Transition to turbulence in a crossed-field gap

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The transition from laminar to turbulent behavior of the electron sheath in a cross-field gap is examined for the regime \( B > B_H \), where \( B \) is the external magnetic field and \( B_H \) is the Hull cutoff value. An analytic expression is presented for the critical emitted current beyond which laminar solutions cease to exist. A one-dimensional particle code is used to corroborate the analytic theory. This code shows several interesting properties when the emitted current exceeds the critical value. Chief among them is the presence of a turbulent microsheath near the cathode surface. The electrostatic potential in the gap’s vacuum region is found to oscillate at a frequency that is quite insensitive to the emitted current and to the electrons’ emission velocity. © 1994 American Institute of Physics.

When a sufficiently strong transverse magnetic field \( B \) is imposed across an anode–cathode gap, electrons released from the cathode will not be able to reach the anode. Under the steady-state condition, that critical magnetic field is the Hull cutoff value \( B_H = (2 \frac{mV}{eD^2})^{1/2} \), where \( D \) is the gap spacing, \( V \) is the gap voltage, \( e \) is the electron charge, and \( m \) is the electron mass. The electrons are assumed to be emitted with zero velocity. It is important to note that \( B_H \) is independent of the emitted current density, \( J \).

In this Letter, we examine the regime \( B > B_H \). Specifically, we present an analytic expression that gives the critical emission current density, \( J_c \), above which steady state solutions cease to exist. We employ a particle-in-cell (PIC) code to examine the dynamical behavior of the gap, both below and above this critical current.

It is anticipated, on physical grounds, that such a critical current exists. If the emission current is vanishingly small, electrons are expected to follow the familiar single particle orbits in the external electric and magnetic fields, which are uniform. A collection of such particles represents a time-independent solution. If, on the other hand, electrons are released in great quantities, steady-state solutions are not expected to exist, as seen from the familiar laminar solutions established when the electrons are emitted normal to the cathode.

For zero injection velocity, therefore, the steady-state solution fails to exist when the emitted current is sufficiently high to render the surface electric field equal to zero. This critical current, for this \( B > B_H \) case, is simply determined by \( B \). As the emitted current is raised, the initially accelerating electric field right in front of the cathode is reduced. For zero injection velocity, therefore, the steady-state solution fails to exist when the emitted current is sufficiently high to render the surface electric field equal to zero. Thus the critical current, for this \( B > B_H \) case, is simply determined from the space-charge-limited condition when the electrons are released with zero velocity.

Consider a time-independent, one-dimensional planar, nonrelativistic model. In the Cartesian coordinates, the cathode is located at \( x = 0 \), and the anode at \( x = D \), held at potential \( V \) with respect to the cathode. The external magnetic field is \( \frac{\partial B}{\partial x} \). Let \( \varphi(x) \) be the self-consistent electrostatic potential, and \( u(x) \) be the (non-negative) velocity component of the cold electrons in the \( x \) direction. Using conservation of energy, \( e \varphi(x) = \frac{m}{2}(u^2 + \Omega^2 x^2) \), we may write the Poisson equation

\[
\frac{d^2 \varphi}{dx^2} = \frac{en}{\varepsilon_0} = \frac{2J}{\varepsilon_0 e_0 u}
\]

in the Llewellyn form (see e.g., Birdsell and Bridges):

\[
\frac{d^2 u}{dt^2} + \Omega^2 u = \frac{2eJ}{me_0},
\]
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Laminar B/B,
FIG. 1. The critical current density (in units of the Child-Langmuir value) above which steady state solutions cease to exist, as a function of the magnetic field $B$ (in units of the Hull cutoff value), for zero electron emission velocity. The points $C_0$, $C_1$, ..., $C_8$ mark the cases simulated.

In Eq. (1), we have used the continuity equation, $n u = \text{constant}$, as well as the fact that the electron density, $n$, is due to the departing electrons and the returning electrons, thus giving rise to a factor of 2 in the last term of Eqs. (1) and (2). The emitted current density, $J$, is a constant.

In terms of the dimensional variables, $\tilde{x} = x/D$, $\tilde{t} = t/\omega$, $\tilde{J} = J J_{CL} \bar{J}/D^2$, $\tilde{\phi} = \phi \bar{J}/D^2$, $\tilde{V} = V \bar{J}/D^2$, $\tilde{u} = u/D$, the differential equation (2) may be integrated to yield $\tilde{u}(\tilde{t}) = 2 [1 - \cos(\tilde{t})]$, under the condition that the electron is initially at rest and nonaccelerated (space-charge-limited condition). This solution may be integrated again to yield $T(\tilde{t}) = 2 [1 - \sin(\tilde{t})]$. From these simple solutions, we see that an electron begins to be turned back when $\tilde{x} = 2 \pi$, at which $\tilde{x} = \tilde{x}_T = 4 \pi \tilde{J}$, and $\tilde{u} = 0$. Note that $\tilde{x}_T$ represents the maximum excursion of electrons (i.e., "hub height") when the critical current is reached. It is easy to show that, at $\tilde{x} = \tilde{x}_T$, the normalized electric potential is $\tilde{\phi}_T = x^2/2 = 8 \pi^2 \tilde{J}^2$, and the normalized electric field is $\tilde{E}_T = 2 \tilde{J}^2 = 4 \pi \tilde{J}$.

The last statement allows us to express the anode voltage as the sum of $\phi_T$ and the potential drop in the vacuum region, $\tilde{x}_T < \tilde{x} < 1$: $V = \tilde{\phi}_T - \tilde{E}_T (1 - \tilde{x}_T)$. This in turn yields $V = 4 \pi \tilde{J} - 8 \pi^2 \tilde{J}^2$. The last expression may be easily solved for $\tilde{J}$ in terms of $\tilde{V}$. This gives the critical current $\tilde{J}_C$ as a function of gap voltage $\tilde{V}$. When normalized to the Child-Langmuir limiting current, $\tilde{J}_{CL} = (2/9)(2 \tilde{V})^{1/2}$, this critical current reads

$$\frac{\tilde{J}_C}{\tilde{J}_{CL}} = \left( \frac{9}{8 \pi} \right) \left( \frac{B}{B_H} \right)^{3/2} \left[ 1 - \sqrt{1 - \left( \frac{B_H}{B} \right)^2} \right],$$

where we have used $\tilde{V} - (B_H/B)^2/2$.

The expression (3) is valid for $B > B_H$. It is shown in Fig. 1, which, for completeness, also includes the regime $B < B_H$. The latter regime was recently reexamined in considerable detail. Thus Fig. 1 provides the critical value of the emitted current, above which time-independent solutions cease to exist, for general values of magnetic field. The discontinuity in $\tilde{J}_C$ at $B = B_H$ reflects a different state of the solutions, a fact observed by Pollack, interpreted as the limiting current, and reaffirmed in particle simulations by Verboncoeur and Birdsall. For the case $B > B_H$, it may be shown that as $J \rightarrow J_C$, the maximum electron excursion in $x$, $x_T$, is simply the Brillouin hub height,$^3$ $D[1 - \sqrt{1 - (B_H/B)^2}]$, which is always less than $D(B_H/B)^2$, the latter being the maximum electron excursion when the space charge is negligible.

We have extensively studied the regime $B > B_H$ using a PIC code, Plasma Device Planar 1 Dimensional$^2$ (PDP1), as the injected current is increased (case $C_0$, ..., $C_8$ in Fig. 1). In the simulations, Figs. 2-4, we fixed $D = 0.00216 \text{ m}$, $B = 0.27 \text{ mT}$, cathode area $A = 0.001492 \text{ m}^2$, the cathode was held at $V_0 = -12,000 \text{ V}$, while the anode was grounded. Thus $V = 12,000 \text{ V}$, $B_H = 0.171 \text{ mT}$, $B_B = 1.579$, $J_C = 2.1 \times 10^5 \text{ A/m}^2$, and $J = A J_C = 313 \text{ A}$. The electrons were injected as a cold beam normal to the cathode with, unless otherwise stated, injection energy of 1/2 eV. After several attempts, we
failed to generalize Eq. (3) to include such a nonzero injection energy.  

The transition from laminar to turbulent behavior is clearly shown from the runs below transition of case C2 (I = A J = 298 amps) and above transition, case C3 (I = A J = 343 A). For case C2, the potential at midway between the anode–cathode gap, \( \phi_{\text{mid}}(t) \), and the cathode surface charge density, \( \sigma_{e}(t) \), remain asymptotically constant [Fig. 2(a)], whereas those for case C3 break into oscillations for time \( t \approx 4 \text{ ns} \) [Fig. 2(b)]. The phase-space plot and density profile for case C2 [Figs. 3(a) and 3(b)] are dictated by single particle motion. The trajectory of one electron is repeated by all others, and this property is shared by low injection current cases, C0 and C1 in Fig. 1. The corresponding figure [Fig. 3(c)] for case C3 shows turbulent behavior: the phase space is randomized and the \( x \) component of the particle velocity is substantially reduced. The space-charge density profile [Fig. 3(d)] is almost flattened, extending from the cathode to roughly the Brillouin hub height. This is true for all above-transition cases C3, C4, ..., C8 (Fig. 1). The surface charge on the cathode [Fig. 2(b)] is \textit{positive}, i.e., a potential minimum is always formed in front of the cathode, when turbulent behaviors emerge from the numerical simulation. The electric field on the cathode is positive, having a mean value on the order of 4 kV/cm. This latter value is shared by all above-transition cases C3, C4, ..., C8. The depth of this potential minimum is on the order of the injection energy that is given to the electrons in the code. Thus, a microsheath is always formed right in front of the cathode for low injection velocity when the injected current exceeds the critical value (Fig. 1). This sheath oscillates at a frequency that varies according to the emitted current and to the emission velocity (Fig. 4). No electrons reach the anode in any of our runs for \( B = 1.597 B_{H} \). In fact, no electrons reach the midpoint, \( x = D/2 \), in the gap. The potential at this midpoint oscillates at a frequency that is quite independent of the injected current (Fig. 4), of the initial energy of the electron (up to 200 eV), and of the grid size and number of computer particles used in the simulations. Neither the microsheath oscillation frequency, nor the oscillation frequency in the midpotential corresponds to the cyclotron frequency, the plasma frequency, nor to the upper hybrid frequency. This characteristic is shared by all cases C4, C5, ..., C8 in Fig. 1. The physical origin of the oscillations remains to be examined.

In summary, this study seems to have added substance to the notion that a necessary condition for quiescent behavior in a crossed-field gap is that electron emission be limited. The criterion is given by Eq. (3) for \( B > B_{H} \), and is confirmed by particle simulation.

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1. A. W. Hull, Phys. Rev. 18, 31 (1921).
2. PDPI (Plasma Device Planar 1 Dimensional), ©1993–93 Regents of the University of California, Plasma Theory and Simulation Group, Berkeley, California. Available from Software Distribution Office of the ILP, 205 Cory Hall, Berkeley, California 94720, software@eecs.Berkeley.EDU. This is a one-dimensional electrostatic code that includes all three components of velocity.
9. Diocotron instabilities are ruled out in this paper since there is no variation in the fields in any direction parallel to the cathode surface. Thus our findings do not contradict the experiments by T. J. Orzechowski and G. Bekett, Phys. Fluids 22, 978 (1979).