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FINAL REPORT  
MODIFIED ARTICULATED VEHICLE SIMULATION

P. O. No. NHTSA-6-5547

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16. Abstract <p>Prior to the work reported herein, a simplified interactive simulation (called the "TBS simulation") for predicting the braking and steering responses of commercial vehicles was developed at the Highway Safety Research Institute of The University of Michigan under sponsorship of the Motor Vehicle Manufacturers Association. The TBS simulation was based on a doctoral dissertation by Leucht entitled "Directional Dynamics of the Tractor-Semi-Trailer Vehicle," The University of Michigan, 1970.</p> <p>This report gives the details of the optional addition of the Breeze jackknife restraint device to the TBS simulation.</p>					
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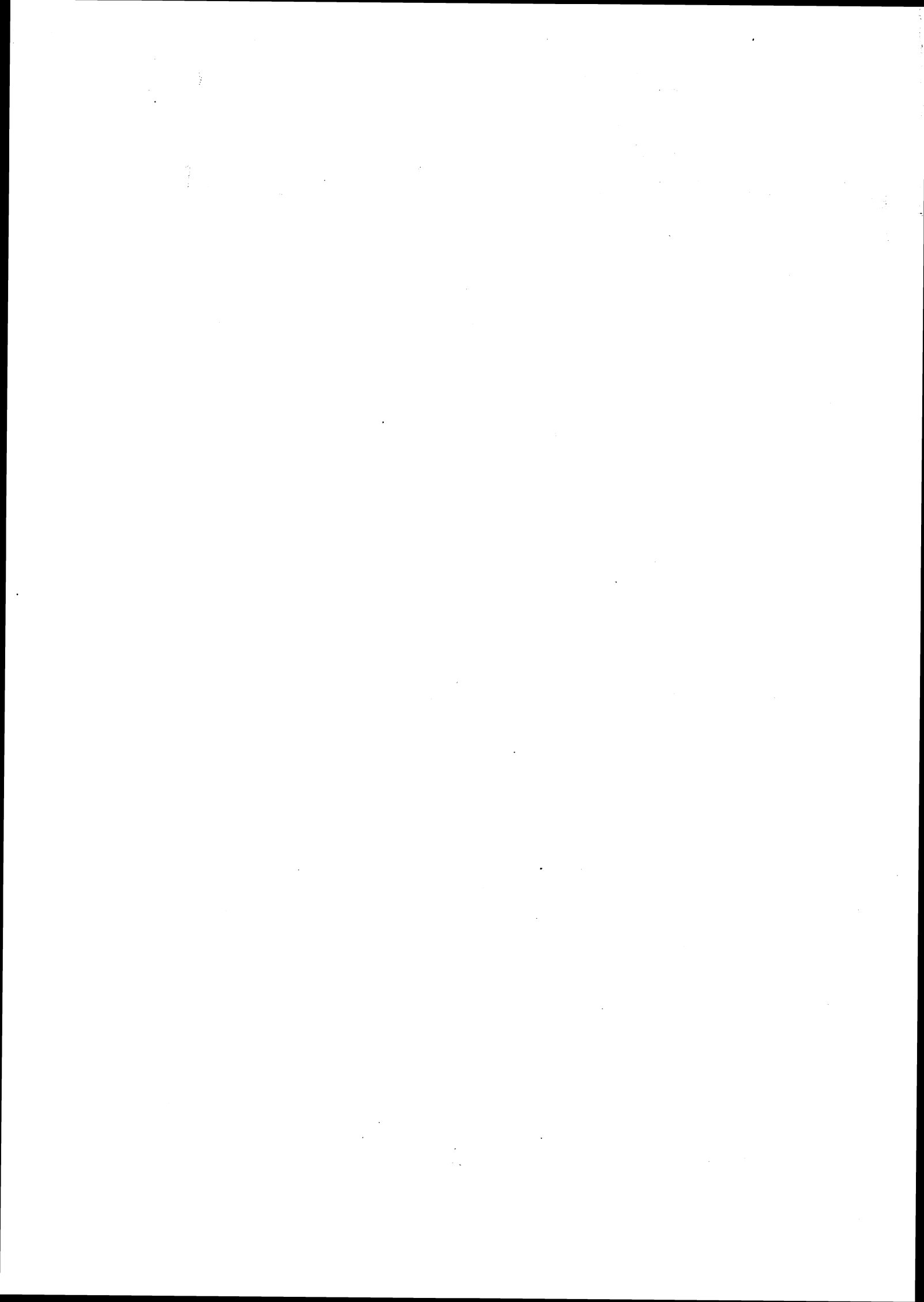
## TABLE OF CONTENTS

1. INTRODUCTION. . . . .	1
2. AN OVERVIEW OF THE ANALYTICAL PROBLEM . . . . .	3
3. THE KINEMATICS OF THE BREEZE JACKKNIFE RESTRAINT. . . . .	9
4. SAMPLE RUNS . . . . .	15
5. REFERENCES. . . . .	23
APPENDIX. . . . .	25

## 1.0 INTRODUCTION

This is a final report on a research task entitled "Modified Articulated Vehicle Simulation," conducted by the Highway Safety Research Institute of The University of Michigan. This study was supported by the National Highway Traffic Safety Administration of the U. S. Department of Transportation.

The goal of this research task was to add to an existing simulation the capability to simulate the Breeze jackknife restraint device. This report documents the addition as follows. First, an overview of the analytical problem is presented, followed by an explanation of the kinematics and some details of the new software. The kinematics section is closely linked to the software by relating equations in the text to line numbers in the computer program. Next, some sample computer runs introduce the input/output (I/O) of the modified simulation. A flow chart and a list of the modified program is given in the appendix.



## 2.0 AN OVERVIEW OF THE ANALYTICAL PROBLEM

It should be emphasized that prior to the work reported herein, a simplified, interactive simulation (called the "TBS Simulation") for predicting the braking and steering responses of commercial vehicles was developed at the Highway Safety Research Institute of The University of Michigan under the sponsorship of the Motor Vehicle Manufacturers Association [2]. The TBS simulation was based on a doctoral dissertation by Leucht entitled "Directional Dynamics of the Tractor-Semitrailer Vehicle," The University of Michigan, 1970 [1].

This report gives the details of the optional addition of the Breeze jackknife restraint device to the TBS simulation. It will be assumed throughout that the reader is conversant with References 1 and 2.

A schematic diagram of the Breeze device is presented in Figure 1. The "brake drum" at the lower right of the figure is mounted on the trailer. As the articulation angle increases, the cable must be played out. The jackknife restraint is applied as the air applied to the trailer brakes is also applied to the brake drum, retarding increased articulation.

One can follow through the equations of Leucht and show that tension in the cables of the Breeze device has the following effects:

1. An equal and opposite additional force at the hitch
2. Load transfer for both the tractor and trailer.

The cable tension and the force at the hitch, of course, form equal and opposite couples on the tractor and the trailer. The couples have components in the body roll, pitch, and yaw directions. The sense of the vertical, or yaw, component of the couples is to reduce the articulation angle.

The addition of the Breeze device to the software has been implemented in the following way.

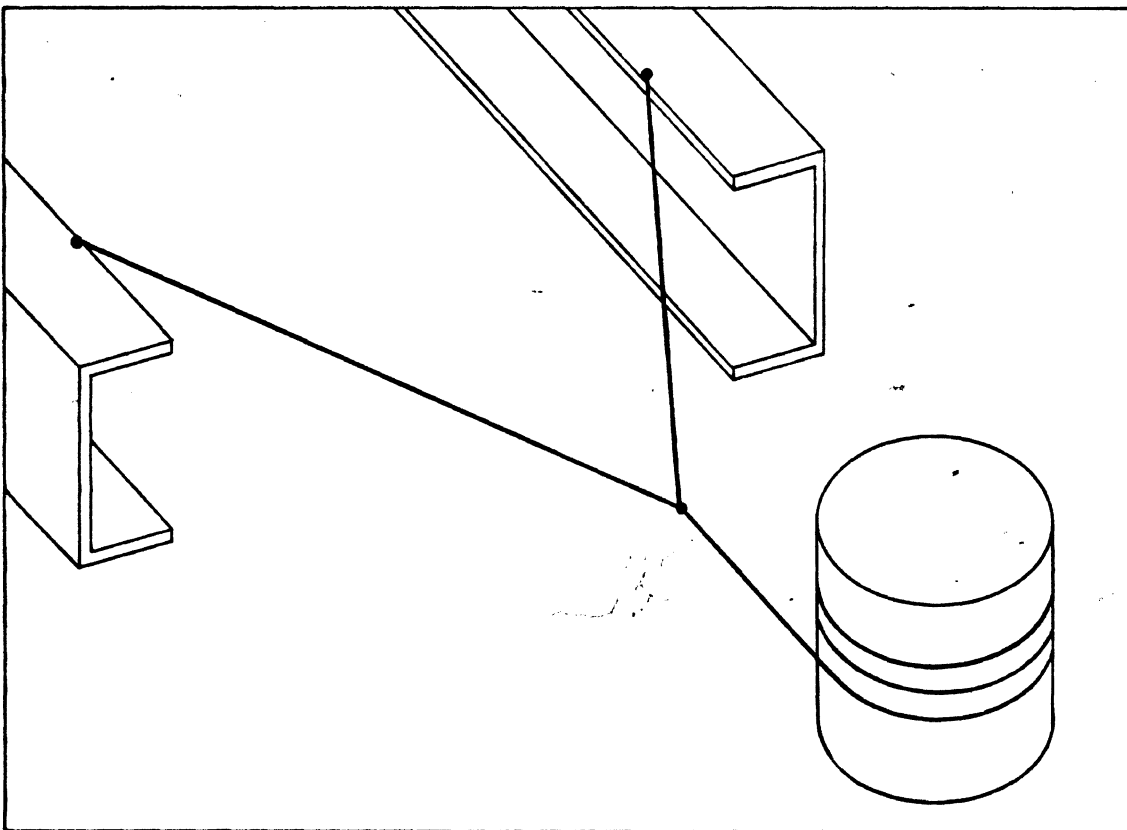


Figure 1. A schematic diagram of the Breeze device.

1. The tension in the cable is assumed to be a multiple of the desired\* trailer brake force.
2. This tension is then used to compute the vertical component of the couple and the longitudinal and lateral load transfers of the tractor and the trailer.
3. The vertical component of the couple appears in the equations of motion.

The additional software has been designed for inclusion into the TBS simulation with minimal changes to the original program. This situation leads us to review the TBS simulation briefly before proceeding into the Breeze device.

## 2.1 The TBS Simulation

The equations of motion of the TBS articulated vehicle program are dynamically coupled in the following way:

$$(A_{(t)})\ddot{\bar{x}} = F_{(t)} \quad (1)$$

where the four by four  $A_{(t)}$  matrix and  $F_{(t)}$  can be computed at any time,  $t$ . The acceleration vector  $\ddot{\bar{x}}$  is

$$\ddot{\bar{x}} = \begin{bmatrix} \ddot{u} \\ \ddot{v} \\ \ddot{r} \\ \ddot{\Gamma} \end{bmatrix} \quad (2)$$

where  $\dot{u}$  is the longitudinal acceleration,  $\dot{v}$  is the lateral acceleration,  $\dot{r}$  is the rate of change of yaw rate, and  $\ddot{\Gamma}$  is the second time derivative of the articulation angle. The interested reader can find the equations of motion in [1].

---

\*Desired force does not equal the actual force if a trailer wheel locks.



The method of integration of equations of motion is relatively\* straightforward. At time,  $t_0$ , the  $A_{(t_0)}$  and  $F_{(t_0)}$  are computed and Equation (1) is solved for the  $\ddot{X}$ , which are then integrated across  $\Delta t$ . The solutions to the integration facilitate the calculation of  $A_{(t_0+\Delta t)}$  and  $F_{(t_0+\Delta t)}$  for use in further integration.

The addition of the Breeze hitch to the formulation causes two changes in Equation (1), namely, the  $\dot{r}$  and  $\ddot{r}$  equations have a Breeze moment term appearing on the right-hand side. Thus we have, in the notation of the computer program,

$$\begin{aligned}
 A_1 \dot{u} + A_5 \dot{v} + A_9 \dot{r} + A_{13} \ddot{r} &= f1(t) \\
 A_2 \dot{u} + A_6 \dot{v} + A_{10} \dot{r} + A_{14} \ddot{r} &= f2(t) \\
 A_3 \dot{u} + A_7 \dot{v} + A_{11} \dot{r} + A_{15} \ddot{r} &= f3(t) + BT1 \cdot TBREEZE \\
 A_4 \dot{u} + A_8 \dot{v} + A_{12} \dot{r} + A_{16} \ddot{r} &= f4(t) - BT1 \cdot TBREEZE
 \end{aligned}
 \tag{3}$$

where TBREEZE is the tension in the cable, and BT1 is a function of vehicle geometry.

(The A's are given in Fortran line numbers 635 through 715 and the right-hand sides are given in Fortran line numbers 2235 to 2310. See the listing in the appendix to this report.)

Equation (3) is operative as long as the system is "unlocked," that is, as long as the cable is not holding the articulation angle constant. In that case, TBREEZE is a straightforward multiple of the desired trailer brake force. If the cable does hold  $r$  fixed, however, then two conditions must follow:

$$1) \quad \ddot{r} = 0$$

---

\*One significant complication is the quasi-static load transfer, which makes  $F_{(t)}$  a function of  $X$ , a situation which is handled by using "old"  $\ddot{X}(t)$  values to get the "new"  $F_{(t)}$ . We will ignore these matters here because they are not material to the present discussion.

- 2) TBREEZE, although limited by some maximum value, is unknown.

Since the "lock value" of the cable tension TBREEZE is limited but unknown, it's not obvious at the start of any  $\Delta t$  wide interval if the tension will be able to hold the articulation angle frozen. To check for lock, we first look for small  $\dot{r}$ . (Fortran line number 1455 will start the lock check any time  $|\dot{r}|$  is less than .03 radians/sec.) If lock is a possibility, then the TBREEZE necessary to provide lock is found. If this is less than the maximum allowed by the Breeze mechanism,  $\ddot{r}$  and  $\dot{r}$  are set to zero. If the tension necessary for lockup is higher than the maximum allowed by the Breeze mechanism, then TBREEZE is reset to a multiple of the desired trailer brake force and Equation (3) is used. (This logic is handled at Fortran line number 2515.)

To solve for the TBREEZE value necessary for articulation lock,

$$A_{13} = 0 \quad (4a)$$

$$A_{14} = 0 \quad (4b)$$

$$A_{15} = -BT1 \quad (4c)$$

$$A_{16} = BT1 \quad (4d)$$

and the right-hand side of Equation (3) becomes

$$f1(t)$$

$$f2(t)$$

$$f3(t)$$

$$f4(t)$$

The solution of this modified form of Equation (3) now gives  $\dot{u}$ ,  $\dot{v}$ ,  $\dot{r}$ , and TBREEZE.

In the next section, the kinematics of the Breeze mechanism are presented, and the moment around the hitch is derived as a function of the cable tension  $T_{BREEZE}$  for use in Equations (3) and (4).

### 3.0 THE KINEMATICS OF THE BREEZE JACKKNIFE RESTRAINT

The derivation of the equations of the Breeze jackknife restraint make use of the nomenclature shown in Figure 2.

From Figure 2, it is apparent that the articulation angle is related to the angle between the Breeze cable and the frame rails by the following relationship:

$$\begin{aligned} \text{when} \quad \phi &= \frac{d}{e} \Gamma & (5) \\ |\phi| &< \theta \end{aligned}$$

(This corresponds to Fortran line number 1245.)

If  $|\phi| > \theta$ , the cables take on the configuration shown in Figure 3. In this case, the vector along the cable from the frame rail is given by

$$\bar{r} = d(-\sin \Gamma i - \cos \Gamma j) - B5i + A5j \quad (6)$$

The tangent of  $\phi$  is the  $i$  component of  $\bar{r}$  divided by the  $j$  component of  $\bar{r}$ , viz.:

$$\tan \phi = \frac{d \sin \Gamma + B5}{d \cos \Gamma - A5} \quad (7)$$

(This corresponds to Fortran line number 1290.)

We also need to compute the angle between the cable tension and the trailer. Figure 3 indicates that this angle is  $\phi - \Gamma$ .

Now we wish to compute the vertical (i.e., the  $z$ ) component of the moment around the hitch produced by the tension in the cables with the aid of the free-body diagrams given in Figure 4. On noting that the vector moment is given by

$$\bar{M} = \bar{r} \times \bar{T} \quad (8)$$

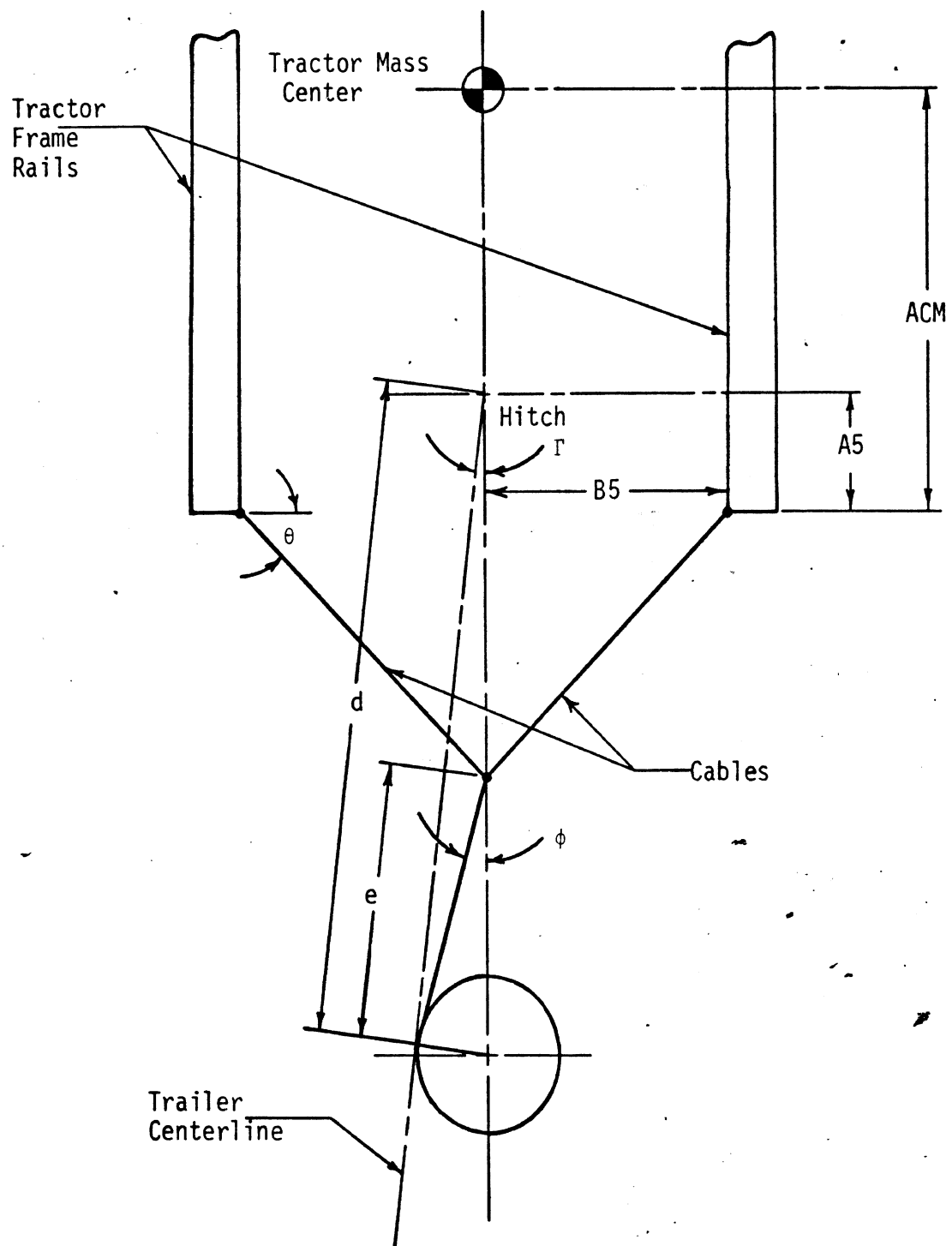


Figure 2. Schematic diagram, Breeze hitch.

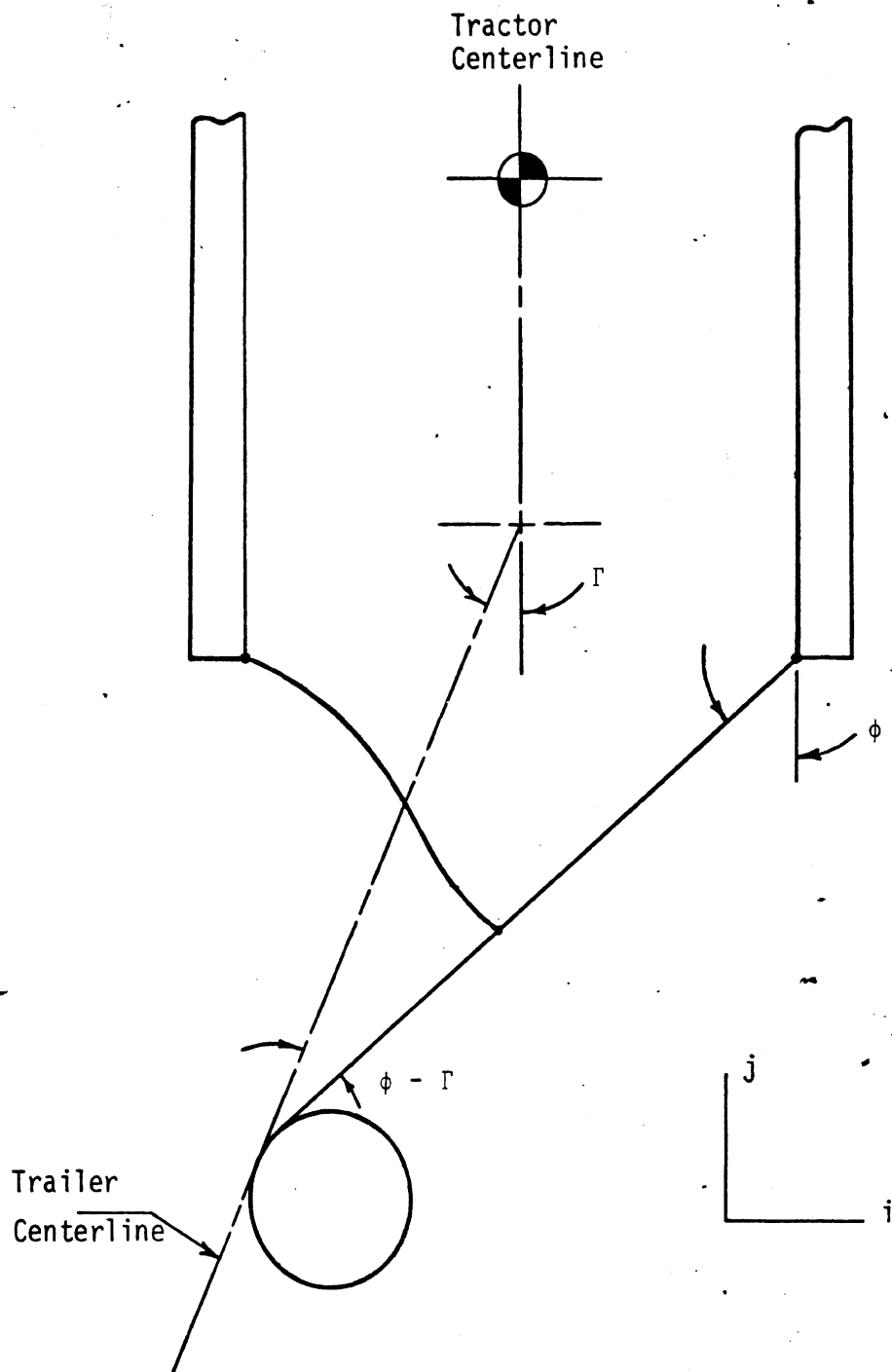


Figure 3. Cable configuration for  $|\phi| > \theta$

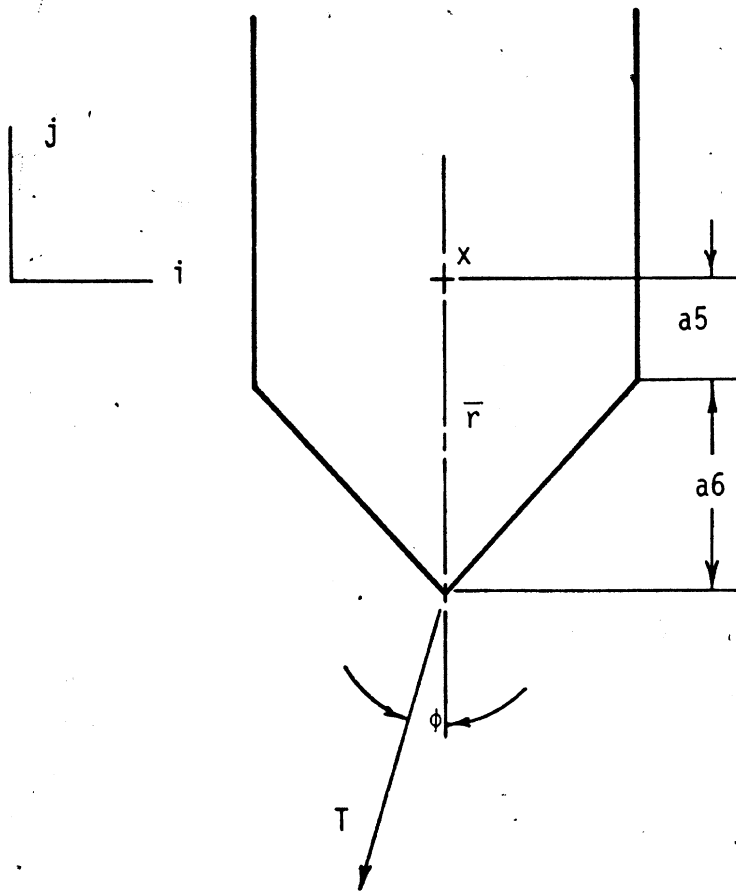


Figure 4a. Tractor free-body diagram,  $|\phi| < \theta$

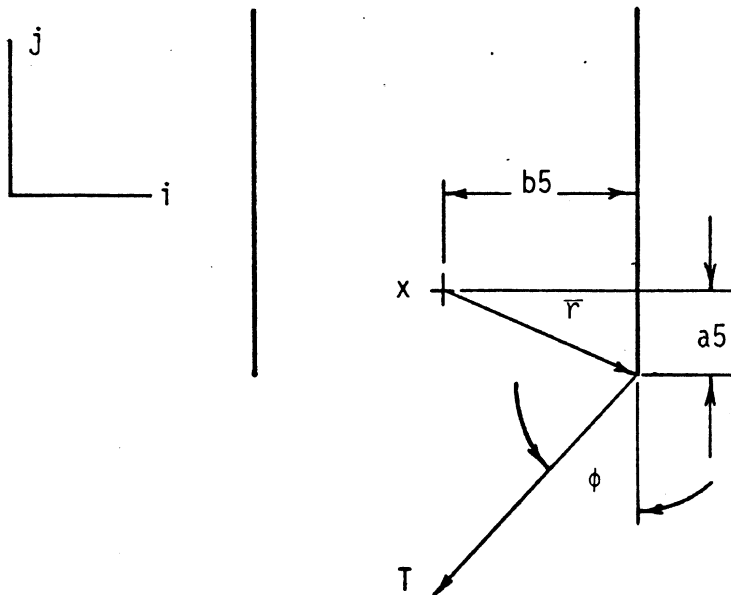


Figure 4b. Tractor free-body diagram,  $|\phi| > \theta$

we find that for  $|\phi| < \theta$  (see Figure 4a)

$$\bar{M} = [(A5 + A6) \sin \phi] \cdot TBREEZ \cdot k \quad (9)$$

where  $k$  is the unit vector in the vertical direction. (The term in brackets is computed in Fortran line number 1425.)

For  $|\phi| > \theta$ , Eq. (8) yields (see Figure 4b)

$$\bar{M} = [A5 \sin \phi + B5 \cos \phi \frac{\phi}{|\phi|}] TBREEZ \cdot k \quad (10)$$

where the absolute value results from the necessity to flip sign on the  $B5 \cos \phi$  term for  $\phi < 0$ . Note for negative  $\phi$ , the other frame rail attaches to the cable and the moment arm becomes  $-B5 \cos \phi$ . (The term in brackets is computed in Fortran line number 1335.)

Finally, we need certain pitch and roll moments to compute longitudinal and lateral load transfer. Noting that the cable is horizontal at height  $ZBREEZ$ , the tractor roll moment about any point in the ground plane due to the tension in the cable is  $-ZBREEZ \cdot TBREEZ \cdot \sin \phi$ . (This is computed in Fortran line number 1700.) The tractor pitch moment about any point in the ground plane is  $ZBREEZ \cdot TBREEZ \cdot \cos \phi$ . (This is computed in Fortran line number 1845.)

The equations of Reference 1 require that the trailer roll moment be calculated about the hitch, and pitch moments about the ground plane. The trailer roll moment about the hitch is  $-TBREEZ \cdot \sin(\phi - \Gamma) \cdot (Z0 - ZBREEZ)$ . (This is computed in Fortran line number 1755.) The trailer pitch moment about the ground plane is  $TZBREEZ \cdot \cos(\phi - \Gamma) \cdot ZBREEZ$ . (This is computed in Fortran line number 1835.)



~~by start~~  
plank

14

## 4.0 SAMPLE RUNS

This section presents an echo of the input to the TBS program, followed by three sample runs. In each sample run, a step 2° steer angle is applied with the vehicle coasting at 45 mph on a high- $\mu$  surface. Then at .5 second, 500 pounds brake force is "demanded" at each front wheel, and 5000 pounds brake force is "demanded" at each of the tractor rear wheels and each of the trailer wheels.

Run 1 proceeds without antilock or Breeze restraint, and a jackknife results.

Run 2 proceeds with antilock operational on all tractor wheels, preventing the jackknife.

Run 3 proceeds using the Breeze device. Again, jackknife is prevented. Note that the input variables to run 3 use the nomenclature of this report. HITCHT is the gain of the Breeze device indicating that, for this run, the allowable cable tension is twice the desired trailer brake force for one trailer wheel.

YOU ARE ABOUT TO RUN THE HSRI SIMULATION PROGRAM FOR  
 A TRACTOR-TRAILER WITH BREEZE HITCH IN THE HORIZONTAL PLANE  
 PRINT PROGRAM EXPLANATIONS? (Y OR N): N  
 LIST INPUT PARAMETERS? Y  
 READ DATA FROM FILE? Y  
 ENTER INPUT DEVICE NUMBER IN I2 FORMAT: 07

◆◆◆ BEGIN INPUT ◆◆◆

41 ENTER ANTILOCK CODE FOR TRACTOR FRONT, TRACTOR REAR,  
 AND TRAILER AXLES.  
 0=NO ANTILOCK, 1=INDEPENDENT ANTILOCK, FORMAT=3I1.

000

42 ENTER CODE FOR TANDEM AXLES TRACTOR REAR, DUAL TIRES  
 TRACTOR REAR, TANDEM AXLES TRAILER, DUAL TIRES TRAILER  
 0=NO, 1=YES, FORMAT=4I1.

1100

INPUT PARAMETER TABLE

NO.	SYMBOL	DESCRIPTION	INITIAL VALUE
01	GVW1	WT. OF TRACTOR (LBS)	14970.00
02	GVW2	WT. OF TRAILER (LBS)	11160.00
03	I2Z	TRACTOR MOM. OF INERTIA (IN-LB-SEC <sup>2</sup> )	241636.00
04	ITZZ	TRAILER MOM. OF INERTIA (IN-LB-SEC <sup>2</sup> )	736983.00
05	AA	DIST. BETWEEN TRACTOR TANDEM AXLES (IN)	54.40
07	A1	DIST. FROM TRACTOR CG TO FRONT AXLE (IN)	63.90
08	A2	DIST. FROM TRACTOR CG TO REAR AXLE (IN)	78.10
09	A3	DIST. FROM TRAILER CG TO FIFTH WHL (IN)	261.20
10	A4	DIST. FROM TRAILER CG TO AXLE (IN)	104.80
11	BB	DIST. FROM TRACTOR REAR SUSPENSION TO FIFTH WHL (IN). FIFTH WHL LOCATED AFT OF SUSPENSION IS NEGATIVE.	0.0
12	TRA1	HALF LAT. DIST. BETWEEN CENTERS OF TIRE CONTACT ON TRACTOR FRONT AXLE (IN)	40.00
13	TRA2	HALF LAT. DIST. BETWEEN CENTERS OF TIRE CONTACT ON TRACTOR REAR AXLES (IN)	35.00
14	TRA3	HALF LAT. DIST. BETWEEN CENTERS OF TIRE CONTACT ON TRAILER AXLES (IN)	36.00
15	Z0	HEIGHT OF FIFTH WHL ABOVE GROUND (IN)	40.00
16	Z1	HEIGHT OF TRACTOR CG ABOVE GROUND (IN)	39.90
17	Z2	HEIGHT OF TRAILER CG ABOVE GROUND (IN)	55.50
18	MUS	FIFTH WHEEL FRICTION COEFFICIENT	0.05
19	RAD5	EQUIVALENT RADIUS OF FIFTH WHEEL (IN)	19.00
20	GAM1	PORTION OF TOTAL LAT. LOAD TRANSFER ON FRONT AXLE OF TRACTOR	0.15
21	GAM3	TRACTOR TANDEM AXLE LOAD X-FER COEF.	0.0
23	VEL	INITIAL VELOCITY: U-DIRECTION (MPH) (FPS)	45.00 66.00
24	TIMF	MAX. SIMULATION TIME FOR THIS RUN (SEC)	4.00
25	IQUIT	MAX. ARTICULATION ANGLE ALLOWED (DEG)	30.00
	CALF	CORNERING STIFFNESS OF TIRES (LBS/DEG)	
29		CALF (1) =	467.00
30		CALF (3) =	200.00
31		CALF (7) =	400.00
	MUP	PEAK TIRE-ROAD FRICTION COEFFICIENT	
32		MUP (1) =	0.95
	MUS	SLIDING TIRE-ROAD FRICTION COEF.	
35		MUS (1) =	0.90
	SP	SLIP CORRESPONDING TO PEAK MU	
38		SP (1) =	0.15

BRAKE FORCE TABLE  
NUMBER OF LINES: 3

TIME (SEC)	DESIRED FORCES:					
	FSX(1)	FSX(2)	FSX(3)	FSX(4)	FSX(7)	FSX(8)
0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.5000	0.0	0.0	0.0	0.0	0.0	0.0
0.6000	500.00	500.00	5000.00	5000.00	5000.00	5000.00

STEER TABLE  
NUMBER OF LINES: 2

TIME (SEC)	STEER ANGLE (DEG)
0.0	0.0
0.1000	2.00

CHANGE PARAMETERS? N  
BREEZE HITCH? N  
CHANGE BRAKE FORCE TABLE? N  
CHANGE STEER TABLE? N  
ECHO STATIC LOADS? Y  
STATIC LOADS (LBS)  
TRACTOR FRONT AXLE: 8233.49  
TRACTOR LEADING TANDEM: 4966.02  
TRAILING TANDEM: 4966.02  
TRAILER AXLE: 7964.46

ENTER INITIAL ARTIC. ANGLE: 0.  
WILL ARTIC. ANGLE BE VARIED? Y  
ANY DATA CHANGES NOW? N

◆◆◆ END OF INPUT ◆◆◆

WOULD YOU LIKE TO ENTER NEW SLIP POLL-OFF TABLE? N  
DO YOU WANT A LIST OF OUTPUT VARIABLES? Y

\*\*\* POSITION VARIABLES \*\*\*

1 X0-COORD  
2 Y0-COORD  
3 PSI  
4 GAMMA

\*\*\* VELOCITY VARIABLES \*\*\*

5 U-VEL  
6 V-VEL  
7 PSIDOT  
8 GAMMADOT

\*\*\*

9 TURN RAD  
10 SIDESLIP

\*\*\* TIRE SLIP ANGLES \*\*\*

11 ALFA 1+2  
12 ALFA 3+4  
13 ALFA 5+6  
14 ALFA 7+8  
15 ALFA9+10

\*\*\* ACCELERATION VARIABLES \*\*\*

16 U-DOT  
17 V-DOT  
18 PSI-DDOT  
19 GAM-DDOT  
20 LONG ACC  
21 LAT. ACC

\*\*\* TIRE-ROAD INTERFACE FORCES \*\*\*

\*\*\* BRAKE FORCES: FX(I), SIDE FORCES FY(I) \*\*\*

22 FX(1)  
23 FX(2)  
24 FX(3)  
25 FX(4)  
26 FX(5)  
27 FX(6)  
28 FX(7)  
29 FX(8)  
30 FX(9)  
31 FX(10)  
32 FY(1)  
33 FY(2)  
34 FY(3)  
35 FY(4)  
36 FY(5)  
37 FY(6)  
38 FY(7)  
39 FY(8)  
40 FY(9)  
41 FY(10)

◆◆◆ LOAD TRANSFERS, LONG. DFX(I),LAT. DFY(I) ◆◆◆

42	DFX(1)
43	DFX(2)
44	DFX(3)
45	DFX(4)
46	DFX(5)
47	DFX(6)
48	DFX(7)
49	DFX(8)
50	DFX(9)
51	DFX(10)
52	DFY(1)
53	DFY(2)
54	DFY(3)
55	DFY(4)
56	DFY(5)
57	DFY(6)
58	DFY(7)
59	DFY(8)
60	DFY(9)
61	DFY(10)

◆◆◆ INSTANTANEOUS LOAD FORCES ◆◆◆

62	FZ(1)
63	FZ(2)
64	FZ(3)
65	FZ(4)
66	FZ(5)
67	FZ(6)
68	FZ(7)
69	FZ(8)
70	FZ(9)
71	FZ(10)

◆◆◆ PROGRAMMED BRAKE FORCES ◆◆◆

72	FSX(1)
73	FSX(2)
74	FSX(3)
75	FSX(4)
76	FSX(5)
77	FSX(6)
78	FSX(7)
79	FSX(8)
80	FSX(9)
81	FSX(10)

◆◆◆ HITCH FORCES ◆◆◆

82	XH
83	YH
84	TBREEZ

RUN #1

PRINT OUTPUT ON FILE? N  
 ENTER TOTAL NUMBER OF OUTPUT VARIABLES (01-06): 06

ENTER NUMBERS OF VARIABLES YOU WANT  
 SEPARATE NUMBERS BY COMMAS-(01,84)  
 04,08,19,20,21,84

ENTER TIME INCREMENT TO BE PRINTED OUT  
 .1

◆◆◆COMPUTATIONS ARE STOPPED◆◆◆  
 ◆◆◆ TIME IS 2.81 SECONDS ◆◆◆  
 ◆◆◆ARTIC. ANGLE IS -31.51 DEGREES ◆◆◆

TIME	GAMMA	GAMMADOT	GAM-DDOT	LONG ACC	LAT. ACC	TBREEZ
0.0	0.0	0.0	0.0	-0.0	0.0	0.0
0.10	-0.04	-1.20	-22.07	-0.07	3.29	0.0
0.22	-0.32	-3.29	-12.70	-0.07	3.35	0.0
0.32	-0.70	-4.20	-5.63	-0.07	3.93	0.0
0.42	-1.14	-4.47	-0.09	-0.07	4.64	0.0
0.50	-1.52	-4.33	3.07	-3.82	5.19	0.0
0.60	-1.97	-4.33	-7.70	-19.34	3.60	0.0
0.71	-2.56	-5.82	-7.85	-19.34	4.31	0.0
0.81	-3.19	-6.64	-8.73	-19.35	5.04	0.0
0.91	-3.90	-7.53	-7.56	-19.37	5.79	0.0
1.01	-4.69	-8.36	-10.78	-19.37	6.69	0.0
1.11	-5.58	-9.36	-4.89	-19.38	7.44	0.0
1.20	-6.45	-10.20	-10.66	-19.37	8.39	0.0
1.30	-7.52	-11.11	-9.34	-19.36	9.32	0.0
1.40	-8.68	-12.00	-8.76	-19.34	10.28	0.0
1.51	-10.05	-12.98	-8.81	-19.31	11.36	0.0
1.61	-11.39	-13.84	-7.55	-19.26	12.29	0.0
1.71	-12.82	-14.62	-8.19	-19.19	13.25	0.0
1.81	-14.32	-15.39	-6.21	-19.11	14.10	0.0
1.91	-15.89	-16.04	-7.01	-19.00	14.96	0.0
2.01	-17.53	-16.67	-4.64	-18.87	15.66	0.0
2.11	-19.22	-17.15	-5.12	-18.71	16.34	0.0
2.21	-20.96	-17.58	-2.84	-18.54	16.82	0.0
2.31	-22.73	-17.84	-2.46	-18.33	17.22	0.0
2.41	-24.52	-17.99	-0.29	-18.13	17.39	0.0
2.51	-26.32	-17.94	1.31	-17.92	17.39	0.0
2.61	-28.10	-17.68	4.00	-17.72	17.11	0.0
2.71	-29.85	-17.12	7.12	-17.55	16.56	0.0
2.81	-31.51	-16.20	11.12	-17.42	15.68	0.0

DO YOU WANT ANY MORE OUTPUT? N  
 STOP? N

RUN #2

CHANGE PARAMETERS? Y

ENTER PARAMETER NUMBER TO BE CHANGED (01-42)

41  
41 ANTILOCK CODE (311): 110

ANTEFF ANTILOCK EFFECTIVENESS COEFFICIENT (LAT.,LONG.)

26 FRONT AXLE: ANTEFF= 0.5,0.0

27 TRACTOR REAR AXLE (OR TANDEM AXLES): ANTEFF= 0.5,0.0

? 0

BREEZE HITCH: N

CHANGE BRAKE FORCE TABLE: N

CHANGE STEEP TABLE: N

ECHO STATIC LOADS: N

ENTER INITIAL ARTIC. ANGLE: 0.

ANY DATA CHANGED NOW? N

\*\*\* END OF INPUT \*\*\*

PRINT OUTPUT ON FILE? N

ENTER TOTAL NUMBER OF OUTPUT VARIABLES (01-06): 06

ENTER NUMBERS OF VARIABLES YOU WANT

SEPARATE NUMBERS BY COMMA: (01,34)

04,08,19,20,21,34

ENTER TIME INCREMENT TO BE PRINTED OUT

.1

TIME	GAMMA	GAMMADOT	GAM-DDOT	LONG ACC	LAT. ACC	TRFEEZ
0.0	0.0	0.0	0.0	-0.0	0.0	0.0
0.10	-0.04	-1.20	-22.07	-0.07	3.29	0.0
0.22	-0.32	-3.29	-12.70	-0.07	3.35	0.0
0.32	-0.70	-4.20	-5.63	-0.07	3.93	0.0
0.42	-1.14	-4.47	-0.09	-0.07	4.64	0.0
0.50	-1.52	-4.33	3.07	-2.92	5.19	0.0
0.60	-1.94	-3.78	11.40	-19.30	4.64	0.0
0.70	-2.36	-2.55	12.39	-19.39	5.14	0.0
0.80	-2.45	-1.28	12.50	-19.30	5.41	0.0
0.90	-2.52	-0.07	11.88	-19.32	5.43	0.0
1.00	-2.47	1.03	3.49	-19.34	5.43	0.0
1.10	-2.32	1.92	9.43	-19.36	5.24	0.0
1.20	-2.08	2.73	4.57	-19.39	5.08	0.0
1.30	-1.79	3.23	3.53	-19.41	4.71	0.0
1.40	-1.43	3.32	0.99	-19.42	4.55	0.0
1.50	-1.03	4.04	1.31	-19.43	4.24	0.0
1.60	-0.62	4.16	0.54	-19.44	3.98	0.0
1.70	-0.21	4.18	-0.09	-19.44	3.75	0.0
1.80	0.21	4.14	-1.09	-19.43	3.56	0.0
1.90	0.62	4.02	-1.17	-19.42	3.36	0.0
2.00	1.02	3.88	-1.99	-19.40	3.19	0.0
2.10	1.39	3.68	-1.90	-19.39	3.00	0.0
2.20	1.75	3.47	-2.56	-19.38	2.82	0.0
2.30	2.09	3.22	-2.54	-19.38	2.62	0.0
2.40	2.39	2.95	-3.01	-19.31	2.42	0.0
2.50	2.67	2.65	-3.10	-19.28	2.20	0.0
2.60	2.92	2.33	-3.38	-19.25	1.93	0.0
2.70	3.14	1.99	-3.49	-19.23	1.75	0.0
2.80	3.32	1.64	-3.56	-19.20	1.51	0.0
2.90	3.47	1.30	-3.49	-19.18	1.27	0.0
3.00	3.58	0.96	-3.39	-19.17	1.03	0.0
3.10	3.66	0.63	-3.23	-19.16	0.80	0.0
3.20	3.71	0.33	-2.99	-19.15	0.58	0.0
3.30	3.73	0.05	-2.62	-19.15	0.37	0.0
3.40	3.72	-0.19	-2.14	-19.15	0.18	0.0
3.50	3.69	-0.37	-1.51	-19.16	0.01	0.0
3.60	3.65	-0.48	-0.73	-19.17	-0.13	0.0
3.70	3.60	-0.51	-0.16	-19.18	-0.19	0.0
3.80	3.54	-0.53	-0.16	-19.18	-0.19	0.0
3.90	3.49	-0.54	-0.16	-19.19	-0.19	0.0
3.94	3.47	-0.55	-0.17	-19.18	-0.19	0.0

DO YOU WANT ANY MORE OUTPUT? N

\*\*\* TRUCK HAS STOPPED IN 3.94 SECONDS \*\*\*

STOP? N



RUN #3

CHANGE PARAMETERS? Y

ENTER PARAMETER NUMBER TO BE CHANGED (01-42)

41  
41 ANTILOCK CODE (311): 000  
? 0

BREEZE HITCH? Y  
ENTER HITCH, DD, E, THETA (DEG), A5, A6, B5, ACM, ZBREEZ  
SEPERATED BY COMMA.  
2.,7.,1.5,45.,3.,1.5,1.5,6.,3.333

HITCH = 2.00000  
DD = 7.00000 FT  
E = 1.50000 FT  
THETA = 45.00000 DEG  
A5 = 3.00000 FT  
A6 = 1.50000 FT  
B5 = 1.50000 FT  
ACM = 6.00000 FT  
ZBREEZ = 3.33300 FT

CHANGE BREEZE HITCH DATA? N  
CHANGE BRAKE FORCE TABLE? N  
CHANGE STEEP TABLE? N  
ECHO STATIC LOADS? N

ENTER INITIAL OPTIC. ANGLE: 0.  
ANY DATA CHANGES NOW? N

\*\*\* END OF INPUT \*\*\*

PRINT OUTPUT ON FILE? N

ENTER TOTAL NUMBER OF OUTPUT VARIABLES (01-06): 06

ENTER NUMBER OF VARIABLES YOU WANT  
SEPERATE NUMBERS BY COMMA--(01-24)  
04,08,13,20,31,34

ENTER TIME INCREMENT TO BE PRINTED OUT  
.1

TIME	GAMMA	GAMMADOT	GAM-DDOT	LONG ACC	LAT. ACC	TBREEZ
0.0	0.0	0.0	0.0	-0.0	0.0	0.0
0.10	-0.04	-1.20	-22.07	-0.07	3.29	0.0
0.20	-0.22	-3.29	-12.70	-0.07	3.35	0.0
0.30	-0.70	-4.20	-5.63	-0.07	3.93	0.0
0.40	-1.14	-4.47	-0.09	-0.07	4.64	0.0
0.50	-1.52	-4.33	4.11	-3.33	5.19	499.35
0.60	-1.93	-3.63	16.26	-19.30	3.70	10000.00
0.71	-2.22	-1.73	13.59	-19.29	4.23	10000.00
0.81	-2.31	-0.15	16.22	-19.30	4.50	10000.00
0.90	-2.31	0.0	0.0	-19.35	4.47	4131.13
1.01	-2.31	0.0	0.0	-19.36	4.61	4311.52
1.11	-2.31	0.0	0.0	-19.39	4.77	4470.73
1.21	-2.31	0.0	0.0	-19.39	4.95	4650.63
1.31	-2.31	0.0	0.0	-19.40	5.14	4839.20
1.41	-2.31	0.0	0.0	-19.41	5.34	5029.16
1.51	-2.31	0.0	0.0	-19.42	5.53	5215.20
1.61	-2.31	0.0	0.0	-19.42	5.70	5394.16
1.71	-2.31	0.0	0.0	-19.43	5.86	5559.32
1.81	-2.31	0.0	0.0	-19.42	5.99	5707.20
1.91	-2.31	0.0	0.0	-19.42	6.09	5830.75
2.01	-2.31	0.0	0.0	-19.41	6.13	5925.20
2.11	-2.31	0.0	0.0	-19.39	6.14	5995.03
2.21	-2.31	0.0	0.0	-19.37	6.09	6004.79
2.31	-2.31	0.0	0.0	-19.35	5.99	5979.25
2.41	-2.31	0.0	0.0	-19.32	5.82	5903.53
2.51	-2.31	0.0	0.0	-19.29	5.59	5773.70
2.61	-2.31	0.0	0.0	-19.25	5.30	5587.05
2.71	-2.31	0.0	0.0	-19.22	4.94	5342.63
2.81	-2.31	0.0	0.0	-19.18	4.52	5042.10
2.91	-2.31	0.0	0.0	-19.15	4.04	4689.82
3.01	-2.31	0.0	0.0	-19.12	3.53	4291.55
3.11	-2.31	0.0	0.0	-19.09	2.99	3864.35
3.21	-2.31	0.0	0.0	-19.03	2.44	3417.54
3.31	-2.31	0.0	0.0	-19.07	1.90	2967.57
3.41	-2.31	0.0	0.0	-19.07	1.40	2530.36
3.51	-2.31	0.0	0.0	-19.03	0.95	2120.74
3.61	-2.31	0.0	0.0	-19.11	0.56	1744.25
3.71	-2.31	0.0	0.0	-19.11	0.42	1604.00
3.81	-2.31	0.0	0.0	-19.11	0.42	1604.54
3.91	-2.31	0.0	0.0	-19.11	0.42	1604.55
3.93	-2.31	0.0	0.0	-19.11	0.42	1604.49

DO YOU WANT ANY MORE OUTPUT? N

\*\*\* TRUCK HAS STOPPED IN 3.93 SECONDS \*\*\*  
STOP? Y

## 5.0 REFERENCES

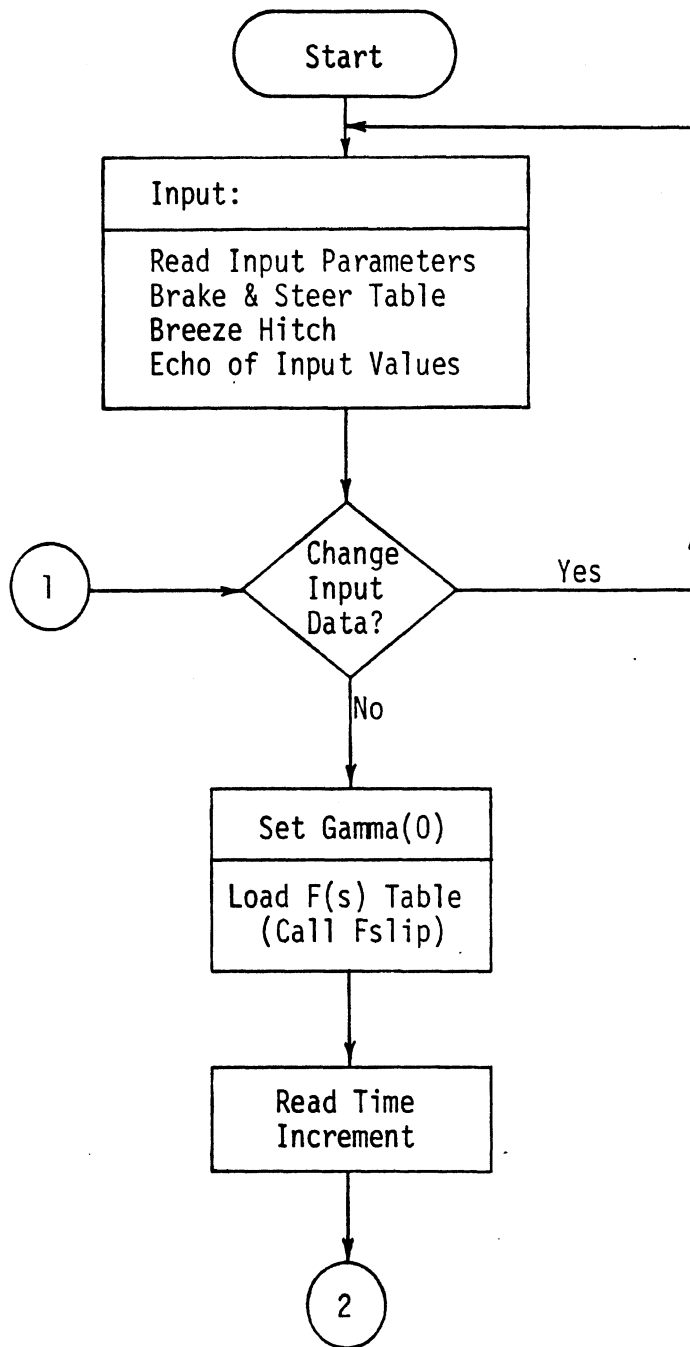
1. Leucht, P.M., Directional Dynamics of the Tractor-Semi-Trailer Vehicle, Ph.D. Thesis, University of Michigan, 1970.
2. Moncarz, H.T., Bernard, J.E., and Fancher, P.S., A Simplified Interactive Simulation for Predicting the Braking and Steering Response of Commercial Vehicles, Highway Safety Research Institute, Univ. of Michigan, August 1975.

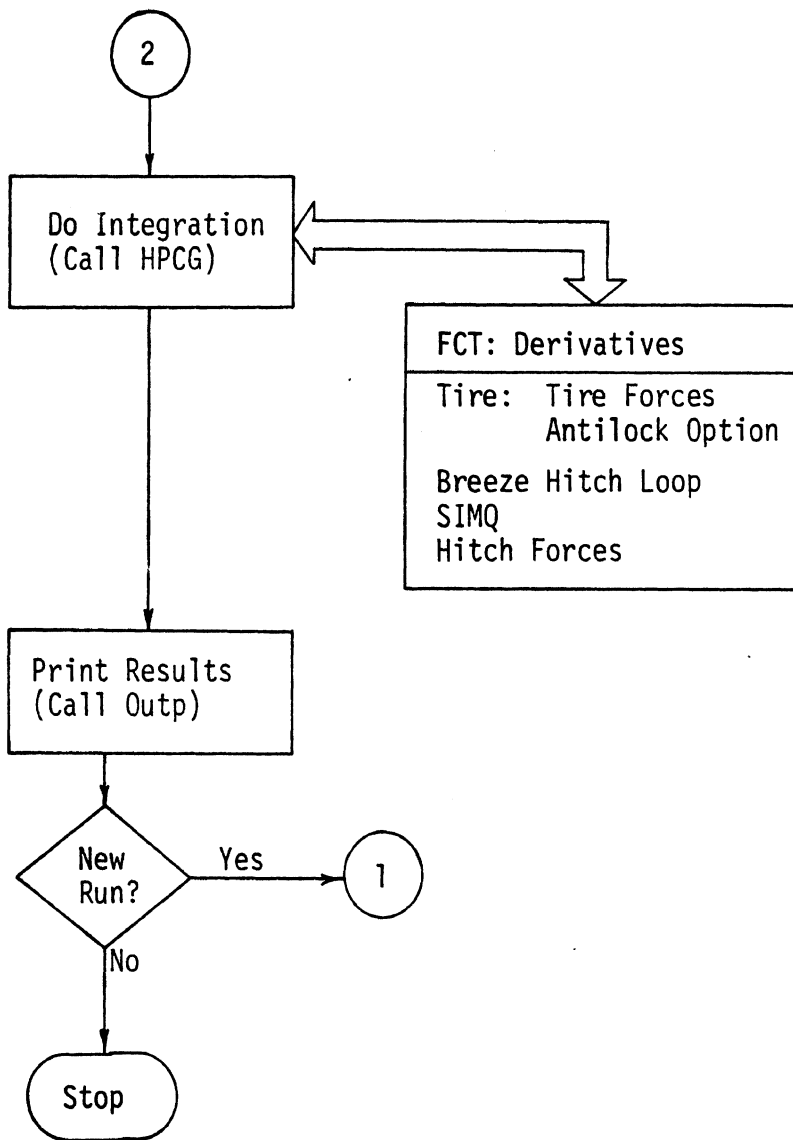
201

## APPENDIX

This appendix presents a flow chart and a source listing for the TBS program. Note that the last two subroutines in the source list are HPCG and SIMQ, both IBM subroutines. HPCG performs the integration and SIMQ solves the four-by-four set of equations to uncouple the accelerations.

# MACRO LOGIC FLOW





```

C *****
C TRACTOR=TRAILOR BREEZE HITCH PROGRAM
C *****
C
C ** MAIN PROGRAM BEGINS HERE
C
C   EXTERNAL  HPCG,FCT,OUTP
C   REAL      MU,MUS,M1,M2,I1,I2,MUS,MUT(10),MUSLOP,IQUIT
C   DIMENSION Y(8),PRMT(5),DERY(8),AUX(16,8),CIA(10),FZ(10),FSX(10),
C 1           DFZ(10),DELDFZ(10),FX(10),FY(10)
C   COMMON    M1,M2,M1,M2,A,B,C,D,H,70,Z1,Z2,GAM1,GAM2,MUS,RADS,DELTA,
C 1           T1,T2,T3,CIA,FSX,FZ,INIT,I1,I2,DERX(4),FRZ(10),ALPHA(10)
C 2           ,WINX,FY,DFZ,DELDFZ,TIMP,FX,DKEY,VEL,AAA,AAT,KEY(4),
C 3           MU(10),ANTEFF(10,2),IDUMP,XDUMP,XDOFF,MUS(10),KEYANT(3),
C 5           MUSLOP(10),BFT(15,7),ITAB,IXON,ITARS,STEER(25,2),ISAV,
C 6           GAM3,GAM4,TRUCK,IQUIT
C   COMMON    /I0/IR,IW
C   DATA     YES /'Y'/
C
C ** READY TO START - READ INPUT DATA
C
C 300 CONTINUE
C   I0=6
C   IR=5
C   TRUCK=2
C   NDIM=1
C   ISAV=1
C   IXON=1
C INITIALIZE TANDEM AXLE FORCES
C 999 CONTINUE
C   FX(5)=0.
C   FX(6)=0.
C   FX(9)=0.
C   FX(10)=0.
C   FY(6)=0.
C   FY(5)=0.
C   FY(9)=0.
C   FY(10)=0.
C   CALL INPUT(Y,DERY,PRMT,NDIM)
C   IF (TRUCK .EQ. 0.) GO TO 1065
C   WRITE(I0,131)
C 131 FORMAT(/'/',T6,'*** END OF INPUT ***'/)
C   DO 2001 I=1,4
C 2001 DEX(I)=0.
C   CALL HPCG(PRMT,Y,DERY,NDIM,IHLF,FCT,OUTP,AUX)
C   IF (PRMT(5) .EQ. 4.) GO TO 75
C   IF (PRMT(5) .EQ. 5.) GO TO 200
C   IF (PRMT(5) .GT. 0) GO TO 71
C   IF (IHLF .GT. 10) GO TO 70
C 71 CONTINUE
C   INIT = 0
C   GO TO 999
C 70 WRITE(I0,107) IHLF
C 107 FORMAT('0', '***** ERROR RETURN, CODE IS', I3, ' *****')
C   DKEY=2.
C   CALL OUTP(X,Y,DERY,IHLF,NDIM,PRMT)
C   GO TO 999
C 75 WRITE(I0,1007) XDOFF

```

```

BRZH0000
BRZH0005
BRZH0010
BRZH0015
BRZH0020
BRZH0025
BRZH0030
BRZH0035
BRZH0040
BRZH0045
BRZH0050
BRZH0055
BRZH0060
BRZH0065
BRZH0070
BRZH0075
BRZH0080
BRZH0085
BRZH0090
BRZH0095
BRZH0100
BRZH0105
BRZH0110
BRZH0115
BRZH0120
BRZH0125
BRZH0130
BRZH0135
BRZH0140
BRZH0145
BRZH0150
BRZH0155
BRZH0160
BRZH0165
BRZH0170
BRZH0175
BRZH0180
BRZH0185
BRZH0190
BRZH0195
BRZH0200
BRZH0205
BRZH0210
BRZH0215
BRZH0220
BRZH0225
BRZH0230
BRZH0235
BRZH0240
BRZH0245
BRZH0250
BRZH0255
BRZH0260
BRZH0265
BRZH0270
BRZH0275
BRZH0280
BRZH0285
BRZH0290
BRZH0295

```

```

1007 FORMAT('0', '*** TRUCK HAS STOPPED IN', F6.2, ' SECONDS ***')
      GO TO 71
200 WRITE(IW, 201) IQUIT
201 FORMAT('0', '*** COMPUTATIONS ARE STOPPED ***//',
1 '*** ARTICULATION ANGLE GREATER THAN',
2 F6.2, ' DEGREES ***//')
      GO TO 71
1006 FORMAT(' ', '*** SEE YOU NEXT TRIP ***')
1 / '*** KEEP ON TRUCKIN! ***')
1005 WRITE(IW, 1008)
1008 FORMAT('//RNEW DATA SET?')
      READ(IR, 1009)ANS
100 FORMAT(A1)
      IF(ANS.EQ.YES)GO TO 300
      WRITE(IW, 1006)
      END

```

```

BRZH0300
BRZH0305
BRZH0310
BRZH0315
BRZH0320
BRZH0325
BRZH0330
BRZH0335
BRZH0340
BRZH0345
BRZH0350
BRZH0355
BRZH0360
BRZH0365
BRZH0370
BRZH0375
BRZH0380
BRZH0385
BRZH0390
BRZH0395
BRZH0400
BRZH0405
BRZH0410
BRZH0415
BRZH0420
BRZH0425
BRZH0430
BRZH0435
BRZH0440
BRZH0445
BRZH0450
BRZH0455
BRZH0460
BRZH0465
BRZH0470
BRZH0475
BRZH0480
BRZH0485
BRZH0490
BRZH0495
BRZH0500
BRZH0505
BRZH0510
BRZH0515
BRZH0520
BRZH0525
BRZH0530
BRZH0535
BRZH0540
BRZH0545
BRZH0550
BRZH0555
BRZH0560
BRZH0565
BRZH0570
BRZH0575
BRZH0580
BRZH0585
BRZH0590
BRZH0595

```

C  
C  
C  
C  
C  
C

```

*****
SUPROUTINE FCT(X,Y,DERY)
*****

```

```

DIMENSION Y(8),DERY(8),CIA(10),DELFZ(10),DFZ(10),FX(10),
1 FY(10),FZ(10),FSX(10),BB(4),AA(16)
REAL MU,MUS,M1,M2,LAM1,LAM2,LAM3,LAM4,I1,I2
REAL MUSLOP,IQUIT,MUS,MUT(10),HM
COMMON W1,W2,M1,M2,A,B,C,D,H,Z4,Z1,Z2,GAM1,GAM2,MUS,RAD5,DELTA,
1 T1,T2,T3,CIA,FSX,FZ,INIT,I1,I2,DERX(4),FRZ(10),ALPHA(10)
2 ,WINX,FY,DFZ,DELFZ,TIME,FX,DFY,VEL,AAA,AAT,KEY(4),
3 MU(10),ANTEFF(10,2),TDUMP,XDUMP,XDOFF,MUS(10),KEYANT(3),
5 MUSLOP(10),BFT(15,7),ITAB,IXON,ITARS,STEER(25,2),ISAV,
6 GAM3,GAM4,TRUCK,IQUIT
COMMON /IO/IR,IN
COMMON /HREEZ/HREEZ,YHREEZ,HITCH,DD,E,THETA,A5,A6,B5,ACM
COMMON /KBREEZ/KBREEZ,ZBREEZ,KKEY
COMMON /FCTOUT/XL,YL,IPL0T

```

C  
C  
C  
C  
C  
C  
C  
C  
C  
C

```

** CALCULATE PARAMETERS FOR NEW DERY VALUES
** BEGIN WITH CALCULATION OF TIRE SLIP ANGLES

```

```

4 IF (INIT .EQ. 1) INIT=0

```

```

** COMPUTE DELTA FROM STEER TABLE

```

```

IF(X.GT.STEER(ITABS,1))GO TO 4004
DO 4002 I=ISAV,ITARS
IF(X.EQ.STEER(I,1))GO TO 4003
IF(X.GT.STEER(I,1))GO TO 4002
IM1=I-1
DELTA=(STEER(I,2)-STEER(IM1,2))/(STEER(I,1)
1 -STEER(IM1,1))*(X-STEER(IM1,1))+STEER(IM1,2)
GO TO 4005
4003 DELTA=STEER(I,2)
GO TO 4005
4002 CONTINUE
GO TO 4005
4004 DELTA=STEER(ITABS,2)
GO TO 4006
4005 ISAV=I-2

```



```

IF(ISAV,LT,1)ISAV=1
4006 CONTINUE
DELTA=DELTA/57.295

```

```

C
C ** THE AA MATRIX IS STORED COLUMNWISE. AA(1)*DERY(1)+AA(5)*DERY(2)
C ** +AA(9)*DERY(3)+AA(13)*DERY(4)=B(1) IS THE FIRST OF FOUR EQUATIONS
C ** SOLVED BY THE SIMQ ROUTINE
C

```

```

AA(1) = M1 + M2
AA(2) = 0.0
AA(3) = 0.0
AA(4) = C*M2*SIN(Y(7))
AA(5) = 0.0
AA(6) = M1 + M2
AA(7) = -H*M2
AA(8) = -C*M2*COS(Y(7))
AA(9) = C*M2*SIN(Y(7))
AA(10) = -M2*(H + C*COS(Y(7)))
AA(11) = M2*(H*M + C*M*CCS(Y(7))) + I1
AA(12) = I2 + C*M2*(C+H*COS(Y(7)))
AA(13) = C*M2*SIN(Y(7))
AA(14) = -C*M2*COS(Y(7))
AA(15) = H*C*M2*COS(Y(7))
AA(16) = I2 + C*C*M2

```

```

5 IF (Y(2) .NE. 0) GO TO 7
DO 6 I=1,10
6 ALPHA(I)=0.
GO TO 1400

```

```

7 ALPHA(1)=((Y(4)+(A*Y(6)))/Y(2))-DELTA
ALPHA(2)=ALPHA(1)
ALPHA(3)=(Y(4)-((B-AAA/2.)*Y(6)))/Y(2)
ALPHA(4)=ALPHA(3)
IF(KEY(1),LT,1)GO TO 1399
ALPHA(5)=(Y(4)-((H+AAA/2.)*Y(6)))/Y(2)
ALPHA(6)=ALPHA(5)

```

```

1399 ALPHA(7)=((Y(4)-(H*Y(6)))*COS(Y(7))-(C+(D-AAT/2.))*(Y(6)+Y(8))
1-Y(2)*SIN(Y(7)))/((Y(2)*COS(Y(7)))+(Y(4)-(H*Y(6))*SIN(Y(7))))
ALPHA(8)=ALPHA(7)
IF(KEY(3),LT,1)GO TO 1400
ALPHA(9)=((Y(4)-(H*Y(6)))*COS(Y(7))-(C+(D+AAT/2.))*(Y(6)+Y(8))
1-Y(2)*SIN(Y(7)))/((Y(2)*COS(Y(7)))+(Y(4)-(H*Y(6))*SIN(Y(7))))
ALPHA(10)=ALPHA(9)

```

```

1400 CONTINUE

```

```

C
C ** COMPUTATION OF LONGITUDINAL AND LATERAL FORCES ON TIRES
C

```

```

IF(X,GT,RFT(ITAH,1))GO TO 8004
DO 8002 I=IXON,ITAR
IF(X,EQ,RFT(I,1))GO TO 8003
IF(X,GT,RFT(I,1))GO TO 8002
IM1=I-1
DO 1701 J=1,6
K=J+1
FSX(J)=(RFT(I,K)-BFT(IM1,K))/(RFT(I,1)-BFT(IM1,1))
1 * (X-BFT(IM1,1))+BFT(IM1,K)

```

```

1701 CONTINUE
GO TO 8005

```

```

8003 CONTINUE
DO 1702 J=1,6
K=J+1

```

```

BRZH0600
BRZH0605
BRZH0610
BRZH0615
BRZH0620
BRZH0625
BRZH0630
BRZH0635
BRZH0640
BRZH0645
BRZH0650
BRZH0655
BRZH0660
BRZH0665
BRZH0670
BRZH0675
BRZH0680
BRZH0685
BRZH0690
BRZH0695
BRZH0700
BRZH0705
BRZH0710
BRZH0715
BRZH0720
BRZH0725
BRZH0730
BRZH0735
BRZH0740
BRZH0745
BRZH0750
BRZH0755
BRZH0760
BRZH0765
BRZH0770
BRZH0775
BRZH0780
BRZH0785
BRZH0790
BRZH0795
BRZH0800
BRZH0805
BRZH0810
BRZH0815
BRZH0820
BRZH0825
BRZH0830
BRZH0835
BRZH0840
BRZH0845
BRZH0850
BRZH0855
BRZH0860
BRZH0865
BRZH0870
BRZH0875
BRZH0880
BRZH0885
BRZH0890
BRZH0895

```

```

      FSX(J)=BFT(I,K)
1702 CONTINUE
      GO TO 8005
8002 CONTINUE
      GO TO 8005
8004 DO 1703 J=1,6
      K=J+1
      FSX(J)=BFT(ITAR,K)
1703 CONTINUE
      GO TO 8006
8005 IXON=I-2
      IF (IXON.LT.1) IXON=1
8006 CONTINUE
      FSX(7)=FSX(5)
      FSX(8)=FSX(6)
      FSX(9)=FSX(5)
      FSX(10)=FSX(6)
      FSX(5)=FSX(3)
      FSX(6)=FSX(4)
      IDUMP2=0
      DO 371 I=1,10
      IF (I.GT.4.AND.I.LT.7.AND.KEY(1).LT.1) GO TO 371
      IF (I.GT.8.AND.KEY(3).LT.1) GO TO 371
      IF (FSX(I).LT.0.AND.I.NE.IPLOT) WRITE(IW,809) I
      IF (FSX(I).LT.0.) IDUMP2=1
371 CONTINUE
809 FORMAT(5X,'COMPUTATIONS ARE STOPPED BECAUSE FSX(',
1 I2,') IS NEGATIVE.')
```

C\*\*\*\*\*  
C\*\*THE FIRE FORCES ARE NOW CALCULATED  
CALL TIRE(Y)

C  
C \*\* CALCULATION OF FIFTH WHEEL TORQUE DUE TO STEEL ON STEEL CONTACT  
C  
C  
14 IF (ABS(Y(8)) .GT. .03) GO TO 22  
T=Y(8)/.03\*((2.\*MUS\*D\*W2\*RADS)/(3.\*(C+D)))  
GO TO 26  
22 T=(Y(8)/ABS(Y(8)))\*((2.\*MUS\*D\*W2\*RADS)/(3.\*(C+D)))

C  
C \*\*\*\*\*  
C FROM HERE TO LINE BRZH1555 IS THE INITIAL BREEZE LOOP  
C \*\*\*\*\*

C  
C \*\* KKEY=1 IMPLIES BREEZE HITCH  
C  
260 IF ( KKEY .NE. 1 ) GO TO 26

C  
C \*\* KBREEZ=0 : BREEZE HITCH UNLOCKED  
C \*\* KBREEZ=1 : BREEZE HITCH LOCKED

C  
C  
C \*\* BREEZE HITCH LOOP  
C  
C \*\* TENSION IN THE CABLES ONLY  
C  
IF (( Y(8)\*Y(7) ) .GT. 0.) GO TO 231

C  
C \*\* THE NEXT STATEMENT PREVENTS PHANTOM UNLOCK DUE  
C \*\* TO HPCG INSPIRED Y(8) PERTURBATIONS. THE ONLY

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BRZH0900
BRZH0905
BRZH0910
BRZH0915
BRZH0920
BRZH0925
BRZH0930
BRZH0935
BRZH0940
BRZH0945
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BRZH0955
BRZH0960
BRZH0965
BRZH0970
BRZH0975
BRZH0980
BRZH0985
BRZH0990
BRZH0995
BRZH1000
BRZH1005
BRZH1010
BRZH1015
BRZH1020
BRZH1025
BRZH1030
BRZH1035
BRZH1040
BRZH1045
BRZH1050
BRZH1055
BRZH1060
BRZH1065
BRZH1070
BRZH1075
BRZH1080
BRZH1085
BRZH1090
BRZH1095
BRZH1100
BRZH1105
BRZH1110
BRZH1115
BRZH1120
BRZH1125
BRZH1130
BRZH1135
BRZH1140
BRZH1145
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BRZH1155
BRZH1160
BRZH1165
BRZH1170
BRZH1175
BRZH1180
BRZH1185
BRZH1190
BRZH1195
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C ** WAY TO UNLOCK A LOCKED HITCH IS TO GO THROUGH
C ** THE LOOP, FIND TBREEZ ,LT. 0, AND START OVER.
C ** SEE STATEMENT 394.4
      IF ( KBREEZ ,EQ. 1 ) GO TO 231
C
      TBREEZ=V.
      GO TO 26
C
C ** COMPUTE THE PULL ANGLE ASSUMING SMALL ANGLES
231 PHI=DD/E*Y(7)
C
C ** SET THE CABLE TENSION, ASSUME NO LOCK
      TBREEZ=MITCHT*FSX(7)
C
      IF (ABS(PHI) ,LT. THETA) GO TO 60
C
C ** HANG FROM THE FRAME RAIL
C
      PHI=ATAN((DD*SIN(Y(7))+B5)/(DD*COS(Y(7))-A5))
C
      SINPHI=SIN(PHI)
      COSPHI=COS(PHI)
C
C ** COMPUTE THE FORCE DIRECTIONS IN THE TRAILER SYSTEM
      TSPHI=SIN(PHI-Y(7))
      TCPHI=COS(PHI-Y(7))
C
      BT1=A5*SINPHI+B5*COSPHI*PHI/ABS(PHI)
C
C ** BT1 IS THE COEFFICIENT OF THE CABLE TENSION
C ** APPEARING IN RIGHT HAND SIDE OF THE RDOT EQUATION.
C ** -BT1 IS THE COEFFICIENT IN THE GAMMADDOT EQUATION
C ** BT1*TBREEZ TURNS OUT TO BE THE MOMENT AROUND THE HITCH
C
      GO TO 61
C
60 CONTINUE
C
C ** HANG FROM THE EYE
C
      SINPHI=SIN(PHI)
      COSPHI=COS(PHI)
      TSPHI=SIN(PHI-Y(7))
      TCPHI=COS(PHI-Y(7))
C
      BT1=(A5+A6)*SINPHI
C
61 CONTINUE
C
      IF ( KBREEZ ,EQ. 1 ) GO TO 62
C
      IF (ABS(Y(8)) ,GT. 0.03 ,OR. (DERX(4)*Y(8)) ,LT. 0 ) GO TO 26
C
C ** ASSUME BREEZE HITCH LOCKED
C ** TBREEZ NOW REPLACES GAMMADDOT AS AN UNKNOWN
C ** IN THE 4*4 OF ACCELERATIONS
C
      REMEMBER TBREEZ IN CASE HITCH IS NOT REALLY LOCKED
62 TBAR=TBREEZ

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BRZH1270
BRZH1205
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BRZH1295
BRZH1300
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BRZH1470
BRZH1475
BRZH1480
BRZH1485
BRZH1490
BRZH1495

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C      GET RID OF TBREEZ FOR RHS EQUATIONS
      TBREEZ=0.
      XY8=Y(8)
      Y(8)=0.
      KBREEZ=1
C
C ** SET-UP NEW (4,4) TO SOLVE FOR TBREEZ
      AA(13)=V.
      AA(14)=V.
      AA(15)=-BT1
      AA(16)=BT1
C
C ** INITIAL BREEZE HITCH LOOP FINISHED
C
C ** COMPUTATION OF INERTIA FORCES AT CENTER OF MASS FOR TRACTOR AND
C ** TRAILER, ALL AXLES IN BOTH X AND Y COORDINATES
      26 LAM1=(-M2*(DERX(1)-(Y(4)*Y(6))+(H*(Y(6)**2)))*COS(Y(7)))-(M2*(DERX(1(2)+(Y(2)*Y(6))-(H*DERX(3)))*SIN(Y(7)))-(C*M2*(Y(6)+Y(8))**2)
      LAM2=(M2*(DERX(1)-(Y(4)*Y(6))+(H*(Y(6)**2)))*SIN(Y(7)))-(M2*(DERX(12)+(Y(2)*Y(6))-(H*DERX(3)))*COS(Y(7)))+(C*M2*(DERX(3)+DERX(4)))
      LAM3=(-M2*(DERX(1)-(Y(4)*Y(6))+(H*(Y(6)**2)))-C*M2*(DERX(3)+DERX(4)))*SIN(Y(7))-(C*M2*((Y(6)+Y(8))**2)*COS(Y(7)))
      LAM4=(-M2*(DERX(2)+(Y(2)*Y(6))-(H*DERX(3)))-C*M2*((Y(6)+Y(8))**2)1)*SIN(Y(7)))+(C*M2*(DERX(3)+DERX(4))*COS(Y(7)))
C*****
C
C 370 IF (DKEY .EQ. 1.) GO TO 15
      DKEY=1.
C
C ** CALCULATION OF LATERAL LOAD TRANSFERS NOTE, THESE ADD TO ZERO
C ** NOTE DERX ARE THE LAGGED ACCELERATION VALUES
C ** AND XBREEZ IS THE LAGGED CABLE TENSION
C
C 37 FX7891=FX(7)+FX(8)+FX(9)+FX(10)
      FY7891=FY(7)+FY(8)+FY(9)+FY(10)
      YTEMP=(FX7891)*SIN(Y(7))+(FY7891)*COS(Y(7))+XBREEZ*SINPHI
      YL=LAM4+YTEMP
      ZTS=ZBREEZ*XBREEZ*SINPHI
      DELFZ(1)=(GAM1/(2.*T1))*((-Z0*YL)+Z1*M1*(DERX(2)+Y(2)*
      &Y(6))+ZTS)
      DELFZ(2)=-DELFZ(1)
      DELFZ(3)=(GAM2/(2.*T2))*((-Z0*YL)+Z1*M1*(DERX(2)+Y(2)*
      &Y(6))+ZTS)
      IF(KEY(1).LT.1)GO TO 3004
      DELFZ(3)=DELFZ(3)/2.
      DELFZ(5)=DELFZ(3)
      DELFZ(6)=-DELFZ(3)
3004 DELFZ(4)=-DELFZ(3)
      DELFZ(7)=(-(Z2-Z0)*LAM2+Z0*FY7891+(Z0-ZBREEZ)*XBREEZ*TSINPHI)
      &/(2.*T3)
      IF(KEY(3).LT.1)GO TO 3005
      DELFZ(7)=DELFZ(7)/2.
      DELFZ(9)=DELFZ(7)
      DELFZ(10)=-DELFZ(7)
3005 DELFZ(8)=-DELFZ(7)
C
C ** COMPUTATION OF LONGITUDINAL LOAD TRANSFERS. NOTE, SUM IS ZERO

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C ** THESE EQUATIONS MAY VARY FROM SOURCE EQUATIONS,
C
XTEMP=(FX7891)*COS(Y(7))-(FY7891)*SIN(Y(7))+XBREEZ*COSPHI
XL=LAM3+XTEMP
C
C ** DZ IS THE DYNAMIC LOAD TRANSFERRED ON TO THE HITCH
DZ=(Z2*LAM1-Z0*(XL*COS(Y(7))+YL*SIN(Y(7)))+XPREEZ
&*ZBPREEZ*TCPHI)/(C+D)
DFZ(1)=(1./(2.*(A+B)))*((B-H)*DZ-M1*(DERX(1)-Y(4)*Y(6))*Z1+XL*Z0
&-XPREEZ*ZBPREEZ*COSPHI)
DFZ(2)=DFZ(1)
DFZ(3)=D7*(A+H)/(A+B)-DFZ(1)
IF(KEY(1),LT,1)GO TO 3002
DFZ(3)=DFZ(3)/2.
DFZ(5)=DFZ(3)
DFZ(6)=DFZ(3)
3002 DFZ(4)=DFZ(3)
IF(KEY(1),LT,1)GO TO 3006
DFZ(3)=DFZ(3)-GAM3*(FX(3)+FX(5))
DFZ(4)=DFZ(4)-GAM3*(FX(4)+FX(6))
DFZ(5)=DFZ(5)+GAM3*(FX(3)+FX(5))
DFZ(6)=DFZ(6)+GAM3*(FX(4)+FX(6))
3006 CONTINUE
DFZ(7)=-DZ/2.
IF(KEY(3),LT,1)GO TO 3003
DFZ(7)=DFZ(7)/2.
DFZ(9)=DFZ(7)
DFZ(10)=DFZ(7)
3003 DFZ(8)=DFZ(7)
IF(KEY(3),LT,1)GO TO 3008
DFZ(7)=DFZ(7)-GAM4*(FX(7)+FX(9))
DFZ(8)=DFZ(8)-GAM4*(FX(8)+FX(10))
DFZ(9)=DFZ(9)+GAM4*(FX(7)+FX(9))
DFZ(10)=DFZ(10)+GAM4*(FX(8)+FX(10))
3008 CONTINUE
C
C ** COMPUTATION OF INSTANTANEOUS LOADS
C
IDUMP=0
DO 30 I=1,10
DUAL=0.0
IF(I,GT,2,AND,J,LT,7,AND,KEY(2),GT,0)DUAL=1.0
IF(I,GT,6,AND,KEY(4),GT,0)DUAL=1.0
FZ(I)=(FRZ(I)+DFZ(I)+DELDFZ(I))/(1.+DUAL)
IF(I,GT,4,AND,I,LT,7,AND,KEY(1),LT,1)GO TO 30
IF(I,GT,8,AND,KEY(3),LT,1)GO TO 30
IF(FZ(I),LT,0.,AND,IW,NE,IPL0T)WRITE(IW,810)I
IF(FZ(I),LT,0.)IDUMP=1
30 CONTINUE
IF(IDUMP,EQ,1)IDUMP=1
810 FORMAT(5X,'COMPUTATIONS ARE STOPPED BECAUSE WHEEL ',I2,
1,' LIFTS OFF GROUND.')
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BRZH1800
BRZH1805
BRZH1810
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BRZH1900
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BRZH1910
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BRZH1940
BRZH1945
BRZH1950
BRZH1955
BRZH1960
BRZH1965
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BRZH2015
BRZH2020
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BRZH2085
BRZH2090
BRZH2095
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C ** Y(2)=U          DERY(2)=U-DOOT          BRZH2100
C ** Y(3)=YH        DERY(3)=YH-DOOT         BRZH2105
C ** Y(4)=V          DERY(4)=V-DOOT         BRZH2110
C ** Y(5)=PSI       DERY(5)=PSI-DOOT       BRZH2115
C ** Y(6)=PSIDOT    DERY(6)=PSI-DDOT      BRZH2120
C ** Y(7)=GAMMA     DERY(7)=GAMMA-DOOT    BRZH2125
C ** Y(8)=GAMMA-DOOT DERY(8)=GAMMA-DDOT    BRZH2130
C                                                    BRZH2135
C 15 CONTINUE                                          BRZH2140
C                                                    BRZH2145
C ** THESE LAM VALUES HAVE DERX(I) REMOVED FROM ABOVE (STATEMENT 26) BRZH2150
C ** LAM VALUES, THEY FORM PART OF THE RB VECTOR IN AA*X=BB EQUATION BRZH2155
C ** WHICH WILL BE SOLVED BY SIMQ                    BRZH2160
C                                                    BRZH2165
C  LAM2 = M2*((-Y(4)*Y(6) + H*Y(6)**2)* SIN(Y(7)) - Y(2)*Y(6)*
1 COS(Y(7)))                                          BRZH2170
C  LAM3 = -M2*((-Y(4)*Y(6) + H*Y(6)**2) + C*(Y(6) + Y(8))**2*
1 COS(Y(7)))                                          BRZH2175
C  LAM4 = -M2*(Y(2)*Y(6) + C*(Y(6) + Y(8))**2*SIN(Y(7))) BRZH2180
C                                                    BRZH2185
C ** THE RHS VALUES ARE THE RIGHT HAND SIDE OF THE LEUCHT EQUATIONS BRZH2190
C ** AS SHOWN IN THE THESIS                          BRZH2195
C                                                    BRZH2200
C 41 FX3456=FX(3)+FX(4)+FX(5)+FX(6)                 BRZH2205
C  FY3456=FY(3)+FY(4)+FY(5)+FY(6)                 BRZH2210
C  F35446=FX(3)+FX(5)-FX(4)-FX(6)                 BRZH2215
C  F79M81=FX(7)+FX(9)-FX(8)-FX(10)                BRZH2220
C  RHS1  =(Y(4)*Y(6))+(1/M1)*((LAM3+(FX(1)+FX(2))*COS(DELTA)
1 +(FX3456)+((FY7891)*COS(Y(7)))-((FY(1)+FY(2))*SIN(DELTA))
2 -((FY7891)*SIN(Y(7))))                            BRZH2225
C 42 RHS2 =-(Y(2)*Y(6))+(1/M1)*((LAM4+((FX(1)+FX(2))*SIN(DELTA))
1 +(FX7891)*SIN(Y(7)))+(FY(1)+FY(2))*COS(DELTA)+(FY3456)+(FY7891)
2 *COS(Y(7)))                                         BRZH2230
C  RHS3  =(1/I1)*((-H*LAM4)+(A*(FX(1)+FX(2))*SIN(DELTA))
4 +(T1*(FX(1)-FX(2)
1)*COS(DELTA)))+(T2*(F35446))-((H*(FX7891)*SIN(Y(7)))+(A*(FY(1)+FY(2)
2)*COS(DELTA))-(T1*(FY(1)-FY(2))*SIN(DELTA)))
3 -((B-AAA/2.)*(FY(3)+FY(4))+(B+AAA/2.)*(FY(5)+FY(6)))
4 -((H*(FY7891)*COS(Y(7)))+T+BT1*TB+FEZ)
RHS4  =(1/I2)*(-C*LAM2+T3*(F79M81)
2 -((C+D+AAT/2.)*(FY(7)+FY(8))+(C+D+AAT/2.)*(FY(9)+FY(10)))-T
3 -BT1*TBREEZ)                                         BRZH2235
C                                                    BRZH2240
C 43 RR(1)=RHS1*M1                                     BRZH2245
C  BB(2)=RHS2*M1                                     BRZH2250
C  BB(3)=RHS3*I1                                     BRZH2255
C  BB(4)=RHS4*I2                                     BRZH2260
C                                                    BRZH2265
C ** SIMQ SOLVES THE AA*X=BB EQUATIONS FOR THE ACCELERATIONS BRZH2270
C ** SEE SUBROUTINE SIMQ FOR DETAILS. NOTE SIMQ RETURNS THE SOLUTION BRZH2275
C ** IN THE RB VECTOR, AND THE AA MATRIX IS DESTROYED. BRZH2280
C                                                    BRZH2285
C 520 CALL SIMQ(AA,RR,4,KS)                            BRZH2290
C                                                    BRZH2295
C ** CALCULATE THE DERIVATIVES                       BRZH2300
C DO 1 I = 1,4                                         BRZH2305
C 1  DERY(2*I) = BB(I)                                  BRZH2310
C  DERY(5)=Y(6)                                        BRZH2315
C  DERY(7)=Y(8)                                        BRZH2320
C  DERY(1)=Y(2)*COS(Y(5))-Y(4)*SIN(Y(5))            BRZH2325
C                                                    BRZH2330
C                                                    BRZH2335
C                                                    BRZH2340
C                                                    BRZH2345
C                                                    BRZH2350
C                                                    BRZH2355
C                                                    BRZH2360
C                                                    BRZH2365
C                                                    BRZH2370
C                                                    BRZH2375
C                                                    BRZH2380
C                                                    BRZH2385
C                                                    BRZH2390
C                                                    BRZH2395

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```

DERY(3)=Y(2)*SIN(Y(5))+Y(4)*COS(Y(5))
C
C
C *****
C FROM HERE TO LINE HPZH2700 IS THE SECOND FREEZE LOOP
C *****
C
C IF ( KKEY .EQ. 0 ) GO TO 3
C
C ** FREEZE HITCH LOCK?????????
C
C IF (KBREEZ .EQ. 0) GO TO 3
C
C ** HERE WE CALCULATE DERIVATIVES AND TBREEZ IF HITCH IS LOCKED
C
C ** ASSUME BREEZE HITCH LOCK
C DERY(8)=0,
C TBREFZ=UB(4)
C
C ** HITCH SHOULD BE UNLOCKED IF GAMMA WANTS TO GET SMALLER
C IF ( BR(4) .LT. 0. ,AND, KBREEZ .EQ. 1 ) GO TO 87241
C
C ** CHECK FOR TENSION FOR BEYOND CAPACITY
C IF ((BR(4)) .LT. (TBAR+0.1) ) GO TO 3
C
C ** BAD ASSUMPTION, NOT ENOUGH TO KEEP HITCH LOCKED
C TBREEZ=TRAR
C GO TO 87242
C
C
C 87241 TBREFZ=0.
C
C 87242 KBPEEZ=0
C Y(8)=XY8
C
C
C ** GO BACK TO ORIGINAL (4,4)
C AA(1) = M1 + M2
C AA(2) = 0.0
C AA(3) = 0.0
C AA(4) = C*M2*SIN(Y(7))
C AA(5) = 0.0
C AA(6) = M1 + M2
C AA(7) = -H*M2
C AA(8) = -C*M2*COS(Y(7))
C AA(9) = C*M2*SIN(Y(7))
C AA(10) = -M2*(H + C*COS(Y(7)))
C AA(11) = M2*(H*H + C*H*COS(Y(7))) + I1
C AA(12) = I2 + C*M2*(C+H*COS(Y(7)))
C AA(13) = C*M2*SIN(Y(7))
C AA(14) = -C*M2*COS(Y(7))
C AA(15) = H*C*M2*COS(Y(7))
C AA(16) = I2 + C*C*M2
C
C ** FIX UP RHS TO INCLUDE THREEZ
C RHS1=RHS1-TBREFZ*COSPHI/M1
C RHS2=RHS2-TBREEZ*SINPHI/M1
C RHS3=RHS3+BT1*TBREFZ/I1
C RHS4=RHS4+BT2*TBREFZ/I2
C
C ** GO BACK TO SIMQ TO FIND GAMMADOT

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BRZH2400
BRZH2405
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GO TO 43
C
C ** SECOND BREEZE HITCH LOOP FINISHED
C
C
C ** THESE CALCULATIONS GIVE THE HITCH FORCES USING DERY RATHER THAN DE
C
3 LAM3=LAM3-M2*(DERY(2)+C*(DERY(6)+DERY(8))*SIN(Y(7)))
  LAM4=LAM4-M2*(DERY(4)-M*DERY(A)-C*(DERY(6)+DERY(8))*COS(Y(7)))
  XL=LAM3+XTEMP+THREEZ*COSPHI
  YL=LAM4+YTEMP+TEREEZ*SINPHI
C
C ** DERY ARRAY NOW CONTAINS ALL NEW VALUES AT TIME STEP X
C ** SUBROUTINE FINISHED RETURN TO HPCG
525 CONTINUE
    RETURN
    END
C
C
C
C
C *****
  SUBROUTINE INPUT(Y,DERY,PRMT,NDIM)
C *****
  DIMENSION Y(8),PRMT(5),AUX(16,8),DERY(8),CIA(10),FZ(10),FSX(10),
1    DFZ(10),DELFZ(10),FX(10),FY(10),PAR(40),PAR2(3)
  REAL MU,MUS,M1,M2,I1,I2,MUS,INIT(10),MUSLOP,IQUIT
  INTEGER COR(25)
  COMMON W1,M2,M1,M2,A,B,C,D,H,Z0,Z1,Z2,GAM1,GAM2,MUS,RADS,DELTA,
1    T1,T2,T3,CIA,FSX,FZ,INIT,I1,I2,DERX(4),FRZ(10),ALPHA(10)
2    ,WINX,FY,DFZ,DELFZ,TIME,FX,DKEY,VEL,AAA,AAT,KEY(4),
3    MU(10),ANTEFF(10,2),IDUMP,XDUMP,XDOFF,MUS(10),KEYANT(3),
5    MUSLOP(10),RFT(15,7),ITAB,IXON,ITABS,STEFF(25,2),ISAV,
6    GAM3,GAM4,TRUCK,IQUIT
  COMMON /IO/IR,IN
  COMMON /BREEZ/THREEZ,XBREEZ,HITCHT,DD,E,THETA,A5,A6,B5,ACH
  COMMON /KBREEZ/KBREEZ,ZBREEZ,KKEY
  DATA YES/'Y'/
  DATA IFLAG,ONCE,MUSLIP/0,M.,./
C
C ** READY TO START
C
C
  NF=0
  IE=0
  IREP=0
  IF (TRUCK .EQ. 1) IREP=1
  IF (IREP .EQ. 1) GO TO 1
  WRITE(IN,90)
90 FORMAT('1', 'YOU ARE ABOUT TO RUN THE HSRI SIMULATION PROGRAM FOR'
1' ', 'A TRACTOR-TRAILER WITH BREEZE HITCH IN THE HORIZONTAL PLANE')
  IBPEZ=0
11000 FORMAT('RPRINT PROGRAM EXPLANATIONS? (Y OR N):')
11002 WRITE(IN,11000)
11003 READ(IN,92) ANS
11004 ISHOW=0
11005 IF(ANS .EQ. YES) ISHOW=1
11006 IF(ISHOW .EQ. 1) CALL EXPLAN(1,ISHOW)
  GO TO 2
1 WRITE(IN,91)

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```

91 FORMAT('R','STOP?')
11013 IF(ISHOW .EQ. 1) CALL EXPLAN(7,ISHOW)
      READ(IR,92) ANS
92 FORMAT(A1)
      IF (ANS .NE. YES) GO TO 2
      TRUCK=0.0
      RETURN
2 TRUCK=1.0
  ISAV=1
  IXON=1
4 DKEY=0.
  IF (IHEP .EQ. 1) GO TO 200
  WRITE(I*,420)
400 FORMAT('R','LIST INPUT PARAMETERS?')
11007 IF(ISHOW .EQ. 1) CALL EXPLAN(2,ISHOW)
      READ(IR,92) ANS
      IF (ANS .EQ. YES) NF=1
      WRITE(I*,98)
98 FORMAT('R','READ DATA FROM FILE?')
      READ(IR,92) ANS
      IF (ANS .NE. YES) GO TO 37
      WRITE(I*,38)
38 FORMAT('R','ENTER INPUT DEVICE NUMBER IN I2 FORMAT:')
      READ(IR,39) IDATA
39 FORMAT(I2)
      IE=1
      IDATA1=IR
      IR=IDATA
37 WRITE(I*,99)
99 FORMAT('R','*** BEGIN INPUT ***')
      PAR(5)=0.
      PAR(6)=0.
      PAR(21)=0.
      PAR(22)=0.
      PAR(26)=0.
      PAR(27)=0.
      PAR(28)=0.
      PAR2(1)=0.
      PAR2(2)=0.
      PAR2(3)=0.
      IF ( NF .EQ. 1) GO TO 402
      READ(IR,3002)(KEYANT(I),I=1,3)
3002 FORMAT(3I1)
      READ(IR,3001)(KEY(I),I=1,4)
3001 FORMAT(4I1)
      PAR(19)=10.
      DO 403 I=1,40
      IF(I .EQ. 19 .AND. PAR(18) .EQ. 0) GO TO 403
      IF(I.EQ.5.AND.KEY(1).LT.1)GO TO 403
      IF(I.EQ.6.AND.KEY(3).LT.1)GO TO 403
      IF(I.EQ.21.AND.KEY(1).LT.1)GO TO 403
      IF(I.EQ.22.AND.KEY(3).LT.1)GO TO 403
      IF(I.GT.25.AND.I.LT.29)GO TO 409
      ANS=NO
      IF(I.EQ.32)READ(IR,92)ANS
      IF(ANS.EQ.YES)MUSLIP=1
      IF(MUSLIP.GT.0)GO TO 410
      READ(IR,103) PAR(I)
      GO TO 403
410 READ(IR,103)PAR(32)

```

```

BRZH3000
BRZH3005
BRZH3010
BRZH3015
BRZH3020
BRZH3025
BRZH3030
BRZH3035
BRZH3040
BRZH3045
BRZH3050
BRZH3055
BRZH3060
BRZH3065
BRZH3070
BRZH3075
BRZH3080
BRZH3085
BRZH3090
BRZH3095
BRZH3100
BRZH3105
BRZH3110
BRZH3115
BRZH3120
BRZH3125
BRZH3130
BRZH3135
BRZH3140
BRZH3145
BRZH3150
BRZH3155
BRZH3160
BRZH3165
BRZH3170
BRZH3175
BRZH3180
BRZH3185
BRZH3190
BRZH3195
BRZH3200
BRZH3205
BRZH3210
BRZH3215
BRZH3220
BRZH3225
BRZH3230
BRZH3235
BRZH3240
BRZH3245
BRZH3250
BRZH3255
BRZH3260
BRZH3265
BRZH3270
BRZH3275
BRZH3280
BRZH3285
BRZH3290
BRZH3295

```

READ(IR,103)PAR(35)	BRZH3300
READ(IR,103)PAR(36)	BRZH3305
GO TO 404	BRZH3310
409 J=I-25	BRZH3315
IF(KEYANT(J).GT.0)READ(IR,140)PAR(I),PAR2(J)	BRZH3320
403 CONTINUE	BRZH3325
GO TO 404	BRZH3330
402 CONTINUE	BRZH3335
WRITE(IW,4001)	BRZH3340
11008 IF(ISHOW.EQ.1)CALL EXPLAN(3,ISHOW)	BRZH3345
READ(IR,3002)(KEYANT(I),I=1,3)	BRZH3350
IF(IE.EQ.1)WRITE(IW,5002)(KEYANT(I),I=1,3)	BRZH3355
WRITE(IW,4002)	BRZH3360
READ(IR,3001)(KEY(I),I=1,4)	BRZH3365
IF(IE.EQ.1)WRITE(IW,5001)(KEY(I),I=1,4)	BRZH3370
4001 FORMAT(' 41 ENTER ANTILOCK CODE FOR TRACTOR FRONT, TRACTOR REAR, /	BRZH3375
1 ' AND TRAILER AXLES.')	BRZH3380
2 ' 0=NO ANTILOCK, 1=INDEPENDENT ANTILOCK, FORMAT=3I1.')	BRZH3385
4002 FORMAT(' 42 ENTER CODE FOR TANDEM AXLES TRACTOR REAR, DUAL TIRES /	BRZH3390
1 ' TRACTOR REAR, TANDEM AXLES TRAILER, DUAL TIRES TRAILER')	BRZH3395
2 ' 0=NO, 1=YES, FORMAT=4I1.')	BRZH3400
5001 FORMAT(1X,4I1)	BRZH3405
5002 FORMAT(1X,3I1)	BRZH3410
WRITE(IW,101)	BRZH3415
PAR(19)=10.	BRZH3420
LAP011=0	BRZH3425
DO 70 I=1,40	BRZH3430
IF(I.EQ.19.AND.PAR(18).EQ.0.)GO TO 70	BRZH3435
IF(I.EQ.5.AND.KEY(1).LT.1)GO TO 70	BRZH3440
IF(I.EQ.6.AND.KEY(3).LT.1)GO TO 70	BRZH3445
IF(I.EQ.21.AND.KEY(1).LT.1)GO TO 70	BRZH3450
IF(I.EQ.22.AND.KEY(3).LT.1)GO TO 70	BRZH3455
11009 IF(I.EQ.29.AND.ISHOW.EQ.1)CALL EXPLAN(4,ISHOW)	BRZH3460
IF(I.NE.32)GO TO 7600	BRZH3465
IF(IE.EQ.2)WRITE(IW,9001)	BRZH3470
9001 FORMAT('DO ALL TIRES HAVE THE SAME MU-SLIP CURVE?')	BRZH3475
READ(IR,92)ANS	BRZH3480
IF(ANS.NE.YES)GO TO 7601	BRZH3485
MUSLIP=1	BRZH3490
CALL WRITEX(32)	BRZH3495
READ(IR,103)PAR(32)	BRZH3500
IF(IE.EQ.1)WRITE(IW,104)PAR(32)	BRZH3505
CALL WRITEX(35)	BRZH3510
READ(IR,103)PAR(35)	BRZH3515
IF(IE.EQ.1)WRITE(IW,104)PAR(35)	BRZH3520
CALL WRITEX(38)	BRZH3525
READ(IR,103)PAR(38)	BRZH3530
IF(IE.EQ.1)WRITE(IW,104)PAR(38)	BRZH3535
GO TO 404	BRZH3540
7600 CONTINUE	BRZH3545
J=I-25	BRZH3550
IF(I.LT.26.OR.I.GT.29)GO TO 7601	BRZH3555
IF(KEYANT(J).LT.1)GO TO 70	BRZH3560
11029 IF(LAP011.NE.0)GO TO 11031	BRZH3565
11030 IF(ISHOW.EQ.1)CALL EXPLAN(9,ISHOW)	BRZH3570
11031 LAP011=1	BRZH3575
7601 CONTINUE	BRZH3580
CALL WRITEX(I)	BRZH3585
IF(IE.EQ.1)GO TO 71	BRZH3590
IF(I.GT.25.AND.I.LT.29)GO TO 7008	BRZH3595

```

    READ(IR,103) PAR(I)
    GO TO 7010
7008 J=I-25
    READ(IR,140)PAR(I),PAR2(J)
7010 CONTINUE
    GO TO 72
    71 CONTINUE
    IF(I.GT.25.AND.I.LT.29)GO TO 7150
    READ(IR,103) PAR(I)
    GO TO 7102
7150 J=I-25
    READ(IR,140)PAR(I),PAR2(J)
7102 CONTINUE
    IF(I.GT.25.AND.I.LT.29)GO TO 7199
    WRITE(IW,104) PAR(I)
    GO TO 72
7199 WRITE(IW,105)PAR(I),PAR2(J)
    72 CONTINUE
    IF (I.NE. 23) GO TO 70
    VEL=PAR(23)*5280./3600.
    WRITE(IW,126) VEL
    70 CONTINUE
C
C ** BRAKE FORCE TABLE
C
404 CONTINUE
    DO 1700 I=1,15
    DO 1700 J=1,7
1700 BFT(I,J)=0.0
C
C ** READ IN TABLE
C
    IF (NF .EQ. 1) GO TO 405
    READ(IR,137) ITAB
    DO 406 I=1,ITAB
    READ(IR,140) (BFT(I,J),J=1,7)
    406 CONTINUE
    GO TO 11
    405 CONTINUE
11011 IF(ISHOW .EQ. 1) CALL EXPLAN(5,ISHOW)
    WRITE(IW,135)
    READ(IR,137) ITAB
    IF(IE.EQ.1) WRITE(IW,136) ITAB
    WRITE(IW,138)
    DO 62 I=1,ITAB
    READ (IR,140) (BFT(I,J),J=1,7)
    IF(IE.EQ.1) WRITE(IW,139) (BFT(I,J),J=1,7)
    62 CONTINUE
    IF (IF .EQ. 1) GO TO 11
    WRITE(IW,142)
142 FORMAT('R', 'ECHO TABLE?')
    READ(IR,92) ANS
    IF(ANS.NE.YES)GO TO 11
    WRITE(IW,138)
    DO 12 I=1,ITAB
    12 WRITE(IW,139)(BFT(I,J),J=1,7)
    11 CONTINUE
C
C ** STEER TABLE
C

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```

BRZH3600
BRZH3605
BRZH3610
BRZH3615
BRZH3620
BRZH3625
BRZH3630
BRZH3635
BRZH3640
BRZH3645
BRZH3650
BRZH3655
BRZH3660
BRZH3665
BRZH3670
BRZH3675
BRZH3680
BRZH3685
BRZH3690
BRZH3695
BRZH3700
BRZH3705
BRZH3710
BRZH3715
BRZH3720
BRZH3725
BRZH3730
BRZH3735
BRZH3740
BRZH3745
BRZH3750
BRZH3755
BRZH3760
BRZH3765
BRZH3770
BRZH3775
BRZH3780
BRZH3785
BRZH3790
BRZH3795
BRZH3800
BRZH3805
BRZH3810
BRZH3815
BRZH3820
BRZH3825
BRZH3830
BRZH3835
BRZH3840
BRZH3845
BRZH3850
BRZH3855
BRZH3860
BRZH3865
BRZH3870
BRZH3875
BRZH3880
BRZH3885
BRZH3890
BRZH3895

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```

DO 1410 I=1,25
DO 1410 J=1,2
1410 STEER(I,J)=0.0
IF(NF.EQ.1)GO TO 1405
READ(IR,137)ITABS
DO 1406 I=1,ITABS
READ(IR,1140)(STEER(I,J),J=1,2)
1406 CONTINUE
1140 FORMAT(2F10.0)
GO TO 200
1405 CONTINUE
11012 IF(ISHOW.EQ.1) CALL EXPLAN(6,ISHOW)
WRITE(IW,1135)
1135 FORMAT(///T10,'STEER TABLE'/'% NUMBER OF LINES: ')
READ(IR,137)ITABS
IF(IE.EQ.1) WRITE(IW,136)ITABS
WRITE(IW,1138)
1138 FORMAT('0',T4,'TIME',T13,'STEER ANGLE'/T4,'(SEC)',T16,'(DEG)'/)
DO 1062 I=1,ITABS
READ(IR,1140)(STEER(I,J),J=1,2)
IF(IE.EQ.1) WRITE(IW,1039)(STEER(I,J),J=1,2)
1062 CONTINUE
IF(IE.EQ.1)GO TO 1011
WRITE(IW,1042)
READ(IR,92)ANS
IF(ANS.NE.YES)GO TO 1011
WRITE(IW,1138)
DO 1012 I=1,ITABS
1012 WRITE(IW,1039)(STEER(I,J),J=1,2)
1039 FORMAT(' ',F10.4,F10.2)
1011 CONTINUE
C
C ** END OF INPUT
C
200 CONTINUE
IF (IE.EQ. 1) IR=IDATA1
WRITE(IW,205)
205 FORMAT('R','CHANGE PARAMETERS?')
READ(IR,92) ANS
IF (ANS.EQ. YES) GO TO 300
GO TO 22131
300 IE=0
IREP=1
207 FORMAT(24(12,1X))
2000 FORMAT('0','*** ERROR, OUT OF RANGE ***')
WRITE(IW,208)
208 FORMAT('M','ENTER PARAMETER NUMBER TO BE CHANGED',
1 ' (01-42)')
210 READ(IR,207)ICOR
IF(ICOR.LT.1)GO TO 22131
IF (ICOR.GT. 42) WRITE(IW,2000)
IF (ICOR.GT. 42) GO TO 211
K=ICOR
IF(K.EQ.41)GO TO 151
IF(K.EQ.42)GO TO 152
CALL WRITEX(K)
IF(K.GT.25.AND.K.LT.29)GO TO 150
READ (IR,123) PAR(K)
GO TO 9150
150 J=K-25

```

```

BRZH3900
BRZH3905
BRZH3910
BRZH3915
BRZH3920
BRZH3925
BRZH3930
BRZH3935
BRZH3940
BRZH3945
BRZH3950
BRZH3955
BRZH3960
BRZH3965
BRZH3970
BRZH3975
BRZH3980
BRZH3985
BRZH3990
BRZH3995
BRZH4000
BRZH4005
BRZH4010
BRZH4015
BRZH4020
BRZH4025
BRZH4030
BRZH4035
BRZH4040
BRZH4045
BRZH4050
BRZH4055
BRZH4060
BRZH4065
BRZH4070
BRZH4075
BRZH4080
BRZH4085
BRZH4090
BRZH4095
BRZH4100
BRZH4105
BRZH4110
BRZH4115
BRZH4120
BRZH4125
BRZH4130
BRZH4135
BRZH4140
BRZH4145
BRZH4150
BRZH4155
BRZH4160
BRZH4165
BRZH4170
BRZH4175
BRZH4180
BRZH4185
BRZH4190
BRZH4195

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```

READ(IR,140)PAR(K),PAR2(J)
KEYANT(J)=0
IF(PAR(K).NE.0..OR.PAR2(J).NE.0.)KEYANT(J)=1
9150 CONTINUE
IF (K .NE. 23) GO TO 211
VEL=PAR(K)*5280./3600.
WRITE(I*,126) VEL
GO TO 211
151 WRITE(I*,1151)
1151 FORMAT('241 ANTILOCK CODE (3T1):')
READ(IR,302)(KEYANT(J),J=1,3)
DO 153 J=1,3
JP25=25+J
IF(KEYANT(J) .NE. 1) GO TO 154
CALL WRITEX(JP25)
READ(IR,140) PAR(JP25),PAR2(J)
GO TO 153
154 PAR(JP25)=0.
PAR2(J)=0.
153 CONTINUE
GO TO 211
152 WRITE(I*,1152)
1152 FORMAT('242 TANDEM AXLE/DUAL TIRE CODE (4I1):')
READ(IR,301)(KEY(J),J=1,4)
IF(KEY(1) .NE. 1) GO TO 2105
CALL WRITEX(5)
READ(IR,103)PAR(5)
CALL WRITEX(21)
READ(IR,103) PAR(21)
2105 CONTINUE
IF(KEY(3) .NE. 1) GO TO 211
CALL WRITEX(6)
READ(IR,103) PAR(6)
CALL WRITEX(22)
READ(IR,103) PAR(22)
211 CONTINUE
WRITE(I*,212)
212 FORMAT('8?')
GO TO 210

C
C ** READ BREEZE HITCH PARAMETERS
C
22131 WRITE(I*,8893)
8893 FORMAT('BREEZE HITCH? ')
KKEY=0
XBREEZ=0.
KBREEZ=0
READ(IR,92) ANS
IF ( ANS .NE. YES) GO TO 88213
KKEY=1

C
IF ( IBREZ .EQ. 1 ) GO TO 8899
IBREZ=1

C
8898 WRITE(I*,8895)
8895 FORMAT(' ENTER HITCH, DD,E,THETA(DEG),A5,A6,B5,ACM,ZBREEZ',/,
8' SEPERATED BY COMMA.')
READ(IR,8896) HITCH,DD,E,THETA,A5,A6,B5,ACM,ZBREEZ
8896 FORMAT(9F10,5)
C

```

```

BRZH4200
BRZH4205
BRZH4210
BRZH4215
BRZH4220
BRZH4225
BRZH4230
BRZH4235
BRZH4240
BRZH4245
BRZH4250
BRZH4255
BRZH4260
BRZH4265
BRZH4270
BRZH4275
BRZH4280
BRZH4285
BRZH4290
BRZH4295
BRZH4300
BRZH4305
BRZH4310
BRZH4315
BRZH4320
BRZH4325
BRZH4330
BRZH4335
BRZH4340
BRZH4345
BRZH4350
BRZH4355
BRZH4360
BRZH4365
BRZH4370
BRZH4375
BRZH4380
BRZH4385
BRZH4390
BRZH4395
BRZH4400
BRZH4405
BRZH4410
BRZH4415
BRZH4420
BRZH4425
BRZH4430
BRZH4435
BRZH4440
BRZH4445
BRZH4450
BRZH4455
BRZH4460
BRZH4465
BRZH4470
BRZH4475
BRZH4480
BRZH4485
BRZH4490
BRZH4495

```

```

C
WRITE(IW,8897) HITCHT,DD,E,THETA,A5,A6,B5,ACM,ZBREEZ
8897 FORMAT(/,T3,'HITCHT = ',F10.5,/,T3,'DD = ',F10.5,
13X,'FT',/,T3,'E = ',F10.5,3X,'FT',/,T3,'THETA = ',F10.5,
22X,'DEG',/,T3,'A5 = ',F10.5,3X,'FT',/,T3,'A6 = ',F10.5,
33X,'FT',/,T3,'B5 = ',F10.5,3X,'FT',/,T3,'ACM = ',F10.5,
43X,'FT',/,T3,'ZBREEZ = ',F10.5,3X,'FT')
THETA=THETA*3.14159/180.

```

```

C
8899 WRITE(IW,89792)
89792 FORMAT('CHANGE BREEZE HITCH DATA? ')
READ(IR,92) ANS
IF (ANS.EQ. YES) GO TO 8898
GO TO 213

```

```

C
88213 IBREEZ=0
TBREEZ=0.

```

```

C
C ** BREEZE HITCH INPUT FINISHED
C

```

```

213 WRITE(IW,214)
214 FORMAT('CHANGE BRAKE FORCE TABLE?')
READ(IR,92) ANS
IF (ANS.EQ. YES) GO TO 301
GO TO 3000
301 WRITE(IW,2150)
2150 FORMAT('ADD NEW LINES?')
READ(IR,92) ANS
IF (ANS.NE. YES) GO TO 2301
WRITE(IW,2151)
2151 FORMAT('HOW MANY LINES ARE TO BE ADDED?')
READ(IR,137) ITAB2
ITAB3=ITAB+ITAB2
IF (ITAB3.LT. 16) GO TO 2155
WRITE(IW,2154)
GO TO 301

```

```

2155 WRITE(IW,2152)
2152 FORMAT('ENTER NEW LINES:')
DO 2153 I=1,ITAB2
2153 READ(IR,140) (HFT(ITAB+I,J),J=1,7)
2154 FORMAT('*** TABLE SIZE EXCEEDED ***//', '*** ENTER SMALLER NUMBER ***//')
ITAB=ITAB+ITAB2
WRITE(IW,138)
WRITE(IW,139) ((HFT(I,J),J=1,7),I=1,ITAB)
WRITE(IW,224)
READ(IR,92) ANS
IF (ANS.EQ. YES) GO TO 3000
GO TO 301

```

```

2301 WRITE(IW,215)
215 FORMAT('HOW MANY LINES ARE TO BE CHANGED?')
READ(IR,216) LNS
IF (LNS.LT.16) GO TO 2156
WRITE(IW,2154)
GO TO 2301
2156 CONTINUE
216 FORMAT(I2)
WRITE(IW,217)
217 FORMAT('ENTER LINE NUMBERS TO BE CHANGED: ')

```

```

BRZH4500
BRZH4505
BRZH4510
BRZH4515
BRZH4520
BRZH4525
BRZH4530
BRZH4535
BRZH4540
BRZH4545
BRZH4550
BRZH4555
BRZH4560
BRZH4565
BRZH4570
BRZH4575
BRZH4580
BRZH4585
BRZH4590
BRZH4595
BRZH4600
BRZH4605
BRZH4610
BRZH4615
BRZH4620
BRZH4625
BRZH4630
BRZH4635
BRZH4640
BRZH4645
BRZH4650
BRZH4655
BRZH4660
BRZH4665
BRZH4670
BRZH4675
BRZH4680
BRZH4685
BRZH4690
BRZH4695
BRZH4700
BRZH4705
BRZH4710
BRZH4715
BRZH4720
BRZH4725
BRZH4730
BRZH4735
BRZH4740
BRZH4745
BRZH4750
BRZH4755
BRZH4760
BRZH4765
BRZH4770
BRZH4775
BRZH4780
BRZH4785
BRZH4790
BRZH4795

```

```

READ(IR,207) (COR(I),I=1,LNS)
WRITE(IN,222)
222 FORMAT('D','ENTER CORRECTIONS:')
DO 223 I=1,LNS
READ(IR,140) (BFT(COR(I),J),J=1,7)
223 CONTINUE
WRITE(IN,138)
WRITE(IN,139) ((BFT(I,J),J=1,7),I=1,ITAB)
WRITE(IN,224)
224 FORMAT('3','IS TABLE CORRECT NOW?')
READ(IR,92) ANS
IF (ANS.EQ. YES) GO TO 3000
GO TO 301
3000 CONTINUE
C
C ** CHANGE STEER TABLE
C
4213 WRITE(IN,4214)
4214 FORMAT('8','CHANGE STEER TABLE?')
READ(IR,92)ANS
IF(ANS.EQ. YES)GO TO 4301
GO TO 3999
4301 WRITE(IN,2150)
READ(IP,92)ANS
IF(ANS.EQ. YES)GO TO 6301
WRITE(IN,2151)
READ(IR,137)ITAB2S
ITAB3S=ITAB2S+ITAB2S
IF(ITAB3S.LT.26)GO TO 4155
WRITE(IN,2154)
GO TO 4301
4155 WRITE(IN,2152)
DO 4153 I=1,ITAB2S
4153 READ(IR,1140)(STEER(ITAB2S+I,J),J=1,2)
ITAB3S=ITAB2S+ITAB2S
WRITE(IN,1138)
WRITE(IN,1139)((STEER(I,J),J=1,2),I=1,ITAB3S)
WRITE(IN,224)
READ(IR,92)ANS
IF(ANS.EQ. YES)GO TO 3999
GO TO 4301
6301 WRITE(IN,215)
READ(IR,216)LNS
WRITE(IN,217)
READ(IR,207)(COR(I),I=1,LNS)
WRITE(IN,222)
DO 4223 I=1,LNS
READ(IR,1140)(STEER(COR(I),J),J=1,2)
4223 CONTINUE
WRITE(IN,1138)
WRITE(IN,1039)((STEER(I,J),J=1,2),I=1,ITAB3S)
WRITE(IN,224)
READ(IR,92)ANS
IF(ANS.EQ. YES)GO TO 3999
GO TO 4301
3999 CONTINUE
C ** EQUIVALENCE STATEMENTS
C
W1=PAR(1)
W2=PAR(2)

```

```

BRZH4870
BRZH4875
BRZH4880
BRZH4885
BRZH4890
BRZH4895
BRZH4900
BRZH4905
BRZH4910
BRZH4915
BRZH4920
BRZH4925
BRZH4930
BRZH4935
BRZH4940
BRZH4945
BRZH4950
BRZH4955
BRZH4960
BRZH4965
BRZH4970
BRZH4975
BRZH4980
BRZH4985
BRZH4990
BRZH4995
BRZH5000
BRZH5005
BRZH5010
BRZH5015
BRZH5020
BRZH5025
BRZH5030
BRZH5035
BRZH5040
BRZH5045
BRZH5050
BRZH5055
BRZH5060
BRZH5065
BRZH5070
BRZH5075
BRZH5080
BRZH5085
BRZH5090
BRZH5095

```

```

A=PAR(7)/12.
R=PAR(8)/12.
C=PAR(9)/12.
D=PAR(10)/12.
BBR=PAR(11)/12.
H=R-RRR
Z0=PAR(15)/12.
Z1=PAR(16)/12.
Z2=PAR(17)/12.
T1=PAR(12)/12.
T2=PAR(13)/12.
T3=PAR(14)/12.
GAM1=PAR(20)
GAM2=1.-GAM1
GAM3=PAR(21)
RAD5=PAR(19)/12.
GAM4=PAR(22)
IF(MUSLIP,EO,0)GO TO 4801
DO 4802 T=1,10
MU(I)=PAR(32)
MUS(I)=PAR(35)
4802 MUSLOP(I)=PAR(38)
GO TO 4803
4801 CONTINUE
MUS(1)=PAR(35)
MUS(2)=MUS(1)
MUS(3)=PAR(36)
MUS(7)=PAR(37)
MU(1)=PAR(32)
MU(2)=MU(1)
MU(3)=PAR(33)
MU(7)=PAR(34)
MUSLOP(1)=PAR(38)
MUSLOP(2)=MUSLOP(1)
MUSLOP(3)=PAR(39)
MUSLOP(7)=PAR(40)
4803 CONTINUE
ANTEFF(1,1)=PAR(26)
ANTEFF(2,1)=ANTEFF(1,1)
ANTEFF(3,1)=PAR(27)
ANTEFF(7,1)=PAR(28)
ANTEFF(1,2)=PAR2(1)
ANTEFF(2,2)=ANTEFF(1,2)
ANTEFF(3,2)=PAR2(2)
ANTEFF(7,2)=PAR2(3)
MUS=PAR(18)
I1=PAR(31)/12.
I2=PAR(4)/12.
VEL=PAR(23)*5280./3600.
TIME=PAR(24)+.01
CIA(1)=PAR(29)*57.295
CIA(2)=CIA(1)
CIA(3)=PAR(30)*57.295
CIA(7)=PAR(31)*57.295
DO 3408 I=1,3
IF(MUSLIP,EO,1)GO TO 4804
MUS(3+I)=MUS(3)
MUS(7+I)=MUS(7)
MU(3+I)=MU(3)
MU(7+I)=MU(7)

```

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BRZH5100
BRZH5105
BRZH5110
BRZH5115
BRZH5120
BRZH5125
BRZH5130
BRZH5135
BRZH5140
BRZH5145
BRZH5150
BRZH5155
BRZH5160
BRZH5165
BRZH5170
BRZH5175
BRZH5180
BRZH5185
BRZH5190
BRZH5195
BRZH5200
BRZH5205
BRZH5210
BRZH5215
BRZH5220
BRZH5225
BRZH5230
BRZH5235
BRZH5240
BRZH5245
BRZH5250
BRZH5255
BRZH5260
BRZH5265
BRZH5270
BRZH5275
BRZH5280
BRZH5285
BRZH5290
BRZH5295
BRZH5300
BRZH5305
BRZH5310
BRZH5315
BRZH5320
BRZH5325
BRZH5330
BRZH5335
BRZH5340
BRZH5345
BRZH5350
BRZH5355
BRZH5360
BRZH5365
BRZH5370
BRZH5375
BRZH5380
BRZH5385
BRZH5390
BRZH5395

```



```

MUSLOP(3+I)=MUSLOP(3)
MUSLOP(7+I)=MUSLOP(7)
4804 CONTINUE
DO 3009 J=1,2
ANTEFF(3+I,J)=ANTEFF(3,J)
3009 ANTEFF(7+I,J)=ANTEFF(7,J)
CIA(3+I)=CIA(3)
3008 CIA(7+I)=CIA(7)
AAA=PAR(5)/12.
AAT=PAR(6)/12.
IQUII=PAR(25)

```

C  
C \*\* COMPUTE STATIC LOADS AND ECHO  
C

```

52 FBZ(1)=((R**1)/(2.*(A+B)))+((D*(R-H)**2)/(2.*(A+B)*(C+D)))
FBZ(2)=FRZ(1)
FBZ(3)=((A**1)/(2.*(A+B)))+((D*(A+H)**2)/(2.*(A+B)*(C+D)))
IF(KEY(1).LT.1)GO TO 3010
FBZ(3)=FBZ(3)/2.
FRZ(5)=FRZ(3)
FBZ(6)=FRZ(3)
3010 FBZ(4)=FBZ(3)
FRZ(7)=(C**2)/(2.*(C+D))
IF(KEY(3).LT.1)GO TO 3011
FBZ(7)=FBZ(7)/2.
FRZ(9)=FRZ(7)
FRZ(10)=FRZ(7)
3011 FRZ(8)=FRZ(7)
DO 5 I=1,10
DUAL=0.0
IF(I.GT.2.AND.I.LT.7.AND.KEY(2).GT.0)DUAL=1.0
IF(I.GT.6.AND.KEY(4).GT.0)DUAL=1.0
5 FZ(I)=FBZ(I)/(1.+DUAL)
WRITE(I,129)
129 FORMAT('ECHO STATIC LOADS?')
READ(I,92)ANS
IF(ANS.NE.YES)GO TO 59

```

C  
C \*\* ECHO LOADS  
C

```

FBAX1=2.*FRZ(1)
FBAX2=2.*FRZ(3)
FBAX3=2.*FRZ(7)
WRITE(I,73)FBAX1
73 FORMAT(' ',T6,'STATIC LOADS (LBS)'/2X,'TRACTOR FRONT AXLE: ',
1 F12.2)
IF(KEY(1).EQ.1)GO TO 74
WRITE(I,75)FBAX2
75 FORMAT(2X,'TRACTOR REAR AXLE: ',F12.2)
GO TO 77
74 WRITE(I,76)FBAX2,FBAX2
76 FORMAT(2X,'TRACTOR LEADING TANDEM: ',F12.2/9X,
1 'TRAILING TANDEM: ',F12.2)
77 CONTINUE
IF(KEY(3).EQ.1)GO TO 78
WRITE(I,79)FBAX3
79 FORMAT(2X,'TRAILER AXLE: ',10X,F12.2)
GO TO 80
78 WRITE(I,81)FBAX3,FBAX3
81 FORMAT(2X,'TRAILER LEADING TANDEM: ',F12.2/9X,

```

BRZH5400  
BRZH5405  
BRZH5410  
BRZH5415  
BRZH5420  
BRZH5425  
BRZH5430  
BRZH5435  
BRZH5440  
BRZH5445  
BRZH5450  
BRZH5455  
BRZH5460  
BRZH5465  
BRZH5470  
BRZH5475  
BRZH5480  
BRZH5485  
BRZH5490  
BRZH5495  
BRZH5500  
BRZH5505  
BRZH5510  
BRZH5515  
BRZH5520  
BRZH5525  
BRZH5530  
BRZH5535  
BRZH5540  
BRZH5545  
BRZH5550  
BRZH5555  
BRZH5560  
BRZH5565  
BRZH5570  
BRZH5575  
BRZH5580  
BRZH5585  
BRZH5590  
BRZH5595  
BRZH5600  
BRZH5605  
BRZH5610  
BRZH5615  
BRZH5620  
BRZH5625  
BRZH5630  
BRZH5635  
BRZH5640  
BRZH5645  
BRZH5650  
BRZH5655  
BRZH5660  
BRZH5665  
BRZH5670  
BRZH5675  
BRZH5680  
BRZH5685  
BRZH5690  
BRZH5695

```

1 *TRAILING TANDEM:*,F12.2)
80 CONTINUE
59 CONTINUE
C
C ** INITIALIZATIONS
C
M1=M1/32.17
M2=M2/32.17
INIT=1
WINX=0.
DELTA=DELTA*(2.*3.14159)/360.
NDIM=8
PRMT(1)=0.0
PRMT(2)=TIME
PRMT(3)=.02
PRMT(4)=.01
DO 60 I=1,8
Y(I)=0.
DERY(I)=0.
60 CONTINUE
DO 61 I=2,8,2
61 DERY(I)=.25
Y(2)=VEL
IF(IFLAG.EQ.1)GO TO 611
WRITE(I,9002)
9002 FORMAT(/'ENTER INITIAL ARTIC. ANGLE: ')
READ(IR,103)Y(7)
Y(7)=Y(7)/57.295
IF(Y(7).EQ.0.,AND.(ONCE.EQ.0.))GO TO 612
ONCE=1.
GO TO 611
612 WRITE(I,9003)
9003 FORMAT('WILL ARTIC. ANGLE BE VARIED? ')
IF(ISHOW.EQ.1)CALL EXPLAN(8,ISHOW)
READ(IR,92)ANS
IF(ANS.NE.YES)IFLAG=1
ONCE=1.
611 CONTINUE
WRITE(I,9004)
READ(IR,92)ANS
IF(ANS.EQ.YES)GO TO 200
C
101 FORMAT('0','INPUT PARAMETER TABLE'/'0','NO:',T6,'SYMBOL',T18,'DESCR
IPTION',T59,'INITIAL VALUE'//)
103 FORMAT(F14.2)
104 FORMAT('+',1Y,F12.2)
105 FORMAT('+',1X,2F6.2)
126 FORMAT(' ',T48,'(FPS)',4X,F14.2)
135 FORMAT('0',T7,'BRAKE FORCE TABLE'/'& NUMBER OF LINES: ')
136 FORMAT(I2)
137 FORMAT(I2)
138 FORMAT('0',T7,'TIME',T35,'DESIRED FORCES:'/T7,'(SEC)',T16, 'FSX(
11)',T26,'FSX(2)',T36,'FSX(3)',T46,'FSX(4)',T56,'FSX(7)',T66,'FSX(8)
1)')
139 FORMAT(' ',F10.4,6F10.2)
140 FORMAT(7F10.0)
141 FORMAT('+',F10.4,6F10.2)
9004 FORMAT('RANY DATA CHANGES NOW?')
XDUMP=0.0
XDOFF=0.0
BRZH5700
BRZH5705
BRZH5710
BRZH5715
BRZH5720
BRZH5725
BRZH5730
BRZH5735
BRZH5740
BRZH5745
BRZH5750
BRZH5755
BRZH5760
BRZH5765
BRZH5770
BRZH5775
BRZH5780
BRZH5785
BRZH5790
BRZH5795
BRZH5800
BRZH5805
BRZH5810
BRZH5815
BRZH5820
BRZH5825
BRZH5830
BRZH5835
BRZH5840
BRZH5845
BRZH5850
BRZH5855
BRZH5860
BRZH5865
BRZH5870
BRZH5875
BRZH5880
BRZH5885
BRZH5890
BRZH5895
BRZH5900
BRZH5905
BRZH5910
BRZH5915
BRZH5920
BRZH5925
BRZH5930
BRZH5935
BRZH5940
BRZH5945
BRZH5950
BRZH5955
BRZH5960
BRZH5965
BRZH5970
BRZH5975
BRZH5980
BRZH5985
BRZH5990
BRZH5995

```

RETURN  
END

BRZH6000  
BRZH6005

C  
C  
C  
C  
C  
C  
C  
C  
C  
C  
C

\*\*\*\*\*  
SUBROUTINE WRITEX(I)  
\*\*\*\*\*

BRZH6010  
BRZH6015  
BRZH6020  
BRZH6025  
BRZH6030  
BRZH6035  
BRZH6040  
BRZH6045  
BRZH6050  
BRZH6055  
BRZH6060  
BRZH6065

COMMON /IO/IR, IW

BRZH6070  
BRZH6075  
BRZH6080  
BRZH6085  
BRZH6090  
BRZH6095  
BRZH6100  
BRZH6105  
BRZH6110  
BRZH6115  
BRZH6120

\*\* FORMATS

101 FORMAT('R01 GVW1 WT. OF TRACTOR (LBS)',19X) BRZH6070  
102 FORMAT('R02 GVW2 WT. OF TRAILER (LBS)',19X) BRZH6075  
103 FORMAT('R03 IZZ TRACTOR MOM. OF INERTIA (IN-LB-SEC\*\*2) ') BRZH6080  
104 FORMAT('R04 ITZZ TRAILER MOM. OF INERTIA (IN-LB-SEC\*\*2) ') BRZH6085  
105 FORMAT('R05 AA DIST. BETWEEN TRACTOR TANDEM AXLES (IN) ') BRZH6090  
106 FORMAT('R06 AAT DIST. BETWEEN TRAILER TANDEM AXLES (IN) ') BRZH6095  
107 FORMAT('R07 A1 DIST. FROM TRACTOR CG TO FRONT AXLE (IN) ') BRZH6100  
108 FORMAT('R08 A2 DIST. FROM TRACTOR CG TO REAR AXLE (IN) ') BRZH6105  
109 FORMAT('R09 A3 DIST. FROM TRAILER CG TO FIFTH WHL (IN) ') BRZH6110  
110 FORMAT('R10 A4 DIST. FROM TRAILER CG TO AXLE (IN) ') BRZH6115  
111 FORMAT('R11 RR DIST. FROM TRACTOR REAR SUSPENSION TO ' / BRZH6120  
1 '19X, 'FIFTH WHL (IN). FIFTH WHL LOCATED ' / BRZH6125  
2 'R',19X, 'AFT OF SUSPENSION IS NEGATIVE. ' ) BRZH6130  
112 FORMAT('R12 TRAI HALF LAT. DIST. BETWEEN CENTERS OF TIRE ' / BRZH6135  
1 'R CONTACT ON TRACTOR FRONT AXLE (IN) ' ) BRZH6140  
113 FORMAT('R13 TRA2 HALF LAT. DIST. BETWEEN CENTERS OF TIRE ' / BRZH6145  
1 'R CONTACT ON TRACTOR REAR AXLE/S (IN) ' ) BRZH6150  
114 FORMAT('R14 TRA3 HALF LAT. DIST. BETWEEN CENTERS OF TIRE ' / BRZH6155  
1 'R CONTACT ON TRAILER AXLE/S (IN) ' ) BRZH6160  
115 FORMAT('R15 Z0 HEIGHT OF FIFTH WHL ABOVE GROUND (IN) ') BRZH6165  
116 FORMAT('R16 Z1 HEIGHT OF TRACTOR CG ABOVE GROUND (IN) ') BRZH6170  
117 FORMAT('R17 Z2 HEIGHT OF TRAILER CG ABOVE GROUND (IN) ') BRZH6175  
118 FORMAT('R18 MUS FIFTH WHEEL FRICTION COEFFICIENT ') BRZH6180  
119 FORMAT('R19 RAD5 EQUIVALENT RADIUS OF FIFTH WHEEL (IN) ') BRZH6185  
120 FORMAT('R20 GAM1 PORTION OF TOTAL LAT. LOAD TRANSFER ' / 'R BRZH6190  
1 ' ON FRONT AXLE OF TRACTOR ' ) BRZH6195  
121 FORMAT('R21 GAM3 TRACTOR TANDEM AXLE LOAD X-FER COEF. ') BRZH6200  
123 FORMAT('R23 VEL INITIAL VELOCITY: U-DIRECTION (MPH) ') BRZH6205  
122 FORMAT('R22 GAM4 TRAILER TANDEM AXLE LOAD X-FER COEF. ') BRZH6210  
124 FORMAT('R24 TIME MAX. SIMULATION TIME FOR THIS RUN (SEC) ') BRZH6215  
125 FORMAT('R25 IQUIT MAX. ARTICULATION ANGLE ALLOWED (DEG) ') BRZH6220  
126 FORMAT('R ANTEFF ANTILOCK EFFECTIVENESS COEFFICIENT', BRZH6225  
1 ' (LAT.,LONG.) ' / BRZH6230  
2 'R26 FRONT AXLE: ANTEFF=' ) BRZH6235  
127 FORMAT('R27 TRACTOR REAR AXLE (OR TANDEM AXLES): ANTEFF=' ) BRZH6240  
128 FORMAT('R28 TRAILER AXLE (OR TANDEM AXLES): ANTEFF=' ) BRZH6245  
129 FORMAT('R CALF CORNERING STIFFNESS OF TIRES (LBS/DEG) ' / 'R BRZH6250  
1829 CALF(1)=' ) BRZH6255  
130 FORMAT('R30 CALF(3)=' ) BRZH6260  
131 FORMAT('R31 CALF(7)=' ) BRZH6265  
132 FORMAT('R MUP PEAK TIRE-ROAD FRICTION COEFFICIENT ' / BRZH6270  
1 'R32',19X, 'MUP(1)=' ) BRZH6275  
133 FORMAT('R33 MUP(3)=' ) BRZH6280  
134 FORMAT('R34 MUP(7)=' ) BRZH6285  
135 FORMAT('R MUS SLIDING TIRE-ROAD FRICTION COFF. ' / BRZH6290  
1 'R35 MUS(1)=' ) BRZH6295

136	FORMAT('R36		MUS(3)=')ARZH6300
137	FORMAT('R37		MUS(7)=')ARZH6305
138	FORMAT(' SP	SLIP CORRESPONDING TO PEAK MU'/	ARZH6310
1	'R38		SP(1)=')ARZH6315
139	FORMAT('R39		SP(3)=')ARZH6320
140	FORMAT('R40		SP(7)=')ARZH6325
	GO TO (1,2,3,4,5,6,7,8,9,10,11,12,13,14,15,16,17,18,19,20,21,22,23	ARZH6330	
	1,24,25,26,27,28,29,30,31,32,33,34,35,36,37,38,39,40),I	ARZH6335	
1	WRITE(IW,101)		ARZH6340
	RETURN		ARZH6345
2	WRITE(IW,102)		ARZH6350
	RETURN		ARZH6355
3	WRITE(IW,103)		ARZH6360
	RETURN		ARZH6365
4	WRITE(IW,104)		ARZH6370
	RETURN		ARZH6375
5	WRITE(IW,105)		ARZH6380
	RETURN		ARZH6385
6	WRITE(IW,106)		ARZH6390
	RETURN		ARZH6395
7	WRITE(IW,107)		ARZH6400
	RETURN		ARZH6405
8	WRITE(IW,108)		ARZH6410
	RETURN		ARZH6415
9	WRITE(IW,109)		ARZH6420
	RETURN		ARZH6425
10	WRITE(IW,110)		ARZH6430
	RETURN		ARZH6435
11	WRITE(IW,111)		ARZH6440
	RETURN		ARZH6445
12	WRITE(IW,112)		ARZH6450
	RETURN		ARZH6455
13	WRITE(IW,113)		ARZH6460
	RETURN		ARZH6465
14	WRITE(IW,114)		ARZH6470
	RETURN		ARZH6475
15	WRITE(IW,115)		ARZH6480
	RETURN		ARZH6485
16	WRITE(IW,116)		ARZH6490
	RETURN		ARZH6495
17	WRITE(IW,117)		ARZH6500
	RETURN		ARZH6505
18	WRITE(IW,118)		ARZH6510
	RETURN		ARZH6515
19	WRITE(IW,119)		ARZH6520
	RETURN		ARZH6525
20	WRITE(IW,120)		ARZH6530
	RETURN		ARZH6535
21	WRITE(IW,121)		ARZH6540
	RETURN		ARZH6545
22	WRITE(IW,122)		ARZH6550
	RETURN		ARZH6555
23	WRITE(IW,123)		ARZH6560
	RETURN		ARZH6565
24	WRITE(IW,124)		ARZH6570
	RETURN		ARZH6575
25	WRITE(IW,125)		ARZH6580
	RETURN		ARZH6585
26	WRITE(IW,126)		ARZH6590
	RETURN		ARZH6595

```

27 WRITE(IW,127)
   RETURN
28 WRITE(IW,128)
   RETURN
29 WRITE(IW,129)
   RETURN
30 WRITE(IW,130)
   RETURN
31 WRITE(IW,131)
   RETURN
32 WRITE(IW,132)
   RETURN
33 WRITE(IW,133)
   RETURN
34 WRITE(IW,134)
   RETURN
35 WRITE(IW,135)
   RETURN
36 WRITE(IW,136)
   RETURN
37 WRITE(IW,137)
   RETURN
38 WRITE(IW,138)
   RETURN
39 WRITE(IW,139)
   RETURN
40 WRITE(IW,140)
   RETURN
   END

```

```

BRZH6620
BRZH6625
BRZH6610
BRZH6615
BRZH6620
BRZH6625
BRZH6630
BRZH6635
BRZH6640
BRZH6645
BRZH6650
BRZH6655
BRZH6660
BRZH6665
BRZH6670
BRZH6675
BRZH6680
BRZH6685
BRZH6690
BRZH6695
BRZH6700
BRZH6705
BRZH6710
BRZH6715
BRZH6720
BRZH6725
BRZH6730
BRZH6735
BRZH6740
BRZH6745
BRZH6750

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*****
SUBROUTINE OUTP(X,Y,DERV,IMLF,NDIM,PRMT)
*****

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BRZH6755
BRZH6760
BRZH6765
BRZH6770
BRZH6775
BRZH6780
BRZH6785
BRZH6790
BRZH6795
BRZH6800
BRZH6805
BRZH6810
BRZH6815
BRZH6820
BRZH6825
BRZH6830
BRZH6835
BRZH6840
BRZH6845
BRZH6850
BRZH6855
BRZH6860
BRZH6865
BRZH6870
BRZH6875
BRZH6880
BRZH6885
BRZH6890
BRZH6895

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DIMENSION PRINT(250,85)
DIMENSION Y(8),PRMT(5),DEPY(8),AUX(16,8),CIA(10),FZ(10),FSX(10),
1 DEZ(10),DELZ(10),FX(10),FY(10)
REAL MU,MU5,M1,M2,I1,I2,MUS,MUT(10),MUSLOP,IQUIT
COMMON W1,W2,M1,M2,A,B,C,D,H,70,Z1,Z2,GAM1,GAM2,MUS,RADS,DELTA,
1 T1,T2,T3,CIA,FSX,FZ,IMIT,I1,I2,DERX(4),FBZ(10),ALPHA(10)
2 ,WINX,FY,DEZ,DELZ,TIME,FX,DKEY,VEL,AAA,AAT,KEY(4),
3 MU(10),ANTEFF(10,2),IDUMP,XDUMP,XDOFF,MUS(10),KEYANT(3),
5 MUSLOP(10),EFT(15,7),ITAR,IXON,ITARS,STEER(25,2),ISAV,
6 GAM3,GAM4,TRUCK,IQUIT
COMMON /IO/IR,IW
COMMON /BREEZ/TBREEZ,XBREEZ,HITCOT,DD,E,THETA,A5,A6,B5,ACM
COMMON /KBREEZ/KXBREEZ,ZBREEZ,KKEY
COMMON /FCTOUT/XL,YL,IPLOT
DATA YES,IFIRST/'Y',W/
DIMENSION NCOL(7)
REAL*8 TITLE(85)
DATA TITLE/' TIME', 'X0-COORD', 'Y0-COORD', ' PSI', ' GAMMA',
1 ' U-VEL', ' V-VEL', ' PSIDOT', 'GAMMADOT', 'TURN RAD', 'SIDESLIP',
2 'ALFA 1+2', 'ALFA 3+4', 'ALFA 5+6', 'ALFA 7+8', 'ALFA9+10',
3 ' U-DOT', ' V-DOT', 'PSI-DOT',
4 'GAM-DOOT', 'LONG ACC', 'LAT. ACC', ' FX(1)', ' FX(2)', ' FX(3)',
5 ' FX(4)', ' FX(5)', ' FX(6)', ' FX(7)', ' FX(8)', ' FX(9)',
6 ' FX(10)', ' FY(1)', ' FY(2)', ' FY(3)', ' FY(4)', ' FY(5)',

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C  
C  
C  
C  
C  
C

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7° FY(6),, FY(7),, FY(8),, FY(9),, FY(10),, DFX(1),, BRZH6990
8° DFX(2),, DFX(3),, DFX(4),, DFX(5),, DFX(6),, DFX(7),, BRZH6995
9° DFX(8),, DFX(9),, DFX(10),, DFY(1),, DFY(2),, DFY(3),, BRZH6912
A° DFY(4),, DFY(5),, DFY(6),, DFY(7),, DFY(8),, DFY(9),, BRZH6915
A° DFY(10),, FZ(1),, FZ(2),, FZ(3),, FZ(4),, FZ(5),, BRZH6920
B° FZ(6),, FZ(7),, FZ(8),, FZ(9),, FZ(10),, FSX(1),, BRZH6925
C° FSX(2),, FSX(3),, FSX(4),, FSX(5),, FSX(6),, FSX(7),, BRZH6930
D° FSX(8),, FSX(9),, FSX(10),, XH ,, YH ,, TBREEZ ,/BRZH6935
C BRZH6940
C ** READY TO START BRZH6945
C ** INITIAL CALL TO OUTP BRZH6950
C BRZH6955
C DKEY=0 BRZH6960
C IF (INIT .NE. 0) GO TO 7 BRZH6965
C INIT=INIT+8 BRZH6970
C LINE=0 BRZH6975
C PAGE=3. BRZH6980
C INW=0 BRZH6985
C IF (IFIRST.GT.0)GO TO 500 BRZH6990
C BRZH6995
C ** DETERMINE WHICH VARIABLES TO BE PRINTED OUT BRZH7000
C WRITE(IW,125) BRZH7005
C IFIRST=1 BRZH7010
125 FORMAT('R','DO YOU WANT A LIST OF OUTPUT VARIABLES?') BRZH7015
READ(IR,101) ANS BRZH7020
IF (ANS .NE. YES) GO TO 500 BRZH7025
DO 471 I=1,84 BRZH7030
IF (I .EQ. 1) WRITE(IW,472) BRZH7035
472 FORMAT('0','*** POSITION VARIABLES ***') BRZH7040
IF (I .EQ. 5) WRITE(IW,473) BRZH7045
473 FORMAT('0','*** VELOCITY VARIABLES ***') BRZH7050
IF (I .EQ. 9) WRITE(IW,474) BRZH7055
474 FORMAT('0','***') BRZH7060
IF (I .EQ. 11) WRITE(IW,475) BRZH7065
475 FORMAT('0','*** TIRE SLIP ANGLES ***') BRZH7070
IF (I .EQ. 16) WRITE(IW,476) BRZH7075
476 FORMAT('0','*** ACCELERATION VARIABLES ***') BRZH7080
IF (I .EQ. 22) WRITE(IW,477) BRZH7085
477 FORMAT('0','*** TIRE-ROAD INTERFACE FORCES ***') BRZH7090
ICES: FX(I), SIDE FORCES FY(I) ***') BRZH7095
IF (I .EQ. 42) WRITE(IW,478) BRZH7100
478 FORMAT('0',' *** LOAD TRANSFERS, LONG, DFX(I),LAT, DFY(I) ***') BRZH7105
IF (I .EQ. 62) WRITE(IW,479) BRZH7110
479 FORMAT('0','*** INSTANTANEOUS LOAD FORCES ***') BRZH7115
IF (I .EQ. 72) WRITE(IW,480) BRZH7120
480 FORMAT('0','*** PROGRAMMED BRAKE FORCES ***') BRZH7125
IF (I .EQ. 82)WRITE(IW,481) BRZH7130
481 FORMAT('0','*** HITCH FORCES ***') BRZH7135
WRITE(IW,126) I,TITLE(I+1) BRZH7140
126 FORMAT(' ',I2,10X,A8) BRZH7145
471 CONTINUE BRZH7150
500 CONTINUE BRZH7155
C TO USE HSRT PLOTTING FACILITY, REMOVE C FROM NEXT 8 CARDS AND BRZH7160
C DELETE IPLOT=100. BRZH7165
C WRITE(IW,600) BRZH7170
C 600 FORMAT('R','PLOT (Y OR N)?') BRZH7175
C READ(IR,101)ANS BRZH7180
C IF(ANS.NE.YES)GO TO 470 BRZH7185
C WRITE(IW,103) BRZH7190
C READ(IR,104)IPLOT BRZH7195

```

C	INW=IPLOT	BRZH7200
C	GO TO 102	BRZH7205
	IPLOT=100	BRZH7210
470	WRITE(I*,100)	BRZH7215
100	FORMAT('R', 'PRINT OUTPUT ON FILE?')	BRZH7220
	READ(IR,101) ANS	BRZH7225
101	FORMAT(A1)	BRZH7230
	IF (ANS .NE. YES) GO TO 102	BRZH7235
	WRITE(I*,103)	BRZH7240
103	FORMAT('R', 'ENTER OUTPUT DEVICE NUMBER IN I2 FORMAT:')	BRZH7245
	READ(IR,104) INW	BRZH7250
104	FORMAT(I2)	BRZH7255
102	WRITE(IR,105)	BRZH7260
105	FORMAT('R', 'ENTER TOTAL NUMBER OF OUTPUT VARIABLES',	BRZH7265
	1 ' (01-06):')	BRZH7270
	READ(IR,104) ICOL	BRZH7275
	WRITE(I*,106)	BRZH7280
106	FORMAT('R', 'ENTER NUMBERS OF VARIABLES YOU WANT'/ ' ',	BRZH7285
	1 'SEPARATE NUMBERS BY COMMAS=(01,84)')	BRZH7290
	READ(IR,107) (NCOL(I), I=1, ICOL)	BRZH7295
107	FORMAT(20(I2,1X))	BRZH7300
	DO 502 I=1, ICOL	BRZH7305
502	NCOL(I)=NCOL(I)+1	BRZH7310
C		BRZH7315
C	** NCOL HAS NUMBERS OF VARIABLES TO BE OUTPUT	BRZH7320
C	** SAVE FOR LATER USE	BRZH7325
C	** READ IN TIME INCREMENT	BRZH7330
C		BRZH7335
	WRITE(I*,108)	BRZH7340
108	FORMAT('R', 'ENTER TIME INCREMENT TO BE PRINTED OUT')	BRZH7345
	READ(IR,109) WINX2	BRZH7350
129	FORMAT(F6.4)	BRZH7355
	WINX2=WINX2/.01	BRZH7360
	IF (ICOL .LT. 7) GO TO 7	BRZH7365
200	CONTINUE	BRZH7370
	WRITE(I*,901)	BRZH7375
901	FORMAT('ERROR: NUMBER OF VARIABLES TOO HIGH')	BRZH7380
	GO TO 102	BRZH7385
C		BRZH7390
C	** PRINT ARRAY DIMENSIONED	BRZH7395
C	** CONTINUE WITH FINAL CALCULATIONS	BRZH7400
C		BRZH7405
	7 IF (INW .EQ. 0) GO TO 201	BRZH7410
	INW1=INW	BRZH7415
	Iw=INW	BRZH7420
201	ACY=DERY(4)+Y(2)*Y(6)	BRZH7425
	ACX=DERY(2)-Y(4)*Y(6)	BRZH7430
	DO 700 I=1,4	BRZH7435
	K=2+I	BRZH7440
700	DERX(I)=DERY(K)	BRZH7445
C		BRZH7450
	XAREEZ=TAPEEZ	BRZH7455
C		BRZH7460
	IF (IDUMP .EQ. 1) PRMT(5)=6.	BRZH7465
	IF (Y(2) .GT. 0.) GO TO 19	BRZH7470
	PRMT(5)=4.	BRZH7475
	XDOFF=X	BRZH7480
	GO TO 1	BRZH7485
C		BRZH7490
		BRZH7495

```

C ** SIDE SLIP + TURN RAD.
C
C 19 CONTINUE
C
C DENOM=(Y(2)*(DERY(4)+Y(2)*Y(6)))-(Y(4)*(DERY(2)-Y(4)*Y(6)))
IF (DENOM .EQ. 0) GO TO 22
RADIUS=((Y(2)*Y(2))+(Y(4)*Y(4)))**(.5)/DENOM
GO TO 23
22 RADIUS=0.
23 IF (Y(2) .EQ. 0.) GO TO 27
IF (ABS(Y(4)/Y(2)) .GT. .2) GO TO 220
SSLIP=Y(4)/Y(2)
GO TO 29
220 SSLIP = ATAN(Y(4)/Y(2))
GO TO 29
27 SSLIP=3.14159/2.
29 CONTINUE
SSLIP =SSLIP*57.295
C
C ** CONTINUE?
C
C IF (X .GE. TIME) GO TO 1
IF (X .GE. (WINX*0.01)) GO TO 1
IF (IDUMP .EQ. 1) GO TO 1
IF (INW .NE. 0) IW=INW1
RETURN
1 WINX=WINX+WINX2
LINE=LINE+1
C
C ** CONVERT RADIAN'S TO DEGREES
C
C PHI=Y(5)*57.295
PSI=Y(7)*57.295
PHID=Y(6)*57.295
PSID=Y(8)*57.295
DO 1714 I=1,12
IF (I.GT.4,AND,I.LT.7,AND,KEY(1).LT.1)GO TO 1714
IF (I.GT.8,AND,KEY(3).LT.1)GO TO 1714
ALPHA(I)=ALPHA(I)*57.295
1714 CONTINUE
IF (Y(2) .LT. 0.00) Y(2)=0.
C
C ** BEGIN OUTPUT SET UP
C ** ICOL HAS NUMBER OF OUTPUT VARIABLES TO BE PRINTED
C ** NCOL HAS NUMBER OF VARIABLES
C ** PRINT IS 2 DIMENSIONAL ARRAY, K*ICOL
C ** WHERE K IS NUMBER OF LINES, DETERMINED BE LENGTH OF RUN.
C
PRINT(LINE,1)=X
PRINT(LINE,2)=Y(1)
PRINT(LINE,3)=Y(3)
PRINT(LINE,4)=PHI
PRINT(LINE,5)=PSI
PRINT(LINE,6)=Y(2)
PRINT(LINE,7)=Y(4)
PRINT(LINE,8)=PHID
PRINT(LINE,9)=PSID
PRINT(LINE,10)=RADIUS
PRINT(LINE,11)=SSLIP

```

```

BRZH7502
BRZH7505
BRZH751P
BRZH7515
BRZH7520
BRZH7525
BRZH753P
BRZH7535
BRZH7540
BRZH7545
BRZH7550
BRZH7555
BRZH7562
BRZH7565
BRZH7572
BRZH7575
BRZH75A2
BRZH75A5
BRZH7592
BRZH7595
BRZH762V
BRZH7625
BRZH7612
BRZH7615
BRZH7622
BRZH7625
BRZH7632
BRZH7635
BRZH764V
BRZH7645
BRZH7652
BRZH7655
BRZH7662
BRZH7665
BRZH7672
BRZH7675
BRZH7682
BRZH7685
BRZH7692
BRZH7695
BRZH7702
BRZH7705
BRZH7712
BRZH7715
BRZH7722
BRZH7725
BRZH773V
BRZH7735
BRZH7742
BRZH7745
BRZH7752
BRZH7755
BRZH7762
BRZH7765
BRZH7772
BRZH7775
BRZH7782
BRZH7785
BRZH7792
BRZH7795

```



```

PRINT(LINE,12)=ALPHA(1)
PRINT(LINE,13)=ALPHA(3)
PRINT(LINE,14)=ALPHA(5)
PRINT(LINE,15)=ALPHA(7)
PRINT(LINE,16)=ALPHA(9)
PRINT(LINE,17)=DERY(2)
PRINT(LINE,18)=DERY(4)
PRINT(LINE,19)=DERY(6)*57,295
PRINT(LINE,20)=DERY(8)*57,295
PRINT(LINE,21)=ACX
PRINT(LINE,22)=ACY
DO 50 I=1,10
DUAL=2.0
IF(I.GT.2.AND.I.LT.7.AND.KEY(2).GT.0)DUAL=1.0
IF(I.GT.4.AND.KEY(4).GT.0)DUAL=1.0
PRINT(LINE,22+I)=FX(I)
PRINT(LINE,32+I)=FY(I)
PRINT(LINE,42+I)=DFZ(I)
PRINT(LINE,52+I)=DELFX(I)
PRINT(LINE,62+I)=FZ(I)*(DUAL+1.)
PRINT(LINE,72+I)=FSX(I)
50 CONTINUE
PRINT(LINE,83)=XL
PRINT(LINE,84)=YL
PRINT(LINE,85)=TBREEZ
C
C ** OUTPUT ARRAY NOW SET UP
C
C ** GET READY TO PRINT
C
LIN=2
KIN=7
SURPG=PAGE
IF (AFS(PST) .LT. IQUIT) GO TO 453
IF(INW.EQ.IPLOT)GO TO 2000
WRITE(IN,454) X,PSI
454 FORMAT('0', '***COMPUTATIONS ARE STOPPED***' / ' ', '*** TIME IS ', F6.2, ' SECONDS ***' / ' ', '***ARTIC. ANGLE IS ', F6.2, ' DEGREES ***')
GO TO 300
453 CONTINUE
IF (Y(2) .LE. 0.0) GO TO 300
IF ((X+.02) .GE. TIME) GO TO 300
IF(IDUMP.EQ.1)GO TO 300
IF (INW .NE. 0) IW=INW1
RETURN
300 CONTINUE
IF(INW.EQ.IPLOT)GO TO 2000
WRITE(IN,401) TITLE(1),(TITLE(NCOL(J)),J=1,ICOL)
2000 CONTINUE
IF(INW.NE.IPLOT)GO TO 2009
WRITE(IN,2002)
2002 FORMAT(3X, '-1.00')
WRITE(INW1,2011)
2011 FORMAT('2MULTIPLE PLOT 2-8? ')
READ(IR,101)ANS
IF(ANS.EQ.YES)GO TO 2009
WRITE(IN,104)ICOL
WRITE(IN,107)(NCOL(I),I=1,ICOL)
2009 CONTINUE
DO 257 K=1,LINE
BRZH7800
BRZH7805
BRZH7810
BRZH7815
BRZH7820
BRZH7825
BRZH7830
BRZH7835
BRZH7840
BRZH7845
BRZH7850
BRZH7855
BRZH7860
BRZH7865
BRZH7870
BRZH7875
BRZH7880
BRZH7885
BRZH7890
BRZH7895
BRZH7900
BRZH7905
BRZH7910
BRZH7915
BRZH7920
BRZH7925
BRZH7930
BRZH7935
BRZH7940
BRZH7945
BRZH7950
BRZH7955
BRZH7960
BRZH7965
BRZH7970
BRZH7975
BRZH7980
BRZH7985
BRZH7990
BRZH7995
BRZH8000
BRZH8005
BRZH8010
BRZH8015
BRZH8020
BRZH8025
BRZH8030
BRZH8035
BRZH8040
BRZH8045
BRZH8050
BRZH8055
BRZH8060
BRZH8065
BRZH8070
BRZH8075
BRZH8080
BRZH8085
BRZH8090
BRZH8095

```

```

GO TO (251,252,253,254,255,256),ICOL
251 WRITE(IW,403) PRINT(K,1),(PRINT(K,NCOL(J)),J=1,ICOL)
GO TO 257
252 WRITE(IW,404) PRINT(K,1),(PRINT(K,NCOL(J)),J=1,ICOL)
GO TO 257
253 WRITE(IW,405) PRINT(K,1),(PRINT(K,NCOL(J)),J=1,ICOL)
GO TO 257
254 WRITE(IW,406) PRINT(K,1),(PRINT(K,NCOL(J)),J=1,ICOL)
GO TO 257
255 WRITE(IW,407) PRINT(K,1),(PRINT(K,NCOL(J)),J=1,ICOL)
GO TO 257
256 WRITE(IW,408) PRINT(K,1),(PRINT(K,NCOL(J)),J=1,ICOL)
257 CONTINUE
IF(INW.NE.0)IW=INW1
WRITE(IW,450)
450 FORMAT('?', 'DO YOU WANT ANY MORE OUTPUT?')
READ(IR,101) ANS
IF (ANS .NE. YES) GO TO 301
WRITE(IW,105)
READ(IR,104) ICOL
WRITE(IW,106)
READ(IR,107) (NCOL(I),I=1,ICOL)
DO 503 I=1,ICOL
503 NCOL(I)=NCOL(I)+1
IF(INW.NE.0)IW=INW
GO TO 301
301 CONTINUE
PRMT(5)=1.
IF (Y(2) .LE. 0.0) PRMT(5)=4.
IF (IDUMP.EQ.1)PRMT(5)=6.
IF (INW .NE. 0) IW=INW1
RETURN

```

```

BRZH8100
BRZH8105
BRZH8110
BRZH8115
BRZH8120
BRZH8125
BRZH8130
BRZH8135
BRZH8140
BRZH8145
BRZH8150
BRZH8155
BRZH8160
BRZH8165
BRZH8170
BRZH8175
BRZH8180
BRZH8185
BRZH8190
BRZH8195
BRZH8200
BRZH8205
BRZH8210
BRZH8215
BRZH8220
BRZH8225
BRZH8230
BRZH8235
BRZH8240
BRZH8245
BRZH8250
BRZH8255
BRZH8260
BRZH8265
BRZH8270
BRZH8275
BRZH8280
BRZH8285
BRZH8290
BRZH8295
BRZH8300
BRZH8305
BRZH8310
BRZH8315
BRZH8320
BRZH8325
BRZH8330
BRZH8335
BRZH8340
BRZH8345
BRZH8350
BRZH8355
BRZH8360
BRZH8365
BRZH8370
BRZH8375
BRZH8380
BRZH8385
BRZH8390
BRZH8395

```

```

C
C ** FORMATS
C
401 FORMAT('1',7(2X,A8))
402 FORMAT(F10,2)
403 FORMAT(2F10,2)
404 FORMAT(3F10,2)
405 FORMAT(4F10,2)
406 FORMAT(5F10,2)
407 FORMAT(6F10,2)
408 FORMAT(7F10,2)
END

```

```

C
C *****
C SURROUTINE TIME(Y)
C *****
C

```

```

DIMENSION Y(8),PRMT(5),DERY(8),AUX(16,A),CIA(10),FZ(10),FSX(10),
1 DFZ(10),DELZ(10),FX(10),FY(10)
REAL MU,MUS,M1,M2,I1,I2,MUS,MUT(10),MUSLOP,MUX,MUMOD(10),IQUIT
COMMON W1,W2,M1,M2,A,B,C,D,H,Z1,Z2,GAM1,GAM2,MUS,RADS,DELTA,
1 T1,T2,T3,CIA,FSX,FZ,INIT,I1,I2,DERX(4),FBZ(10),ALPHA(10)
2 ,WINX,FY,DFZ,DELZ,TIME,FX,KEY,VEL,AAA,AAT,KEY(4),
3 MU(10),ANTEFF(10,2),IDUMP,XDUMP,XDOFF,MUS(10),KEYANT(3),
5 MUSLOP(10),BFT(15,7),ITAB,IXON,ITARS,STEER(25,2),ISAV,
6 GAM3,GAM4,TRUCK,IQUIT

```

COMMON /10/IR, IW

C  
C  
C

IAX=1  
IF(Y(2) .LT. 5.0) RETURN  
DO 500 K=1,5

C TANDEM AXLFS  
IF(K.EQ.3.AND.KEY(1).LT.1)GO TO 500  
IF(K.EQ.5.AND.KEY(3).LT.1)GO TO 500  
II1=2\*K-1  
II2=2\*K

C DUAL TIRES  
DUAL=0.0  
IF(K.GT.1.AND.K.LT.4.AND.KEY(2).GT.0)DUAL=1.0  
IF(K.GT.3.AND.KEY(4).GT.0)DUAL=1.0  
C WHEELS 1 AND 2 ARE IN GROUP 1; 3-6 ARE IN GROUP 2; 7-10 ARE  
C IN GROUP 3.  
IF(K.GT.1)IAX=2  
IF(K.GT.3)IAX=3

C  
C ANTILOCK OPTIONS

C  
14 CONTINUE  
II=2  
DO 141 I=II1,II2  
GO TO 201  
141 CONTINUE  
GO TO 500

C  
C TIRE FORCES

C  
201 CONTINUE  
C FOR 2 TIRES IF DUAL  
FX(I)=-FSX(I)  
ALFBR=CTA(I)\*ALPHA(I)/(MU(I)\*FZ(I))  
IF(ABS(ALFBR).GE.3.)GO TO 205  
FY(I)=-MU(I)\*FZ(I)\*(ALFBR-(ALFBR\*ABS(ALFBR))/3.  
1+(ALFBR\*\*3)/27.)\*(1.+DUAL)  
GO TO 206

205 SGN=1.  
IF(ALFBR.LT.0.)SGN=-1.  
FY(I)=-MU(I)\*FZ(I)\*(1.+DUAL)\*SGN

206 CONTINUE  
MUMOD(I)=MU(I)\*(1.-1.72\*ABS(ALPHA(I)))  
IF(MUMOD(I).LT.MUS(I)\*COS(ALPHA(I)))MUMOD(I)=MUS(I)\*COS(ALPHA(I))  
IF(ABS(FX(I)).GE.MUMOD(I)\*FZ(I)\*(1.+DUAL))GO TO 202  
MUX=-(FX(I)/(1.+DUAL))/FZ(I)  
S=(MUX/MU(I))\*MUSLOP(I)  
FY(I)=FY(I)\*FSLIP(S)  
GO TO 141

202 CONTINUE  
IGOTO=KEYANT(IAX)+1  
GO TO (203,204,204,204,204),IGOTO

203 CONTINUE  
FX(I)=-MUS(I)\*FZ(I)\*COS(ALPHA(I))\*(1.+DUAL)  
FY(I)=-MUS(I)\*FZ(I)\*SIN(ALPHA(I))\*(1.+DUAL)  
GO TO 141

204 CONTINUE  
DELTA1=FY(I)+MUS(I)\*FZ(I)\*SIN(ALPHA(I))\*(1.+DUAL)

BRZH8400  
BRZH8405  
BRZH8410  
BRZH8415  
BRZH8420  
BRZH8425  
BRZH8430  
BRZH8435  
BRZH8440  
BRZH8445  
BRZH8450  
BRZH8455  
BRZH8460  
BRZH8465  
BRZH8470  
BRZH8475  
BRZH8480  
BRZH8485  
BRZH8490  
BRZH8495  
BRZH8500  
BRZH8505  
BRZH8510  
BRZH8515  
BRZH8520  
BRZH8525  
BRZH8530  
BRZH8535  
BRZH8540  
BRZH8545  
BRZH8550  
BRZH8555  
BRZH8560  
BRZH8565  
BRZH8570  
BRZH8575  
BRZH8580  
BRZH8585  
BRZH8590  
BRZH8595  
BRZH8600  
BRZH8605  
BRZH8610  
BRZH8615  
BRZH8620  
BRZH8625  
BRZH8630  
BRZH8635  
BRZH8640  
BRZH8645  
BRZH8650  
BRZH8655  
BRZH8660  
BRZH8665  
BRZH8670  
BRZH8675  
BRZH8680  
BRZH8685  
BRZH8690  
BRZH8695

```

FY(I)=-MUS(I)*FZ(I)*SIN(ALPHA(I))*(1,+DUAL)+ANTEFF(I,1)*DELTA1
DELTA2=(MUS(I)*COS(ALPHA(I))-MU(I))*FZ(I)
FX(I)=-MUS(I)*FZ(I)*COS(ALPHA(I))+ANTEFF(I,2)*DELTA2*(1,+DUAL)
GO TO 141
500 CONTINUE
RETURN
END

```

```

BRZHA700
BRZHA705
BRZHA710
BRZHA715
BRZHA720
BRZHA725
BRZHA730
BRZHA735
BRZHA740
BRZHA745
BRZHA750
BRZHA755
BRZHA760
BRZHA765
BRZHA770
BRZHA775
BRZHA780
BRZHA785
BRZHA790
BRZHA795
BRZHA800
BRZHA805
BRZHA810
BRZHA815
BRZHA820
BRZHA825
BRZHA830
BRZHA835
BRZHA840
BRZHA845
BRZHA850
BRZHA855
BRZHA860
BRZHA865
BRZHA870
BRZHA875
BRZHA880
BRZHA885
BRZHA890
BRZHA895
BRZHA900
BRZHA905
BRZHA910
BRZHA915
BRZHA920
BRZHA925
BRZHA930
BRZHA935
BRZHA940
BRZHA945
BRZHA950
BRZHA955
BRZHA960
BRZHA965
BRZHA970
BRZHA975
BRZHA980
BRZHA985
BRZHA990
BRZHA995

```

C  
C  
C  
C  
C  
C

```

*****
FUNCTION FSLIP(S)
*****

```

```

DIMENSION F(6),FDIFF(6),SLIP(6)
COMMON /IO/ IR,IW
DATA YES /'Y'/
DATA SLIP /0.,.05,.10,.15,.20,.25/
DATA F /1.0,.88,.64,.46,.33,.26/
DATA INITIA /0/

```

C  
C

```

IF(INITIA.GT.0)GO TO 10
WRITE(IW,900)
900 FORMAT('WOULD YOU LIKE TO ENTER NEW SLIP ROLL-OFF TABLE?')
READ(IR,900) ANS
800 FORMAT(A1)
IF(ANS.NE.YES)GO TO 1
WRITE(IW,901)
901 FORMAT('ENTER F(S) FOR SLIPS OF 0,0.05,0.10,0.15,0.20,0.25')
1 *SEPARATE 6 NUMBERS BY COMMAS.*
READ(IR,901)(F(I),I=1,6)
801 FORMAT(6F10.0)
1 CONTINUE
SDIFF=.05
FDIFF(1)=0.
DO 5 I=1,5
J=I+1
5 FDIFF(J)=F(J)-F(I)
INITIA=1
10 CONTINUE
DO 20 I=1,10
IF(S.EQ.SLIP(I))GO TO 30
IF(S.LT.SLIP(I))GO TO 25
20 CONTINUE
25 IM1=I-1
FSLIP=F(IM1)+(S-SLIP(IM1))*FDIFF(I)/SDIFF
RETURN
30 FSLIP=F(I)
RETURN
END

```

C  
C  
C  
C  
C  
C

```

*****
SUBROUTINE EXPLAN(NUMBER,ISHOW)
*****

```

```

COMMON /IO/ IR,IW
DATA YES /'Y'/

```

C  
C

```
GO TO (1,12,13,14,15,16,17,18,19),NUMBER
1 WRITE(IN,1000)
  RETURN
1000 FORMAT('      SINCE THE "EXPLANATION OPTION" HAS BEEN REQUESTED,/'
1 ' SUPPLEMENTARY INFORMATION IS PRINTED THE FIRST TIME THROUGH/'
2 ' THE EXECUTION OF THE PROGRAM TO AID THE USER IN UNDERSTAND-'/'
3 ' ING THE PROGRAM. '/'
5 '     IN RESPONDING TO ANY QUESTION FOLLOWING, A YES-RESPONSE/'
6 ' WILL BE ASSUMED IF THE FIRST LETTER OF THE RESPONSE IS "Y."/'
7 ' ANY OTHER RESPONSE WILL BE ASSUMED NO. '/'
12 WRITE(IN,12000)
12000 FORMAT('/' BY ENTERING "Y", THE VALUE ENTERED FOR EACH PAR-'/'
1 ' AMETER IS PRECEDED BY ITS IDENTIFYING PARAMETER NUMBER, ITS/'
2 ' ABBREVIATION, AND ITS VERBAL DESCRIPTION. '/'
3 ' ENTER RESPONSE: '/'
  RETURN
13 WRITE(IN,13000)
13000 FORMAT(' IDENTICAL ANTILOCK SYSTEMS ARE ASSUMED FOR TANDEM/'
1 ' AXLES. ENTER ANTILOCK CODE: ')
  RETURN
14 WRITE(IN,14000)
  WRITE(IN,14500)
14000 FORMAT('/' TIRE PARAMETERS AND I.D. NUMBERS: '/'
+ ' NUMBERS IN PARENTHESES ASSOCIATED WITH TIRE PROPER- '/'
1 ' TIES CALF, MHP, MHS, AND SP REFER TO A PARTICULAR TIRE. '/'
2 ' THE TIRES ARE NUMBERED AS FOLLOWS: '/'
3 ' 1 AND 2: TRACTOR LEFT FRONT AND RIGHT FRONT, RESPECTIVELY. '/'
4 ' 3 AND 4: TRACTOR LEFT REAR AND RIGHT REAR, RESPECTIVELY. '/'
5 ' IF THE TRACTOR HAS TANDEM AXLES, 3 AND 4 ARE THE LEFT AND '/'
6 ' RIGHT TIRES, RESPECTIVELY, ON THE LEADING TANDEM. '/'
7 ' 5 AND 6: TRACTOR LEFT TRAILING TANDEM AND RIGHT TRAILING '/'
8 ' TANDEM, RESPECTIVELY. 5 AND 6 ARE IGNORED IF SINGLE AXLE '/'
9 ' ON TRACTOR REAR. '/'
A ' 7 AND 8: TRAILER LEFT AND RIGHT, RESPECTIVELY. IF THE '/'
A ' TRAILER HAS TANDEM AXLES, 7 AND 8 ARE THE LEFT AND RIGHT '/'
B ' TIRES, RESPECTIVELY, ON THE LEADING TANDEM. ')
14500 FORMAT(
1 ' 9 AND 10: TRAILER LEFT TRAILING TANDEM AND RIGHT TRAILING '/'
2 ' TANDEM, RESPECTIVELY. 9 AND 10 ARE IGNORED IF SINGLE AXLE '/'
3 ' ON TRAILER. '/'
9 ' VALUES ARE ENTERED PER TIRE, EVEN IF DUALS ARE INDICATED. '/'
A ' TIRES 1 AND 2 ARE ASSUMED EQUIVALENT; TIRES 3, 4, 5, AND '/'
B ' 6 ARE ASSUMED EQUIVALENT; AND TIRES 7, 8, 9, AND 10 ARE '/'
E ' ASSUMED EQUIVALENT. IF SINGLE MU-SLIP CURVE IS OPTED. '/'
C ' TIRES 1 TO 10 HAVE THE SAME MU-SLIP CURVE. IN THIS '/'
D ' CASE VALUES FOR TIRE 1, ONLY, ARE ENTERED. '/')
  RETURN
15 WRITE(IN,15000)
15000 FORMAT('/' BRAKE FORCE TABLE: '/'
+ ' AT LEAST ONE LINE MUST BE ENTERED. THE INITIAL TIME '/'
1 ' MUST BE AT TIME T=0. BRAKES ARE NUMBERED IN THE SAME '/'
2 ' MANNER AS ARE TIRES. BRAKES 3 AND 5 ARE EQUIVALENT AS ARE '/'
3 ' 4 AND 6 (THOUGH BRAKES 5 AND 6 ARE IGNORED IF THE TRACTOR '/'
4 ' HAS A SINGLE REAR AXLE). THEREFORE, TABULAR DATA IS '/'
5 ' NOT ENTERED FOR BRAKES 5 AND 6. THE SAME IS TRUE FOR THE '/'
6 ' TRAILER BRAKES. TABULAR DATA IS ENTERED FOR BRAKES 7 AND '/'
7 ' 8 ONLY. BRAKES 9 AND 10 ARE ASSUMED IDENTICAL TO BRAKES '/'
8 ' 7 AND 8, RESPECTIVELY, OR IGNORED IF THE TRAILER HAS A '/'
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BRZH9000  
BRZH9005  
BRZH9010  
BRZH9015  
BRZH9020  
BRZH9025  
BRZH9030  
BRZH9035  
BRZH9040  
BRZH9045  
BRZH9050  
BRZH9055  
BRZH9060  
BRZH9065  
BRZH9070  
BRZH9075  
BRZH9080  
BRZH9085  
BRZH9090  
BRZH9095  
BRZH9100  
BRZH9105  
BRZH9110  
BRZH9115  
BRZH9120  
BRZH9125  
BRZH9130  
BRZH9135  
BRZH9140  
BRZH9145  
BRZH9150  
BRZH9155  
BRZH9160  
BRZH9165  
BRZH9170  
BRZH9175  
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BRZH9210  
BRZH9215  
BRZH9220  
BRZH9225  
BRZH9230  
BRZH9235  
BRZH9240  
BRZH9245  
BRZH9250  
BRZH9255  
BRZH9260  
BRZH9265  
BRZH9270  
BRZH9275  
BRZH9280  
BRZH9285  
BRZH9290  
BRZH9295

```

9 * SINGLE AXLE. LINE 1 FOR A STEP BRAKE INPUT WITHOUT SIDE*/
A * TO SIDE IMBALANCE MAY BE: 0.,0.,0.,1000.,1000.,1500.,1500.*/
RETURN
16 WRITE(IN,16000)
16000 FORMAT(/' STEER TABLE:*/
+ * AT LEAST ONE LINE MUST BE ENTERED, AND THE FIRST LINE*/
1 * MUST BE AT TIME T=0. EACH LINE CONTAINS THE TIME FOLLOWED*/
2 * BY THE AVERAGE STEER ANGLE (IN DEGREES) OF THE TRACTOR*/
3 * FRONT WHEELS.*/
RETURN
17 WRITE(IN,17000)
17000 FORMAT(/' IF YOU ANSWER "Y" TO THIS QUESTION, YOU MAY ENTER A*/
1 * WHOLE NEW DATA SET OR ELSE TERMINATE THE PROGRAM. ANY */
2 * OTHER RESPONSE WILL ALLOW YOU TO CHANGE ANY OF THE INPUT*/
3 * DATA WITHOUT ENTERING A WHOLE NEW DATA SET.*/
4 * &ENTER RESPONSE:*/
ISHOW=0
RETURN
18 WRITE(IN,18000)
18000 FORMAT(/' A "Y"-RESPONSE WILL ALLOW YOU TO ENTER AN INITIAL */
1 * ARTIC. ANGLE WHEN YOU CHANGE PARAMETERS. OTHERWISE, THE*/
2 * INITIAL ARTIC. ANGLE WILL BE ASSUMED 0.*/&ENTER RESPONSE:*/
RETURN
19 WRITE(IN,19000)
19000 FORMAT(/' ANTILOCK EFFECTIVENESS:*/
+ * TWO COEFFICIENTS ARE ENTERED HERE--THE LATERAL COEF-*/
1 * FICIENT, FOLLOWED BY THE LONGITUDINAL COEFFICIENT.*/
RETURN
END

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BRZH9300
BRZH9305
BRZH9310
BRZH9315
BRZH9320
BRZH9325
BRZH9330
BRZH9335
BRZH9340
BRZH9345
BRZH9350
BRZH9355
BRZH9360
BRZH9365
BRZH9370
BRZH9375
BRZH9380
BRZH9385
BRZH9390
BRZH9395
BRZH9400
BRZH9405
BRZH9410
BRZH9415
BRZH9420
BRZH9425
BRZH9430
BRZH9435
BRZH9440

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C		HPCG	10
C		HPCG	20
C	.....	HPCG	30
C		HPCG	40
C	SUBROUTINE HPCG	HPCG	50
C		HPCG	60
C	PURPOSE	HPCG	70
C	TO SOLVE A SYSTEM OF FIRST ORDER ORDINARY GENERAL	HPCG	80
C	DIFFERENTIAL EQUATIONS WITH GIVEN INITIAL VALUES.	HPCG	90
C		HPCG	100
C	USAGE	HPCG	110
C	CALL HPCG (PRMT, Y, DERY, NDIM, IHLF, FCT, OUTP, AUX)	HPCG	120
C	PARAMETERS FCT AND OUTP REQUIRE AN EXTERNAL STATEMENT.	HPCG	130
C		HPCG	140
C	DESCRIPTION OF PARAMETERS	HPCG	150
C	PRMT - AN INPUT AND OUTPUT VECTOR WITH DIMENSION GREATER	HPCG	160
C	OR EQUAL TO 5, WHICH SPECIFIES THE PARAMETERS OF	HPCG	170
C	THE INTERVAL AND OF ACCURACY AND WHICH SERVES FOR	HPCG	180
C	COMMUNICATION BETWEEN OUTPUT SUBROUTINE (FURNISHED	HPCG	190
C	BY THE USER) AND SUBROUTINE HPCG, EXCEPT PRMT(5)	HPCG	200
C	THE COMPONENTS ARE NOT DESTROYED BY SUBROUTINE	HPCG	210
C	HPCG AND THEY ARE	HPCG	220
C	PRMT(1)- LOWER BOUND OF THE INTERVAL (INPUT),	HPCG	230
C	PRMT(2)- UPPER BOUND OF THE INTERVAL (INPUT),	HPCG	240
C	PRMT(3)- INITIAL INCREMENT OF THE INDEPENDENT VARIABLE	HPCG	250
C	(INPUT),	HPCG	260
C	PRMT(4)- UPPER ERROR BOUND (INPUT), IF ABSOLUTE ERROR IS	HPCG	270
C	GREATER THAN PRMT(4), INCREMENT GETS HALVED,	HPCG	280
C	IF INCREMENT IS LESS THAN PRMT(3) AND ABSOLUTE	HPCG	290
C	ERROR LESS THAN PRMT(4)/5%, INCREMENT GETS DOUBLED,	HPCG	300
C	THE USER MAY CHANGE PRMT(4) BY MEANS OF HIS	HPCG	310
C	OUTPUT SUBROUTINE.	HPCG	320
C	PRMT(5)- NO INPUT PARAMETER. SUBROUTINE HPCG INITIALIZES	HPCG	330
C	PRMT(5)=W. IF THE USER WANTS TO TERMINATE	HPCG	340
C	SUBROUTINE HPCG AT ANY OUTPUT POINT, HE HAS TO	HPCG	350
C	CHANGE PRMT(5) TO NON-ZERO BY MEANS OF SUBROUTINE	HPCG	360
C	OUTP. FURTHER COMPONENTS OF VECTOR PRMT ARE	HPCG	370
C	FEASIBLE IF ITS DIMENSION IS DEFINED GREATER	HPCG	380
C	THAN 5. HOWEVER SUBROUTINE HPCG DOES NOT REQUIRE	HPCG	390
C	AND CHANGE THEM. NEVERTHELESS THEY MAY BE USEFUL	HPCG	400
C	FOR HANDING RESULT VALUES TO THE MAIN PROGRAM	HPCG	410
C	(CALLING HPCG) WHICH ARE OBTAINED BY SPECIAL	HPCG	420
C	MANIPULATIONS WITH OUTPUT DATA IN SUBROUTINE OUTP.	HPCG	430
C	Y - INPUT VECTOR OF INITIAL VALUES. (DESTROYED)	HPCG	440
C	LATERON Y IS THE RESULTING VECTOR OF DEPENDENT	HPCG	450
C	VARIABLES COMPUTED AT INTERMEDIATE POINTS X.	HPCG	460
C	DERY - INPUT VECTOR OF ERROR WEIGHTS. (DESTROYED)	HPCG	470
C	THE SUM OF ITS COMPONENTS MUST BE EQUAL TO 1.	HPCG	480
C	LATERON DERY IS THE VECTOR OF DERIVATIVES, WHICH	HPCG	490
C	BELONG TO FUNCTION VALUES Y AT A POINT X.	HPCG	500
C	NDIM - AN INPUT VALUE, WHICH SPECIFIES THE NUMBER OF	HPCG	510
C	EQUATIONS IN THE SYSTEM.	HPCG	520
C	IHLF - AN OUTPUT VALUE, WHICH SPECIFIES THE NUMBER OF	HPCG	530
C	BISECTIONS OF THE INITIAL INCREMENT. IF IHLF GETS	HPCG	540
C	GREATER THAN 10, SUBROUTINE HPCG RETURNS WITH	HPCG	550
C	ERROR MESSAGE IHLF=11 INTO MAIN PROGRAM.	HPCG	560
C	ERROR MESSAGE IHLF=12 OR IHLF=13 APPEARS IN CASE	HPCG	570
C	PRMT(3)=0 OR IN CASE SIGN(PRMT(3)).NE.SIGN(PRMT(2)-	HPCG	580
C	PRMT(1)) RESPECTIVELY.	HPCG	590
C	FCT - THE NAME OF AN EXTERNAL SUBROUTINE USED. IT	HPCG	600





C	IF(H*(PRMT(2)-X))3,2,4	HPCG1210
C	ERROR RETURNS	HPCG1220
	2 IHLF=12	HPCG1230
	GOTO 4	HPCG1240
	3 IHLF=13	HPCG1250
C	COMPUTATION OF DERY FOR STARTING VALUES	HPCG1260
C	4 CALL FCT(X,Y,DERY)	HPCG1270
C	RECORDING OF STARTING VALUES	HPCG1280
C	CALL OUTP(X,Y,DERY,IHLF,NDIM,PRMT)	HPCG1290
	IF(PRMT(5))6,5,6	HPCG1300
	5 IF(IHLF)7,7,6	HPCG1310
	6 RETURN	HPCG1320
	7 DO 8 I=1,NDIM	HPCG1330
	8 AUX(8,I)=DERY(I)	HPCG1340
C	COMPUTATION OF AUX(2,I)	HPCG1350
C	ISW=1	HPCG1360
	GOTO 100	HPCG1370
C	9 X=X+H	HPCG1380
	DO 10 I=1,NDIM	HPCG1390
	10 AUX(2,I)=Y(I)	HPCG1400
C	INCREMENT H IS TESTED BY MEANS OF BISECTION	HPCG1410
C	11 IHLF=IHLF+1	HPCG1420
	X=X-H	HPCG1430
	DO 12 I=1,NDIM	HPCG1440
	12 AUX(4,I)=AUX(2,I)	HPCG1450
	H=.5*H	HPCG1460
	N=1	HPCG1470
	ISW=2	HPCG1480
	GOTO 100	HPCG1490
C	13 X=X+H	HPCG1500
	CALL FCT(X,Y,DERY)	HPCG1510
	N=2	HPCG1520
	DO 14 I=1,NDIM	HPCG1530
	AUX(2,I)=Y(I)	HPCG1540
	14 AUX(9,I)=DERY(I)	HPCG1550
	ISW=3	HPCG1560
	GOTO 100	HPCG1570
C	COMPUTATION OF TEST VALUE DELT	HPCG1580
C	15 DELT=0.	HPCG1590
	DO 16 I=1,NDIM	HPCG1600
	16 DELT=DELT+AUX(15,I)*ABS(Y(I)-AUX(4,I))	HPCG1610
	DELT=.66666667*DELT	HPCG1620
	IF(DELT-PRMT(4))19,19,17	HPCG1630
	17 IF(IHLF=10)11,18,18	HPCG1640
C	NO SATISFACTORY ACCURACY AFTER 10 BISECTIONS. ERROR MESSAGE.	HPCG1650
C	18 IHLF=11	HPCG1660
	X=X+H	HPCG1670
	GOTO 4	HPCG1680
C	THERE IS SATISFACTORY ACCURACY AFTER LESS THAN 11 BISECTIONS.	HPCG1690
C	19 X=X+H	HPCG1700
		HPCG1710
		HPCG1720
		HPCG1730
		HPCG1740
		HPCG1750
		HPCG1760
		HPCG1770
		HPCG1780
		HPCG1790
		HPCG1800

	CALL FCT(X,Y,DERY)	HPCG1810
	DO 20 I=1,NDIM	HPCG1820
	AUX(3,I)=Y(I)	HPCG1830
20	AUX(10,I)=DERY(I)	HPCG1840
	N=3	HPCG1850
	ISW=4	HPCG1860
	GOTO 170	HPCG1870
C		HPCG1880
21	N=1	HPCG1890
	X=X+H	HPCG1900
	CALL FCT(X,Y,DERY)	HPCG1910
	X=PRMT(1)	HPCG1920
	DO 22 I=1,NDIM	HPCG1930
	AUX(11,I)=DERY(I)	HPCG1940
22	Y(I)=AUX(1,I)+H*(.375*AUX(8,I)+.7916667*AUX(9,I)	HPCG1950
	1+.2083333*AUX(10,I)+.04166667*DERY(I))	HPCG1960
23	X=X+H	HPCG1970
	N=N+1	HPCG1980
	CALL FCT(X,Y,DERY)	HPCG1990
	CALL OUTP(X,Y,DERY,IHLF,NDIM,PRMT)	HPCG2000
	IF(PRMT(5))6,24,6	HPCG2010
24	IF(N=4)25,203,203	HPCG2020
25	DO 26 I=1,NDIM	HPCG2030
	AUX(N,I)=Y(I)	HPCG2040
26	AUX(N+7,I)=DERY(I)	HPCG2050
	IF(N=3)27,29,202	HPCG2060
C		HPCG2070
27	DO 28 I=1,NDIM	HPCG2080
	DELT=AUX(9,I)+AUX(9,I)	HPCG2090
	DELT=DELT+DELT	HPCG2100
28	Y(I)=AUX(1,I)+.3333333*H*(AUX(8,I)+DELT+AUX(10,I))	HPCG2110
	GOTO 23	HPCG2120
C		HPCG2130
29	DO 30 I=1,NDIM	HPCG2140
	DELT=AUX(9,I)+AUX(10,I)	HPCG2150
	DELT=DELT+DELT+DELT	HPCG2160
30	Y(I)=AUX(1,I)+.375*H*(AUX(8,I)+DELT+AUX(11,I))	HPCG2170
	GOTO 23	HPCG2180
C		HPCG2190
C	THE FOLLOWING PART OF SUBROUTINE HPCG COMPUTES BY MEANS OF	HPCG2200
C	RUNGE-KUTTA METHOD STARTING VALUES FOR THE NOT SELF-STARTING	HPCG2210
C	PREDICTOR-CORRECTOR METHOD.	HPCG2220
100	DO 101 I=1,NDIM	HPCG2230
	Z=H*AUX(N+7,I)	HPCG2240
	AUX(5,I)=Z	HPCG2250
101	Y(I)=AUX(N,I)+.4*Z	HPCG2260
C	Z IS AN AUXILIARY STORAGE LOCATION	HPCG2270
C		HPCG2280
	Z=X+.4*H	HPCG2290
	CALL FCT(Z,Y,DERY)	HPCG2300
	DO 102 I=1,NDIM	HPCG2310
	Z=H*DERY(I)	HPCG2320
	AUX(6,I)=Z	HPCG2330
102	Y(I)=AUX(N,I)+.2969776*AUX(5,I)+.1587596*Z	HPCG2340
C		HPCG2350
	Z=X+.4557372*H	HPCG2360
	CALL FCT(Z,Y,DERY)	HPCG2370
	DO 103 I=1,NDIM	HPCG2380
	Z=H*DERY(I)	HPCG2390
	AUX(7,I)=Z	HPCG2400

	103 Y(I)=AUX(N,I)+.2181004*AUX(5,I)-3.050965*AUX(6,I)+3.832865*Z	HPCG2410
C	Z=X+H	HPCG2420
	CALL FCT(Z,Y,DERY)	HPCG2430
	DO 104 I=1,NDIM	HPCG2440
	1040 Y(I)=AUX(N,I)+.1747603*AUX(5,I)-.5514807*AUX(6,I)	HPCG2450
	1+1.205536*AUX(7,I)+.1711848*H*DERY(I)	HPCG2460
	GOTO(9,13,15,21),ISW	HPCG2470
		HPCG2480
C		HPCG2490
C	POSSIBLE BREAK-POINT FOR LINKAGE	HPCG2500
C		HPCG2510
C	STARTING VALUES ARE COMPUTED.	HPCG2520
C	NOW START HAMMINGS MODIFIED PREDICTOR-CORRECTOR METHOD.	HPCG2530
	200 ISTEP=0	
	ICT=3	
	201 IF(N=8)204,202,204	HPCG2550
C		HPCG2560
C	N=8 CAUSES THE ROWS OF AUX TO CHANGE THEIR STORAGE LOCATIONS	HPCG2570
	202 DO 203 N=2,7	HPCG2580
	DO 203 I=1,NDIM	HPCG2590
	AUX(N-1,I)=AUX(N,I)	HPCG2600
	203 AUX(N+6,I)=AUX(N+7,I)	HPCG2610
	N=7	HPCG2620
		HPCG2630
C		HPCG2640
C	N LESS THAN 8 CAUSES N+1 TO GET N	HPCG2650
	204 N=N+1	HPCG2660
C		HPCG2670
C	COMPUTATION OF NEXT VECTOR Y	HPCG2680
	DO 205 I=1,NDIM	HPCG2690
	AUX(N-1,I)=Y(I)	HPCG2700
	205 AUX(N+6,I)=DERY(I)	HPCG2710
	X=X+H	HPCG2720
	206 ISTEP=ISTEP+1	
	ICT=ICT+1	
	DO 207 I=1,NDIM	HPCG2730
	DELTA=AUX(N-4,I)+1.333333*H*(AUX(N+6,I)+AUX(N+6,I)-AUX(N+5,I)+	HPCG2740
	1AUX(N+4,I)+AUX(N+4,I))	HPCG2750
	Y(I)=DELTA-.9256198*AUX(16,I)	HPCG2760
	207 AUX(16,I)=DELTA	HPCG2770
C	PREDICTOR IS NOW GENERATED IN ROW 16 OF AUX, MODIFIED PREDICTOR	HPCG2780
C	IS GENERATED IN Y. DELTA MEANS AN AUXILIARY STORAGE.	HPCG2790
C		HPCG2800
	CALL FCT(X,Y,DERY)	HPCG2810
C	DERIVATIVE OF MODIFIED PREDICTOR IS GENERATED IN DERY	HPCG2820
C		HPCG2830
	DO 208 I=1,NDIM	HPCG2840
	DELTA=.125*(9.*AUX(N-1,I)-AUX(N-3,I)+3.*H*(DERY(I)+AUX(N+6,I)+	HPCG2850
	1AUX(N+6,I)-AUX(N+5,I)))	HPCG2860
	AUX(16,I)=AUX(16,I)-DELTA	HPCG2870
	208 Y(I)=DELTA+.07438017*AUX(16,I)	HPCG2880
C		HPCG2890
C	TEST WHETHER H MUST BE HALVED OR DOUBLED	HPCG2900
	DELTA=0.	HPCG2910
	DO 209 I=1,NDIM	HPCG2920
	209 DELTA=DELTA+AUX(15,I)*ABS(AUX(16,I))	HPCG2930
	IF(DELTA-PRMT(4))210,222,222	HPCG2940
		HPCG2950
C		HPCG2960
C	H MUST NOT BE HALVED. THAT MEANS Y(I) ARE GOOD.	HPCG2970
	210 CALL FCT(X,Y,DERY)	HPCG2980
	CALL OUTP(X,Y,DERY,IHLF,NDIM,PRMT)	

	IF (PRMT(5)) 212, 211, 212	HPCG2990
211	IF (IHLF-11) 213, 212, 212	HPCG3000
212	RETURN	HPCG3010
213	IF (H*(X-PRMT(2))) 214, 212, 212	HPCG3020
214	IF (ABS(X-PRMT(2))- .1*ABS(H)) 212, 215, 215	HPCG3030
215	IF (DELT-.42*PRMT(4)) 216, 216, 201	HPCG3040
C		HPCG3050
C		HPCG3060
C	H COULD BE DOUBLED IF ALL NECESSARY PRECEEDING VALUES ARE AVAILABLE	HPCG3070
C		HPCG3080
216	IF (IHLF) 201, 201, 218	
218	IF (ISTEP-3) 201, 219, 219	
219	IMOD=ICT/2	
	IF (ICT-IMOD-IMOD) 201, 220, 201	
220	H=H+H	HPCG3140
	ICT=IMOD	
	IHLF=IHLF-1	HPCG3150
	ISTEP=0	HPCG3160
	DO 221 I=1,NDIM	HPCG3170
	AUX(N-1,I)=AUX(N-2,I)	HPCG3180
	AUX(N-2,I)=AUX(N-4,I)	HPCG3190
	AUX(N-3,I)=AUX(N-6,I)	HPCG3200
	AUX(N+6,I)=AUX(N+5,I)	HPCG3210
	AUX(N+5,I)=AUX(N+3,I)	HPCG3220
	AUX(N+4,I)=AUX(N+1,I)	HPCG3230
	DELT=AUX(N+6,I)+AUX(N+5,I)	HPCG3240
	DELT=DELT+DELT+DELT	HPCG3250
221	AUX(16,I)=8.962963*(Y(I)-AUX(N-3,I))-3.361111*H*(DERY(I)+DELT	HPCG3260
	1+AUX(N+4,I))	HPCG3270
	GOTO 201	HPCG3280
C		HPCG3290
C		HPCG3300
C	H MUST BE HALVED	HPCG3310
222	IHLF=IHLF+1	HPCG3320
	ICT=ICT+ICT	
	IF (IHLF-10) 223, 223, 210	HPCG3330
223	H=.5*H	HPCG3340
	ISTEP=1	HPCG3350
	DO 224 I=1,NDIM	HPCG3360
	0Y(I)=.00390625*(00.*AUX(N-1,I)+135.*AUX(N-2,I)+40.*AUX(N-3,I)+	HPCG3370
	1AUX(N-4,I))- .1171875*(AUX(N+6,I)-6.*AUX(N+5,I)-AUX(N+4,I))*H	HPCG3380
	0AUX(N-4,I)=.00390625*(12.*AUX(N-1,I)+135.*AUX(N-2,I)+	HPCG3390
	1108.*AUX(N-3,I)+AUX(N-4,I))- .0234375*(AUX(N+6,I)+18.*AUX(N+5,I)-	HPCG3400
	29.*AUX(N+4,I))*H	HPCG3410
	AUX(N-3,I)=AUX(N-2,I)	HPCG3420
224	AUX(N+4,I)=AUX(N+5,I)	HPCG3430
	X=X-H	HPCG3440
	DELT=X-(H+H)	HPCG3450
	CALL FCT(DELT,Y,DERY)	HPCG3460
	DO 225 I=1,NDIM	HPCG3470
	AUX(N-2,I)=Y(I)	HPCG3480
	AUX(N+5,I)=DERY(I)	HPCG3490
225	Y(I)=AUX(N-4,I)	HPCG3500
	DELT=DELT-(H+H)	HPCG3510
	CALL FCT(DELT,Y,DERY)	HPCG3520
	DO 226 I=1,NDIM	HPCG3530
	DELT=AUX(N+5,I)+AUX(N+4,I)	HPCG3540
	DELT=DELT+DELT+DELT	HPCG3550
	0AUX(16,I)=8.962963*(AUX(N-1,I)-Y(I))-3.361111*H*(AUX(N+6,I)+DELT	HPCG3560
	1+DERY(I))	HPCG3570

226 AUX(N+3,I)=DERY(I)  
GOTO 246  
END

HPCG3580  
HPCG3590  
HPCG3600

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C DECK SIMQ
C ..... SIMQ 10
C ..... SIMQ 20
C ..... SIMQ 30
C SUBROUTINE SIMQ SIMQ 40
C ..... SIMQ 50
C PURPOSE SIMQ 60
C OBTAIN SOLUTION OF A SET OF SIMULTANEOUS LINEAR EQUATIONS, SIMQ 70
C AX=B SIMQ 80
C ..... SIMQ 90
C USAGE SIMQ 100
C CALL SIMQ(A,B,N,KS) SIMQ 110
C ..... SIMQ 120
C DESCRIPTION OF PARAMETERS SIMQ 130
C A - MATRIX OF COEFFICIENTS STORED COLUMNWISE. THESE ARE SIMQ 140
C DESTROYED IN THE COMPUTATION. THE SIZE OF MATRIX A IS SIMQ 150
C N BY N. SIMQ 160
C B - VECTOR OF ORIGINAL CONSTANTS (LENGTH N). THESE ARE SIMQ 170
C REPLACED BY FINAL SOLUTION VALUES, VECTOR X. SIMQ 180
C N - NUMBER OF EQUATIONS AND VARIABLES. N MUST BE .GT. ONE. SIMQ 190
C KS - OUTPUT DIGIT SIMQ 200
C 0 FOR A NORMAL SOLUTION SIMQ 210
C 1 FOR A SINGULAR SET OF EQUATIONS SIMQ 220
C ..... SIMQ 230
C REMARKS SIMQ 240
C MATRIX A MUST BE GENERAL. SIMQ 250
C IF MATRIX IS SINGULAR, SOLUTION VALUES ARE MEANINGLESS. SIMQ 260
C AN ALTERNATIVE SOLUTION MAY BE OBTAINED BY USING MATRIX SIMQ 270
C INVERSION (MINV) AND MATRIX PRODUCT (GMPRD). SIMQ 280
C ..... SIMQ 290
C SUBROUTINES AND FUNCTION SUBPROGRAMS REQUIRED SIMQ 300
C NONE SIMQ 310
C ..... SIMQ 320
C METHOD SIMQ 330
C METHOD OF SOLUTION IS BY ELIMINATION USING LARGEST PIVOTAL SIMQ 340
C DIVISOR. EACH STAGE OF ELIMINATION CONSISTS OF INTERCHANGING SIMQ 350
C ROWS WHEN NECESSARY TO AVOID DIVISION BY ZERO OR SMALL SIMQ 360
C ELEMENTS. SIMQ 370
C THE FORWARD SOLUTION TO OBTAIN VARIABLE N IS DONE IN SIMQ 380
C N STAGES. THE BACK SOLUTION FOR THE OTHER VARIABLES IS SIMQ 390
C CALCULATED BY SUCCESSIVE SUBSTITUTIONS. FINAL SOLUTION SIMQ 400
C VALUES ARE DEVELOPED IN VECTOR B, WITH VARIABLE 1 IN B(1), SIMQ 410
C VARIABLE 2 IN B(2),....., VARIABLE N IN B(N). SIMQ 420
C IF NO PIVOT CAN BE FOUND EXCEEDING A TOLERANCE OF 0.0, SIMQ 430
C THE MATRIX IS CONSIDERED SINGULAR AND KS IS SET TO 1. THIS SIMQ 440
C TOLERANCE CAN BE MODIFIED BY REPLACING THE FIRST STATEMENT, SIMQ 450
C ..... SIMQ 460
C ..... SIMQ 470
C ..... SIMQ 480
C SUBROUTINE SIMQ(A,B,N,KS) SIMQ 490
C DIMENSION A(1),B(1) SIMQ 500
C ..... SIMQ 510
C FORWARD SOLUTION SIMQ 520
C ..... SIMQ 530
C TOL=0.0 SIMQ 540
C KS=0 SIMQ 550
C JJ=-N SIMQ 560
C DO 65 J=1,N SIMQ 570
C JY=J+1 SIMQ 580

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	JJ=JJ+N+1	SIMQ 590
	BIGA=0	SIMQ 600
	IT=JJ-J	SIMQ 610
	DO 30 I=J,N	SIMQ 620
C		SIMQ 630
C	SEARCH FOR MAXIMUM COEFFICIENT IN COLUMN	SIMQ 640
		SIMQ 650
	IJ=IT+1	SIMQ 660
	IF(ABS(BIGA)-ABS(A(IJ))) 20,30,30	SIMQ 670
20	BIGA=A(IJ)	SIMQ 680
	IMAX=I	SIMQ 690
30	CONTINUE	SIMQ 700
C		SIMQ 710
C	TEST FOR PIVOT LESS THAN TOLERANCE (SINGULAR MATRIX)	SIMQ 720
		SIMQ 730
	IF(ABS(BIGA)-TOL) 35,35,40	SIMQ 740
35	KS=1	SIMQ 750
	RETURN	SIMQ 760
C		SIMQ 770
C	INTERCHANGE ROWS IF NECESSARY	SIMQ 780
		SIMQ 790
40	I1=J+N*(J-2)	SIMQ 800
	IT=IMAX-J	SIMQ 810
	DO 50 K=J,N	SIMQ 820
	I1=I1+N	SIMQ 830
	I2=I1+IT	SIMQ 840
	SAVE=A(I1)	SIMQ 850
	A(I1)=A(I2)	SIMQ 860
	A(I2)=SAVE	SIMQ 870
C		SIMQ 880
C	DIVIDE EQUATION BY LEADING COEFFICIENT	SIMQ 890
		SIMQ 900
50	A(I1)=A(I1)/BIGA	SIMQ 910
	SAVE=B(IMAX)	SIMQ 920
	B(IMAX)=B(J)	SIMQ 930
	B(J)=SAVE/BIGA	SIMQ 940
C		SIMQ 950
C	ELIMINATE NEXT VARIABLE	SIMQ 960
		SIMQ 970
	IF(J=N) 55,70,55	SIMQ 980
55	IQS=N*(J-1)	SIMQ 990
	DO 65 IX=JY,N	SIMQ1000
	IXJ=IQS+IX	SIMQ1010
	IT=J-IX	SIMQ1020
	DO 60 JX=JY,N	SIMQ1030
	IXJX=N*(JX-1)+IX	SIMQ1040
	JJX=IXJX+IT	SIMQ1050
60	A(IXJX)=A(IXJX)-(A(IXJ)*A(JJX))	SIMQ1060
65	B(IX)=B(IX)-(B(J)*A(IXJ))	SIMQ1070
C		SIMQ1080
C	BACK SOLUTION	SIMQ1090
		SIMQ1100
70	NY=N-1	SIMQ1110
	IT=N*N	SIMQ1120
	DO 80 J=1,NY	SIMQ1130
	IA=IT-J	SIMQ1140
	IB=N-J	SIMQ1150
	IC=N	SIMQ1160
	DO 80 K=1,J	SIMQ1170
	B(IB)=B(IB)-A(IA)*B(IC)	SIMQ1180

IA=IA-N  
BP IC=IC-1  
RETURN  
END

SIMQ1190  
SIMQ1200  
SIMQ1210  
SIMQ1220