An explanation of the sheath instability

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When the sheath accelerates in its plasma-bound motion as a result of the ion response to the electric field, one has a top-heavy equilibrium. In the sheath frame ions are accelerated towards the wall–sheath boundary. In such a situation sheath may become unstable. The sheath instability is examined as the Rayleigh–Taylor (RT) instability and RT growth rate is compared with the reported sheath instability in the literature. © 2003 American Institute of Physics.

I. INTRODUCTION

The sheath formation at the plasma–wall interface is ubiquitous in a bounded plasma. The specific feature of the plasma sheath is the formation of a charged boundary layer due to the difference in the mobility among different plasma particles, viz., electrons and ions in a two component plasma. Since electron mobility is much higher than the ion mobility, the plasma boundary becomes negatively charged leaving behind a positively charged column. The resultant potential gradient tends to slow incoming (to the boundary wall) electrons and accelerate the ions until a steady state is reached, with equal ion and electron fluxes. A stationary sheath exists only if the ion flow velocity satisfies the Bohm criteria at the plasma–sheath boundary, or if the electric field at the plasma–sheath interface exceeds some critical value.1 With no net current, the sheath width is typically few Debye length and the voltage drop, a few electron temperatures.

Consider an application where the boundary of the substrate is negatively biased, e.g., in plasma processing. Then, the static boundary sheath formation is limited to the case when fluctuations in the applied voltage at the negatively biased wall during the time of flight of ions through the sheath is negligible. If the fluctuation frequency in the applied voltage is smaller than the ion plasma frequency, the particles move in the quasistatic field of the sheath and static sheath model is a valid description. However, when fluctuation in the voltage and ion plasma frequency becomes comparable, the sheath field changes during the transition of the particle through the sheath, and static sheath description becomes invalid.4,5 The size and location of the plasma sheath may change due to the rapid variation at the plasma–sheath boundary and the sheath motion can be highly irregular and unstable.6–12

When the sheath accelerates in its plasma bound motion as a result of the ion response to the electric field, one has a top-heavy equilibrium. In the sheath frame, plasma is accelerated towards the wall. This effective “gravity” pulls the heavy fluid through the plasma–sheath boundary layer as plasma density in the quasineutral region is more than near the negatively charged wall. The experimental observation of sheath instability in a double plasma device has been reported in the literature.12,13 Although experimental details of different sheath experiment varies,7–14 common features of observed sheath instability are the following: the oscillation frequency \( f \) scales with the grid bias as \( f \propto n_s^{1/2} \) and \( f \) scales with the grid bias as \( f \propto \phi^{-\alpha} \) with \( \alpha \) between 0.5 and 0.25. A different mechanism has been proposed to explain the sheath instability. For example, klystron bunching of the ions in the sheath,15 resonant interaction of the ions due to asymmetry in the sheath potential,11 potential relaxation instability9 or intermittent oscillation due to the onset of chaos16 are some of the possible mechanisms proposed to explain the instability.

In the present work, one develops a model whereby the sheath instability is explained in terms of Rayleigh–Taylor (RT) instability. The RT instability is believed to operate in space as well as in a laboratory environment. The instability has been extensively studied in a wide range of physical contexts both theoretically and experimentally.17–22 The primary source of the RT instability is the free energy available due to the presence of an inverted density gradient in the presence of gravitational force. In the vicinity of a near wall plasma region, number densities of plasma particles decline considerably. The electrons are repelled from the negatively biased wall whereas ions are accelerated towards the wall and thus their respective number density in the sheath–presheath region is much less than the corresponding number in the quasi-neutral presheath region. Therefore, the sheath region near the wall can be visualized as a “lighter fluid” under the “heavy fluid” of the quasi-neutral plasma region. The boundary of such an arrangement is accelerated towards the wall in the presence of an electric field. The resultant acceleration provides an effective “gravity.” Thus, stationary sheath equilibrium is a “top-heavy” arrangement and a slight oscillation at the sheath–presheath boundary will help the...
heavy fluid to pierce through the lighter fluid. As a result, sheath instability may well be a manifestation of the Rayleigh–Taylor instability.

II. BASIC MODEL

We shall assume a collisionless sheath model and employ a fluid description to study the problem at hand. Due to the formation of sheath at the plasma boundary, there exist two regions in a bounded plasma: (a) The quasi-neutral bulk plasma, where electron and ion number densities \( n_e \) and \( n_i \) equal each other; and (b) the sheath at the boundary where \( n_e \ll n_i \). We assume that the sheath–plasma boundary is located at \( z = z_0 \). The typical sheath width is a few Debye lengths (a spatial scale of a local electric field) that could be very small in practical applications, while the quasi-neutrality scale corresponds to the typical size of the system. This circumstance leads to nonuniversality of the plasma distribution functions for the whole region and allows the near wall sheath layer to be modeled separately from the bulk plasma region.\(^2\)

Generally, governing equations of the sheath model are time independent. We shall consider such a sheath-equilibrium near the wall. Most sheath models are based upon the assumption that electrons are in thermal equilibrium and may be given as \( n_e = n_0 \exp(e \phi / T_e) \), where \( \phi \) is the sheath voltage near the wall and is always positive and \( n_0 \) is the plasma number density when \( \phi = 0 \), and \( T_e \) is the electron energy in eV with \( e \) as the electronic charge. The steady state ion equation of motion is given as

\[
\nabla \cdot (n_i \mathbf{v}_i) = 0,
\]

\[
\nabla \cdot [(m_i n_i \mathbf{v}_i) \mathbf{v}_i] = - \nabla p_i + e n_i \mathbf{E},
\]

\[
\nabla^2 \phi = 4 \pi e n_0 \left[ \exp \left( \frac{e \phi}{T_e} \right) - \frac{n_i}{n_0} \right].
\]

For the cold ion case,

\[
\frac{v_i^2}{2} + \frac{e \phi}{m_i} = C_1.
\]

Now making use of \( n_i v_i = C_2 \), one can write

\[
n_i = C_3 \left[ \frac{m_i}{e \phi} \right]^{-1/2}.
\]

The boundary condition will require \( C_2 = n_0 v_{i,0} \) and \( C_3 = m_i v_{i,0}^2 / 2 \) as one must have \( \phi(\infty) = 0 \), \( n_i(\infty) = n_0 \) and \( v_i(\infty) = v_{i,0} \). The above set of equations reduces to a well known equation for the planner sheath,

\[
\nabla^2 \phi = 4 \pi e n_0 \left[ \exp \left( \frac{e \phi}{T_e} \right) - \left( 1 - \frac{2e \phi}{m_i v_{i,0}^2} \right) \right]^{-1/2}.
\]

At the plasma–sheath boundary, \( v_{i,0} = v_B \), where \( v_B \) is the Bohm velocity. If sheath voltage is high, then Poisson’s equation (3) can be simplified by assuming \( n_e = 0 \) and

\[
\nabla^2 \phi = -4 \pi e n_i.
\]

The above set of equations can be solved for a stationary sheath either with the zero potential at the plasma sheath boundary (the so called plasma mirror\(^2\)) or with nonzero electric field (the so called step sheath model). An analytical expression for plasma density, potential, etc. can be derived. The focus of the present work is to investigate the stability of a stationary sheath model and to that end, an applied electric field at the plasma–sheath boundary is assumed. The presence of such an electric field will accelerate the ions towards the wall and thus, the plasma–sheath layer can be modeled as a surface that separates the heavy fluid from the light fluid in the presence of an effective gravity. The inhomogeneity scale length based on the ambient density gradient for ion is \( L_n^{-1} = n_0^{-1} d n_0 / d z \). It is well known\(^{17} \) that the equilibrium with the inverted density gradient against gravity is unstable if \( \mathbf{a} \cdot \nabla n_0 < 0 \), where \( \mathbf{a} \) is the acceleration. In order to study the instability of the sheath equilibrium, one perturbs the equilibrium quantities as \( n_i(z) = n_0(z) + n_1(t, x, z) \), \( v_i = v_{i,0}(z) + v_1(t, x, z) \), \( p = p_0 + p_1 \), \( \mathbf{E} = \mathbf{E}_0(z) + \mathbf{E}_1(t, x, z) \). Then the linearized equations are

\[
\frac{\partial n_1}{\partial t} + \nabla \cdot (n_0 v_1 + n_1 v_0) = 0;
\]

\[
m n_0 \left[ \frac{\partial v_1}{\partial t} + v_0 \nabla v_1 + v_1 \nabla v_0 \right] = - \nabla p_1 + e n_1 \mathbf{E}.
\]

The perturbed electric field needs to be calculated self-consistently using Poisson’s equation. However, an imposed electric field at the plasma–sheath boundary\(^2\) is assumed here, i.e., \( E_{z,0} = T_e / \lambda_D \) where \( \lambda_D = \sqrt{T_e/(4 \pi n_0 e^2)} \) is the Debye length defined at the plasma–sheath boundary.

The perturbation of the form \( \exp[i(kz - \omega t)] \) is assumed. Then the linearized continuity equation (8) becomes

\[
-i \omega n_1 + v_1 n_0' + v_0 n_1' = 0,
\]

where a prime denotes derivative \( \partial / \partial z \). The components of Eq. (9) are given as

\[
m n_0 (-i \omega v_{1,0} + v_0 v_{1,0}') = -i k v_1,
\]

\[
m n_0 (-i \omega v_{1,0} + v_0 v_{1,0} - v_1 v_0') = -p_1' + e n_1 E_0.
\]

For simplicity, the incompressibility condition is assumed for the ion fluid, \( \nabla \cdot \mathbf{v}_i = 0 \). Then,

\[
v_z = \frac{i}{k} \frac{\partial v_{1,0}'}{\partial z}.
\]

After some simple algebra, from Eqs. (10)–(13) one gets

\[
\omega \left[ \frac{\partial v_{1,0}'}{\partial z} - \frac{v_0}{\omega} \frac{\partial^2 v_{1,0}}{\partial z^2} - \frac{i k^2}{\omega^2} v_0 v_{1,0}' \right]
\]

\[
= k^2 \left[ 1 - \frac{e}{m} \left( \frac{E_0}{\omega^2} \right) \left( L_n^{-1} + \frac{n_1'}{n_0'} \right) + \frac{v_0}{i \omega} v_{1,0}' \right].
\]

Integrating the above equation from \( -e \) to \( +e \) across the plasma sheath boundary and invoking the continuity of velocity along with its derivative, one obtains

\[
\omega^2 - \frac{e}{m} E_0 \left( L_n^{-1} + \frac{n_1'}{n_0'} \right) - i \omega v_0 = 0.
\]
The stability in the context of plasma sheath dynamics will be further explored in our future work.

In the case of a transient sheath, a situation germane to plasma processing, the plasma–sheath boundary initially propagates into the plasma at a velocity higher than the ion acoustic speed $C_s$ and at this time a refractive ion disturbance begins to propagate ahead of the sheath. $^{25–27}$ Gradually its velocity drops below $C_s$. In the case of substantial ion–neutral collisions, the wave front does not get separated from the sheath. $^5$ It is speculated that the supersonic sheath expansion and the subsequent subsonic sheath evolution in case of a transient sheath, might be triggered by the RT instability.

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