Wigner and Racah coefficients for $SU_3^*$

J. P. Draayer † and Yoshimi Akiyama †

Department of Physics, The University of Michigan, Ann Arbor, Michigan 48105

1904

Received 19 March 1973; revised manuscript received 22 May 1973

A general yet simple and hence practical algorithm for calculating $SU_3 \supset SU_2 \times U_1$ Wigner coefficients is formulated. The resolution of the outer multiplicity follows the prescription given by Biedenharn and Louck. It is shown that $SU_3$ Racah coefficients can be obtained as a solution to a set of simultaneous equations with unknown coefficients given as a by-product of the initial steps in the $SU_3 \supset SU_2 \times U_1$ Wigner coefficient construction algorithm. A general expression for evaluating $SU_3 \supset R_3$ Wigner coefficients as a sum over a simple subset of the corresponding $SU_3 \supset SU_2 \times U_1$ Wigner coefficients is also presented. State conjugation properties are discussed and symmetry relations for both the $SU_3 \supset SU_2 \times U_1$ and $SU_3 \supset R_3$ Wigner coefficients are given. Machine codes based on the results are available.

1. INTRODUCTION

The work of Wigner on the theory of group representations coupled with Racah's development of the algebra of tensor operators provides basic simplifying techniques for spectroscopic analyses. The usefulness of their techniques in any particular situation, however, depends to a great extent upon the availability of the appropriate Wigner and Racah coefficients. Ordinary angular momentum algebra, for example, owes its utility as a calculational tool to the ready availability of the $SU_3$ Wigner and Racah coefficients. Other more complicated group structures for which Wigner and Racah coefficients are not so readily available, however, are also known to have real physical significance. The special unitary group in three dimensions, $SU_3$, is a case in point. In 1958 Elliott pointed out its usefulness in understanding the rotational structure of light nuclei. Some four years later it was also recognized as being of importance in the classification of elementary particles. As a consequence, Wigner and Racah coefficients for this group have been given in either algebraic or numeric form for simple cases of special interest by a number of authors. More general results have only recently been made available through the work of Biedenharn and Louck and co-workers. Except for the case of multiplicity free and the so-called $P$ coupling, however, an additional algorithm is needed if numerical values for Wigner coefficients are to be extracted from the formalism. And since most authors disagree in their choice of a phase convention, extreme caution must be used if results so obtained are used to augment simple algebraic formulas currently available. An additional complication exists because two inequivalent reductions are needed: $SU_3 \supset SU_2 \times U_1$ in particle physics and $SU_3 \supset R_3$ in nuclear physics.

The purpose of this article is to: (i) Formulate in the spirit of an ordinary tensor formalism (built with tensors which by construction have the same null space properties as the Biedenharn and Louck Wigner operators) a general but simple and hence practical algorithm for generating $SU_3 \supset SU_2 \times U_1$ Wigner coefficients for arbitrary couplings and multiplicities; (ii) express $SU_3$ Racah coefficients as the solution to a set of simultaneous equations with the unknown coefficients given as a by-product of the initial steps in the $SU_3 \supset SU_2 \times U_1$ Wigner coefficient construction algorithm; (iii) exploit properties of the $SU_3 \supset R_3$ projection process together with known transformation coefficients between the $SU_3 \supset SU_2 \times U_1$ and $SU_3 \supset R_3$ schemes to express $SU_3 \supset R_3$ Wigner coefficients as a sum over a particularly simple subset of the corresponding $SU_3 \supset SU_2 \times U_1$ Wigner coefficients; (iv) list symmetry properties of the transformation coefficients between the $SU_3 \supset SU_2 \times U_1$ and $SU_3 \supset R_3$ schemes and discuss conjugation properties of state vectors for both reductions; (v) give symmetry properties for both the $SU_3 \supset SU_2 \times U_1$ and $SU_3 \supset R_3$ Wigner coefficients. We begin by briefly reviewing common notations and discussing their relationship to one another.

2. BASIC NOTATION

The labels $\lambda$ and $\mu$ are used to characterize the irreducible representations of $SU_3$. The row labels in the $SU_3 \supset SU_2 \times U_1$ reduction are chosen as

$$\epsilon = 2\lambda + \mu - 3(p + q) = -3Y,$$

$$\Lambda = (\mu + p - q)/2 = I,$$

$$M_A = r - \Lambda = I_1,$$

where the integers $p, q, r$ satisfy $0 \leq p \leq \lambda$, $0 \leq q \leq \mu$, $0 \leq r \leq \Lambda$. The notation $(\lambda\mu)^{\Lambda M_A}$ is that introduced by Elliott into nuclear physics to label states in the so-called intrinsic or body-fixed system. In terms of a three-dimensional oscillator with $n_i$ quanta in the $i$-direction, $\epsilon = 2n_3 - n_2 - n_1$, while $\Lambda$ labels the irreducible representation of $SU_2$ with projection $M_A = (n_1 - n_2)/2$. In particle physics states are labeled as $(\lambda\mu)^{\Lambda M_A}$ with $Y$ denoting the hypercharge and $I$ and $I_1$ the isospin and its projection, respectively.

An equivalent but mathematically more elegant notation is due to Gel'fand in which case states are labeled by patterns of the type

$$|G\rangle = \begin{pmatrix} g_{13} & g_{23} & g_{33} \\ g_{12} & g_{22} & g_{11} \end{pmatrix}.$$

The $g_{ij}, 1 \leq i \leq j \leq 3$, specify the irreducible representation of $U_1$ in the chain $U_3 \supset U_2 \supset U_1$. Specifically, $g_{ij}$ is the number of boxes in row $i$ of the Young tableau for $U_1, \lambda = g_{13} - g_{23}, \mu = g_{23} - g_{33}$, and $\nu = g_{33}$ are then the number of columns containing 1, 2, and 3 boxes, respectively, in the Young tableau for $U_3$. For notational convenience $G$ (for Gel'fand) will be used to denote the full set of $g_{ij}$ labels. Apart from an $n_i$-dependent phase factor $|G\rangle = (\lambda\mu)^{\Lambda M_A}$ with $g_{12} = p + \mu + \nu = \frac{3(\lambda + 2\mu)}{2} - \frac{3}{2} - \frac{\lambda + \mu}{2}$, $g_{22} = g + \nu = \frac{3(\lambda + 2\mu)}{2} - \frac{3}{2} - \frac{\lambda + \mu}{2}$, and $g_{11} = r + q + \nu = 2M_A + \frac{3(\lambda + 2\mu)}{2} - \frac{3}{2} - \frac{\lambda + \mu}{2}$, the so-called betweenness conditions ($g_{ij} \geq g_{i+1,j-1}$) are equivalent to the restrictions $0 \leq p \leq \lambda$, $0 \leq q \leq \mu$, $0 \leq r \leq \Lambda$.

States of particular interest are those for which the number of oscillator quanta $(n_i = \sum_j g_{ij} - \sum_j g_{j+1,i-1})$ in
the 3-direction is either a maximum or a minimum. The
value of the subgroup labels for these so-called extremal
states \((G_E)\) are summarized by Table 1. The \(I\) and \(J\)
labels form a convenient code by which the states can be
distinguished. The labels \(\lambda, \mu, \nu\) can therefore be thought
of as either specifying or being specified by the dis­
bution of oscillator quanta for extremal states.

In the \(SU_3 \supset R_3\) reduction states are labeled by the
total angular momentum \(L\) and its projection \(M\). Multiple
occurrences of a given \(L\) can be distinguished in a
variety of ways.\(^{16}\) The physically most significant scheme
is that due to Elliott in which case \(K\), the projection of \(L\)
along the body-fixed 3-axis, is used to sort the \(L\)-values
into the familiar \(K\)-bands of rotational model theory.\(^{17}\)
The prescription given is that projected states defined by

\[
|G)KLM\rangle = P_{Bk}(G) |G) = (2L + 1) \int d\Omega D^*_B(G)(R(\Omega))|G) \quad (3)
\]

form a complete basis if \(G = G_E\) and for:

\[
\begin{align*}
G_E &= G_W: \\
L &= K, K + 1, \ldots, K + \mu, \quad K \neq 0, \\
L &= \mu, \mu - 2, \ldots, 1, 0, \quad K = 0; \quad (4a)
\end{align*}
\]

\[
\begin{align*}
G_E &= G_W: \\
L &= K, K + 1, \ldots, K + \lambda, \quad K \neq 0, \\
L &= \lambda, \lambda - 2, \ldots, 1, 0, \quad K = 0. \quad (4b)
\end{align*}
\]

In Eq. (3), \(D^*_B(G)\) is an \(R_3\) rotation matrix and \(R(\Omega)\) is
an \(R_3\) rotation operator. The integration is over Euler
angles.

States defined by Eqs. (3)–(4) are not normalized nor
are they orthogonal with respect to the \(K\)-label. Working
within such a scheme leads ultimately to nonhermitian
matrices. To avoid this complication, it is convenient to
orthonormalize the basis using a Gram–Schmidt process.
The physical interpretation of \(K\) as a band label can be
maintained approximately if a prescription analogous to
that outlined by Vergados is used.\(^{18}\) In this case

\[
|G)X\rangle_{KLM} = \sum_{j=I} O_{ij} |G)K_jLM\rangle, \quad (5)
\]

where the orthonormalization matrix \(O_{ij}\) is defined re­
cursively by the formulas

\[
O_{ii} = 1/|\langle(G)K_iLM |(G)K_iLM\rangle - \sum_{j \neq i} O_{ij} O_{ji}|^{1/2}, \quad (6a)
\]

\[
O_{ij} = O_{ji}(\delta_{ij} - \sum_{k \neq i} O_{kj} O_{ki})^{1/2}. \quad (6b)
\]

An analytic expression which allows the coefficients
\(\langle(G)K_iLM |(G)K_iLM\rangle\) to be evaluated is given in Sec. 3.
Unlike the \(K\) of Vergados, \(K\) like \(K\) is given by either Eq.
\((4a)\) or Eq. \((4b)\). The extent to which different \(K\)-values
are mixed by the orthonormalization process depends
upon the relative magnitude of the coefficients \(\langle(G)K_iLM |(G)K_jLM\rangle\) and \(\langle(G)K_iLM |(G)K_jLM\rangle\). It can be verified that
the mixing is indeed small. In particular, for \(G_E = G_W\) and \(i \neq j \langle(G)K_iLM |(G)K_jLM\rangle \to 0 \) if \(\mu(\mu)\) is
fixed and \(\mu(\mu) \to \infty\).

3. ALGEBRAIC FORMULATION

If \(\alpha\) represents a set of row labels used to distinguish
orthonormal basis states within a given representation of
\(SU_3(\alpha = \epsilon M\lambda, \text{or } SU_3\text{, or } \cdots)\), the Wigner co­
efficients \(\langle(\lambda_1\mu_1)\alpha_1 |(\lambda_2\mu_2)\alpha_2 \rangle\) are by definition
the elements of a unitary transformation between coupled
and uncoupled representations of \(SU_3\) in the \(\alpha\)-scheme,

\[
\sum_{\alpha_2} \langle(\lambda_1\mu_1)\alpha_1 |(\lambda_2\mu_2)\alpha_2 |(\lambda_3\mu_2)\alpha_2 |(\lambda_3\mu_3)\alpha_3 \rangle |(\lambda_3\mu_3)\alpha_3 \rangle = \epsilon^2 |\alpha_3\rangle. \quad (7)
\]

The outer multiplicity label \(\rho = 1, 2, \ldots, \rho_{\text{max}}\) is used to
distinguish multiple occurrences of a given \((\lambda_3\mu_3)\) in the
direct product \((\lambda_1\mu_1) \times (\lambda_2\mu_2)\). Although a definition
bearing physical significance comparable, for example,
to that associated with Elliott’s choice of \(K\) for a resolu­tion
of the inner multiplicity problem in the \(SU_3 \supset R_3\)
reduction has not been proposed to fix \(\rho,\) Biedenharn and
Louch and co-workers have demonstrated in a series of
articles\(^{6–12}\) that a mathematically canonical definition
which puts the outer multiplicity on a sound group theo­
retical basis can be obtained through the use of the labels
of an upper Gel’fand pattern for a Wigner operator of
irreducible tensor character \((\lambda_1\mu_2)\). The practical
aspects of this choice are manifest in the vanishing of cer­
tain Wigner and Racah coefficients \([\text{Eqs. (18), (23), below}],\)
simple symmetry relations under conjugation [\text{Eqs. (35)–
(38), below}], and nice limiting properties for the \(SU_3 \supset SU_2 \times U_1\) Wigner coefficients \([\text{see Ref. 11, for example}].\)
Oblivious below are techniques which exploit the essential
features of this definition (albeit somewhat obscure but
only so as to minimize notational needs) in defining an
algorithm (based on an ordinary tensor formalism built
with tensor operators which by construction have the
same null space properties as the Wigner operators of
Biedenharn and Louch) which can be used to evaluate all
\(SU_3 \supset SU_2 \times U_1\) Wigner coefficients. Note that for most
practical purposes, however, the outer multiplicity can
be considered fully labelled with a running index \(\rho = 1,
2, \ldots, \rho_{\text{max}}\) which distinguishes orthonormal basis states
in the product space,

\[
\sum_{\rho_{\text{max}}} \langle(\lambda_1\mu_1)\alpha_1 |(\lambda_2\mu_2)\alpha_2 |(\lambda_3\mu_3)\alpha_3 \rangle |(\lambda_3\mu_3)\alpha_3 |(\lambda_{\rho_{\text{max}}}\mu_{\rho_{\text{max}}}\alpha_\rho) \rangle = \delta_{\lambda_1\lambda_2} \delta_{\mu_1\mu_2} \delta_{\rho_{\text{max}}\rho_{\text{max}}} \delta_{\rho \rho_{\text{max}}}. \quad (8)
\]

A. \(SU_3 \supset SU_2 \times U_1\) Wigner coefficients

Irreducible tensor operators under \(SU_3, T^{(\rho\rho)}\), can be
defined through their commutation properties with the
infiniteansmal generators of the group.\(^{19}\) The Wigner–Eckart theorem allows one to express the matrix ele­
ments of tensor operators defined in this manner as a
sum over \(\rho\) of the product of a \(\rho\)-dependent generalized
reduced matrix element multiplied by the corresponding Wigner coefficient, for the $SU_3 \times SU_2 \times U_1$ reduction, 
\[
\langle \lambda_3 \mu_3 | \langle 3 | M_{\lambda_3} \rangle | \lambda_1 \mu_1 \rangle = \sum_{A_2, A_3, A_4} \langle \lambda_1 \mu_1 | A_1 \lambda_1 M_{\lambda_1} \rangle \langle \lambda_2 M_{\lambda_2} | \lambda_3 \mu_3 \rangle,
\]
(9)

This result can be used to define Wigner coefficients through the matrix elements of specially chosen tensor operators $K^{(a_2^{\pm}(\rho)}$:
\[
\langle \lambda_3 \mu_3 | \pi_{A_2} \pi_{A_3} \pi_{A_4} \rangle | \lambda_1 \mu_1 \rangle = \langle \lambda_1 \mu_1 \rangle \langle \lambda_2 \mu_2 | \lambda_3 \mu_3 \rangle = \langle \lambda_1 \mu_1 \rangle \langle \lambda_2 \mu_2 | \lambda_3 \mu_3 \rangle,
\]
(10)

for which the $\rho$ summation of Eq. (9) is not required. The generalized reduced matrix element $(\langle A_1 \lambda_1 \mu_1 \rangle)/(\langle A_2 \lambda_2 \mu_2 \rangle)$ is then just a normalization factor. In particular, the infinitesimal generators which have irreducible tensor character $(\lambda_1 \mu_1 \lambda_2 \mu_2)$ are by definition matrix elements of the $\rho = 1$ variety.

The problem is then one of constructing the operators $K^{(a_2^{\pm}(\rho)}$; and in particular, constructing them in a manner which serves to uniquely define the outer multiplicity label $\rho$. The scheme is straightforward: Clearly $\rho_{\text{max}}$ the number of occurrences of $(\lambda_3 \mu_3)$ in the direct product $(\lambda_1 \mu_1) \times (\lambda_2 \mu_2)$ depends upon $\lambda_1, \mu_1, \lambda_2, \mu_2, \lambda_3, \mu_3$. It is also clear that there exists an $\eta$ such that $(\lambda_3 \mu_3)$ occurs exactly $\eta$ times in the product $(\lambda_1 \mu_1) \times (\lambda_2 \mu_2) - \eta \lambda_3, \lambda_2 \mu_2 - \eta \lambda_2, \lambda_2 \mu_2 - \eta \lambda_3, \mu_2$. And in this case $\rho$ depends upon $\lambda_1, \mu_1, \lambda_2 - \eta \lambda_3, \mu_2 - \eta \lambda_2, \lambda_2 - \eta \lambda_3, \mu_2 - \eta \lambda_2$. Let $\eta_{\text{max}}$ be the value of $\eta$ such that $(\lambda_1 \mu_1) \times (\lambda_2 - \eta \lambda_3, \mu_2 - \eta \lambda_2) \times (\lambda_3 \mu_3)$ is not allowed whereas $(\lambda_1 \mu_1) \times (\lambda_2 - \eta \lambda_3, \mu_2 - \eta \lambda_2) \times (\lambda_3 \mu_3)$ occurs with a multiplicity of one. Then $(\lambda_1 \mu_1) \times (\lambda_2 - \eta \lambda_3, \mu_2 - \eta \lambda_2)$ occurs with a multiplicity of $\rho$ for $\rho = 1, 2, \ldots, \eta_{\text{max}}$. In this way, $(\lambda_1 \mu_1) \times (\lambda_2 - \eta \lambda_3, \mu_2 - \eta \lambda_2)$ can be considered the parent coupling for the $\rho$th occurrence of $(\lambda_3 \mu_3)$ in the product $(\lambda_1 \mu_1) \times (\lambda_2 - \eta \lambda_3, \mu_2 - \eta \lambda_2)$. The question then arises: Is it possible to construct the $K^{(a_2^{\pm}(\rho)}$ from the corresponding $K^{(a_2^{\pm}(\rho)}$ in such a way as to preserve the unique null space property of the parent operator which allow it to generate the $\rho$th occurrence (and no more) of $(\lambda_3 \mu_3)$ in the product space? The answer is yes, it can be done via a build-up process using the group generators $K^{(1)}$.

In particular, the result
\[
K^{(a_2^{\pm}(\rho)} = [K^{(\rho - 1, \mu_2 - 1)} \times K^{(1)}] \langle \rho | \pi_{A_1} \pi_{A_2} \rangle, 
\]
(11)

allows one to relate $K^{(a_2^{\pm}(\rho)}$ to $K^{(a_2^{\pm}(\rho)}$ for each $\rho$. Logical consistency demands, of course, that each step $\rho$ be chosen numerically equal to $\rho$ and that $\rho = 1$ corresponds to a multiplicity free parent coupling, $\rho = 2$ to the second solution in the parent coupling having a twofold outer multiplicity, etc. The tilde, however, is used to denote the fact that $\rho$-orthogonality in the product space is not guaranteed; that is, $K^{(a_2^{\pm}(\rho)}$ will in general be a linear combination of all $K^{(a_2^{\pm}(\rho)}$ with $\rho \leq \rho$. That operators with $\rho > \rho$ are not generated is a consequence of the fact that the group generators preserve the null space properties of the parent operator. Further discussion on the consequence of this result is given below. In effect, it means that the weight diagram for a coupled operator of the type $T^{(a_2^{\pm}(\rho)} \times K^{(1)}$ is the same as for $T^{(a_2^{\pm}(\rho)}$. To be sure, the build-up process cannot be used to define $K^{(a_2^{\pm}(\rho)}$ because $K^{(a_2^{\pm}(\rho)} = 0$. But this presents no major problem since an analytic expression for the Wigner coefficients corresponding to the $\rho$th occurrence of $(\lambda_3 \mu_3)$ in the product $(\lambda_1 \mu_1 \lambda_2 \mu_2) = \langle \rho \rangle (9)$ is available [Eq. (20), below] and through Eq. (10) serves to define the first nonvanishing operator in the build-up process. Note that the Wigner coefficient appearing in Eq. (11) is multiplicity free. Substitution of Eq. (11) into Eq. (10) yields
\[
\langle \lambda_1 \mu_1 | \pi_{A_1} \pi_{A_2} \pi_{A_3} \rangle | \lambda_2 \mu_2 | \lambda_3 \mu_3 \rangle = \langle \lambda_1 \mu_1 \rangle \langle \lambda_2 \mu_2 \rangle \langle \lambda_3 \mu_3 \rangle,
\]
(12)

If $K^{(1)}$ were not chosen to be of the generator type, representations other than $(\lambda_1 \mu_1)$ would appear on the right- and left-hand sides of the matrix elements of $K^{(a_2^{\pm}(\rho)}$ and a summation over these representation labels would be required. Factoring each coupling coefficient into a reduced coefficient (double-barred or isoscalar part) multiplied by an ordinary coefficient which carries the dependence upon the $SU_3$ projection labels and carrying out the summation over projection quantum numbers yields
\[
\langle \lambda_1 \mu_1 \rangle \langle \lambda_2 \mu_2 \rangle \langle \lambda_3 \mu_3 \rangle = \langle \lambda_1 \mu_1 \rangle \langle \lambda_2 \mu_2 \rangle \langle \lambda_3 \mu_3 \rangle.
\]
(13)

It should be emphasized that Eq. (13) is valid for completely general arguments $\lambda_1, \lambda_2, \lambda_3, \lambda_2, \lambda_3$ and, furthermore, that certain coupling coefficients derived using this expression must necessarily vanish identically. To see this, consider in more detail a coefficient calculated by repeating the recursion process $\eta$ times. The required matrix elements are for a tensor operator.

\[ K^{(\lambda,\mu)}(\rho) = \left[ \cdots \left\{ K^{(\lambda-n,\mu-n)}(\rho) \times K^{(1)}(\rho) \right\} \times K^{(1)}(\rho) \cdots \times K^{(1)}(\rho) \right]_{\rho=0}^{\eta}, \]

in which \( K^{(1)}(\rho) \) appears \( \eta \) times. In general, the maximum change in \( \Lambda \) induced by an operator \( K^{(\lambda,\mu)} \) is \( \frac{1}{2}(\lambda + \mu) \) since this is the maximum value of \( \Lambda \) in the representation \( (\lambda, \mu) \). The generators, however, are of a special type; they change \( \Lambda \) by at most \( \frac{1}{2} \). The operator given by Eq. (14) can therefore change \( \Lambda \) by at most \( (\Lambda_2 - \lambda_2 - \mu_2)/2 + \eta/2 = (\lambda_3 + \mu_3 - \eta)/2 \). Consequently, the corresponding coupling coefficient must be zero if \( |\Lambda_1 - \Lambda_2| > \frac{1}{2}(\lambda_2 + \mu_2 - \mu) \). The maximum \( \eta \) for which this result is valid is simply \( \eta = \eta_{\text{max}} - \rho \). Consequently \( \langle (\lambda_1, \mu_1)_{\lambda_1} ; (\lambda_2, \mu_2)_{\lambda_2} \rangle \langle (\lambda_3, \mu_3)_{\lambda_3} \rangle \) must vanish for \( |\Lambda_1 - \Lambda_2| > \frac{1}{2}(\lambda_2 + \mu_2 - \mu_3) \). This property is completely general and a direct consequence of the build-up process used to define the coefficients. Note that the number of predictions forced to be zero (more zeros may appear but for other reasons) is always a decreasing function of \( \rho \). Although solutions obtained via repeated applications of Eq. (13) are not necessarily orthogonal with respect to the \( \rho \)-label, orthogonalizing in the increasing order \( \rho = 1, 2, \ldots, \rho_{\text{max}} \) using a Gram-Schmidt process preserves the vanishings; and hence the Wigner coefficients satisfy

\[ \langle (\lambda_1, \mu_1)_{\lambda_1} ; (\lambda_2, \mu_2)_{\lambda_2} ; (\lambda_3, \mu_3)_{\lambda_3} \rangle \]

This then guarantees the uniqueness of our result which by construction coincides with the Biedenharn and Louck prescription for a resolution of the outer multiplicity. Thus Eq. (13) provides a recursive means of defining the \( SU_3 \times SU_3 \times U_1 \) Wigner coefficients for each mode of coupling characterized by \( \rho \).

An expression which is computationally convenient to evaluate can be obtained from Eq. (13) by restricting \( \lambda, \mu, \lambda_2, \mu_2 \) to be of HW and \( \lambda_3, \mu_3 \) are determined. Coefficients with \( \epsilon_3 A_3 = \text{HW} \) follow from the ordinary recursion formulas

\[ \langle (\lambda, \mu)_{\lambda} ; (\lambda_2, \mu_2)_{\lambda_2} \rangle \langle (\lambda_3, \mu_3)_{\lambda_3} \rangle = N(\lambda_2 + \frac{1}{2}) \]
is allowed and Eq. (20) cannot be used to generate an additional independent solution or \((\lambda_1, \mu_1) \times (\lambda_2 - 1, \mu_2 - 1) \rightarrow (\lambda_3, \mu_3)\) is not allowed and Eq. (20) provides the only solution. For \(n = 2\), \(p_{\text{max}}\) may be either one, two, or three. And in this case it is still possible to generate useful algebraic results. For \(n > 2\), however, the recursion process yields unwieldy expressions making the algebraic approach extremely difficult if not impossible.

However, from the systematics of the results it is possible to predict a general algebraic expression for \(\langle \lambda_1, \mu_1 | \text{HW}; (\lambda_2, \mu_2) | (\lambda_3, \mu_3) | \text{HW}\rangle_\rho = N^p(\tilde{p}_2) [\tilde{G}(\tilde{q}_2)/H(\tilde{q}_2)]^{1/2},\)

\[
F(\tilde{p}_2) = \left\{ \begin{array}{ll}
1, & \tilde{p}_2 = 0, \\
(1 - \tilde{p}_2^2) \sum_{i=0}^{\tilde{p}_2} \tilde{p}_2 \tilde{f}_{\rho i-1} / i, & \tilde{p}_2 \neq 0,
\end{array} \right.
\]

\[
f(j) = \left\{ \begin{array}{ll}
0, & j < \tilde{p}_2, \\
(\tilde{p}_2 + j + 1)(\mu_1 + \tilde{\lambda}_2 + \tilde{\mu}_2 - n - j + 2), & j > \tilde{p}_2, \\
(2a + j)(b - j - 1), & j = \tilde{p}_2,
\end{array} \right.
\]

\[
G(\tilde{q}_2) = \left( \begin{array}{c}
(\tilde{\lambda}_2 - 2\tilde{\mu}_2 + n + 1) / \tilde{q}_2 \\
1 \\
i/2,
\end{array} \right),
\]

\[
ge(j) = \left\{ \begin{array}{ll}
0, & j < \tilde{q}_2, \\
(\tilde{p}_2 + j)(b - j - 1)/2 + 1, & j = \tilde{q}_2,
\end{array} \right.
\]

\[
H(\tilde{q}_2) = \left( \begin{array}{c}
(\tilde{\lambda}_2 - \tilde{\mu}_2 + 1) / \tilde{q}_2 \\
1/(2\sqrt{\tilde{\lambda}_2 + 1}) \\
1/(\tilde{\mu}_2 + \tilde{\lambda}_2 + 1)
\end{array} \right),
\]

where \(N\) is again the normalization factor. The formula \[\langle \lambda_1, \mu_1 | \text{HW}; (\tilde{\lambda}_2, \tilde{\mu}_2) | (\lambda_3, \mu_3) | \text{HW}\rangle_\rho = N(\tilde{p}_2) [\tilde{G}(\tilde{q}_2)/H(\tilde{q}_2)]^{1/2},\]

\[
\begin{align*}
&= \left( \frac{2\lambda'_1 + 1}{2\lambda'_1 + 2} \right)^{1/2} \sum_{\lambda'_2, \mu'_2} Y(\lambda'_1, \lambda'_2) \\
&\times \langle \lambda_1, \mu_1 | \lambda'_1, \mu'_2; (\lambda_2, \mu_2) | (\lambda_3, \mu_3) | \text{HW}\rangle,
\end{align*}
\]

\[
Y(\lambda_1 + \frac{1}{2}, \lambda_2 - \frac{3}{2}) = - \left[ S(\tilde{q}_2) [B(\lambda_1, \lambda_2, \frac{\lambda_3}{2}) + \frac{1}{2}] \right] \times [B(\lambda_1, \lambda_2, \lambda_3/2) + \frac{1}{2}]^{1/2},
\]

\[
Y(\lambda_1 + \frac{1}{2}, \lambda_2 - \frac{1}{2}) = - \left[ S(\tilde{p}_2) [C(\lambda_1, \lambda_2, \lambda_3/2) + \frac{1}{2}] \right] \times [D(\lambda_1, \lambda_2, \lambda_3/2) + \frac{1}{2}]^{1/2},
\]

\[
Y(\lambda_1 - \frac{1}{2}, \lambda_2 - \frac{3}{2}) = - \left[ S(\tilde{q}_2) [C(\lambda_1, \lambda_2, \lambda_3/2) + \frac{1}{2}] \right] \times [D(\lambda_1, \lambda_2, \lambda_3/2) + \frac{1}{2}]^{1/2},
\]

\[
Y(\lambda_1 - \frac{1}{2}, \lambda_2 - \frac{1}{2}) = - \left[ S(\tilde{p}_2) [C(\lambda_1, \lambda_2, \lambda_3/2) + \frac{1}{2}] \right] \times [D(\lambda_1, \lambda_2, \lambda_3/2) + \frac{1}{2}]^{1/2},
\]

\[
N(\lambda_1 + \frac{1}{2}) = S(\tilde{q}_1),
\]

\[
N(\lambda_1 - \frac{1}{2}) = R(\tilde{p}_1),
\]

\[
\text{can be used to generate coefficients with } \epsilon_1 \Lambda_1 = \text{HW recursively. Note that Eq. (20) is valid for all } \rho; \text{ it can be}
\]

\[
\text{used to provide the starting coefficients for the recursion process.}
\]

The computational algorithm is then clear: Neglecting normalization factors, for each \(\rho = 1, 2, \ldots, p_{\text{max}}, (1)\) start with the \(\langle \lambda_1, \mu_1 | \text{HW}; (\tilde{\lambda}_2, \tilde{\mu}_2) | (\lambda_3, \mu_3) | \text{HW}\rangle_\rho \) of Eq. (20) and use Eq. (21) to generate the \(\langle \lambda_1, \mu_1 | \lambda'_1, \mu'_2; (\lambda_2, \mu_2) | (\lambda_3, \mu_3) | \text{HW}\rangle_\rho \) (i) make use of Eq. (17) to generate the \(\langle \lambda_1, \mu_1 | \lambda'_1, \mu'_2; (\lambda_2, \mu_2) | (\lambda_3, \mu_3) | \text{HW}\rangle_\rho \) from the \(\langle \lambda_1, \mu_1 | \lambda'_1, \mu'_2; (\lambda_2, \mu_2) | (\lambda_3, \mu_3) | \text{HW}\rangle_\rho \) and (ii) obtain the \(\langle \lambda_1, \mu_1 | \lambda'_1, \mu'_2; (\lambda_2, \mu_2) | (\lambda_3, \mu_3) | \text{HW}\rangle_\rho \) by using Eq. (18) to stop the \(\epsilon_1 \Lambda_1 \) labels. Then (iv) use Eq. (8) with \(\epsilon_3 = \epsilon_3 \Lambda_3 = \text{HW} \) to orthonormalize the resultant coefficients in the increasing order \(\rho = 1, 2, \ldots, p_{\text{max}}\), and, depending upon need, (v) obtain the \(\langle \lambda_1, \mu_1 | \lambda'_1, \mu'_2; (\lambda_2, \mu_2) | (\lambda_3, \mu_3) | \text{HW}\rangle_\rho \) by using Eq. (19) to stop the \(\epsilon_3 \Lambda_3 \) labels.

The process serves to define SU \(3 \times SU \times U_1 \) Wigner coefficients to within an overall phase. The simplest and most natural way for fixing the phase is to take all the normalization factors involved in the process to be positive, and we adopt this convention. This is very different from the ordinary procedure in which a particular coefficient is assigned to be positive for each mode of coupling, i.e., each \(p\)-label.\(^{12}\) With the current approach, however, it is difficult to predict the sign of each individual coefficient, making a \textit{a priori} introduction of the ordinary convention practically impossible. Of course, the technique outlined above allows the ordinary convention to be introduced \textit{a posteriori} during the orthonormalization process. And such a choice reflects it-
self in the p-dependence of the symmetry properties of the Wigner coefficients (see Sec. 4).

It is interesting to note the effect of changing the order of the coupling in Eq. (11),
\[
K^{(1)\lambda \mu} \left( \epsilon_{12} \right) \left( \epsilon_{23} \right) = \sum_{\lambda_{1} \mu_{1} \lambda_{2} \mu_{2} \lambda_{3} \mu_{3}} \left( \lambda_{1} \mu_{1} \lambda_{2} \mu_{2} \lambda_{3} \mu_{3} \right) \left( \lambda_{12} \mu_{12} \lambda_{23} \mu_{23} \lambda_{3} \mu_{3} \right) \left( \lambda_{1} \mu_{1} \right) \left( \lambda_{2} \mu_{2} \right) \left( \lambda_{3} \mu_{3} \right) \left( \epsilon_{12} \right) \left( \epsilon_{23} \right)
\]

For this form, the result corresponding to Eq. (13) is
\[
\sum_{\lambda_{1} \mu_{1} \lambda_{2} \mu_{2} \lambda_{3} \mu_{3}} \left( \lambda_{1} \mu_{1} \lambda_{2} \mu_{2} \lambda_{3} \mu_{3} \right) \left( \lambda_{12} \mu_{12} \lambda_{23} \mu_{23} \lambda_{3} \mu_{3} \right) \left( \lambda_{1} \mu_{1} \right) \left( \lambda_{2} \mu_{2} \right) \left( \lambda_{3} \mu_{3} \right) \left( \epsilon_{12} \right) \left( \epsilon_{23} \right)
\]

The choice \( \epsilon_{1} \lambda_{1} = HW \) and \( \epsilon_{2} \lambda_{2} = LW \) rather than \( \epsilon_{1} \lambda_{2} \) = HW and \( \epsilon_{2} \lambda_{1} = LW \) can then be used to obtain a recursion relationship analogous to Eq. (17).

B. \( SU_{3} \) Racah coefficients

A straightforward generalization of the relationships between \( SU_{2} \) unitary recoupling coefficients and \( SU_{3} \) Wigner coefficients leads to the corresponding relationships between \( SU_{3} \) unitary recoupling (Racah or U functions) and \( SU_{3} \) Wigner coefficients.19 The most practical of these relationships for evaluating recoupling coefficients in terms of known Wigner coefficients is
\[
\sum_{\lambda_{1} \mu_{1} \lambda_{2} \mu_{2} \lambda_{3} \mu_{3}} \left( \lambda_{1} \mu_{1} \lambda_{2} \mu_{2} \lambda_{3} \mu_{3} \right) \left( \lambda_{1} \mu_{1} \right) \left( \lambda_{2} \mu_{2} \right) \left( \lambda_{3} \mu_{3} \right) \left( \epsilon_{12} \right) \left( \epsilon_{23} \right)
\]

The choice \( \epsilon_{1} \lambda_{1} = HW \) and \( \epsilon_{2} \lambda_{2} = LW \) in this expression will then be used to obtain a recursion relationship analogous to Eq. (17).

The sum on the right-hand side of Eq. (13) can with the help of Eq. (22) be identified (apart from orthogonality) as simply
\[
\sum_{\lambda_{1} \mu_{1} \lambda_{2} \mu_{2} \lambda_{3} \mu_{3}} \left( \lambda_{1} \mu_{1} \lambda_{2} \mu_{2} \lambda_{3} \mu_{3} \right) \left( \lambda_{12} \mu_{12} \lambda_{23} \mu_{23} \lambda_{3} \mu_{3} \right) \left( \lambda_{1} \mu_{1} \right) \left( \lambda_{2} \mu_{2} \right) \left( \lambda_{3} \mu_{3} \right) \left( \epsilon_{12} \right) \left( \epsilon_{23} \right)
\]

This is a direct consequence of the special character of the couplings involved in the product tensors of Eq. (11). More general couplings would, by analogy with \( SU_{2} \), require a 9-(\( \lambda \mu \)) symbol.22 The recursion formula (13) could therefore, in retrospect, be obtained from Eq. (22) by requiring \( U((1)_{\lambda_{1} \mu_{1}}(11)_{\lambda_{2} \mu_{2}}(12)_{\lambda_{3} \mu_{3}}) = \delta(\lambda_{1} \mu_{1} = 1, \lambda_{2} \mu_{2} = \lambda_{3} \mu_{3} = 1, \rho_{P} = \rho_{\mu_{P}}) = 0 \) for \( \rho_{P} = \rho_{\mu_{P}} \). And indeed, this suggests a simple method by which the techniques developed in this article may be generalized to other group structures. Note that the orthonormalization process, if carried out in the increasing order \( p = 1, 2, \ldots, \rho_{\mu_{P}} \), maintains the zero value of the \( U \) function for \( \rho_{P} > \rho_{\mu_{P}} \).

Consequently,
\[
U((1)_{\lambda_{1} \mu_{1}}(11)_{\lambda_{2} \mu_{2}}(12)_{\lambda_{3} \mu_{3}})(1)_{\lambda_{1} \mu_{1}}(11)_{\lambda_{2} \mu_{2}}(12)_{\lambda_{3} \mu_{3}}) = \delta(\lambda_{1} \mu_{1} = 1, \lambda_{2} \mu_{2} = \lambda_{3} \mu_{3} = 1, \rho_{P} = \rho_{\mu_{P}}) = 0 \text{ for } \rho_{P} > \rho_{\mu_{P}}.
\]

This result also follows from property (15) and is a direct consequence of the Biedenharn and Louck prescription for specifying the outer multiplicity.

C. \( SU_{3} \rightarrow SU_{2} \) Wigner coefficients

The coefficients which effect the transformation between the \( \epsilon_{AM} \) and \( \chi_{LM} \) schemes are known.23 The choice made in Eq. (3) requires that an additional factor of \( 2L + 1 \) be included in evaluating Eq. (35) of Ref. 23. In addition, including the phase factor \( i^{L_{1}E_{2}} \) in the definition of \( |G\rangle \) makes the coefficient real. Explicitly, if
\[
|G_{p} \rangle = \sum_{g} O_{g} |G\rangle |G_{p} \rangle_{K_{g} L_{M}}
\]

then
\[
|G\rangle |G_{p} \rangle_{K_{g} L_{M}} = \sum_{g_{p}} O_{g_{p}} |G\rangle |G_{p} \rangle_{K_{g_{p}} L_{M}}
\]

where \( O_{g} \) is the orthonormalization matrix of Eq. (6) and \( |G\rangle |G_{p} \rangle_{K_{g} L_{M}} \) is the inner product of a state \(|G\rangle\) [defined by Eq. (2)] with a state \(|G_{p} \rangle\) [defined by Eqs. (3)–(4)]. The parameter \( g \) in Eq. (24) is used to denote the subgroup labels \( |G_{12} \rangle |G_{22} \rangle |G_{11} \rangle \sim p, q, r \) of \( G \). In terms of summation (\( K \rightarrow M, M \rightarrow M' \) for reasons of symmetry),
\[
|G\rangle |G_{p} \rangle_{K_{g} L_{M}} = \sum_{g_{p}} O_{g_{p}} |G\rangle |G_{p} \rangle_{K_{g_{p}} L_{M}}
\]

\[
|G\rangle |G_{p} \rangle_{K_{g} L_{M}} = \sum_{g_{p}} O_{g_{p}} |G\rangle |G_{p} \rangle_{K_{g_{p}} L_{M}}
\]

The corresponding expression for \( |G\rangle \langle G|^\dagger \) can be obtained by conjugation (see Sec. 4). Note in particular that the overlap of two projected states required for a determination of the orthonormalization matrix \( C_{ij} \) is given by

\[
\langle G_p | X^* (G^\dagger) | G_{2} \rangle = \langle G_p | X (G_{2}) \rangle.
\]  

(27)

Since \( |G\rangle \) differs from \(|\mu \rangle \langle \mu | M_\rho \rangle \) by at most an \( n_i \) dependent phase factor and \( n_i^{(1)} + n_i^{(2)} = n_i^{(0)} \), it is convenient to write

\[
|G_1 ; G_2 | G_3 \rangle_p = \langle \lambda_1 \mu_1 \rangle_e A_1 \lambda_1 \mu_1 (M_1) \lambda_2 \mu_2 A_2 \lambda_2 \mu_2 (M_2) \lambda_3 \mu_3 A_3 \lambda_3 \mu_3 (M_3).
\]

(28)

The \( SU_3 \to R_3 \) Wigner coefficients are then given by

\[
\langle G_1 | X_{\rho} | G_2 \rangle = \sum_{\rho \in \rho_0} \langle G_1 | X_{\rho} | G_2 \rangle \langle G_2 | X_{\rho} | G_3 \rangle_p
\]

(29)

An expression which is more convenient to evaluate from a computational point of view may be obtained by directly expanding the inner product

\[
\langle G_1 | X_{\rho} | G_2 \rangle = \sum_{\rho \in \rho_0} \langle G_1 | X_{\rho} | G_2 \rangle \langle G_2 | X_{\rho} | G_3 \rangle_p
\]

(30)

Making use of the fact that \( R_3 (\Omega) = R_1 (\Omega) R_2 (\Omega) \), the effect of the projection operator acting to the left can be determined. Integrating over Euler angles by means of the Clebsch–Gordan series for rotation matrices then leads to the result

\[
\langle G_1 | X_{\rho} | G_2 \rangle = \sum_{\rho \in \rho_0} \langle G_1 | X_{\rho} | G_2 \rangle \langle G_2 | X_{\rho} | G_3 \rangle_p
\]

(31)

Applying Eq. (5) to the 3-space yields the required \( SU_3 \to R_3 \) Wigner coefficients. Note that the summation in this case is over \( SU_3 \to SU_2 \times U_1 \) Wigner coefficients of the type \( G_3 \), i.e., \( \rho \), those which can be evaluated through Eqs. (17)–(18) without use of Eq. (19). Clearly a factorization into the product of a reduced \( SU_3 \to R_3 \) Wigner coefficient and an ordinary Wigner coefficient in \( R_3 \) space is possible. Note that it is unnecessary and indeed redundant to fix the phase for the \( SU_3 \to R_3 \) Wigner coefficients independently of that already chosen for the \( SU_3 \to SU_2 \times U_1 \) reduction. The orthonormality of the transformation coefficients between the two schemes guarantees a unique solution. In effect the choice is made by selecting positive roots in Eq. (6).

4. CONJUGATION AND SYMMETRY PROPERTIES

Since the \( SU_3 \to R_3 \) reduction is linked to the \( SU_3 \to SU_2 \times U_1 \) reduction via the transformation coefficients of Eqs. (24), it suffices to make a determination of the conjugation relationship and all symmetry properties for the \( SU_3 \to SU_2 \times U_1 \) reduction only. The corresponding \( SU_3 \to R_3 \) results follow from known relationships among the transformation coefficients between the two schemes.

A. State conjugation

The transformation coefficients \( (G | G_p) X (G_3) \) are the elements of a real unitary (hence orthogonal) matrix if \( |G\rangle \) = \( (i)^{\frac{n_1+2(n_2)}{2}} (h_{ij}) \), where the \( (h_{ij}) \) are states of the type defined by Moshinsky in terms of polynomials in creation operators acting on the vacuum.\(^{24}\) The choice \( (i)^{\frac{n_1}{2}} (h_{ij}) \) as suggested in Ref. 23 is also acceptable. In this case, however, the states would not transform according to conventional phase through the SU operation (\( r \)-rotation about the 2 axis \( \times \) time reversal) as defined by Bohr and Mottelson.\(^{29}\) The results given in Appendix A2 of Ref. 19 for the adjoint irreducible representation can then be used to show that\(^{26}\)

\[
|G\rangle = (-1)^{\rho r} \langle G\rangle^*, \quad \lambda = \mu, \quad \vec{p} = \mu - q, \quad \vec{q} = \lambda - \rho, \quad \vec{r} = \rho + q - r
\]

(32)

Note that \( p - r = \frac{1}{2} (\lambda - \mu) - \frac{1}{2} \epsilon - M_\rho = \vec{r} - \vec{p} \). The sign of \( M_\rho \) differs from that of Hecht due to the choice \( M_\rho = - \tilde{\lambda} \) of Eq. (1). This choice allows the more natural correspondence (\( \tilde{\lambda} \) = \( \frac{1}{2} \)) rather than (\( \lambda \) = \( \frac{1}{2} \)).

To discover the conjugation properties of the \( |G\rangle \langle G|^\dagger \) it suffices to know in addition to Eq. (32) the symmetry properties of the \( (G \langle G|^\dagger) \). By straightforward but tedious substitution it can be shown that for the inner product of \( |G\rangle \) with a state \( \langle G| \langle G|^\dagger \rangle \) defined by Eq. (3),

1. \( \langle G | G \rangle \langle G | ^\dagger \rangle = (\langle G | ^\dagger \rangle \langle G | ) \langle G \rangle \langle G|^\dagger \rangle \),
2. \( \langle G | \langle G \rangle = 0, \langle G \rangle = M \),
3. \( \langle G | \langle G \rangle = (-1)^{\lambda_1 + \lambda_2 + \lambda_3} \langle G | \langle G \rangle \),
4. \( \langle G | \langle G \rangle = \langle G | ^\dagger \rangle \langle G | ^\dagger \rangle \),
5A. \( \langle G | M \rangle = (-1)^{\lambda_1 + \lambda_2 + \lambda_3} \langle G | M \rangle \langle G | M \rangle \),
5B. \( \langle G | M \rangle = \langle G | M \rangle \langle G | M \rangle \),
6A. \( \langle G | M \rangle = \langle G | M \rangle \langle G | M \rangle \),
6B. \( \langle G | M \rangle = \langle G | M \rangle \langle G | M \rangle \).

(33)

Since \( K = 2n \) when \( n \) is integral, the symmetries apply directly to the \( |G\rangle \langle G|^\dagger \) as well as the \( \langle G | \langle G|^\dagger \rangle \). Property 6 together with property 1 insures that the \( \langle G | \langle G|^\dagger \rangle \) vanish for either \( 2A' + M \) or \( 2A + M \) odd. Properties 1, 5A, 4 can then be used to show that

\[
|G\rangle \langle G|^\dagger = (-1)^{\lambda_1 + \lambda_2 + \lambda_3} |G\rangle \langle G|^\dagger.
\]

(34)

Note that \( G = G_{1w} \) implies Eq. (4a) [Eq. (4b)] applies on the left whereas Eq. (4b) [Eq. (4a)] applies on the right. But since \( \lambda \) and \( \mu \) also interchange roles, \( K \) is left invariant.

B. Symmetry properties

In Sec. 3 a prescription is given for a unique determination, including phase, of all \( SU_3 \to SU_2 \times U_1 \) Wigner coefficients. In terms of \( g = \lambda_1 + \lambda_2 - \lambda_3 + \mu_1 + \mu_2 - \mu_3 \) which is even or odd as \( \lambda_1 + \lambda_2 + \lambda_3 - \mu_1 - \mu_2 + \mu_3 \)= \( \lambda_1 - \lambda_2 + \lambda_3 - \mu_1 + \mu_2 - \mu_3 \), \( \rho \) is even or odd. The corresponding symmetry properties are:

Symmetry Properties of the \( SU_3 \to SU_2 \times U_1 \) Wigner Coefficients

1A. \((G_1; G_2 | G_3)\) 
\[ \langle \mathbf{1}; \mathbf{2} | \mathbf{3} \rangle = \langle \mathbf{1}; \mathbf{2} | \mathbf{3} \rangle \]
where \(\langle \mathbf{1}; \mathbf{2} | \mathbf{3} \rangle = \langle \mathbf{1}; \mathbf{2} | \mathbf{3} \rangle \) is the symmetry of the expression for \((G_1; G_2 | G_3)\), given by the right-hand side of Eq.(13) with that for \((G_2; G_1 | G_3)\) given by the right-hand side of Eq. (13) then suffices by induction to establish the relationship for the general case. The validity of Symmetry 2, apart from phase, is a direct consequence of the symmetry nature of the formulation under the operation of conjugation. The appearance of the phase factor in this case, however, is by no means obvious. The factor \((-1)^\xi\) is a direct consequence of Eq. (32). But, as already suggested, consistency requires an additional phase, \((-1)^{\xi} \), in the general two-body effective interactions. Machine codes based on the results are therefore available. They allow a numerical determination of \(SU_3 \supset SU_2 \times U_1\) and \(SU_3 \supset R_3\) Wigner coefficients as well as \(SU_3\) Racah coefficients to be made for arbitrary couplings and multiplicity.

Practical considerations may favor adopting a different phase convention. But doing so requires a modification in the phases for the symmetries of Eq.(35). For example, under the convention adopted by Hecht, namely requiring \((\lambda_1 \mu_1 | \lambda_2 \mu_2 | \lambda_3 \mu_3) = 1\), i.e., \(\lambda_1 \mu_1 = 1\), the results can be summarized as follows:

Among these, the most important is Symmetry 1. Expression (20) satisfies this relation, for it follows that it holds for the coefficients \((G_1; G_2 | G_3)\), \((G_2; G_1 | G_3)\), and \((G_1; G_3 | G_2)\). A comparison of the expression for \((G_1; G_2 | G_3)\) given by the right-hand side of Eq.(13) with that for \((G_2; G_1 | G_3)\) given by the right-hand side of Eq. (13') then suffices by induction to establish the relationship for the general case. The validity of Symmetry 2, apart from phase, is a direct consequence of the symmetry nature of the formulation under the operation of conjugation. The appearance of the phase factor in this case, however, is by no means obvious. The factor \((-1)^\xi\) is a direct consequence of Eq. (32). But, as already suggested, consistency requires an additional phase, \((-1)^{\xi} \), in the general two-body effective interactions. Machine codes based on the results are therefore available. They allow a numerical determination of \(SU_3 \supset SU_2 \times U_1\) and \(SU_3 \supset R_3\) Wigner coefficients as well as \(SU_3\) Racah coefficients to be made for arbitrary couplings and multiplicity.

Although the emphasis in the present article has been on the practical aspects of calculating \(SU_3\) Wigner and Racah coefficients, it is quite possible, and indeed likely, that the build-up process using the group generators can be applied to the \(\Gamma\), Wigner operators of Biedenharn and Louck and co-workers for the couplings \((\lambda_1 \mu_1) \times (\lambda_2 \mu_2) \rightarrow (\lambda_3 \mu_3)\), \(\rho = 1, 2, \ldots, \rho_{\text{max}}\) to obtain the full set of Wigner operators for the coupling \((\lambda_1 \mu_1) \times (\lambda_2 \mu_2) \rightarrow (\lambda_3 \mu_3)\). Because of nonorthogonality, however, it is not clear that a simple interpretation of the structure of the operators in terms of geometrical properties of the so-called arrow patterns will be possible. Nevertheless, since our purpose in the present article is to avoid the luxury of mathematical sophistication the validity of such conjectures must be relegated to a later work.

**ACKNOWLEDGMENTS**

Thanks are due to nearly all the individuals with whom the authors had contact during the period in which the results reported in this article developed from mere speculation to concrete formulation. Special thanks, however, are due to K. T. Hecht for the expertise he provided in this technical phase of our research into the structure of light nuclei. It is also a pleasure to acknowledge the support of W. C. Parkinson and the cyclotron group at Michigan.

\*Work supported by the U.S. National Science Foundation.

† Present address: Department of Physics, University of Rochester, Rochester, New York.

‡ Present address: Department of Physics, Nihon University, Setagaya, Tokyo, Japan.


For a coupled system \((\lambda_1\mu_1) \times (\lambda_2\mu_2) = (\lambda_3\mu_3)\), Eq. (32) cannot simultaneously be applied to all three representations \((\lambda_1\mu_1)\), \((\lambda_2\mu_2)\), and \((\lambda_3\mu_3)\) in a consistent fashion. An additional dependence upon the multiplicity label is required. See, for example, J. J. deSwart, Rev. Mod. Phys. 35, 916 (1963), Sec. 14 and Sec. 4B of the current article.
