTION OF THE EARTH AROUND THE SUN

Note the constant tilt of the Earth's polar axis.

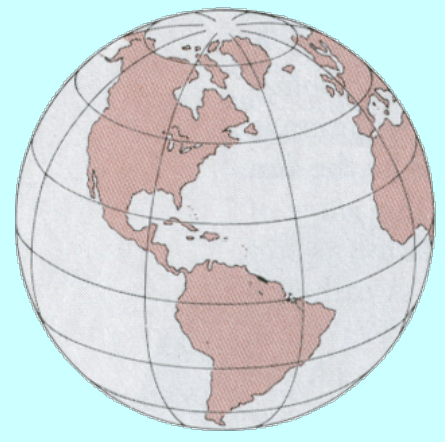
The circle of illumination, or terminator, marks the separation of day and night.

At the equinoxes (about March and September 21), the circle of illumination passes through both poles (the only time of the year at which it does so). Thus, at those times, the circle of illumination bisects all parallels of latitude; half the day is on the dark side, half the day is on the light side for all latitudes. Hence, equinox=equal night, all over the world.



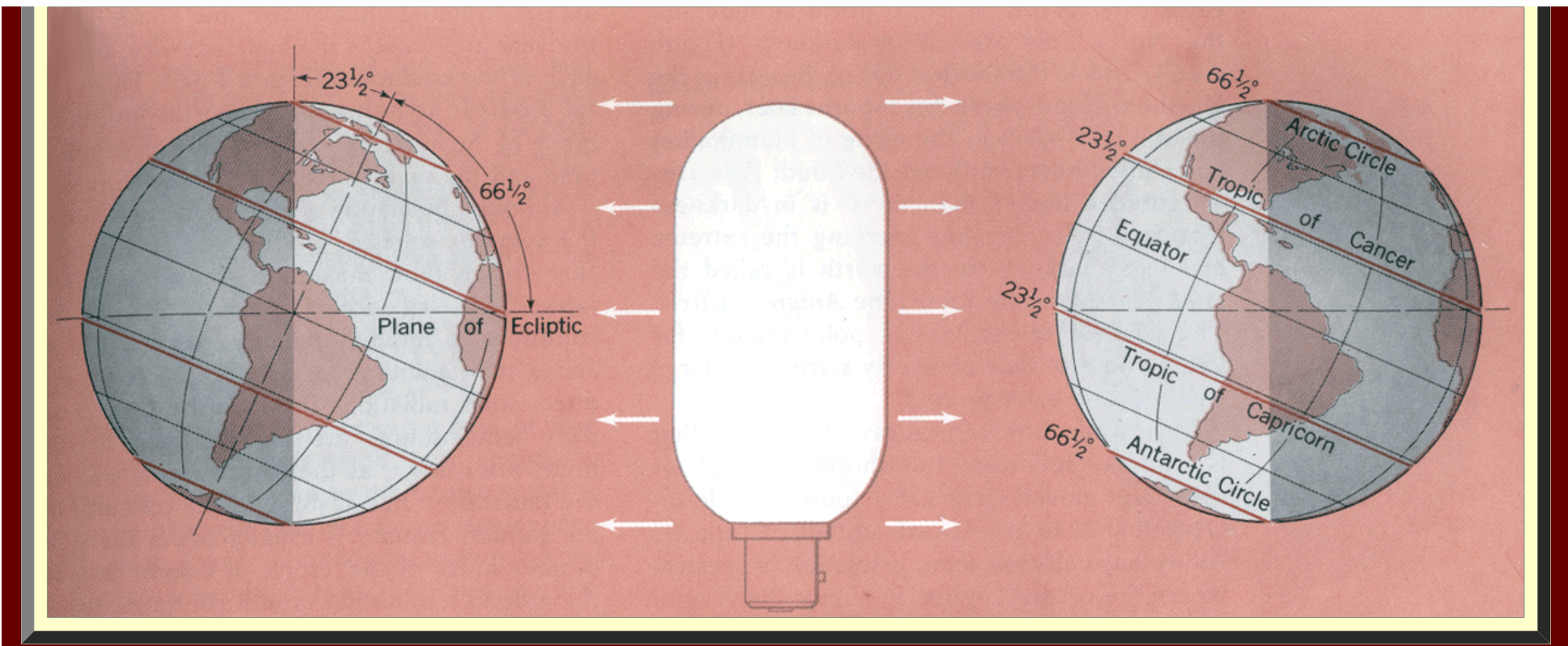
ANIMATION SHOWING THE EARTH VIEWED FROM THE SUN AT SOLSTICES AND EQUINOXES

June 21



LATITUDE AND LONGITUDE MEASURE POSITION OF SUN'S RAYS

The direct ray of the sun is overhead at 23.5 north on June 21 (as far north as it ever will be);
at 23.5 south on December 21 (as far south as it ever will be);
and at 0 degrees on the equinoxes.
The ecliptic is the Sun's diametral plane.

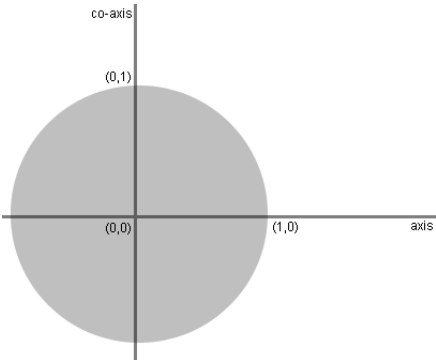
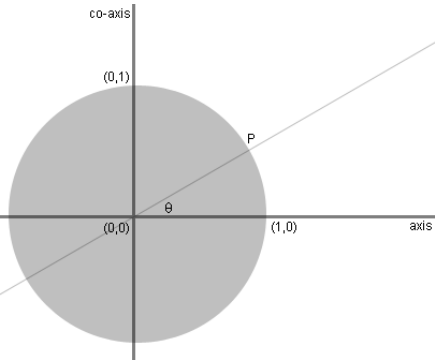
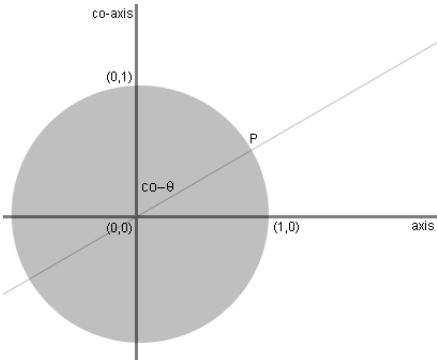


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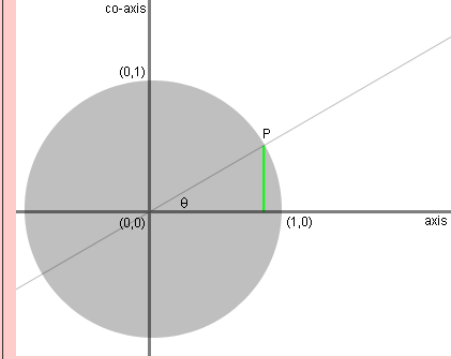
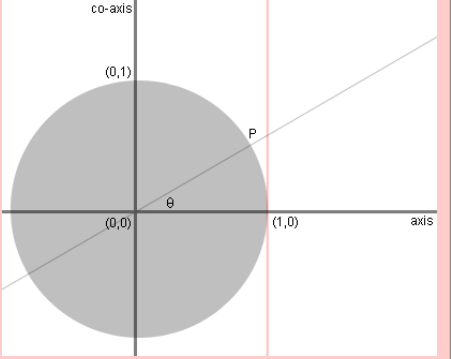
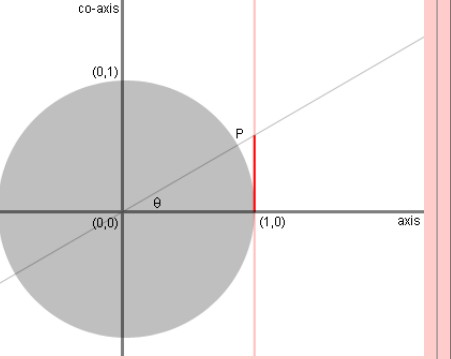
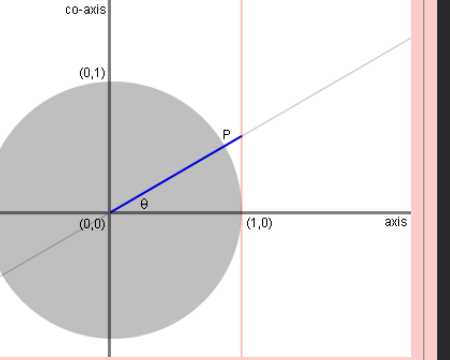
VISUAL TRIGONOMETRY REVIEW

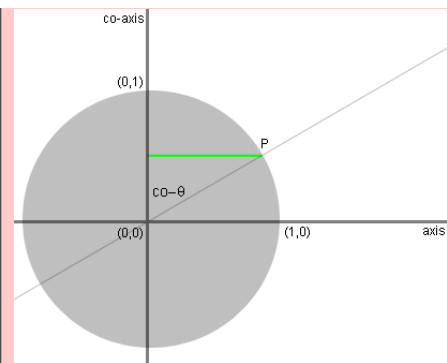
Set screen to highest resolution; scroll to the right when needed. The big table has four columns.

THE BASIC SETUP:

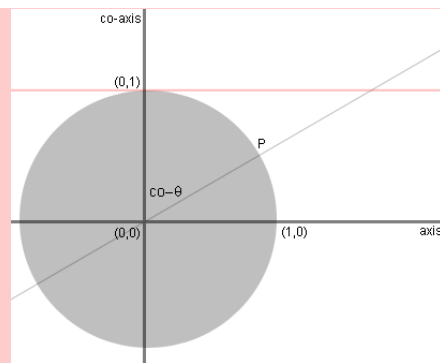
 <p>Unit circle, axis, and complementary (orthogonal) axis designated as co-axis.</p>	 <p>Secant line, a geometric object, cuts the circle at an angle of theta to the horizontal axis. The secant line intersects the circle at point P.</p>	 <p>The same secant line also determines the complementary angle to theta (another geometric object), denoted co-theta.</p>
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THE TOP ROW SHOWS DERIVATIONS OF TRIGONOMETRIC FUNCTIONS FOR ANGLE THETA;
 THE SECOND ROW SHOWS DERIVATIONS OF TRIGONOMETRIC FUNCTIONS FOR ANGLE CO-THETA.

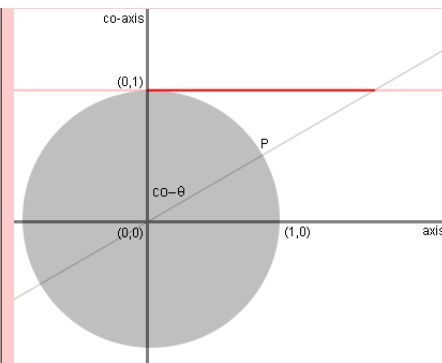
 <p>The length of the green line, dropping from P to the axis, measures the sine of theta: opposite side of a right triangle over a hypotenuse of the unit circle.</p>	 <p>The pink line is a geometric line tangent to the unit circle at (1,0) on the horizontal axis.</p>	 <p>The length of the red line, intercepted by the secant line along the tangent line, measures the tangent of theta.</p>	 <p>The length of the blue line, intercepted by the tangent line along the secant line, measures the secant of theta.</p>



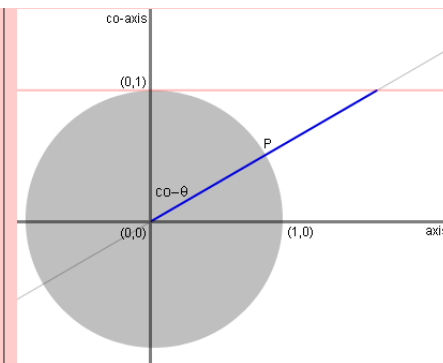
The length of the green line, dropping from P to the co-axis, measures the sine of co-theta: opposite side of a right triangle over a hypotenuse of the unit circle. Hence, cosine of theta.



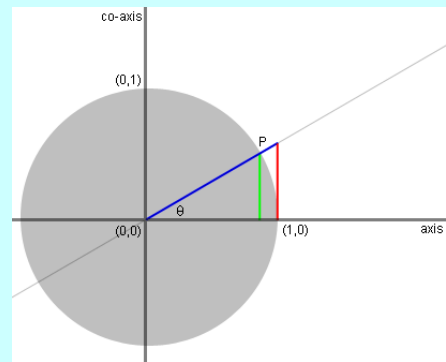
The pink line is a geometric line tangent to the unit circle at (1,0) on the co-axis.



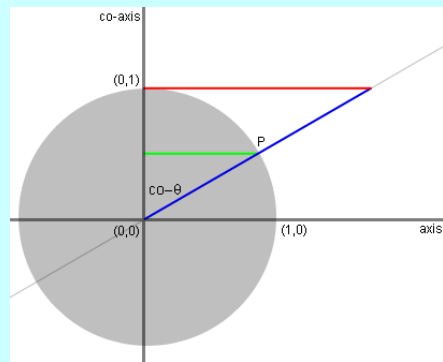
The length of the red line, intercepted by the secant line along the tangent line, measures the tangent of co-theta. Hence, cotangent of theta



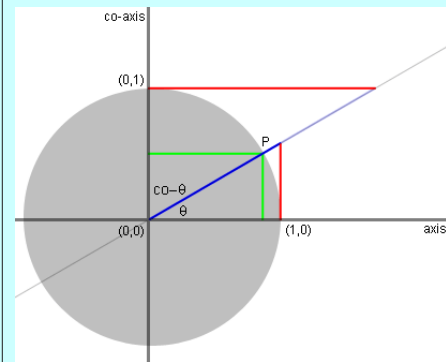
The length of the blue line, intercepted by the tangent line along the secant line, measures the secant of co-theta. Hence, cosecant of theta.



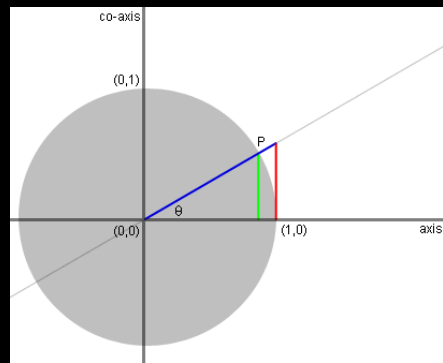
The three functions of theta measuring sine, tangent, and secant shown together.



The three functions of co-theta measuring sine of co-theta (cosine of theta), tangent of co-theta (cotangent of theta), and secant of co-theta (cosecant of theta).



All six functions of theta are shown in this image. The representations for secant lies on top of that for cosecant of theta. The latter is thus shaded a lighter shade.



An animation of the ideas shown as individual frames above.

A number of trigonometric identities are evident from this visual approach.

From the Pythagorean Theorem, it follows that:

$\sin^2 \theta + \cos^2 \theta = 1$, the radius of the unit circle measured along the secant line;

$\sec^2 \theta = \tan^2 \theta + 1$, the radius of the unit circle measured along the horizontal axis;

$\csc^2 \theta = \cot^2 \theta + 1$, the radius of the unit circle measured along the co-axis.

What others do you note?

Based on an approach learned by S. Arlinghaus at The University of Chicago Laboratory Schools.

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Bisectors, Buffers, and Base Maps

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Introduction

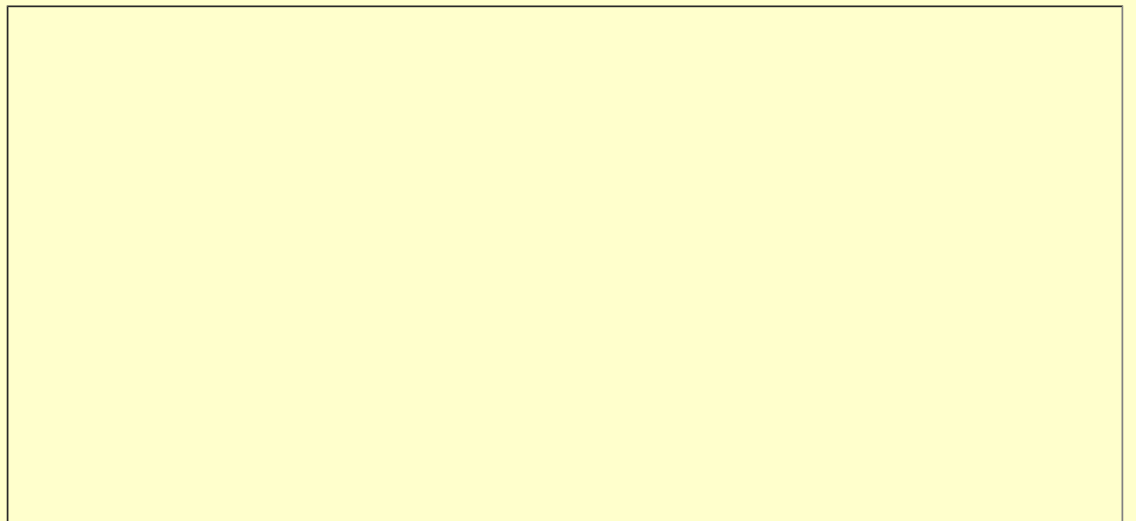
In 1911, Thiessen and Alter [21] wrote on the analysis of rainfall using polygons surrounding rain gauges. Given a scatter of rain gauges, represented abstractly as dots, partition the underlying plane into polygons containing the dots in such a way that all points within any given polygon are closer to the rain gauge dot within that polygon than they are to any other gauge-dot. The geometric construction usually associated with performing this partition of the plane into a mutually exclusive, yet exhaustive, set of polygons is performed by joining the gauge-dots with line segments, finding the perpendicular bisectors of those segments, and extracting a set of polygons with sides formed by perpendicular bisectors. It is this latter set of polygons that has come to be referred to as "Thiessen polygons" (and earlier names such as Dirichlet region or Voronoi polygon, see Coxeter [4]). The construction using bisectors is tedious and difficult to execute with precision when performed by hand. Kopec (1963) [11] noted that an equivalent construction results when circles of radius the distance between adjacent points are used. Indeed, that construction is but one case of a general construction of [Euclid](#). Like Kopec, Rhynsburger (1973) [20] also sought easier ways to construct Thiessen polygons: Kopec through knowledgeable use of geometry and Rhynsburger through the development of computer algorithms. The world of the Geographical Information System (GIS) software affords an opportunity to combine both.

Bisectors

A theorem/construction of Euclid shows how to draw a perpendicular bisector separating any pair of distinct points in the Euclidean plane. The animation in Figure 1 illustrates this procedure:

- Given O and O' in the plane.
- Draw a segment joining O and O'
- Construct two circles, one centered on O and the other centered on O' , each of radius greater than half the distance between O and O' . The radii are the same.
- Label the intersection points of the circle as A and B . Draw a line through A and B . This line is the perpendicular bisector of $|OO'|$.

In the final frame of the animation in Figure 1, the highly colorful one, the use of a GIS displays clearly that radius length produces the same position for $|AB|$ independent of choice (greater than $0.5*|OO'|$). The last frame was produced in ArcView 3.2 (with Spatial Analyst Extension enabled) using the "calculate distance" feature. It shows the general result, of which Kopec used one element. One need not be limited to choosing the distance between adjacent points--any distance greater than half that distance will produce the same result.



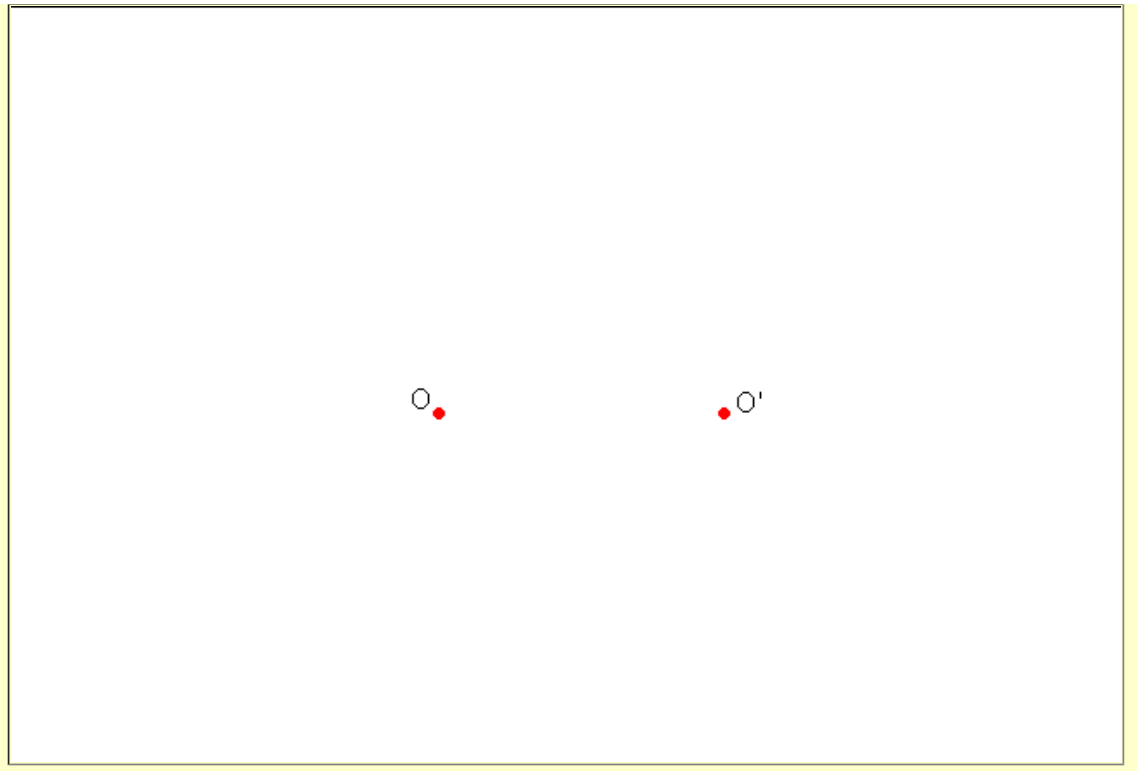


Figure 1. Animation showing construction of perpendicular bisector, AB, of $|OO'|$.

Buffers

Traditionally one might have used a drawing compass and a straightedge to construct a perpendicular bisector between two points. It is an easy matter to do so, however, using a GIS, as suggested above. If there are more than two points, the matter can become quickly tedious. Again, the GIS offers a quick and accurate way to calculate positions (Figure 2).

- Given a distribution of points in the plane (O and O' are now among this set).
- Create circular buffers around all the points, leaving the entire circle surrounding each point. It has become difficult to visualize the location of the set of perpendicular bisectors that are determined by this circular mass.
- Dissolve arcs within the circular mass. This procedure offers some help in visualizing where bisectors might be, but only a vague picture of bisector position is generated.



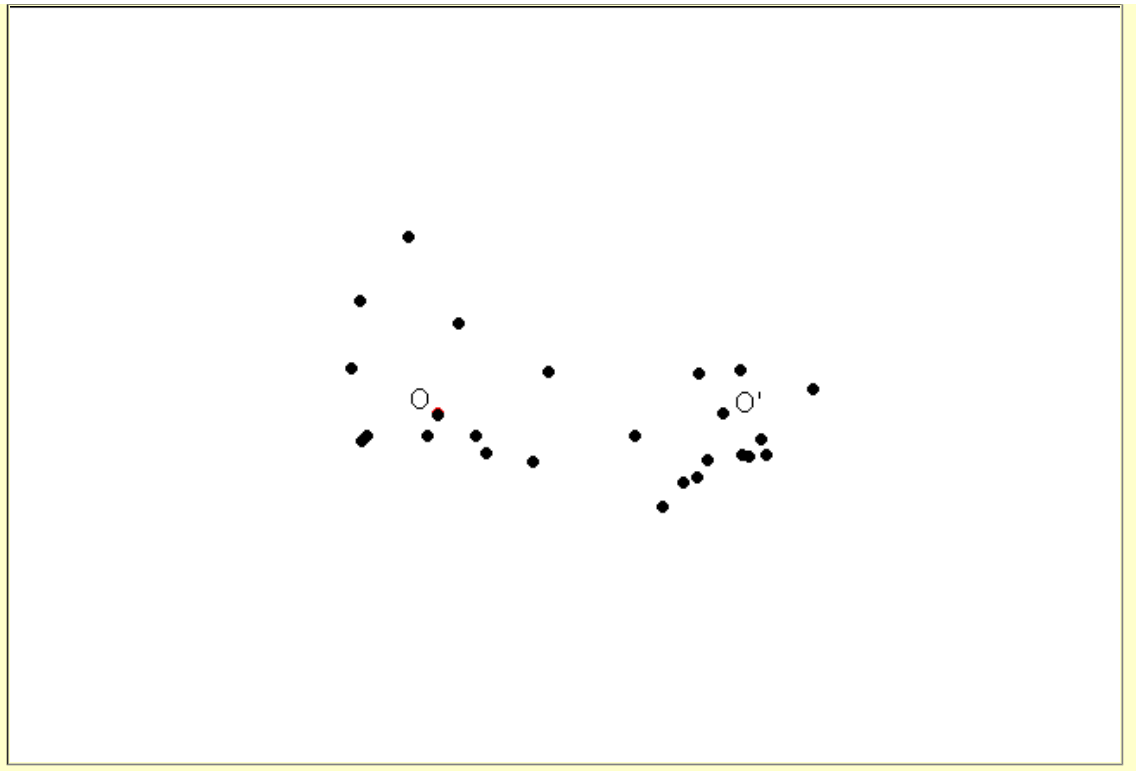


Figure 2. Circular buffers centered on a distribution of 25 points.

To actually position the lines of partition, or Thiessen polygon edges, in the GIS, use the "split polygon" feature available in ArcView or other GIS software, creating a sort of bubble foam (Figure 3 shows one split created in this manner). Numerous websites offer suggestions for use of Thiessen polygons ranging from rainfall regions, to hydrological modelling, to road centerline location (and others) [12, 13, 14].

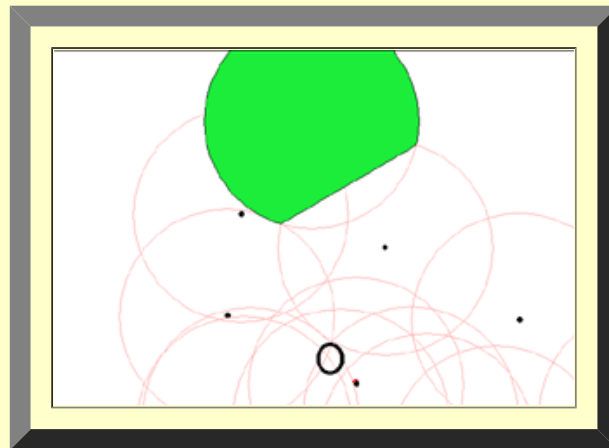


Figure 3. Use of the Polygon-split tool.

One contemporary website demonstrates the mechanics of this sort of approach using one buffer distance [6]. Others employ a variety of software to construct Thiessen polygons [22].

Again, the GIS is helpful: ArcView (Spatial Analyst extension) offers a single tool that quickly calculates Thiessen polygons. Use "Assign Proximity" to create zones around each point. Within each zone, all points are nearer to the distribution point in that zone than they are to any other point in the distribution. In Figure 4, the relationship between perpendicular bisector, buffer (construction of Euclid), proximity zone/Thiessen polygon becomes clear.

- The initial frame shows the result of running the "assign proximity" feature of ArcView 3.2, Spatial Analyst Extension, on the scatter of 25 points. The colorful polygons separate the plane into Thiessen polygons. Within each polygon, all points are closer to the point from the 25 dot scatter that is in that polygon than they are to any other point in the 25 point scatter.
- The second frame superimposes circular buffers; thus, one sees how the Thiessen polygons are a

direct consequence of the Theorem/Construction of Euclid.

- The third frame dissolves part of the circular buffer, exposing more clearly the relation between circular buffer and proximity zone as calculated by the computer algorithm in ArcView GIS.

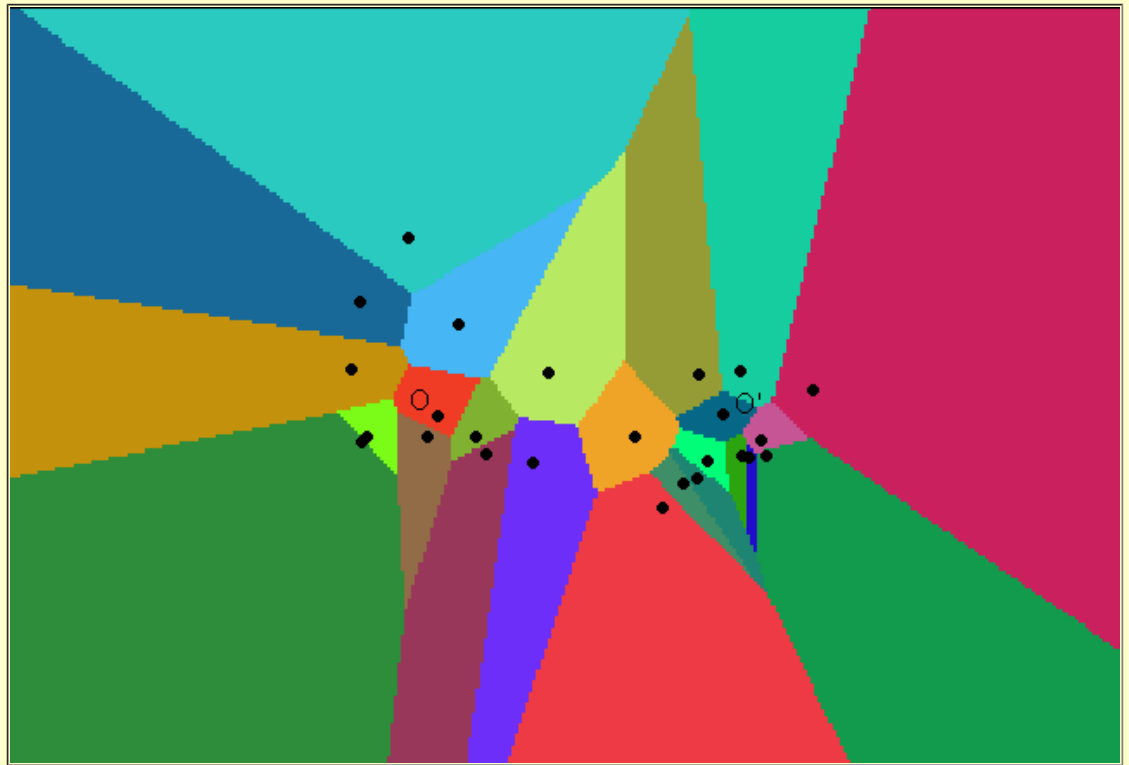


Figure 4. Bisectors, buffers, and proximity zones (Thiessen polygons).

Whether one considers rail networks within sausage-like linear buffers, counts population in buffered bus routes, or selects minority groups from within a circular buffer intersecting census tracts, the buffer has long served, and continues to serve, as a basis for making decisions from maps. Buffers have a rich history in geographical analysis. [Mark Jefferson](#) [10, 2] rolled a circle along lines on a map representing railroad tracks to create line-buffers representing proximity to train service and suggested consequent implications for population patterns in various regions of the world. Julian Perkal and John Nystuen saw buffers in parallel with delta-epsilon arguments employed in the calculus to speak of infinitesimal quantities (reprint of Perkal, "An Attempt at Objective Generalization," Michigan Interuniversity Community of Mathematical Geographers, [16, 19]). Jefferson's mapping effort in 1928 was extraordinary; today, buffers of points, lines, or regions are trivial to execute in the environment of Geographic Information Systems software. To paraphrase Faulkner (1949), 'good ideas will not merely endure, they will prevail' [7].

Base Maps

In a recent invited lecture (2001) to The University of Michigan Lecture Series in GIS Education, Arthur Getis noted [15] that he had used circular buffers around point observations and that he used a sequence of nested buffers to successively fill space to eventually include all individuals in the underlying point distribution gathered from field evidence. Thus, viewed abstractly, each set of buffers serves as a base map, with the sequence successively filling more space and including more individual observations in the analysis. A different view might see the Thiessen map as the base map (Figure 5). When it is calculated at the outset, it can serve as a standard against which to test more specialized views at varying buffer radii, on a continuing basis, as the research within buffers evolves. The Thiessen base map serves, therefore, as an "absolute" base map against which to view the "relative" base maps of varying local radii (and other configurations): it is a limit of a sequence of measures based on buffers that increasingly fill more space (but still leave gaps). Getis noted [15] that he and Ord had recently completed an article involving issues of global and local spatial statistical measures [18]. What is suggested here is the appropriate use of a geometric foundation: a use for a Thiessen, space-filling, base against which to test the results of sequences of successive measures in buffers that may not fill the underlying universe of discourse.

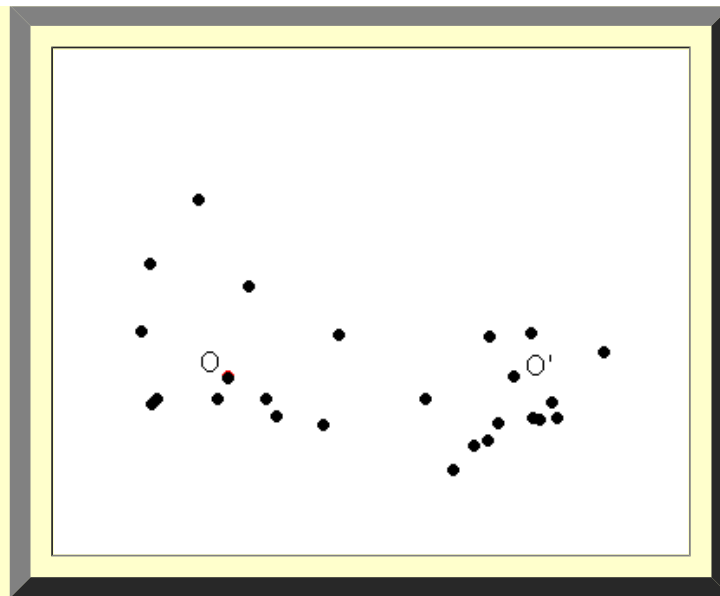


Figure 5. Distribution of 25 Canadian cities against Thiessen base map and circular buffer set. Files may be clipped to suit user needs. Note polygon sides in relation to pattern of intersecting circles (as in Figure 1 above) and space filling pattern of successive buffers closing in on individual Thiessen polygons in the background. Values within the buffers thus approach, with increasing buffer radius, values associated with the underlying Thiessen polygons (as the buffers never fall outside the polygon, due to the construction of Euclid). In cases where clipping matches buffer boundaries, the buffer values converge to and attain the limiting values associated with the Thiessen polygons.

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Software used

- Adobe, Photoshop, 6.0.
- Environmental Systems Research Institute (ESRI), Redlands, CA.
 - ArcView 3.2
 - ArcView Spatial Analyst Extension
- Gamani, Movie Gear
- Macromedia, DreamWeaver, 3.0
- Netscape Composer

I-Maps: Interactive Maps

- **I-Map 6.1:** [Click here](#) for a link to an interactive map showing building footprints and height (on mouse-over) as well as building address and street names (on mouse-over). Parcel boundaries are shown on the underlying aerial and on the green Downtown Development Authority (DDA) area. The Allen Creek floodway (underground) and flood plain are shown, shaded, respectively in blue and turquoise. Click on a building or a street to see associated entries in the underlying database.
- **I-Map 6.2:** [Click here](#) for a link to an interactive aerial showing parcel boundaries, zoning, building height (on mouse-over), and street name. DDA outline, only, is shown in light yellow so the user may zoom in to get a closer view of the aerial within the DDA (up to 800% enlargement--can see cars clearly). The Allen Creek floodway (underground) and flood plain are shown, outlined, respectively in blue and light blue; again, because the shading is removed, the viewer may look at the content of the floodway/floodplain in greater detail than above. Click on a building or a street to see associated entries in the underlying database.
- **I-Map 6.3:** [Click here](#) for a link to an interactive aerial showing zoning boundaries in the downtown, zoning type (on mouse-over), building height (in the "zoneht" record of the database), and street name. Click on a building or a street to see associated entries in the underlying database.

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Spatial Synthesis: Centrality and Hierarchy, Volume I, Book 1.
Sandra Lach Arlinghaus and William Charles Arlinghaus

Virtual Reality

Requires Cosmo Player or other viewer to be loaded in the Browser.

- K=3 Poles** *K=3* central place dot scatter produces a field of poles of height varying according to the principles of the associated central place hierarchy.
- K=4 Poles** *K=4* central place dot scatter produces a field of poles of height varying according to the principles of the associated central place hierarchy.
- K=7 Poles** *K=7* central place dot scatter produces a field of poles of height varying according to the principles of the associated central place hierarchy.
-

K=3 Solid Interactive virtual model showing single tile at three levels of detail.

K=3 Translucent Interactive virtual model showing single tile at three levels of detail.

K=4 Solid Interactive virtual model showing single tile at three levels of detail.

K=4 Translucent Interactive virtual model showing single tile at three levels of detail.

K=7 Solid Interactive virtual model showing single tile at three levels of detail.

K=7 Translucent Interactive virtual model showing single tile at three levels of detail.

Core Downtown Ann Arbor, existing core scene

1000 Downtown Ann Arbor, one scenario for 1000 new residential units

2500 Downtown Ann Arbor, one scenario for 2500 new residential units

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